



Two-beam module review, 14-16 September 2009 Test modules: hardware, program, resources, schedule

G. Riddone, 16.09.2009

Thanks to K. Artoos, JP. Delahaye, C. Hauviller, C. Garion, H. Mainaud-Durand, M. Modena, R. Nousiainen, A. Samoshkin, L Soby, I. Syratchev



Content



- Objectives and motivation
- EuCARD NCLinac WP9.2
- Strategy
- Test module layout
- Resources (preliminary estimations)
- Conclusions





- Q4 mock-up (see Kurt talk)
- Girder mock-ups (see Helene talk)
- Test modules 0 and 1 (Eucard NCLinac WP9.2/9.3)

How to establish a short-medium term coherent test program with milestones before and after CDR



Objectives for CDR



- Address feasibility issues in an integrated approach
 - e.g. Stabilization-alignment-supporting systems
- Establish coherence between existing test set-up and future test modules in CLEX
- Prepare test modules for CLEX
 - if possible use components from stand-alone tests for test modules in CLEX

Question:

- what can be realistically done before CDR



Strategy for main linac two-beam module validation





Objectives of the test modules 🖨



From NCLinac kick-off meeting / march 2009

- Two-beam acceleration in a realistic environment
- Cost- and performance optimized accelerating structures and their integration in CLIC modules.
- Accelerating structure (ACS) alignment on girder using probe beam
- Wakefield monitor (WFM) performance in low and high power conditions (and after a breakdown)
- Cost- and performance optimized PETS (several option, e.g. mini-tank, on-off mechanism not integrated)
- Investigation of the breakdown effect on the beam
- Alignment and stabilization systems in a dynamic accelerator environment
- RF network phase stability especially independent alignment of linacs
- Vacuum system performance especially dynamics with rf
- Cooling system especially dynamics due to beam loss and power flow changes
- Integration of all different sub-systems:, i.e. to simultaneously satisfy requirements of highest possible gradient, power handling, tight mechanical tolerances and heavy HOM damping
- Validation of assembly, transport, activation, maintenance etc.

EUCARD – NCLinac - Task 9 Normal Conducting High Gradient Cavities

- Sub-task I: Design, manufacture, and validate experimentally a Power Extraction and Transfer Structure (PETS) prototype to improve CTF3 → F.Toral/D. Carrillo - CIEMAT
- Sub-task 2: Explore influence of alignment errors on wake fields, elaborate and demonstrate appropriate High Order Mode (HOM) damping in the presence of alignment errors. → R. Jones/A. D'Elia Un. of Manchester
- Sub-task 3: Breakdown simulation: Develop and use atomistic simulations of atom migration enhanced by the electric field or by bombarding particles, understand what kind of roughening mechanisms lead to the onset of RF breakdown in high gradient accelerating structures. → K. Österberg - HIP(#I)
- Sub-task 4: Design and build equipment to diagnose the electrons, ions and light emanating from the breakdown event both in the CTF3 Two-Beam Test-Stand at CERN and inside a scanning electron microscope in UU to analyze the surface science relevant to RF-breakdown
 R. Ruber/V. Ziemann - UPPSALA
- Sub-task 5: Precise assembly: Develop a strategy of assembly for the CLIC accelerating and power extraction structures satisfying the few to 10 micrometer precision requirement of positioning both radial and longitudinal taking into account dynamical effects present during accelerator operation. → K. Österberg HIP(#2)







From mock-up to test modules



CERN

G. Riddone, TBM review, 16.09.2009

Test module configurations in CLEX



FR

Nominal power and pulse length for 1 PETS and 2 AS Recirculation 12 A and 240 ns

No modifications on the test module type 0 HW No Recirculation Current increase from 12 A to 19.2 A Pulse length reduced from 240 ns to 140 ns

No modifications on the test module type 0 HW Addition of a module type 1 Increase of current from 19.2 A to 22 A

Modification on the test module type I HW (2 CLIC PETS) Needed klystrons and PC

G. Riddone, TBM review, 16.09.2009





Inventory of main components

Conf.	Existing PETS	Double- length PETS	CLIC PETS	CLIC structures/ WFM	DB Q/ DB BPM	MB Q/ MB BPM
3.1	I	2	0	8	4	I (TI)
3.3	I	2	0	8	4	I (TI)
4.1	Ι	4	0	14	6	2 (TI-T4)
4.2	Ι	3	2	14	6	2 (TI-T4)
TOTAL	I	4	2	16	6	2

	UCARD-NCL inac-						4								EuC	ARD											
																						-					
	WP9.2		2	800				2009				201	0			2	011			:	2012				20	013	
		q	g	g	q	q	g		x 4		g g	ຊ	ğ	đ	ğ	g	g	q	g	g	g	9	ð	10	g	g	đ
Test Modu	le						M1																-				
Phase 3																											
9	9.2 Design of NCLinac hardware for test module															M24											
	9.2 Prototype components for CLIC module prepared																			M36							
	Phase 3 Design																										
	Phase 3 Procurement																										
	Phase 3 Assembly/Installation																										
	Phase 3 Test																\leftarrow			-							
Phase 4																											
9	3.3 Quadrupole mock-up manufactured and ready for a second se	rinsta	llation															M30									
	Phase 4 Design																										
	Phase 4 Procurement				+++																						
	Phase 3 Assembly/Installation																										
	Phase 4 Test																										
Sub-task 1	: PETS																										
	Coupler/PETS engineering and detailed design										M10																
	First prototype PETS fabrication and assembly														M22	2											
	First prototype PETS tests															M2	5										
	Design review																M27										
	Second prototype PETS production																			M36							
	Complete TEST module tests																						M45	5			
Sub-task 2	: Wakefields and HOM damping																										
	Design RF aspects of wakefield suppression											Ν	A15														
	Beam dynamics simulation study														M21												
	Fabrication Tolerance Study																-										
	Finalise Design															M2	5										
	Measure HOMS in Module																										
	Refine Wakefield Suppression Inc Exp Results																										
Cub tack 2	Beam dynamics and RF of WF Suppression												++-												11/148		
SUD-LASK 3	Simulate effects of sparking on surface merchale									N.44																	
	Simulate the direct field emission of stoms from	BY flat cu	rfaces							M	-		++-														
	Dynamically simulate the onset of electrical (dc a	nd rf)	hreakd	own						IVI.									M33		_						
Sub-task 4	Diagnostics equipment		breaka	00000															10133			_					
Sub tusk 4	Diagnostics for dark current and ion measuremen	ts	+ + +							M	9		++-				+++					_					
	Install and commission improved diagnostics																		M33								
	Surface analysis of breakdown sites with, SEM, AF	м,																									
	DC-breakdown analyzer (flash box)														M21												
Sub-task 5	Precision assembly (AS&PETS)																										
Phase 3																											
	R&D																										
	Manufacturing & Testing																	M30									
	Final assembly (tech. support)			\square																							
Phase 4																											
	R&D				+ $+$ $+$																	\square					
	Manufacturing & Testing																										+++
	Final assembly (tech. support)																					M4	2				



104 TM Schedule (aggressive)







(in brackets person which supplied the input)			quantit	y	quantity	Material	Material		
					total	cost / unit	cost/module		
Systems		TO	T1	T4		[CHF]	[CHF]		
RF (G. Ri	ddone)						(TBC)	2 080 000	
	accelerating structures, incl. cooling	8	6	0	14	110 000	1 540 000		
	PETS., incl. mini-tanks	2	4	0	6	60 000	360 000		
	Loads with DC	4	3	0	7	10 000	70 000		
	ON-OFF system	2	4	0	6	7 500	45 000		
	RF distribution	2	4	0	6	7 500	45 000		
	acquisition system				1	20 000	20 000		
Pre-aligr	nment girders (H. Mainaud-Durand)							505 000	
	actuators	6	20	11	37	10 000	370 000		
	cradles	2	5	2	9	3 000	27 000		
	sensor support	2	5	2	9	1 000	9 000		
	sensors	4	10	4	18	4 000	72 000		
	link to floor	2	5	2	9	3 000	27 000		
	acquisition system				0		0		
Pre-aligr	nment MB Q (H. Mainaud-Durand)							252 000	
.0.	interface stabilisation/pre-alignment		1	1	2		0		
	pre-alignment system		5	5	10	20 000	200 000		
	pre-alignment interface		3	4	7	4 000	28 000		
	link to floor		4	4	8	3 000	24 000		
	acquisition system				0		0		
Stabiliza	tion MB O (K. Artoos)				-			0	
	stabilization system				0		0	-	
	overall stab/pre-align integration				0		0		
					0		0		
Supports	s for structures (R. Nousiainen, G. Riddone	2)			-			131 000	
	girders	2	2	1	5	15 000	75 000	1	
	AS supports	8	6		14	2 000	28 000		
	DB Q supports				0		о 0		
	PETS supports	2	3		5	2 000	10 000		
	RF components supports	4	3		7	1 500	10 500		
	Rf distribution supports	2	3		5	1 500	7 500		
Vacuum	(C. Garion)							196 850	
	vacuum chambers	0	1	4		55 600	55 600	1	
	pumping system	2	3	2		105 500	105 500		
	interconnections	16	16	16		20 850	20 850		
	RF flanges /bellows					11 900	11 900		
	Supports					3 000	3 000		
Magnets	(M. Modena)							280 000	
	MB Q Type 4			1	1	90 000	90 000	power supplies	missing
	MB Q Type 1		1		1	32 000	32 000		-
	DBQ	2	2	2	6	25 000	150 000		
	Correctors				0				
	Cooling circuits	2	3	3	8	1 000	8 000		
Beam ins	strumentation (L. Soby)							320 000	
	MB BPM		1	1	2	10 000	20 000		
	DB BPM	2	2	2	6	10 000	60 000		
	WFM	8	8	8	24	10 000	240 000		
								50 000	
Infrastru	icture/Assembly				1	50 000	50 000	1	
				TO		RIAL COST	3 814 850		



Material cost estimate (preliminary)



Conclusions



- Important to show a solid case for CDR
- Important to freeze the design by QI 2010
- Needed Green light for 104 TM
- Missing resources are urgent