# **ESTIMATING UNCERTAINTIES: MONTE CARLO vs HESSIAN**

### STEFANO FORTE MILAN UNIVERSITY & INFN



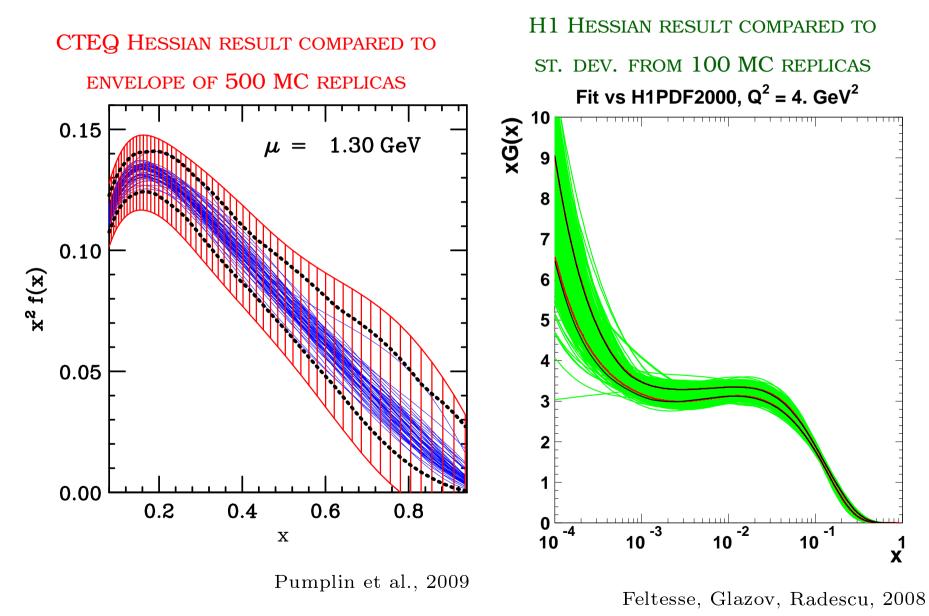
PDF4LHC WORKSHOP



CERN, MAY 29, 2009

### A PUZZLE?

#### GLUON DISTRIBUTION



### HESSIAN ERROR ESTIMATES

#### THE STANDARD METHOD

OBSERVABLE X DEPENDING ON PARAMETERS  $\vec{z}$ : (LINEAR ERROR PROPAGATION)  $X(\vec{z}) \approx X_0 + z_i \partial_i X(\vec{z})$  ASSUMING MOST LIKELY VALUE AT  $\vec{z} = 0$ VARIANCE:  $\sigma_X^2 = \sigma_{ij} \partial_i X \partial_j X$ ,

 $\sigma_{ij} \Rightarrow$  COVARIANCE MATRIX IN PARAMETER SPACE

MAXIMUM LIKELIHOOD: COVARIANCE  $\Leftrightarrow$  HESSIAN  $\sigma_{ij} = \partial_i \partial_j \chi^2$  EVALUATED AT MIN. OF  $\chi^2$ DIAGONALIZATION: CHOOSE  $z_i$  AS EIGENVECTORS OF  $\sigma_{ij}$  WITH UNIT EIGENVALUES  $\sigma_X^2 = |\vec{\nabla}X|^2$  (LENGTH OF GRADIENT)

THE ENVELOPE METHOD

ONE SIGMA CONTOUR IN PARAMETER SPACE:

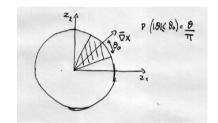
TWO PARAMETERS  $X - X_0 = \partial_1 X \cos \theta + \partial_2 X \sin \theta$  n parameters  $X - X_0 = \vec{n} \cdot \vec{\nabla} X$ ; ( $\vec{n}$  unit vector in parameter space) HALF-WIDTH OF THE ENVELOPE:  $Max(X) = |\vec{\nabla} X| = \sigma_X$  (Max if  $\vec{n} \& \vec{\nabla} X$  paral.)  $\Rightarrow$  ENVELOPE & STANDARD DEVIATION COINCIDE

### THE "HESSIAN MONTE CARLO"

Q:IF ONE PICKS REPLICAS AT RANDOM ON THE ONE-SIGMA CONTOUR WHAT IS THE CHANCE OF "FILLING" THE ENVELOPE? A:DETERMINE THE PROBABILITY FOR AT LEAST ONE REPLICA TO BE WITHIN ANGLE  $\theta$  OF DIRECTION  $\vec{\nabla}X$  OF MAX

TWO PARAMETERS: ONE REPLICA WITH  $\theta < \theta_0 \Rightarrow P(2, 1 : \theta_0) = \frac{\theta_0}{\pi}$ PROBABILITY OF MAX(ENVELOPE)= $\sigma_X \cos \theta_0$ 

 $\Rightarrow$  All *n* REPLICAS HAVE  $\theta > \theta_0 \Rightarrow P(2, n; \theta_0) = \left(1 - \frac{\theta_0}{\pi}\right)^n$ 



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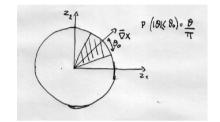
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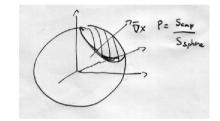
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$$\Rightarrow P(d, 1:\theta_0) = \frac{\Gamma\left(\frac{d}{2}\right)}{(d-1)\sqrt{\pi}\Gamma\left(\frac{d-1}{2}\right)} \theta_0^{d-1} (1+O(\theta_0)) \approx \frac{\theta_0^{d-1}}{\sqrt{2\pi d}}$$

PROBABILITY OF MAX(ENVELOPE)= $\sigma_X \cos \theta_0$ 

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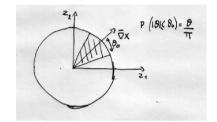
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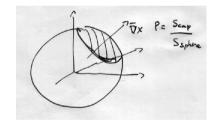
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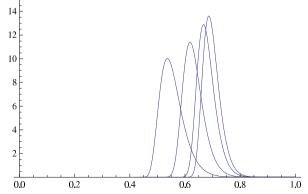
PROBABILITY FOR THE WIDTH OF THE ENVELOPE

TO BE SMALLER BY A FACTOR R THAN THE STANDARD DEVIATION  $\sigma_X$ PLOTTED VS R FOR

d = 23 parameters and n = 10, 100, 500, 1000 replicas







PARAMETER SPACE:

OBSERVABLE X DEPENDS ON PARAMETERS  $\vec{z}$ VARIANCE:  $\sigma_X^2 = \langle X^2 \rangle - \langle X \rangle^2$ AVERAGES:  $\langle X \rangle = \int d^d z X(\vec{z}) P(\vec{z})$ , WITH  $P(\vec{z}) \Rightarrow$  PROBABILITY DISTN. OF PARAMETER VALUES & INTEGRAL PERFORMED BY MONTE CARLO SAMPLING HOW MANY REPLICAS DOES ONE NEED?

PARAMETER SPACE: NOT ADVISABLE

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#### DATA SPACE

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converges to true average with standard dev.  $\frac{\sigma}{\sqrt{n}}$ 10 Replicas enough for  $\frac{\sigma}{3}$  accuracy

PARAMETER SPACE: NOT ADVISABLE

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ALL OTHER PARMS  $\Rightarrow$  FLAT DIRECTIONS

AVERAGES:  $\langle X \rangle = \int dz_1 X(\vec{z}) P(z_1)$ 

HOW MANY REPLICAS DOES ONE NEED? ONE-DIMENSIONAL AVERAGE OF n REPLICAS

CONVERGES TO TRUE AVERAGE WITH STANDARD DEV.  $\frac{\sigma}{\sqrt{n}}$ 

10 REPLICAS ENOUGH FOR  $\frac{\sigma}{3}$  ACCURACY

- Q: HOW IS IT DONE IN PRACTICE?
- A: CHOOSE REPLICAS OF THE DATA, DISTRIBUTED AS THE DATA

MANY OBSERVABLES

IN GLOBAL PARTON FITS, THE NUMBER OF OBSERVABLES (DATA) IS LARGE BUT THEY ARE NOT COMPLETELY INDEPENDENT! Q: HOW MANY REPLICAS DOES ONE NEED? AT WORST, COULD BE VERY LARGE >  $N_{dat}$ A: JUST TRY. COMPUTE AVERAGES, VARIANCES, COVARIANCES FROM MC SAMPLE & ENLARGE SAMPLE UNTIL THEY AGREE WITH THOSE OF DATA

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NNPDF1.2 dataset,  $N_{\rm dat} \sim 3500$ 

**REPLICA AVERAGES** 

VS. CENTRAL VALUES

REPLICA STANDARD DEV.

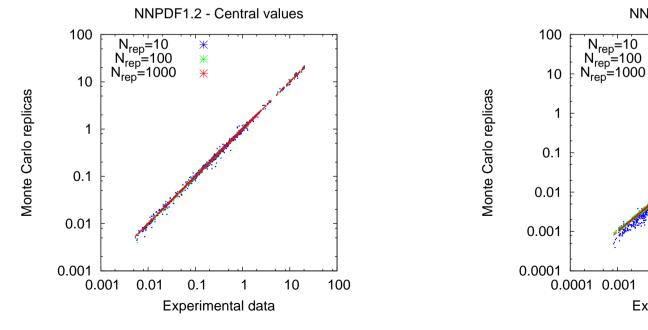
**VS. UNCERTAINTIES** 

0.01

Experimental data

0.1

10



NNPDF1.2 - Errors



### NORMALIZATION UNCERTAINTIES

#### HESSIAN

• FIRST OPTION (MSTW08) RESCALE ALL DATA VALUES & ST. DEVNS. BY FACTOR f & TREAT f AS A FIT PARM WITH A PENALTY TERM SUCH AS

$$\chi_f^2 = \frac{(f-1)^2}{\sigma_f^2}$$

- SECOND OPTION TREAT NORMALIZATION AS AN OFFSET UNCERTAINTY  $x = x_{true} + \sigma_0$ ADD OFFSET UNCERTAINTY AS A CORRELATED UNCERTAINTY TO COVARIANCE MATRIX  $\operatorname{cov}_{ij} = \left(\sum_{k=1}^{N_{\mathrm{sys}}} \sigma_{i,k} \sigma_{j,k} + \delta_{ij} \sigma_{i,t}\right)$
- WRONG OPTIONS RESCALE DATA VALUES BUT NOT STANDARD DEVIATIONS & FIT WITH PENALTY;

ADD NORMALIZATION UNCERTAINTY TO COVARIANCE MATRIX

$$\operatorname{cov}_{ij} = \left(\sum_{k=1}^{N_{\text{sys}}} \sigma_{i,k} \sigma_{j,k} + F_i F_j \sigma_N^2\right) + \delta_{ij} \sigma_{i,t}.$$

#### MONTE CARLO

- FIRST OPTION (NNPDF) INCLUDE NORMALIZATION UNCERTAINTY ALONG WITH OTHER SYSTEMATICS IN DATA GENERATION  $F_i^{(art)(k)} = \left(1 + r_N^{(k)} \sigma_N\right) \left(F_i^{(exp)} + \sum_{p=1}^{N_{sys}} r_p^{(k)} \sigma_{i,p} + r_i^{(k)} \sigma_{i,t}\right)$
- SECOND OPTION NORMALIZATION IS NOT INCLUDED IN DATA GENERATION, & TREATED AS A FREE PARAMETER, TO BE FITTED REPLICA BY REPLICA

### **INCOMPATIBLE DATA**

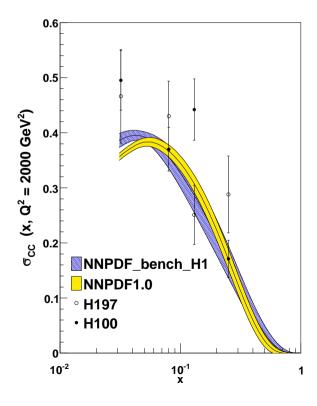
WHEN USED TOGETHER WITH NEURAL NETWORK & CROSS-VALIDATION STOPPING MONTE CARLO LEADS TO INFLATION OF UNCERTAINTY

WHEN COMBINING INCONSISTENT DATA  $\Rightarrow$  SIMILAR TO PDG (SCALE FACTOR) METHOD

EXAMPLE BENCHMARK FIT (HERALHC WSHOP)

LARGER COMPATIBLE DATASET

 $\Rightarrow$  ERROR REDUCTION



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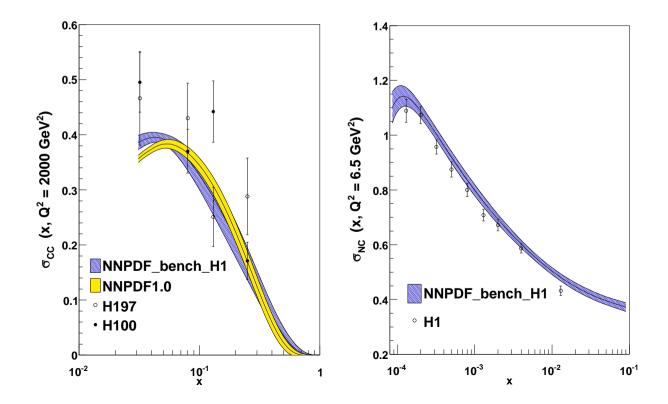
WHEN USED TOGETHER WITH NEURAL NETWORK & CROSS-VALIDATION STOPPING MONTE CARLO LEADS TO INFLATION OF UNCERTAINTY WHEN COMBINING INCONSISTENT DATA  $\Rightarrow$  SIMILAR TO PDG (SCALE FACTOR) METHOD

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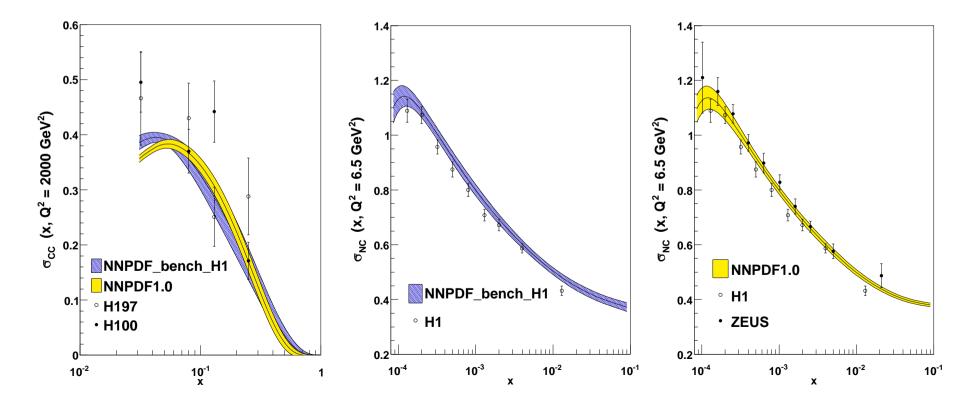
EXAMPLE BENCHMARK FIT (HERALHC WSHOP)

LARGER COMPATIBLE DATASET

LARGER DATASET INCOMPATIBLE

 $\Rightarrow$  ERROR REDUCTION

 $\Rightarrow$  NO ERROR REDUCTION



## CONCLUSION

- HESSIAN & MONTE CARLO METHOD GIVE THE SAME RESULTS IN THE LINEAR (ERROR PROPAGATION) APPROXIMATION
- MONTE CARLO MORE FLEXIBLE IN HANDLING NON GAUSSIAN OR NON LINEAR BEHAVIOUR
- MONTE CARLO MUST BE DONE IN THE SPACE OF DATA, NOT IN THE SPACE OF PARAMETERS
- MONTE CARLO COUPLED WITH NEURAL NETWORKS AND CROSS-VALIDATION STOPPING ALLOWS FOR AN IMROVED TREATMENT OF INCONSISTENT DATA