Prototype of a charged particles tracking device

Vlad Fabbri ISHEP BCD School 2017

Introduction

Realization of charged particles prototype tracker device.

→ Triangular scintillator bars coupled to silicon photomultipliers (SiPM). Analog readout of the SiPM signal.

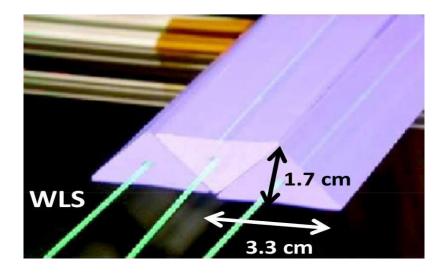
In this thesis:

- Evaluation of the tracker resolution by using MC simulations data
- Evaluation of the tracker resolution by using the data of a test beam

Tracker

Scintillator bars

- Lenght 30 cm
- Triangular cross-section
- Central hole Ø 2.6 mm
- Wavelength shifting fiber, WLS
 Ø = 2 mm , Blue to Green Shifter



Light collection

- 3x3 mm² SiPM
- Analog readout of the output signal from the SiPM

Triangular cross-section

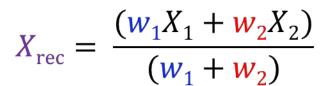
Position reconstruction compairing the deposited energy in adjacent bars

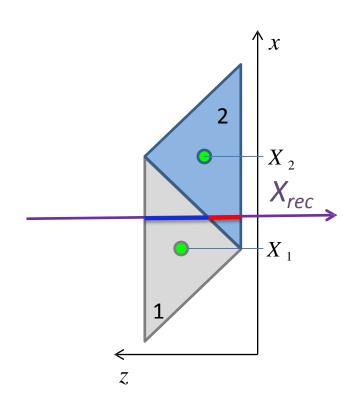
Position reconstruction

For high momentum charged particles the path through the tracker is approximately straight.

In this case:

- The deposited energy in the detector is proportional to the crossed section leght
- The pulse heigth w_i is proportional to the deposited energy.





Experimental setup

5 modules at 25 cm from each other made of 2 planes of 16 scintillators bars. 160 Channels.

For the analog reading of the SiPM it has been used a EASIROC chip whose signal is acquired via a chain of NIM and VME modules.



Bars of consecutive planes are perpendicular to each other

X and Y reconstructed position of the particle.

MC Simulations

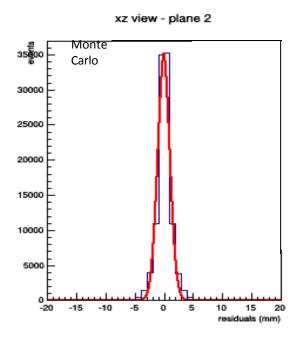
- "Clean" events selection : only two fired channels on each plane : $\mu^+ \sim \! 65\% \ , \ \pi^+ \sim \ 50\%$

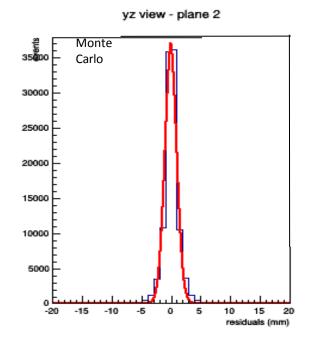
- Reconstruction of particle position on each plane

- Linear fit on both the YZ and XZ projections by using the reconstructed positions on each plane

Results from MC simulations

From the residual distribution between the recontructed position and the fitted one it's possible to evaluate the tracker resolution

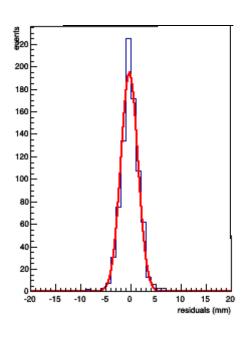


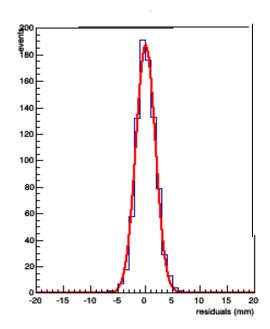


For 5 GeV π^+ events the resolution ~ 1.5 mm.

Resolution using real data

 From the residual distribution between the lineat fit and the recontructed position it's possible to evaluate the tracker prototype spatial resolution





Spatial resolution

~ 2 mm (preliminary)

Conclusions

It's possible to improve this resolution introducing some corrections like the recalibration of the individual channel signals and then analysing all the data.

Thank you

