

fast and precise calculation of trajectories through a magnetic field

(inspired by the LHCb context)

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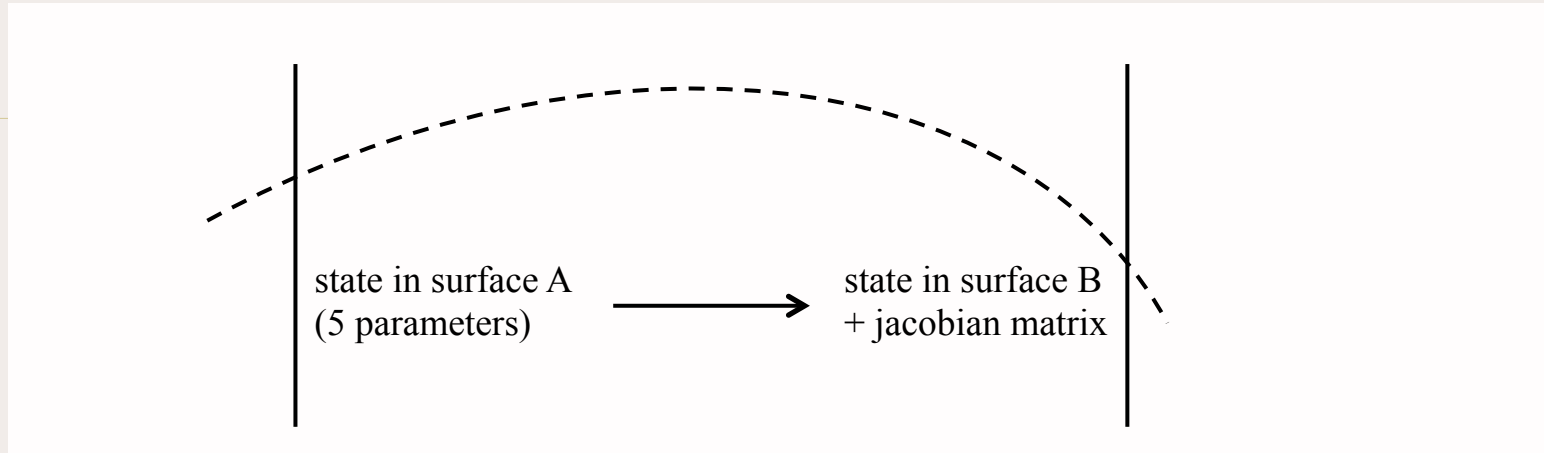
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08/03/17

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what do we need ?



wanted precision:

- pattern recognition: better than the hit separation distance
- track fit: *much better* than the combination of measurement and multiple scattering errors

useful trajectories: from primary vertices + short lived decays + K_S/Λ decays if possible

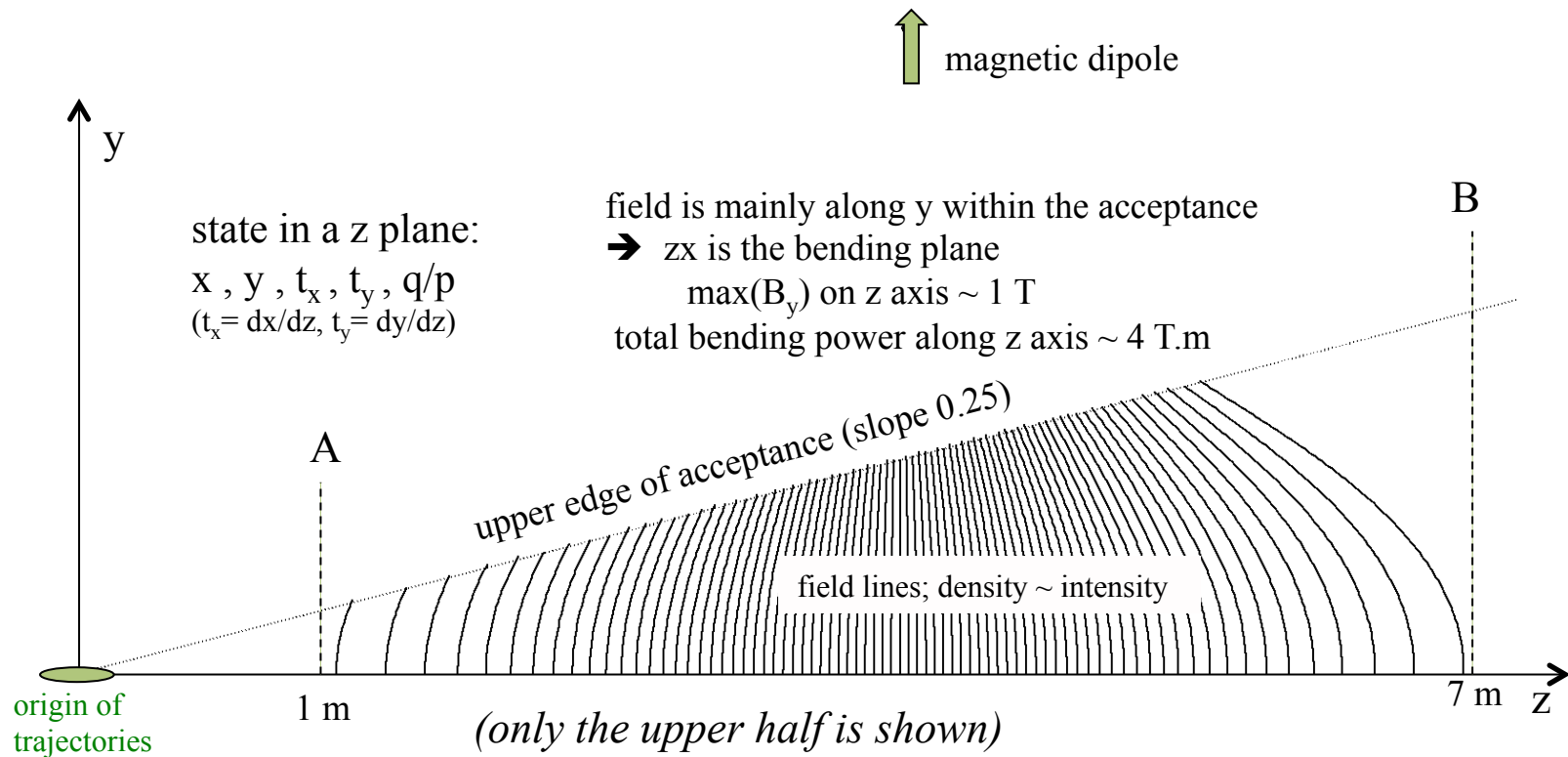
guidelines:

- the state on surface A lies in a *small region* of the 5D-space of track parameters
- the wanted precision scales as $1/p$ in most cases
- in general, one needs to consider a few predefined surfaces + short range extrapolations

standard method (used as reference): stepwise propagation using the Runge-Kutta algorithm

problem: access to a field map (possibly big size) and CPU time consumption

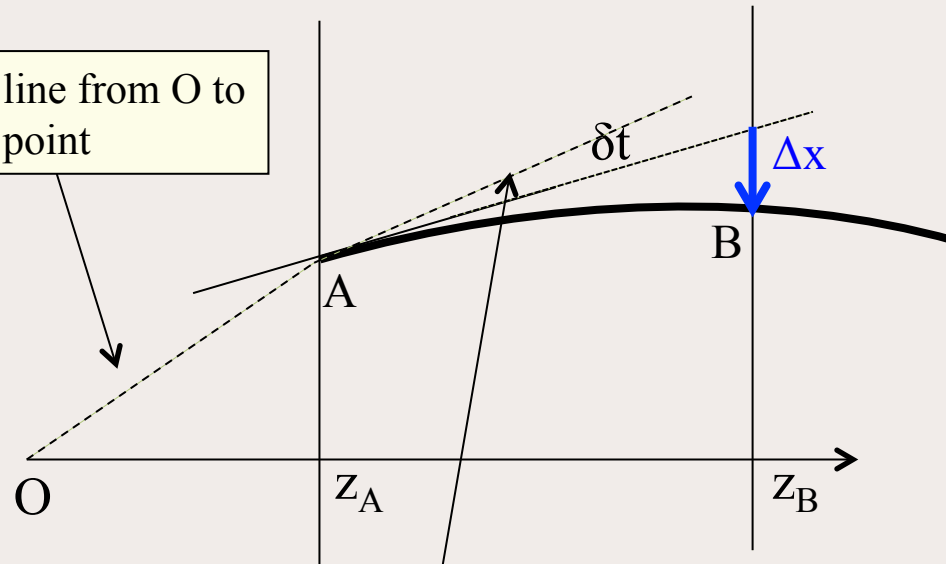
framework: forward spectrometer on a collider (similar to LHCb)



in this study: extrapolation from the state in plane A to the state in plane B

a polynomial expansion of the deviation from the straight line

straight line from O to starting point



including the magnetic deviation
from 0 to z_A as $q/p F(z_A)$
(F from a table)
→ $|\delta t_x|$ and $|\delta t_y|$ are small

deviation $\Delta x =$

$$\Sigma C_{ijk} \delta t_x^i \delta t_y^j (q/p)^k$$

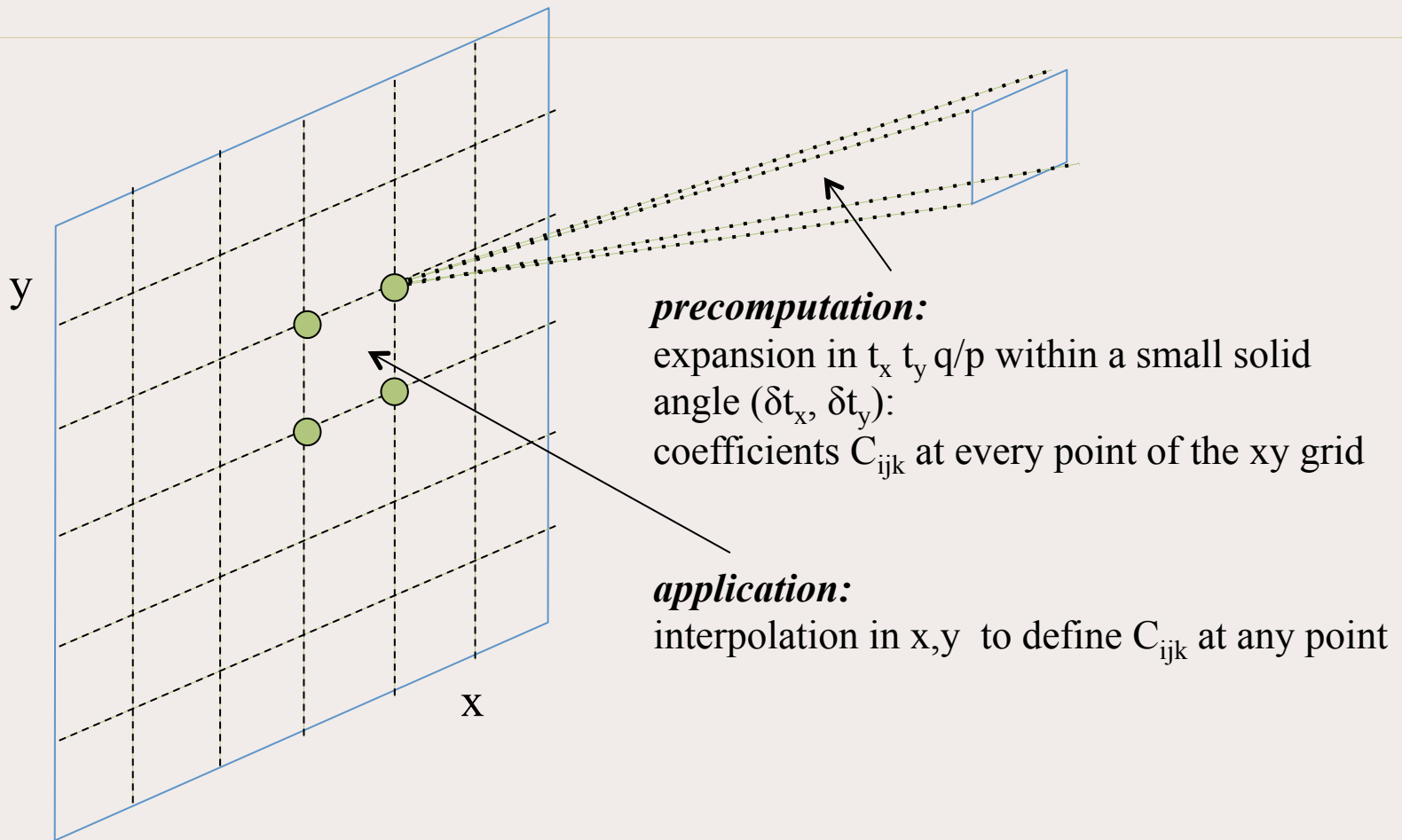
similar expressions for
 $\Delta y, \Delta t_x, \Delta t_y$

tabulate the coefficients
as functions of x, y at z_A

+ apply global corrections in
higher powers of q/p
(independent of x, y, t_x, t_y)

***jacobian matrix easy to obtain
from this parametrization***

implementation on a planar surface



orders of magnitude and working conditions

typical conditions for initial plane at $z = 1$ m:

$$\sigma(z_{\text{vertex}}) \sim 5 \text{ cm} \rightarrow \delta t \sim 0.05 \times t$$

$$\text{impact parameter for } K_S \text{ products} \sim 2.5 \text{ cm} \rightarrow \delta t \sim 0.025$$

domain used in initial plane to fit the coefficients

- $p > p_{\text{min}} = 3 \text{ GeV}/c$ (good chance to remain within the acceptance)
- $|\delta t|_{\text{max}} = 0.01$ (0.03 for K_S studies)
- $|x|$ and $|y| < 0.25 \text{ m}$

computation:

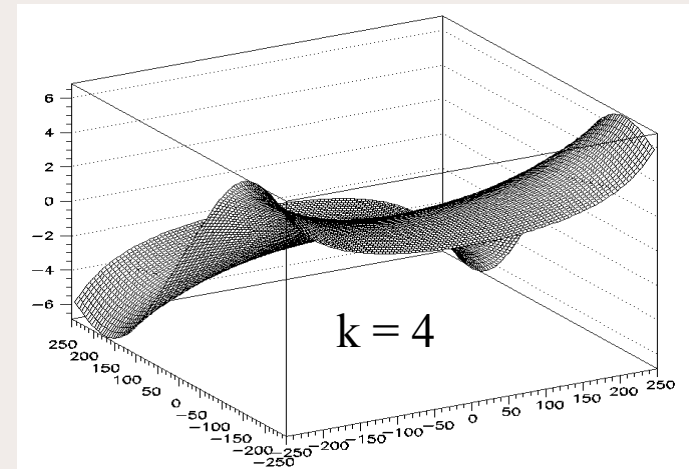
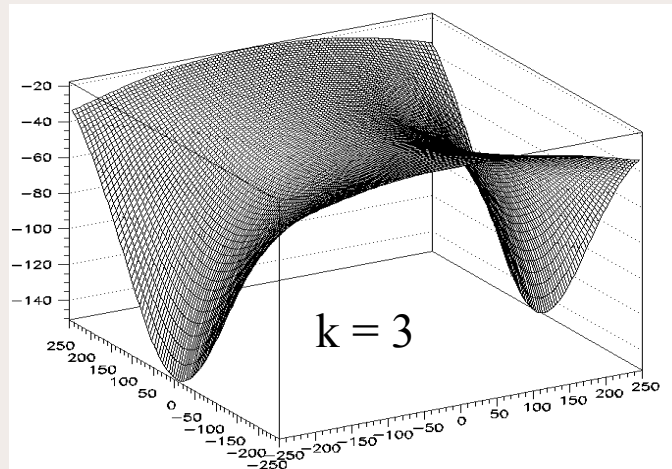
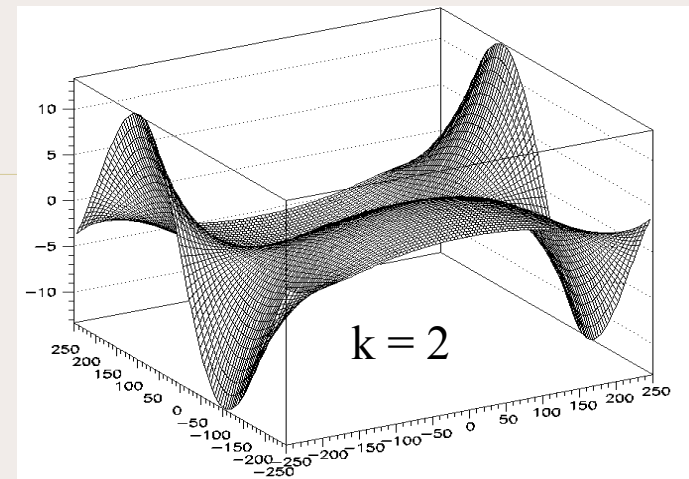
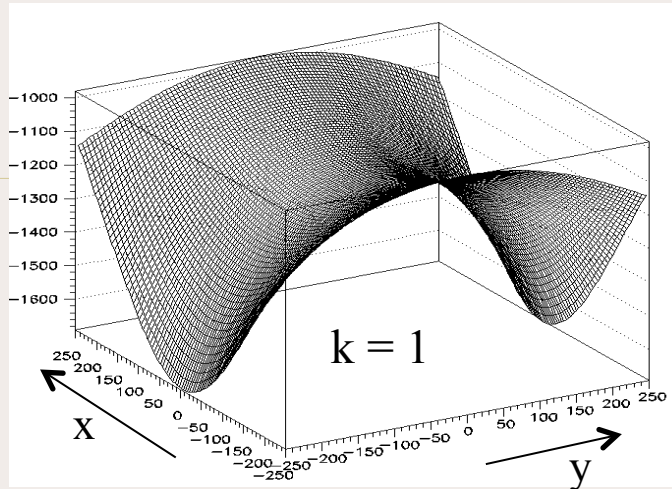
- tabulation on 100×100 or 25×25 positions in plane A within $\pm 0.25 \text{ m}$
- 20 values of q/p within $(-1/p_{\text{min}}, 1/p_{\text{min}})$
- for each one, 20×20 values of $\delta t_x, \delta t_y$ in $(-|\delta t|_{\text{max}}, |\delta t|_{\text{max}})$
- deviations from straight line using Runge-Kutta
- l.s. fit of the coefficients up to the wanted degree
- coefficient of global dependence on q/p : fit on the test sample

test sample:

- flat distribution in q/p in $(-1/p_{\text{min}}, 1/p_{\text{min}})$
- distribution in p_t : $\exp(-p_t/1 \text{ GeV}/c)$
- vertex: $\sigma_z = 60 \text{ mm}$, $\sigma_x = \sigma_y = 0.1 \text{ mm}$ (15 mm for K_S studies)

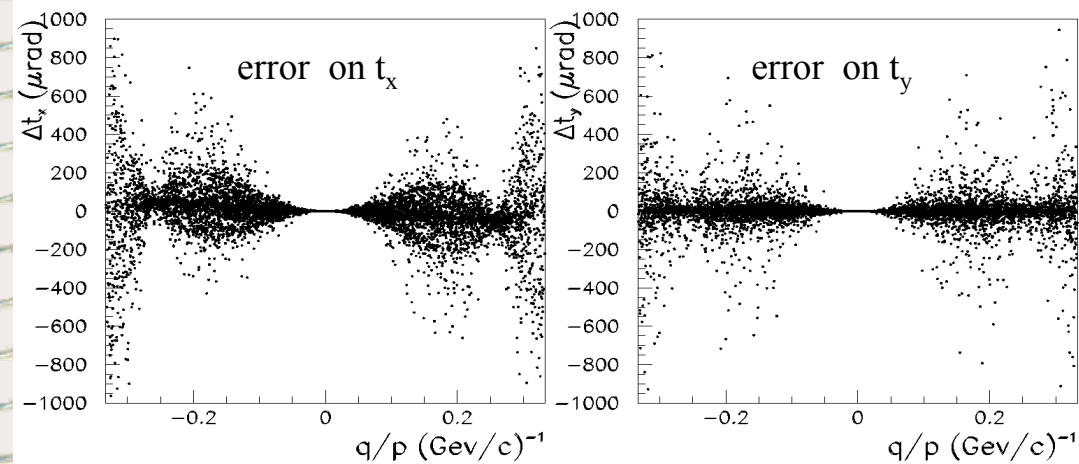
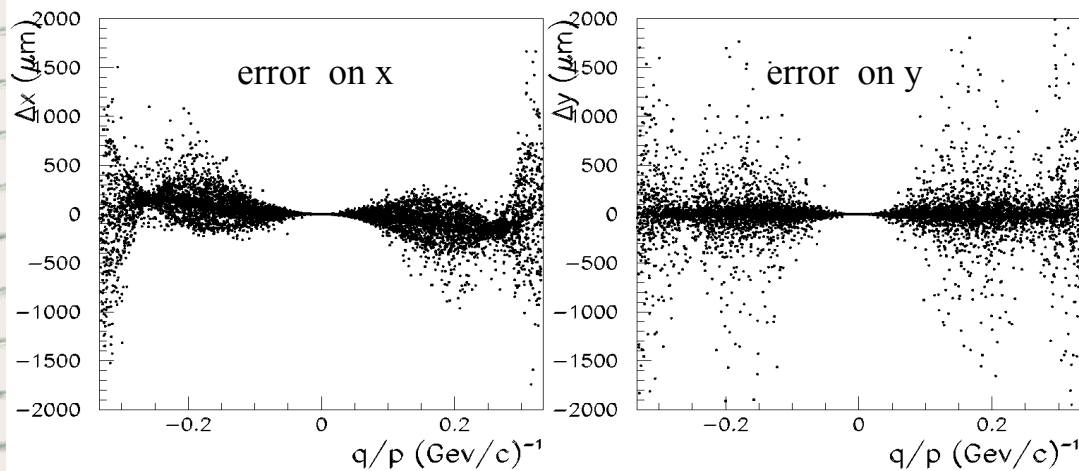
Remark: Δx expanded in $q/p \rightarrow q/p$ expanded in Δx
(prediction of momentum with initial segment + hit assignment)

exploration of tables (here: C_{00k}/p_{\min}^k for extrapolated x , in mm)



expectations for a submillimetric precision: we need at least k up to 4
problematic region: large y

first trial: degree 1 in $\delta t_x, \delta t_y$, 3 in q/p
100x100 tabulation in x, y (4-point interpolation)
applied to the test sample

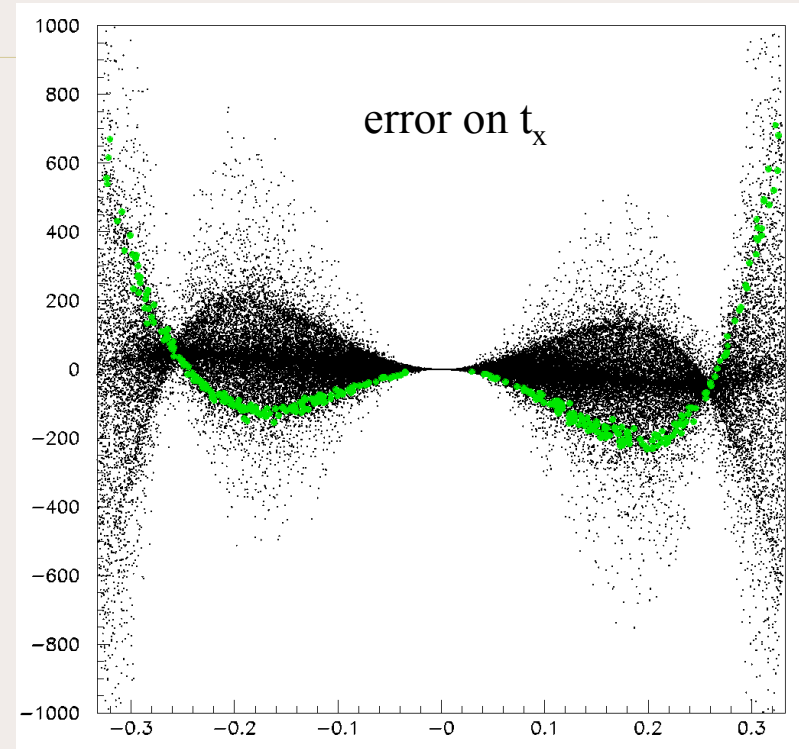
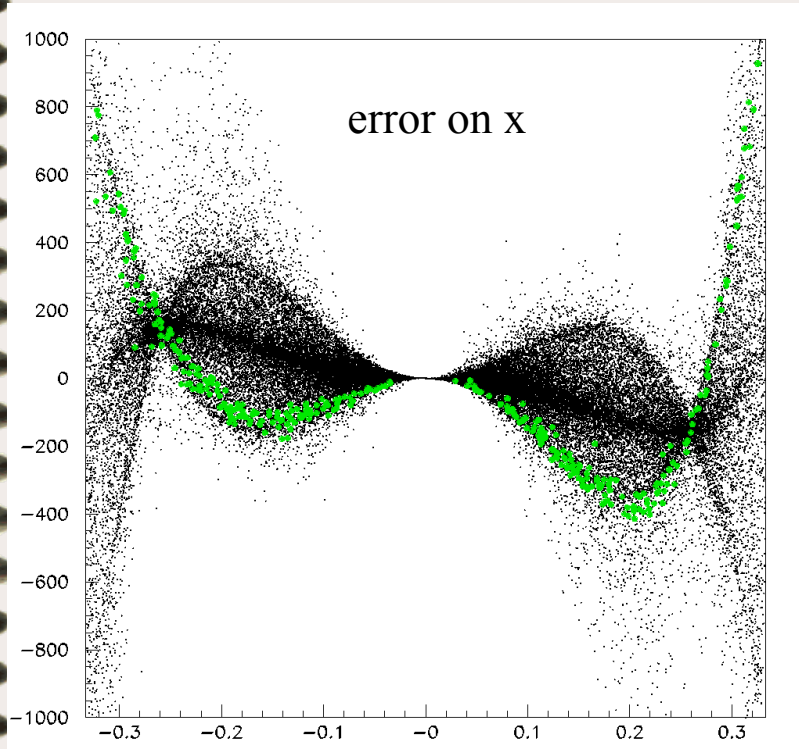


for most tracks:
error on position $\lesssim 0.2$ mm
error on direction $\lesssim 0.2$ mrad

may be good enough for some applications (especially in non-bending plane zy , where less precision is needed)

but: the structure of the plots suggests a possible improvement

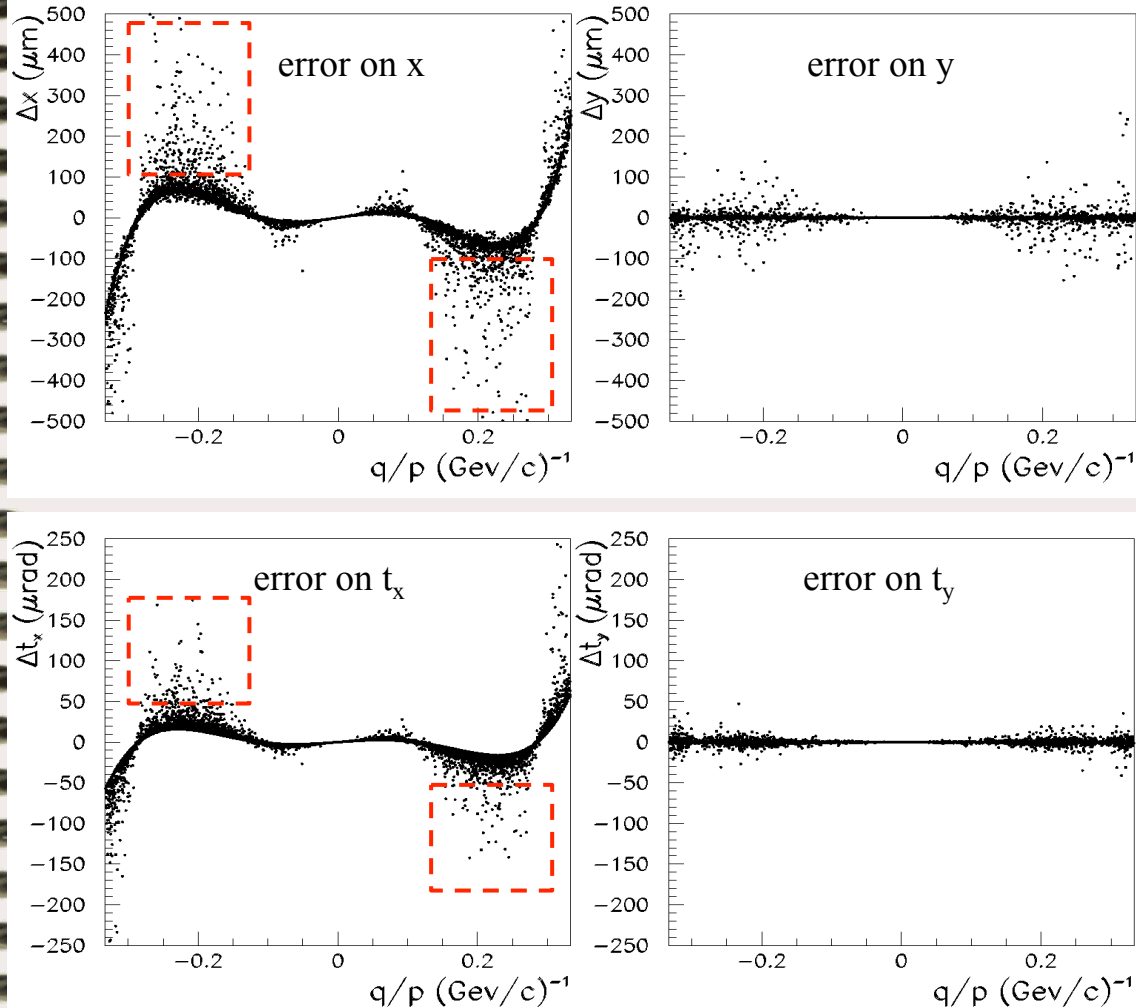
need for degree 4 in q/p ?



in green: x and y within (0.08, 0.12 m)

clear quartic dependence suggests a *tabulated* term in $(q/p)^4$

with degree 4 in q/p (tabulated in x,y)



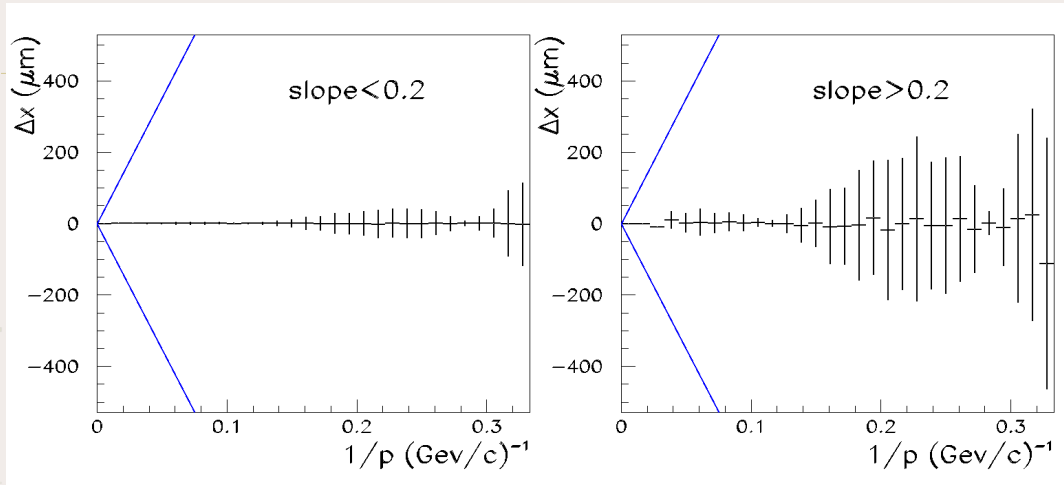
quite sufficient in zy plane

systematic dependence on q/p in zx plane suggests to add *global* corrections in $(q/p)^k$ (here with *odd* k because of the symmetry of the field)

but: outliers (red rectangles) will remain far away. Where do they come from ?

with global correction (degree 7 on q/p) for x, t_x

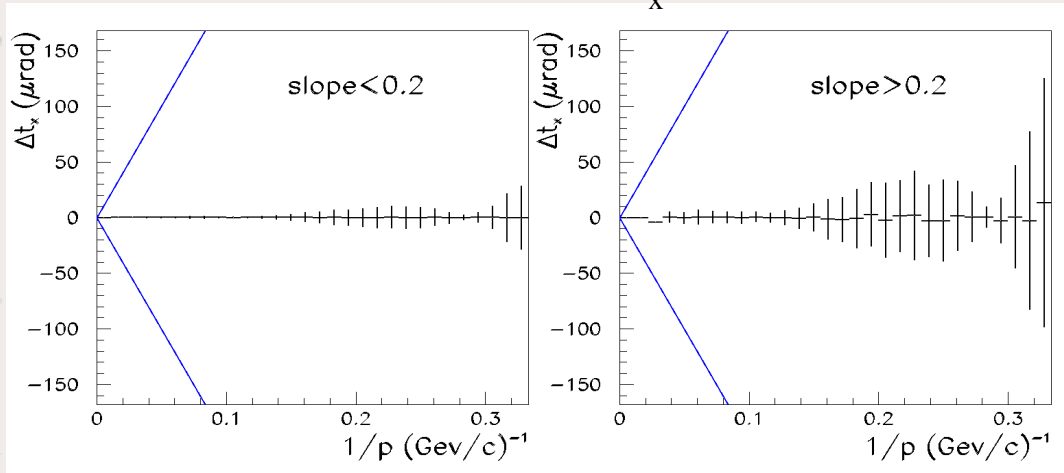
error on x



blue lines: effect of multiple scattering in air
(*measurement error does not matter here*)

precision is excellent in the central region

error on t_x



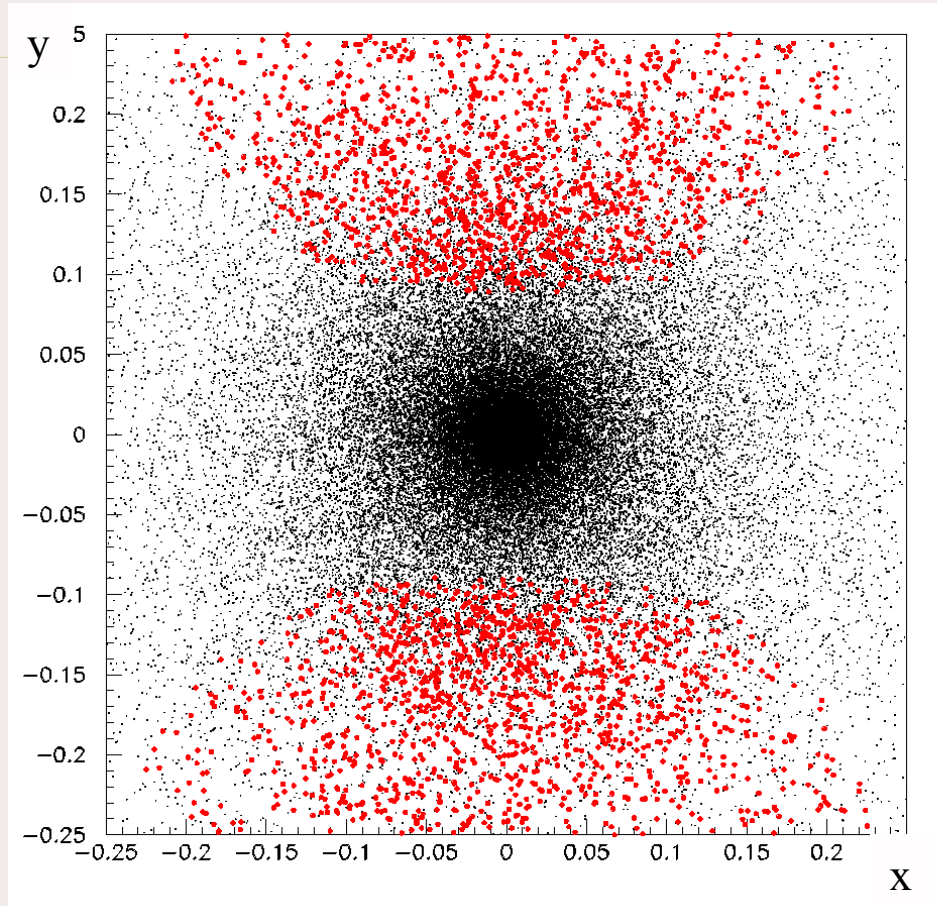
degradation for peripheral tracks is mainly due to outliers (*see possible solutions in next slide*)

warnings:

- real field
- Pmin

where are the outliers ?

(plot with more statistics)

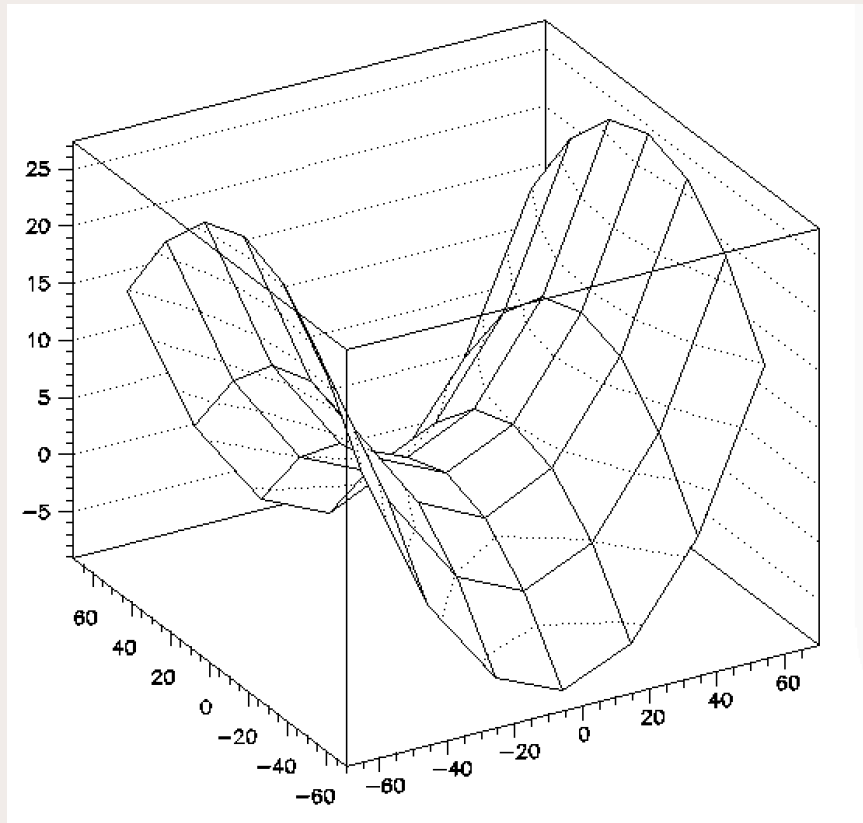


well defined region in the initial plane
(small fraction of the sample)
as expected from the C_{00k} plots

possible solutions:

- apply standard Runge-Kutta extrapolation in this region
- define subregions with different expansions in q/p
- find a simple parametrization in x,y for the additional corrections

errors due to interpolation (here: trying to use a 25x25 xy table)

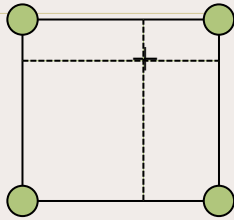


zoom on the central part of
the C_{001} plot (subtracting
value at 0,0):

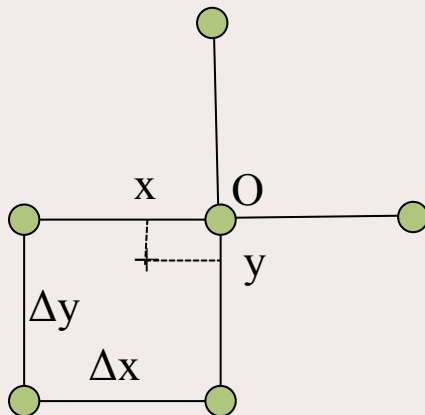
*simple interpolation from 4
(x,y) points may produce a
millimetric error*

can we try a second degree
approximation in x,y ?

interpolation from xy table: bilinear vs quadratic



bilinear interpolation using 4 neighbouring points:
amounts to define $a+bx+cy+dxy$ within the square
(exact value on the vertices of the rectangle, but biased if
terms in x^2 and/or y^2 are needed to match the shape)



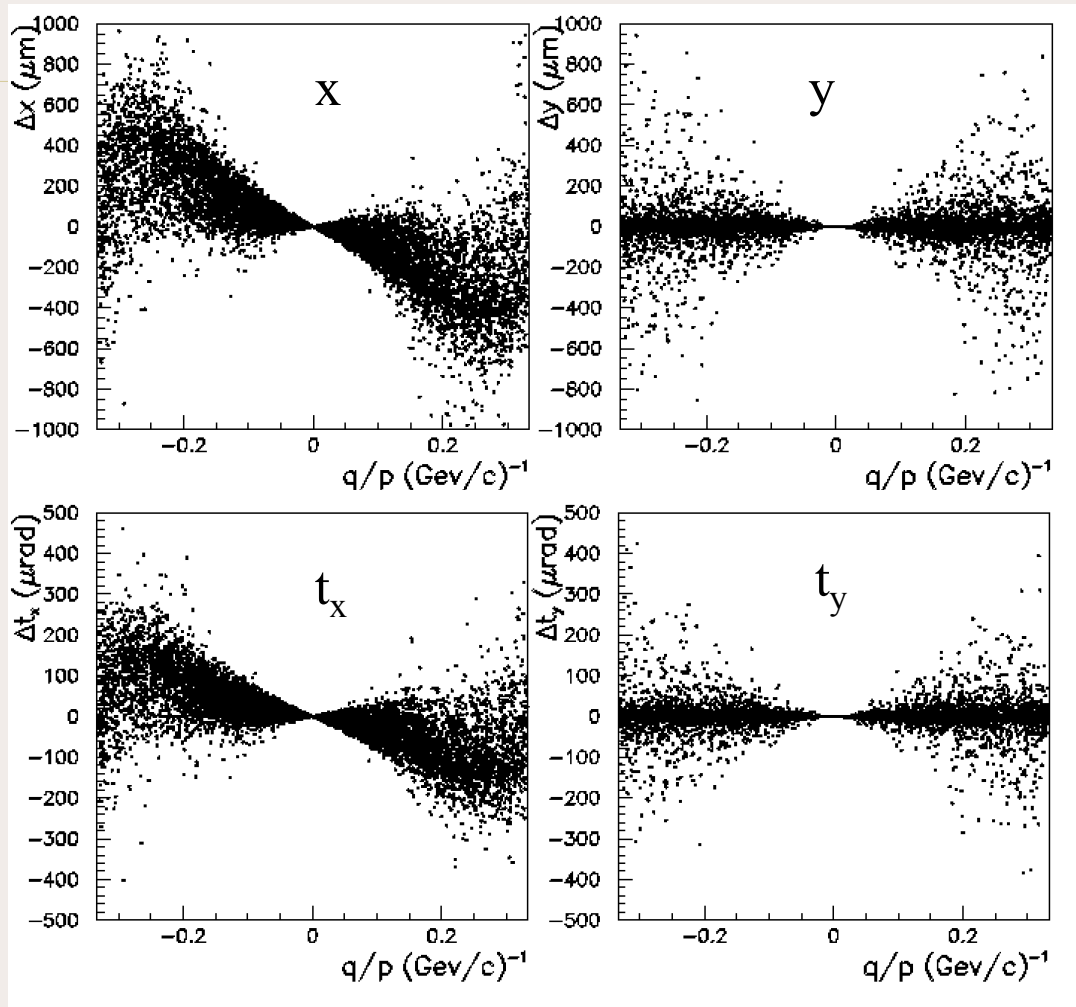
quadratic interpolation using 6 closest points to define
 $a+bx+cy+dxy+ex^2+fy^2$

may be defined as a linear combination of the 6 values
with $X = x/\Delta x$, $Y = y/\Delta y$, the « matrix » of coefficients may
be written in this configuration (X and Y in $[-0.5,0]$) as:

$$\begin{pmatrix} 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \frac{X}{2} \begin{pmatrix} 0 \\ -1 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \frac{Y}{2} \begin{pmatrix} 1 \\ 0 & 0 & 0 \\ 0 & -1 & 0 \end{pmatrix} + \frac{X^2}{2} \begin{pmatrix} 0 \\ 1 & -2 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \frac{Y^2}{2} \begin{pmatrix} 1 \\ 0 & -2 & 0 \\ 0 & 1 & 0 \end{pmatrix} + XY \begin{pmatrix} 0 \\ -1 & 1 & 0 \\ 1 & -1 & 0 \end{pmatrix}$$

more computations but better precision with reduced tables

using reduced tables (25x25 instead of 100x100)
with 4-point interpolation



~ millimetric error
(as expected)

no clear substructure

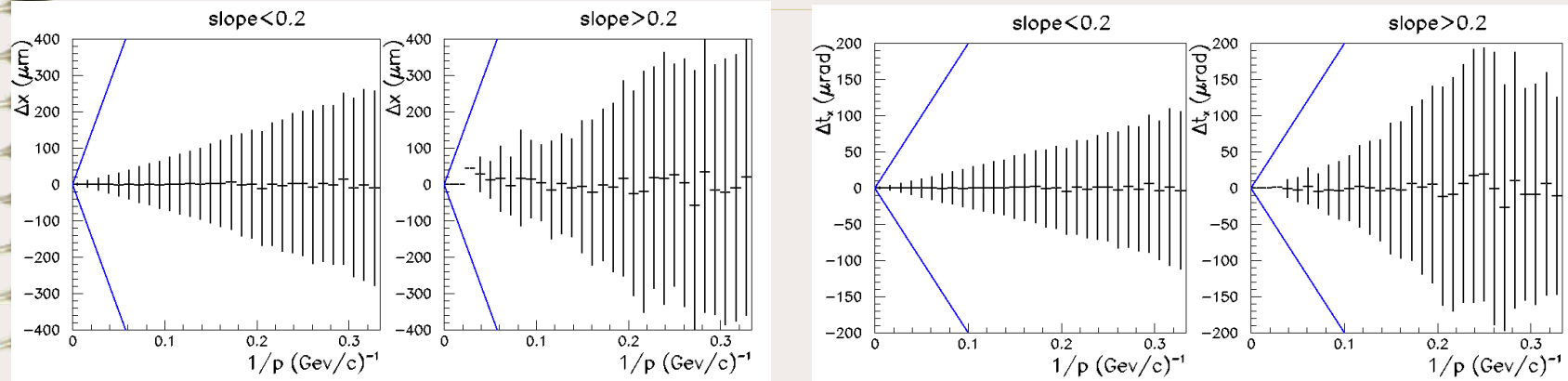
systematic bias in zx
plane (convexity effect):
compensated in average
by global coefficients in
 q/p expansion, but
dispersion remains

4-points/6-points results with reduced tables

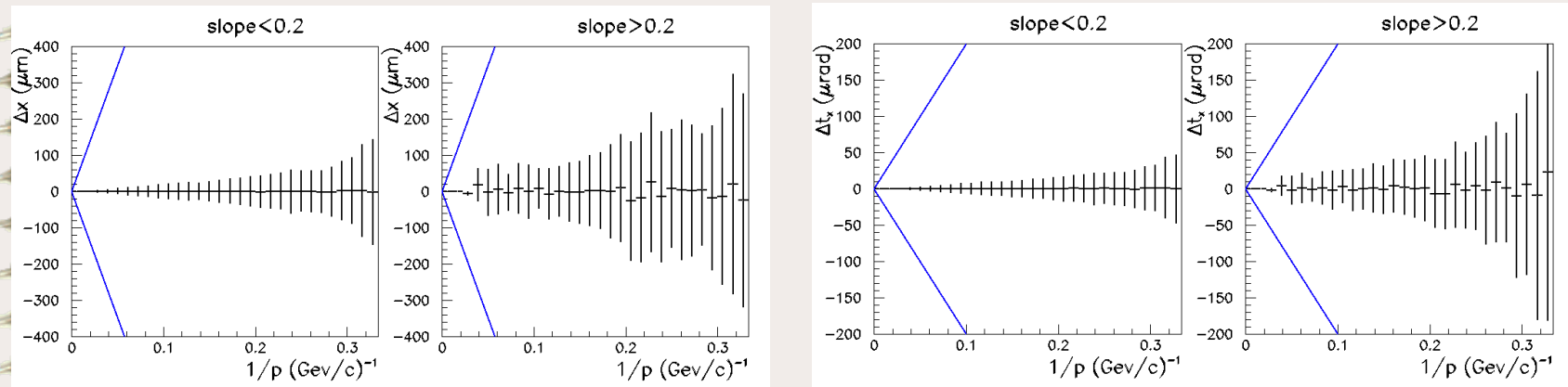
bilinear interpolation

error on x

error on t_x



quadratic interpolation



including larger impact parameters (e.g. K^0_S or Λ decay products)

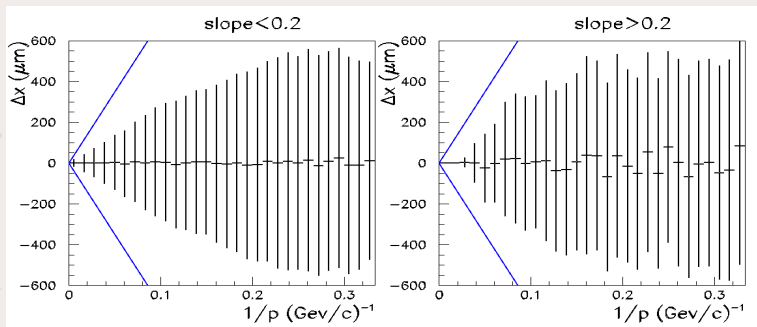
with $|\delta t|_{\max} = 0.01$, the coefficients of degree 2 in $\delta t_x, \delta t_y$ are small:

no significant difference when applied to the test sample

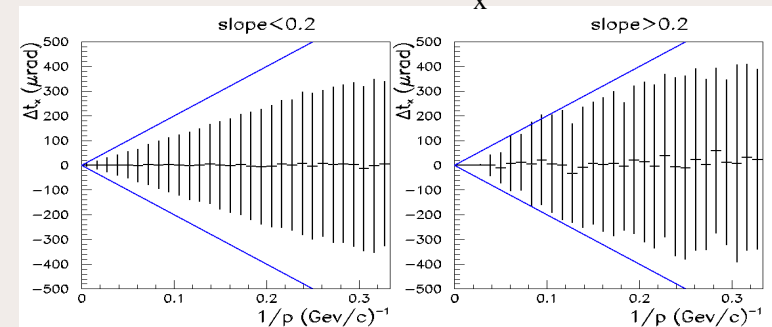
here we set $|\delta t|_{\max} = 0.03$ and $\sigma_x = \sigma_y = 15$ mm in the test sample

table: 25×25 with quadratic interpolation

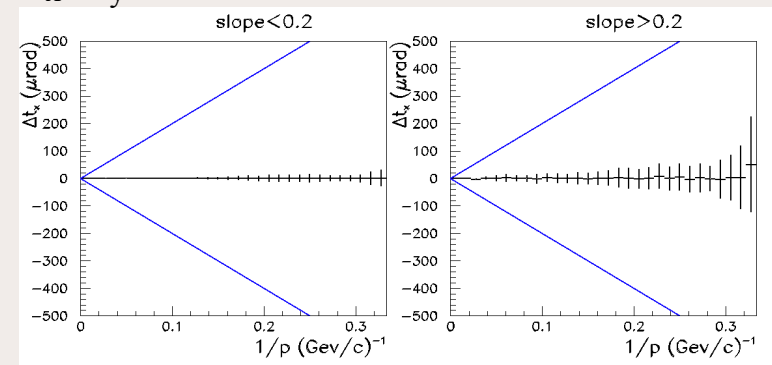
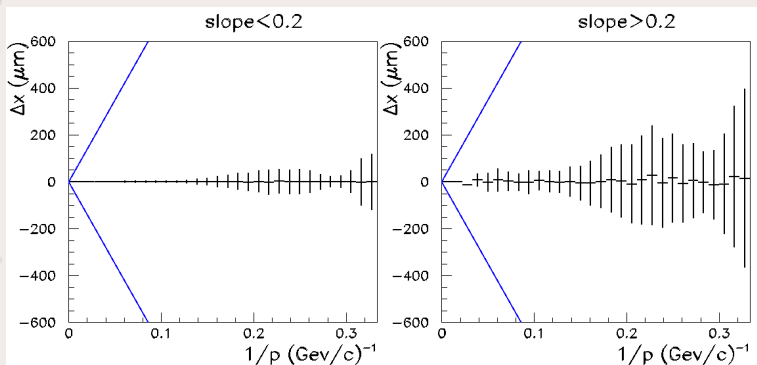
error on x degree 1 in $\delta t_x, \delta t_y$



error on t_x



degree 2 in $\delta t_x, \delta t_y$



much better (and sufficient for applications)

technical issues

- **polynomial of high degree fitted on equidistant points:**
the residuals are large on the ends (and diverge rapidly when going beyond); here the fit is done on points at $(-0.9, -0.7 \dots 0.7, 0.9)/p_{\min}$ so it is actually constrained for $p > p_{\min}/0.9$
the result is often « too good » at high p compared to low p . It may be possible to compensate this effect by setting more fitting points at large $1/p$; it may be advantageous to chose p_{\min} lower than the value wanted for applications
- **linking extrapolations between successive planes:**
if the trajectory is split in several steps (e.g. for a Kalman Filter), it may be easier to find separately solutions with lower degrees. However, the errors on x and t_x are tightly correlated (similarly for y and t_y), so there is a cumulative effect: even if each step fulfills the quality criteria, their combination may be unacceptable.
- **accessing big tables vs making many operations:**
to be discussed with experts

summary and comments

- within a restricted region of the 5D phase space of trajectories (tracks of physical interest), it is possible to obtain a fast and precise extrapolation between two predefined surfaces, through a polynomial expansion with tabulated coefficients. These tables provide *also* the jacobian matrix.
- there are many tunable « handles » in the machinery (degrees of expansion, fitting ranges, region within the acceptance). It may be tailored for a specific purpose in a specific setup (done for LHCb, *see talk by S. Stemmler*)
- there may be « bad » regions in the phase space: depending on the population, one can make a local refinement, or apply the standard Runge-Kutta method. **In any case, one can know *a priori* if a state is in a bad region**
- a compromise has to be found between the size of the tables and the precision of the interpolation.
- for large p , in a central region with nearly parallel field lines, convenient parametrizations with less coefficients may be used (*see talk by S. Stemmler*)