

# Crab Cavity Alignment and Monitoring System Inner triplets cold mass monitoring System

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Projet HL-LHC: mini revue sur les activités SU CERN – 2017.06.29

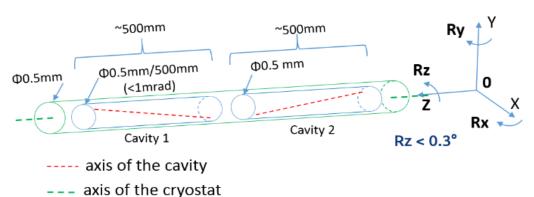
# Crab cavities position monitoring system

- Introduction to crab cavities position monitoring
- Position monitoring and adjustment issues
- Position monitoring systems status



# Crab cavities alignment tolerances

- X-Y: 0.5mm (3σ) for mechanical alignment
  - + 0.5mm for operation errors
- $Rz < 0.3^{\circ}$
- Rx, Ry (mean axis of CC inside Φ0.5mm)



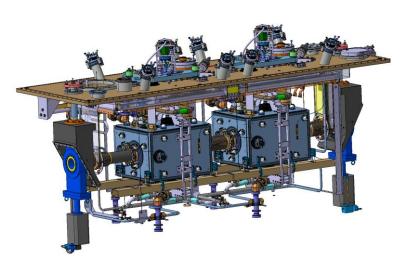




# Adjustment and position monitoring issues

#### Mean axis of the cavities within Φ0.5mm

- Complex structure of cryomodule → unknown impact of RF, vacuum, cryogenics interfaces on cavity alignment
- Required information about cavities alignment under cooling down, operation conditions
- Monitoring system accuracy ~50-100µm needed



#### Main issues

- Monitoring of cold objects (<3K) from the level of room temperature cryostat
- Contraction of the cavities (helium tank) –
  impossible to fiducialise the components
  at operating temperature. Use of thermal contraction
  models needed (verification and correction of the models
  during in-situ measurements SM18, SPS)
- Stability of the cryostat shape during operation

- HL-LHC environmental conditions:
  - Radiation → 10MGy (beam pipe), 1MGy (cryostat surface)
  - All position monitoring system components installed on cavity (helium tank) should work well after cool-down and withstand cooling-warming cycles
  - Vacuum compatible



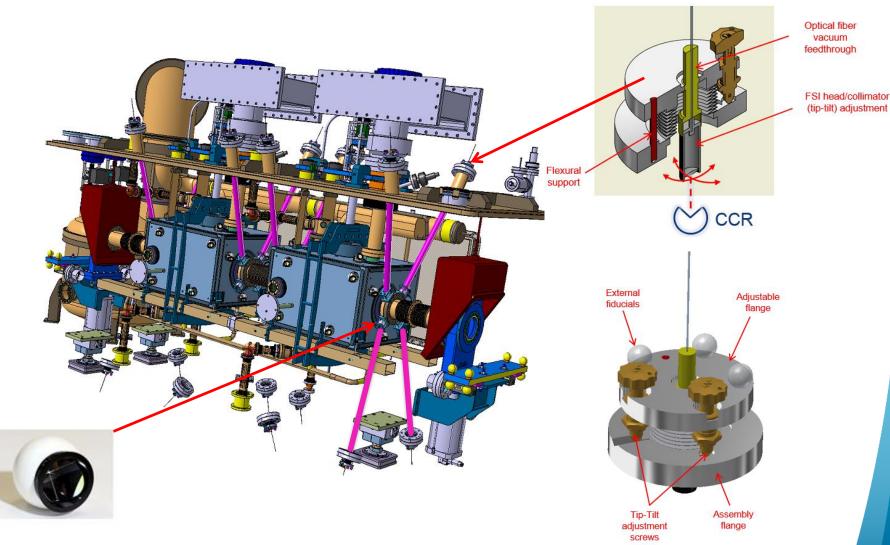
# **Position monitoring systems**

#### **SPS Cryo-module monitoring systems**

- Two systems selected one as primary for future HL-LHC use, second one for cross-check purposes:
  - Frequency Scanning Interferometry (FSI) based future LHC solution
  - "Brandeis" Camera Angle Monitoring (BCAM) only for SPS test
- Both systems provide non contact measurements
- FSI system selected as baseline solution for future HL-LHC use
  - Monitor of the SPS prototype through different phases (vacuum, cold, etc.) will allow for final decision on extrapolation of monitoring solution to HL-LHC crabcavity cryomodules



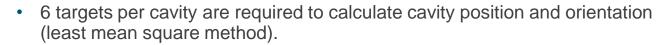
# Position monitoring systems - FSI



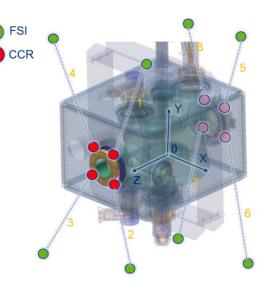


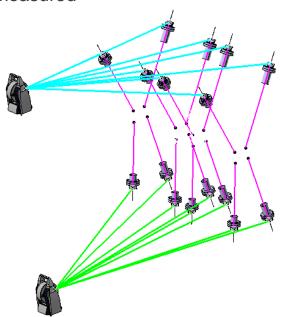
# Position monitoring systems - FSI

#### Frequency Scanning Interferometry (FSI)



- Cavity fiducialisation data and measured distances between FSI heads and centres of CCR targets used
- Current design assumes 4 targets per flange (8 Corner Cube Retroreflectors [CCR] per cavity) to provide minimum measurements redundancy
- Positions of the FSI heads to be measured

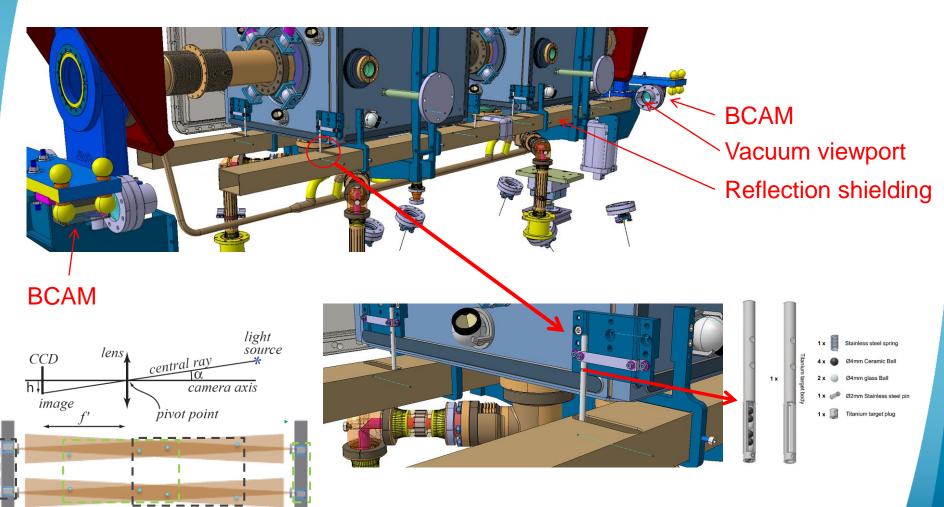




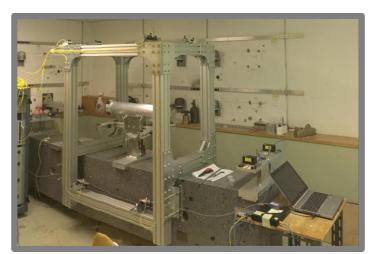


# Position monitoring systems - BCAM

**BCAM** solution – cryo-module implementation (DQW)



# Position monitoring systems - solution validation



Test setup



Strategy verified in geodesy base on the 1:1 alignment monitoring system mock-up

- Tests at room temperature (~20°C)
- Atmospheric pressure, stable bench frame shape
- Accuracy of both systems better than 50μm (1σ)



Helium tank mock up (CMM measurement : micrometric uncertainty)

Parameters FSI	Accuracy
Tx : radial (mm)	0.021
Ty: vertical (mm)	0.009
Tz : longitudinal (mm)	0.028
Rx : pitch (mrad)	0.030
Ry : yaw (mrad)	0.072
Rz : roll (mrad)	0.187

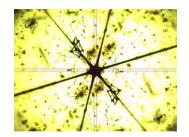


# Position monitoring systems - components validation









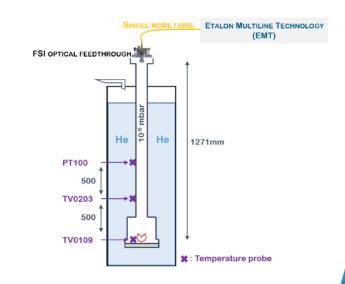
Radiation tests of BMRs and optical components finished in December 2016

- Ceramic BMRs and collimators validated with TID of 10MGy
- BMR mirror centricity lost ~20µm

Irradiated and new reflectors tested under cryogenic conditions in CERN Cryo-Lab

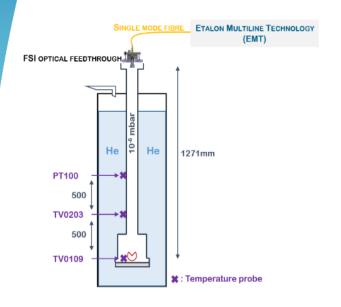
- Liquid nitrogen test
- Test of whole measurement setup under operation conditions – helium cooling setup
- No damage of targets or FSI reading performance lost observed







# Position monitoring systems - components validation









Test of FSI measurement chain in operation conditions

- BMR + flange support cooled down to 4K, setup under vacuum
- FSI head prototype at room temperature
- 3 cooling-warming cycles per target. The FSI measurement crosschecked with AT401 measurements between the cycles
  - No visible deformation of FSI head under vacuum, measurements stable in time
  - AT401 measurements between cooling cycles confirmed FSI reading within 20µm accuracy
  - Intensity of BMR reflected signal lower when reflector cooled, but no impact on measurements

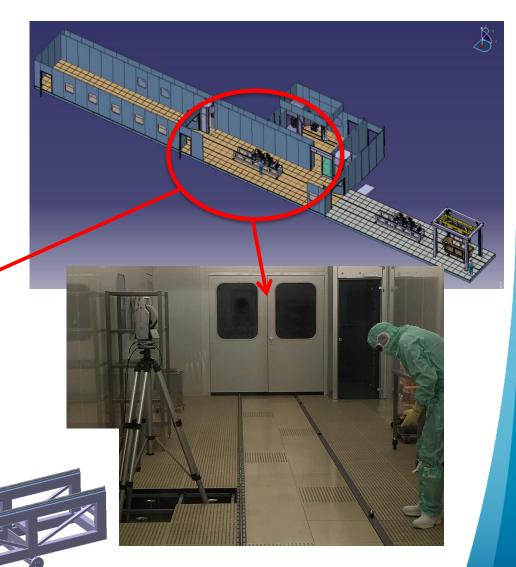


# Position monitoring systems – cavities string assembly

- Validation of survey equipment use in ISO5 clean room
  - Laser tracker stability and placement
  - Verification of available space and optimal measurements position
  - CC alignment chariot tests next week









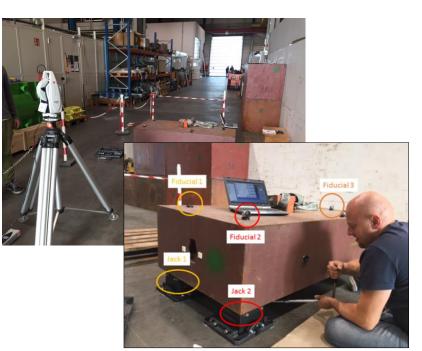
# Position monitoring systems – SPS test

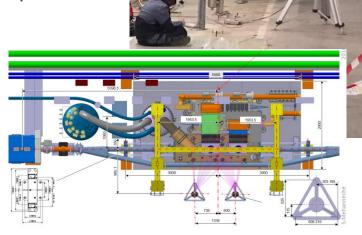
 SPS-LSS6 crab-cavity cryomodule installation zone equipped with network of fiducials and re-measured

Coordinates of all important (requested) components marked

 Special supports for laser tracker pillars installed in transport zone

Cables installation pending





Cryomodule supporting jacks tested with the 3. 7T nominal load

- OK for the manual pre-adjustment of cryomodule
- Adjustment resolution at the level ~10um
- The jack adjustment precision at the level ~50um (fixing of blocking screws)



# **Crab cavities position monitoring systems – status**

- BCAM and FSI strategy for crab-cavity position monitoring validated in laboratory conditions. Waiting for SM18 test to confirm real system accuracy under cold
- FSI head prototypes and reflectors validated under nominal cavity operation conditions without performance lost
- Alignment steps / acceptance criteria (+ methods and tools) in the assembly process have been defined
- Components for BCAM and FSI system (especially series of 18 FSI heads) received and under validation
- Preparations of string assembly and cryomodule assembly ongoing
  - Tests of alignment activities with ,string-chariot' and cavity mock-up out of clean room to elaborate best practices in ISO5

#### **Further works**

- Measurements in SM18 validation of the final system
- Finalize SPS test preparation
  - Validation of SPS movable table at supplier premises
  - Implementation of movable table stability monitoring
  - SPS test stand components alignment
  - Monitoring system software integration



# Inner triplet cold mass monitoring system

- Introduction to triplet cold mass position monitoring
- FSI integration layout
- Dipole test preparation
- Cold mass monitoring system status

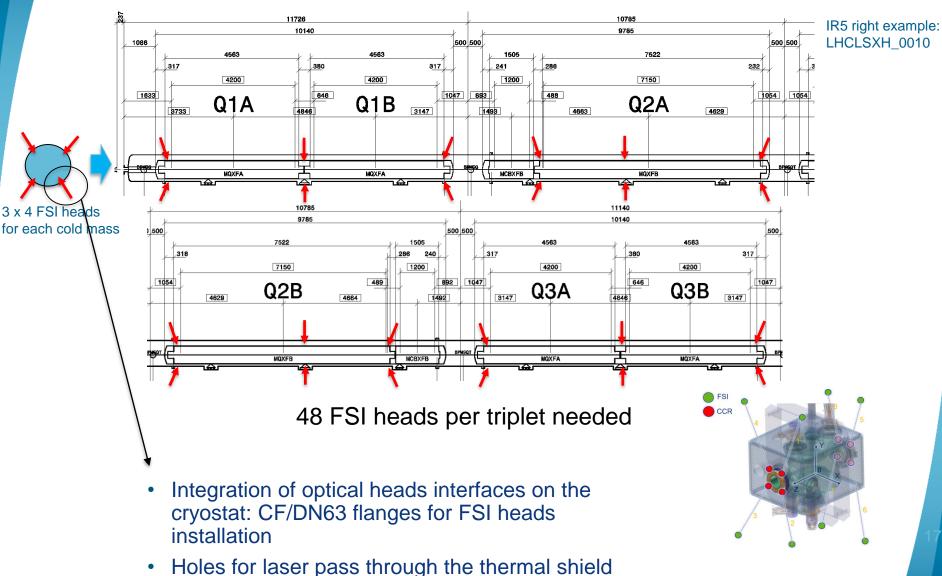


### Introduction

- Reason to monitor triplets cold masses position
  - Unknown position of cold mass w.r.t. warm, fiducialised cryostat
  - Impact of very small triplets moves for beam orbit
  - Variable conditions of cryogenic, vacuum system impact on cold mass position



# Inner triplet – proposed FSI integration layout

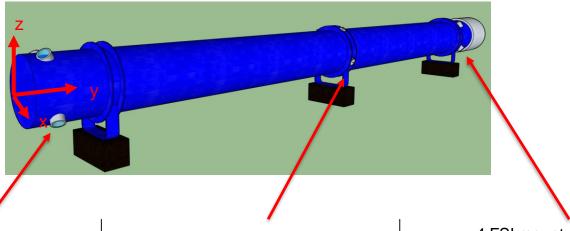


Include the case of contraction of cold masses

# **Dipole test**

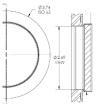
#### Dipole test objective:

- Check real performance of cold mass monitoring system with triplet similar object (dipole 4001)
- Verify stability of 3 foot support of cold mass (planned for future triplet design)
- Verify real impact of cryogenic and vacuum on cold mass position



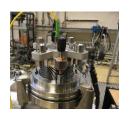
- 4 FSI mount + collimator
- + 4 Viewport ISOK DN63
- + 4 PLX NMBR 1.5" targets







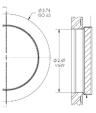
4 Feedthrough + 4 CCR targets





- 4 FSI mount + collimator
- + 4 Viewport ISOK DN63
- + 4 Low-cost Alu reflector

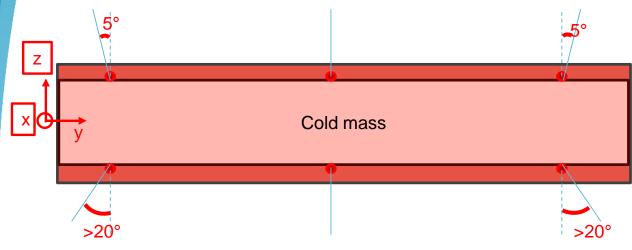








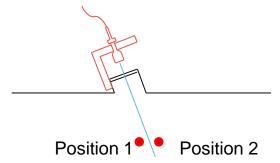
# Dipole test - FSI instrumentation layout



Inclination of FSI mounts at the cryomodule extremity will provide information about longitudinal variation of cold mass position

Cold mass thermal contraction at FSI extremity locations :

- FSI viewport flange tube positioned in the middle between room temp (Position 1) and cold (Position 2) of reflecting target
- tilt-tip adjustment system will provide collimator position variation in case of measurement before cooling down and after cooling down



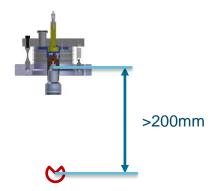


# Mechanical integration of FSI instrumentation

#### FSI head (feedtrough):

- ISOK DN63 flange needed
- Minimum distance between collimator ferrule tip and target centre: 200mm

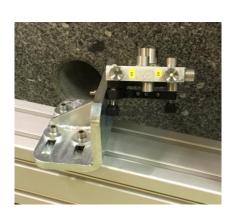




#### FSI collimator tip-tilt adjusters:

 Fixation to the flange-tube (or vacuum vessel) by special clamp







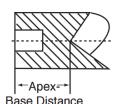
# Mechanical integration of FSI instrumentation

#### Reflector assembly on the cold mass;

- Spherical reflector needs a conical prism
- To avoid components contraction effects (damage of prism, sustain repeatability) – prism should be pre-stressed with springs
- Conical cup might be re-designed to be welded to cold mass surface
- Low-cost Alu reflector mounted using threaded hole (intermediate plate to be welded needed



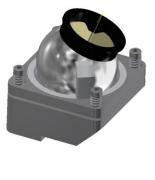


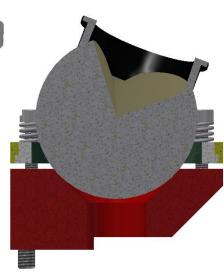














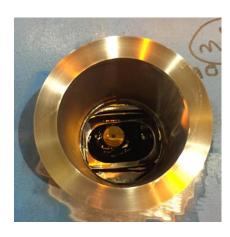


# **Current status of preparations**

- 4 FSI heads & 8 External collimator structures ready to test with dipole
- All targets installed on the dipole cold mass
- Dipole cold mass cryostated and ready for fiducialisation in SM18
- First cool down mid July-Mid August
- More robust optics, 20-30mm transversal range optics under development



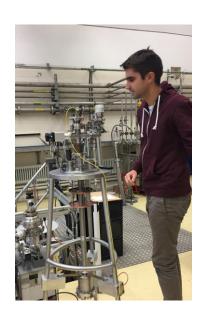








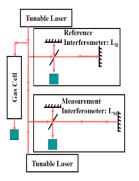
# Thank you for your attention



# **Lessons learnt**

- Experience in precision measurements of cold objects
- Know-how about behaviour of precise survey equipment under cryogenic and radiation

- Design of µm-precision measurement equipment for vacuum and radiation
- FSI became a reliable and economic solution for high precision measurements in harsh accelerator environment
  - Interest of developments carried out by ITER, ESO,
  - Industrila manufacturing of FSI heads
     requested by commercial partners





FSI central unit housing the reference interferometer

