



PSB longitudinal painting: concept and control

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Acknowledgements: B. Mikulec, C. Carli, E. Benedetto, J. Sanchez

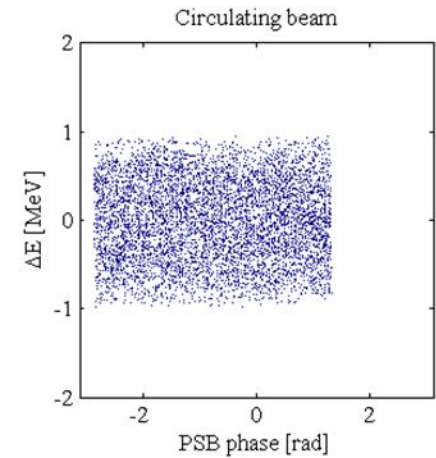
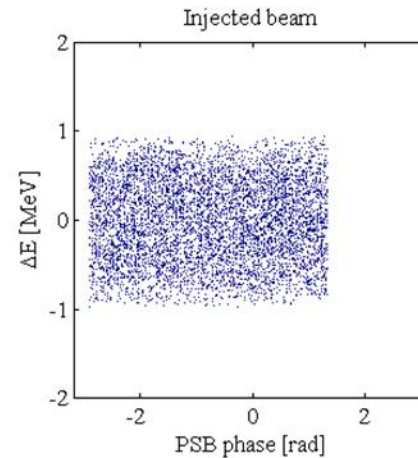
Outline

- Longitudinal painting concept
 - The process
 - Physical parameters
 - Present hardware limitations
- A longitudinal painting control algorithm
- Summary and next steps



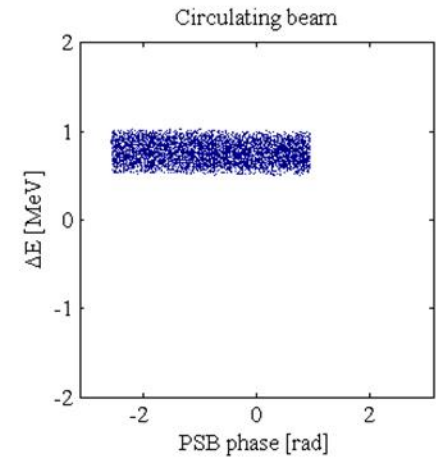
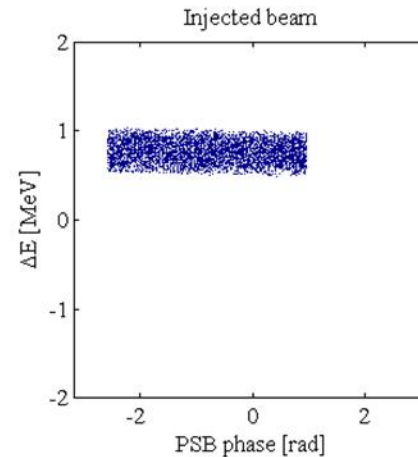
➤ Multi-turn **un-modulated energy injection**

- The L4 bunch trains arrive to the PSB with **the same central energy $E_0 = 160$ MeV**
- The **rms energy spread δE is usually large (~400-450 keV)** to compensate peaks of line density
 - bad for space charge
- The **chopping factor is fixed (~60%)**

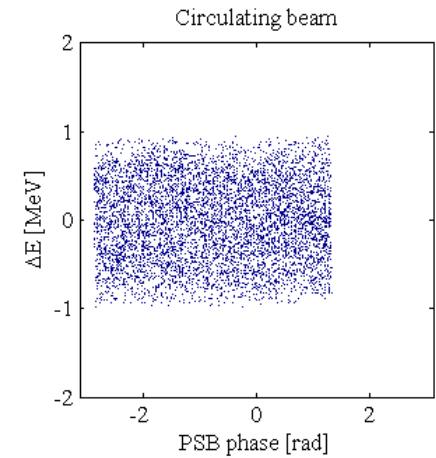
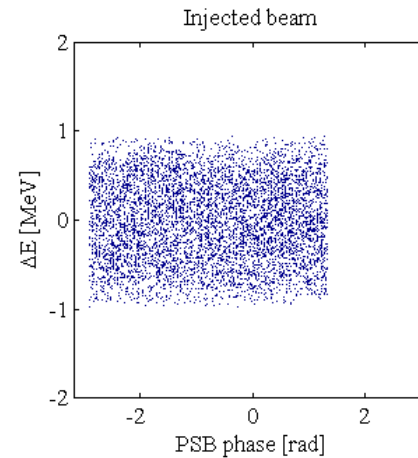


➤ Multi-turn **longitudinal painting**

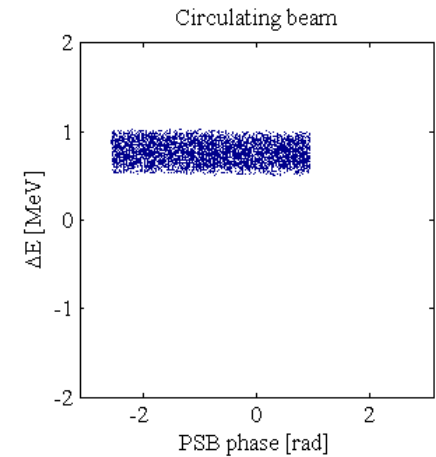
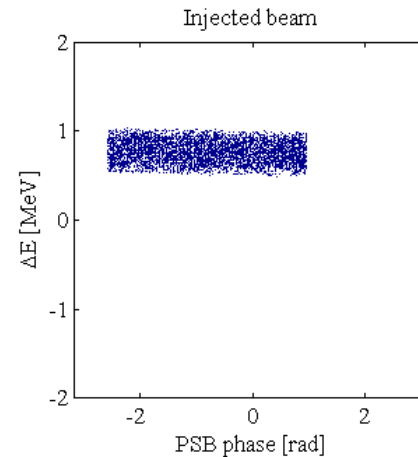
- The **L4 bunch trains** arrive to the PSB with **different (turn-by-turn) central energy around $E_0 = 160$ MeV**
- The **rms energy spread δE is fixed (120-250 keV)**
- The **chopping factor is varying** to follow the longitudinal iso-Hamiltonian contours for a give longitudinal emittance.



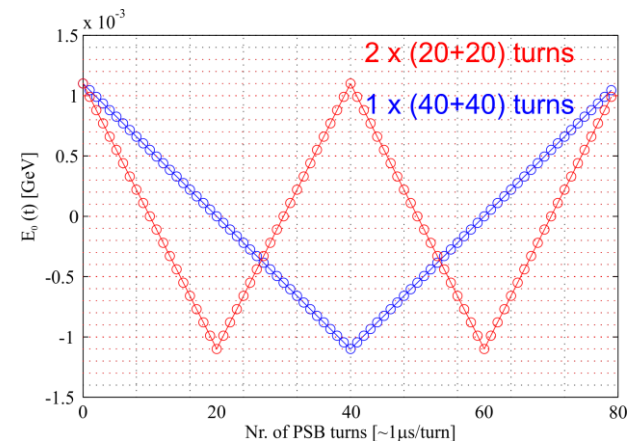
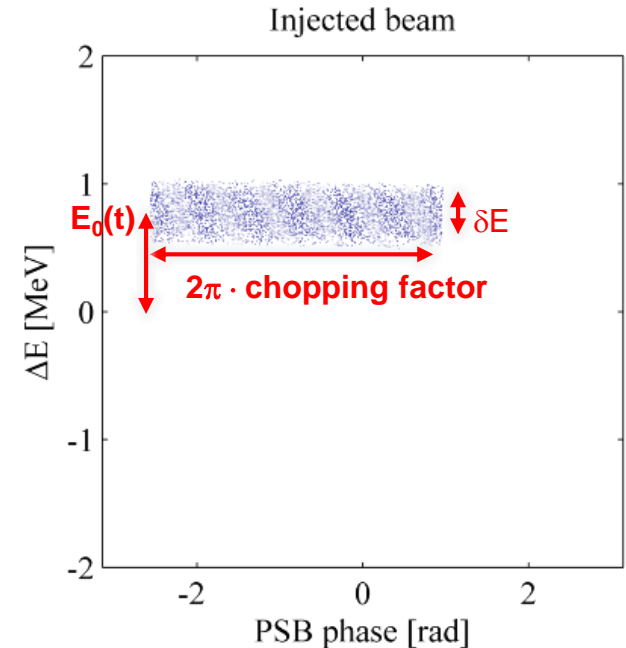
- Multi-turn **un-modulated energy injection**
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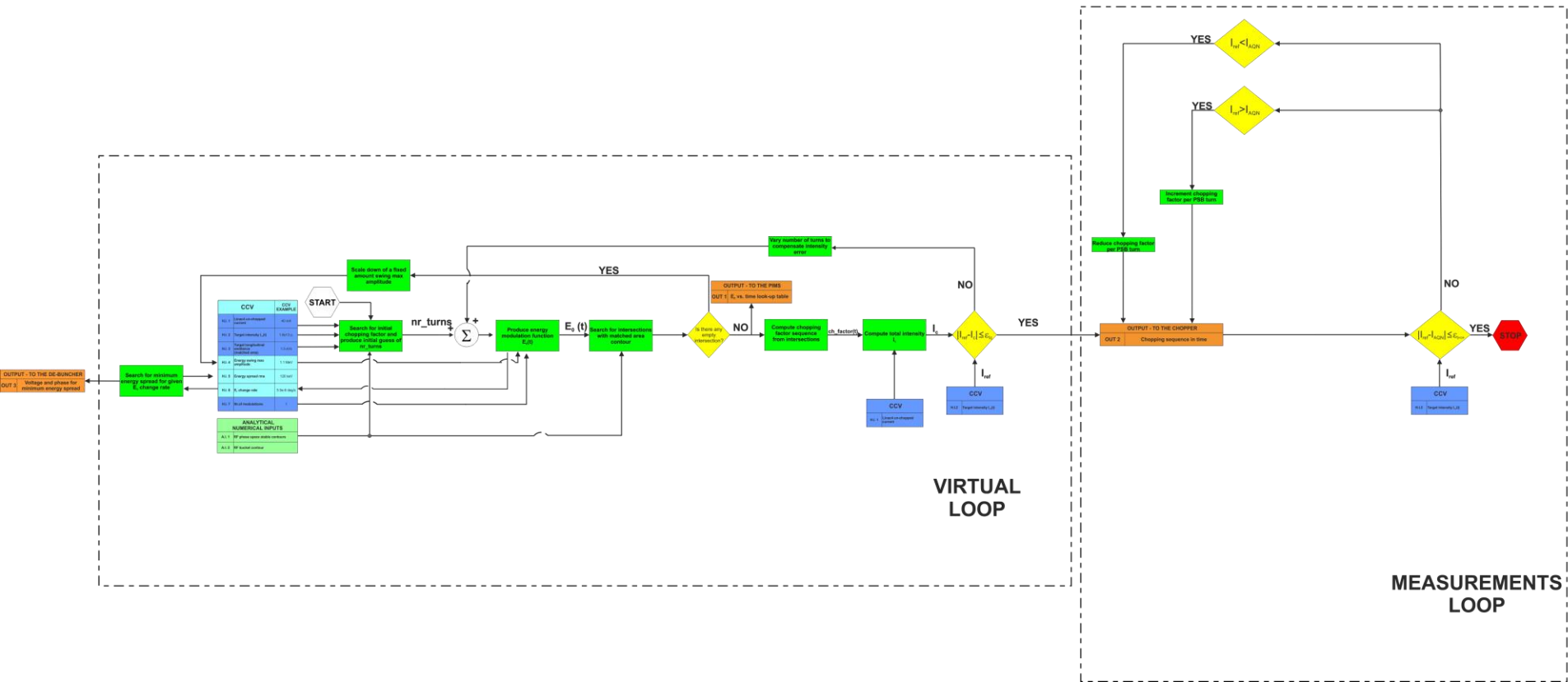


- **The rms energy spread δE**
 - Imposed **by the de-buncher**
 - **Fixed** during the injection process
- **The central energy $E_0(t)$**
 - Imposed **by the last two PIMS**
 - **Can be swept turn-by-turn** at injection
- **The central energy sweeping rate $dE_0(t)/dt$**
 - Imposed by the last two PIMS → **change of phase and, thus, power requested to the de-buncher**
- **The chopping factor (≤ 1)**
 - Imposed **by the chopper**
 - **Rations the effective current/turn** at the PSB entrance
 - $I_{\text{eff}}(t) = \text{chop. factor} \times \text{unchopped current} = \text{chop. factor} \times 40 \text{ mA}$
 - **Can be modulated** turn-by-turn at injection
 - **Determines the number of turns to be injected** for any given target intensity
- **The number of injectable turns**
 - **Is limited** by the BI.DIS at **<150 per PSB ring**



A possible energy sweep through the PIMS

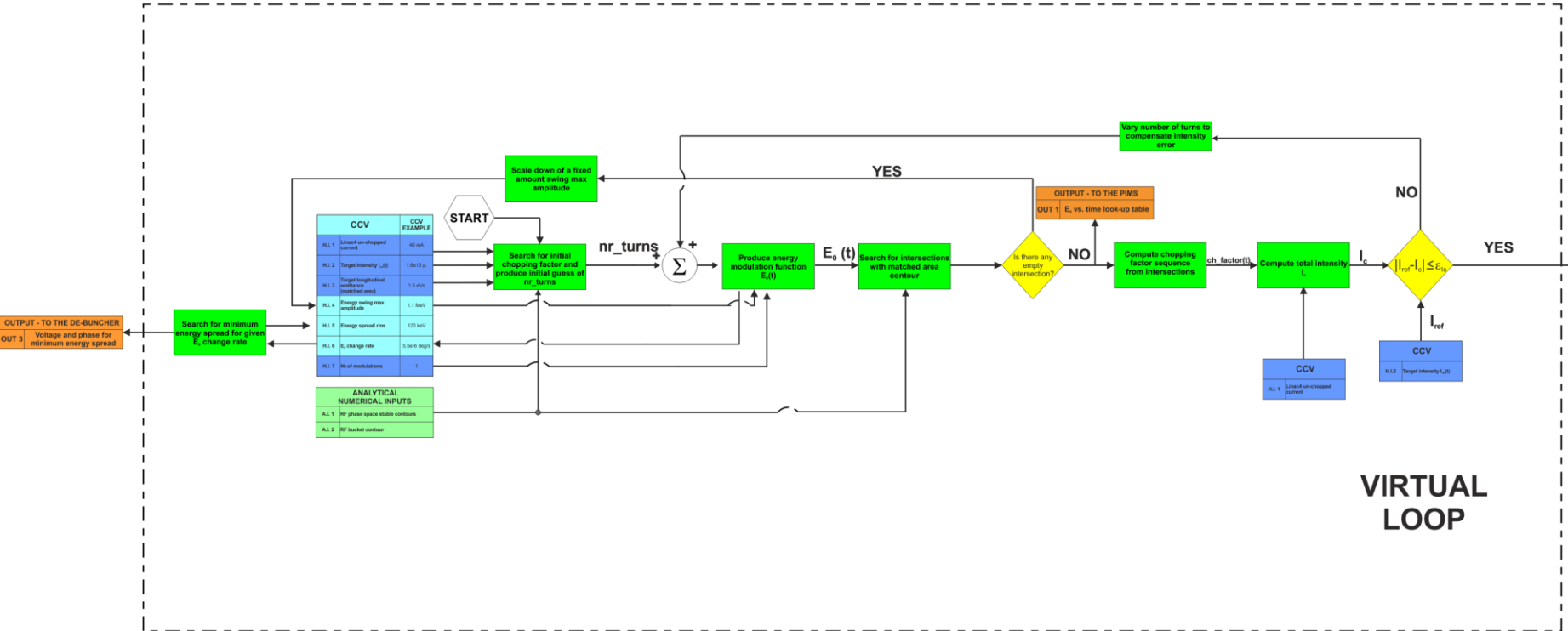
A longitudinal painting control algorithm



Virtual loop



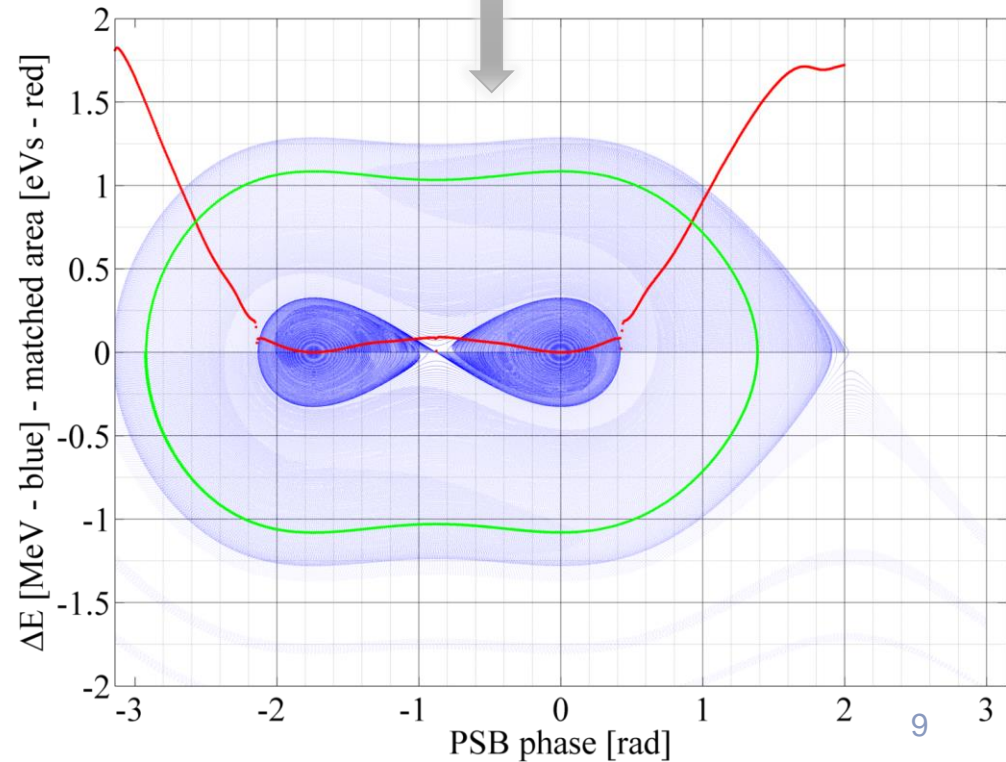
- The virtual loop, from the inputs, is an algorithm to set the HW through:
 - Chopping factor sequence (chopper)
 - Energy swing function (PIMS)
 - Energy-spread (de-buncher)



CCV		CCV EXAMPLE
H.I. 1	Linac4 un-chopped current	40 mA
H.I. 2	Target intensity $I_{ref}(t)$	1.6×10^{13} p.
H.I. 3	Target longitudinal emittance (matched area)	1.5 eVs
H.I. 4	Energy swing max amplitude	1.1 MeV
H.I. 5	Energy spread rms	120 keV
H.I. 6	E_0 change rate	5.5×10^{-6} deg/s
H.I. 7	Nr.of modulations	1

Fixed inputs
Variable inputs

ANALYTICAL NUMERICAL INPUTS	
A.I. 1	RF phase space stable contours
A.I. 2	RF bucket contour



HW outputs



OUTPUT - TO THE DE-BUNCHER

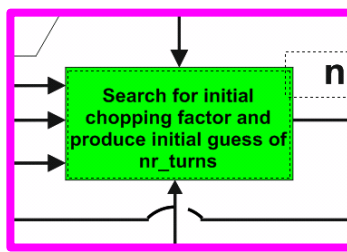
OUT 3	Voltage and phase for minimum energy spread
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OUTPUT - TO THE PIMS

OUT 1	E_0 vs. time look-up table
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OUTPUT - TO THE CHOPPER

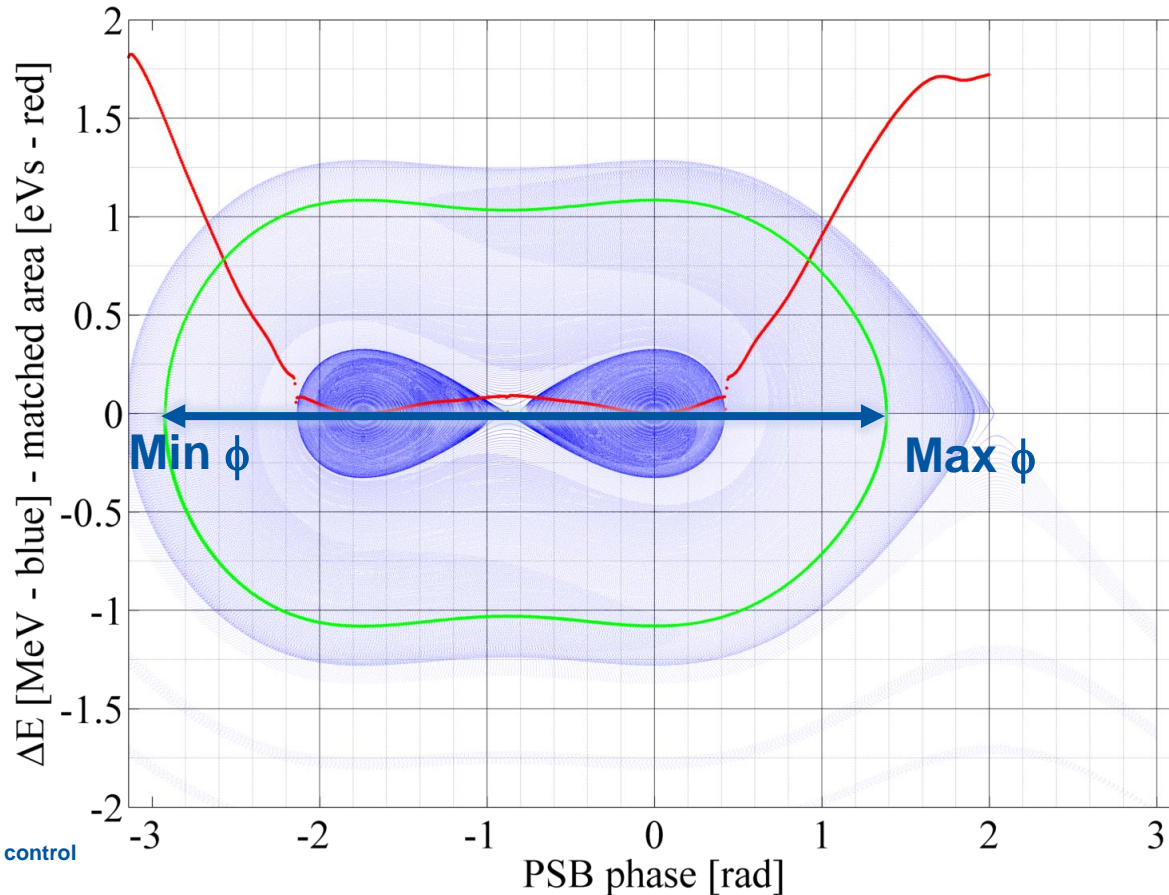
OUT 2	Chopping sequence in time
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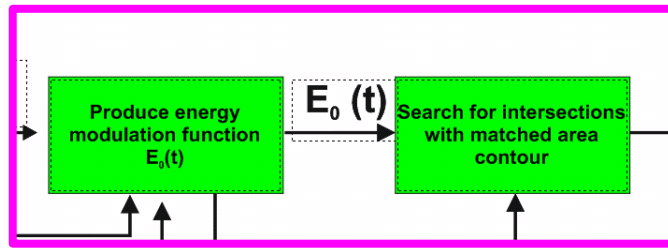


➤ First guess of the chopping factor → initial nr. of turns (under-estimated!)

$$\text{Initial chopping factor} = (\text{Max } \phi - \text{Min } \phi) / 2\pi$$

nr. of turns = f (L4 unchopped current, chopping factor , target intensity)

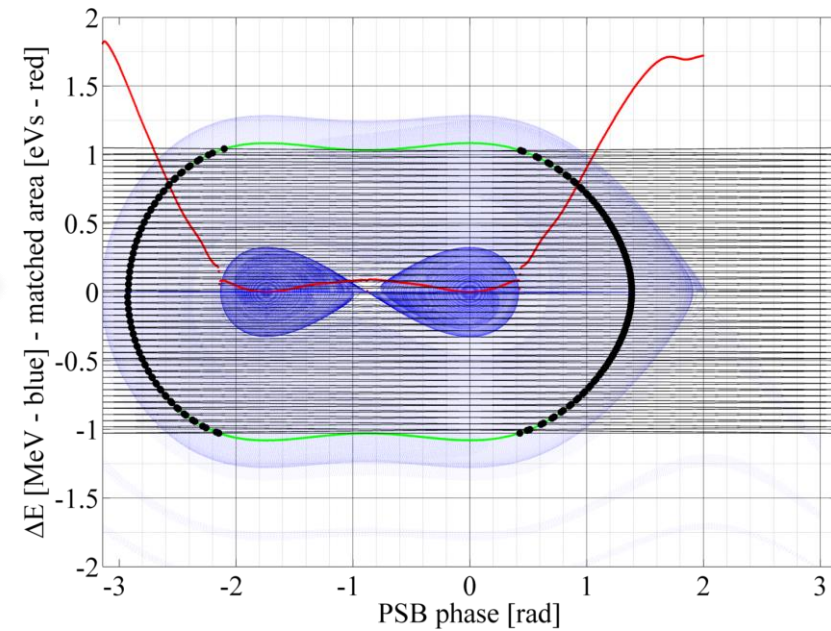
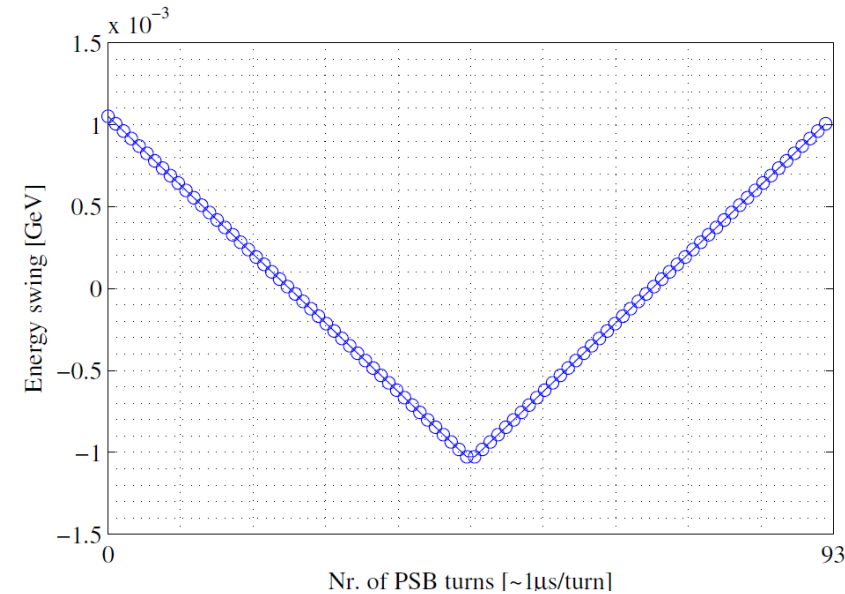




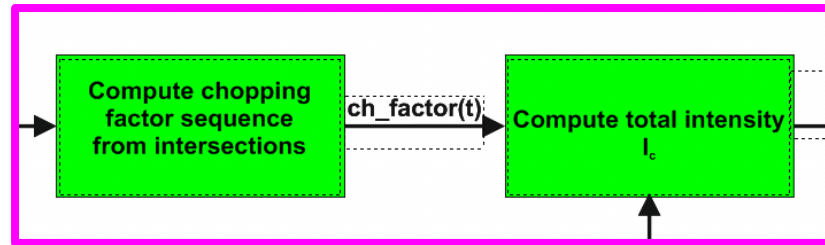
- Estimation of the energy modulation function for the PSB (e.g. triangular waveform)

$$\text{energy_modulation} = f(\text{nr turns, nr of modulations, amplitude})$$

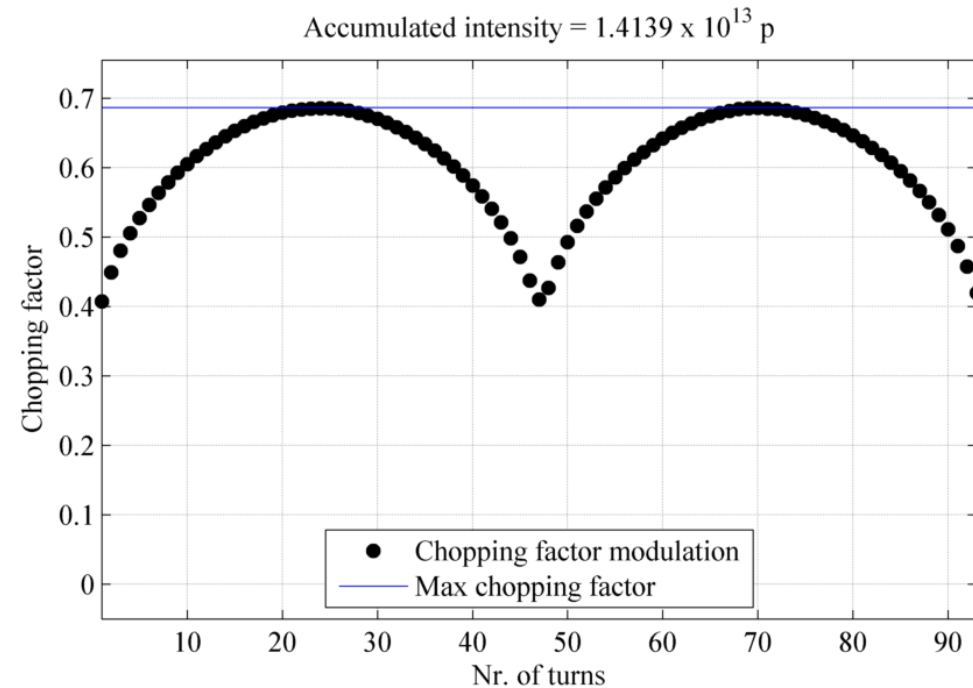
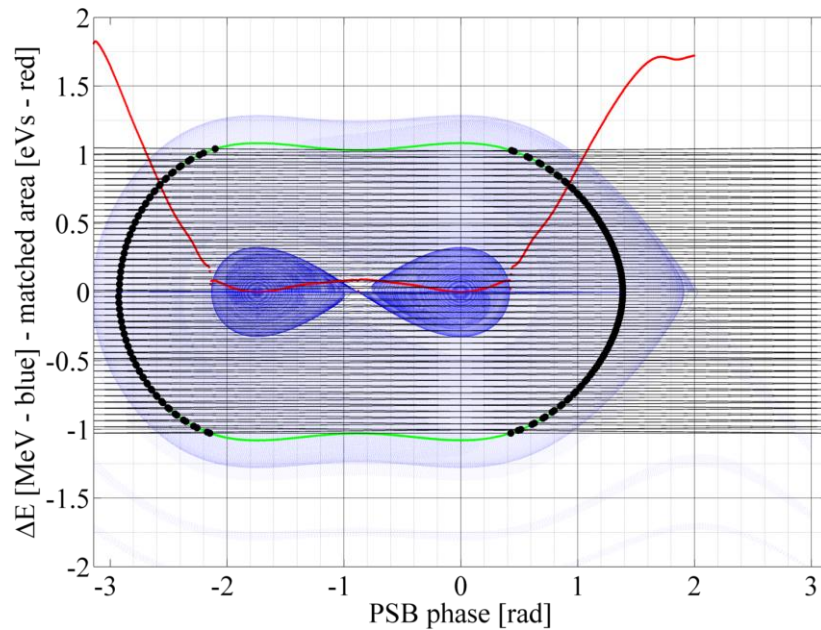
- **The intersections of the energy swing function with the target contour** determines the portion of the L4 pulse that has to be retained at every PSB turn
→ **the chopping factor**

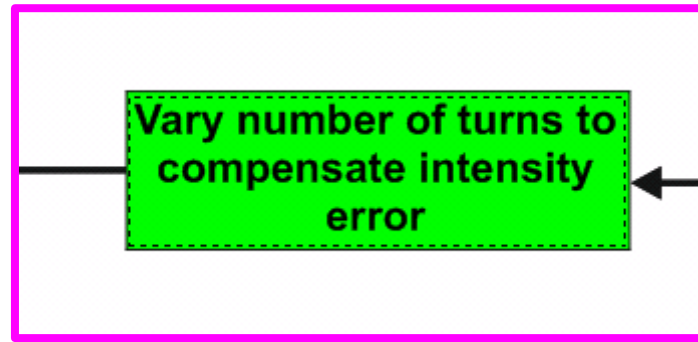


- **NOTA BENE! Empty intersections are un-useful and un-wanted** → if present, one has to scale down the PIMS amplitude in feed-back by a small amount

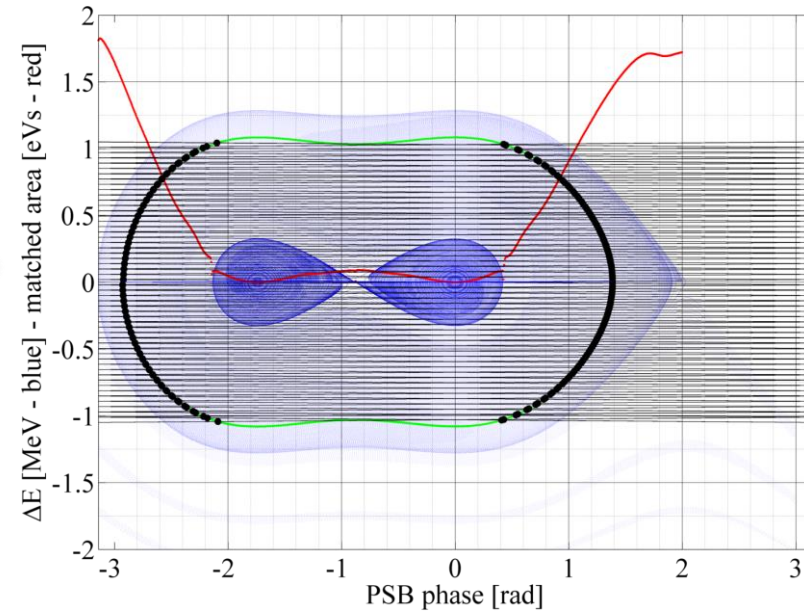
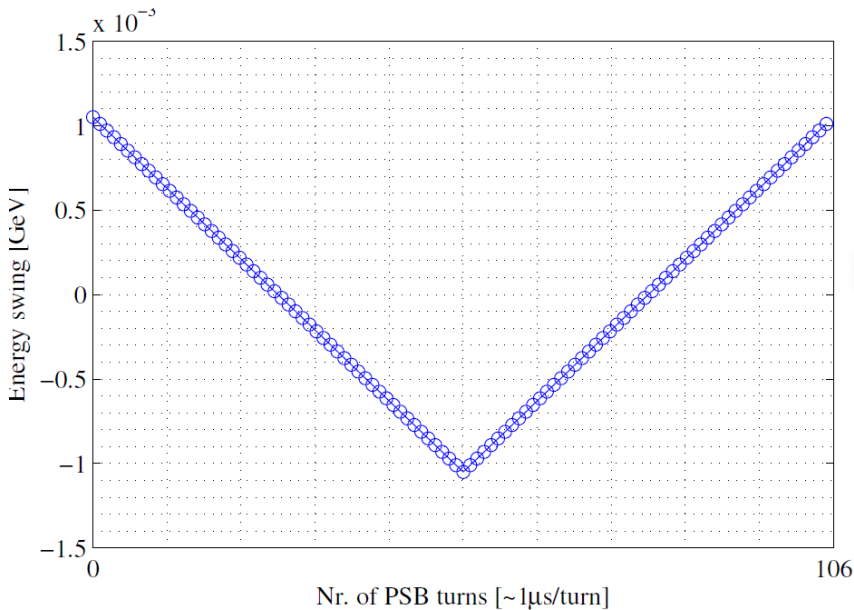


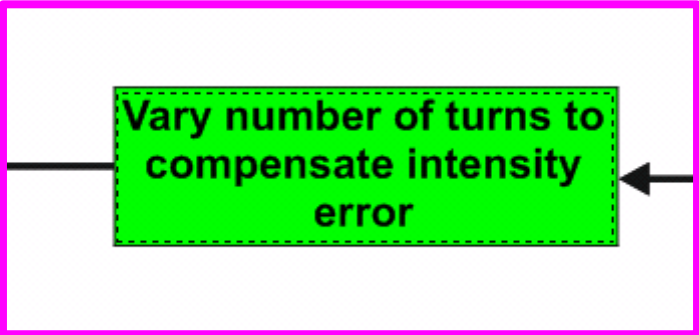
➤ For convexity of the phase edges of the longitudinal iso-Hamiltonian contours, the chopping factor modulation causes the accumulated intensity to be lower than the reference intensity ($1.4139e13 < 1.6e13$ p.)



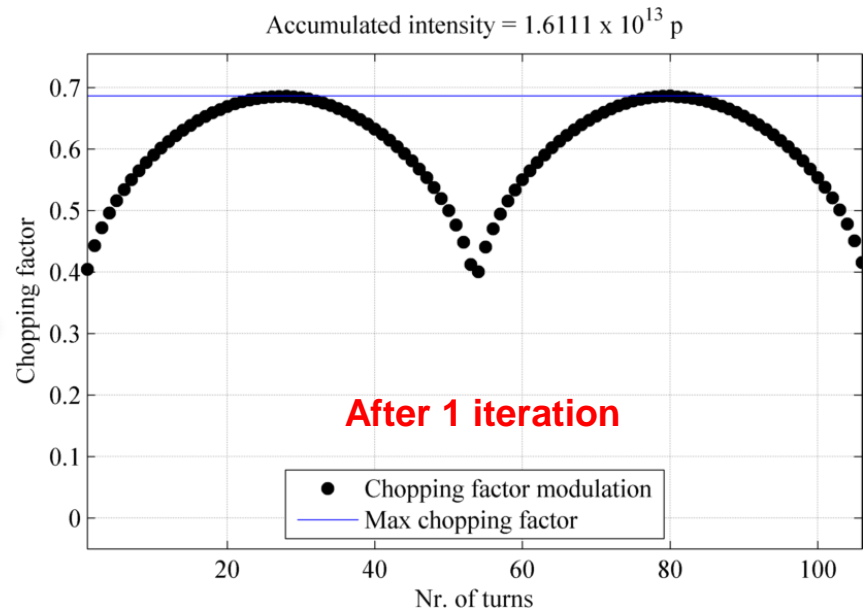
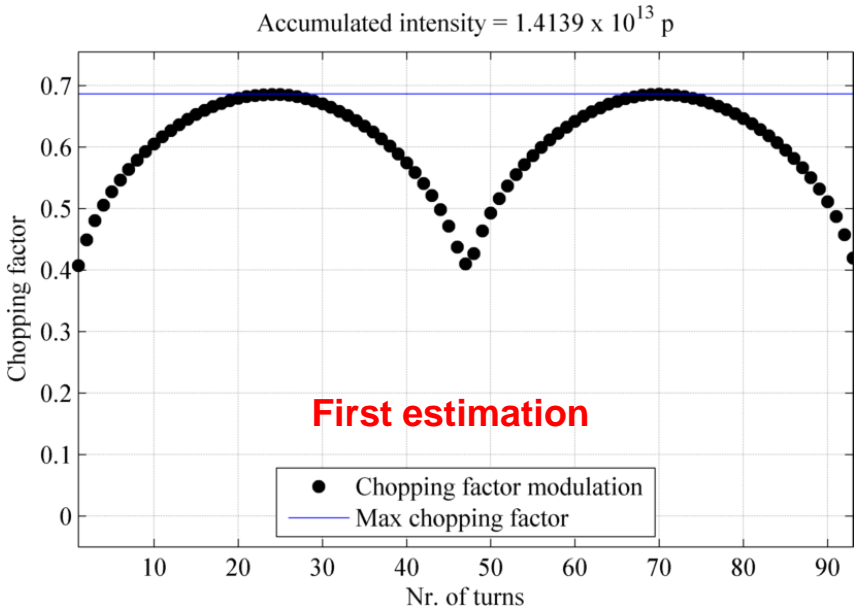


➤ An iteration (feed-back) is needed to compensate the intensity difference → More turns are needed (from 93 to 106!) → Slower energy modulation





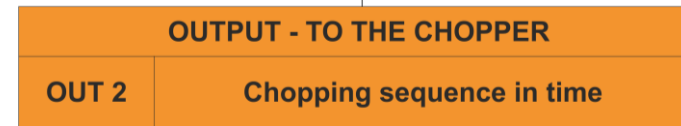
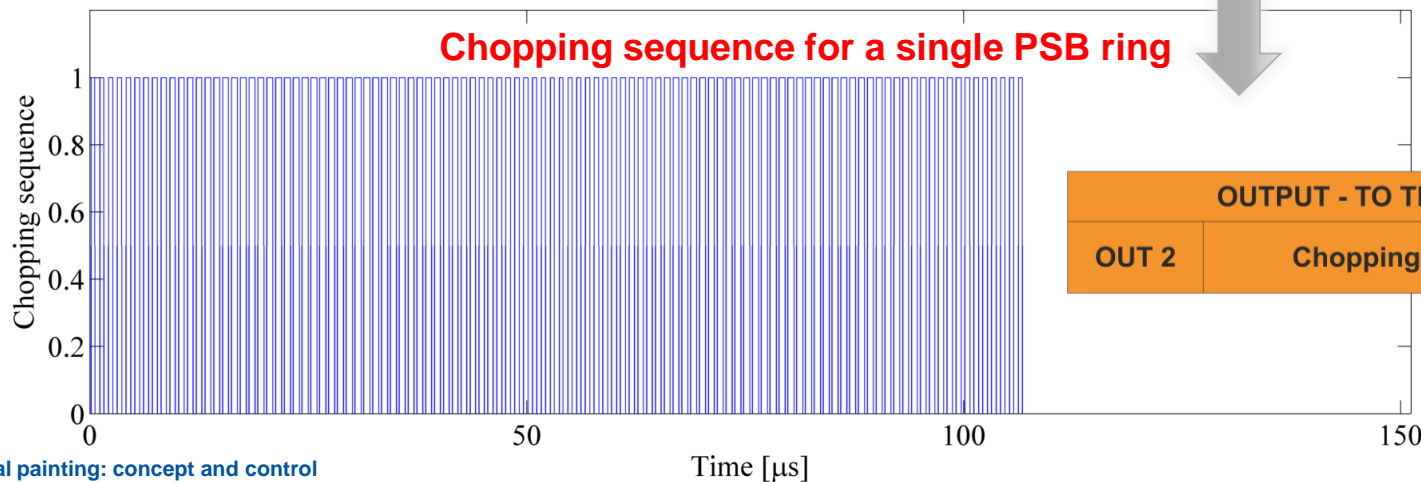
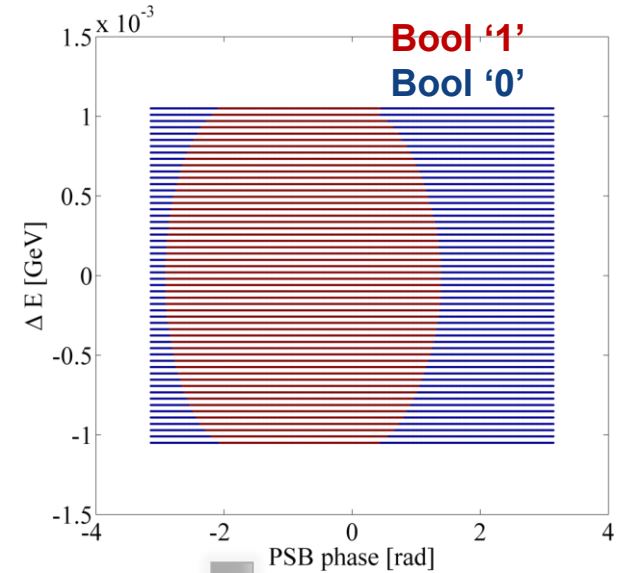
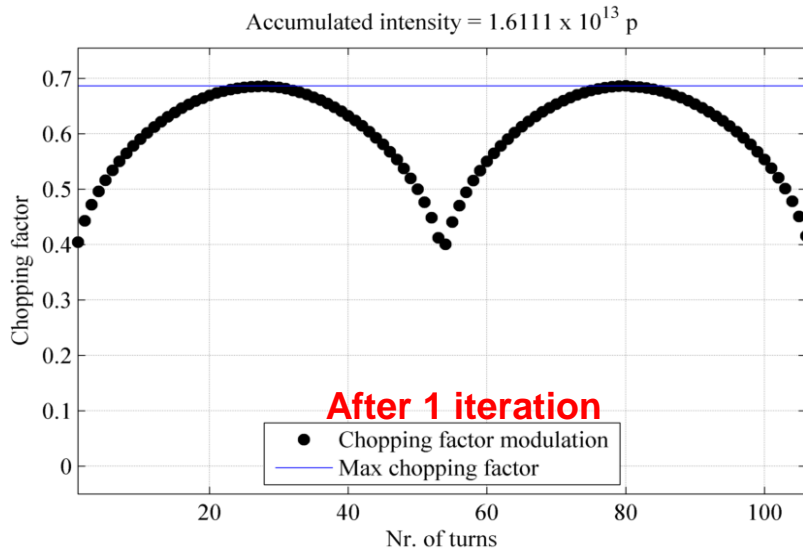
- After 1 iteration the estimated intensity is reasonably close to the target value ($1.6111 \times 10^{13} \sim 1.6 \times 10^{13}$ p.)
 → The chopping factor pattern period becomes slower



Output to the hardware: the chopping

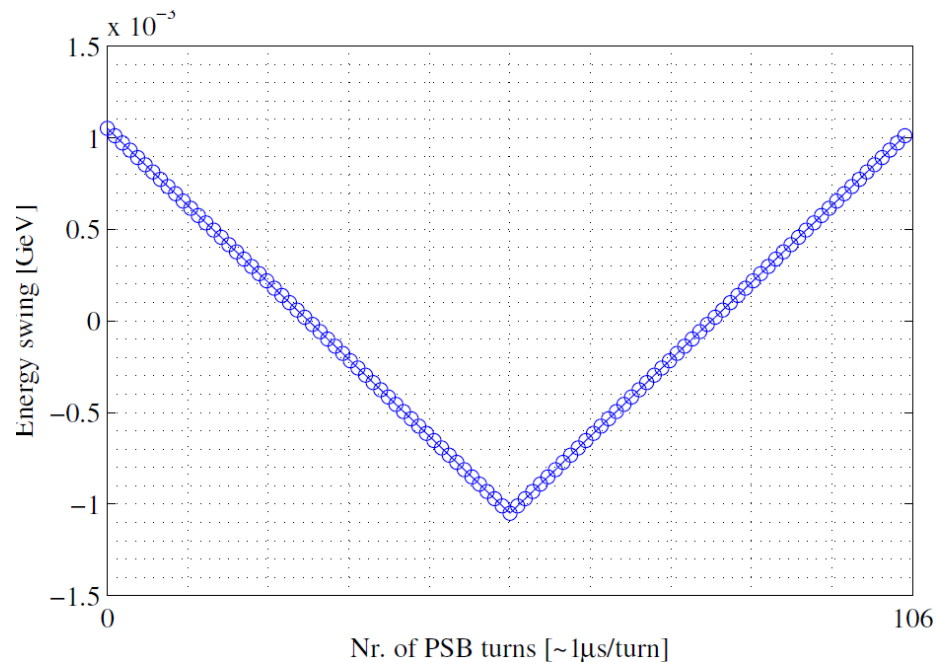


- The chopping pattern must be translated in information for the chopper hardware: e.g. a binary sequence (0/1) of L4 microbunches



OUTPUT - TO THE PIMS	
OUT 1	E_0 vs. time look-up table

- The E_0 swing function could be **translated in form of GFA** (look-up table) for the PIMS cavities (11+12) regulations.



- The swing rate (dE_0/dt) depends on the wanted energy spread by the de-buncher and by the power (available) at the de-buncher cavity.

Output to the hardware: the de-buncher



OUTPUT - TO THE DE-BUNCHER	
OUT 3	Voltage and phase for minimum energy spread

- The de-buncher is needed to generate different energy spreads at the entrance of the PSB.
- The voltage and the phase must be defined once, respecting the present hardware limitation constraints.
- The minimum energy spread achievable strictly depends on the E_0 sweep rate (imposed by the PIMS)
- **NOTA BENE!** For a finest painting, **the smaller the energy spread, the better!** → We aim to use ~100 keV rms at the entrance of the PSB
→ max E_0 sweep rate of 5.5 deg/s (limits the number of PSB turns to achieve given intensity)
- The correlation between de-buncher phase and energy spread at given voltage is foreseen during the commissioning in the LBS line.

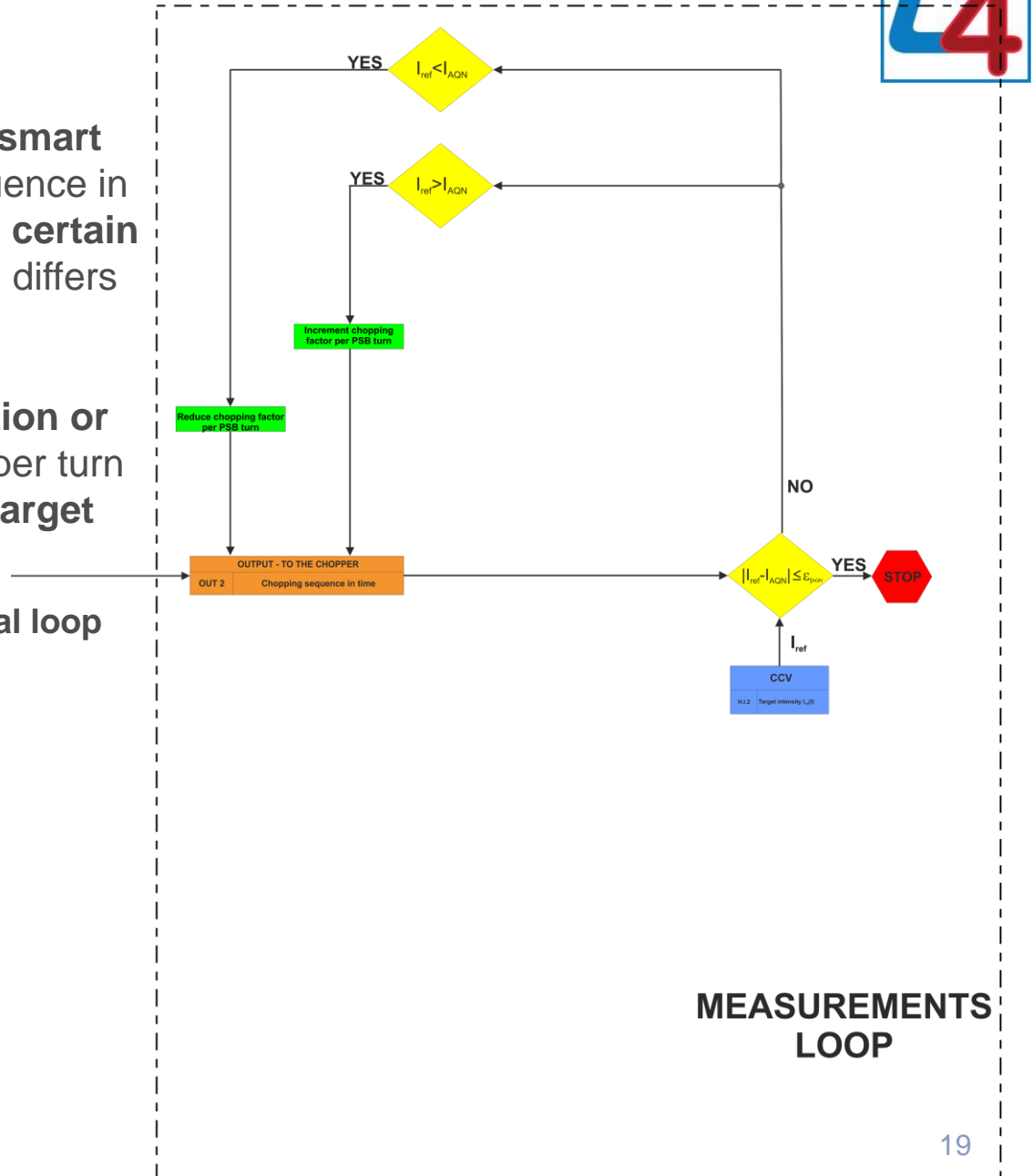
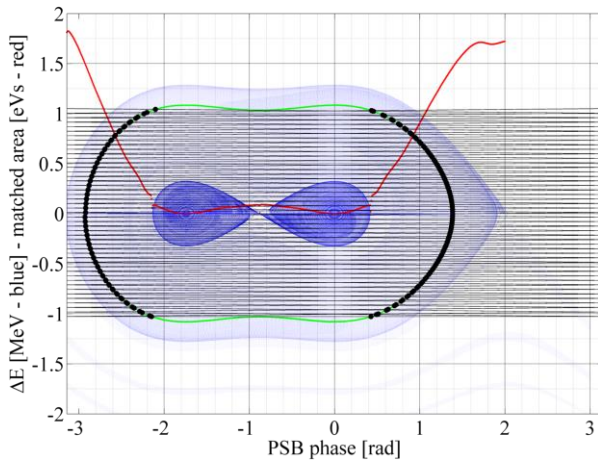


The measurements loop



- The measurements loop acts in a **smart way** on the **chopping factor** sequence in case the **measured intensity at a certain time marker soon after injection** differs from the desired one
- **E.g. 'Smart' way: random reduction or increment of the chopping factor per turn to minimize the mismatch with target contour.**

From virtual loop



MEASUREMENTS
LOOP



Next: longitudinal painting quality figures of merit



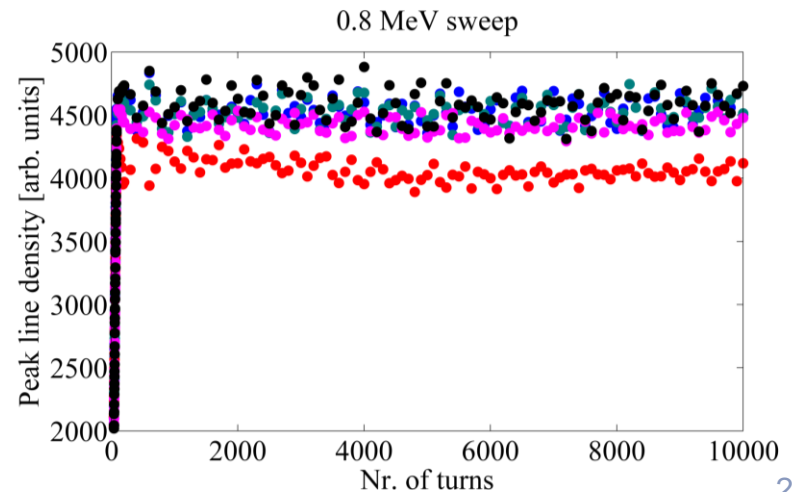
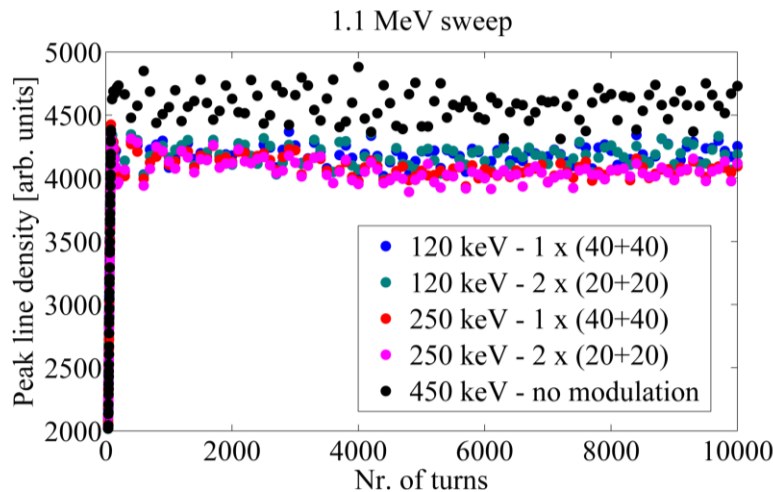
- The historical reasons for the painting in the PSB with L4 have always been related to space charge reduction.
- We might need another loop to control a specific figure of merit.
- **Suggestion: instead of pointing at target longitudinal emittance, shall we point to the contour with lowest peak line density amplitude and beating in time?**

➤ Peak line density

- An advantage of the longitudinal painting is to lead to a SMALLER peak line density (10%), compared to the un-modulated energy case.

$$\Delta Q_y = -\frac{r_0 \lambda}{2\pi e \beta^2 \gamma^3} \oint \frac{\beta_y(s)}{\sigma_y(s) [\sigma_x(s) + \sigma_y(s)]} ds$$

Simulations for future ISOLDE beams





Summary and next steps



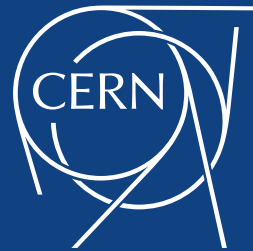
- The longitudinal painting technique for the new L4 to PSB injection has been initially proposed by C. Carli and R. Garoby, as an **elegant and efficient way to reduce longitudinal filamentation**, **thus bunch shape (bunching factor) beating** from the very beginning.
- An introduction to the longitudinal painting process and control has been given.
- The longitudinal painting has the advantage to control the longitudinal plane with **high flexibility**, as we will do with the painting in the transverse plane.
- **It gives the possibility to implement in a very controlled way different longitudinal (and also exotic, e.g. hollow bunches) beam phase spaces.**
- **A 'simple' control algorithm, totally generic (for any given RF bucket shape) has been proposed**
- **This algorithm could work also for the un-modulated injection**, as this last is a particular case of injection with $E_0(t)=0$
- **The longitudinal painting is foreseen only at a late stage of the commissioning, so this is the moment to make brain storming and propose ideas for its realization.**

Next steps



- Missing implementative details:
 - Timing
 - Control
 -

- Control tolerances and quality indexes
- Interlocks
- Suggestions?



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