

The new MYTHEN III detector prototype

Microstrip sYstem for Time rEsolved experimeNts

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Wir schaffen Wissen - heute für morgen

The new Mythen III chip

What is MYTHEN?

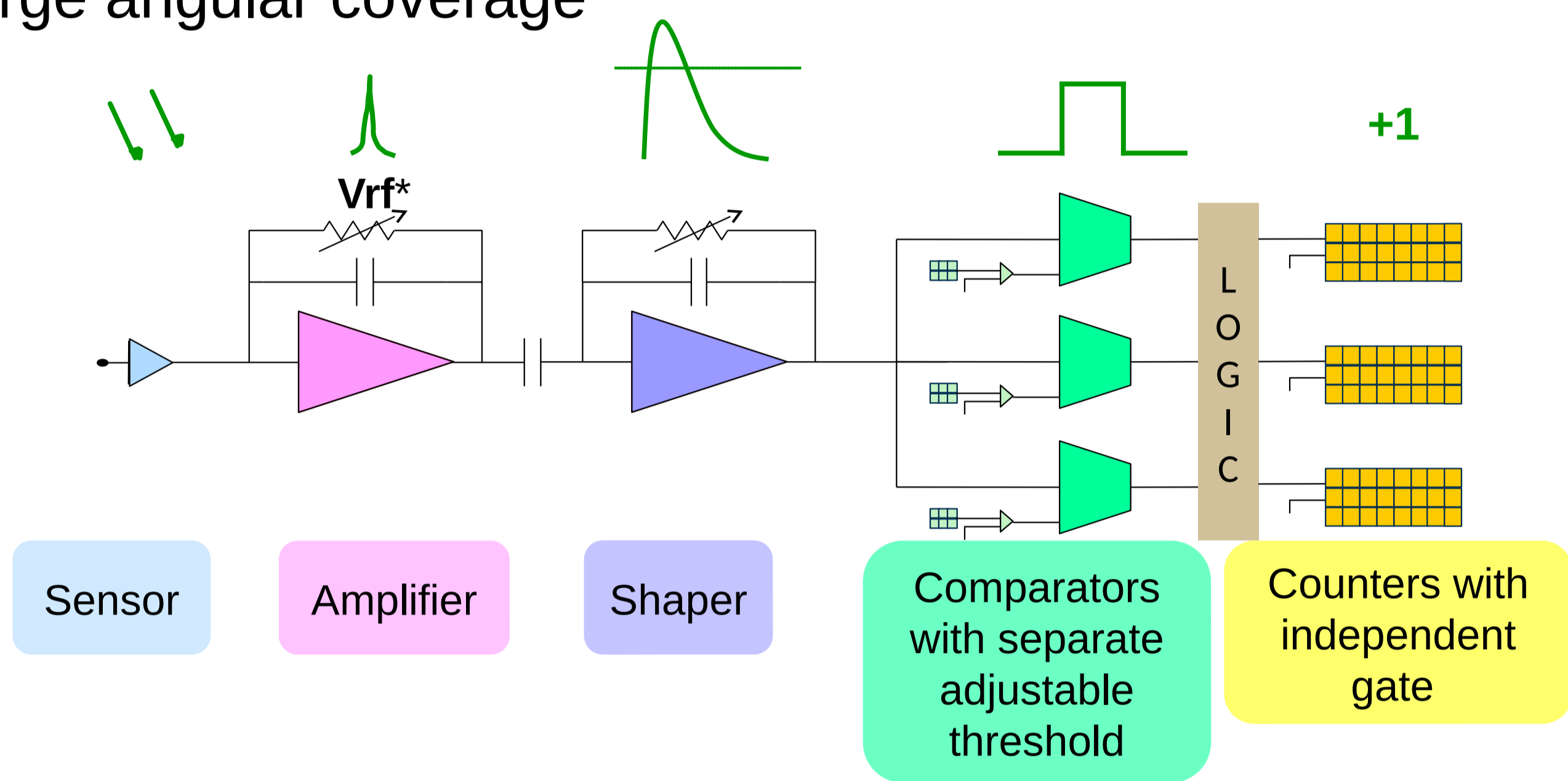
- silicon microstrip detector with 50 μm pitch, 8 mm long strips
- single photon counting
- for time-resolved powder diffraction, medical imaging, etc

Why a strip detector?

- less channels per area:
 - fast frame rates
- small pitches possible:
 - high resolution
- large angular coverage

Why photon counting?

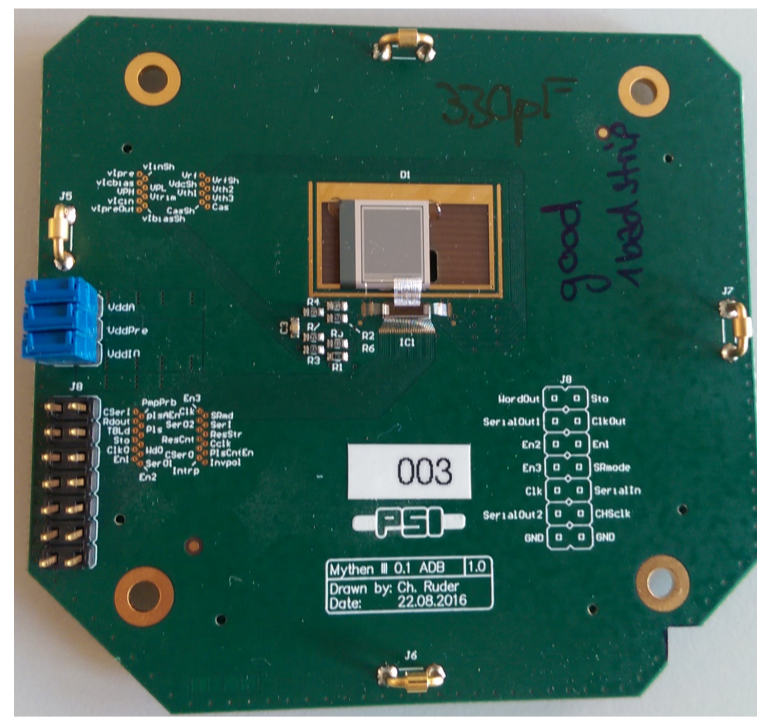
- ideally noiseless
- large dynamic range
- fluorescence suppression



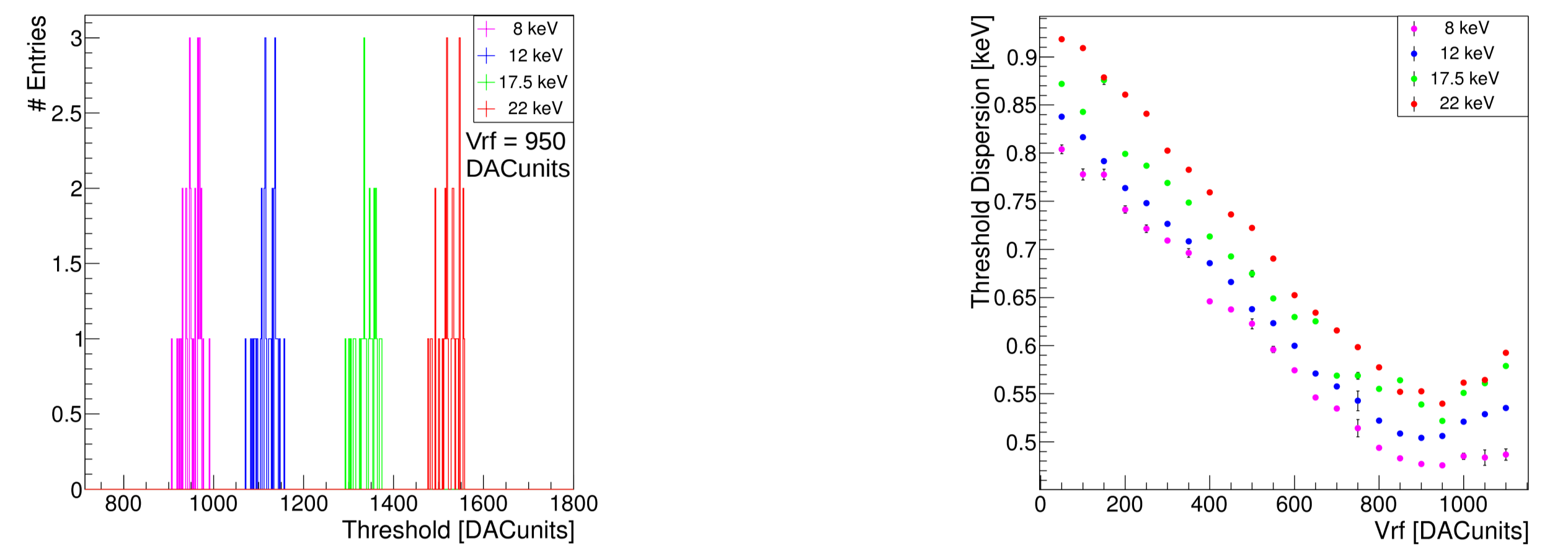
*Vrf changes the feedback resistance, i.e. the gain and shaping time

What is new?

- three comparators and three 24-bit-counters for:
 - energy-windowing
 - count rate improvement (track pile-up)
 - pump-probing with multiple time slots, counters are independently gateable
- reduced threshold dispersion
- improved noise performance
- small dead time → increased count rate capability



Untrimmed threshold dispersion

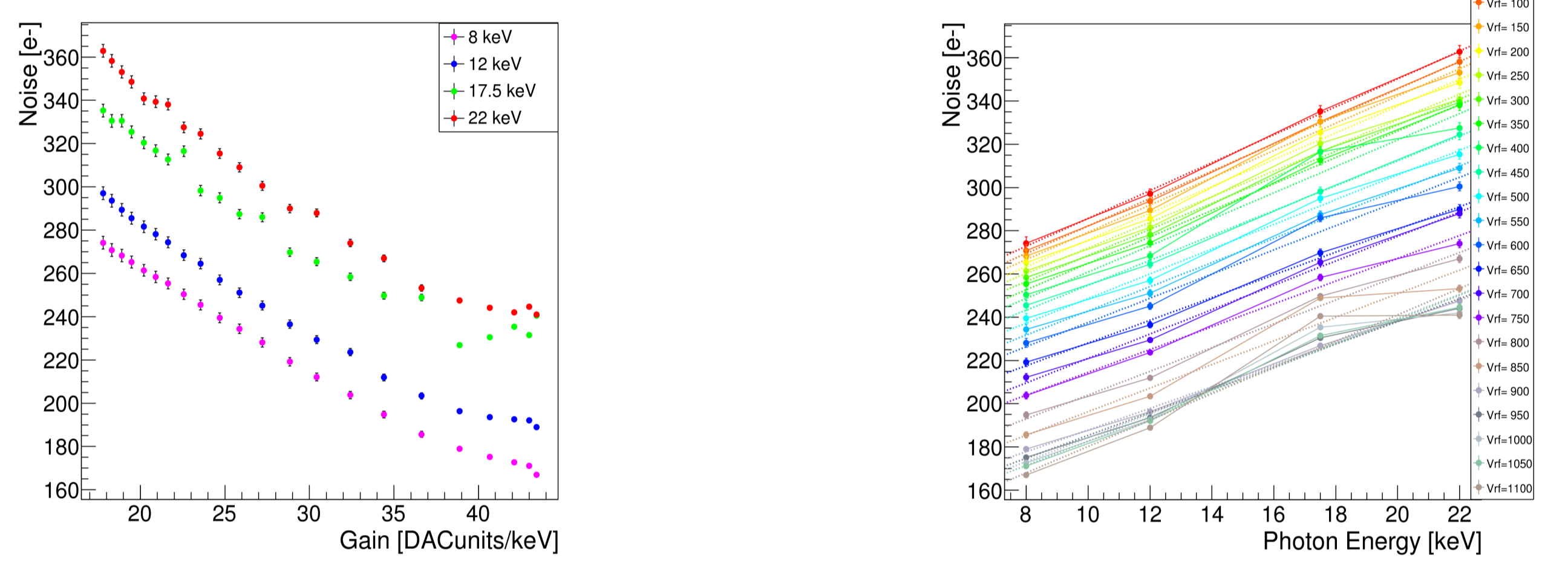


The threshold dispersion is given by the spread of the inflection points, i.e. the resulting thresholds, over all sensor-strips.

The threshold dispersion

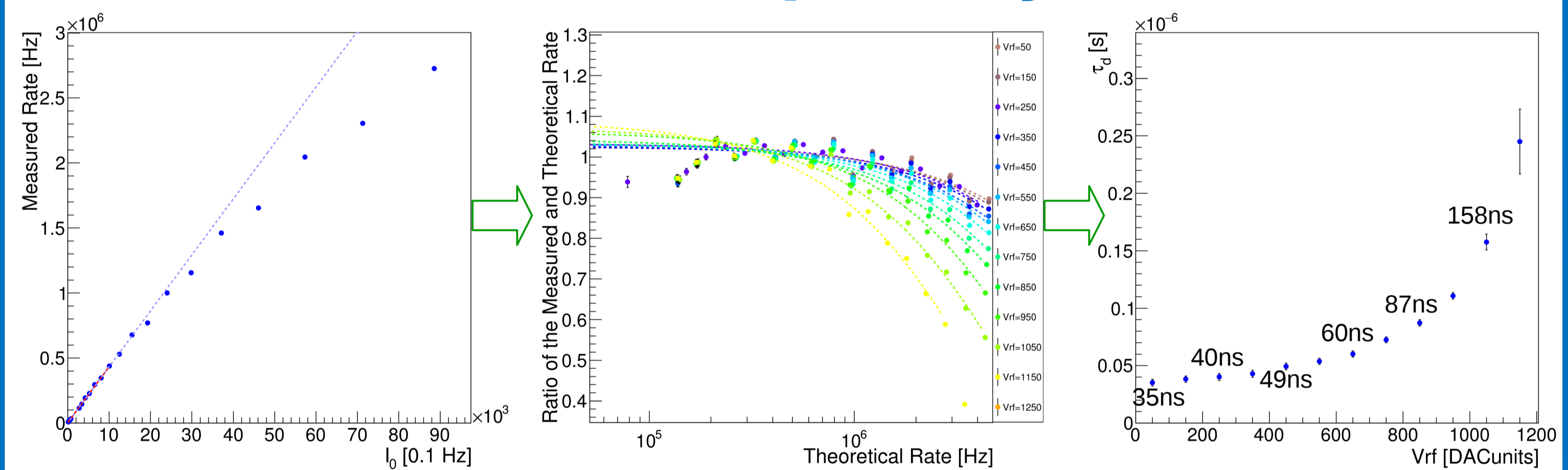
- depends on the gain (Vrf) ✓
- depends slightly on the photon energy ?
- 2.5-4.5% at 22 keV
- 6-10% at 8 keV

Noise performance



The noise decreases with increasing gain ✓ and falls below 200 e- at moderate gains ✓, but depends linearly on the photon energy ?

Rate capability



1. Plot the measured rate vs the reference rate I_0^*
 *given by the beamline
 2. Estimate the ideal theoretical rate with a linear fit

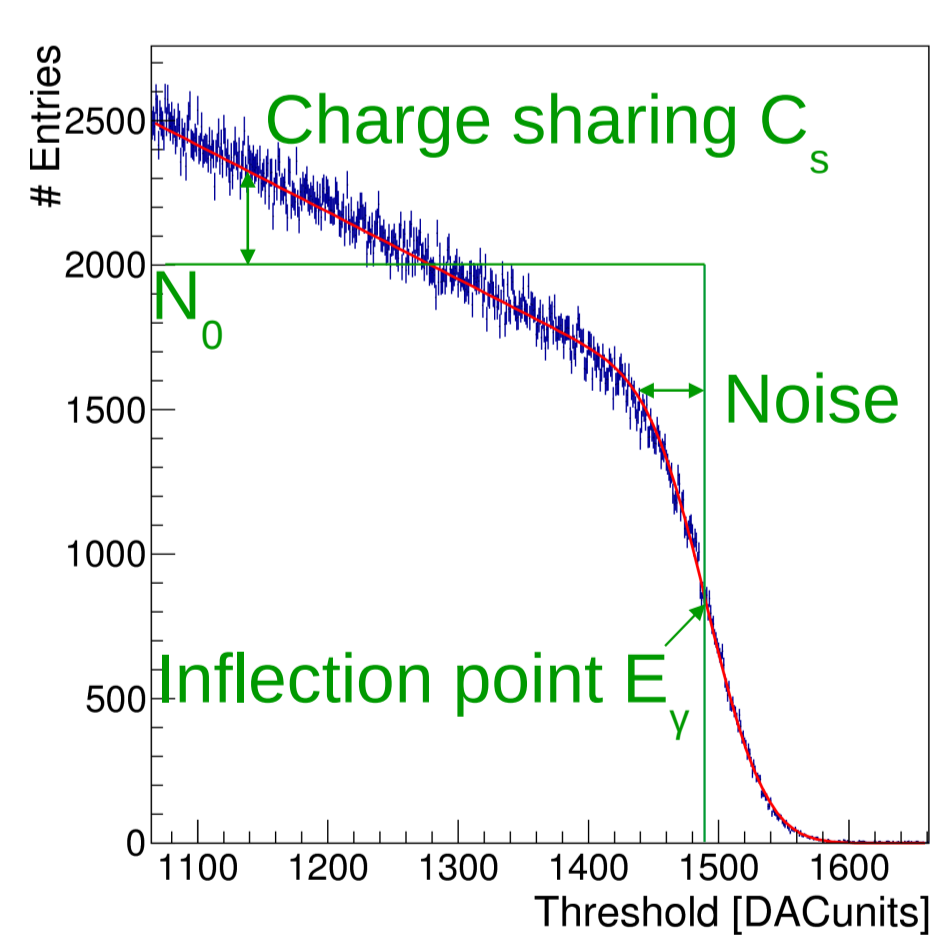
3. Fit the ratio ϵ of the measured and theoretical rate Φ to find the shaping time τ_d with:
 $\epsilon = \exp(-\tau_d \Phi)^*$
 *paralyzable counter model [1]

The shaping time

- increases with the gain (Vrf) ✓
- allows for fast count rates ✓

Threshold scans

All data are taken with a preliminary readout system !

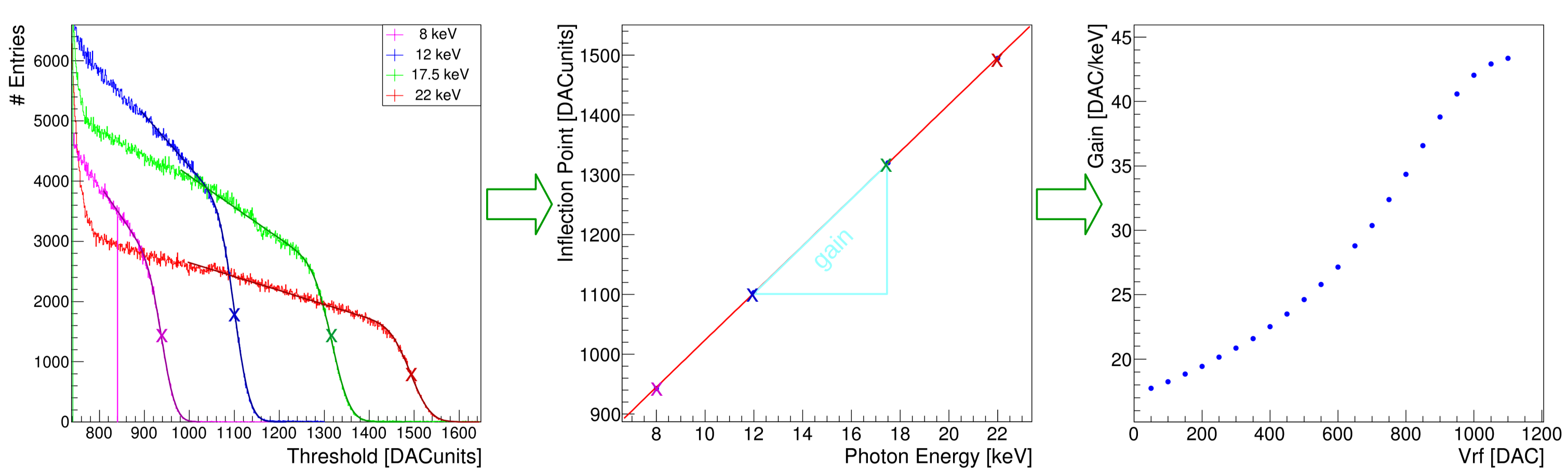


The number of photon hits is a function of the threshold:

$$N_y(E_{thr}) = \frac{N_0}{2} (1 + C_s(E_y - E_{thr})) \left(1 + \text{Erf} \left(\frac{E_y - E_{thr}}{\sqrt{2} \text{Noise}} \right) \right)$$

*Noise = extra counts due to pulse height variations overcoming the comparator threshold [1]

Calibration



1. Take threshold scans at different photon energies
2. Extract the inflection points

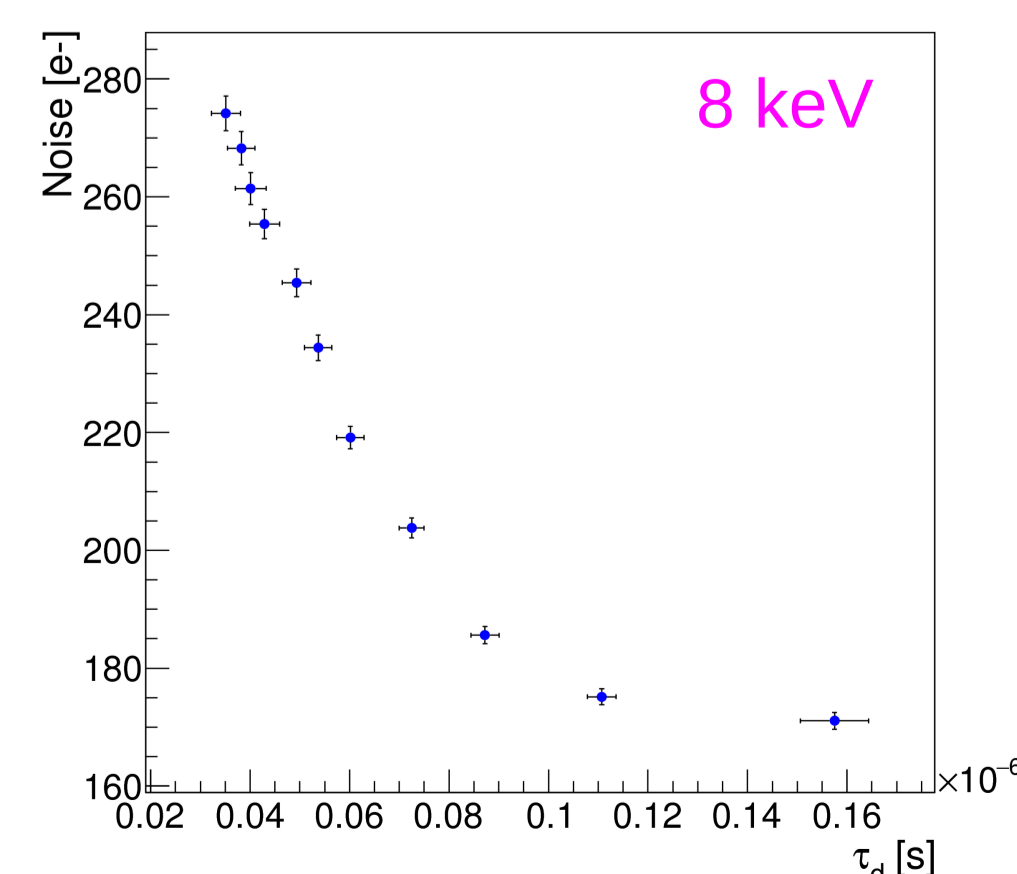
3. Calculate the gain [DACunits/keV] for every Vrf-setting

The gain

- increases with Vrf ✓
- starts to saturate at high Vrf ✓

Conclusion

The noise decreases with increasing shaping time:



	MYTHEN II @ 8.75 keV, Standard settings Fast settings [1]	MYTHEN III @ 8.0 keV, Vrf = 950 DACunits Vrf = 250 DACunits
Untrimmed threshold dispersion [eV]	1623 ± 6 1761 ± 7	476 ± 3 721 ± 4
Noise [e-]	230 ± 7 262 ± 7	175 ± 1 261 ± 3
Shaping time τ_d [ns]	170 ± 10 110 ± 10	111 ± 3 40 ± 3

References

[1] A. Bergamaschi et al, The MYTHEN detector for X-ray powder diffraction experiments at the Swiss Light Source (2010), J. Synchrotron Rad.(2010) 17, 653-668

