

The track finding algorithm of the Belle II vertex detectors

T. Lück

on behalf of the Belle II tracking group

Connecting the Dots / Intelligent Trackers 2017
LAL-Orsay (France)

March 8, 2017



UNIVERSITÀ DI PISA

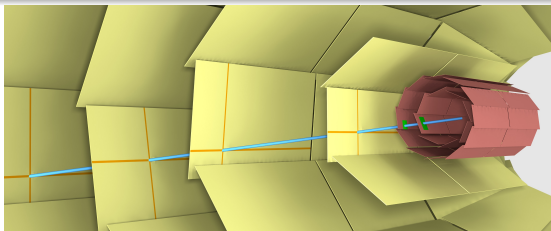


- Introduction
- The Belle II vertex detector
- Concept of the track finding at Belle II
- Implementation at Belle II
- Preliminary results
- Summary

- Belle II multipurpose detector operated at the SuperKEKB accelerator
- SuperKEKB will deliver a peak luminosity of $8 \times 10^{35} \text{cm}^{-2} \text{s}^{-1}$
- electrons and positrons will be collided at a center of mass energy corresponding to $m(\Upsilon(4S)) = 10.58 \text{GeV}/c^2$
- aims to test the standard model with unprecedented precision
- on average 11 tracks in a $\Upsilon(4S)$ event
- tracking devices:
 - 2 layers of pixel detectors (PXD) + 4 layers of double sided silicon strip detectors (SVD)
 - central drift chamber (not part of this talk)
- reliable track finding is crucial for the success of the Belle II experiment

Track finding used for data reduction

- Belle II has two trigger stages:
 - hardware based trigger L1
 - High Level Trigger (HLT): software based trigger
- track finding algorithm will be used on the HLT to reduce the amount of data read out by the PXD
 - find tracks in the SVD
 - extrapolate found tracks to the PXD
 - define Regions Of Interest (ROI) on PXD sensors
 - read only PXD - hits found in ROI (data reduction factor $\approx 10\%$)



The Belle II inner Vertex Detectors

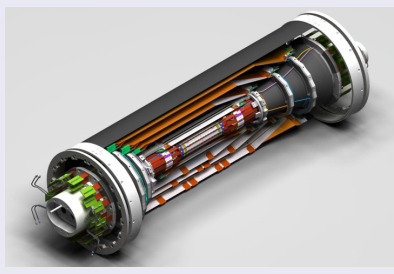
Silicon Vertex Detector (SVD)

- 4 layers of Double-sided Silicon Strip Detectors (DSSD) at radii of 38, 80, 115, and 140 mm from the interaction point
- $17^\circ < \theta < 150^\circ$ coverage in polar angle

Pixel Detector (PXD)

- two layers of DEPFET pixel detectors at radii of 14 and 22 mm

Computer rendering of the Belle II vertex detectors (SVD+PXD)



Mechanical mockup of the PXD



- on average an $\Upsilon(4S)$ event has 11 low momentum tracks
- due to machine background largely increased number of space points
- MC studies predict 318 space points for the first layer of the SVD (234 from bkg alone)
- for the whole SVD a total of 721 space points (535 from bkg alone)
- needed: fast and efficient way to reduce the number of combinations
- adopted the sector on sensor concept proposed by R. Frühwirth et. al.

$\Upsilon(4S)$ event with and without background

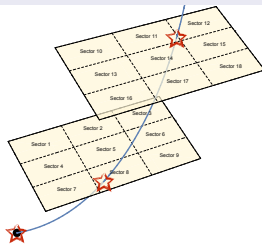
Case	$\Upsilon(4S)$ -only	BG-only	$\Upsilon(4S) + \text{BG}$	$\Upsilon(4S) + 2 \times \text{BG}$
L3 strips u/v	49.2/36.7	260.0/121.7	308.1/158.0	562.2/278.8
L3 clusters u/v	11.8/11.8	39.0/37.9	50.3/49.3	87.0/86.1
L3 SPs	26.1	233.9	318.0	791.0
L4 strips u/v	39.4/29.1	120.3/61.2	159.1/90.1	277.8/150.6
L4 clusters u/v	12.7/12.6	29.9/26.7	42.5/39.2	71.8/65.3
L4 SPs	22.5	100.5	143.1	320.4
L5 strips u/v	37.3/28.5	122.7/67.2	160.1/95.8	282.7/162.9
L5 clusters u/v	12.3/12.1	35.0/30.5	47.3/42.7	82.0/72.9
L5 SPs	19.2	99.3	132.3	299.3
L6 strips u/v	38.3/28.6	134.6/76.8	172.9/105.4	307.1/182.0
L6 clusters u/v	12.4/12.2	42.1/36.3	54.4/48.5	96.2/84.5
L6 SPs	17.0	100.8	127.9	283.1
Average strips/layer u/v	164.3/122.8	159.4/81.7	200.1/112.3	1429.8/774.4
Total clusters u/v	49.2/48.7	146.0/131.3	194.4/179.6	337.1/308.9
Total SPs	84.8	534.6	721.3	1693.8
	Signal	Noise		

- ◆ SP : Space Points. “u” is the local r ϕ direction. “v” is the local z direction.
- ◆ The combinatorial problem is dominated by background hits

The sector on sensor concept

- divide sensor into rectangular sectors
- first step track finding: combine two space points (SP) to form a *segment*
- SP combinations searched only on two sectors which are *friends*
- two sectors are friends if during training same MC particle passes both sectors

Illustration of the sector concept



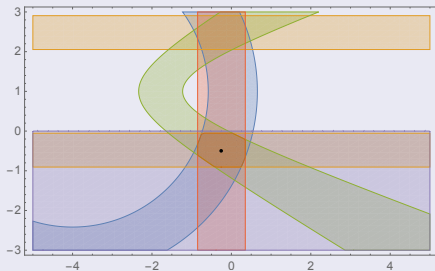
Filtering of space point combinations

- simple geometric cuts are used to accept/reject segments and tracklets (combinations of segments):
 - 2 SP: e.g. direction of the segment, distance between the two space points
 - 3 SP: angle between the two segments, transverse momentum
 - 4 SP: difference in transverse momentum between the first three SP and the last three SP, zig zag
- simulation is used to obtain cut values (upper / lower bound)
- customized set of cut values provided:
 - i.e. a separate set of cut values for each occurring sector combinations is given

Illustration of the filtering of two SP combinations

- shown is the effect of various cuts applied on 2-hit combinations
- each coloured area presents the selected region by the respective cut

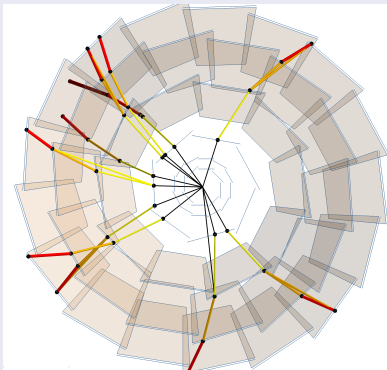
Out[59]=



- Cut(Distance3D)
- Cut(Distance2D)
- Cut(SlopeRZ)
- Cut(Distance1DZ)
- Cut(CosXY)
- AllCuts

Connecting the Dots

- Cellular automaton collects segments and connects them to track candidates
- virtual IP is used to increase the number of space points



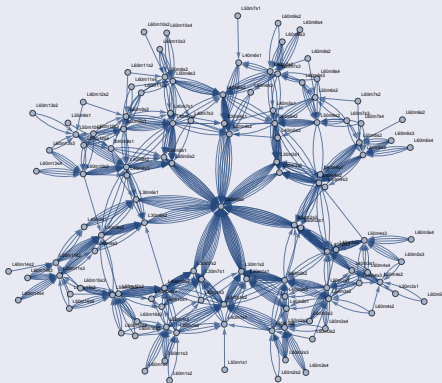
Overlap removal

- the cellular automaton provides a set of potentially overlapping track candidates
 - share at least one common space point
- these are used to construct a Hopfield neural network
- input to the network:
 - connection between track candidates (shared space points)
 - a quality indicator for each track candidate (e.g. a circle fit)
- output of the Hopfield network is a unique (non overlapping) set of track candidates

Sector Map

- store friend relations
- needs to be trained on simulated events to learn the allowed connections between sectors
- store a set of individual cuts for each sector combination
- adapts to geometry during the training
- currently uses 13MB of disc space, will be stored in the Belle II condition database

Graphical representation of a sector map for the Belle II geometry



Current status of the implementation

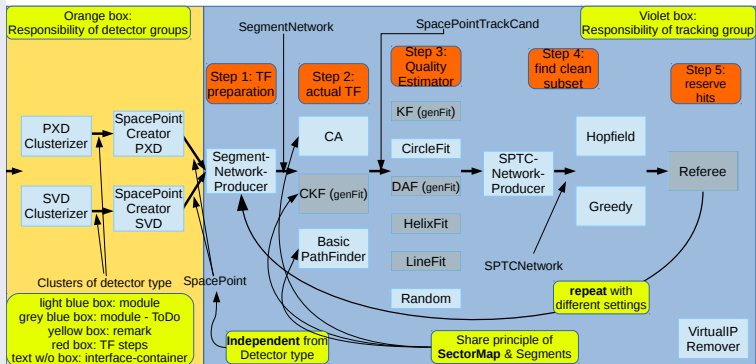
VXD Track Finder version 1 (VXDTFv1)

- implemented and working stably
- some issues (hard to maintain, main developer left)

VXD Track Finder version 2 (VXDTFv2)

- currently under development
- fix the issues with version 1:
 - increase modularity
 - facilitate maintainability
 - facilitate adding of new features
 - facilitate exchanging of features
- some features not yet implemented (e.g. multiple passes)

Data flow of the VXDTF version 2



- space point creation is provided by the different sub detector reconstruction software
- each reconstruction step is (at least) one separate module in the code: better maintainability, easier to switch out parts, easier to add new features

(Very) preliminary results in the following

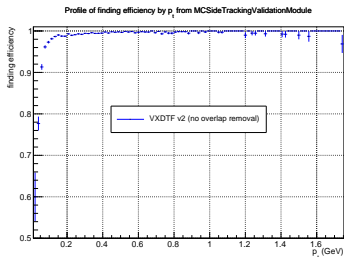
- VXDTFv2 trained on 900k $\Upsilon(4S)$ - events (no background)
- 4x4 sectors per sensor (same as in VXDTF v1)
- no PXD information used (same for VXDTF v1)
- tested: 10 k $\Upsilon(4S)$ -events (no bkg., differ from trainings sample)

NOTE: when comparing VXDTFv1 with VXDTFv2

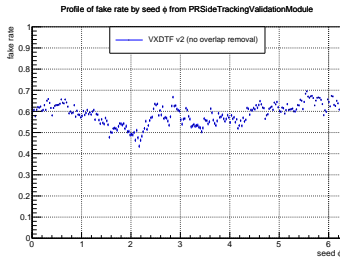
- VXDTFv1 has multiple passes:
 - three different momentum ranges ($35 < p_T \leq 100\text{MeV}$, $100 < p_T \leq 400\text{MeV}$, $400\text{MeV} < p_T$)
 - specialization of training
 - better ability to reject false combinations
 - less combinatorial background per pass
- VXDTFv2 single pass only (multipass not implemented yet)
- VXDTFv1 uses high occupancy cut (i.e. more than 5000 overlapping TC or more than 5500 segments event will be skipped). VXDTFv2 not.

- pattern recognition alone (without overlap removal) is almost 100% efficient over a wide momentum range
- but without overlap removal high fake rate observed
- normalized to tracks found using MC information (theoretical trackable particles)

Track finding efficiency for $\Upsilon(4S)$ MC events (overlap not removed)

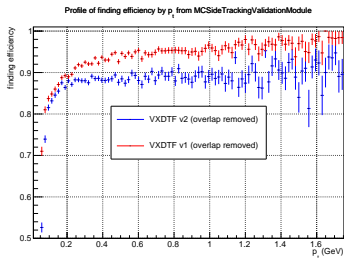


Fraction of fake tracks for $\Upsilon(4S)$ MC events (overlap not removed)

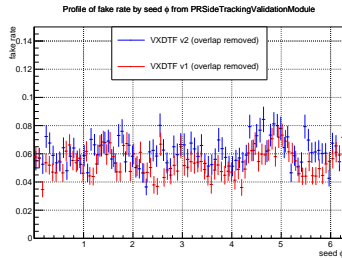


- at present performance of VXDTFv2 is slightly decreased compared to VXDTFv1
- most track candidates lost in overlap removal
- expected to improve with new track quality estimators and introduction of multiple passes

Track finding efficiency for $\Upsilon(4S)$ MC events (overlap removed)



Fraction of fake tracks for $\Upsilon(4S)$ MC events (overlap removed)

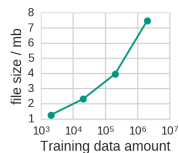
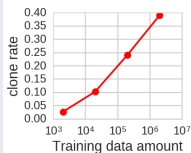
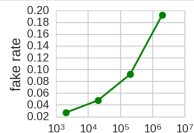
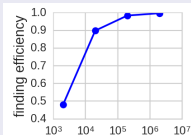
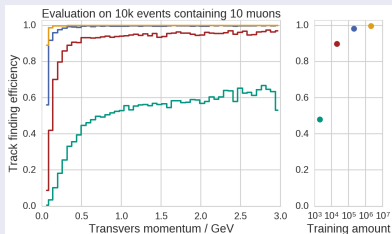


How to train a sector map?

- training the sector map is crucial for optimal performance
- many things to take into account and the optimal way yet unclear
- how many sectors per sensor, use different amount of sectors in different regions of the detector?
- selection of trainings sample:
 - $\Upsilon(4S)$ events,
 - particle gun equally distributed in phase space
 - mix of both ... ?
- use multiple passes? How many? Which momentum ranges?
- how many trainings events, too many increase the combinatorics, too few results in drop of efficiency
- use all tracks for training or only those which are "usable" for physics (i.e. give good estimate for track parameters)

- studies to optimize the training of the sector map
- performed in very clean environment (events 10 muons generated by particle gun, flat probability in momentum)

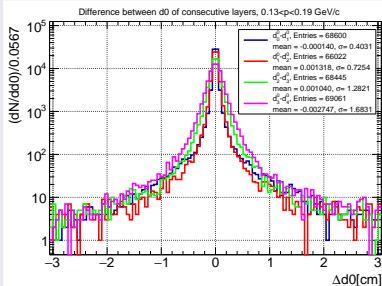
Performance of the VXD-TF2 as a function of the amount of data used in the training (overlap not removed)



Study new Ansätze to select tracks for training of the sector map

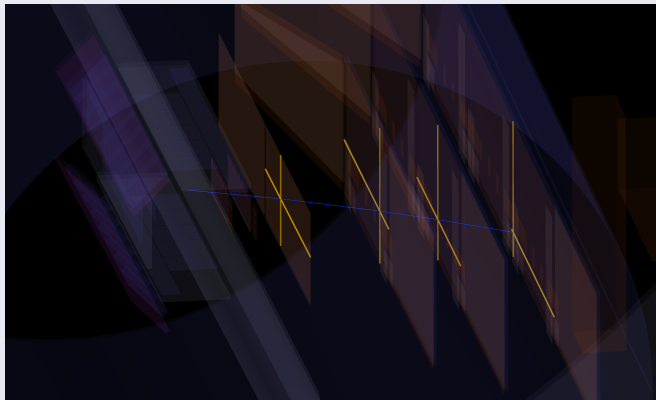
- scattering on material increases the connectivity of the sector map and thus decreases ability to reject bad SP combinations
- currently investigated: select tracks for training which undergone no hard scattering
- study change of track parameters between two hits on simulated events
- select tracks without drastic changes in the track parameter

As example the difference of the track parameter d_0 between two subsequent hits (d_0 : impact parameter of the helix in x-y-plane at closest approach to IP)



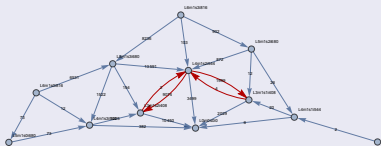
- 13th Feb - 5th Mar: test a part of the SVD+PXD in electron beam at DESY
- successful test VXDTF under data taking conditions (on HLT and offline reconstruction), both VXDTFv1 and prototype of VXDTFv2

Event display for a reconstructed track

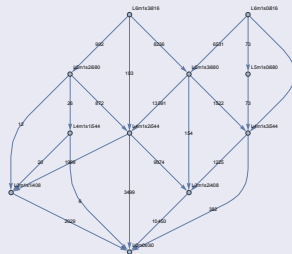


- problem: cycles in the sector map
- currently under investigation
- cycles can be removed by requiring more than 5 connections between two sectors

Graphical illustration of a sector map for the test beam geometry



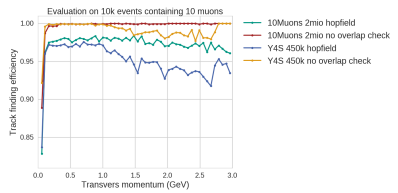
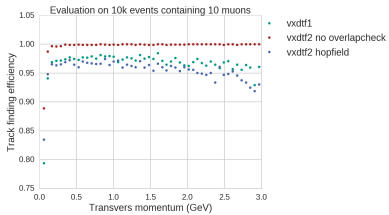
Same as to the left, but require more than 5 connections



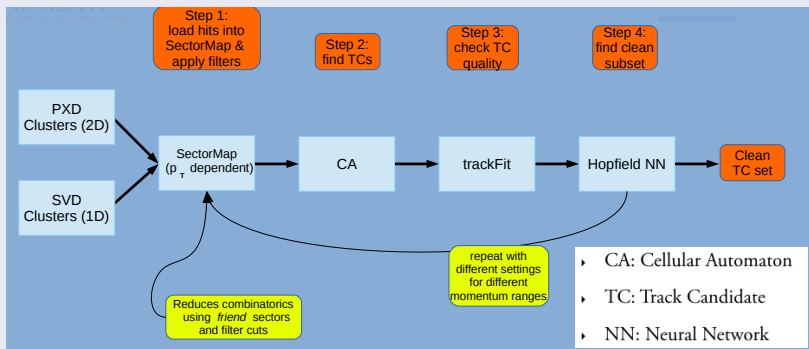
Summary

- track finding with the Belle II vertex detectors
- sector on sensor concept
- VXDTFv1: already implemented and working
- VXDTFv2: currently implemented to improve version 1
- tested track finder (version 1 and version 2) on a test beam at DESY

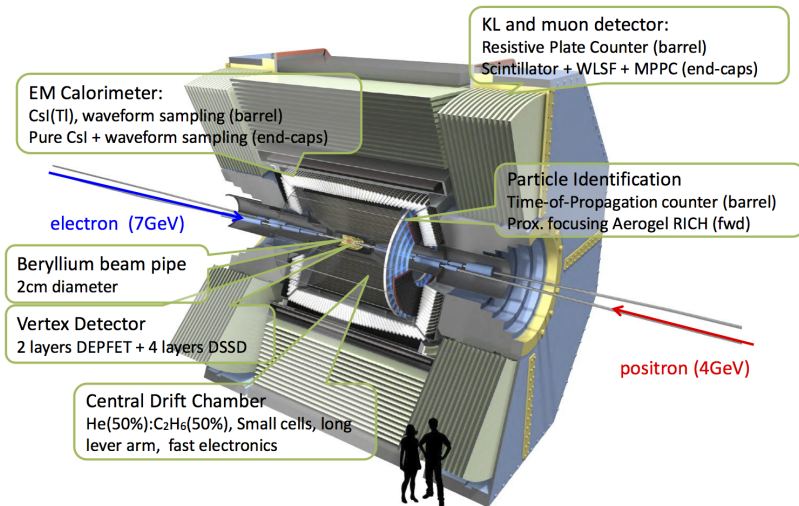
BACKUP



Data flow of the VXDTF version 1



Belle II Detector



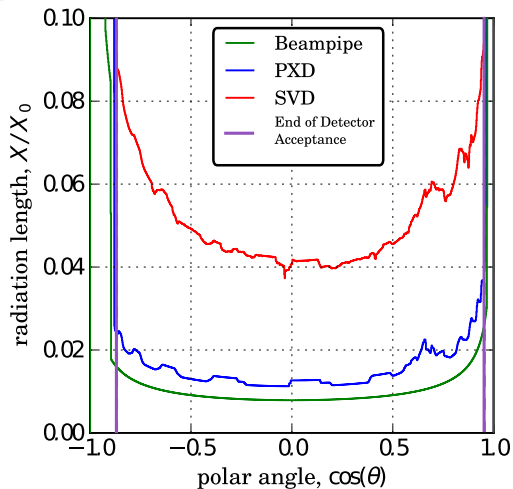


Figure 2.10: The cumulative material budget of the Beampipe, the **PXD** and the **SVD**. The violet vertical lines mark the end of the acceptance region. Plot courtesy of Martin Ritter and the **Belle II** Collaboration.

Schematic view of the low momentum track finder in Belle II

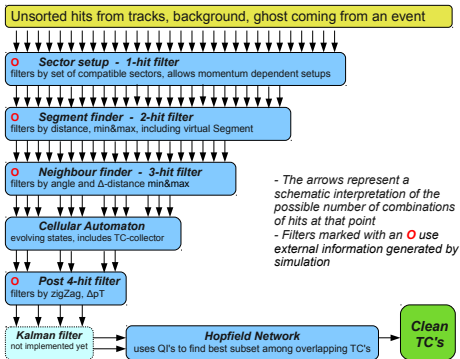


Figure 3.2.: A schematic view representing the parts of the track finder and their use in reducing combinatorics