



# Imaging Algorithm Optimization of Dry Storage Casks Based on Micro-Pattern Gas Detector

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- 2 MUON IMAGING FUNDAMENTAL PRINCIPLES
- 3 RECONSTRUCTION ALGORITHM AND RESULTS
- 4 SUMMARY AND FUTURE WORK



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# 1

## RESEARCH BACKGROUNDS AND SIGNIFICANCE

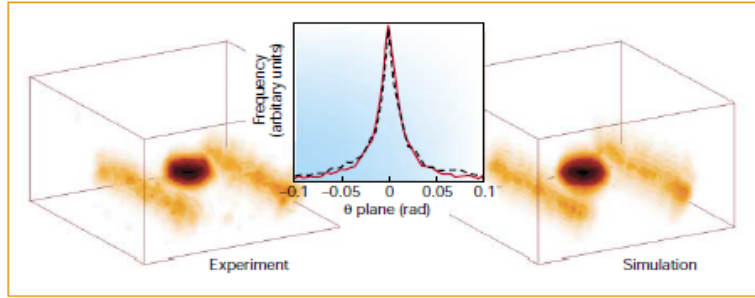


**brief communications**

# Radiographic imaging with cosmic-ray muons

Natural background particles could be exploited to detect concealed nuclear materials.

Despite its enormous success, X-ray radiography<sup>1</sup> has its limitations: an inability to penetrate dense objects, the need for multiple projections to resolve three-dimensional structure, and health risks from radiation. Here we show that natural background muons, which are generated by cosmic rays and are highly penetrating, can be used for radiographic imaging of medium-to-large, dense objects, without these limitations and with a reasonably short exposure time. This inexpensive and harmless technique may offer a



In 2003, "Nature" magazine put forward the concept of scattering imaging using the muon of natural background in the package.

**Nature, 2003, 422(6929): 277-277**

✓ **No artificial radiation**

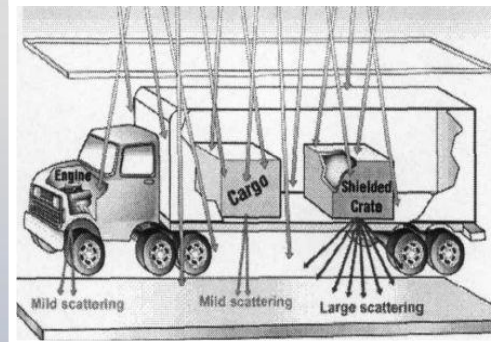
The flux is about  $1 / (cm^2 \cdot min)$

✓ **No radiation damage**

Only electromagnetic effect, no nuclear effect

✓ **Strong penetration**

Energy distribution in the distribution of 0.1-1000GeV, the average energy of 3-4GeV



Lausanne Alamos National Laboratory  
First Muon Imaging Principle Prototype





# Foreign Research Status Quo

(DATA STATISTICS AS OF 2017)

| Country | Group                          | Purpose  |
|---------|--------------------------------|--|
| Japan   | Nagoya University<br>KEK , NEP | Khufu Pyramid Voids Imaging<br>(2017-nature)             |
| Canada  | Chalk Reactor Creek<br>Site    | Zed-2 Reactor Imaging And Dry Storage Cask<br>Monitoring |
| France  | CEA                            | Saclay To Tower Imaging                                  |
| America | Los Alamos                     | Fukushima Nuclear Accident Simulation<br>(2012-prl)      |
|         | Purdue University              | Dry Storage Tank Monitoring                              |
| Sweden  | Uppsala University             | Nuclear Fuel Barrel Imaging                              |
| Japan   | KEK                            | Reactor Imaging  |
|         | Tsukuba University             | Reactor Imaging  |

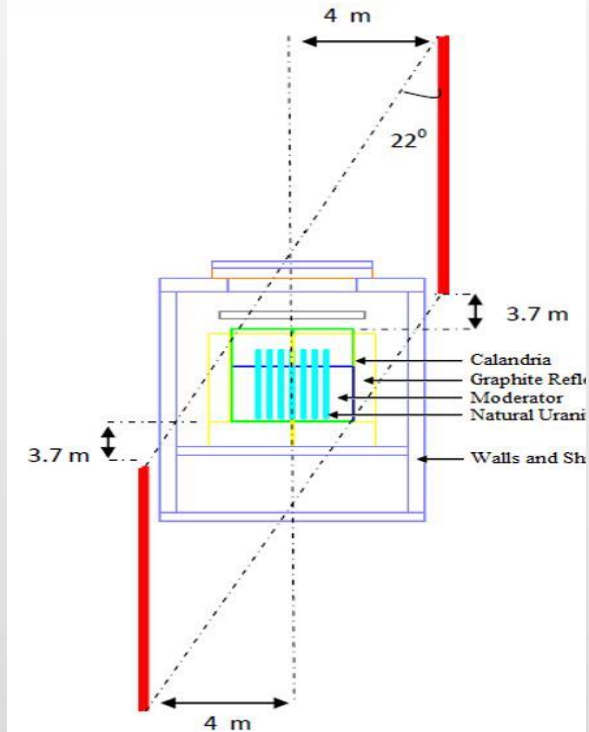


## Research Significance:

- I. Check if the reactor core melts under accident conditions.
- II. Two-dimensional imaging of heavy nuclear matter in the encapsulated body.

## Application:

- Nondestructive testing of spent fuel dry storage drums
- Imaging in-reactor nuclear fuel assembly
- Imaging the damaged reactor
- Remote monitoring and control reactor core



**ZED-2 Reactor Bilateral  
Imaging Structure**

Proceedings of the INMM 54th Annual Meeting, Palm Desert, CA, USA, 2013 July 14-18

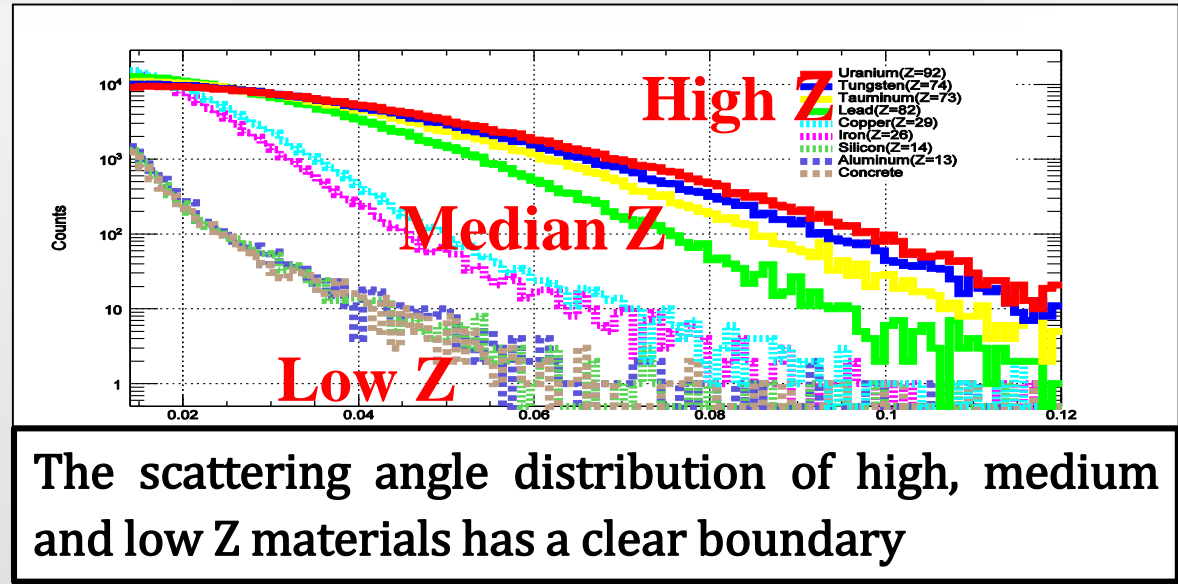
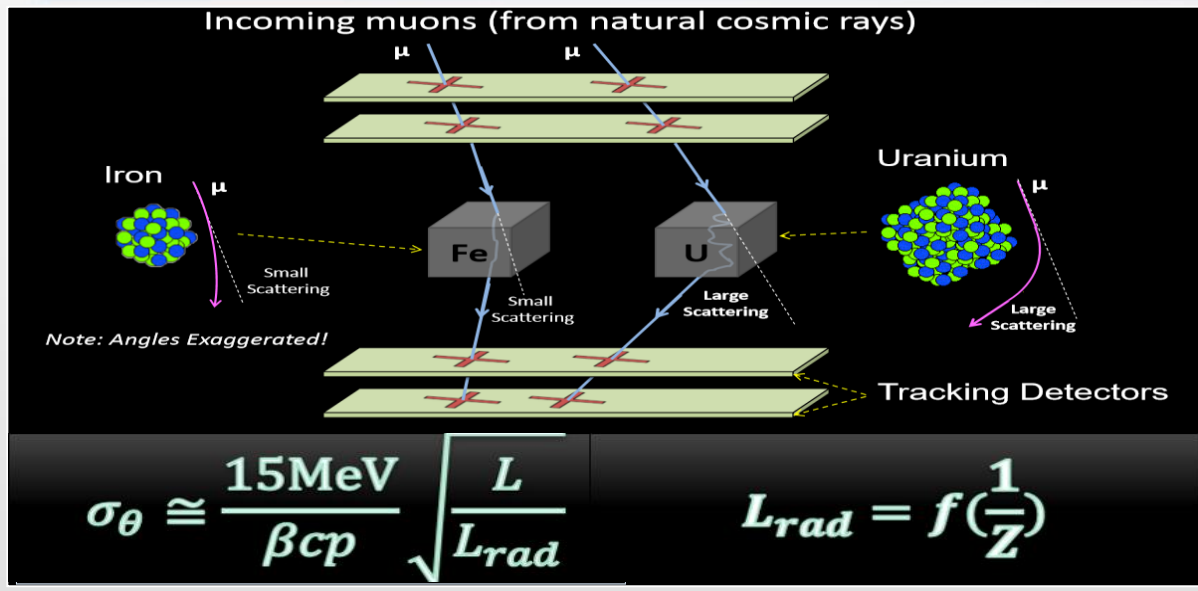
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# 2

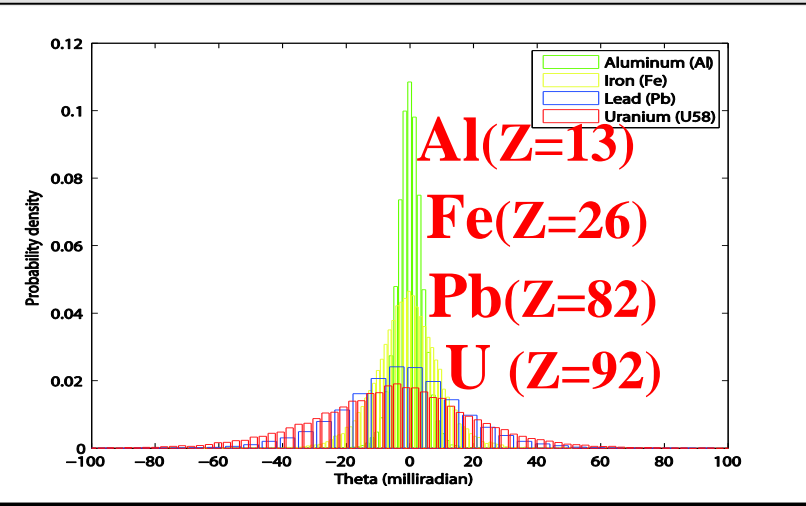
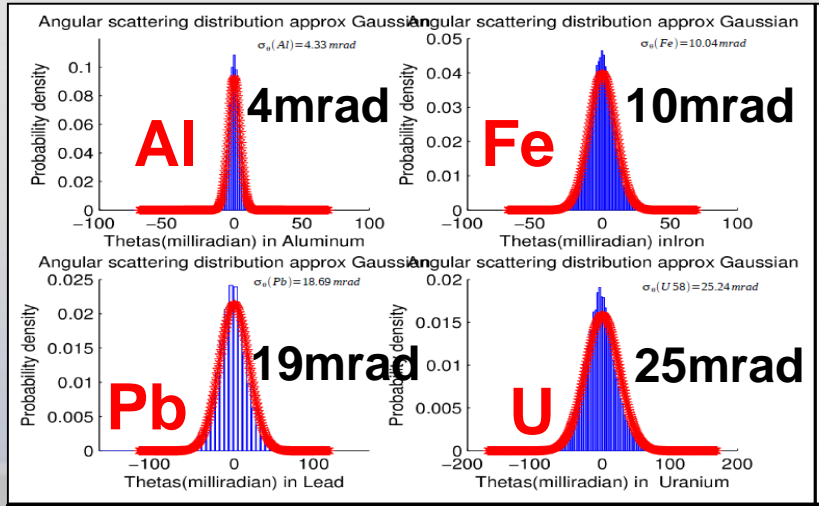
# MUON IMAGING FUNDAMENTAL PRINCIPLES





The scattering angle distribution of high, medium and low Z materials has a clear boundary

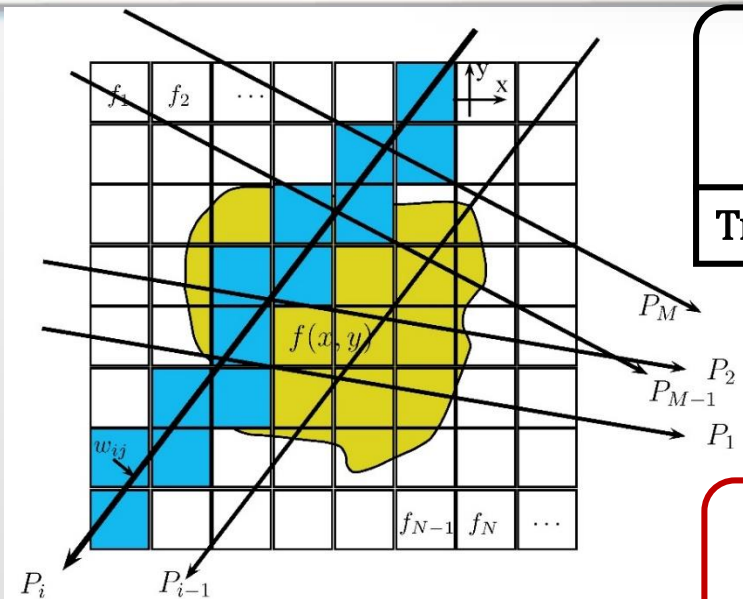
Muon Multiple Coulomb Scattering (MCS)



The scattering angle of Muon approximates the Gaussian distribution



# Muon Multiple Coulomb Scattering (MCS)



B. Rossi. High Energy Particles, 1952.

$$P_i = \sum_j L_{ij} f_j$$

Traditional Tomography

$$\Sigma_i = p_{r,i}^2 \sum_j L_{ij} \lambda_j$$

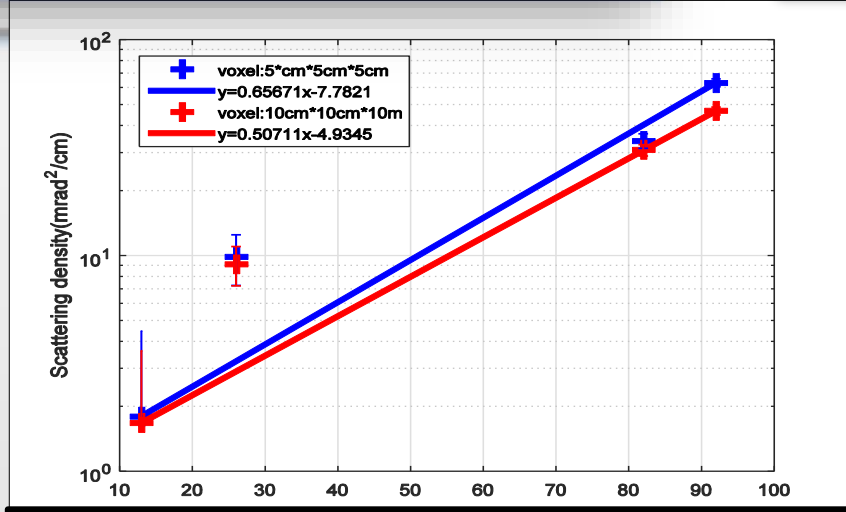
Object Characteristic Function Lambda\_j

$$\lambda = \left(\frac{p}{p_0}\right)^2 \frac{\sigma_\theta}{L}$$

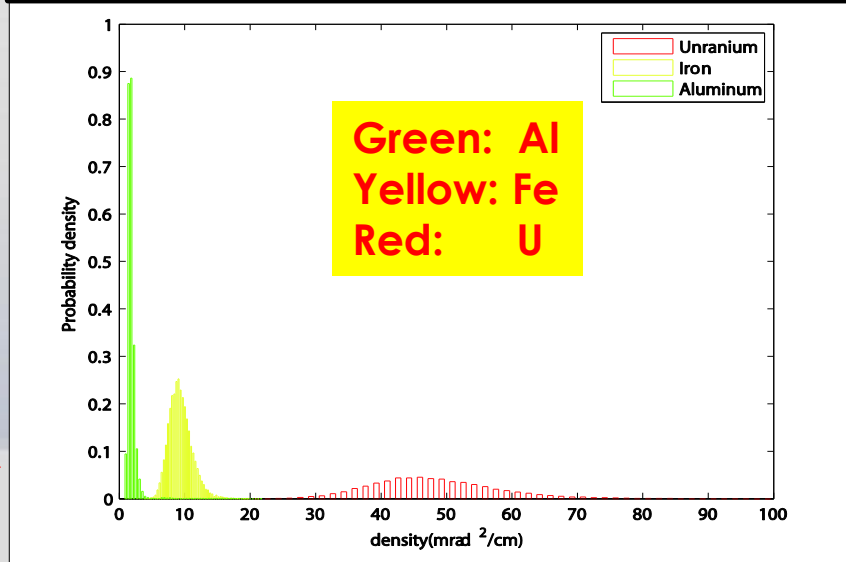
$$\sigma_\theta \cong \frac{15MeV}{\beta cp} \sqrt{\frac{L}{L_{rad}}}$$

$$\lambda(L_{rad}) = \left(\frac{15}{p_0}\right)^2 \frac{1}{L_{rad}}$$

Scattering density : Standard muons pass through the material per unit thickness, Its scattering angle variance size.



Scattering density is proportional to Z  
 Clear demarcation of the distribution



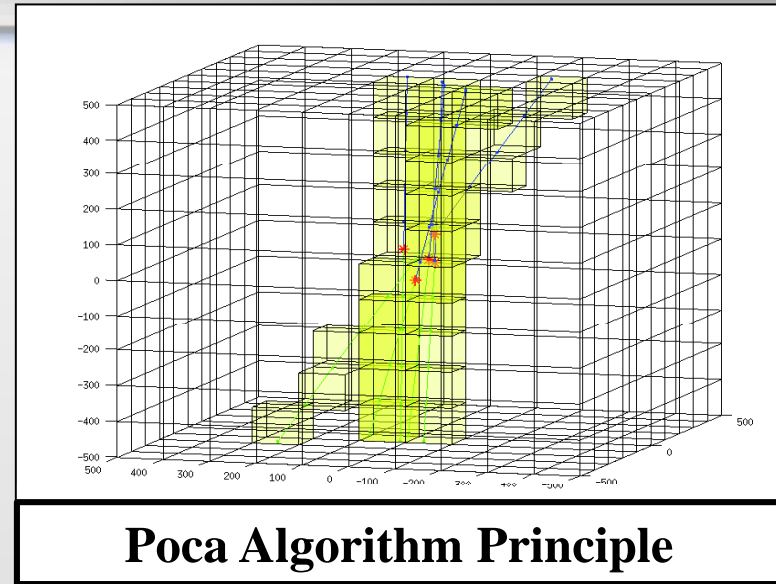
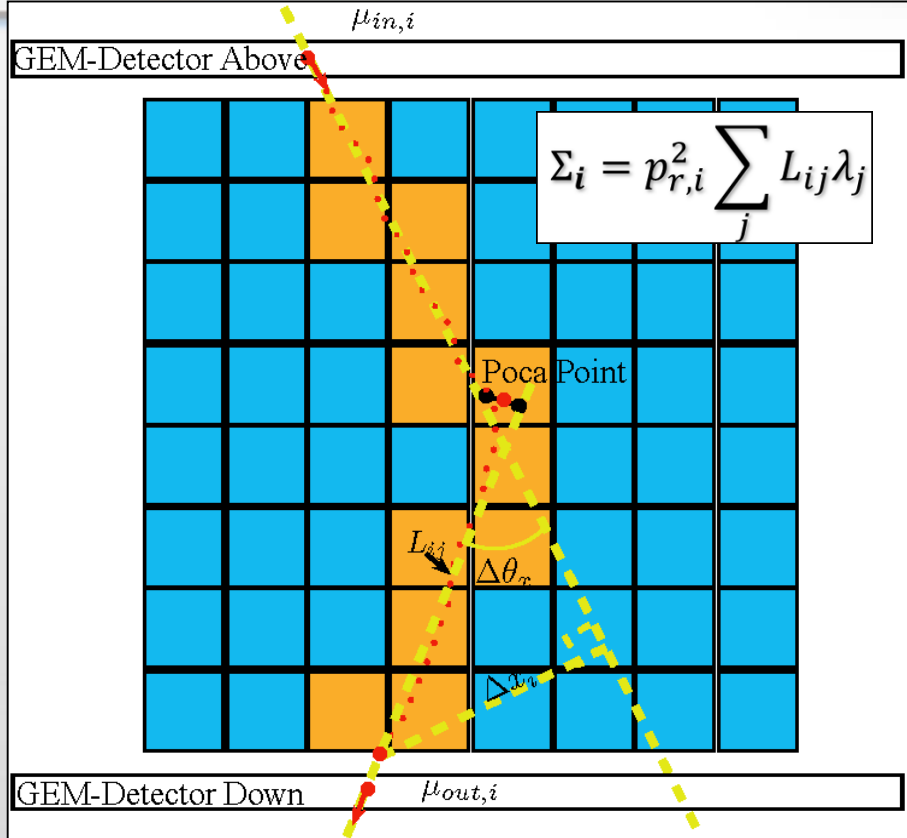
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# 3

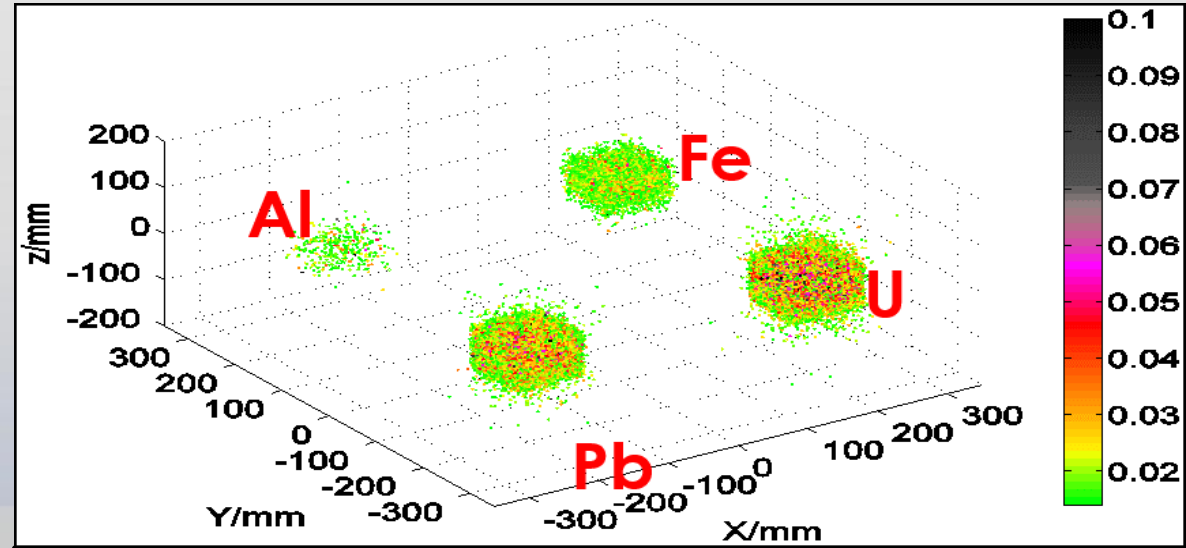
## RECONSTRUCTION ALGORITHM AND RESULTS



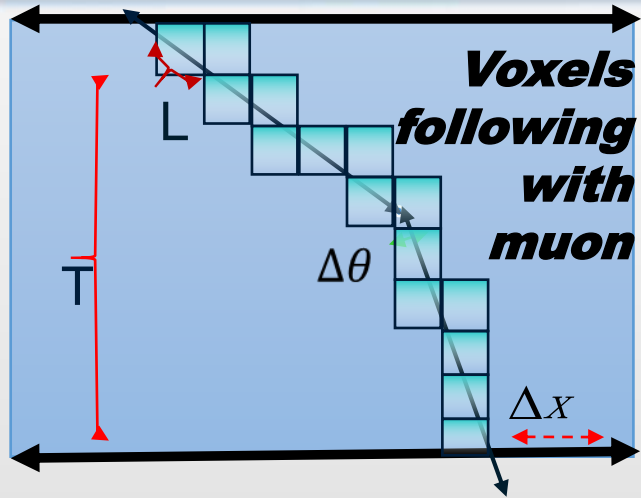


Point Of Closet Approach (PoCA)

Estimates the scattering points by solving the midpoint of the out-of-plane-line to obtain the estimated scattering density of each voxel.



The PoCA algorithm is sensitive to high Z materials



$$MLS: D_i = \Delta\theta_i$$

$$MLSD: D_i = \begin{bmatrix} \Delta\theta_i \\ \Delta x_i \end{bmatrix}$$

$$\Sigma_i = p_{r,i}^2 \sum_j L_{ij} \lambda_j$$

$$\Sigma_i = p_{r,i}^2 \sum_j W_{ij} \lambda_j$$

Maximum Likelihood Scattering-Expectation Maximization (ML-EM)

Step E: Calculate the conditional probability distribution  $P(D, H|\lambda)$  of implicit data H

$$\begin{bmatrix} L_{ij} & \frac{L_{ij}^2}{2} + L_{ij}T_{ij} \\ \frac{L_{ij}^2}{2} + L_{ij}T_{ij} & \frac{L_{ij}^3}{3} + L_{ij}^2T_{ij} + T_{ij}^2L_{ij} \end{bmatrix}$$

$$MLS - EM: S_{ij} = f(L_{ij}, D_i, \Sigma_i, p_{r,i}^2, \lambda_j)$$

$$MLSD - EM: S_{ij} = f(L_{ij}, T_{ij}, D_i, \Sigma_i, p_{r,i}^2, \lambda_j)$$

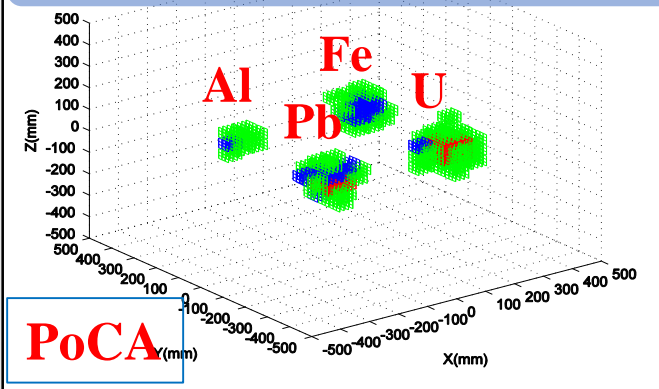
Step M: Maximize the likelihood function and obtain the estimated scattering density  $\lambda$

$$\lambda_j^{n+1} = \sum_{i:L_{ij} \neq 0} \frac{S_{ij}}{2M_j}$$

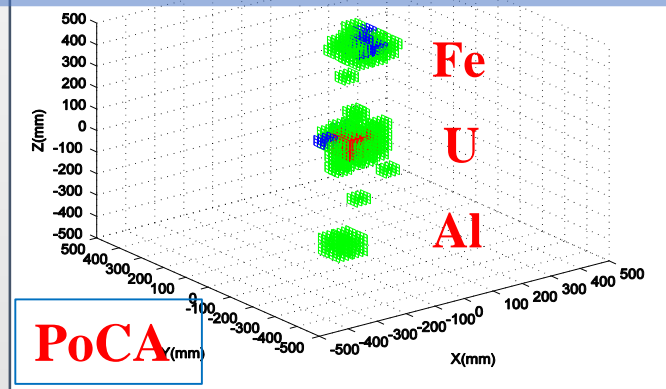
$$\lambda_j^{n+1} = \frac{1}{2} \text{median}_{i:L_{ij} \neq 0} \cdot S_{ij}$$

Iterates to the distribution of the previous step, iterating until convergent.

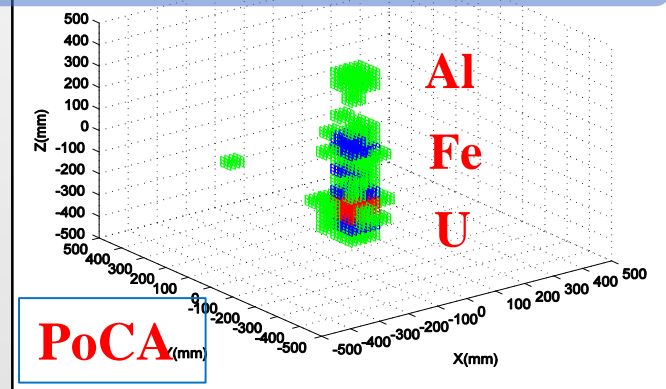
Rapidly, Qualitative distinction



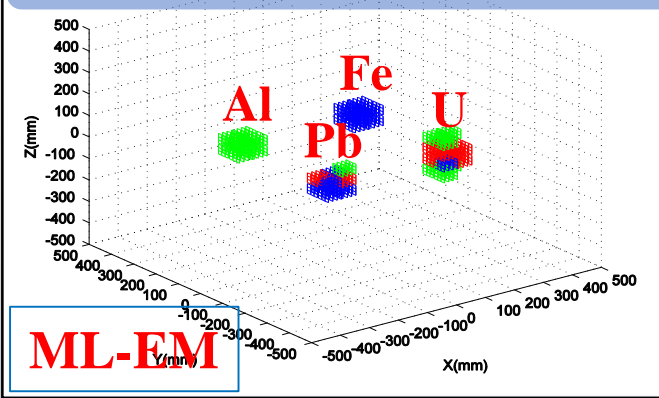
Poor resolution results



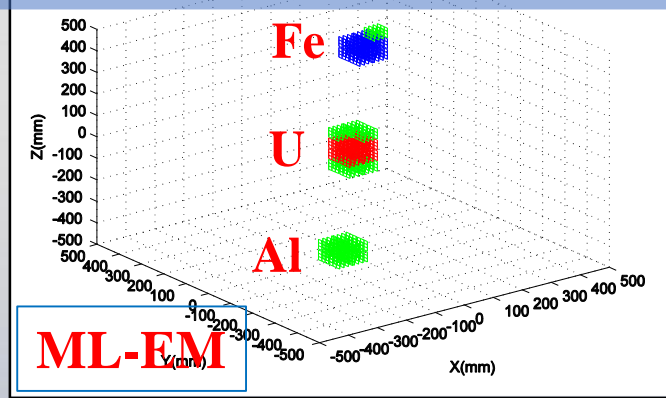
Poor resolution results



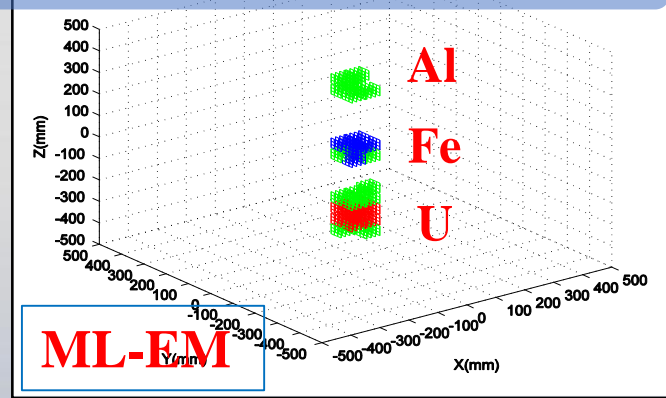
High resolution, Slow convergence



Longitudinal resolution obvious



Longitudinal resolution obvious



Horizontal imaging

Diagonal imaging

Longitudinal imaging

**ML-EM  
AND  
PoCA  
Results  
Compared**



Use Bayes' rule to get the posterior probability

$$P(D|\lambda) = \frac{P(D|\lambda)P(\lambda)}{P(D)}$$

Add prior knowledge of the constraints

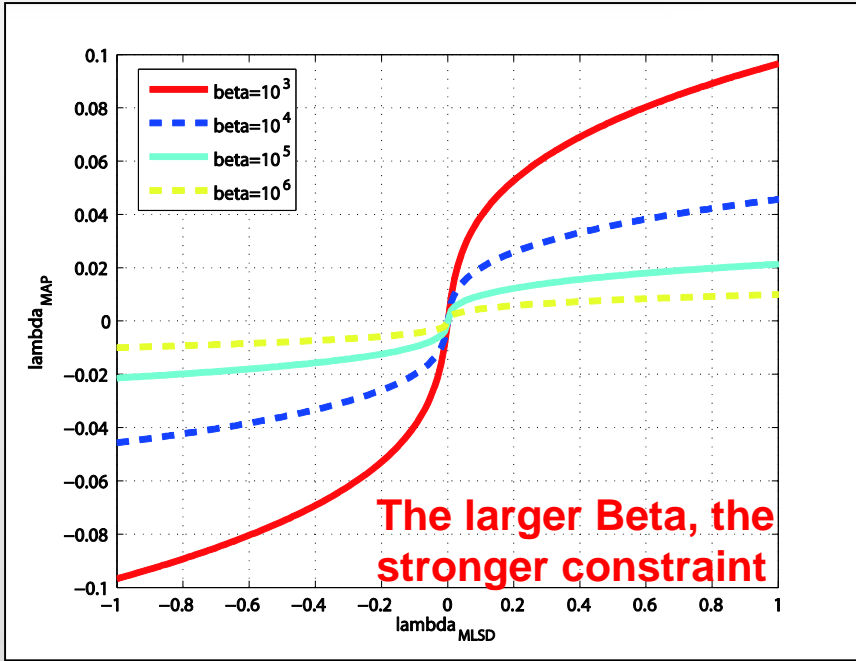
$$p(\lambda) = Ae^{-\beta U(\lambda)}, U(\lambda) = \sum_j V(\lambda_j)$$

Divide the data into ordered subsets for acceleration

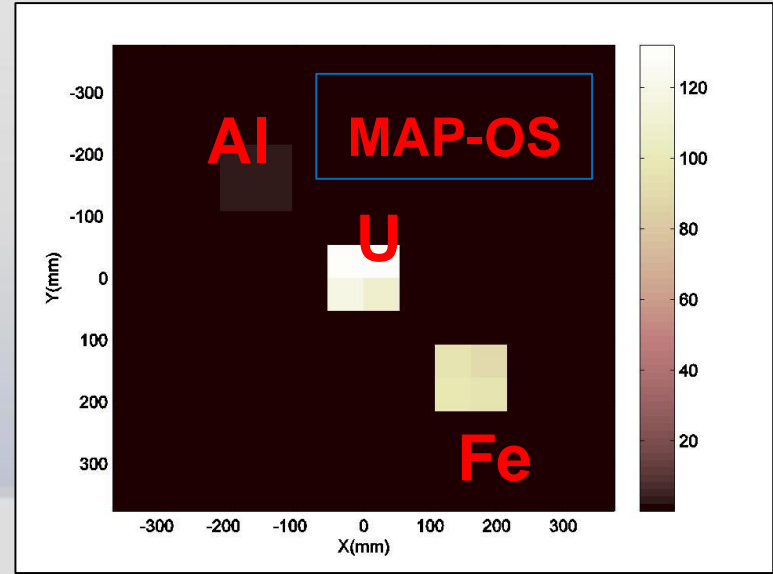
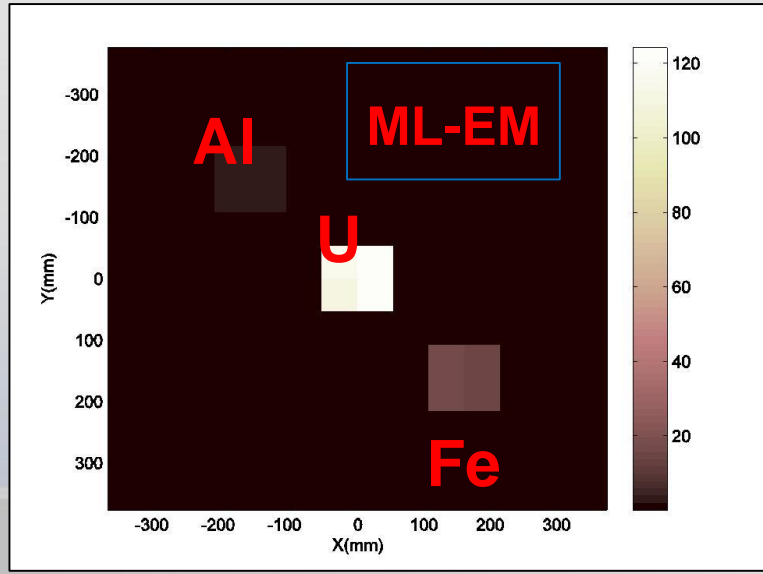
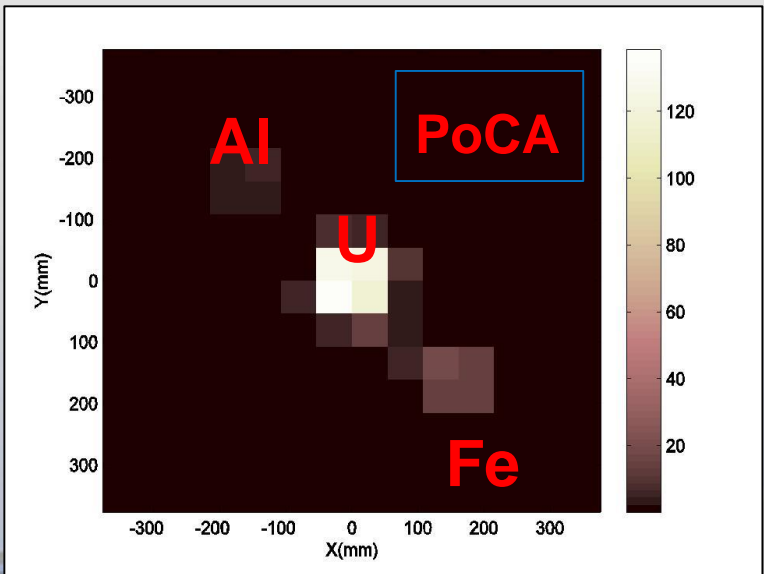
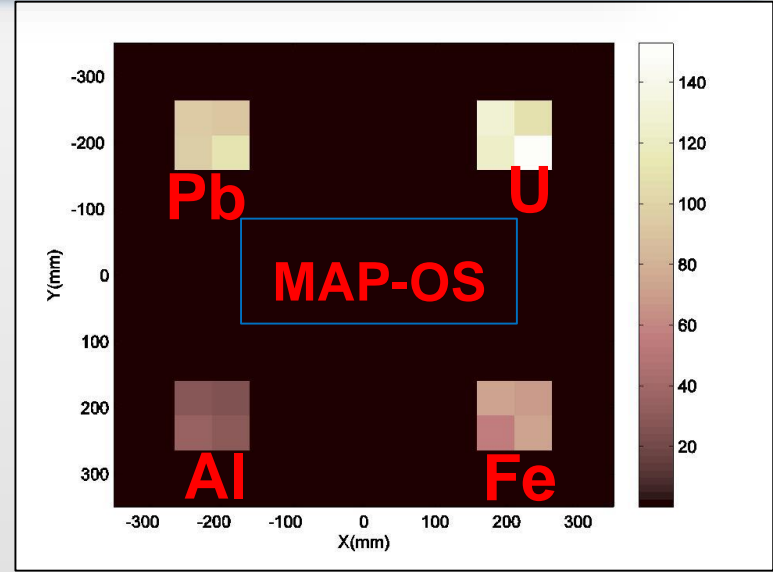
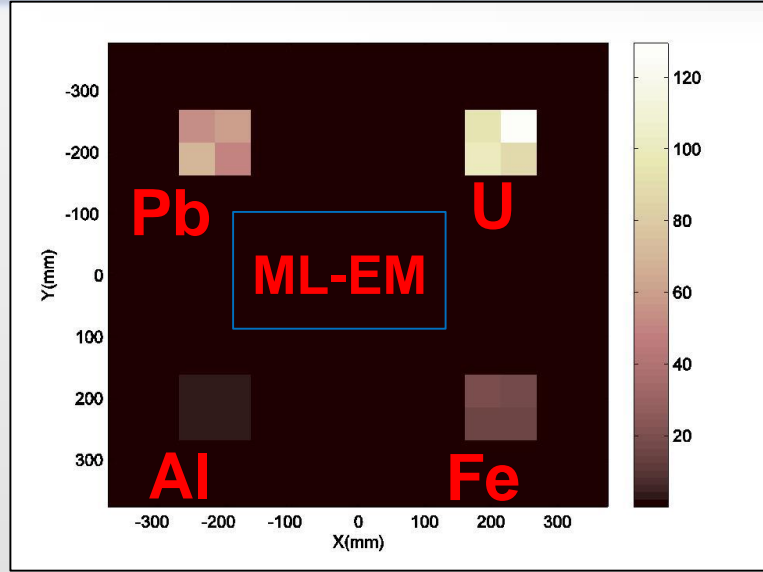
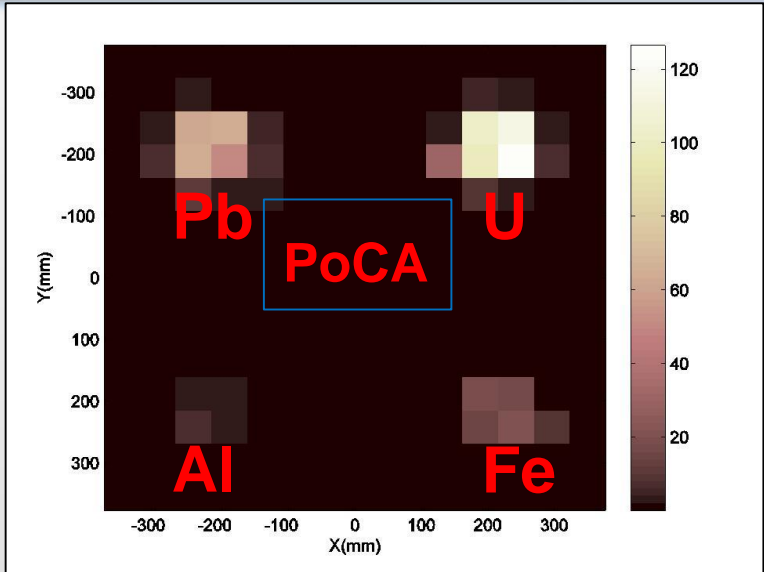
$$\lambda_{MAP-OS}^{n+1} = \arg \max_{\lambda} \left( \sum_j \sum_{i \in S_b} (-\log \lambda_j - S_{ij} / (2\lambda_j)) \right) - \beta U(\lambda)$$

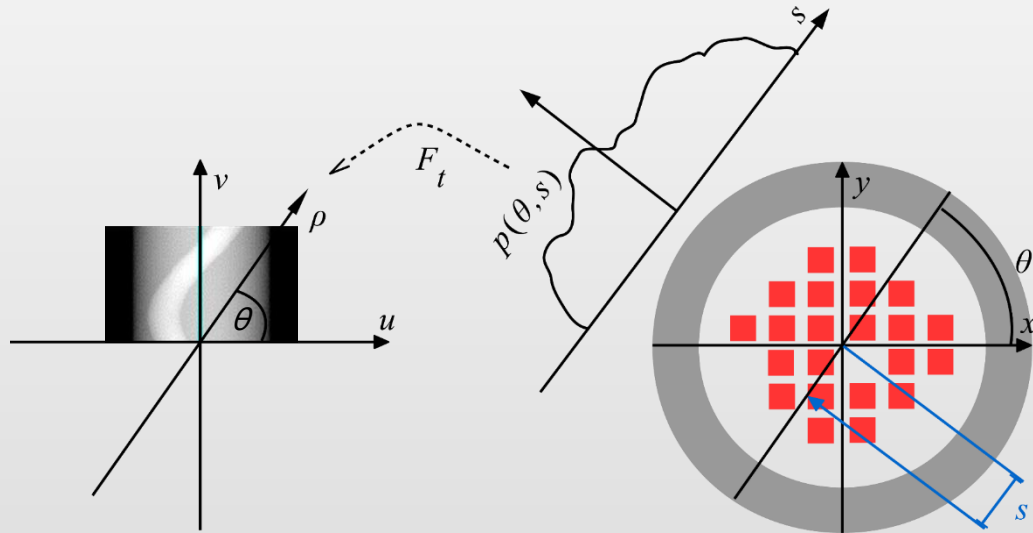
The equations for solving the optimal scattering density are iterated each step

$$-\frac{M_j}{\lambda_j} + \sum_{i:L_{ij} \neq 0} S_{ij}^n - \beta \dot{V}(\lambda_j) = 0$$



Maximum A Posteriori Probability Ordered Subset Acceleration  
**MAP-OS**

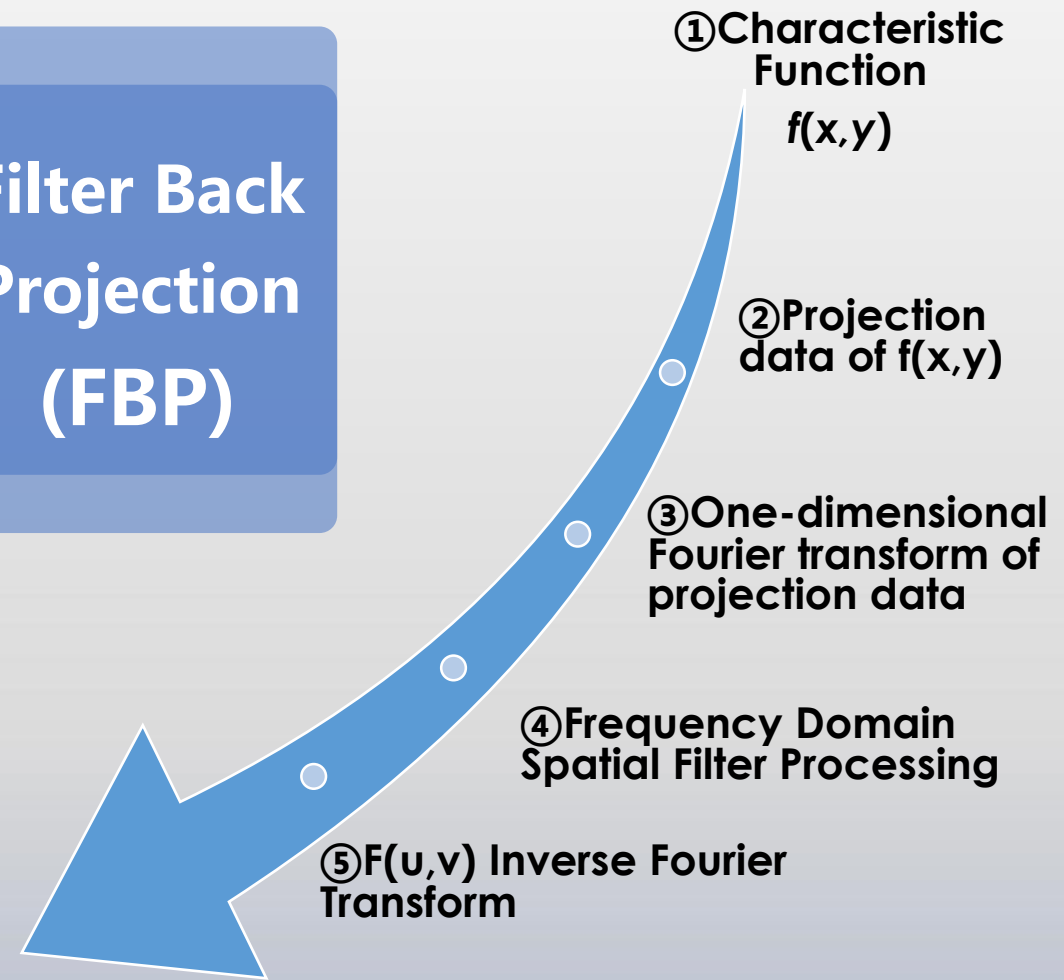




**Sinogram:** 2D image of projection data at all  $\theta$  angles.

**Projection:** The amount of attenuation collected by Muon after it reached the detector through a spent fuel bucket on a path.

**Filter Back Projection (FBP)**



① Characteristic Function  $f(x,y)$

② Projection data of  $f(x,y)$

③ One-dimensional Fourier transform of projection data

④ Frequency Domain Spatial Filter Processing

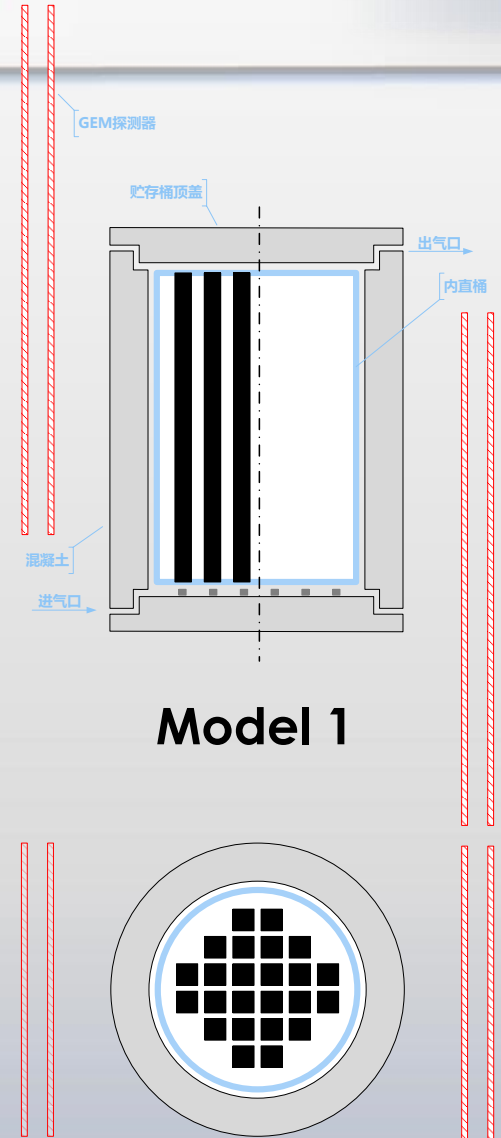
⑤  $F(u,v)$  Inverse Fourier Transform

⑥ Get the eigenfunction image

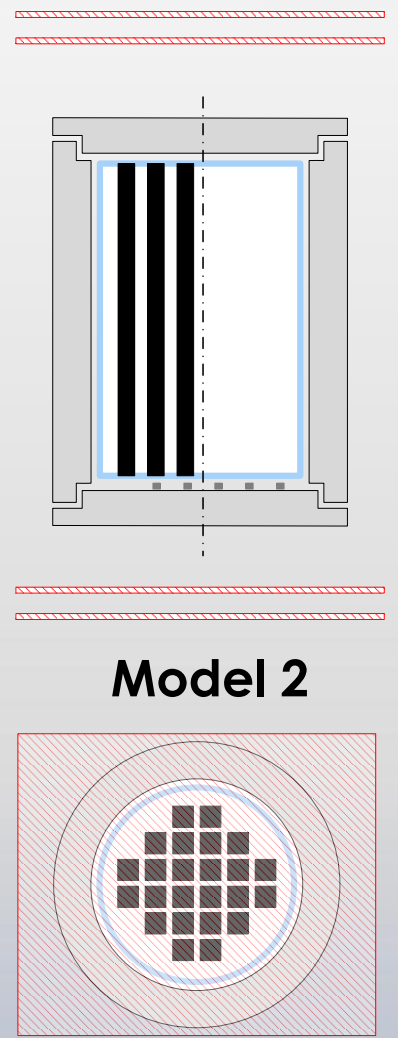




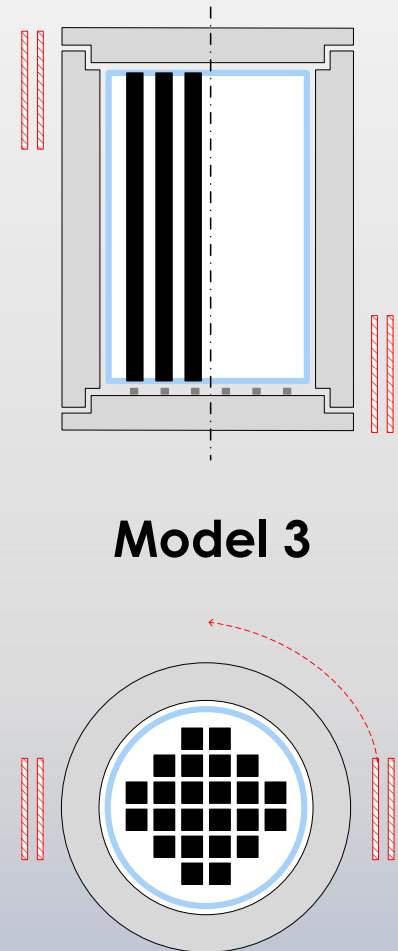
Four models  
for building  
detectors  
outside dry  
storage casks



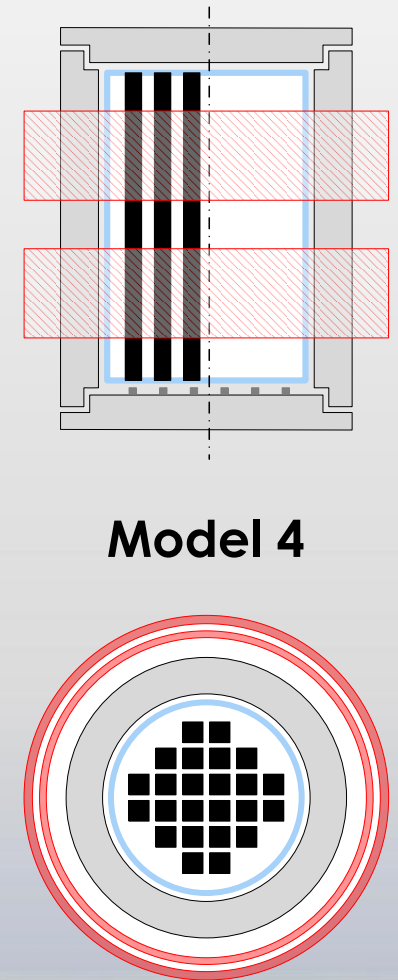
Model 1



Model 2

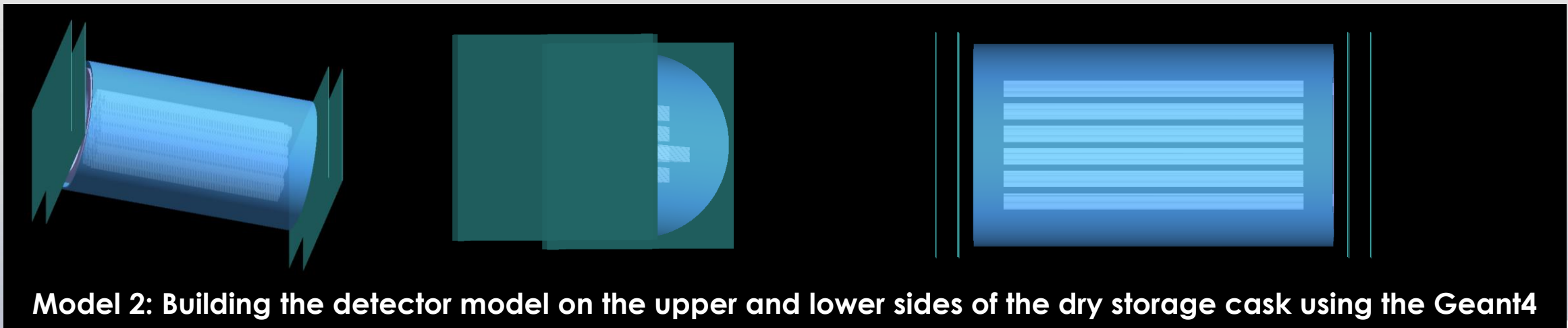
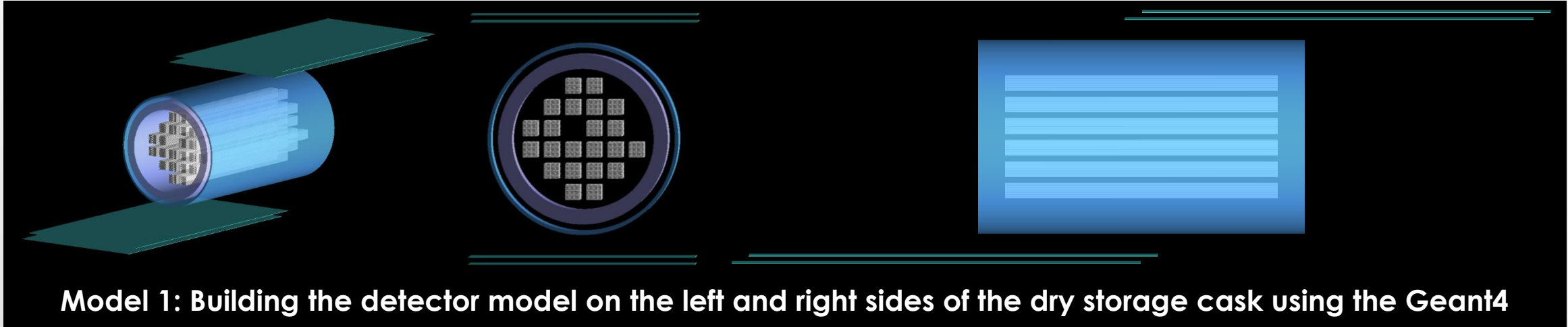


Model 3

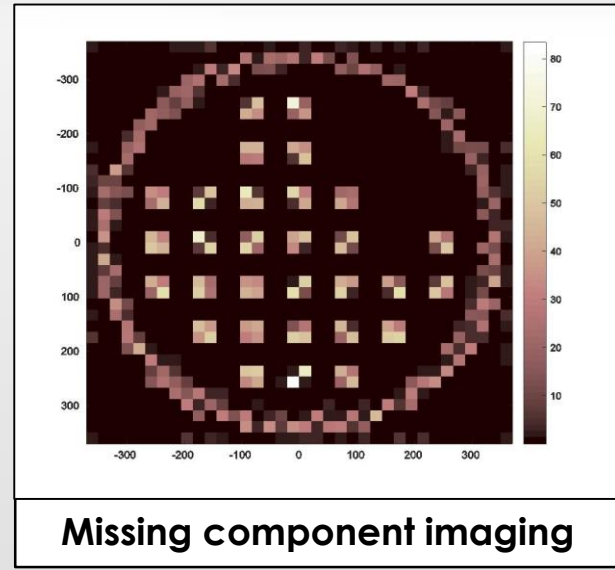
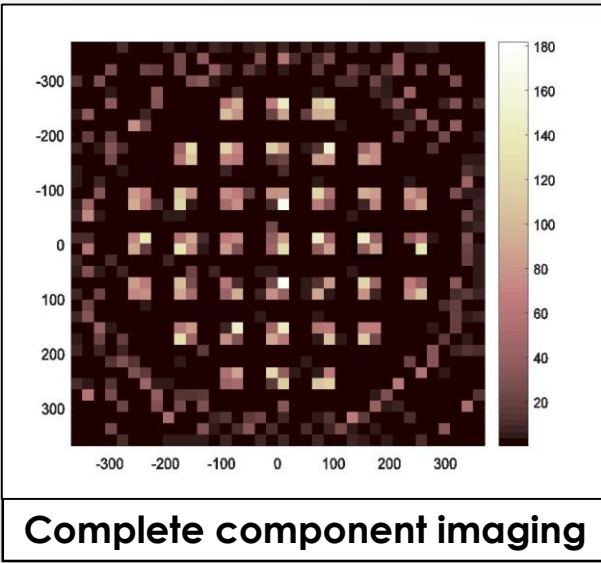


Model 4

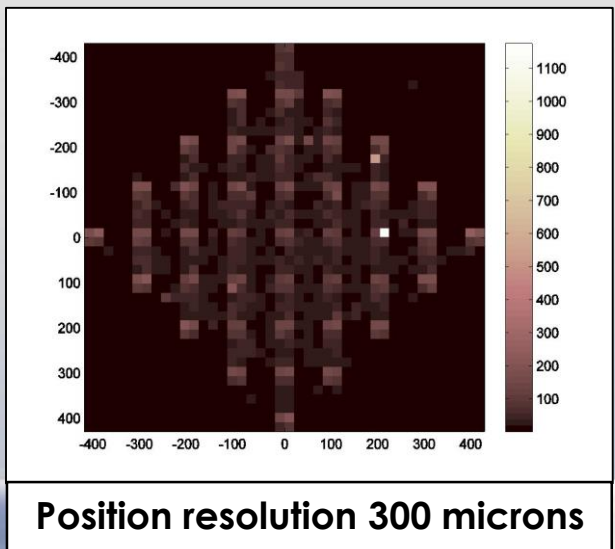
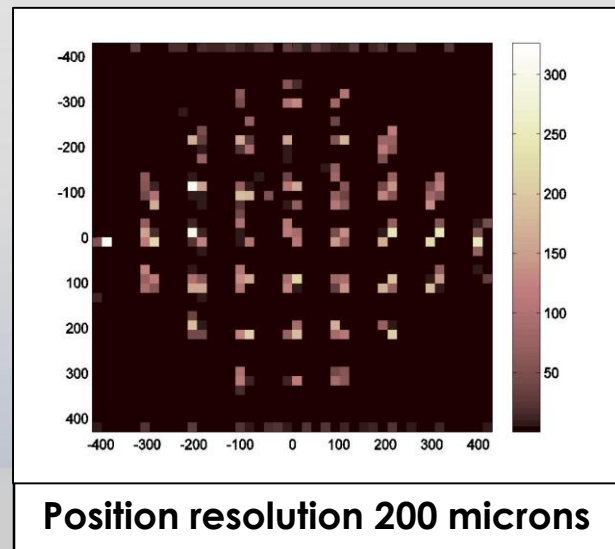
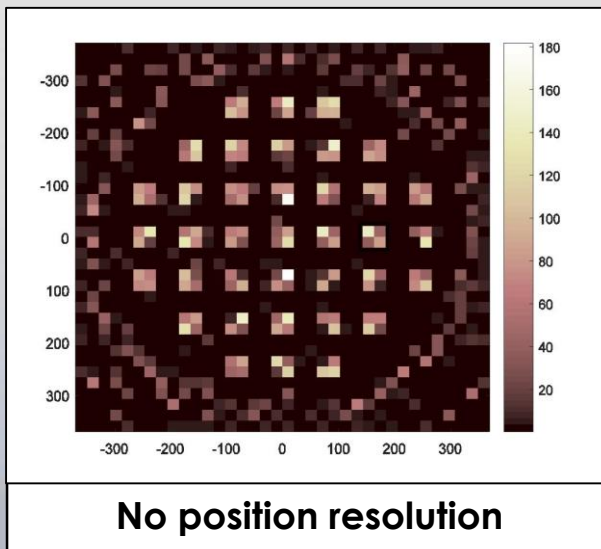


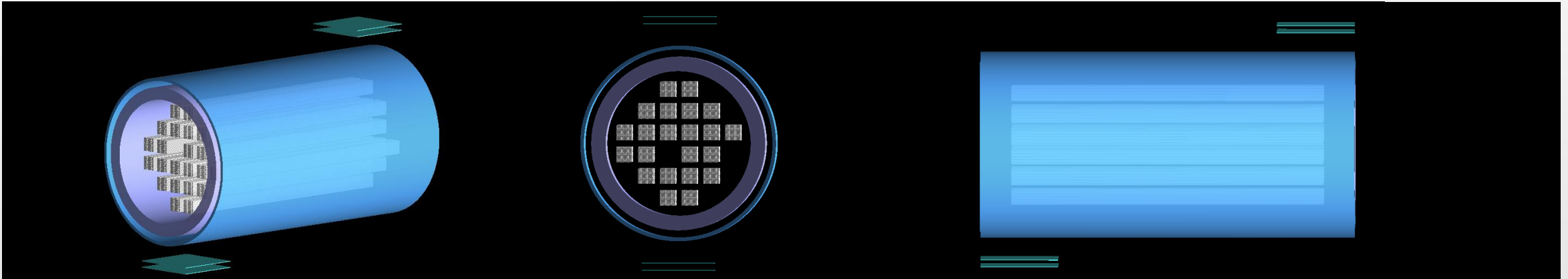


The results of simulation imaging of dry storage cask using PoCA algorithm

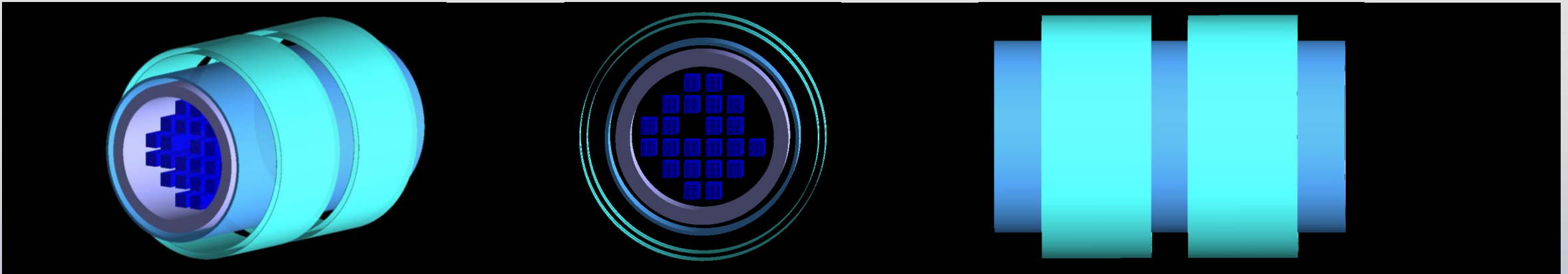


Increased positional resolution of 200,300 microns





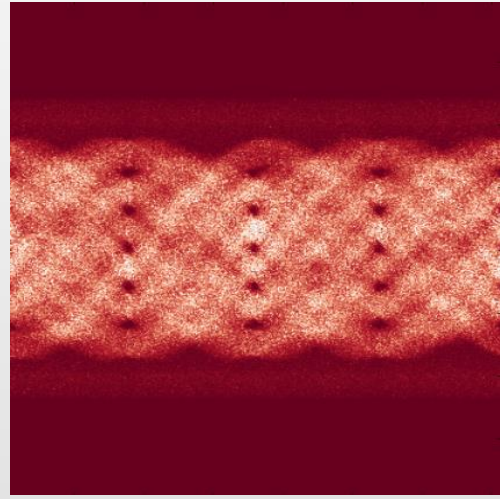
**Model 3: Building the miniature detector model on the left and right sides of the dry storage cask using Geant4**



**Model 4: Building the ring detector model around the dry storage cask using the Geant4**

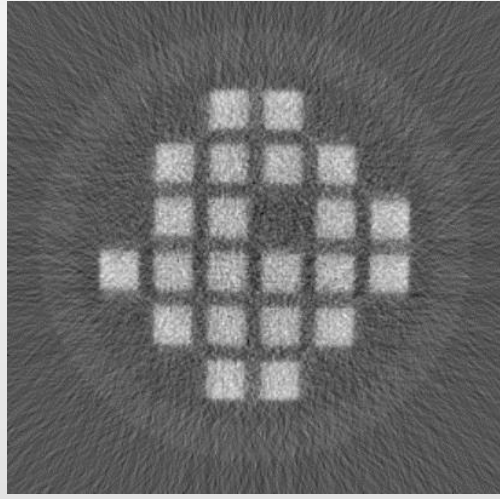


The results of simulation imaging of dry storage cask using FBP algorithm

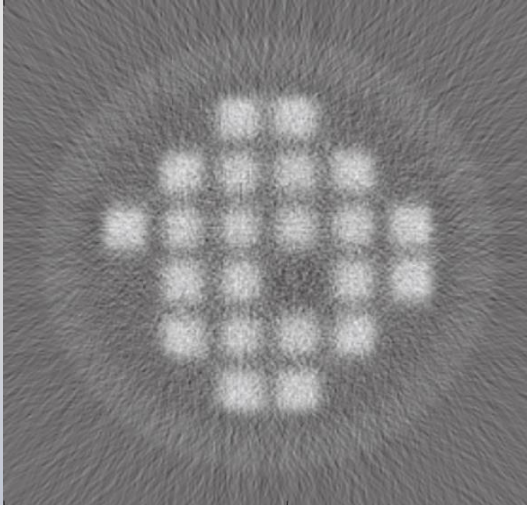
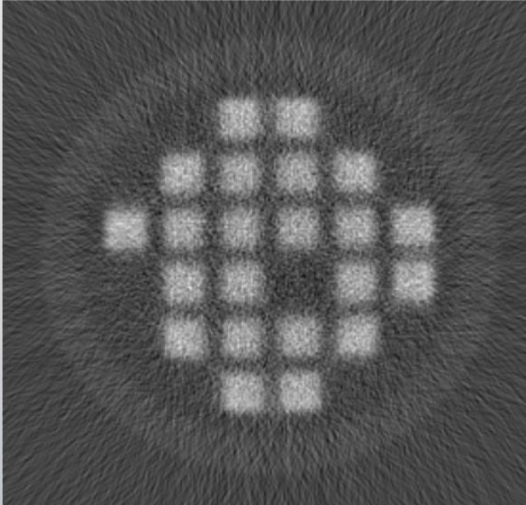
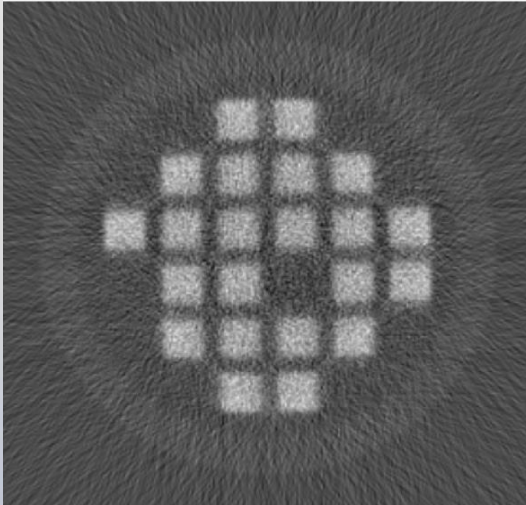


Missing component imaging

Sinogram using FBP

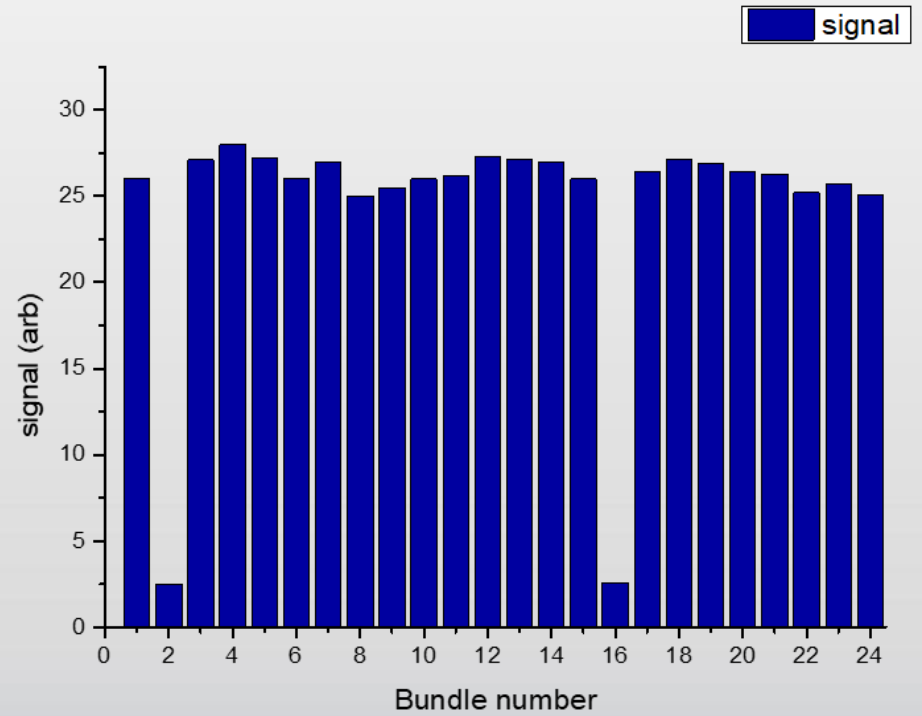
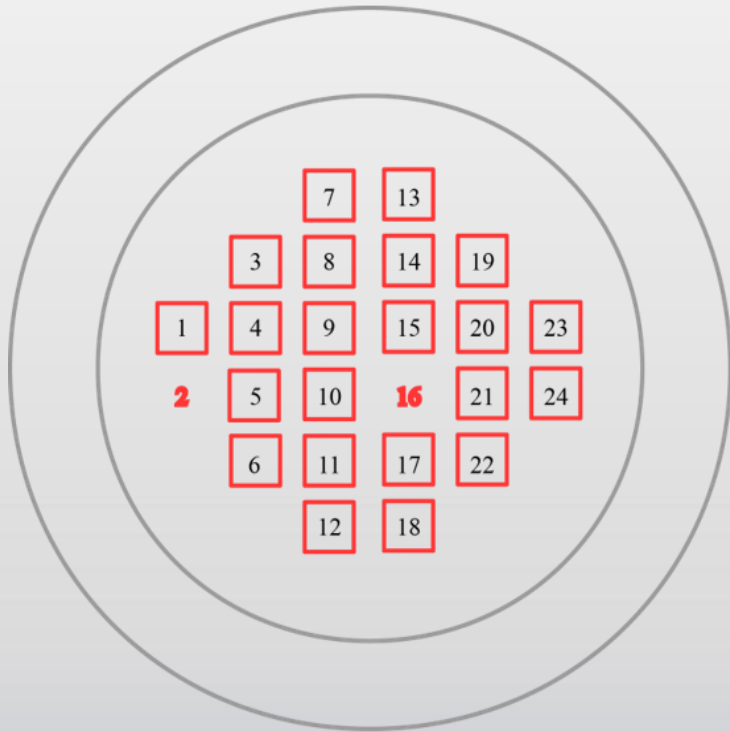


Increased positional resolution of 100, 200, 300 microns





## Quantification Process





# 4

## SUMMARY AND FUTURE WORK



## SUMMARY

- I. The current Muon imaging algorithm is debugged and implemented by Monte Carlo simulation, the results show that:
  - a. The **PoCA** algorithm can rapidly image, qualitatively discriminate the material but poorly image the longitudinal multilayered object;
  - b. The **ML-EM** and **MAP-OS** algorithms sharply image the location and structure of matter;
  - c. The **MAP-OS** algorithm has less iteration time and less memory, and the image smoothing and noise suppression effect is the **best**.





## SUMMARY

- II. Combining with the algorithm, four models are built for simulation of spent fuel dry storage barrel. Through data simulation and image reconstruction, the results show that:
- Both solutions based on the **PoCA algorithm** can **image missing fuel assemblies but take too long time**, and are difficult to operate in view of the problems of oversized gas detectors, high cost, and harsh location conditions.
  - Two optimization schemes based on the **FBP algorithm** can realize the **rapid imaging** of the material in the barrel, the **imaging result is intuitive and the resolution is stronger**. The required detector area is small, the location of the conditions is very simple and easy to implement.



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2018



**Thanks For Your Attention**

USC

University of South China

