

# AliTMinuitToolkit - Robust M-estimator

<https://alice.its.cern.ch/jira/browse/ATO-410>

# Requirement

## AliTMinuitToolkit

- user interface
- comparison of new and “default” fitting algorithm

## Status and to do

# Requirements

## Requirement for “batch” QA/calibration production (not user)

- Robust non linear minimizer
- N dimensional space
- User defined cost function to minimize
  - e.g chi2, log-likelihood + constraints + week constraints
- Robust error estimator

## Usage:

- Distortion fits - line charge density - 2D( $dr, dr\phi$ ) x 3D( $r, r\phi, z$ )
- Analytical Performance fits for QA trending
  - Automatic alarms examples
  - DCA/Angular/Qpt resolution/pulls as function of pt and eta
  - Nsigma band alarm

# M-estimator

In statistics, M-estimators are a broad class of estimators, which are obtained as the minima of sums of functions of the data. **Least-squares estimators** are a special case of M-estimators.

More generally, an M-estimator may be defined to be a zero of an estimating function.

For example, a **maximum-likelihood estimate** is often defined to be a zero of the derivative of the likelihood function with respect to the parameter;

<https://en.wikipedia.org/wiki/M-estimator>

# Maximum likelihood estimator:

Another popular M-estimator is maximum-likelihood estimation.

For a family of probability density functions  $f$  parameterized by  $\theta$ , a maximum likelihood estimator of  $\theta$ , is computed for each set of data by maximizing the likelihood function over the parameter space  $\{ \theta \}$

Maximum-likelihood estimators are often inefficient and biased for finite samples (e.g **local minima**)

For many regular problems, maximum-likelihood estimation performs well for "large samples", being an approximation of a posterior mode.

## cross validation

- Cross-validation, sometimes called rotation estimation is a model validation technique for assessing how the results of a statistical analysis will generalize to an independent data set. (Wikipedia)
  - [https://en.wikipedia.org/w/index.php?title=Cross-validation\\_\(statistics\)&oldid=769508660](https://en.wikipedia.org/w/index.php?title=Cross-validation_(statistics)&oldid=769508660)
  - <http://www.milanor.net/blog/cross-validation-for-predictive-analytics-using-r/>

## bootstrapping

- bootstrapping is any test or metric that relies on random sampling with replacement.
- Bootstrapping allows assigning measures of accuracy (defined in terms of bias, variance, confidence intervals, prediction error or some other such measure) to sample estimates
  - [https://en.wikipedia.org/w/index.php?title=Bootstrapping\\_\(statistics\)&oldid=762130479](https://en.wikipedia.org/w/index.php?title=Bootstrapping_(statistics)&oldid=762130479)

# Random sample consensus (RANSAC)

- Random sample consensus (**RANSAC**) is an iterative method to estimate parameters of a mathematical model from a set of observed data that contains outliers, when outliers are to be accorded no influence on the values of the estimates. Therefore, it also can be interpreted as an **outlier detection method**.
- A basic assumption is that the data consists of "**inliers**", i.e., data whose distribution can be explained by some set of model parameters, though may be subject to noise, and "outliers" which are data that do not fit the model.  
[https://en.wikipedia.org/wiki/Random\\_sample\\_consensus](https://en.wikipedia.org/wiki/Random_sample_consensus)
- RANSAC also assumes that, given a (usually small) set of inliers, there **exists a procedure** which can **estimate the parameters** of a model that optimally explains or fits this data.

*[https://en.wikipedia.org/wiki/Random\\_sample\\_consensus](https://en.wikipedia.org/wiki/Random_sample_consensus)*

# Minimization benchmark



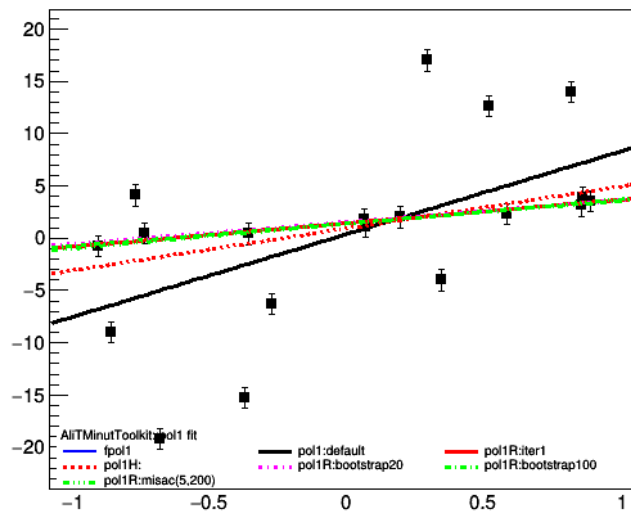
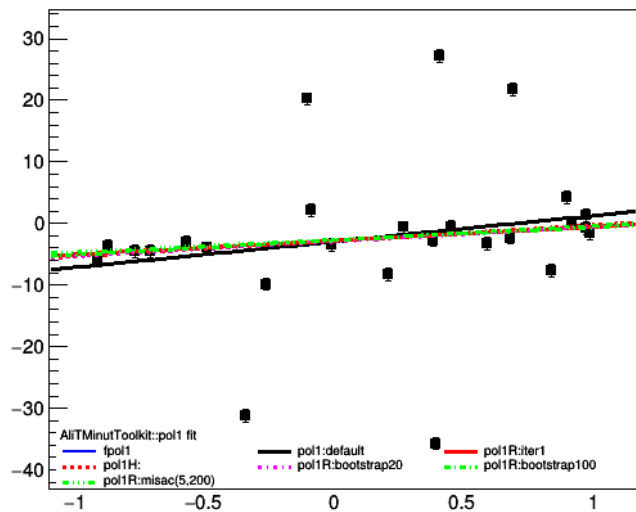
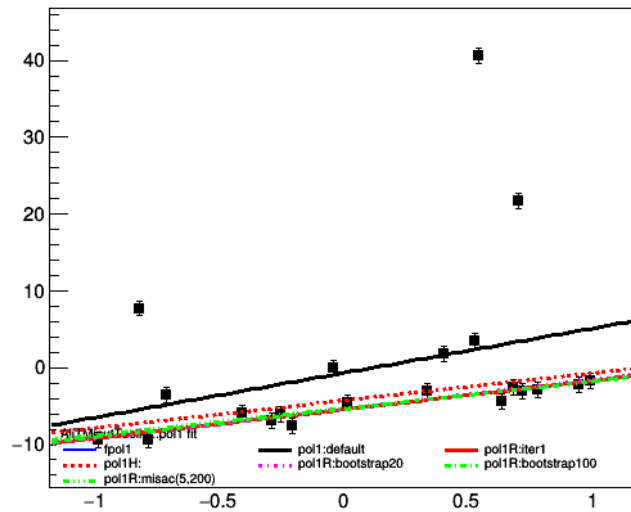
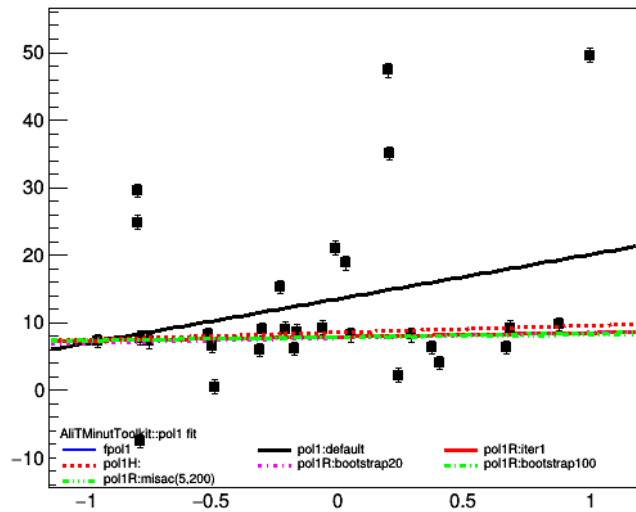
## Input - linear model

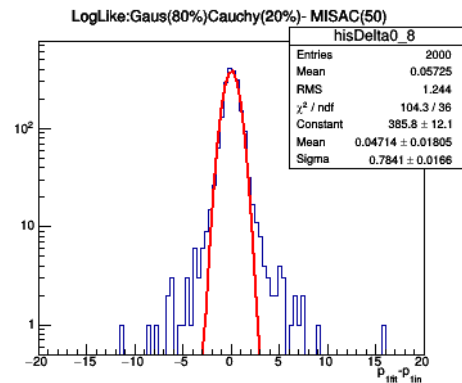
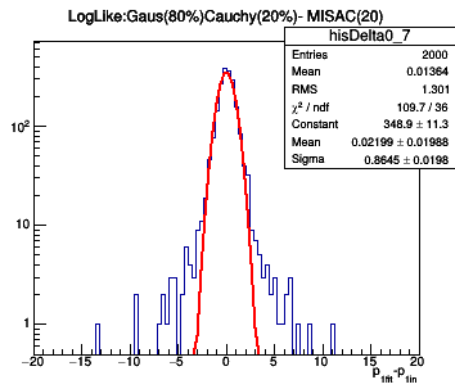
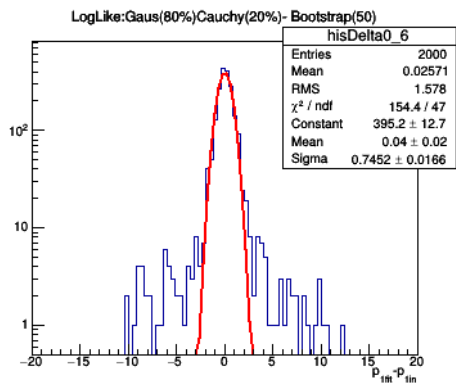
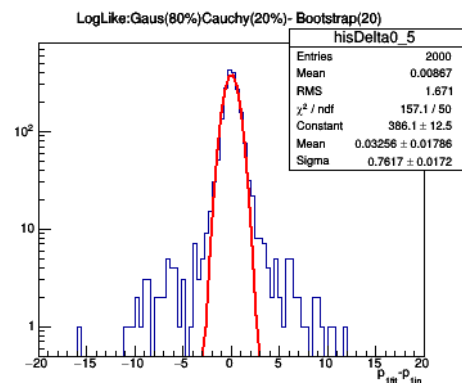
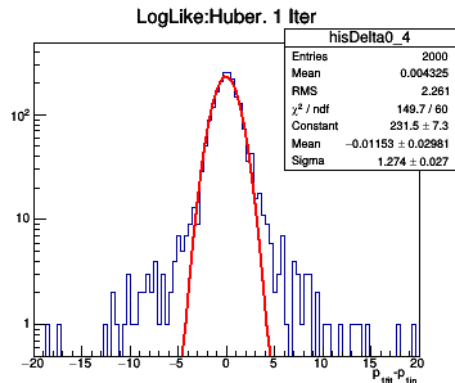
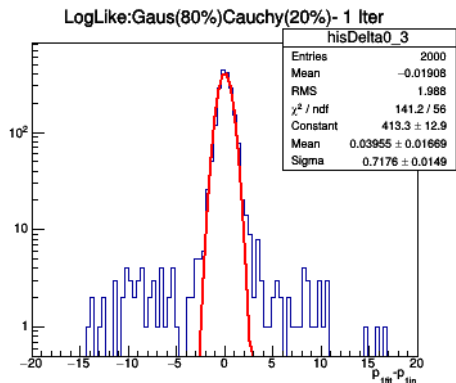
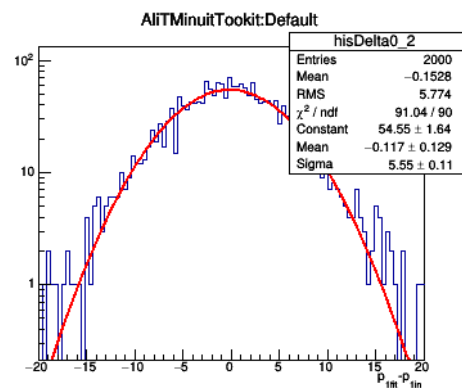
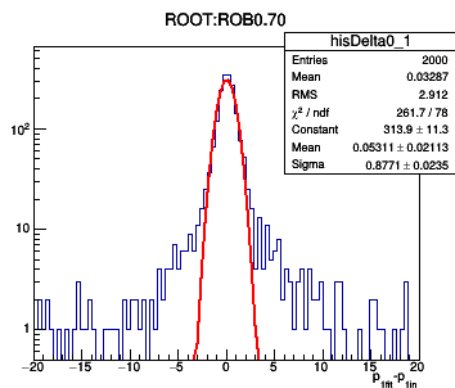
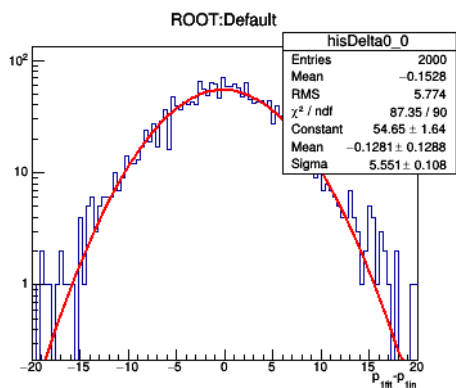
- noise = (60-80%) Gaus(1) + (20%-40%) Gaus(20)

## Methods compared:

- ROOT:Default
- ROOT:Robust linear fitter (2005, AK,MI)
  - LTS estimator
- AliTMinuitToolkit:Default (chi2)
- LogLike: 80% Gaus+20% Cauchy
  - 1 iter
- LogLike:Huber
- Bootstrap
  - 20,50 iteration
  - LogLike: 80% Gaus+20% Cauchy
- MISAC/RANSAC
  - 20,50 iteration
  - LogLike: 80% Gaus+20% Cauchy

# Comparison of M-estimator minimizers





## Interface similar in standard fits:

- `AliTMinuitToolkit * AliTMinuitToolkit::Fit(TGraph *graph, const char *fitterName, Option_t* option, Option_t* goption, Option_t* foption, Double_t xmin, Double_t xmax);`
- `AliTMinuitToolkit * AliTMinuitToolkit::Fit(TH1* his, const char *fitterName, Option_t* option, Option_t* goption, Option_t* foption, Double_t xmin, Double_t xmax) ;`

## Parameters:

- `fitterName` instead of the fit function (fitters to be registered before)
- `foption` to specify draw option for function itself
- other parameters as in standard `TH1::Fit` and `TGraph::Fit`
- `fioption` can be used to parse fitter parameters - e.g. number of fitting iteration for bootstrap and MISAC (see example below)

# User interface. Example

## Example usage: code to compare different minimizer setting

- `AliTMinuitToolkit*fitter2 =  
 AliTMinuitToolkit::Fit(gr,"pol1","default", "",  
 "funOption(1,3,1)"); // standard minuit`
- `AliTMinuitToolkit*fitter3 =  
 AliTMinuitToolkit::Fit(gr,"pol1R","iter1", "",  
 "funOption(2,3,1)"); // logLike:gaus+cauchy`
- `AliTMinuitToolkit*fitter4 =  
 AliTMinuitToolkit::Fit(gr,"pol1H","", "",  
 "funOption(2,3,2)"); // logLike: huber`
- `AliTMinuitToolkit*fitter5 =  
 AliTMinuitToolkit::Fit(gr,"pol1R","bootstrap20",  
 "", "funOption(6,3,4)"); // bootstrap20`
- `AliTMinuitToolkit*fitter6 =  
 AliTMinuitToolkit::Fit(gr,"pol1R","bootstrap100", "",  
 "funOption(3,3,5)"); // bootstrap100`
- `fit6=*(fitter6->GetParameters()); rms6=*(fitter6-  
 >GetRMSEstimator());`
- `AliTMinuitToolkit*fitter7 =  
 AliTMinuitToolkit::Fit(gr,"pol1R","misac(5,200)", "", "fun  
 Option(3,3,6)"); // misac 20`

# To do

Test fits in N-dimensions for fit of the distortion models

- fit parameters - space charge density in hotspots

Improve MISAC/RANSAC method and use correlation

Implementation of other robust methods