Computational challenges *in Experimental High Energy Physics*

how to convert 100TB/s into a Nobel prize

or

Slides stolen from: Erica Brondolin Lindsay Gray John Harvey Sverre Jarp Chris Jones Pere Mato Felice Pantaleo Lucia Silvestris

Vincenzo Innocente CMS Experiment & CERN/ EP-SFT

> Data Science Workshop **CERN** November 9th, 2015

Why are we here today?

Memory Latency

Simple, but illustrative example

- KNL has ~64 cores @1.30GHz, 2FMA port (VPU) each, 4-way hardware threading, hardware vectors of size 8 (Double Precision), 16GB of fast memory:
- 3TFLOPS DP for $400GB/s = 0.5bit/flop-sp$ -60 fp-ops = 1 fp-load

Streaming Multiprocessor Architecture

NVIDIA Pascal 32 CUDA core $x4 x5 x4 = 2560$ Floating Point Units @1.7GHz 8GB fast memory

Require 110 fp-ops to compensate one memory access!

Total Bandwidth

320GB/sec

224GB/sec

192GB/sec

192GB/sec

Conclusions

- Improving throughput or latency requires exploiting optimal massive parallelization at all levels
- Speeding up algorithms will not pay up if memory access is not reduced

Collisions at the LHC: summary

Selection of 1 event in 10,000,000,000,000

VI DS in EHEP 7

Detector "onion" structure

An experiment: CMS

Toward 2023

- High Luminosity: proton collisions per bunch-crossing (PU) 40 -> 200
	- x5 more occupancy in detectors
	- $-$ Access to new corners of phase-space
		- **High Mass, Boosted topologies**
			- **Dense environment**
- New Detectors
	- New Tracker
		- Higher granularity (x4), extended coverage, hardware trigger capability
	- $-$ CMS: New High granularity Calorimeter
	- $-$ Timing information
- First Level Trigger
	- $-$ Include Tracking information
	- $-$ Output Rate up to 1MHz
- High Level Trigger
	- More use of tracking
	- Detailed analysis in search of new signals
	- Output Rate up to 10KHz
- Offline
	- $-$ Not just do as well as today but at PU 200
	- $-$ More precision to look for tiny signals of New Physics

Data Hierarchy: Our solution to BigData

"RAW, ESD, AOD, TAG"

Reconstruction of CMS Simulated Event

 $t\bar{t}$ event at <PU>=140 (94 vertices, 3494 tracks)

Event parallelism

Opportunity: Reconstruction Memory-Footprint shows large condition data

How to share common data between different process?

 \rightarrow multi-process and multi-thread applications are now in production

 \rightarrow CMS simulation and reconstruction runs on KNL with 126 threads well within the16GB of fast memory

End

Lumi

Event

 $5⁵$

Begin

End

Job

End

Lumi

End

Stream

End

End

Run

End

End

Lumi

Event

End

Run

End

 \rightarrow I/O remains a problem...

Lumi

End

Input Beyond event-level parallelism

- » We may endup with more core than events
- » Resources (shared access to memory, to disk) may be scarce
	- Typical example is a KNL used as a cluster of \sim 256 cpus
- $-$ Parallelize a DAG workflow is relatively easy including the management of a mild overcommit to mitigate starvation issues

Processing

Time

- » All concurrent framework implements it (or plan to implement it)
- » To work well it requires a reasonably balanced workflow:
	- a single long pipeline may easily defeat its purpose!
- » Iterative tracking is the most striking example of long pipeline (50% of reco time spent in it for CMS...)
- $-$ NB: up to this point data-processing is fully reproducible independently of the order of execution and granularity of concurrency

Output

Outer loop parallelization

- Typically each processing module has an "outer loop" on its input collection
	- $-$ The most trivial concurrency model is to parallelize it
		- "For loop" parallelization is a well established practice
- In CMS proven to work "almost" out of the box for both seed and track building
	- $-$ Seed building is fully combinatorial, no reproducibility issues
	- $-$ Track building includes "cleaning passes" to remove already used hits
		- Introduces a sequential dependency and therefore an irreproducibility in case of parallel processing
- Current implementation
	- $-$ Avoid "cleaning" and pay the price

In-Out parallelization

- Out-In parallelization will allow to overcome the limitation of traditional batch processing, exploiting new (heterogeneous) concurrent hardware (SIMD/SIMT) will require a completely new approach, most probably a full rethinking of algorithms, data structures and even of the workflow decomposition
- By definition SIMD/SIMT applies to the innermost loop
	- Either directly or by code transformation
- w/r/t multi-threading, effective concurrency is "broken" in SIMD/SIMT by pretty common patterns such as
	- Branch predication
	- Random memory access
	- Recursion
- SIMD/SIMT algorithms are fragile
	- $-$ Supporting a new use case (even adding some protections or a minor variant) may destroy efficient parallelism
	- $-$ Often better to duplicate code and/or to partition data and manage conditionals at a higher level (which is not necessarily a bad thing even in general!)
	- $-$ Runtime polymorphism is out-of-question: has to be managed outside.
- Mitigation strategies do exist, still for a full efficient use of these architectures a dedicated, specialized software effort is required
	- $-$ Think parallel
	- $-$ Think $local$

Making the code SIMD/SIMT friendly

- Several "success stories" in CMS: pattern very similar
	- $-$ Transform storage representation in algorithm specific data
		- SOA to AOS, variable transformation, sorting, filtering, re-indexing etc
	- $-$ Move all constant components outside
	- $-$ Devirtualize, Use explicit RTTI, inline
		- Move from generic to specific
		- Limit the number of use-cases to the few known
	- $-$ Make functions to act on collections not on single objects
- The net effect is a significant speed up just from such code transformation
	- $-$ In many cases vectorization itself adds little
		- Short inner loops
		- Little computations
		- Branch predication

Traditional track building

- 1. Build doublets
- 2. "Propagate" doublets to third layer and search for compatible hits (open search window on target layer)
- 3. Propagate 1-2-3 triplet to 4th layer and search for compatible hits

Highly divergent code, optimized to bail out asap. Easy to parallelize "Outermost Loop", amost impossible to vectorize

Cellular Automaton (CA)

- The CA is a track seeding algorithm designed for parallel architectures
- It requires a list of layers and their pairings
	- $-$ A graph of all the possible connections between layers is created
	- $-$ Doublets aka Cells are created for each pair of layers (compatible with a region hypothesis)
		- Doublet building identical to traditional approach
	- $-$ "Connect" cells that share hit
	- $-$ Fast computation of the compatibility between two connected cells
		- Vectorized loop of floating point operations
	- $-$ No knowledge of the world outside adjacent neighboring cells required, making it easy to parallelize

Current Performance

• Plan to use Cellular Automaton in its sequential implementation at the HLT already in 2017

On GPU CA is Memory-Bandwidth limited (on CPU as well...)

• Hardware: Intel Core i7-4771@3.5GHz, NVIDIA GTX 1080

The dream of every experimental HEP Physicist:

Identify and measure each single particle produced in a collision

This may need high resolution calorimetry that will compete with trackers in complexity and data volume

Still, using current data-processing approach, most of this information will reach the physicists only in a very condensed form

Difficult to estimate the real impact of such a detector on physics analysis w/o a new data-processing paradigm

Big Question

- Can a "new" Paradigm make the difference?
	- Artificial Intelligence
		- Used already for classification
	- Dedicated Specialized Hardware
		- In use in First Level Trigger since ever
			- CMS Track trigger demonstrated with latency < 4us
	- Smart data mining
		- Analysis currently limited to a single data-tier level

CMS simulation & data processing Software "Legacy"

- ~10k "modules"
- ~1000 "data processing" modules
- Code (SLOC)
	- $-$ C++: 3,558,032 (68.86%)
	- $-$ python: 1,240,801 (24.02%)
		- Used only in initialization
	- fortran: 277,857 (5.38%)
		- Interface to physics simulation code
- Total size of TEXT sections : 229,246,680 bytes
	- $-$ + \sim 220MB of "external software"

Conclusions

- Free lunch is over
	- $-$ To improve the efficiency of software we need to increase the granularity of parallelism, optimize data access patterns and make use of heterogeneous resources
- Waiting for the definitive standard to emerge we need to develop our own infrastructure to support the implementation of concurrent algorithms able to exploit parallelism on heterogeneous hardware
- Recent work shows that
	- $-$ An efficient concurrent schedule of algorithms is feasible
	- $-$ With huge effort it is possible to make current algorithm implementations free from data-race (thread safe)
	- $-$ Making use of parallelism in algorithms requires a total reimplementation
- More R&D is required to tackle the challenges of
	- $-$ Exploiting heterogeneity
	- $-$ Efficient parallelize algorithms
	- $-$ Efficient utilization of memory hierarchy
	- $-$ Efficient utilization of the few developers left

BACKUP

The real issue: maximize throughput **Theoretical peak throughput:** the maximum amount of data that a kernel can read and produce in the unit time.

Throughput_{peak} $(GB/s) = 2$ x access width (byte) x mem_freq (GHz)

This means that if your device comes with a memory clock rate of 3GHz DDR (double data rate) and a 384-bit wide memory interface, the amount of data that a kernel can process and produce in the unit time is at most:

Throughput_{peak} $(GB/s) = 2 \times (384/8)(byte) \times 3 (GHz) = 288 GB/s$

Consequence: cpu starvation!

- NVIDIA TESLA Kepler K40:
	- **1.4 TFLOPS DPFP** peak throughput
	- 288 GB/s peak off-chip memory access bandwidth – 36 G DPFP operands per second
- In order to achieve peak throughput, a program must perform $1,400/36 = -39$ **DPFP** arithmetic operations for each operand value fetched from offchip memory
	- In most of current code is **0.5** (fetch two operands, never use them again)!

Tracking at CMS

- Particles produced in the collisions leave traces (hits) as they fly through the detector
- The innermost detector of CMS is called **Tracker**
- **Tracking:** the art of associate each hit to the particle that left it
- The collection of all the hits left by the same particle in the tracker along with some additional information (e.g. momentum, charge) defines a **track**
- **Pile-up**: $\#$ of p-p collisions per bunch crossing

Reconstructing Jet Constituents

Illustrations: Lindsey Gray

Non trivial regression to compute best estimation of particle energy combining all available information taking into account non-uniformity in detector response

Based on intensive, iterative statistical analysis of data themselves to extract alignment and calibration constants

VI DS in FHFP

HEP Applications

Algorithms read and write from/to the event-data store and the "services"

Only interfaces are defined (with no "cost" associated)

Algorithms are in turn based on a large set of utilities and foundation libraries

A real application (LHCb Brunel)

