

SOFTWARE BASED CONTROL AND MONITORING OF A HARDWARE BASED TRACK RECONSTRUCTION SYSTEM FOR THE ATLAS EXPERIMENT

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CHEP 2018

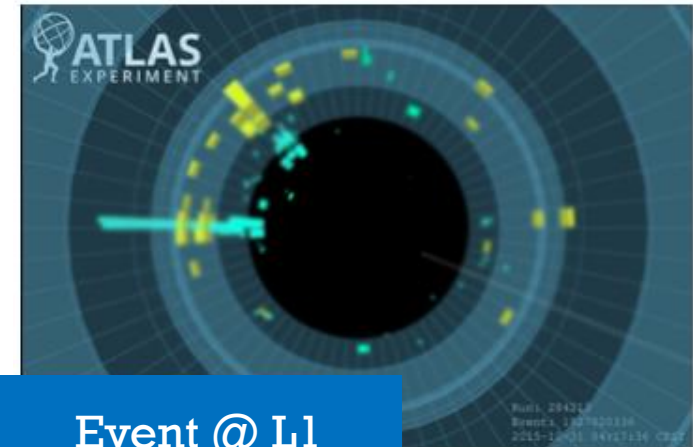


OUTLINE

- Triggering at LHC and tracking challenge
- FTK overview
- FTK online software status
- FTK monitoring status
- FTK commissioning status
- Conclusions

ATLAS TRIGGER @ LHC

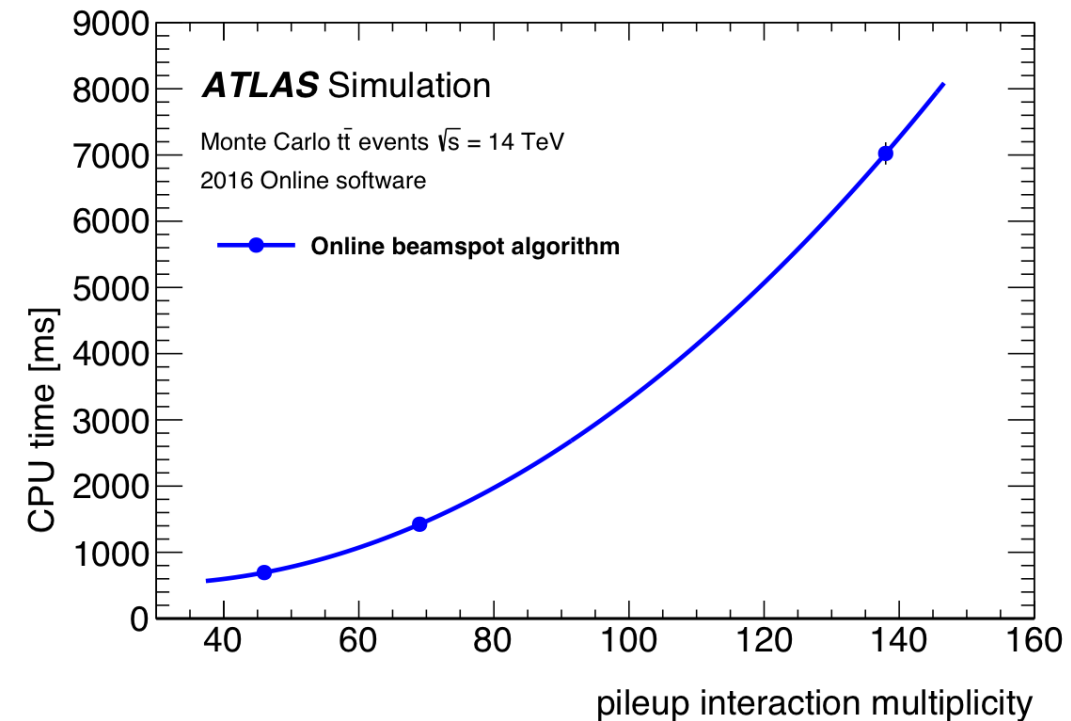
- **Rate reduction required $\sim 40k$**
 - Through multilevel architecture
- **Level 1 (L1):**
 - Hardware based
 - Low resolution data
 - **no Inner Detector (ID) data**
 - Rate reduction ~ 400 in $2.5\mu s$
- **High Level Trigger (HLT):**
 - Software based
 - Full resolution data from all the detectors
 - Rate reduction ~ 100 in $200ms$ avg



THE TRACKING CHALLENGE

- **Track-based trigger selection fundamental**
 - Less pileup dependent
 - Mandatory for jet reconstruction, MET, b and τ tagging ...
- **Tracking is a combinatorial problem**
 - CPU processing time does not scale (linearly) with pileup
 - Tracking information used in small Region of Interest (RoI) for subset of events
 - Reconstruction times:
 - $O(10)$ ms for a single RoI
 - $O(10)$ s for full scan
- **New hardware track trigger:**
 - Designed to provide good resolution global track reconstruction at full L1 rate
 - Reconstructs all tracks ($p_T > 1$ GeV) for all L1 accepted events
 - Tracks **provided at HLT in ~ 100 μ s** at the L1 rate (100 kHz)

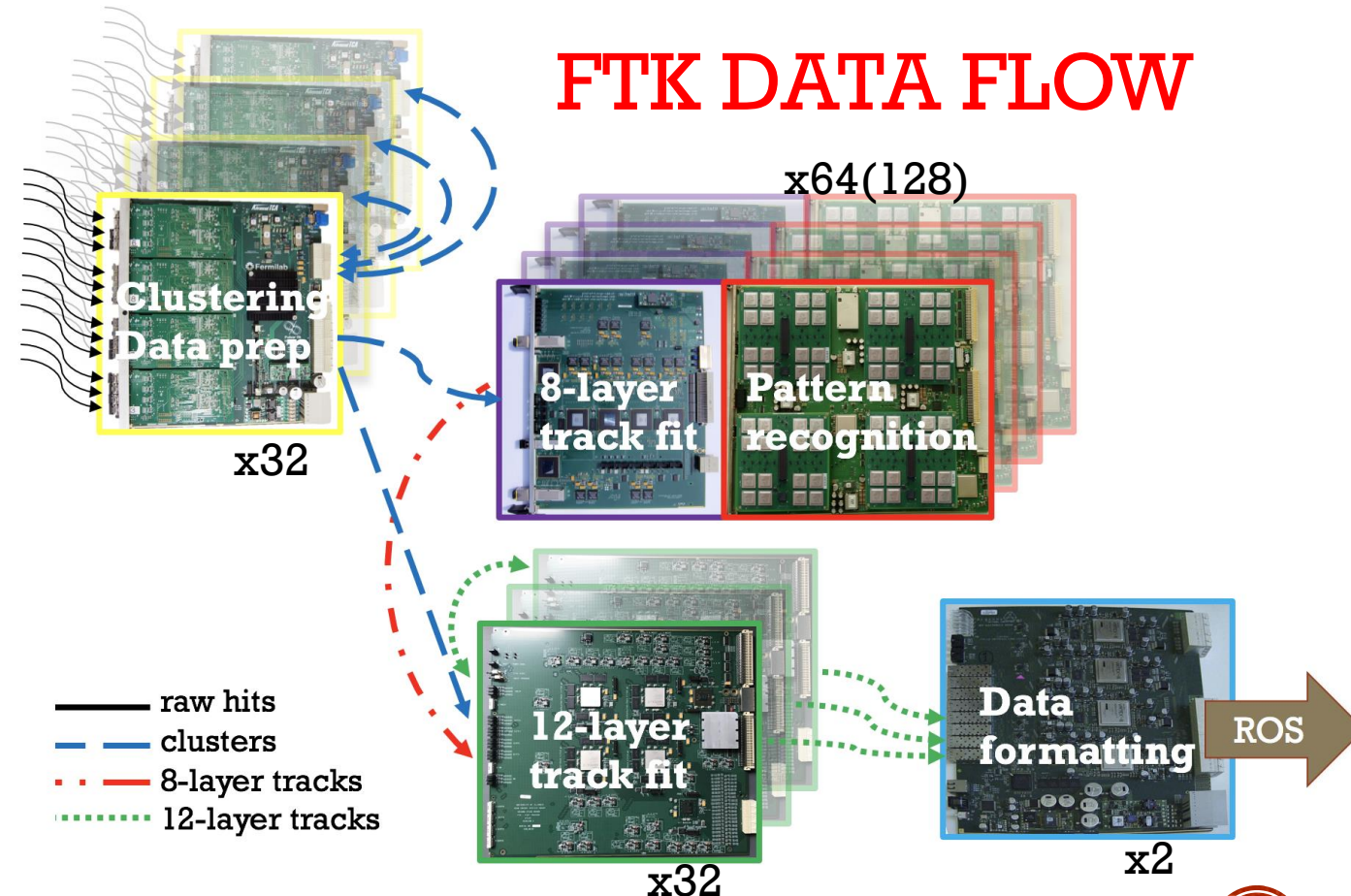
For more details see
[Julie's talk](#)



THE FAST TRACKER

For more details see
[Todd's](#) talk

- FTK: hardware system based on pattern recognition able to find and reconstruct tracks in the ATLAS ID
- Data driven and massively parallel processing system
 - 8k Custom Associative Memory (AM) chips for pattern matching
 - 2k FPGAs for track fitting, data preparation, ambiguity resolution ...
- Very complex system!
 - > 450 boards and many interfaces
 - ~400 input links (from ID)
 - O(10)k links in total
 - Data flows among boards
 - Both vertically and horizontally
 - Synchronization between all the boards crucial
 - Two different standards used: VME and ATCA



FTK CONTROL SOFTWARE

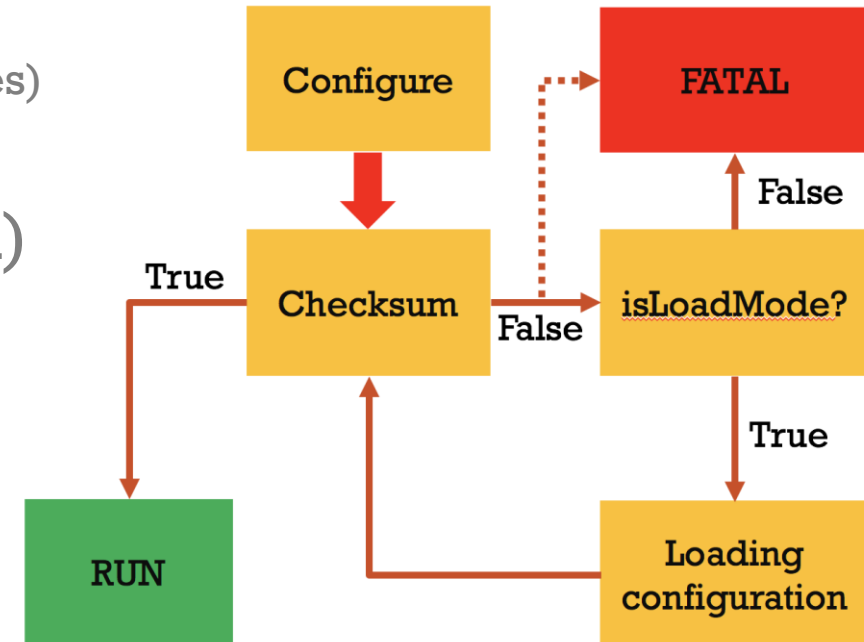
- **Current FTK goal: achieve stable processing providing tracks to HLT in a $\eta - \phi$ region of ATLAS**
 - FTK Online SW strategy: make use of the available ATLAS tools while spotting problems and bottlenecks
 - Custom solutions will be introduced during Long Shutdown
- **ATLAS control SW based on Finite State Machine**
 - **FTK configuration needs to fit in FSM transitions**
 - **System configuration very complex**
 - Many links to be set-up in the correct order
 - Definition of FTK specific sub-transitions required to cope with configuration complexity
 - Many operations required, some to be repeated in case of errors

The screenshot displays the ATLAS Run Control software interface. The top left panel shows the 'RUN CONTROL STATE' as 'RUNNING' in a green box. Below this, there are buttons for 'SHUTDOWN', 'INITIALIZE', 'UNCONFIG', 'CONFIG', 'STOP', 'START', 'HOLD TRG', and 'RESUME TRG'. The 'Auto Pilot' section shows 'Stable Beams' and 'R4P' as active (red circles). The 'Run Information & Settings' section shows 'Run number' as 341529. Below this is a table for 'Lumi Block', 'Level 1', and 'HLT' with columns for 'Number' and 'Rate'. The right side of the interface shows a hierarchical tree view of the system components, including 'RootController', 'Online Segment', 'Infrastructure', and 'FTK'. A context menu is open over the 'FTK' component, showing options like 'MEMBERSHIP', 'RECOVERY', 'SEARCH', and 'ADVANCED'.

Lumi Block	Number	Rate
Level 1	0	0,00 mHz
HLT	0	0,00 mHz
Recorded	0	0

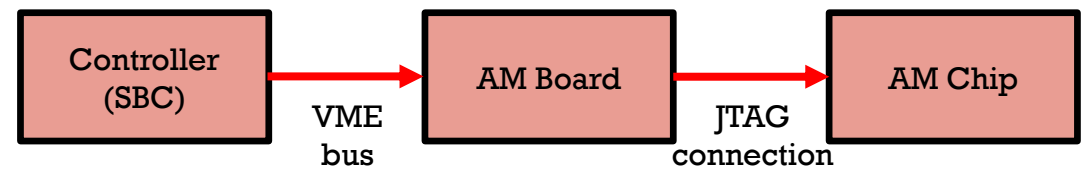
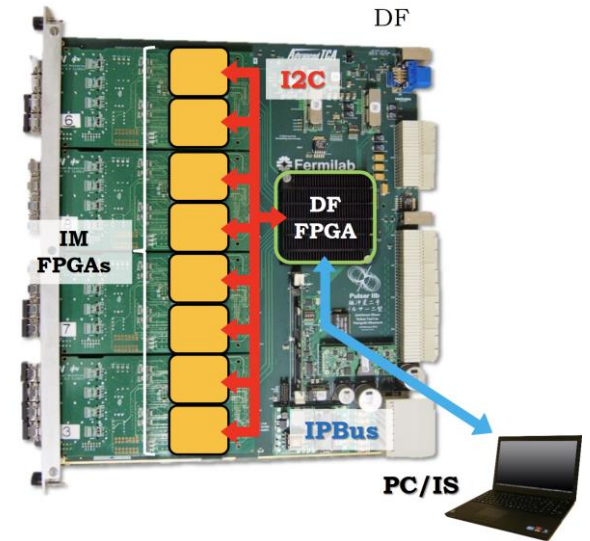
FTK CONFIGURATION

- **FTK boards configuration:**
 - Pattern banks and constants to be loaded on AMChips and FPGAs
 - Not stored in permanent memory
 - SBCs with limited memory (4GB) and CPU power (1.9 GHz - 4 Cores)
- **FTK configuration loading time larger than ATLAS configure transition ($O(1)h$ vs $O(1)min$)**
 - Configuration data size ~ 500 MB/board
 - Configuration time ~ 5 min/board
- **Data loading moved to interfill period**
 - During ATLAS configure transition just verify the validity of the configuration
 - Using checksums computed by both FW and SW on the whole memory content
 - Tool for automatic generation of FTK configurations developed



FTK BOARD ACCESS INTERFERENCES

- Big effort to make board access thread safe
 - Race conditions observed during board configuration
- SW solutions implemented
 - Mutexes to serialize board access from same process
 - System semaphores for multiproces accesses
 - **Cons:**
 - Board monitoring slowed down
 - Control software less responsive
- Work ongoing on concurrent access management at FW level
 - Where possible

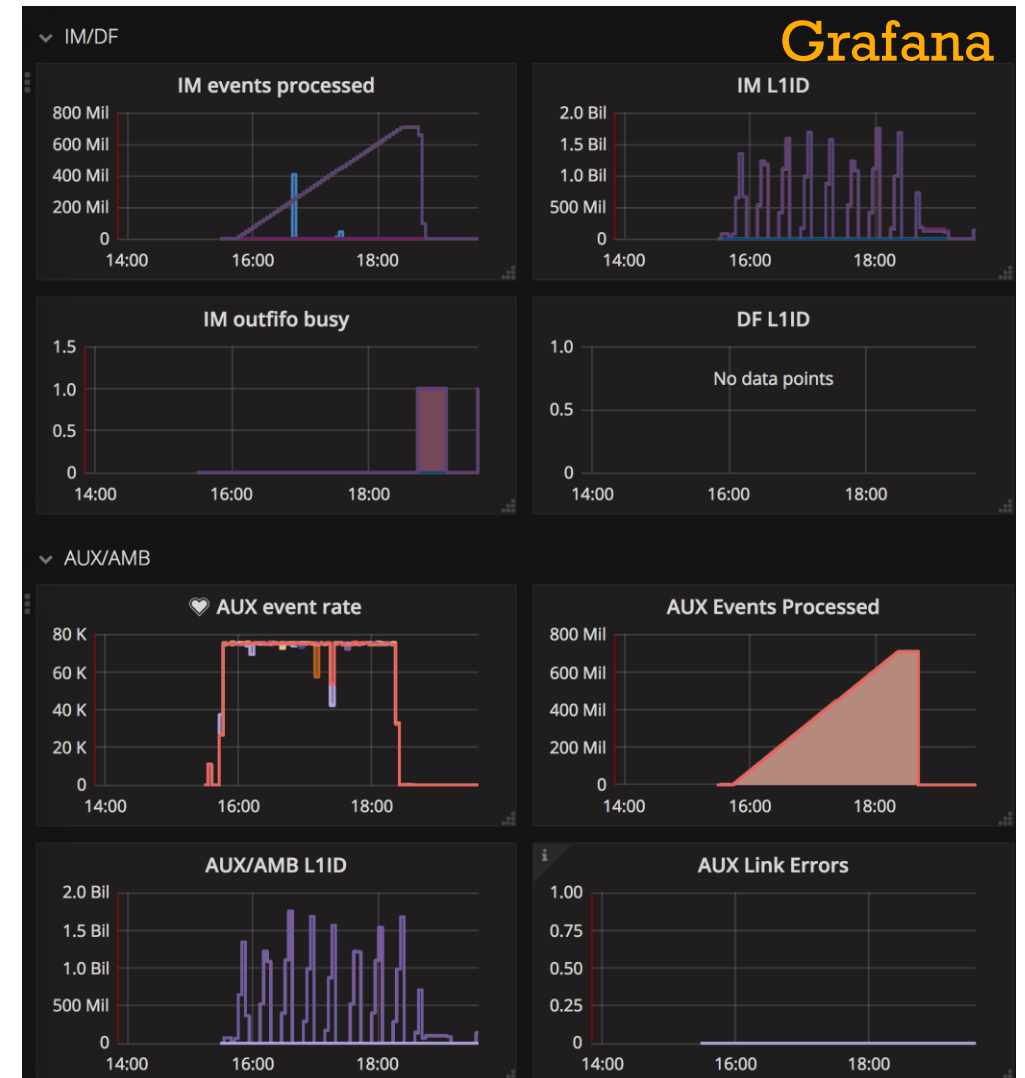


FTK REMOVAL AND RECOVERY

- ATLAS provides procedures to remove and recover faulty subsystem parts while running
 - **Challenging for FTK**
- **Removal**: allows excluding part of the readout blocking the trigger
 - Output replaced with empty fragments
 - FTK Removal requires deep knowledge on possible failing conditions
 - Currently triggered when too many fragments are missing
- **Recovery**: allows re-activating components previously disabled
 - Recovering the system behind the scenes and stopping the L1 accepts only when FTK re-joins the data taking session
 - **FTK needs to recover while ATLAS is taking data**
 - Recovery operations require definition of FTK internal FSM
 - Application to manage internal FSM and commands dispatching developed

FTK MONITORING

- **FTK monitoring sprinted out by the advancement of the commissioning**
- **Currently focused on board monitoring**
 - Status of the internal dataflow
- **Information stored in board status registers**
 - monitoring thread in Controller application
 - Data collected via VME/IPbus
 - Published in ATLAS Information and Histogram services and displayed in high level monitoring applications
- **Work ongoing on online validation of FTK output**
 - Required in view of stable FTK integration
 - Fragments sampled from ATLAS dataflow
 - Online comparison with simulations

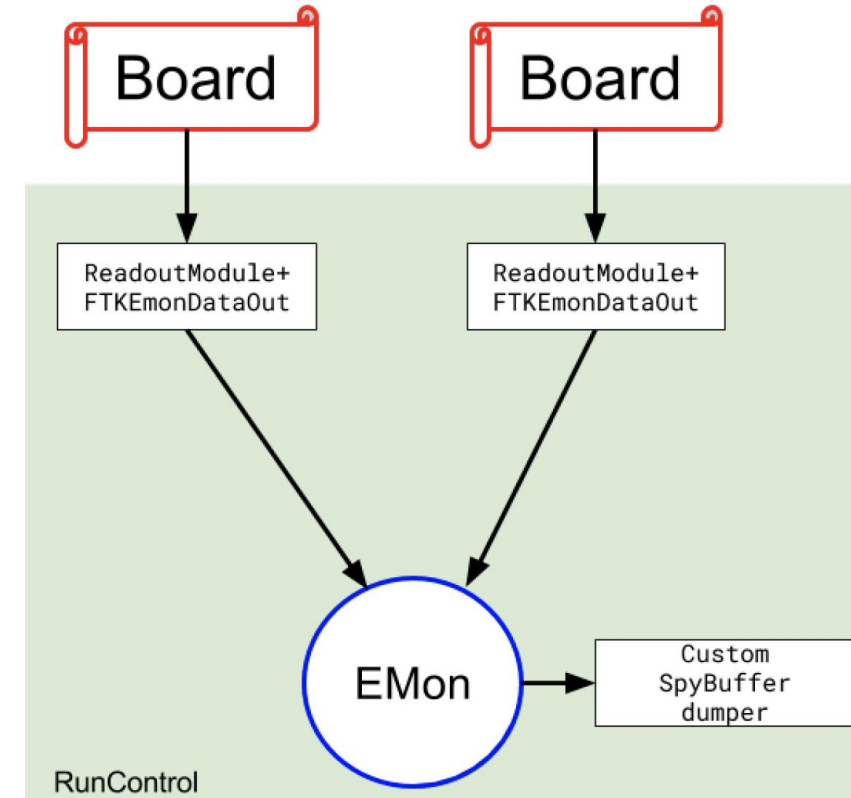


FTK SPYBUFFERS MONITORING

- **FW debugging requires collection of board input/output data**
 - Require data of the same event for all the boards
 - Blocking the monitoring registers writing as soon as an interesting error occurs
- **Spybuffer:**
 - large register in which monitoring data are stored
 - Typical use-case is monitor input/output of a FW module prior to an error
 - FTK Spybuffers are circular buffers
- **Freeze:**
 - Operation that triggers the board's FW to deliberately stop updating its Spybuffers
 - Affects only the monitoring registers, not the processing FIFOs
- **Online Spybuffer readout system provided**
 - Based on ATLAS Event monitoring (EMon)

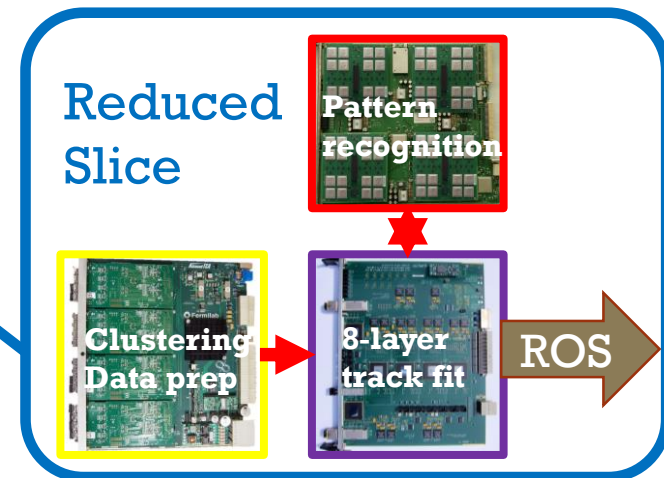
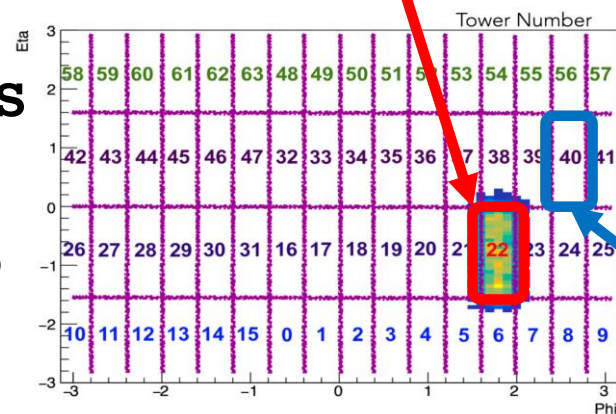
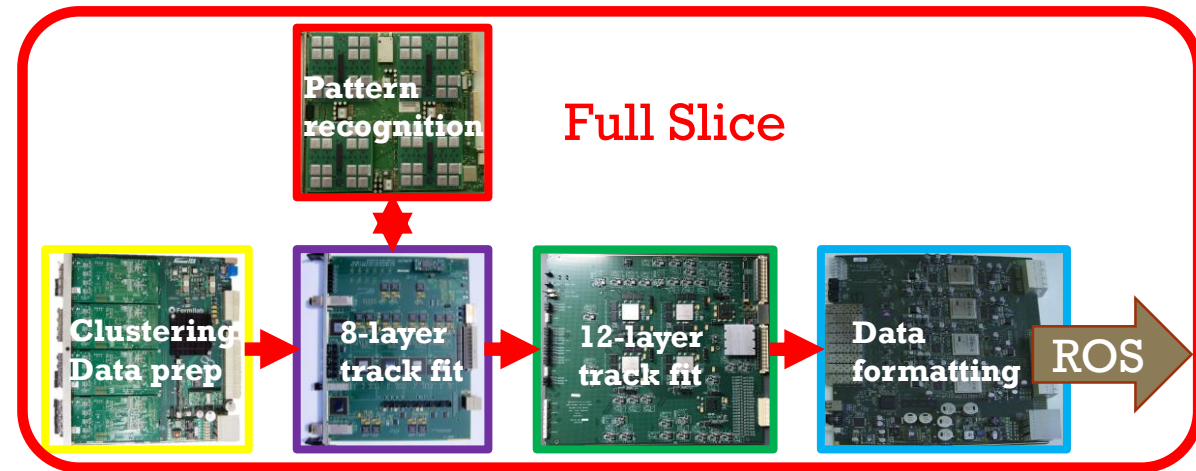
FTK SPYBUFFERS MONITORING

- **Current readout logic:**
 - Spybuffers collected from the boards by the control application
 - Periodically, through monitoring thread
 - Data made available through the ATLAS EMon service
- **Spybuffer readout is slow**
 - Serialization mutex locked too long
 - Dataflow monitoring stopped during the Spybuffer readout
 - It should have higher priority
 - Useful information only from Spybuffers containing problems
- **Readout logic optimization**
 - Spybuffers read in case of error only
 - Decision driven by a dedicated status register
 - Pre-defined set of selection criteria defined in configuration



FTK STATUS: COMMISSIONING

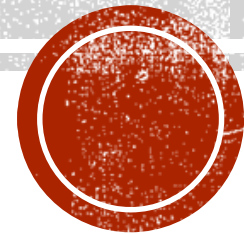
- Commissioning focuses on two slices
 - Full slice outputting 12-layer tracks
 - Reduced slice outputting 8-layer tracks
 - Used for commissioning upstream boards
 - Slices stably integrated in ATLAS data taking architecture
- First validated FTK 12-layer tracks written to the ATLAS bytestream
- In parallel, working on scaling up the system



CONCLUSIONS

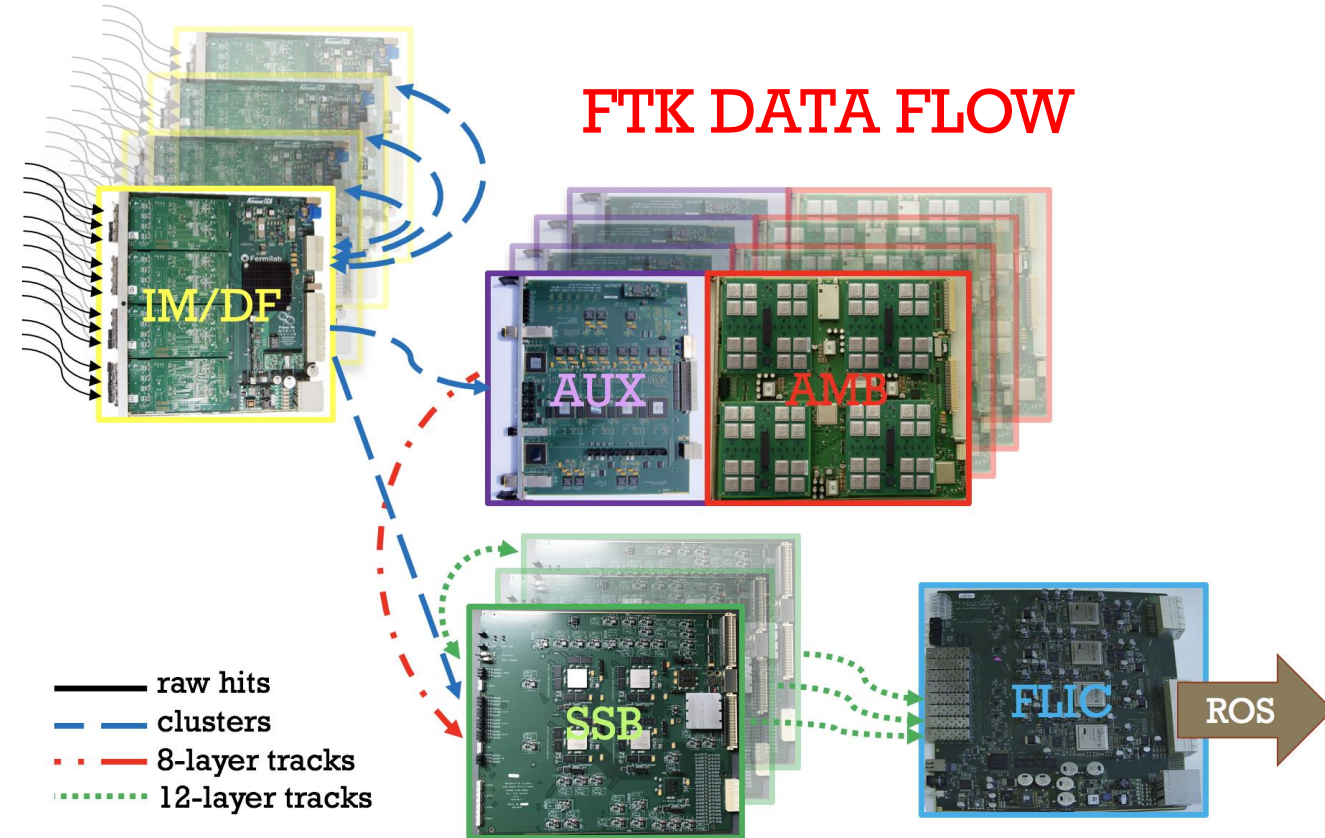
- **FTK system currently under commissioning**
 - Made steady progress in the last year
 - First 12-layer tracks written in the ATLAS bytestream
 - FTK system well integrated within ATLAS data taking
- **Integration of FTK in ATLAS Control SW challenging**
 - SW stable and in continuous development
 - Current architecture has some limitations and bottlenecks
 - Custom solutions will be introduced during LS2
- **FTK monitoring sprinted out by the advancement of the commissioning**
 - Big effort in boosting up dataflow and Spybuffer monitoring to ease debugging

BACKUP



OVERVIEW

- **FTK system**
 - **IM**: receive, cluster hits from Inner Detector
 - **DF**: distribute data to FTK towers
 - **AUX**: reduce data for pattern recognition, 8-layer track fits
 - **AMB**: 8-layer pattern recognition
 - **SSB**: 12-layer track fitting
 - **FLIC**: data formatting for HLT



FTK CONFIGURATION GENERATOR

- **ATLAS configuration defined in xml files stored on CVS**
 - Usually managed individually through custom configuration editors in Java
 - Cumbersome operation for FTK especially during commissioning
- **A software package has been deployed to generate the FTK configurations**
 - Python tool able to generate configuration files for FTK
 - Configured via a python dictionary with editable options
 - Used to generate dynamically the whole FTK configurations

MONITORING STATUS

- **Board DataFlow**: check that the sub-systems are not stuck – processing is ongoing
 - Status register data published in IS
 - Widely used by FTK experts (e.g. Grafana, custom tools, ...)
 - Big effort to define optimal variables for monitoring purpose
- **Board DataQuality**: check that sub-systems produce a reasonable output
 - Information from SpyBuffers published in emon
 - Currently available for 2 boards
- **FTK output DQM**: check FTK output is reasonable
 - using FTK fragment in ATLAS event
 - Framework available, not currently in use
- **High-level FTK output monitoring**: compare FTK output to FTK emulation run on the same ID hits
 - ATLAS events containing FTK and ID fragments
 - Advanced/stable prototype available, to be speed up

WHERE CAN FTK HELP?

- Trigger and DAQ Run3 goals:
 - Reduce HLT rate by rejecting events which are background
 - Add sensitivity in channels or open sensitivity to new channels by improving the HLT
- **FTK will help reaching these goals**
 - Jet reconstruction and pileup reduction using data from all pile-up vertices in event
 - Better isolation requirements avoiding inefficiency from pileup
 - MET: tracking can reduce effects of pileup
 - τ : FTK tracking at early stage will avoid inefficiency from calo only selection
 - b : FTK tracks will save HLT time allowing L1 threshold lowering
 - ...