

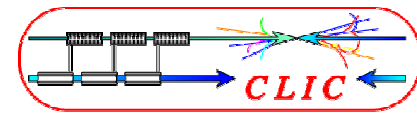
Two-beam module review, 14-16 September 2009  
Test modules:  
hardware, program, resources, schedule

G. Riddone, 16.09.2009

*Thanks to K.Artoos, JP. Delahaye, C. Hauviller, C. Garion, H. Mainaud-Durand, M. Modena, R. Nousiainen, A. Samoshkin, L Soby, I. Syrathev*



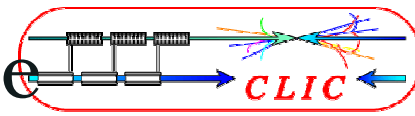
# Content



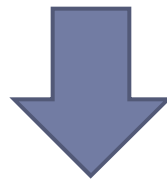
- ▶ Objectives and motivation
- ▶ EuCARD – NCLinac – WP9.2
- ▶ Strategy
- ▶ Test module layout
- ▶ Resources (preliminary estimations)
- ▶ Conclusions



# Recall of test stands in the pipeline



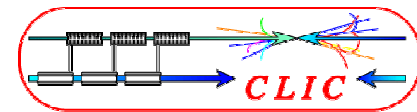
- ▶ Q4 mock-up (see Kurt talk)
- ▶ Girder mock-ups (see Helene talk)
- ▶ Test modules 0 and 1 (Eucard – NCLinac – WP9.2/9.3)



How to establish a short-medium term coherent test program with milestones before and after CDR



# Objectives for CDR



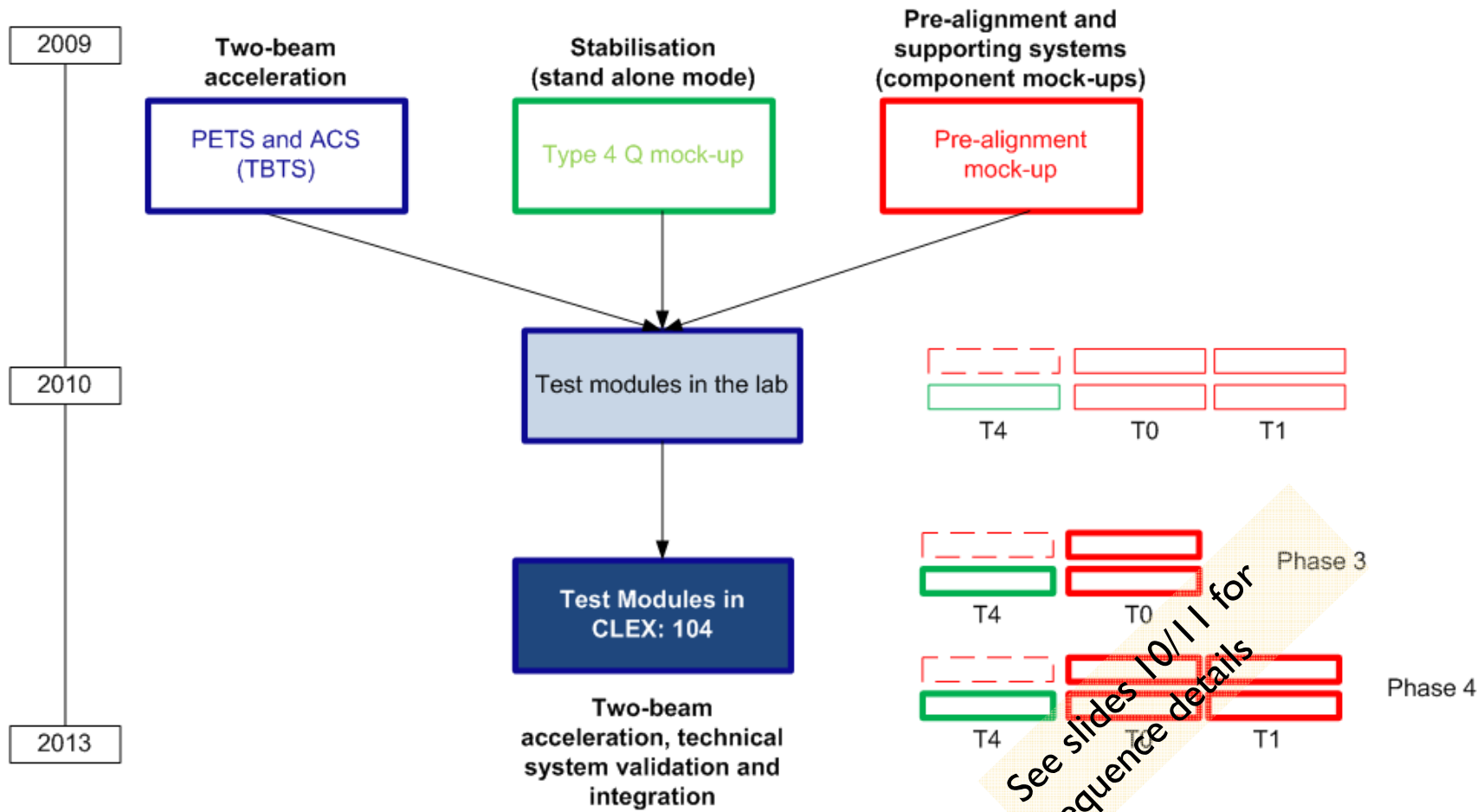
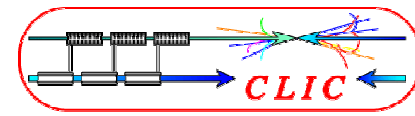
- ▶ Address feasibility issues in an integrated approach
  - ▶ e.g. Stabilization-alignment-supporting systems
- ▶ Establish coherence between existing test set-up and future test modules in CLEX
- ▶ Prepare test modules for CLEX
  - ▶ if possible use components from stand-alone tests for test modules in CLEX

## Question:

- what can be realistically done before CDR

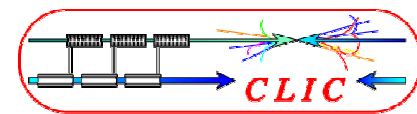


# Strategy for main linac two-beam module validation



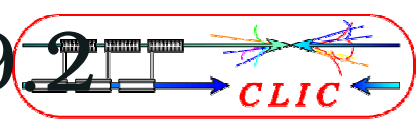


# Objectives of the test modules



From NCLinac kick-off meeting / march 2009

- ▶ Two-beam acceleration in a realistic environment
- ▶ Cost- and performance optimized accelerating structures and their integration in CLIC modules.
- ▶ Accelerating structure (ACS) alignment on girder using probe beam
- ▶ Wakefield monitor (WFM) performance in low and high power conditions (and after a breakdown)
- ▶ Cost- and performance optimized PETS (several option, e.g. mini-tank, on-off mechanism not integrated)
- ▶ Investigation of the breakdown effect on the beam
- ▶ Alignment and stabilization systems in a dynamic accelerator environment
- ▶ RF network phase stability especially independent alignment of linacs
- ▶ Vacuum system performance especially dynamics with rf
- ▶ Cooling system especially dynamics due to beam loss and power flow changes
- ▶ Integration of all different sub-systems: , i.e. to simultaneously satisfy requirements of highest possible gradient, power handling, tight mechanical tolerances and heavy HOM damping
- ▶ Validation of assembly, transport, activation, maintenance etc.

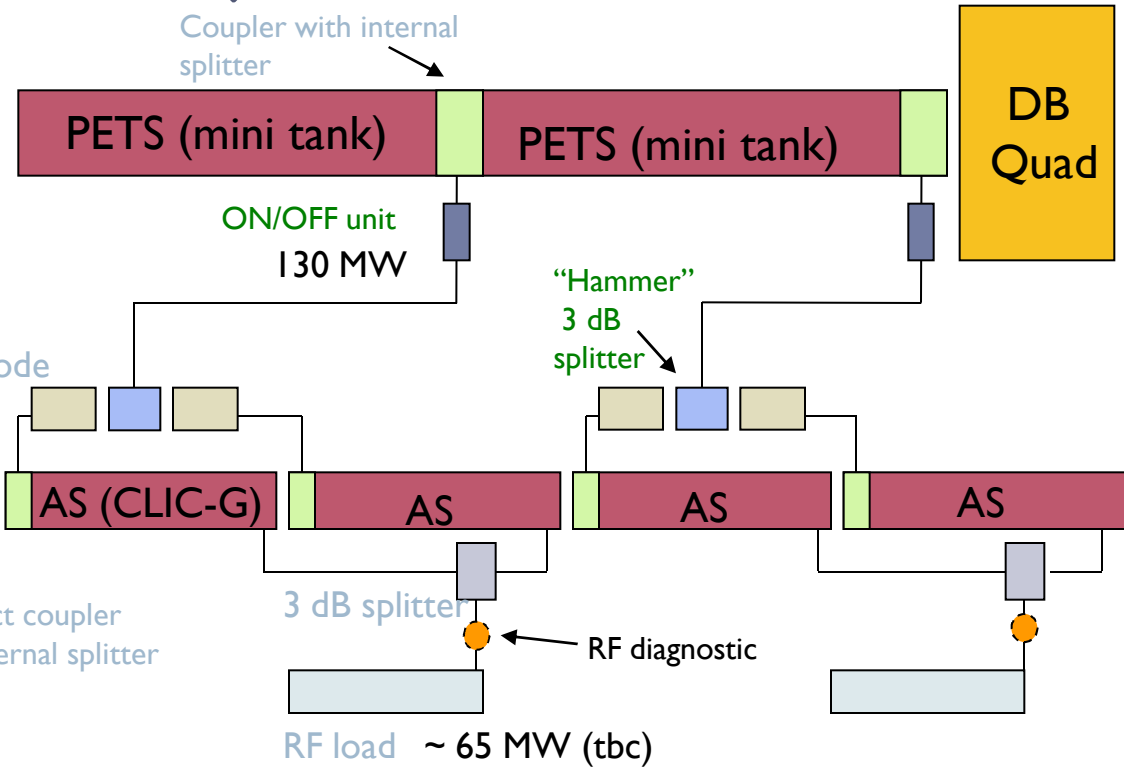
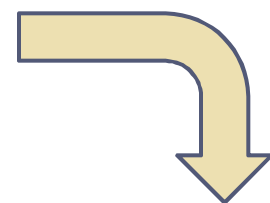
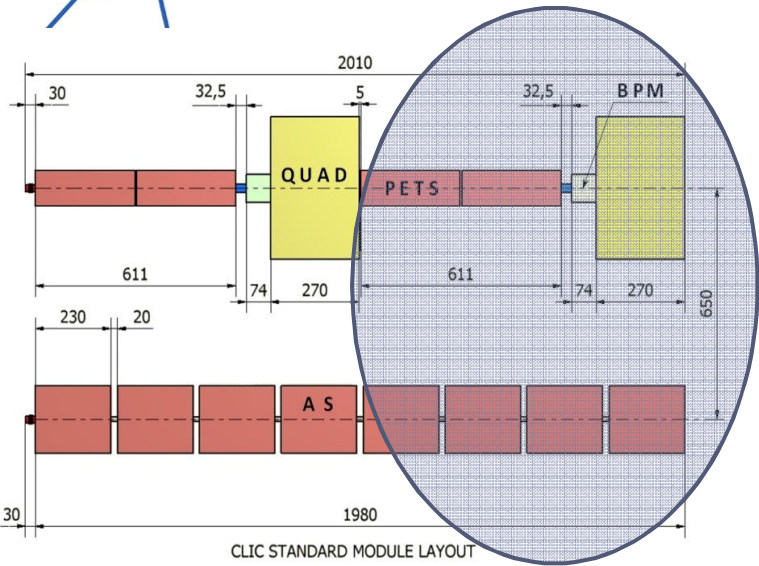
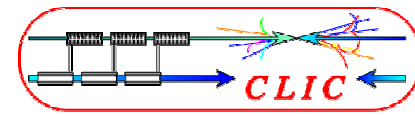


## Normal Conducting High Gradient Cavities

- ▶ **Sub-task 1:** Design, manufacture, and validate experimentally a **Power Extraction and Transfer Structure (PETS)** prototype to improve CTF3 → **F.Toral/D. Carrillo - CIEMAT**
- ▶ **Sub-task 2:** Explore influence of **alignment errors on wake fields**, elaborate and demonstrate **appropriate High Order Mode (HOM) damping** in the presence of alignment errors. → **R. Jones/A. D'Elia - Un. of Manchester**
- ▶ **Sub-task 3: Breakdown simulation:** Develop and use atomistic simulations of atom migration enhanced by the electric field or by bombarding particles, understand what kind of roughening mechanisms lead to the onset of RF breakdown in high gradient accelerating structures. → **K. Österberg - HIP(#1)**
- ▶ **Sub-task 4: Design and build equipment to diagnose the electrons, ions and light emanating from the breakdown event** both in the CTF3 Two-Beam Test-Stand at CERN and inside a scanning electron microscope in UU to analyze the surface science relevant to RF-breakdown → **R. Ruber/V. Ziemann - UPPSALA**
- ▶ **Sub-task 5: Precise assembly:** Develop a strategy of assembly for the CLIC accelerating and power extraction structures satisfying the few to 10 micrometer precision requirement of positioning both radial and longitudinal taking into account dynamical effects present during accelerator operation. → **K. Österberg - HIP(#2)**



# From CLIC module to test module

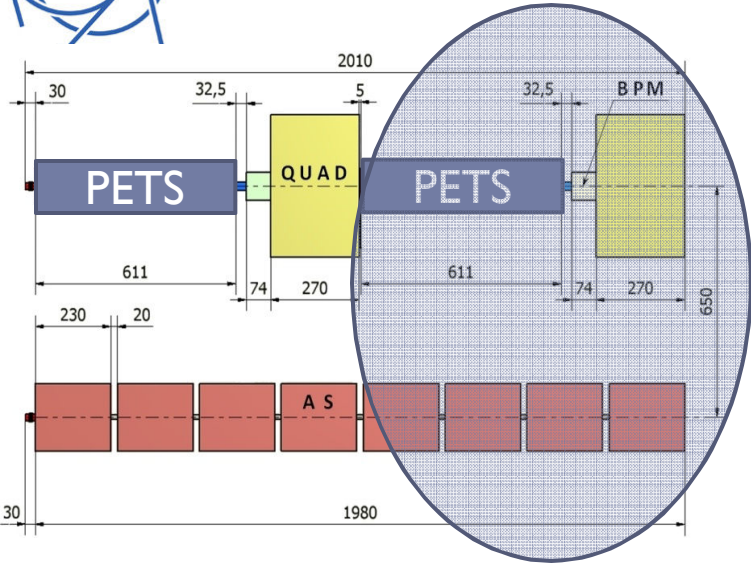
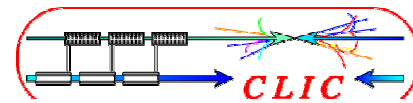


## CLIC module type 0

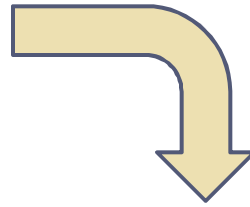




# From CLIC module to test module

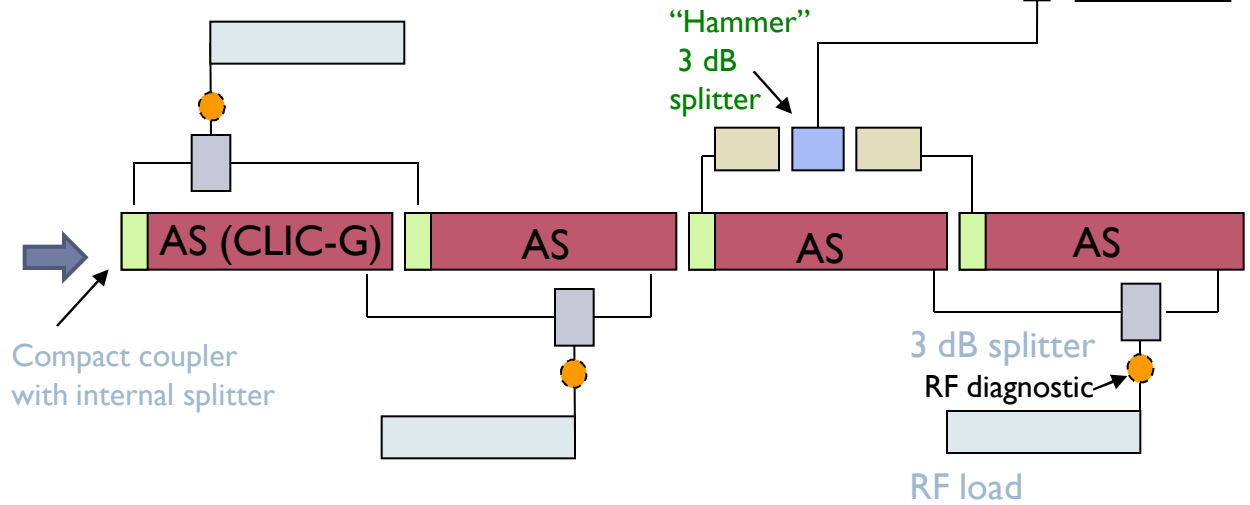


Parameters	CTF3	CLIC
Energy	0.150 GeV	2.4 GeV
Pulse length	1.2 $\mu$ s	140 $\mu$ s
Multiplication factor	$2 \times 4 = 8$	$2 \times 3 \times 4 = 24$
Linac current	3.75 A	4.2 A
DB final current	30 A	100 A
RF frequency	3 GHz	1 GHz
Repetition rate	up to 5 Hz	50 Hz
Energy per beam pulse	0.7 kJ	1400 kJ
Average DB power	3.4 kW	70 MW

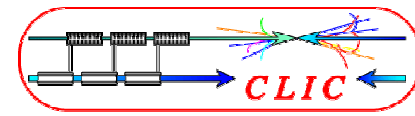


## Test module type 0

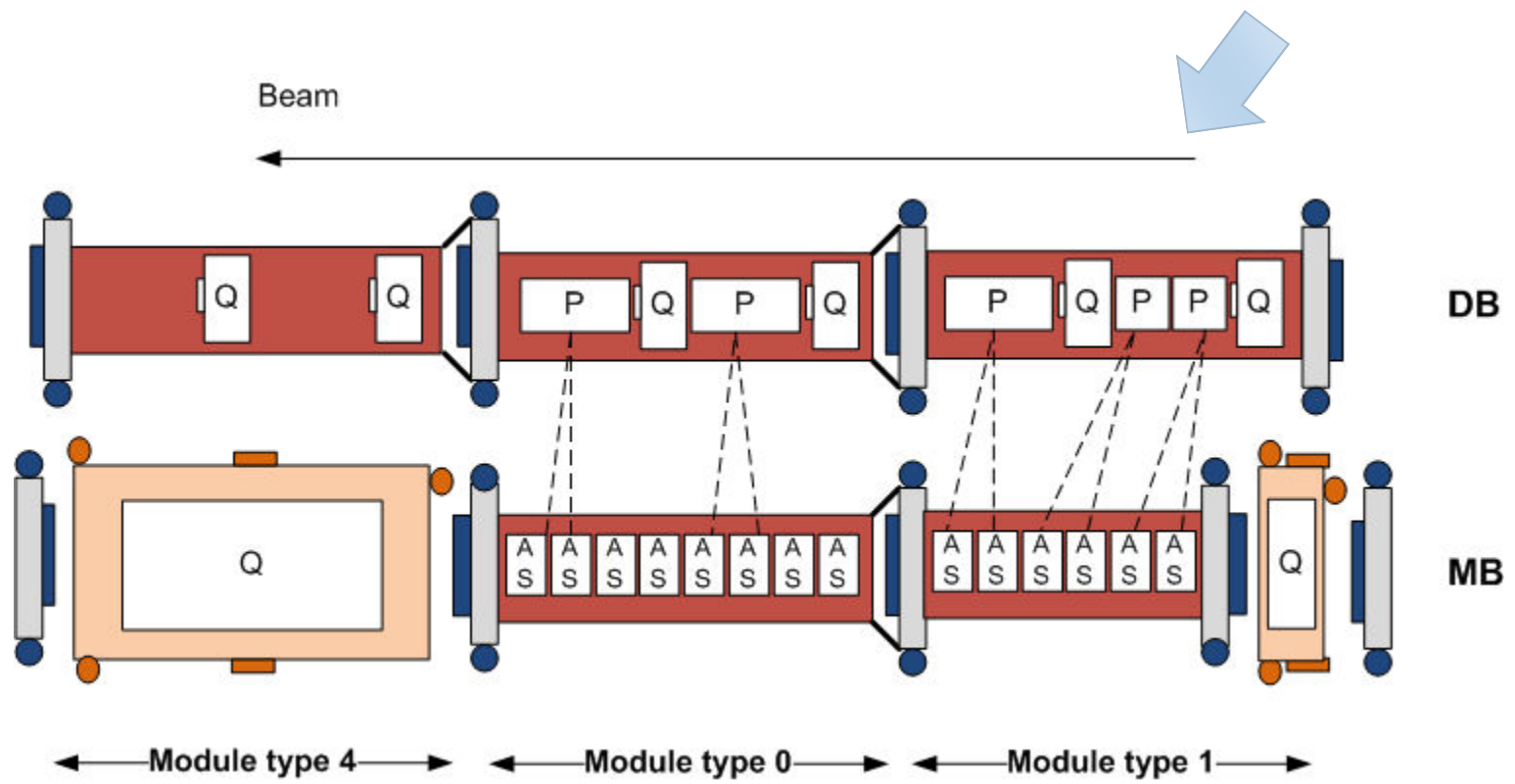
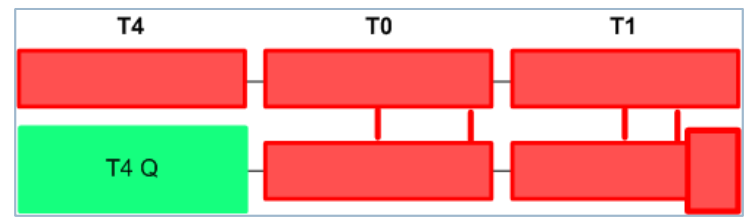
Existing 1-m PETS with recirculation



# Test Modules 104 (final configuration)

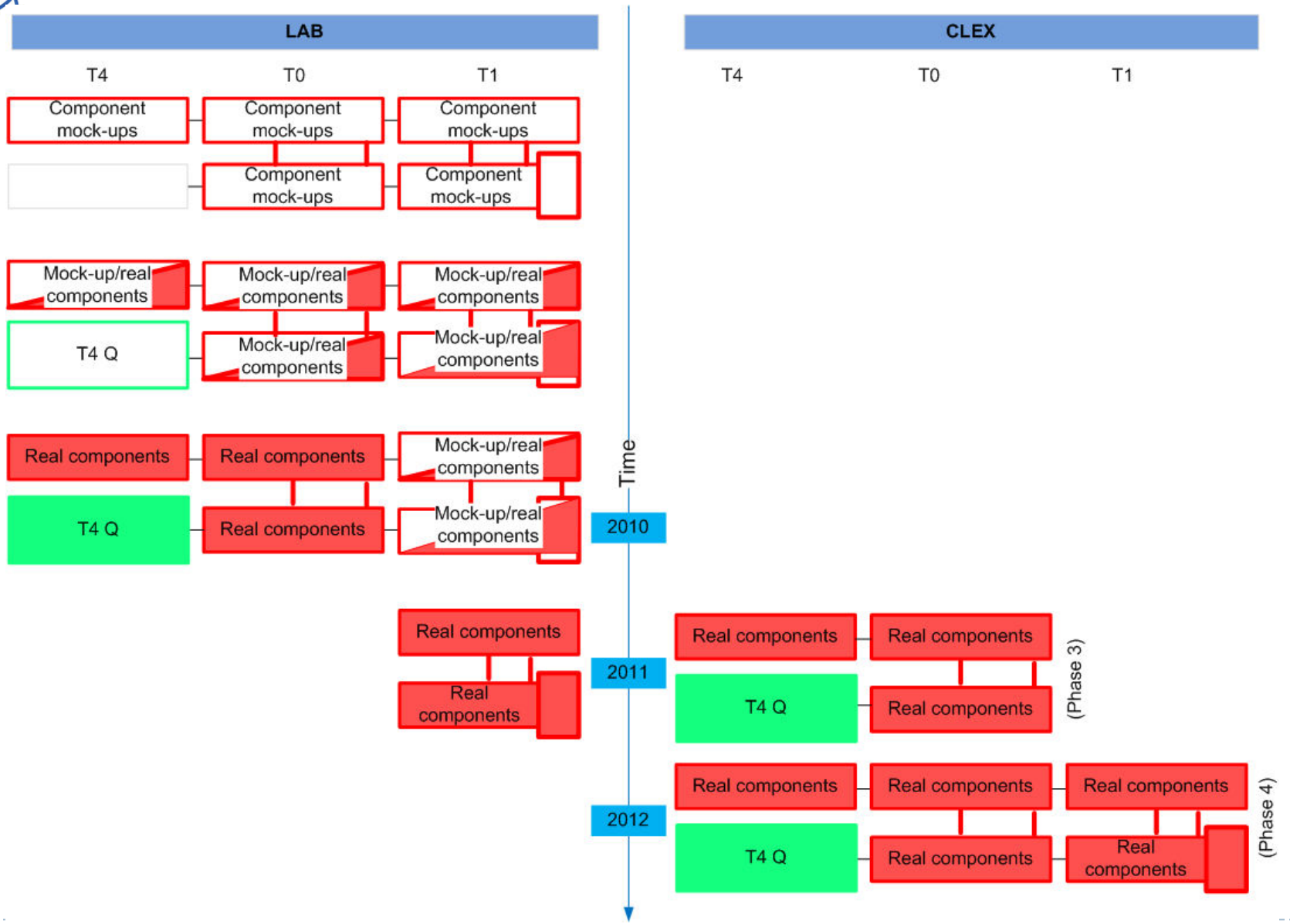
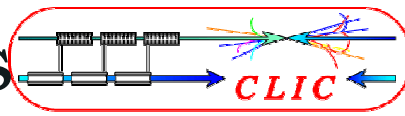


The test module types 1-0-4 are representative of all module types



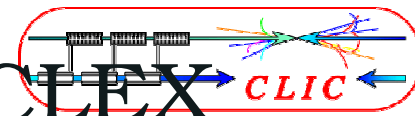


# From mock-up to test modules





# Test module configurations in CLEX



Phase 3, Conf. 3.1

Nominal power and pulse length for 1 PETS and 2 AS  
Recirculation  
12 A and 240 ns

Phase 3, Conf. 3.3

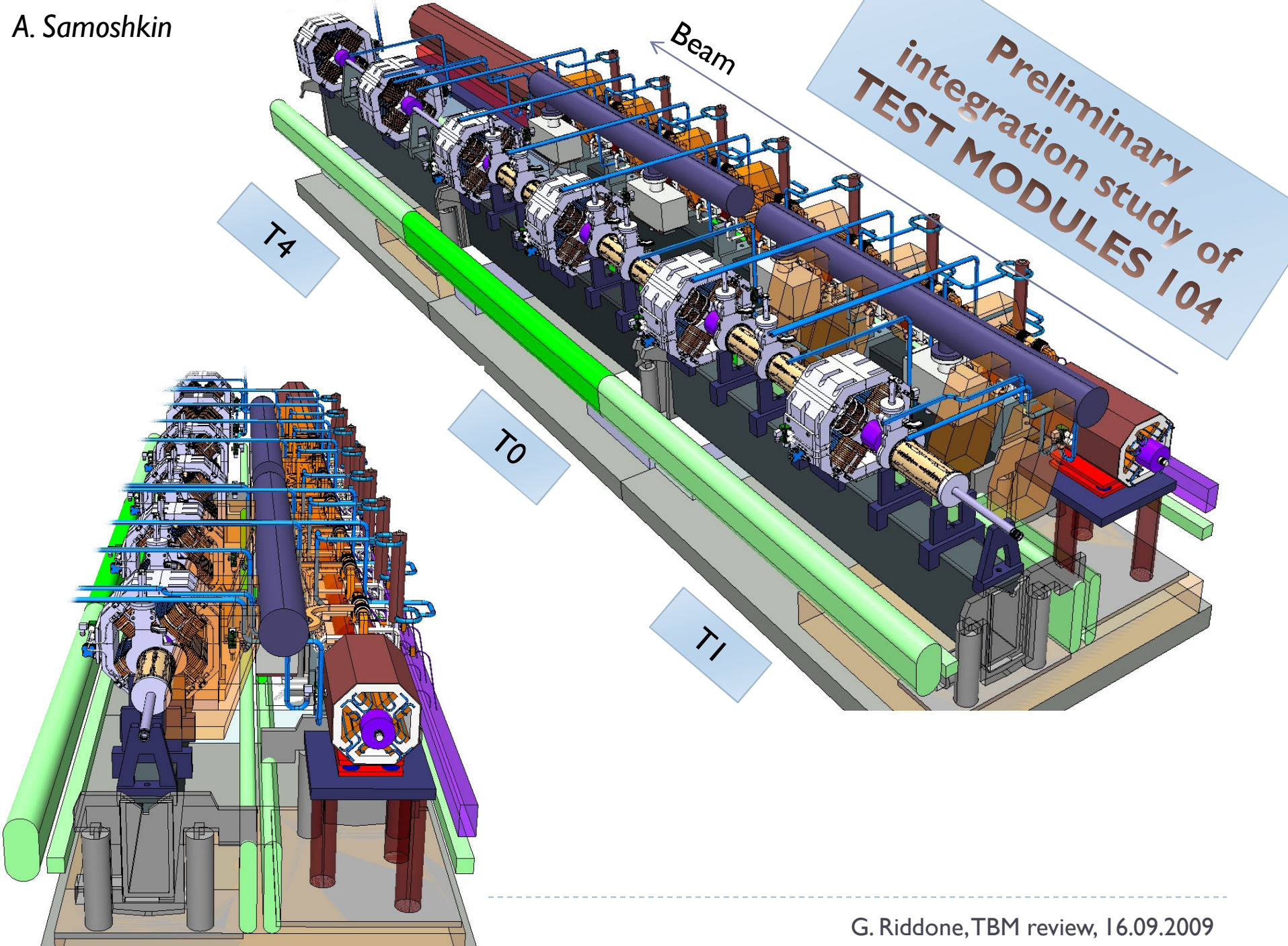
No modifications on the test module type 0 HW  
No Recirculation  
Current increase from 12 A to 19.2 A  
Pulse length reduced from 240 ns to 140 ns

Phase 4, Conf. 4.1

No modifications on the test module type 0 HW  
Addition of a module type I  
Increase of current from 19.2 A to 22 A

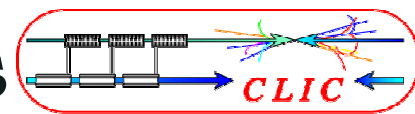
Phase 4, Conf. 4.2

Modification on the test module type I HW (2 CLIC PETS)  
Needed klystrons and PC





# Inventory of main components

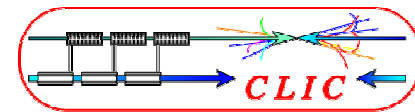


Conf.	Existing PETS	Double-length PETS	CLIC PETS	CLIC structures/WFM	DB Q/DB BPM	MB Q/MB BPM
<b>3.1</b>	1	2	0	8	4	1 (T1)
<b>3.3</b>	1	2	0	8	4	1 (T1)
<b>4.1</b>	1	4	0	14	6	2 (T1-T4)
<b>4.2</b>	1	3	2	14	6	2 (T1-T4)
<b>TOTAL</b>	<b>1</b>	<b>4</b>	<b>2</b>	<b>16</b>	<b>6</b>	<b>2</b>





# 104 TM Schedule (aggressive)



Systems	2009			2010					2011					2012					Remarks									
	Sep	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec	Jan	Feb		Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov
<b>RF</b>																												
accelerating structures																												
PETS																												
RF components/on-off																												
RF distribution																												
Acquisition system																												
<b>Pre-alignment girders</b>																												
repositioning system																												
cradles																												
sensor support																												
sensors																												
link to floor																												
acquisition / control command system																												
<b>Pre-alignment MB Q</b>																												
interface stabilisation/pre-alignment																												
repositioning system																												
pre-alignment interface																												
sensors																												
sensors support																												
link to floor																												
acquisition/control command system																												
<b>Stabilization MB Q</b>																												
stabilization system																												
overall align./stab. integration																												
<b>Supports for structures</b>																												
girders																												
AS supports																												
PETS supports																												
RF components supports																												
Rf distribution supports																												
<b>Vacuum</b>																												
vacuum chambers																												
pumping system																												
interconnections																												
RF flanges																												
Supports																												
<b>Magnets</b>																												
MB Q type 4																												
MB Q type 1																												
DB Q																												
Supports																												
Correctors																												
<b>Beam instrumentation</b>																												
MB BPM (CERN/Fermilab)																												
DB BPM																												
WFM																												
<b>Module engineering/integration design</b>																												
<b>Assembly</b>																												
<b>Legend</b>																												
prototype validation																												
RF/magnet design																												
mechanical design																												
procurement																												

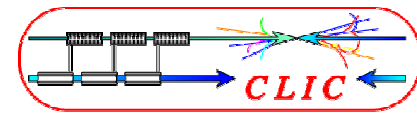
Missing 2x eng., FSU, designer

Missing designer, experts electronics for WFM





# Conclusions



- ▶ Important to show a solid case for CDR
- ▶ Important to freeze the design by Q1 2010
- ▶ Needed Green light for I04 TM
- ▶ Missing resources are urgent