

A new method of constructing binary black hole initial data

István RÁCZ

Wigner RCP
Budapest

racz.istvan@wigner.mta.hu

PoToR 4 Conference
Kazimierz Dolny, 2017 September 27

Outline:

- 1 Motivations
- 2 The parabolic-hyperbolic form of the constraints
- 3 Kerr-Schild black holes and the superposed ones
- 4 Solving the constraints as an initial-boundary value problem
- 5 Input parameters and ADM charges
- 6 Summary

Motivations:

GW observations:

- inspiral and merger of binary black holes is of distinguished importance for the emerging field of gravitational wave astronomy
- non-linearities necessitate the use of accurate numerical approaches in determining the emitted waveforms
- precision of these simulations—in particular, their initializations—is of critical importance in enhancing the detection of gravitational wave signals

A new construction:

- I. Rácz: *Constraints as evolutionary systems*, *Class. Quantum Grav.* **33** 015014 (2016)
- I. Rácz: *A simple method of constructing binary black hole initial data*, arXiv:1605.01669
- I. Rácz: *On the ADM charges of multiple black holes*, arXiv:1608.02283

Motivations:

GW observations:

- inspiral and merger of binary black holes is of distinguished importance for the emerging field of gravitational wave astronomy
- non-linearities necessitate the use of accurate numerical approaches in determining the emitted waveforms
- precision of these simulations—in particular, their initializations—is of critical importance in enhancing the detection of gravitational wave signals

A new construction:

- I. Rácz: *Constraints as evolutionary systems*, *Class. Quantum Grav.* **33** 015014 (2016)
- I. Rácz: *A simple method of constructing binary black hole initial data*, arXiv:1605.01669
- I. Rácz: *On the ADM charges of multiple black holes*, arXiv:1608.02283

Initialization:

The constraints:

- vacuum initial data: (h_{ij}, K_{ij}) on a 3-dimensional manifold Σ

- it is an underdetermined system: 4 equations for 12 variables

Initialization:

The constraints:

- vacuum initial data: (h_{ij}, K_{ij}) on a 3-dimensional manifold Σ

$$\begin{aligned} {}^{(3)}R + (K^e_e)^2 - K_{ef}K^{ef} &= 0 \\ D_e K^e_a - D_a K^e_e &= 0 \end{aligned}$$

where D_a denotes the covariant derivative operator associated with h_{ab}

- it is an underdetermined system: 4 equations for 12 variables

Initialization:

The constraints:

- vacuum initial data: (h_{ij}, K_{ij}) on a 3-dimensional manifold Σ

$$\begin{aligned} {}^{(3)}R + (K^e_e)^2 - K_{ef}K^{ef} &= 0 \\ D_e K^e_a - D_a K^e_e &= 0 \end{aligned}$$

where D_a denotes the covariant derivative operator associated with h_{ab}

- it is an underdetermined system: 4 equations for 12 variables

The conformal (elliptic) method:

Lichnerowicz A (1944) and **York J W (1972)**:

- replace

$$h_{ij} = \phi^4 \tilde{h}_{ij} \quad \text{and} \quad K_{ij} - \frac{1}{3} h_{ij} K^l_l = \phi^{-2} \tilde{K}_{ij}$$

using these variables the constraints are put into the **semilinear elliptic system**

$$\tilde{D}^l \tilde{D}_l \phi - \frac{1}{8} \tilde{R} \phi + \frac{1}{8} \tilde{K}_{ij} \tilde{K}^{ij} \phi^{-7} - \frac{1}{12} (K^l_l)^2 \phi^5 = 0$$

where $\tilde{D}_l, \tilde{R}, \dots, \tilde{h}_{ij}$

- $\tilde{K}_{ij} = \tilde{K}_{ij}^{[L]} + \tilde{K}_{ij}^{[TT]}$, where $\tilde{K}_{ij}^{[L]} = \tilde{D}_i X_j + \tilde{D}_j X_i - \frac{2}{3} \tilde{h}_{ij} \tilde{D}^l X_l$

$$\tilde{D}^l \tilde{D}_l X_i + \frac{1}{3} \tilde{D}_i (\tilde{D}^l X_l) + \tilde{R}_i^l X_l - \frac{2}{3} \phi^6 \tilde{D}_i (K^l_l) = 0$$

- $(h_{ij}, K_{ij}) \longleftrightarrow (\phi, \tilde{h}_{ij}; K^l_l, X_i, \tilde{K}_{ij}^{[TT]})$

The conformal (elliptic) method:

Lichnerowicz A (1944) and York J W (1972):

- replace

$$h_{ij} = \phi^4 \tilde{h}_{ij} \quad \text{and} \quad K_{ij} - \frac{1}{3} h_{ij} K^l_l = \phi^{-2} \tilde{K}_{ij}$$

using these variables the constraints are put into the **semilinear elliptic system**

$$\tilde{D}^l \tilde{D}_l \phi - \frac{1}{8} \tilde{R} \phi + \frac{1}{8} \tilde{K}_{ij} \tilde{K}^{ij} \phi^{-7} - \frac{1}{12} (K^l_l)^2 \phi^5 = 0$$

where $\tilde{D}_l, \tilde{R}, \dots, \tilde{h}_{ij}$

- $\tilde{K}_{ij} = \tilde{K}_{ij}^{[L]} + \tilde{K}_{ij}^{[TT]}$, where $\tilde{K}_{ij}^{[L]} = \tilde{D}_i X_j + \tilde{D}_j X_i - \frac{2}{3} \tilde{h}_{ij} \tilde{D}^l X_l$

$$\tilde{D}^l \tilde{D}_l X_i + \frac{1}{3} \tilde{D}_i (\tilde{D}^l X_l) + \tilde{R}_i^l X_l - \frac{2}{3} \phi^6 \tilde{D}_i (K^l_l) = 0$$

- $(h_{ij}, K_{ij}) \longleftrightarrow (\phi, \tilde{h}_{ij}; K^l_l, X_i, \tilde{K}_{ij}^{[TT]})$

The conformal (elliptic) method:

Lichnerowicz A (1944) and York J W (1972):

- replace

$$h_{ij} = \phi^4 \tilde{h}_{ij} \quad \text{and} \quad K_{ij} - \frac{1}{3} h_{ij} K^l{}_l = \phi^{-2} \tilde{K}_{ij}$$

using these variables the constraints are put into the **semilinear elliptic system**

$$\tilde{D}^l \tilde{D}_l \phi - \frac{1}{8} \tilde{R} \phi + \frac{1}{8} \tilde{K}_{ij} \tilde{K}^{ij} \phi^{-7} - \frac{1}{12} (K^l{}_l)^2 \phi^5 = 0$$

where $\tilde{D}_l, \tilde{R}, \dots, \tilde{h}_{ij}$

$$\tilde{K}_{ij} = \tilde{K}_{ij}^{[L]} + \tilde{K}_{ij}^{[TT]}, \quad \text{where} \quad \tilde{K}_{ij}^{[L]} = \tilde{D}_i X_j + \tilde{D}_j X_i - \frac{2}{3} \tilde{h}_{ij} \tilde{D}^l X_l$$

$$\tilde{D}^l \tilde{D}_l X_i + \frac{1}{3} \tilde{D}_i (\tilde{D}^l X_l) + \tilde{R}_i{}^l X_l - \frac{2}{3} \phi^6 \tilde{D}_i (K^l{}_l) = 0$$

$$(h_{ij}, K_{ij}) \quad \longleftrightarrow \quad (\phi, \tilde{h}_{ij}; K^l{}_l, X_i, \tilde{K}_{ij}^{[TT]})$$

The conformal (elliptic) method:

Lichnerowicz A (1944) and York J W (1972):

- replace

$$h_{ij} = \phi^4 \tilde{h}_{ij} \quad \text{and} \quad K_{ij} - \frac{1}{3} h_{ij} K^l_l = \phi^{-2} \tilde{K}_{ij}$$

using these variables the constraints are put into the **semilinear elliptic system**

$$\tilde{D}^l \tilde{D}_l \phi - \frac{1}{8} \tilde{R} \phi + \frac{1}{8} \tilde{K}_{ij} \tilde{K}^{ij} \phi^{-7} - \frac{1}{12} (K^l_l)^2 \phi^5 = 0$$

where $\tilde{D}_l, \tilde{R}, \dots, \tilde{h}_{ij}$

- $\tilde{K}_{ij} = \tilde{K}_{ij}^{[L]} + \tilde{K}_{ij}^{[TT]}$, where $\tilde{K}_{ij}^{[L]} = \tilde{D}_i X_j + \tilde{D}_j X_i - \frac{2}{3} \tilde{h}_{ij} \tilde{D}^l X_l$

$$\tilde{D}^l \tilde{D}_l X_i + \frac{1}{3} \tilde{D}_i (\tilde{D}^l X_l) + \tilde{R}_i{}^l X_l - \frac{2}{3} \phi^6 \tilde{D}_i (K^l_l) = 0$$

$$(h_{ij}, K_{ij}) \longleftrightarrow (\phi, \tilde{h}_{ij}; K^l_l, X_i, \tilde{K}_{ij}^{[TT]})$$

The conformal (elliptic) method:

Lichnerowicz A (1944) and York J W (1972):

- replace

$$h_{ij} = \phi^4 \tilde{h}_{ij} \quad \text{and} \quad K_{ij} - \frac{1}{3} h_{ij} K^l_l = \phi^{-2} \tilde{K}_{ij}$$

using these variables the constraints are put into the **semilinear elliptic system**

$$\tilde{D}^l \tilde{D}_l \phi - \frac{1}{8} \tilde{R} \phi + \frac{1}{8} \tilde{K}_{ij} \tilde{K}^{ij} \phi^{-7} - \frac{1}{12} (K^l_l)^2 \phi^5 = 0$$

where $\tilde{D}_l, \tilde{R}, \dots, \tilde{h}_{ij}$

- $\tilde{K}_{ij} = \tilde{K}_{ij}^{[L]} + \tilde{K}_{ij}^{[TT]}$, where $\tilde{K}_{ij}^{[L]} = \tilde{D}_i X_j + \tilde{D}_j X_i - \frac{2}{3} \tilde{h}_{ij} \tilde{D}^l X_l$

$$\tilde{D}^l \tilde{D}_l X_i + \frac{1}{3} \tilde{D}_i (\tilde{D}^l X_l) + \tilde{R}_i{}^l X_l - \frac{2}{3} \phi^6 \tilde{D}_i (K^l_l) = 0$$

- $(h_{ij}, K_{ij}) \longleftrightarrow (\phi, \tilde{h}_{ij}; K^l_l, X_i, \tilde{K}_{ij}^{[TT]})$

The conformal method:

Impressive mathematical developments since 1944 but ...

- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with excision in the black hole interior—cannot simply be supported by intuition (trumpet data ...)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$

The conformal method:

Impressive mathematical developments since 1944 but ...

- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with excision in the black hole interior—cannot simply be supported by intuition (trumpet data ...)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$

The conformal method:

Impressive mathematical developments since 1944 but ...

- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with excision in the black hole interior—cannot simply be supported by intuition (trumpet data ...)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$

The conformal method:

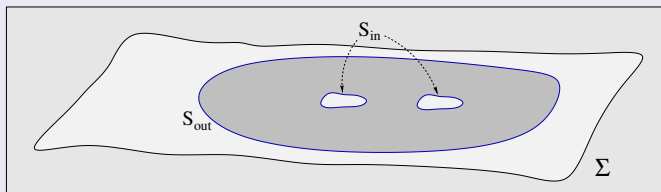
Impressive mathematical developments since 1944 but ...

- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with excision in the black hole interior—cannot simply be supported by intuition (trumpet data ...)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$

The conformal method:

Impressive mathematical developments since 1944 but ...

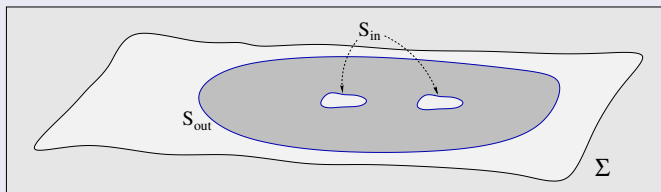
- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$



The conformal method:

Impressive mathematical developments since 1944 but ...

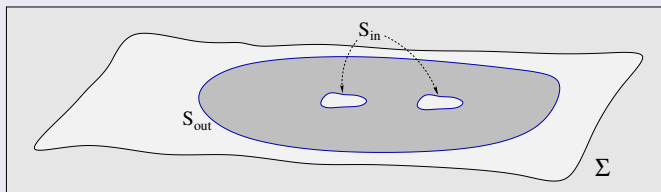
- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$



The conformal method:

Impressive mathematical developments since 1944 but ...

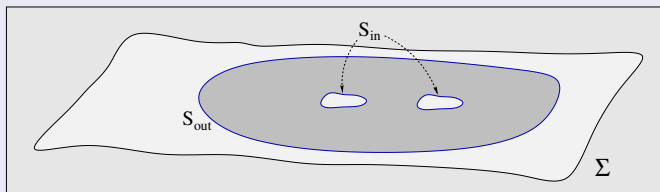
- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$



The conformal method:

Impressive mathematical developments since 1944 but ...

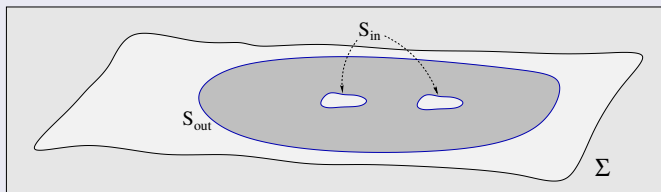
- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$



The conformal method:

Impressive mathematical developments since 1944 but ...

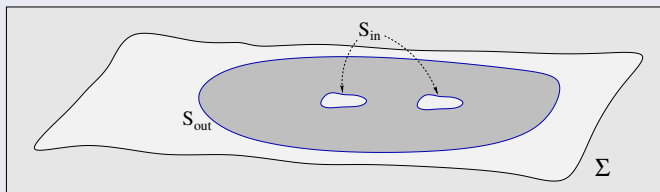
- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$ Kerr-BH



The conformal method:

Impressive mathematical developments since 1944 but ...

- either “constancy” of K^l_l or “smallness” of the TT part of \tilde{K}_{ij} is required
- it is highly implicit due to its elliptic character and the replacements $h_{ij} = \phi^4 \tilde{h}_{ij}$ and $K_{ij} = \frac{1}{3} \phi^4 \tilde{h}_{ij} K^l_l + \phi^{-2} \tilde{K}_{ij} \implies$
 - no direct control on the physical parameters of the initial data specifications
- **boundary conditions:**
 - are known to influence solutions everywhere in their domains
 - the inner boundary conditions—they are applied with **excision** in the black hole interior—cannot simply be supported by intuition (**trumpet data ...**)
 - Bowen-York type initial data: \tilde{h}_{ij} is flat $\tilde{h}_{ij} = \delta_{ij}$ and $K^l_l = 0$ Kerr-BH non-negligible spurious gravitational wave content of yielded time evolutions



New variables by applying $2 + 1$ decompositions:

Splitting of the metric h_{ij} :

New variables by applying $2 + 1$ decompositions:

Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

New variables by applying 2 + 1 decompositions:

Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

$$\implies \hat{n}_i = \hat{N} \partial_i \rho \dots \& \dots h^{ij} \longrightarrow \hat{n}^i = h^{ij} \hat{n}_j$$

New variables by applying $2 + 1$ decompositions:Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

$$\implies \hat{n}_i = \hat{N} \partial_i \rho \dots \& \dots h^{ij} \longrightarrow \hat{n}^i = h^{ij} \hat{n}_j$$

- choose ρ^i to be a vector field on Σ : the integral curves... & $\rho^i \partial_i \rho = 1$

New variables by applying $2 + 1$ decompositions:

Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

$$\implies \hat{n}_i = \hat{N} \partial_i \rho \dots \& \dots h^{ij} \longrightarrow \hat{n}^i = h^{ij} \hat{n}_j$$

- choose ρ^i to be a vector field on Σ : the integral curves... & $\rho^i \partial_i \rho = 1$
- 'lapse' and 'shift' of ρ^i

$$\rho^i = \hat{N} \hat{n}^i + \hat{N}^i$$

New variables by applying $2 + 1$ decompositions:

Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

$$\implies \hat{n}_i = \hat{N} \partial_i \rho \quad \& \dots \quad h^{ij} \longrightarrow \hat{n}^i = h^{ij} \hat{n}_j$$

- choose ρ^i to be a vector field on Σ : the integral curves... & $\rho^i \partial_i \rho = 1$
- 'lapse' and 'shift' of ρ^i

$$\rho^i = \hat{N} \hat{n}^i + \hat{N}^i$$

$$\hat{\gamma}^i_j = \delta^i_j - \hat{n}^i \hat{n}_j, \quad \hat{N}^i = \hat{\gamma}^i_j \rho^j \quad \text{and} \quad \hat{\gamma}_{ij} = \hat{\gamma}^k_i \hat{\gamma}^l_j h_{kl}$$

New variables by applying $2 + 1$ decompositions:Splitting of the metric h_{ij} :

assume

$$\Sigma \approx \mathbb{R} \times \mathcal{S}$$

Σ is smoothly foliated by a one-parameter family of two-surfaces \mathcal{S}_ρ :
 $\rho = \text{const}$ level surfaces of a smooth real function $\rho : \Sigma \rightarrow \mathbb{R}$ with $\partial_i \rho \neq 0$

$$\implies \hat{n}_i = \hat{N} \partial_i \rho \dots \& \dots h^{ij} \longrightarrow \hat{n}^i = h^{ij} \hat{n}_j$$

- choose ρ^i to be a vector field on Σ : the integral curves... & $\rho^i \partial_i \rho = 1$
- 'lapse' and 'shift' of ρ^i

$$\rho^i = \hat{N} \hat{n}^i + \hat{N}^i$$

$$\hat{\gamma}^i_j = \delta^i_j - \hat{n}^i \hat{n}_j, \quad \hat{N}^i = \hat{\gamma}^i_j \rho^j \quad \text{and} \quad \hat{\gamma}_{ij} = \hat{\gamma}^k_i \hat{\gamma}^l_j h_{kl}$$

- the metric h_{ij} can then be given as

$$h_{ij} = \hat{\gamma}_{ij} + \hat{n}_i \hat{n}_j$$



$$\{\hat{N}, \hat{N}^i, \hat{\gamma}_{ij}\}$$

2 + 1 decompositions:

Splitting of the symmetric tensor field K_{ij} :

-

$$K_{ij} = \kappa \hat{n}_i \hat{n}_j + [\hat{n}_i \mathbf{k}_j + \hat{n}_j \mathbf{k}_i] + \mathbf{K}_{ij}$$

where

$$\kappa = \hat{n}^k \hat{n}^l K_{kl}, \quad \mathbf{k}_i = \hat{\gamma}^k{}_i \hat{n}^l K_{kl} \quad \text{and} \quad \mathbf{K}_{ij} = \hat{\gamma}^k{}_i \hat{\gamma}^l{}_j K_{kl}$$

- the **trace** and **trace free** parts of \mathbf{K}_{ij}

$$\mathbf{K}^l{}_l = \hat{\gamma}^{kl} \mathbf{K}_{kl} \quad \text{and} \quad \hat{\mathbf{K}}_{ij} = \mathbf{K}_{ij} - \frac{1}{2} \hat{\gamma}_{ij} \mathbf{K}^l{}_l$$

The new variables:

-

$$(h_{ij}, K_{ij}) \iff (\hat{N}, \hat{N}^i, \hat{\gamma}_{ij}; \kappa, \mathbf{k}_i, \mathbf{K}^l{}_l, \hat{\mathbf{K}}_{ij})$$

- these variables retain the physically distinguished nature of h_{ij} and K_{ij}

2 + 1 decompositions:

Splitting of the symmetric tensor field K_{ij} :

-

$$K_{ij} = \kappa \hat{n}_i \hat{n}_j + [\hat{n}_i \mathbf{k}_j + \hat{n}_j \mathbf{k}_i] + \mathbf{K}_{ij}$$

where

$$\kappa = \hat{n}^k \hat{n}^l K_{kl}, \quad \mathbf{k}_i = \hat{\gamma}^k{}_i \hat{n}^l K_{kl} \quad \text{and} \quad \mathbf{K}_{ij} = \hat{\gamma}^k{}_i \hat{\gamma}^l{}_j K_{kl}$$

- the **trace** and **trace free** parts of \mathbf{K}_{ij}

$$\mathbf{K}^l{}_l = \hat{\gamma}^{kl} \mathbf{K}_{kl} \quad \text{and} \quad \mathring{\mathbf{K}}_{ij} = \mathbf{K}_{ij} - \frac{1}{2} \hat{\gamma}_{ij} \mathbf{K}^l{}_l$$

The new variables:

-

$$(h_{ij}, K_{ij}) \iff (\hat{N}, \hat{N}^i, \hat{\gamma}_{ij}; \kappa, \mathbf{k}_i, \mathbf{K}^l{}_l, \mathring{\mathbf{K}}_{ij})$$

- these variables retain the physically distinguished nature of h_{ij} and K_{ij}

2 + 1 decompositions:

Splitting of the symmetric tensor field K_{ij} :

-

$$K_{ij} = \kappa \hat{n}_i \hat{n}_j + [\hat{n}_i \mathbf{k}_j + \hat{n}_j \mathbf{k}_i] + \mathbf{K}_{ij}$$

where

$$\kappa = \hat{n}^k \hat{n}^l K_{kl}, \quad \mathbf{k}_i = \hat{\gamma}^k{}_i \hat{n}^l K_{kl} \quad \text{and} \quad \mathbf{K}_{ij} = \hat{\gamma}^k{}_i \hat{\gamma}^l{}_j K_{kl}$$

- the **trace** and **trace free** parts of \mathbf{K}_{ij}

$$\mathbf{K}^l{}_l = \hat{\gamma}^{kl} \mathbf{K}_{kl} \quad \text{and} \quad \mathring{\mathbf{K}}_{ij} = \mathbf{K}_{ij} - \frac{1}{2} \hat{\gamma}_{ij} \mathbf{K}^l{}_l$$

The new variables:

-

$$(h_{ij}, K_{ij}) \iff (\hat{N}, \hat{N}^i, \hat{\gamma}_{ij}; \kappa, \mathbf{k}_i, \mathbf{K}^l{}_l, \mathring{\mathbf{K}}_{ij})$$

- these variables retain the physically distinguished nature of h_{ij} and K_{ij}

2 + 1 decompositions:

Splitting of the symmetric tensor field K_{ij} :

-

$$K_{ij} = \kappa \hat{n}_i \hat{n}_j + [\hat{n}_i \mathbf{k}_j + \hat{n}_j \mathbf{k}_i] + \mathbf{K}_{ij}$$

where

$$\kappa = \hat{n}^k \hat{n}^l K_{kl}, \quad \mathbf{k}_i = \hat{\gamma}^k{}_i \hat{n}^l K_{kl} \quad \text{and} \quad \mathbf{K}_{ij} = \hat{\gamma}^k{}_i \hat{\gamma}^l{}_j K_{kl}$$

- the **trace** and **trace free** parts of \mathbf{K}_{ij}

$$\mathbf{K}^l{}_l = \hat{\gamma}^{kl} \mathbf{K}_{kl} \quad \text{and} \quad \mathring{\mathbf{K}}_{ij} = \mathbf{K}_{ij} - \frac{1}{2} \hat{\gamma}_{ij} \mathbf{K}^l{}_l$$

The new variables:

-

$$(h_{ij}, K_{ij}) \iff (\hat{N}, \hat{N}^i, \hat{\gamma}_{ij}; \kappa, \mathbf{k}_i, \mathbf{K}^l{}_l, \mathring{\mathbf{K}}_{ij})$$

- these variables retain the physically distinguished nature of h_{ij} and K_{ij}

The parabolic-hyperbolic form of the constraints:

An evolutionary system for the constrained fields \widehat{N} , \mathbf{k}_i and \mathbf{K}^l_l :

$$\begin{aligned} \dot{K}^* [(\partial_\rho \widehat{N}) - \widehat{N}^l (\widehat{D}_l \widehat{N})] - \widehat{N}^2 (\widehat{D}^l \widehat{D}_l \widehat{N}) - \mathcal{A} \widehat{N} + \mathcal{B} \widehat{N}^3 &= 0 \\ \mathcal{L}_{\widehat{n}} \mathbf{k}_i - \frac{1}{2} \widehat{D}_i (\mathbf{K}^l_l) - \widehat{D}_i \boldsymbol{\kappa} + \widehat{D}^l \overset{\circ}{\mathbf{K}}_{li} + \widehat{N} \dot{K}^* \mathbf{k}_i + [\boldsymbol{\kappa} - \frac{1}{2} (\mathbf{K}^l_l)] \dot{\widehat{n}}_i - \dot{\widehat{n}}^l \overset{\circ}{\mathbf{K}}_{li} &= 0 \\ \mathcal{L}_{\widehat{n}} (\mathbf{K}^l_l) - \widehat{D}^l \mathbf{k}_l - \widehat{N} \dot{K}^* [\boldsymbol{\kappa} - \frac{1}{2} (\mathbf{K}^l_l)] + \widehat{N} \overset{\circ}{\mathbf{K}}_{kl} \dot{K}^{*kl} + 2 \dot{\widehat{n}}^l \mathbf{k}_l &= 0, \end{aligned}$$

where \widehat{D}_i denotes the covariant derivative operator associated with $\widehat{\gamma}_{ij}$

$$\dot{K}^* = \frac{1}{2} \widehat{\gamma}^{ij} \mathcal{L}_\rho \widehat{\gamma}_{ij} - \widehat{D}_j \widehat{N}^j$$

$$\begin{aligned} \dot{K}^*_{ij} &= \frac{1}{2} \mathcal{L}_\rho \widehat{\gamma}_{ij} - \widehat{D}_{(i} \widehat{N}_{j)}, & \dot{\widehat{n}}_k &= \widehat{n}^l D_l \widehat{n}_k = -\widehat{D}_k (\ln \widehat{N}) \\ \mathcal{A} &= (\partial_\rho \dot{K}^*) - \widehat{N}^l (\widehat{D}_l \dot{K}^*) + \frac{1}{2} [\dot{K}^{*2} + \dot{K}^*_{kl} \dot{K}^{*kl}] \\ \mathcal{B} &= \frac{1}{2} [\widehat{R} + 2 \boldsymbol{\kappa} (\mathbf{K}^l_l) + \frac{1}{2} (\mathbf{K}^l_l)^2 - 2 \mathbf{k}^l \mathbf{k}_l - \overset{\circ}{\mathbf{K}}_{kl} \overset{\circ}{\mathbf{K}}^{kl}] \end{aligned}$$

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\widehat{N}^i, \widehat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{K}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\widehat{\gamma}_{ij}$ and $\widehat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields \widehat{N}, κ_i and $K^l{}_l$ are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\widehat{N}^i, \widehat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{K}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\widehat{\gamma}_{ij}$ and $\widehat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields \widehat{N}, κ_i and $\overset{\circ}{K}^i{}_j$ are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{K}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\hat{\gamma}_{ij}$ and $\hat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields \hat{N}, κ_i and K^i_j are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{\mathbf{K}}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\hat{\gamma}_{ij}$ and $\hat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields \hat{N}, \mathbf{k}_i and \mathbf{K}^l_l are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{\mathbf{K}}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\hat{\gamma}_{ij}$ and $\hat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields \hat{N}, \mathbf{k}_i and \mathbf{K}^l_l are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The parabolic-hyperbolic system:

The parabolic-hyperbolic system:

- no restriction applies to $\widehat{N}^i, \widehat{\gamma}_{ij}, \kappa$ and $\overset{\circ}{\mathbf{K}}_{ij} \implies$ they are freely specifiable throughout Σ
- the parabolic equation is uniformly parabolic in those subregions of Σ , where $\overset{\star}{K}$ is either positive or negative
- $\overset{\star}{K}$ depends exclusively on the freely specifiable fields $\widehat{\gamma}_{ij}$ and $\widehat{N}^i \implies$ its sign can be tailored according to the desire of the investigated problem
- the combined evolutionary system is (locally) well-posed
 - if suitable initial values for the constrained fields $\widehat{N}, \mathbf{k}_i$ and \mathbf{K}^l_l are given, on some level surface \mathcal{S}_0 in Σ , then, in the domain of dependence of \mathcal{S}_0 , unique solution exists to the evolutionary system
 - the fields h_{ij} and K_{ij} that can be reconstructed from the freely specifiable and constrained variables do satisfy the Hamiltonian and momentum constraints

The Kerr black hole:

In Kerr-Schild form:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H\ell_{\alpha}\ell_{\beta}$$

- inertial coordinates (t, x, y, z) adapted to the Minkowski background $\eta_{\alpha\beta}$

$$H = \frac{r^3 M}{r^4 + a^2 z^2}$$

$$\ell_{\alpha} = \left(1, \frac{rx+ay}{r^2+a^2}, \frac{ry-ax}{r^2+a^2}, \frac{z}{r} \right)$$

- the Boyer-Lindquist radial coordinate r is related to the spatial part of the inertial coordinates as

$$r^4 - (x^2 + y^2 + z^2 - a^2)r^2 - a^2 z^2 = 0$$

The Kerr black hole:

In Kerr-Schild form:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H\ell_{\alpha}\ell_{\beta}$$

- inertial coordinates (t, x, y, z) adapted to the Minkowski background $\eta_{\alpha\beta}$

$$H = \frac{r^3 M}{r^4 + a^2 z^2}$$

$$\ell_{\alpha} = \left(1, \frac{rx+ay}{r^2+a^2}, \frac{ry-ax}{r^2+a^2}, \frac{z}{r} \right)$$

- the Boyer-Lindquist radial coordinate r is related to the spatial part of the inertial coordinates as

$$r^4 - (x^2 + y^2 + z^2 - a^2)r^2 - a^2 z^2 = 0$$

The Kerr black hole:

In Kerr-Schild form:



$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H\ell_{\alpha}\ell_{\beta}$$

- inertial coordinates (t, x, y, z) adapted to the Minkowski background $\eta_{\alpha\beta}$

$$H = \frac{r^3 M}{r^4 + a^2 z^2}$$

$$\ell_{\alpha} = \left(1, \frac{rx+ay}{r^2+a^2}, \frac{ry-ax}{r^2+a^2}, \frac{z}{r} \right)$$

- the Boyer-Lindquist radial coordinate r is related to the spatial part of the inertial coordinates as

$$r^4 - (x^2 + y^2 + z^2 - a^2)r^2 - a^2 z^2 = 0$$

The Kerr black hole:

In Kerr-Schild form:



$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H\ell_{\alpha}\ell_{\beta}$$

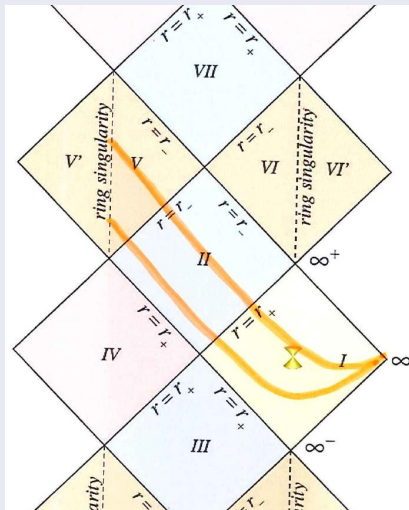
- inertial coordinates (t, x, y, z) adapted to the Minkowski background $\eta_{\alpha\beta}$

$$H = \frac{r^3 M}{r^4 + a^2 z^2}$$

$$\ell_{\alpha} = \left(1, \frac{rx+ay}{r^2+a^2}, \frac{ry-ax}{r^2+a^2}, \frac{z}{r} \right)$$

- the Boyer-Lindquist radial coordinate r is related to the spatial part of the inertial coordinates as

$$r^4 - (x^2 + y^2 + z^2 - a^2)r^2 - a^2 z^2 = 0$$

$t = \text{const}$ slices in Kerr spacetime:

the $\theta = \frac{\pi}{2}$ section

$$\Sigma \approx \mathbb{R}^3 \setminus \{ \text{"ring singularity"} \}$$

Generic Kerr-Schild black holes:

- the Kerr-Schild metrics are form-invariant under Lorentz transformations
 - if a Lorentz transformation $x'^{\alpha} = \Lambda^{\alpha}_{\beta} x^{\beta}$ is performed
 - the metric retains its distinguished Kerr-Schild form

$$g'_{\alpha\beta} = \eta_{\alpha\beta} + 2H'\ell'_{\alpha}\ell'_{\beta}$$

- where $H' = H'(x'^{\alpha})$ and $\ell'_{\beta} = \ell'_{\beta}(x'^{\epsilon})$ are given as

$$H' = H([\Lambda^{\alpha}_{\beta}]^{-1}x'^{\beta}), \quad \ell'_{\beta} = \Lambda^{\alpha}_{\beta}\ell_{\alpha}([\Lambda^{\epsilon}_{\varphi}]^{-1}x'^{\varphi})$$

- boosts and spatial rotations are special Lorentz transformations \implies it is straightforward to construct models of moving and rotating black holes with preferably oriented speed and spin

Generic Kerr-Schild black holes:

- the Kerr-Schild metrics are form-invariant under Lorentz transformations
 - if a Lorentz transformation $x'^{\alpha} = \Lambda^{\alpha}_{\beta} x^{\beta}$ is performed
 - the metric retains its distinguished Kerr-Schild form

$$g'_{\alpha\beta} = \eta_{\alpha\beta} + 2H'\ell'_{\alpha}\ell'_{\beta}$$

- where $H' = H'(x'^{\alpha})$ and $\ell'_{\beta} = \ell'_{\beta}(x'^{\epsilon})$ are given as

$$H' = H([\Lambda^{\alpha}_{\beta}]^{-1}x'^{\beta}), \quad \ell'_{\beta} = \Lambda^{\alpha}_{\beta}\ell_{\alpha}([\Lambda^{\epsilon}_{\varphi}]^{-1}x'^{\varphi})$$

- boosts and spatial rotations are special Lorentz transformations \implies it is straightforward to construct models of moving and rotating black holes with preferably oriented speed and spin

Generic Kerr-Schild black holes:

- the Kerr-Schild metrics are form-invariant under Lorentz transformations
 - if a Lorentz transformation $x'^{\alpha} = \Lambda^{\alpha}_{\beta} x^{\beta}$ is performed
 - the metric retains its distinguished Kerr-Schild form

$$g'_{\alpha\beta} = \eta_{\alpha\beta} + 2H'\ell'_{\alpha}\ell'_{\beta}$$

- where $H' = H'(x'^{\alpha})$ and $\ell'_{\beta} = \ell'_{\beta}(x'^{\epsilon})$ are given as

$$H' = H([\Lambda^{\alpha}_{\beta}]^{-1}x'^{\beta}), \quad \ell'_{\beta} = \Lambda^{\alpha}_{\beta}\ell_{\alpha}([\Lambda^{\epsilon}_{\varphi}]^{-1}x'^{\varphi})$$

- boosts and spatial rotations are special Lorentz transformations \implies it is straightforward to construct models of moving and rotating black holes with preferably oriented speed and spin

Generic Kerr-Schild black holes:

- the Kerr-Schild metrics are form-invariant under Lorentz transformations
 - if a Lorentz transformation $x'^{\alpha} = \Lambda^{\alpha}_{\beta} x^{\beta}$ is performed
 - the metric retains its distinguished Kerr-Schild form

$$g'_{\alpha\beta} = \eta_{\alpha\beta} + 2H'\ell'_{\alpha}\ell'_{\beta}$$

- where $H' = H'(x'^{\alpha})$ and $\ell'_{\beta} = \ell'_{\beta}(x'^{\epsilon})$ are given as

$$H' = H([\Lambda^{\alpha}_{\beta}]^{-1}x'^{\beta}), \quad \ell'_{\beta} = \Lambda^{\alpha}_{\beta}\ell_{\alpha}([\Lambda^{\epsilon}_{\varphi}]^{-1}x'^{\varphi})$$

- boosts and spatial rotations are special Lorentz transformations \implies it is straightforward to construct models of moving and rotating black holes with preferably oriented speed and spin

Generic Kerr-Schild black holes:

- the Kerr-Schild metrics are form-invariant under Lorentz transformations
 - if a Lorentz transformation $x'^{\alpha} = \Lambda^{\alpha}_{\beta} x^{\beta}$ is performed
 - the metric retains its distinguished Kerr-Schild form

$$g'_{\alpha\beta} = \eta_{\alpha\beta} + 2H'\ell'_{\alpha}\ell'_{\beta}$$

- where $H' = H'(x'^{\alpha})$ and $\ell'_{\beta} = \ell'_{\beta}(x'^{\epsilon})$ are given as

$$H' = H([\Lambda^{\alpha}_{\beta}]^{-1}x'^{\beta}), \quad \ell'_{\beta} = \Lambda^{\alpha}_{\beta}\ell_{\alpha}([\Lambda^{\epsilon}_{\varphi}]^{-1}x'^{\varphi})$$

- boosts and spatial rotations are special Lorentz transformations \implies it is straightforward to construct models of moving and rotating black holes with preferably oriented speed and spin

Superposed Kerr-Schild black holes:

A binary system will be approximated by:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H^{[1]}\ell_{\alpha}^{[1]}\ell_{\beta}^{[1]} + 2H^{[2]}\ell_{\alpha}^{[2]}\ell_{\beta}^{[2]} \quad (*)$$

- $H^{[n]}$ and $\ell_{\alpha}^{[n]}$ correspond to the Kerr-Schild data for individual black holes
- good approximation close to the individual black holes
- Einstein tensor falls off at the rate $\mathcal{O}(|\vec{x}|^{-4})$, where $|\vec{x}| = \sqrt{x^2 + y^2 + z^2}$

Choice for the free data:

- $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\hat{\mathbf{K}}_{ij}$ as if (*) solved the Einstein equations
- \hat{N}, \mathbf{K}^l_l and \mathbf{k}_i on some level surface \mathcal{S}_0 in Σ deduced from (*) [only on \mathcal{S}_0 !]

Superposed Kerr-Schild black holes:

A binary system will be approximated by:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H^{[1]}\ell_{\alpha}^{[1]}\ell_{\beta}^{[1]} + 2H^{[2]}\ell_{\alpha}^{[2]}\ell_{\beta}^{[2]} \quad (*)$$

- $H^{[n]}$ and $\ell_{\alpha}^{[n]}$ correspond to the Kerr-Schild data for individual black holes
- good approximation close to the individual black holes
- Einstein tensor falls off at the rate $\mathcal{O}(|\vec{x}|^{-4})$, where $|\vec{x}| = \sqrt{x^2 + y^2 + z^2}$

Choice for the free data:

- $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\hat{\mathbf{K}}_{ij}$ as if (*) solved the Einstein equations
- \hat{N}, \mathbf{K}^l_l and \mathbf{k}_i on some level surface \mathcal{S}_0 in Σ deduced from (*) [only on \mathcal{S}_0 !]

Superposed Kerr-Schild black holes:

A binary system will be approximated by:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H^{[1]}\ell_{\alpha}^{[1]}\ell_{\beta}^{[1]} + 2H^{[2]}\ell_{\alpha}^{[2]}\ell_{\beta}^{[2]} \quad (*)$$

- $H^{[n]}$ and $\ell_{\alpha}^{[n]}$ correspond to the Kerr-Schild data for individual black holes
- good approximation close to the individual black holes
- Einstein tensor falls off at the rate $\mathcal{O}(|\vec{x}|^{-4})$, where $|\vec{x}| = \sqrt{x^2 + y^2 + z^2}$

Choice for the free data:

- $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\hat{\mathbf{K}}_{ij}$ as if (*) solved the Einstein equations
- \hat{N}, \mathbf{K}^l_l and \mathbf{k}_i on some level surface \mathcal{S}_0 in Σ deduced from (*) [only on \mathcal{S}_0 !]

Superposed Kerr-Schild black holes:

A binary system will be approximated by:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H^{[1]}\ell_{\alpha}^{[1]}\ell_{\beta}^{[1]} + 2H^{[2]}\ell_{\alpha}^{[2]}\ell_{\beta}^{[2]} \quad (*)$$

- $H^{[n]}$ and $\ell_{\alpha}^{[n]}$ correspond to the Kerr-Schild data for individual black holes
- good approximation close to the individual black holes
- Einstein tensor falls off at the rate $\mathcal{O}(|\vec{x}|^{-4})$, where $|\vec{x}| = \sqrt{x^2 + y^2 + z^2}$

Choice for the free data:

- $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\hat{\mathbf{K}}_{ij}$ as if (*) solved the Einstein equations
- \hat{N}, \mathbf{K}^l_l and \mathbf{k}_i on some level surface \mathcal{S}_0 in Σ deduced from (*) [only on \mathcal{S}_0 !]

Superposed Kerr-Schild black holes:

A binary system will be approximated by:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + 2H^{[1]}\ell_{\alpha}^{[1]}\ell_{\beta}^{[1]} + 2H^{[2]}\ell_{\alpha}^{[2]}\ell_{\beta}^{[2]} \quad (*)$$

- $H^{[n]}$ and $\ell_{\alpha}^{[n]}$ correspond to the Kerr-Schild data for individual black holes
- good approximation close to the individual black holes
- Einstein tensor falls off at the rate $\mathcal{O}(|\vec{x}|^{-4})$, where $|\vec{x}| = \sqrt{x^2 + y^2 + z^2}$

Choice for the free data:

- $\hat{N}^i, \hat{\gamma}_{ij}, \kappa$ and $\hat{\mathbf{K}}_{ij}$ as if (*) solved the Einstein equations
- \hat{N}, \mathbf{K}^l_l and \mathbf{k}_i on some level surface \mathcal{S}_0 in Σ deduced from (*) [only on \mathcal{S}_0 !]

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :

- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K} from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :

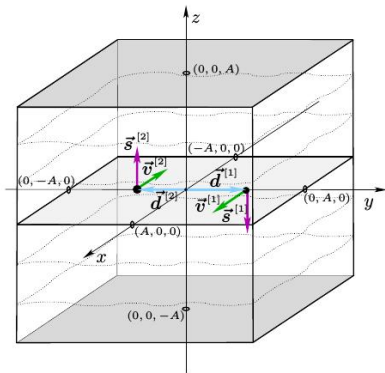
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K} from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



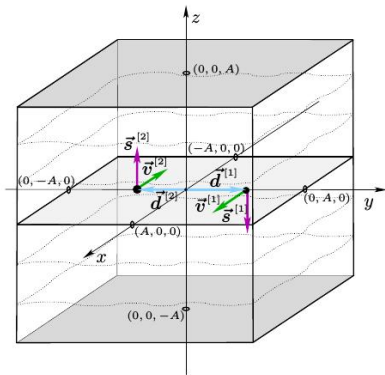
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



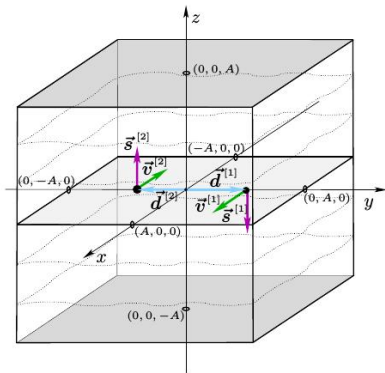
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



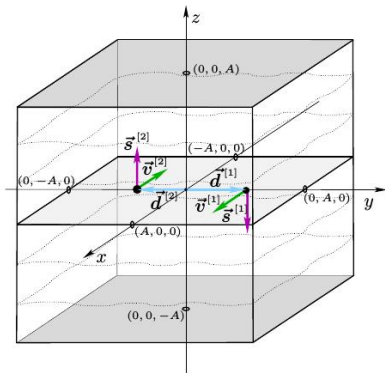
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



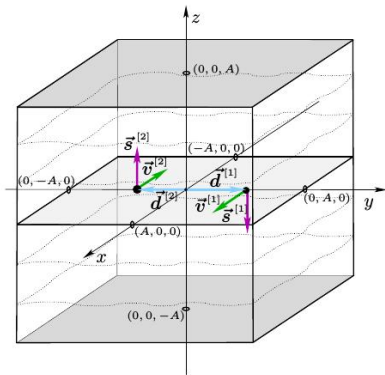
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



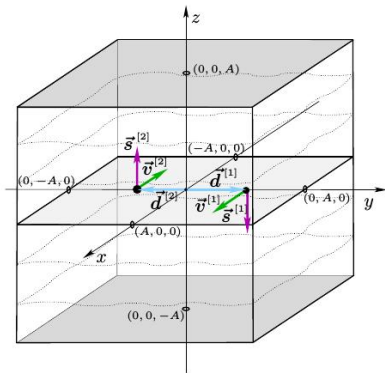
- for large enough value of A ...
- boundary of Σ :
six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



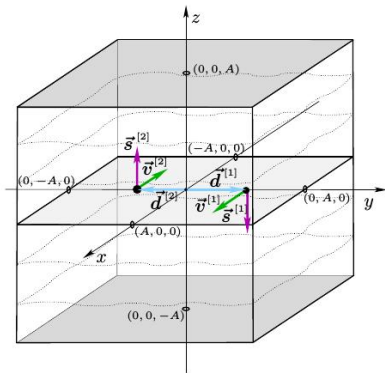
- for large enough value of A ...
- boundary of Σ :
 - six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce \hat{K}^* from (*)

The initial-boundary value problem:

the \mathcal{S}_ρ surfaces have tacitly been assumed to be compact without boundary:

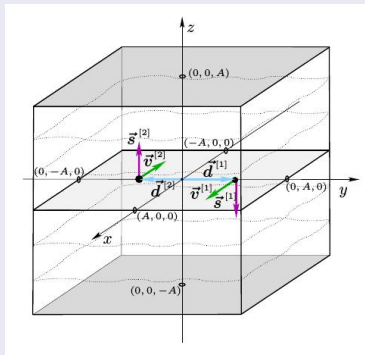
- in numerical approaches Σ is chosen to be a large but bounded subset of \mathbb{R}^3
- the product structure $\Sigma \approx \mathbb{R} \times \mathcal{S}$ can be guaranteed by choosing the \mathcal{S}_ρ leaves to be diffeomorphic to a closed disk in \mathbb{R}^2

choose Σ to be a cube centered at the origin in \mathbb{R}^3 :



- for large enough value of A ...
- boundary of Σ :
six squares each with edges of size $2A$
- the black holes are assumed to be located on the $z = 0$ plane
- speeds are parallel, spins are orthogonal to the $z = 0$ plane
- foliation by $z = \text{const}$ level surfaces
- deduce K^* from (*)

The critical coefficient \hat{K}^* :

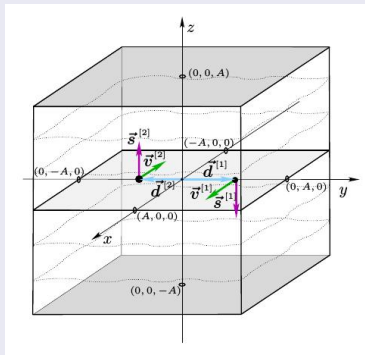


- the sign of \hat{K}^* decides whether the parabolic-hyperbolic system evolves in the positive or negative ρ -direction

$$\hat{K}^* [(\partial_\rho \hat{N}) - \hat{N}^l (\hat{D}_l \hat{N})] = \hat{N}^2 (\hat{D}^l \hat{D}_l \hat{N}) + \mathcal{A} \hat{N} + \mathcal{B} \hat{N}^3$$

- it propagates aligned ρ^i for positive \hat{K}^* , while anti-aligned for negative \hat{K}^*
- restrict considerations to a binary BH system arranged as indicated on the figure

The critical coefficient \hat{K}^* :

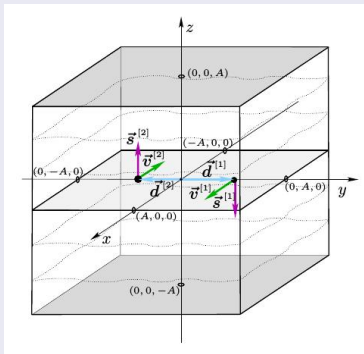


- the sign of \hat{K}^* decides whether the parabolic-hyperbolic system evolves in the positive or negative ρ -direction

$$\hat{K}^* [(\partial_\rho \hat{N}) - \hat{N}^l (\hat{D}_l \hat{N})] = \hat{N}^2 (\hat{D}^l \hat{D}_l \hat{N}) + \mathcal{A} \hat{N} + \mathcal{B} \hat{N}^3$$

- it propagates aligned ρ^i for positive \hat{K}^* , while anti-aligned for negative \hat{K}^*
- restrict considerations to a binary BH system arranged as indicated on the figure

The critical coefficient \hat{K}^* :



- the sign of \hat{K}^* decides whether the parabolic-hyperbolic system evolves in the positive or negative ρ -direction

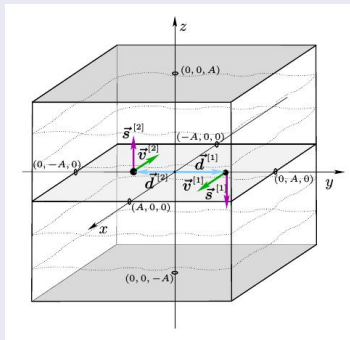
$$\hat{K}^* [(\partial_\rho \hat{N}) - \hat{N}^l (\hat{D}_l \hat{N})] = \hat{N}^2 (\hat{D}^l \hat{D}_l \hat{N}) + \mathcal{A} \hat{N} + \mathcal{B} \hat{N}^3$$

- it propagates aligned ρ^i for positive \hat{K}^* , while anti-aligned for negative \hat{K}^*
- restrict considerations to a binary BH system arranged as indicated on the figure

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube

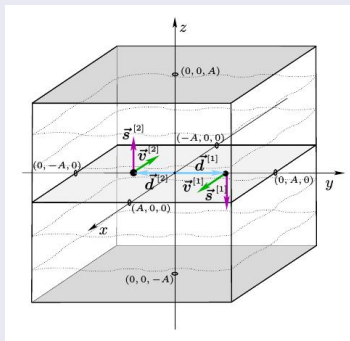


- \hat{N} , \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
- the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
- (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube

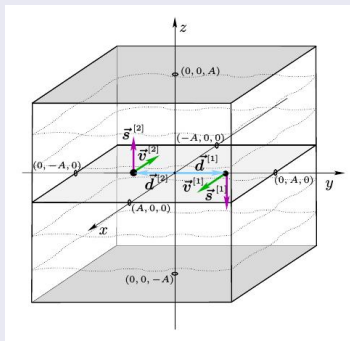


- \hat{N} , \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
- the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
- (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube

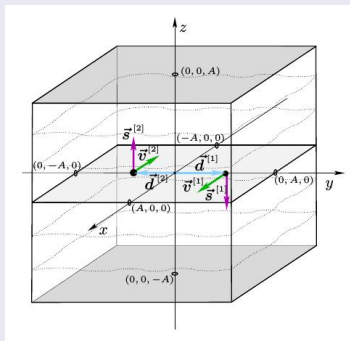


- \hat{N} , \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
- the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
- (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube

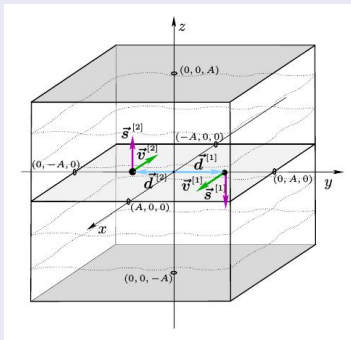


- \hat{N} , \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
- the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
- (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

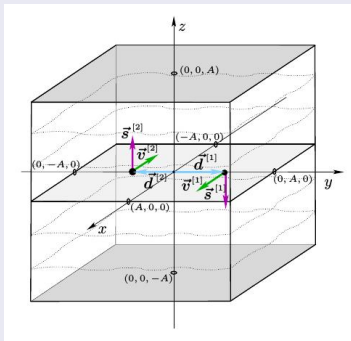
- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube
- \hat{N}, \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
 - the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
 - (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified



Solving the initial-boundary value problem:

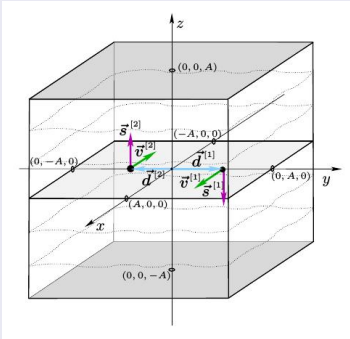
The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube
- \hat{N}, \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
 - the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
 - (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified



Solving the initial-boundary value problem:

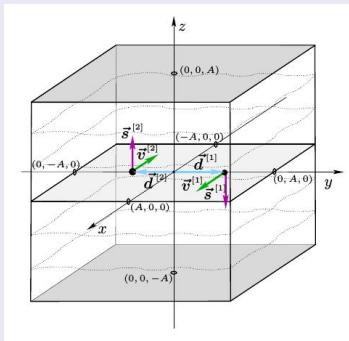
The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
 - \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
 - solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
 - boundary values are to be given on the four vertical sides of the cube
- 
- \hat{N}, \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
 - the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
 - (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified

Solving the initial-boundary value problem:

The parabolic-hyperbolic system:

- \hat{K}^* can be given as $\hat{K}^* = -z \cdot \hat{K}^\dagger$
- \hat{K}^* is positive below the $z = 0$ plane, while it is negative above that plane
- solved by propagating, along the z -streamlines, initial values specified on the horizontal $z = \pm A$ squares
- boundary values are to be given on the four vertical sides of the cube
- \hat{N}, \mathbf{K}^l_i and \mathbf{k}_i are developed on Σ^+ and Σ^- separately
 - global existence and matching of these solutions at their common Cauchy horizon—at the $z = 0$ plane—is of fundamental importance
- the auxiliary metric (*) possesses a $z \rightarrow -z$ reflection symmetry
- (apart from singularities) the existence of unique (at least) C^2 solutions with proper matching at the “common Cauchy horizon” can be verified



Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Input parameters and global ADM charges:

- **Input parameters:** the rest masses $M^{[n]}$, displacements $\vec{d}^{[n]}$, speeds $\vec{v}^{[n]}$ and spins $a^{[n]}\vec{s}_o^{[n]}$ of the involved black holes
 - essentially the same as used in post-Newtonian description of binaries !!!
- **Global ADM charges:** in terms of the input parameters
 - though (*) does not satisfy Einstein's equations it is asymptotically flat
 - constructed by adding contributions of individual black hole metrics to a Minkowski background
 - the ADM quantities are linear in deviation from flat Euclidean space at infinity

$$\begin{aligned}
 M^{ADM} &= \gamma^{[1]} M^{[1]} + \gamma^{[2]} M^{[2]} \\
 M^{ADM} \vec{d}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{d}^{[1]} + \gamma^{[2]} M^{[2]} \vec{d}^{[2]} \\
 \vec{P}^{ADM} &= \gamma^{[1]} M^{[1]} \vec{v}^{[1]} + \gamma^{[2]} M^{[2]} \vec{v}^{[2]} \\
 \vec{J}^{ADM} &= \gamma^{[1]} \left\{ M^{[1]} \vec{d}^{[1]} \times \vec{v}^{[1]} + M^{[1]} a^{[1]} \vec{s}_o^{[1]} \right\} \\
 &\quad + \gamma^{[2]} \left\{ M^{[2]} \vec{d}^{[2]} \times \vec{v}^{[2]} + M^{[2]} a^{[2]} \vec{s}_o^{[2]} \right\}
 \end{aligned}$$

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

Summary:

- 1 a new method to initialize time evolution of binary black hole systems by applying
 - a parabolic-hyperbolic formulation of constraint equations
 - superposing Kerr-Schild black holes
- 2 the parabolic-hyperbolic equations solved as an initial-boundary value problem
- 3 existence of unique (at least) C^2 solutions is guaranteed (apart from singularities)
- 4 **!!!** Anna Nakonieczna's talk in the afternoon: construct initial data by integrating numerically the parabolic-hyperbolic form of the constraints
- 5 the input parameters—the rest masses, speeds, spins and displacements—are essentially the same as used in PN **!!!**
- 6 each of the ADM charges can be given in terms of the input parameters
- 7 no use of boundary conditions in the strong field regime (tidal deformations)

The ADM quantities as flux integrals:

- in the applied admissible coordinates the ADM mass, center of mass, linear and angular momenta are determined by the flux integrals

$$\begin{aligned}
 M^{ADM} &= \frac{1}{16\pi} \oint_{\infty} [\partial_i h_{ij} - \partial_j h_{ii}] n^j dS \\
 M^{ADM} d_i &= \frac{1}{16\pi} \oint_{\infty} \left\{ x_i [\partial_k h_{kj} - \partial_j h_{kk}] - [h_{kj} \delta^k_i - h_{kk} \delta_{ij}] \right\} n^j dS \\
 P_i^{ADM} &= \frac{1}{8\pi} \oint_{\infty} [K_{ij} - h_{kj} K^l_l] n^j dS \\
 J_i^{ADM} &= \frac{1}{8\pi} \oint_{\infty} [K_{kj} - h_{kj} K^l_l] Y_i^k n^j dS
 \end{aligned}$$

- the symbol \oint_{∞} is meant to denote limits of integrals over spheres while their radii tend to infinity
- n^i and dS denote the outward normal and the volume element of the individual spheres in the sequences
- the symbol $Y_i^k = \epsilon_i^{jk} x_j$ denote the components of the three rotational Killing vector fields, defined with respect to the applied admissible asymptotically Euclidean coordinates