

# Searching for new physics at ATLAS

## Rough guide to data analysis

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UNIVERSITÉ  
DE GENÈVE

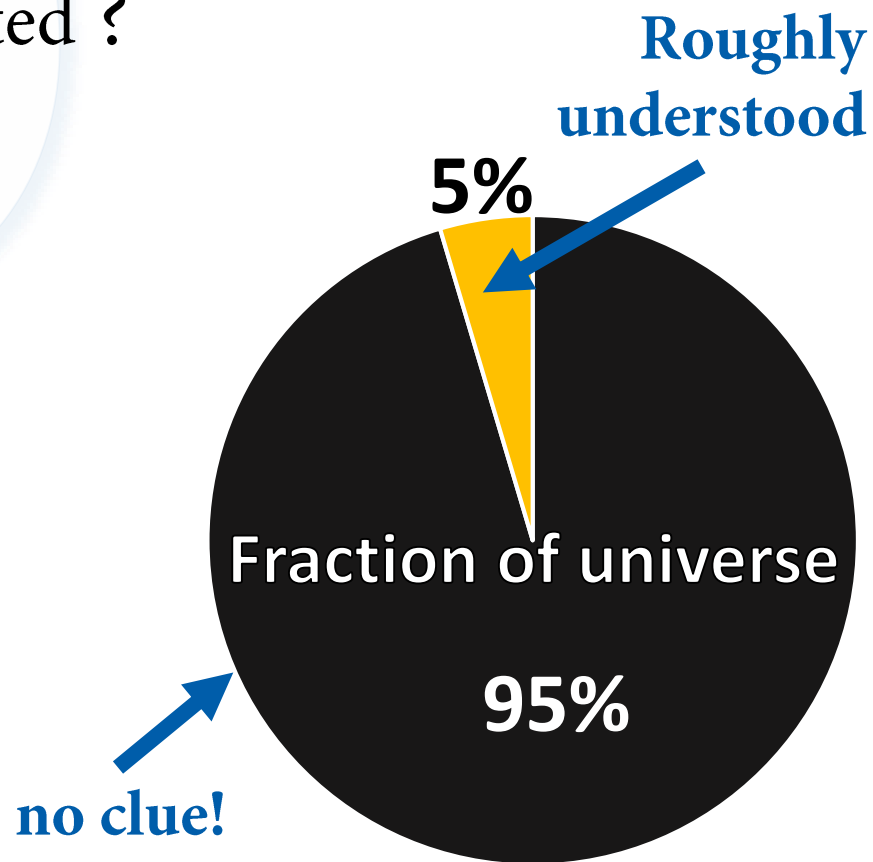


**ATLAS**  
EXPERIMENT

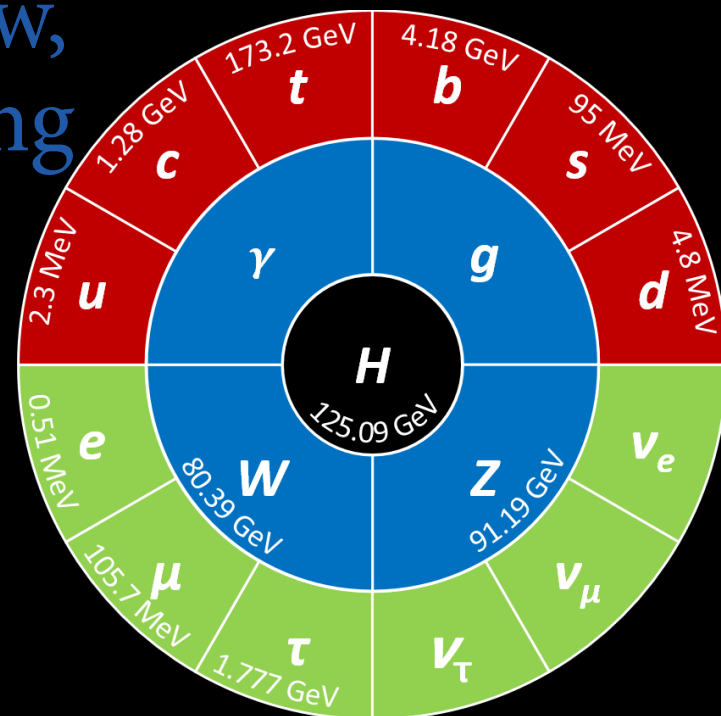
- **LHC and ATLAS detector**
- **Physics objects**
- **Analysis – Boosted diboson search**
- ~~**Summary Discussion**~~

- Ever wondered ..
  - .. what am I and everything around me made of ?
  - .. how was our universe created ?
  - .. and what is it made of ?

- We do!  
This is why we do particle physics.



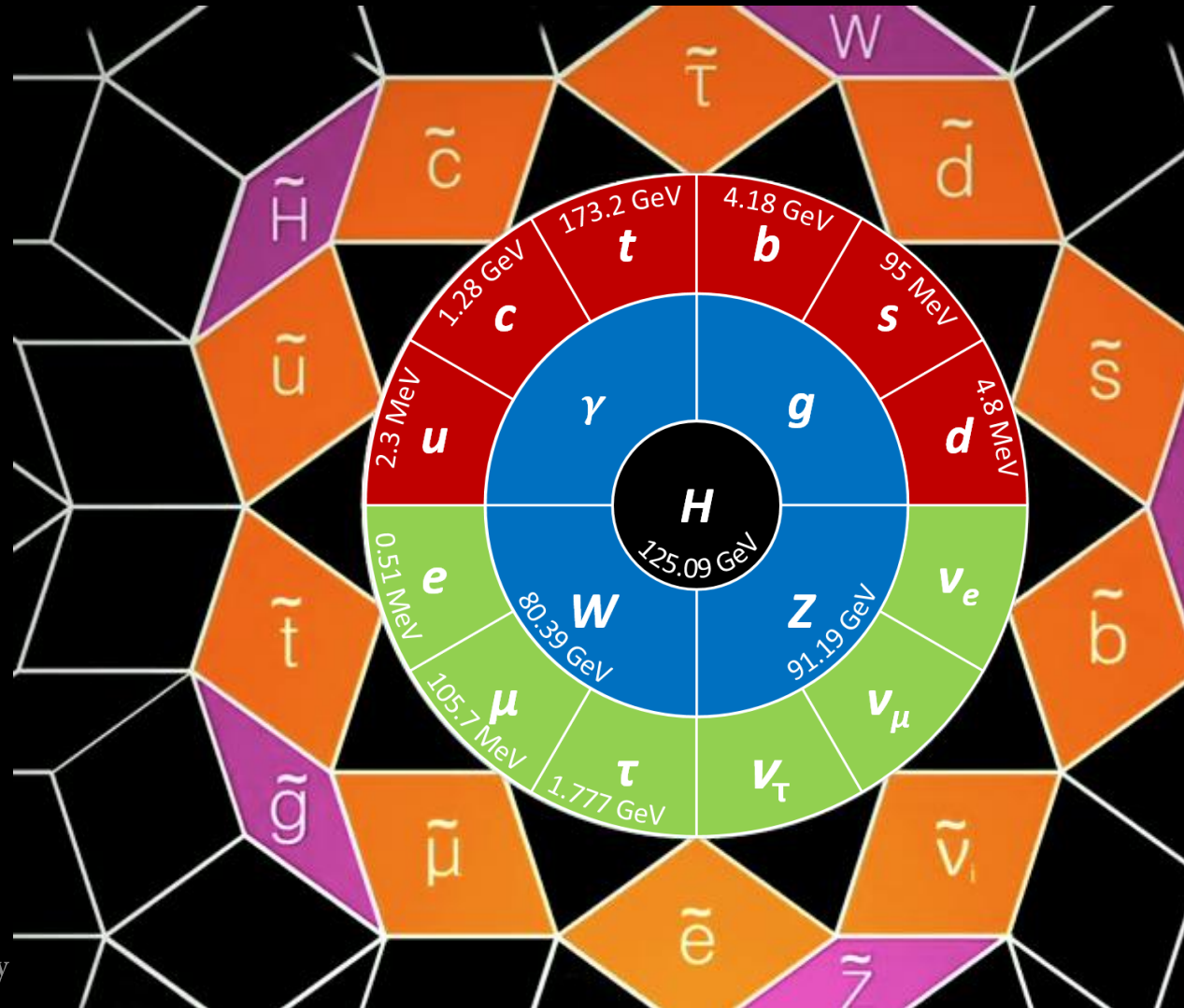
- What particles?
- These particles we know, and they are the building block of the 5%



# Particle physics – Why do we care?

- What else could there be?

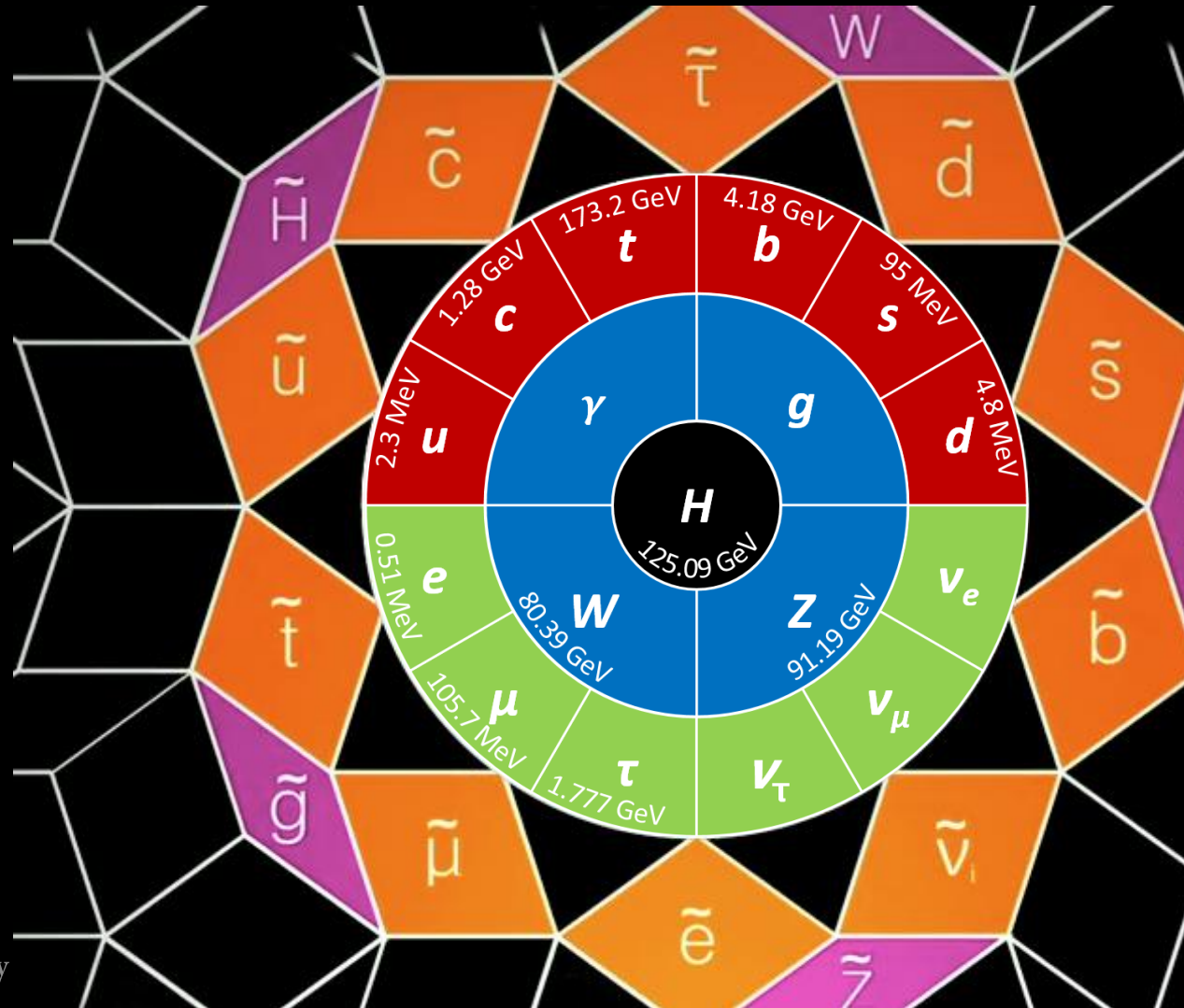
- Are these the 95% ?



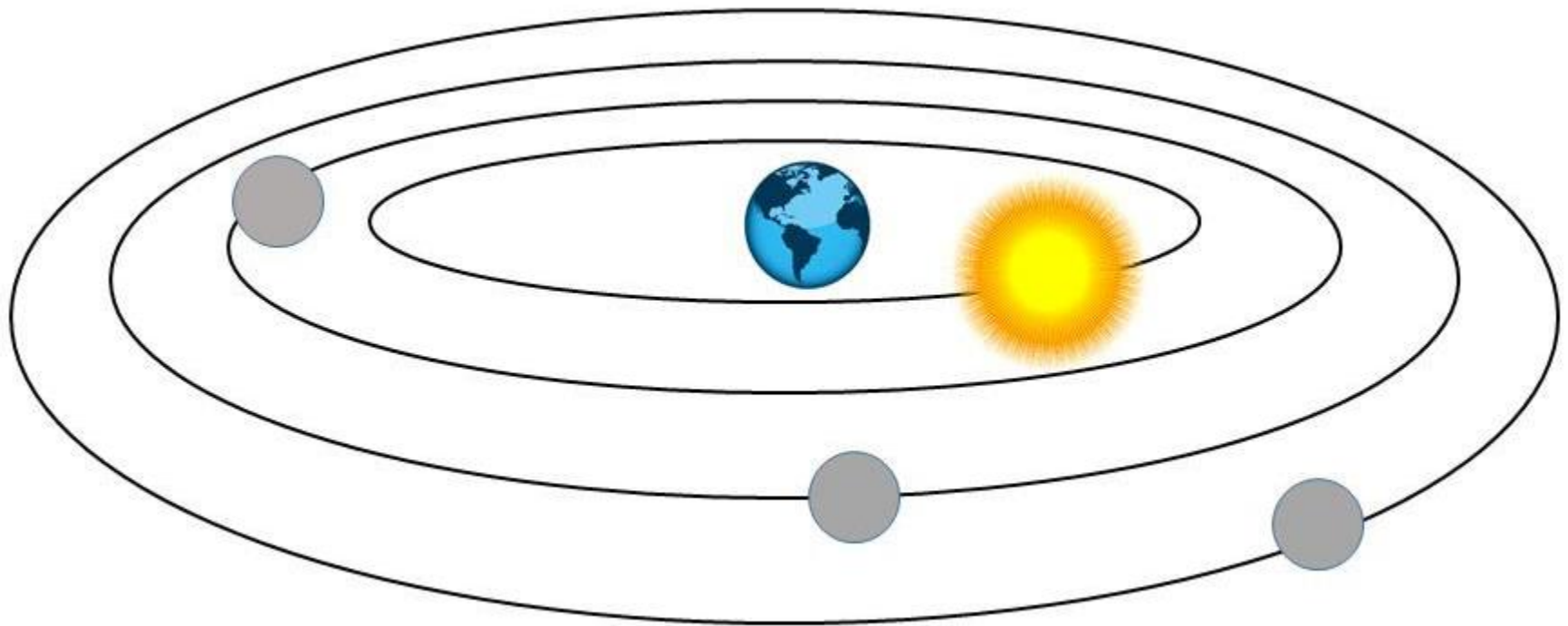
# Particle physics – Why do we care?

- What else could there be?

- Are these the 95% ?



- Sun goes around earth, earth around sun...  
sounds all the same to me.



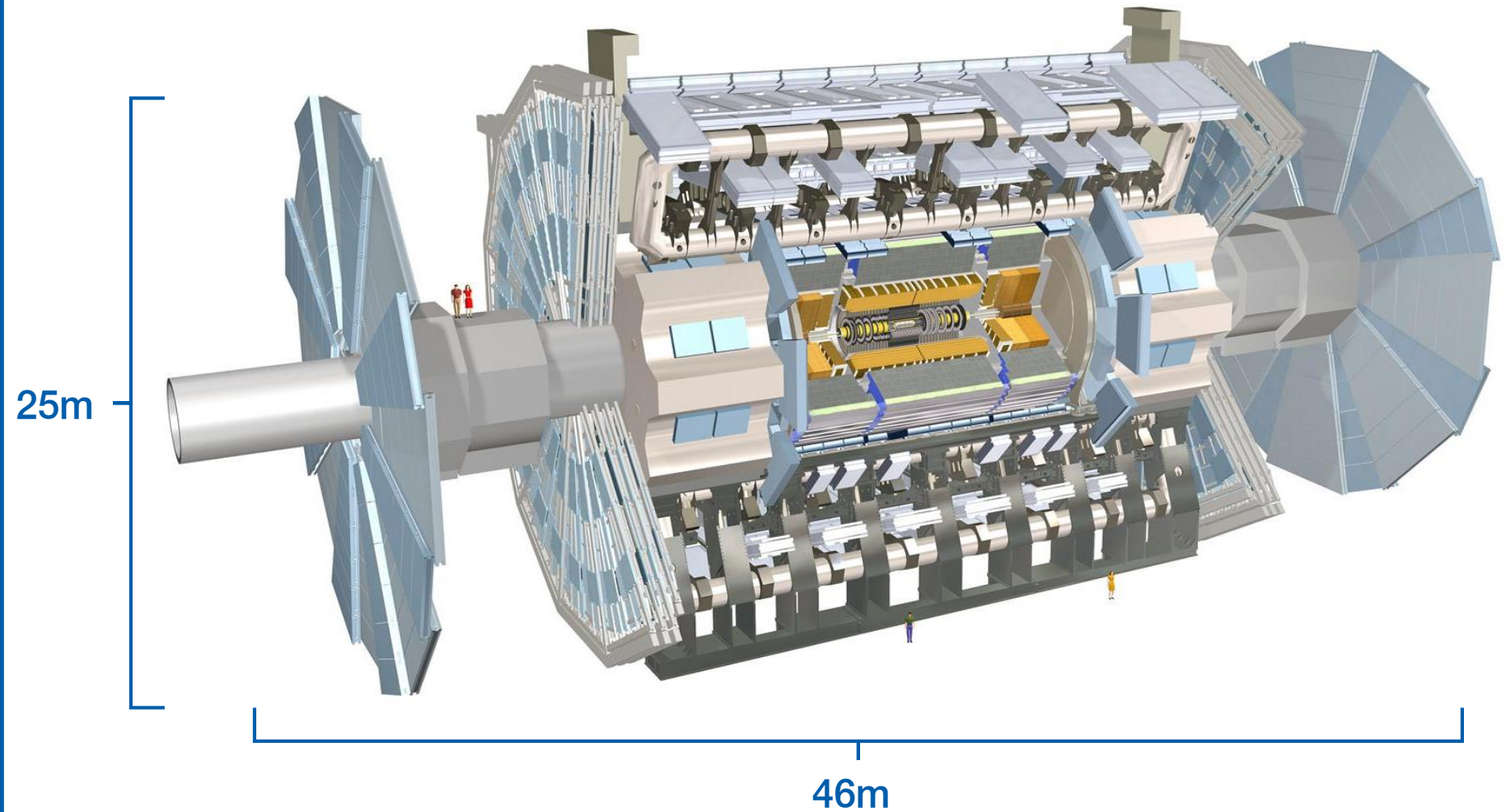


# Large Hadron Collider





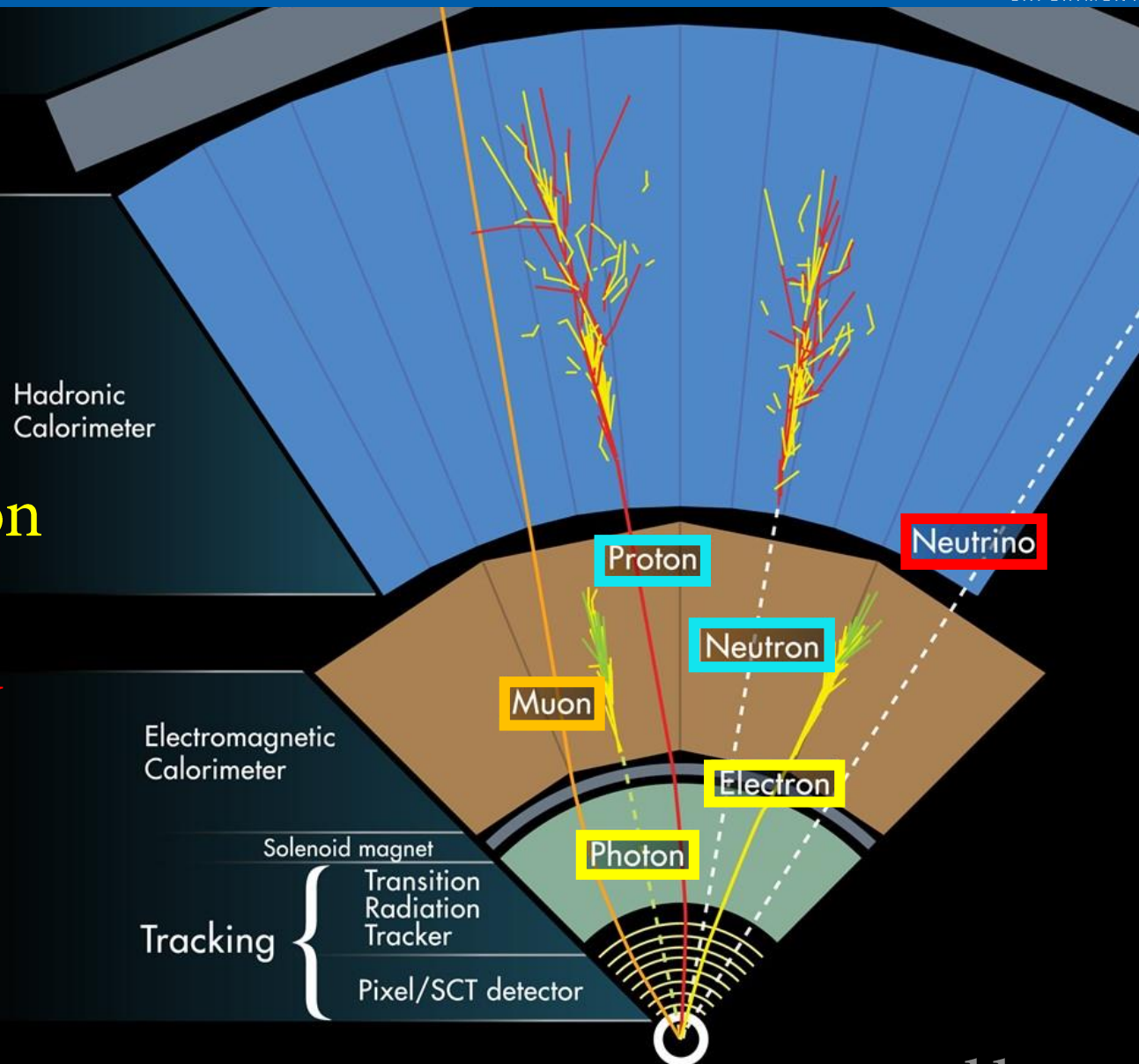
# ATLAS Detector



# Physics Objects

Physic objects:

- Muon
- Electron/Photon
- Hadronic jet
- Missing energy



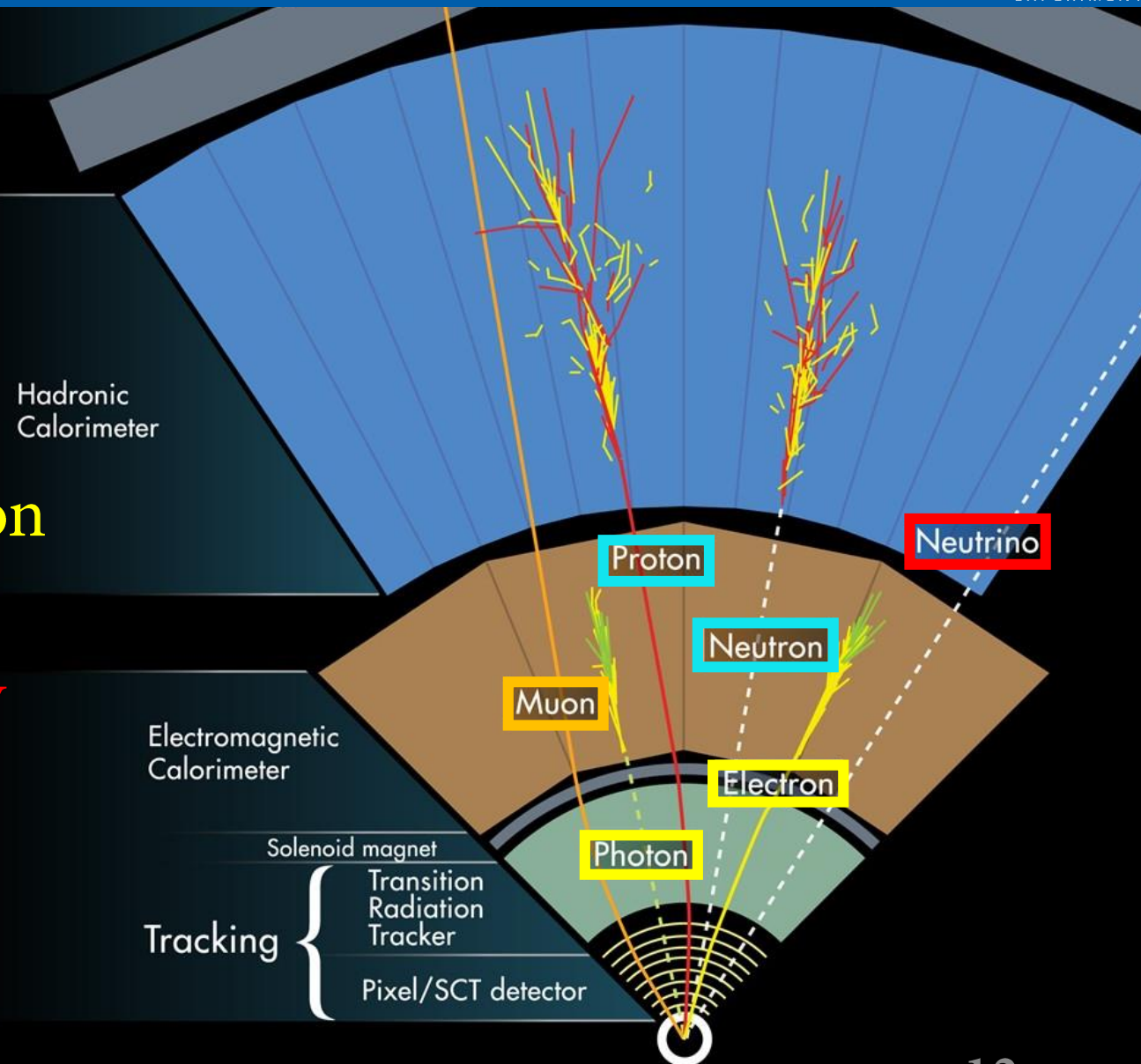
# ATLAS Detector & Objects

Physic objects:

- Muon
- Electron/Photon
- Hadronic jet
- Missing energy

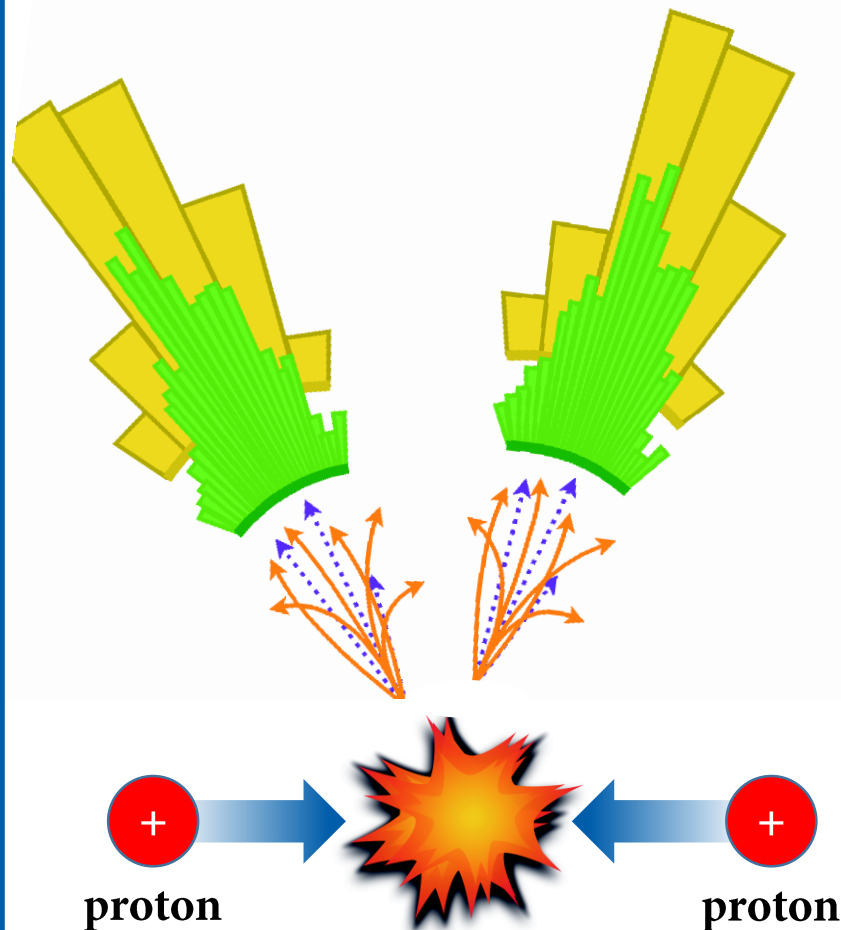
Build from:

- Jets
- Tracks





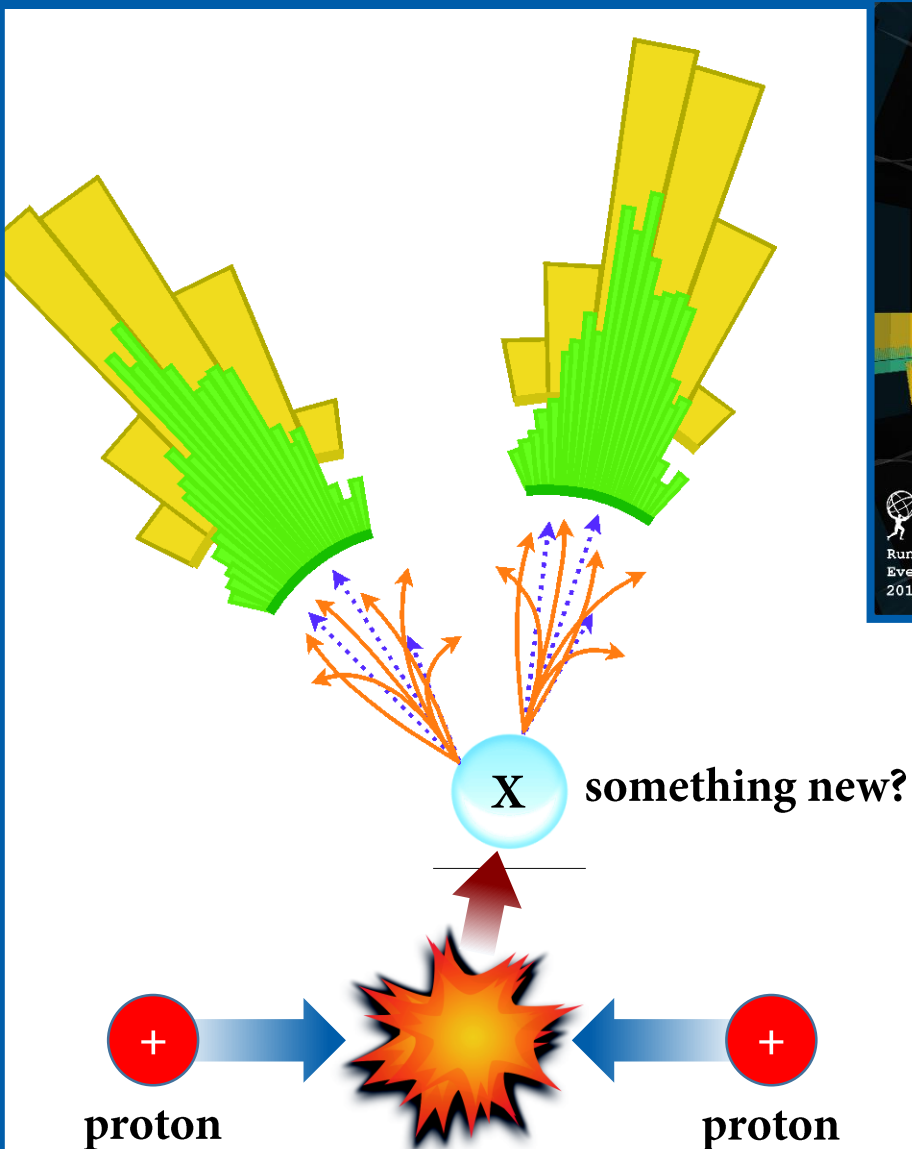
# Energy Frontier: Jets



$m=8.1$  TeV dijet event  
 $\text{jet}_{1/2} p_T=3.79$  TeV

- Newly opened energy regime:  $\sqrt{s} = 13$  TeV.

# Energy Frontier: Jets

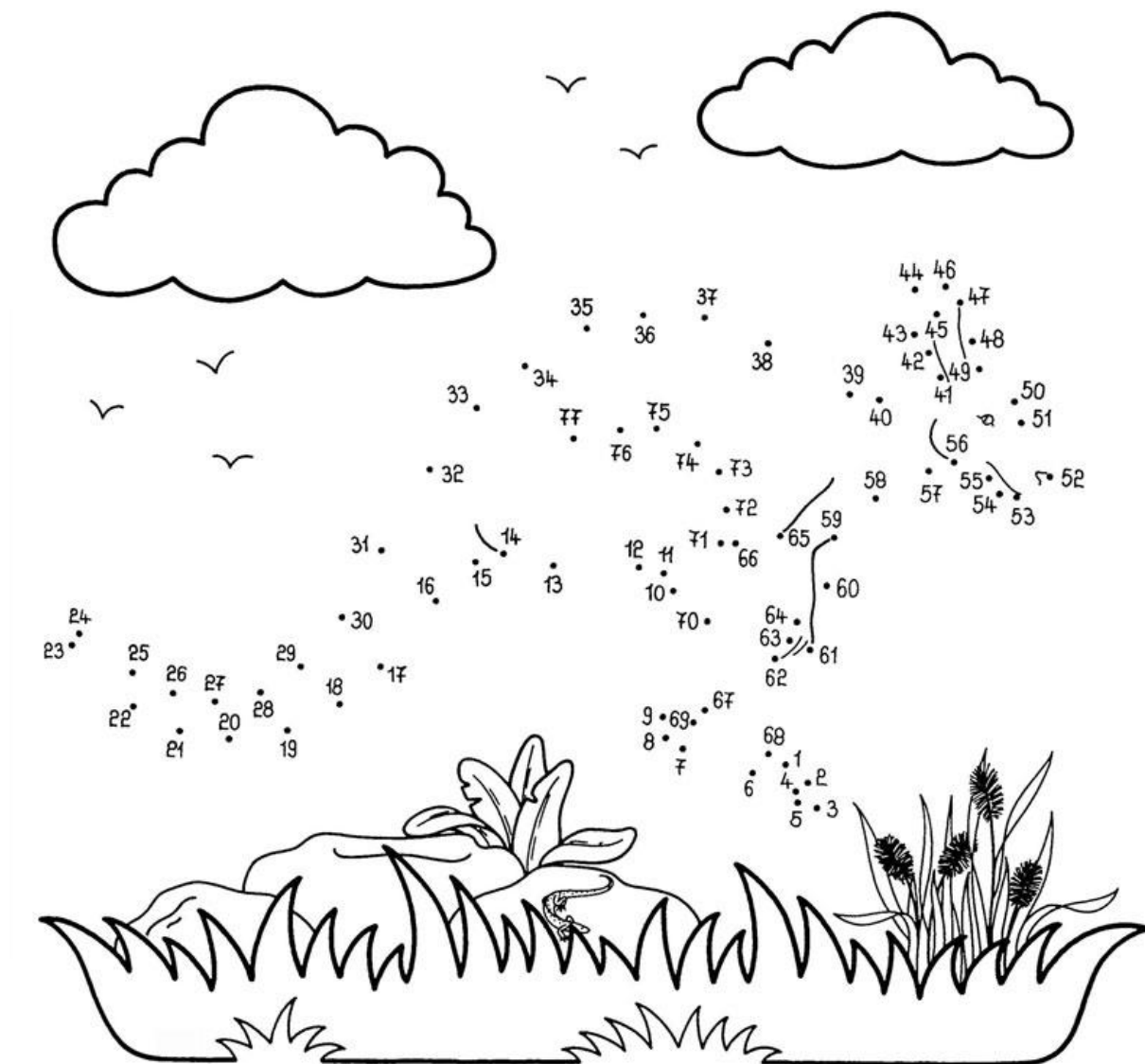


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# Track reconstruction - Concept

- Nowadays finding particle tracks is like this ..



# Track reconstruction - Concept

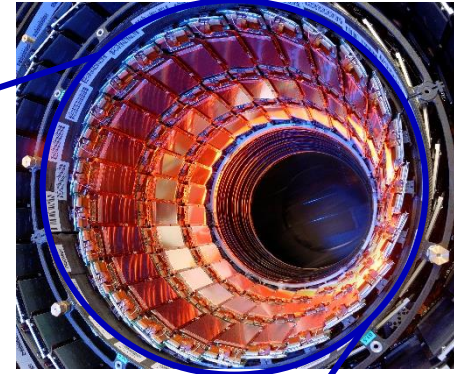
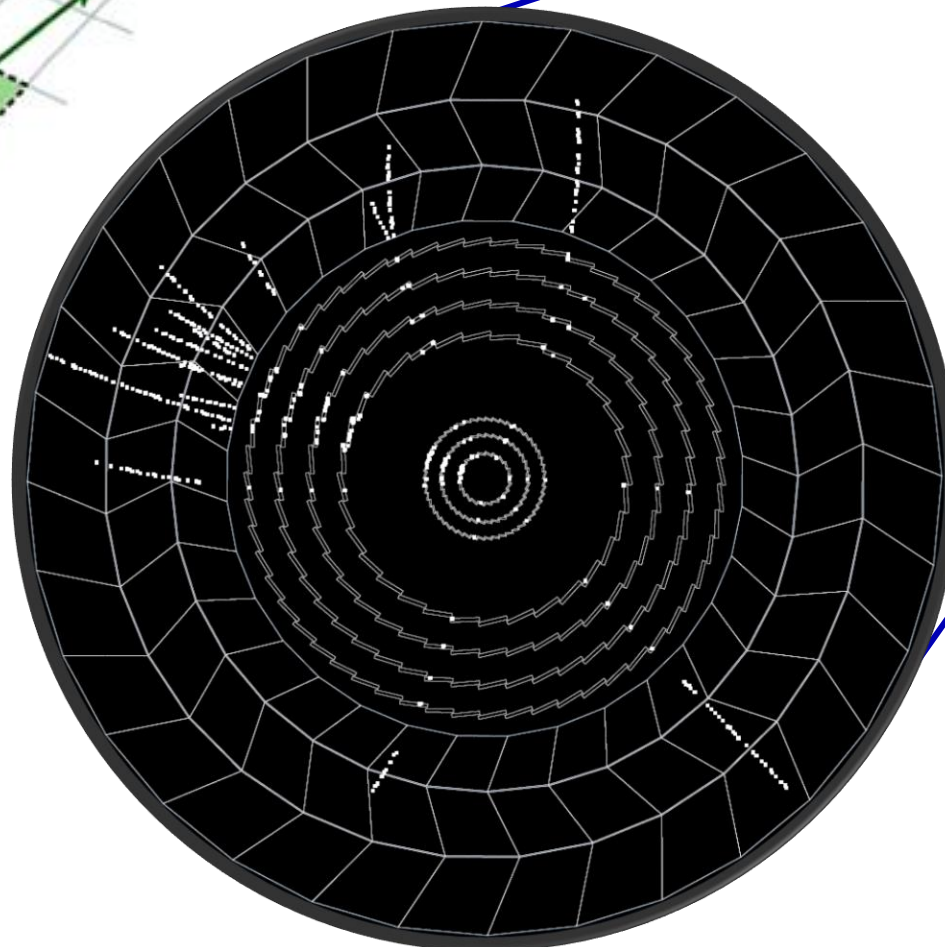
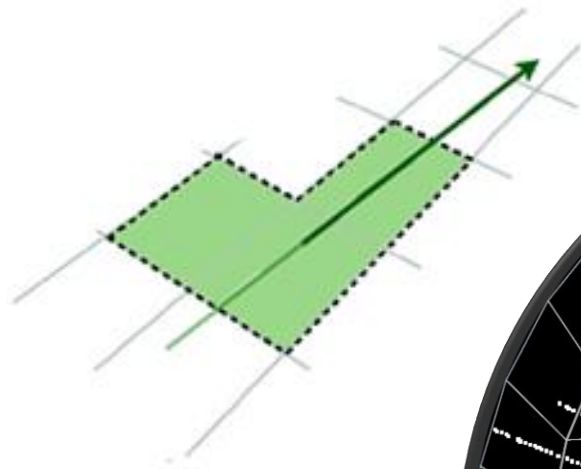
- Nowadays finding particle tracks is like this ..
- But without the numbers!





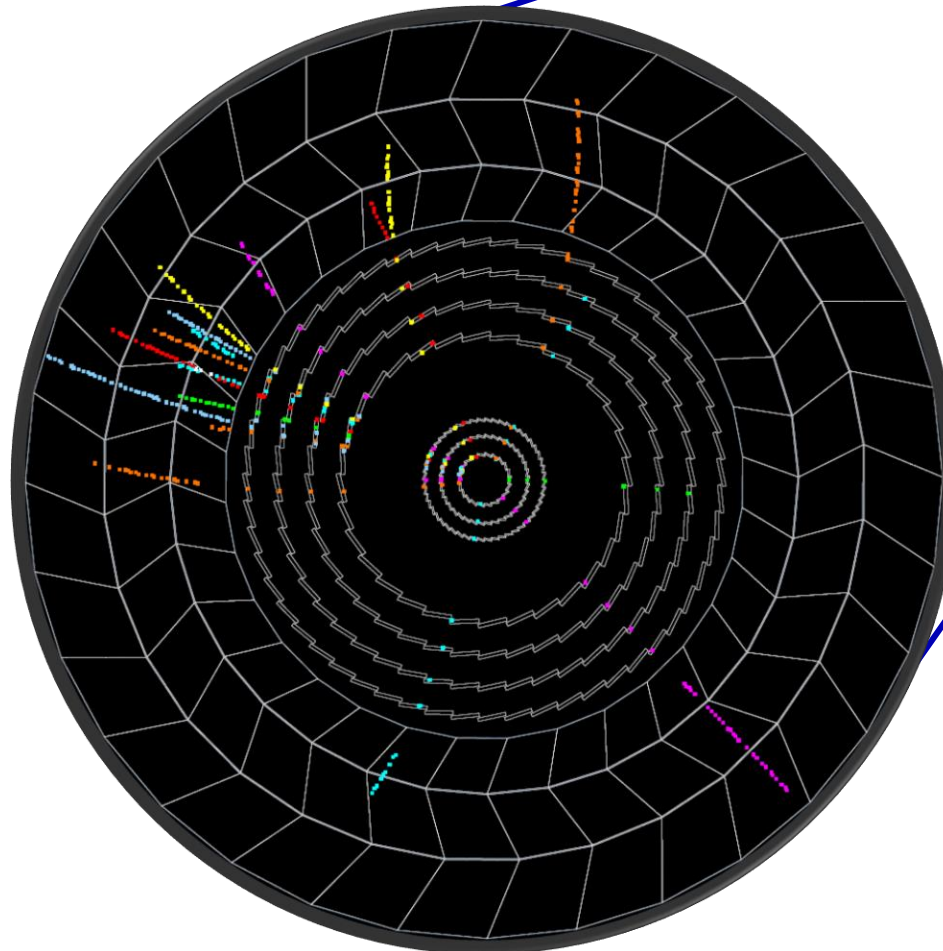
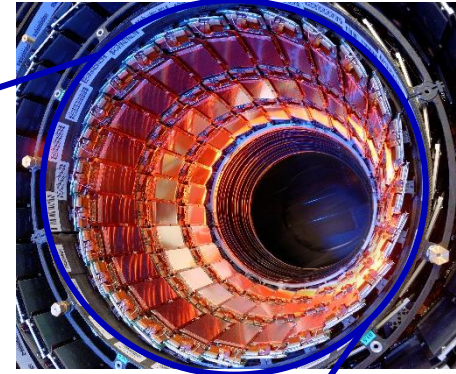
# Track reconstruction – Step by step

## 1. Register measurements (called **clusters**).



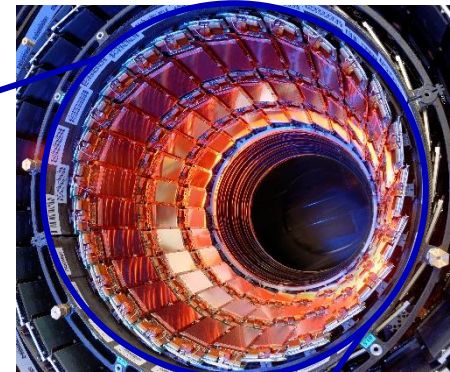
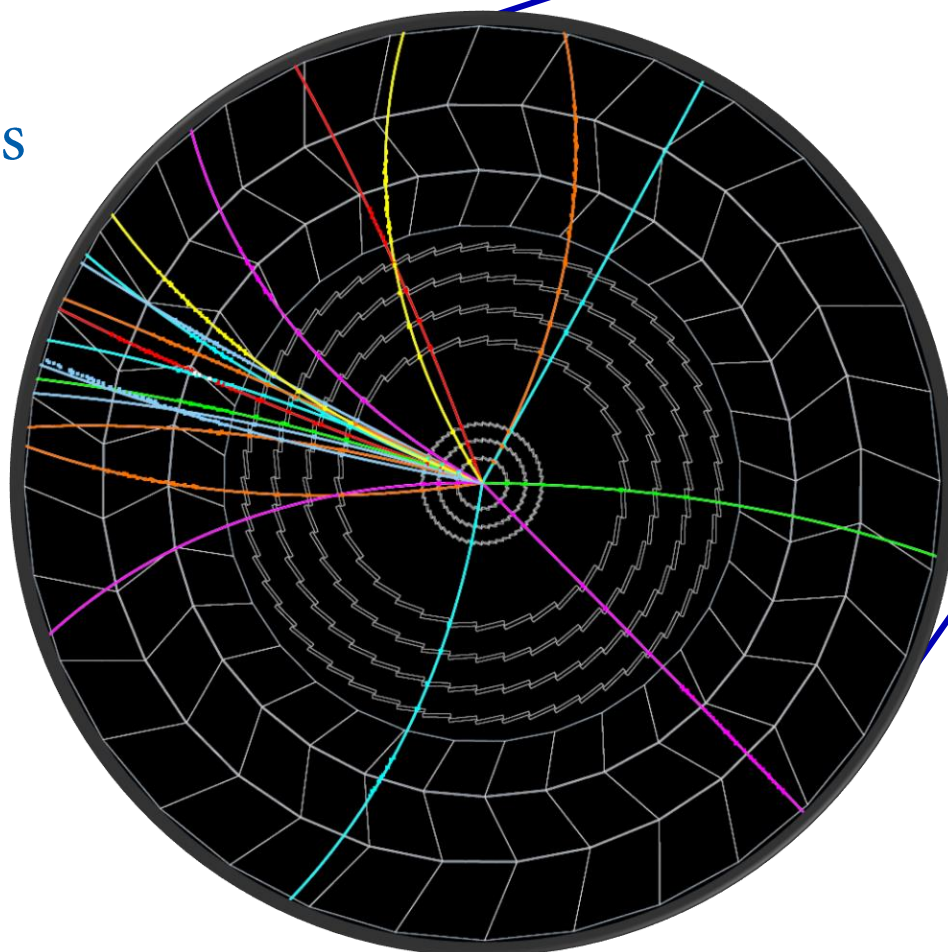
# Track reconstruction – Step by step

1. Register measurements (called **clusters**).
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# Track reconstruction – Step by step

1. Register measurements (called **clusters**).
2. Associate clusters to particles' tracks.
3. Fit particles trajectory.

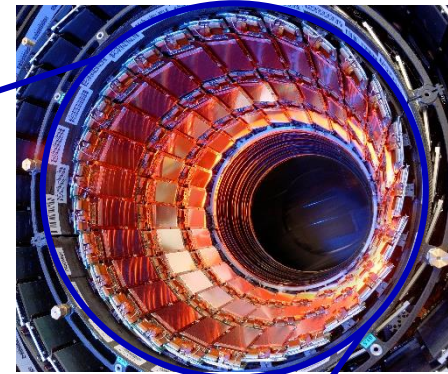
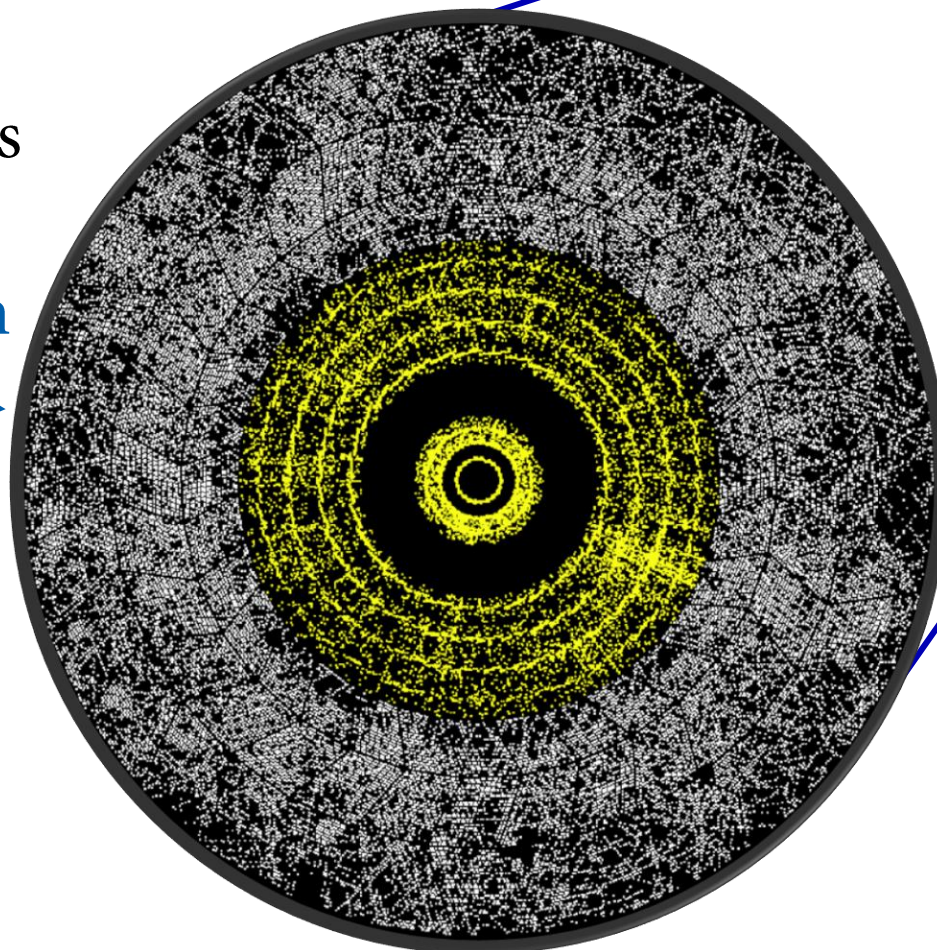




# Track reconstruction – Step by step

1. Create measurements (called clusters).
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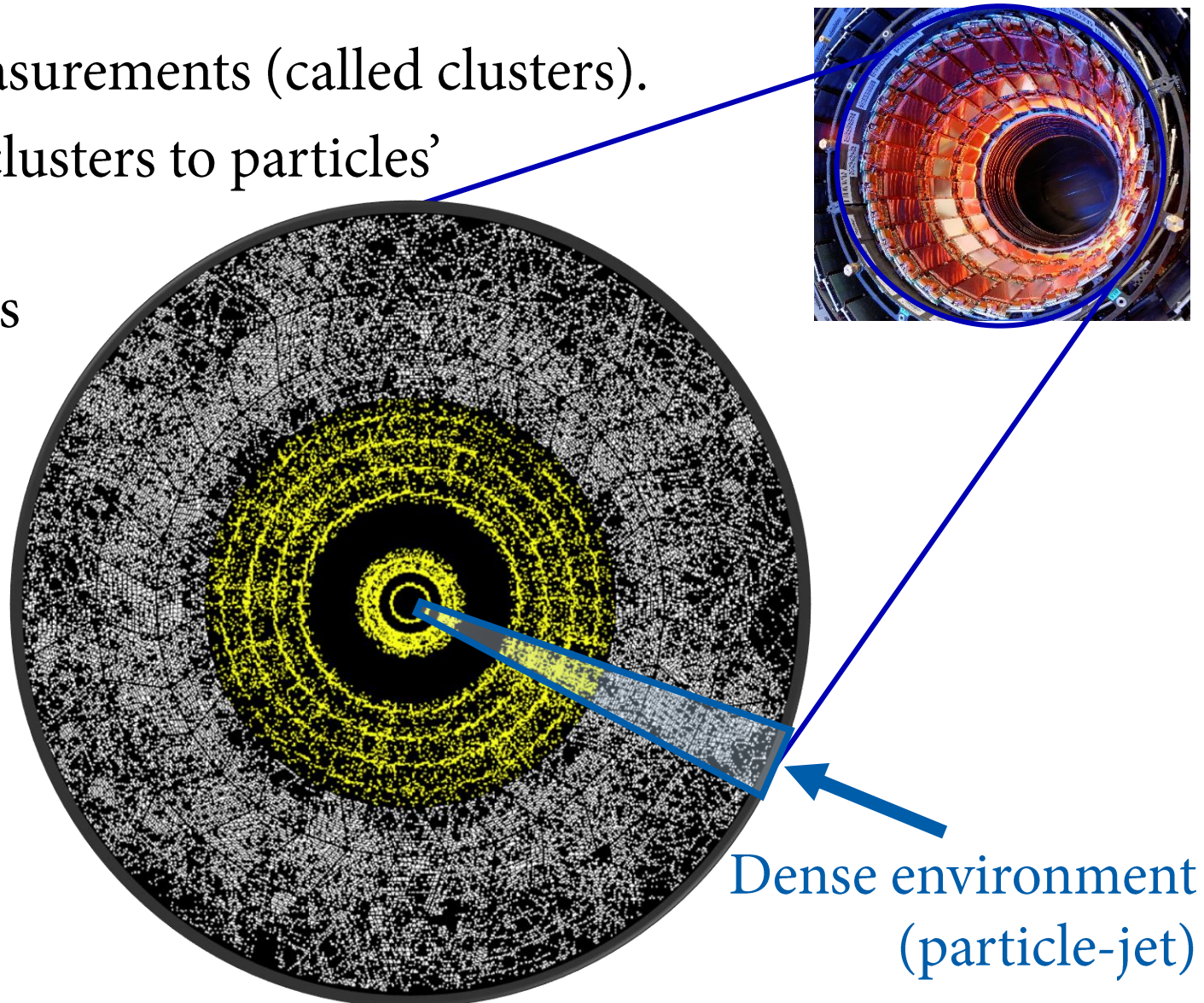
How it looks in reality →





# Track reconstruction – Step by step

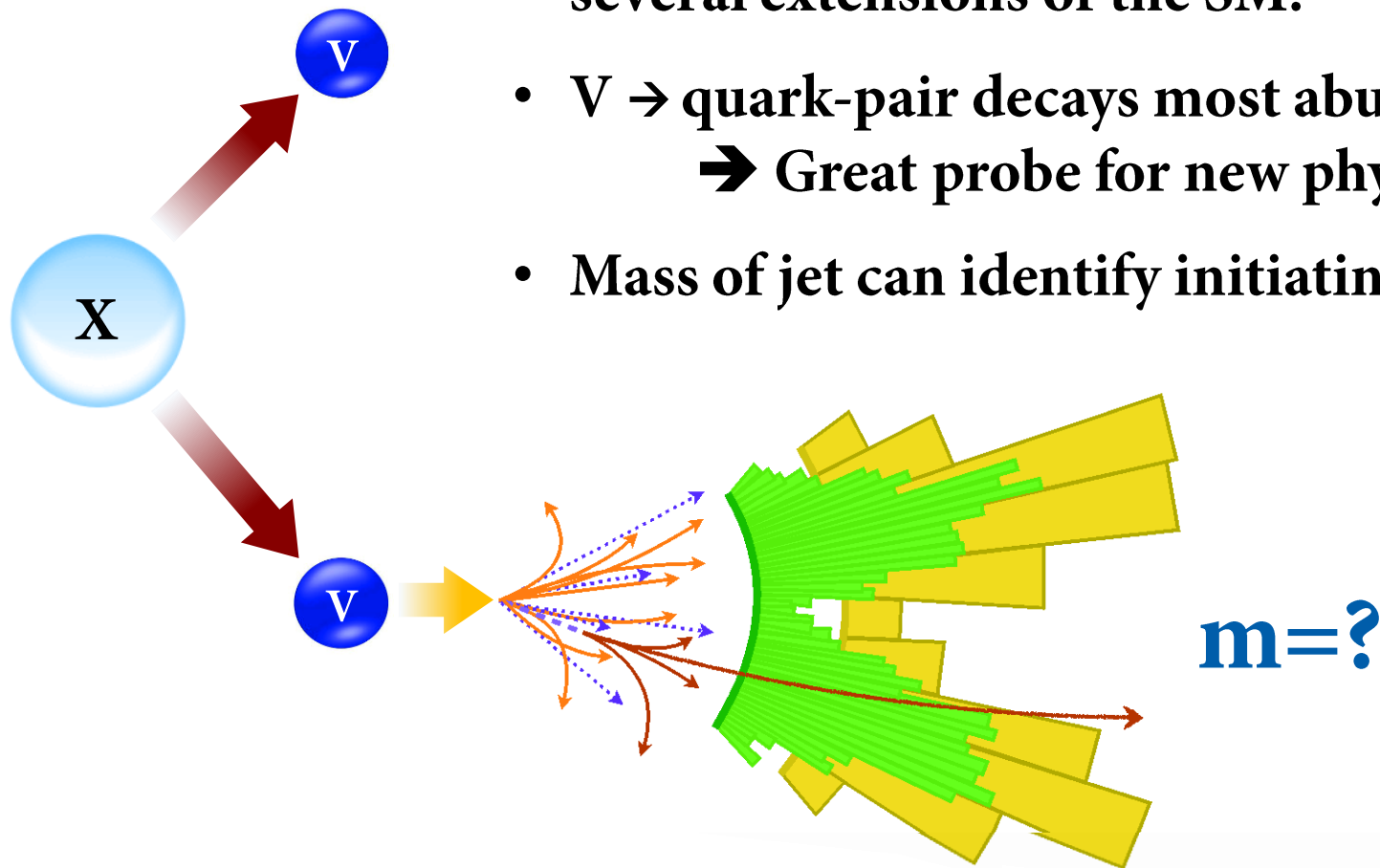
1. Create measurements (called clusters).
2. Associate clusters to particles' tracks.
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# Example Analysis

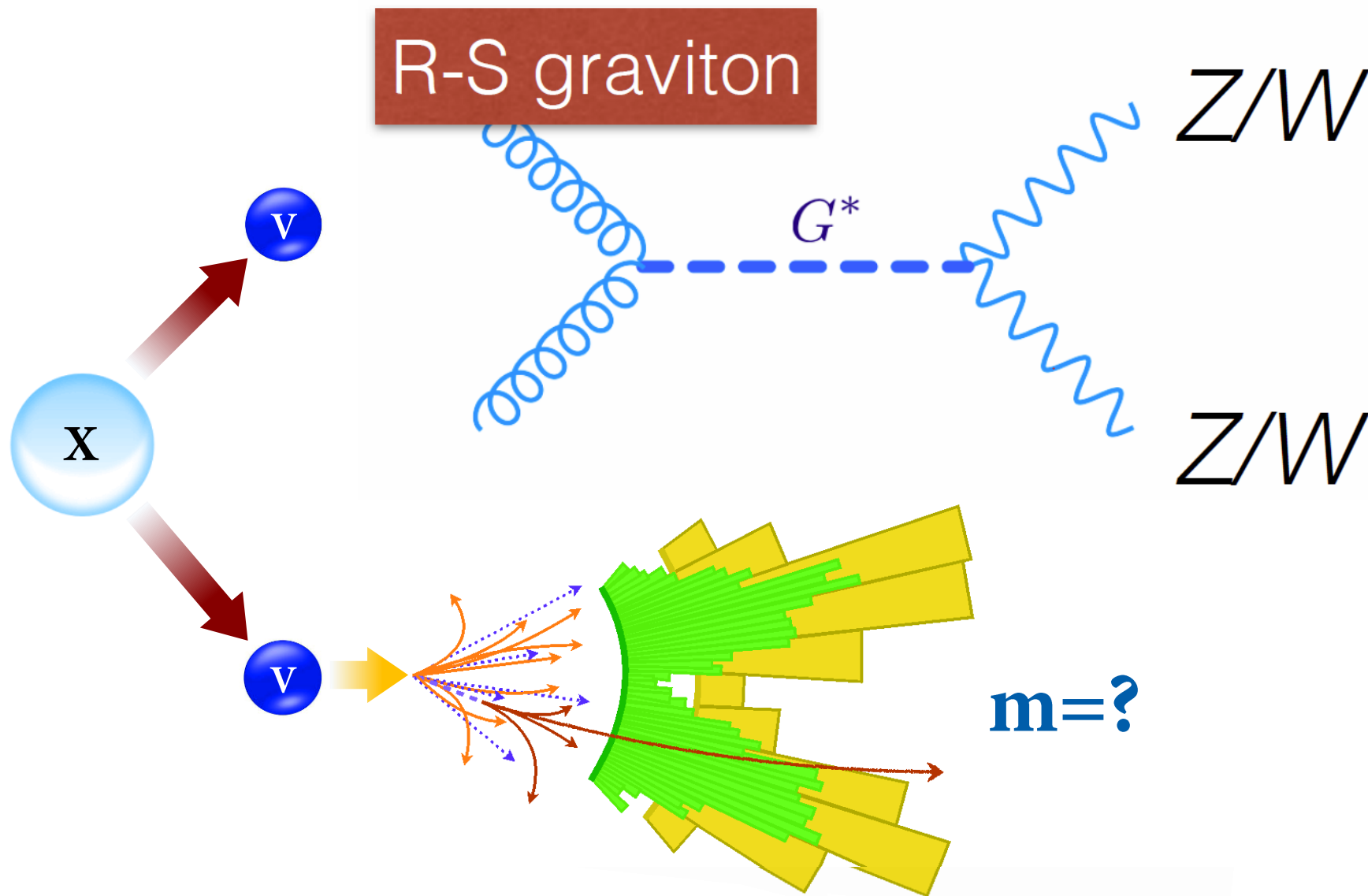
1. Collect data : Detector, trigger, DAQ
2. Reconstruction of physics objects
3. Simulation : Generate events, detector simulation

- Heavy ( $>1$  TeV) **resonances to pairs of vector bosons** ( $V=W/Z$ ) predicted by several extensions of the SM.
- $V \rightarrow$  quark-pair decays most abundant.  
     **$\rightarrow$  Great probe for new physics!**
- Mass of jet can identify initiating particle.



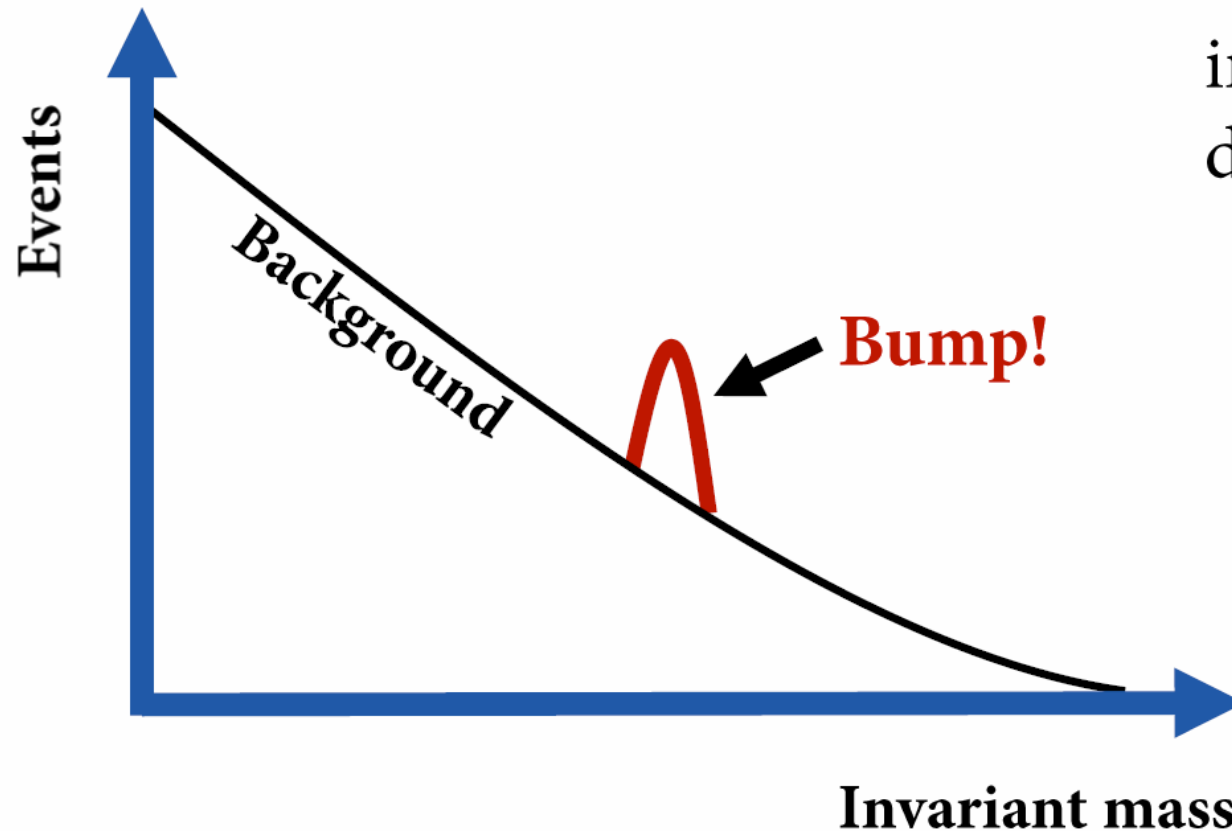


# Boosted diboson search strategy



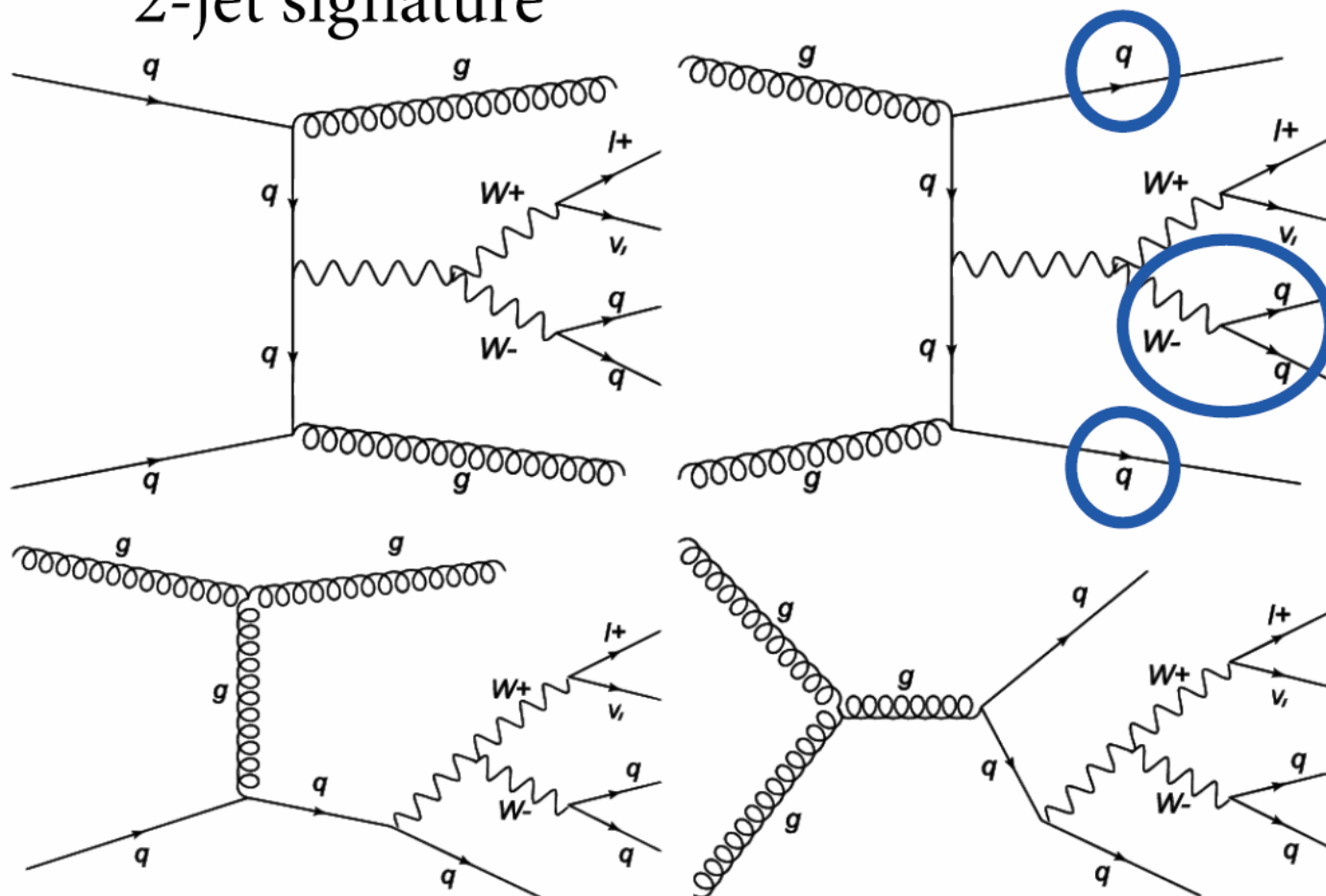
# Boosted diboson search strategy

- Look for bump in steeply falling invariant mass distribution.



## Main background:

- Standard model processes that can give the same 2-jet signature



“Distinguishing the signal from the noise requires both scientific knowledge and self-knowledge: the serenity to accept the things we cannot predict, the courage to predict the things we can, and the wisdom to know the difference.”

– Nate Silver, *The Signal and the Noise: Why So Many Predictions Fail - But Some Don't*



- Cross section  $\sigma = \frac{N}{\mathcal{L}} \rightarrow \sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$

$N_{obs}$  = Observed number of events

$N_{bkg}$  = Estimated number of background

$\mathcal{L}$  = Integrated luminosity

$\epsilon$  = efficiency

$A$  = acceptance

$\mathcal{B}$  = Branching ratio

# How to measure a cross-section

- Cross section 
$$\sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

N(obs) Direct from data

N(bkg) (from data and MC, most critical part of analysis)

L (Someone else calculates this!)

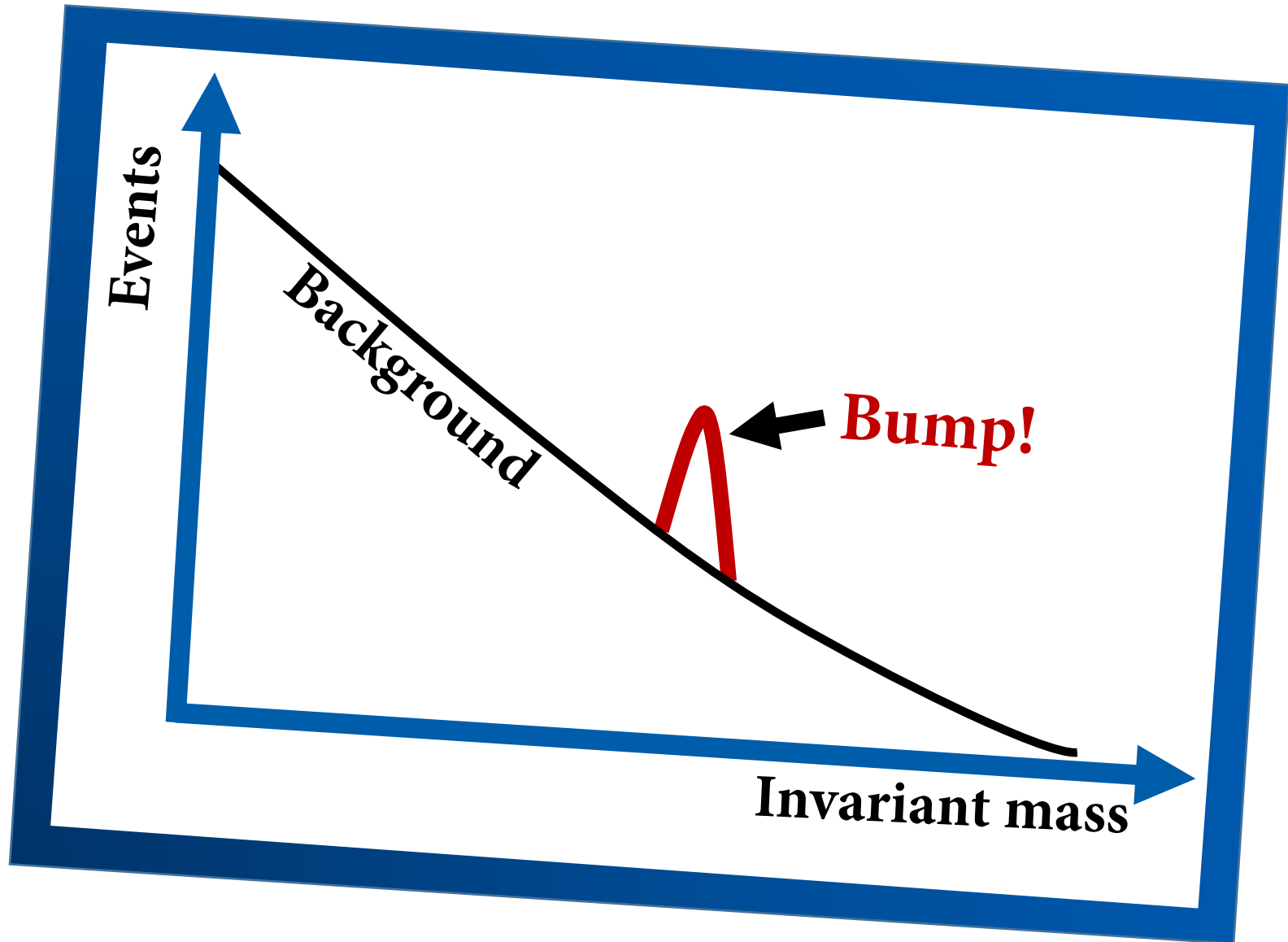
$\epsilon$  = efficiency (from Monte Carlo)

A = acceptance (from Monte Carlo)

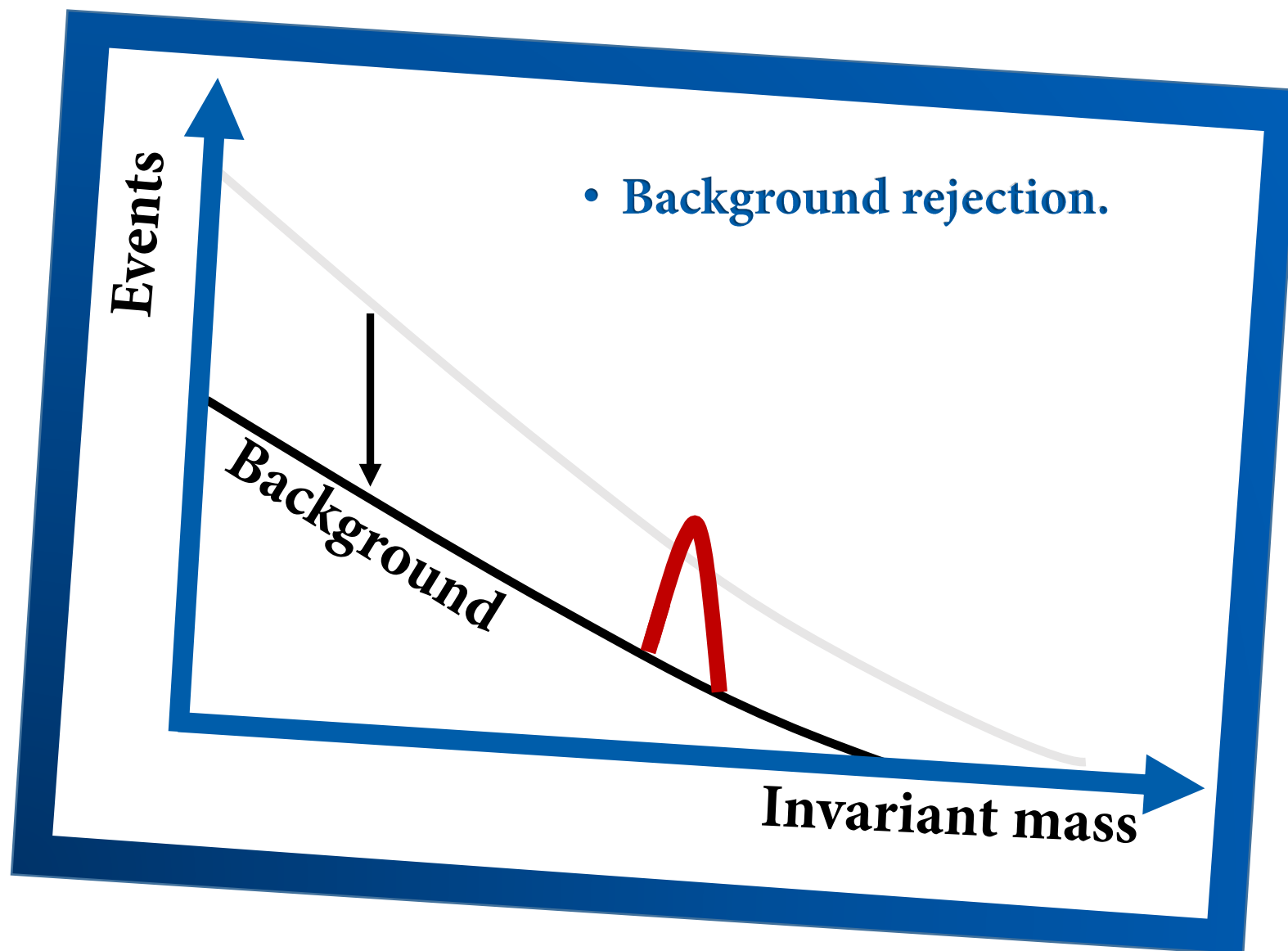
B = Branching ratio (from Particle data group)

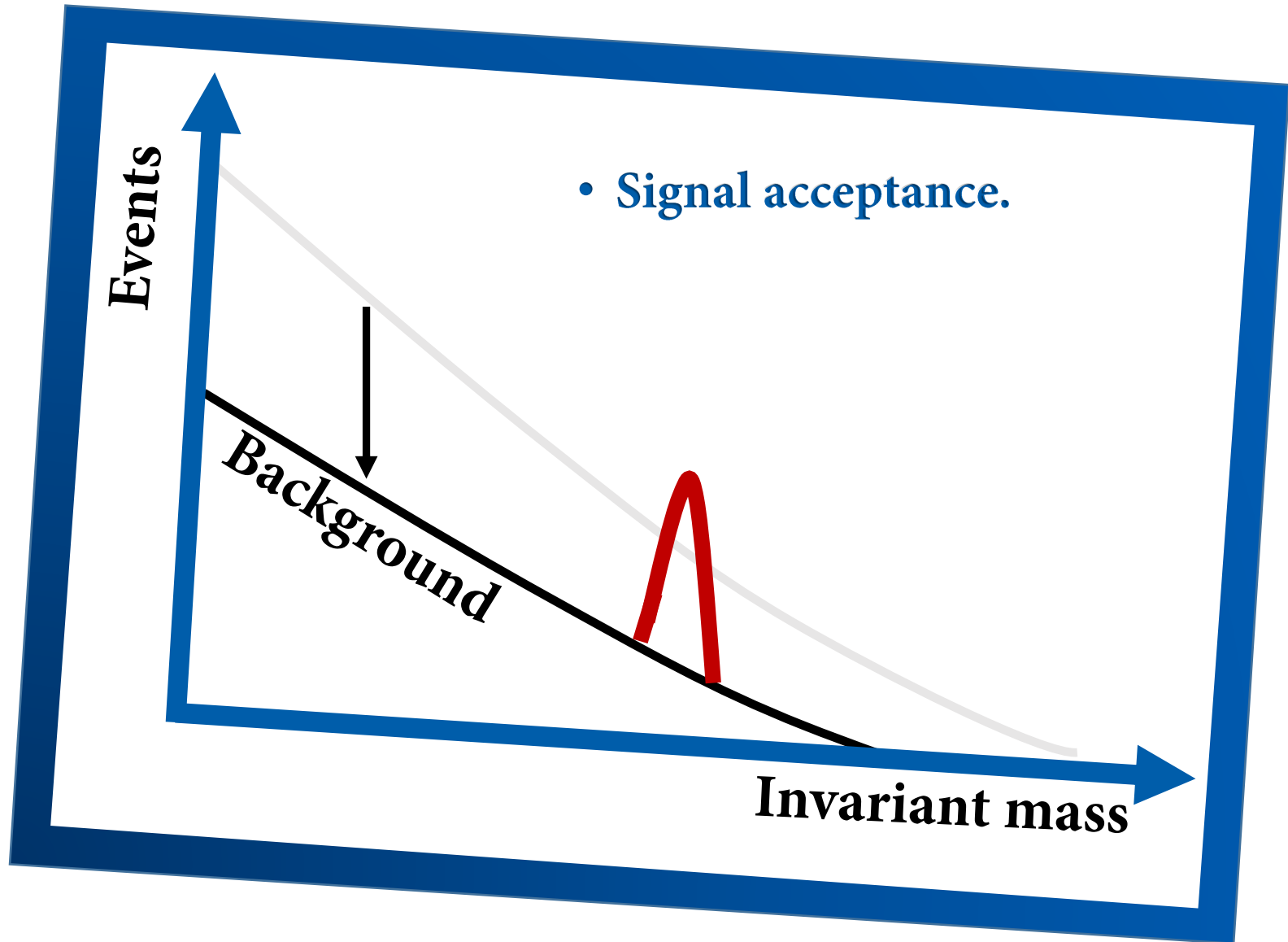
$$\sigma = \frac{N_{obs} - N_{bkg}}{\mathcal{L} \cdot \epsilon \cdot A \cdot \mathcal{B}}$$

- Minimise the uncertainty on  $\sigma$ !
- Maximise probability for signal detection, minimise probability for arriving at a fake signal detection.
- High signal to background :  $N(obs) \gg N(bkg)$
- High signal efficiency  $\epsilon A$
- Reliable, robust method to determine  $N(bkg)$ .
- Most important is the measurement of the uncertainty on  $N(bkg)$
- Use Monte Carlo to help decide selection criteria that attempt to minimise the uncertainty on  $\sigma$  or significance of a discovery.







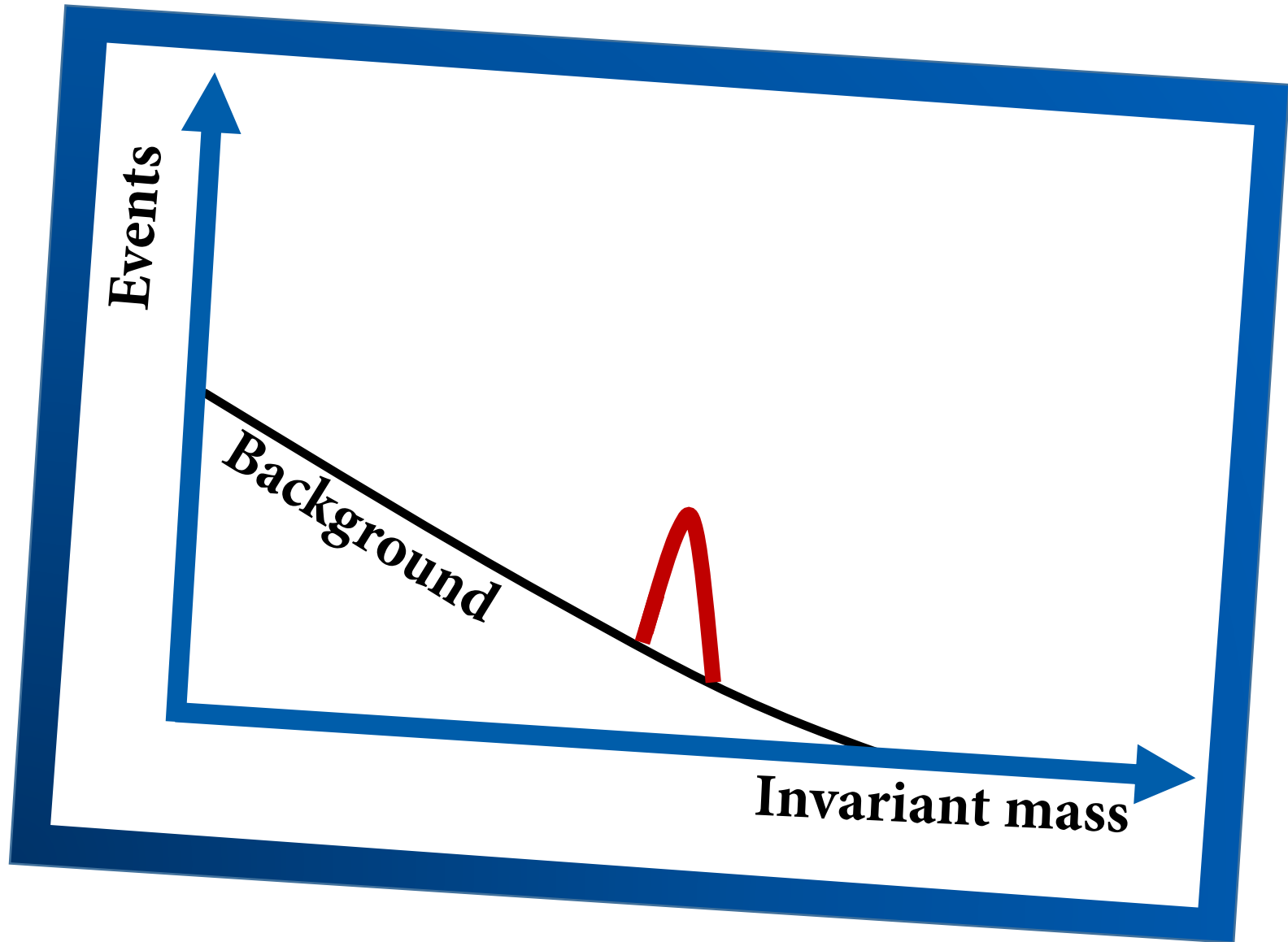


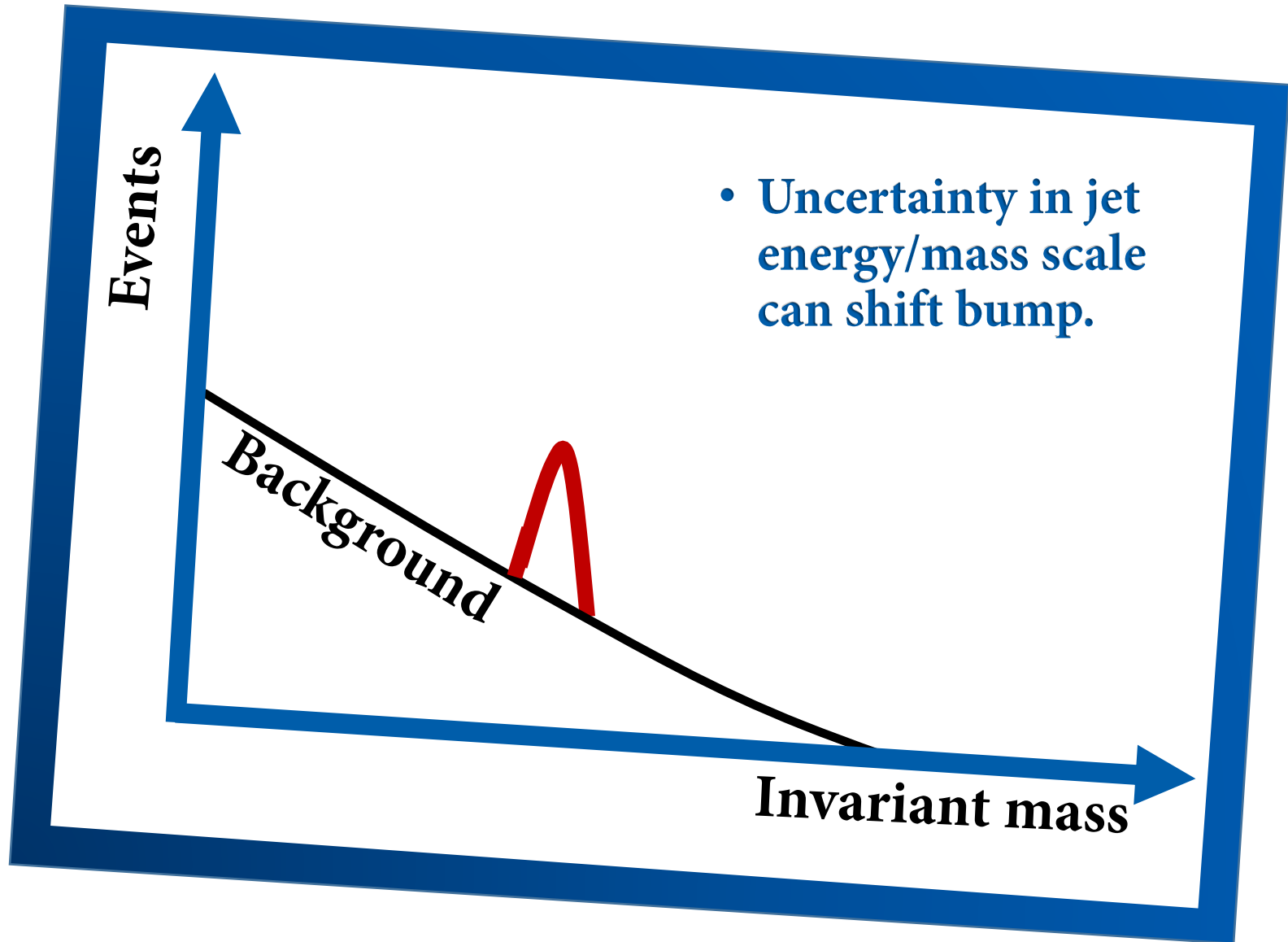
- Arise from stochastic fluctuations arising from the fact that a measurement is based on a finite set of observations
- Repeated measurements will give a set of observations that will differ from each other.
- Statistical uncertainty is a measure of this variation
- Poisson fluctuations associated with random variations in the system one is examining

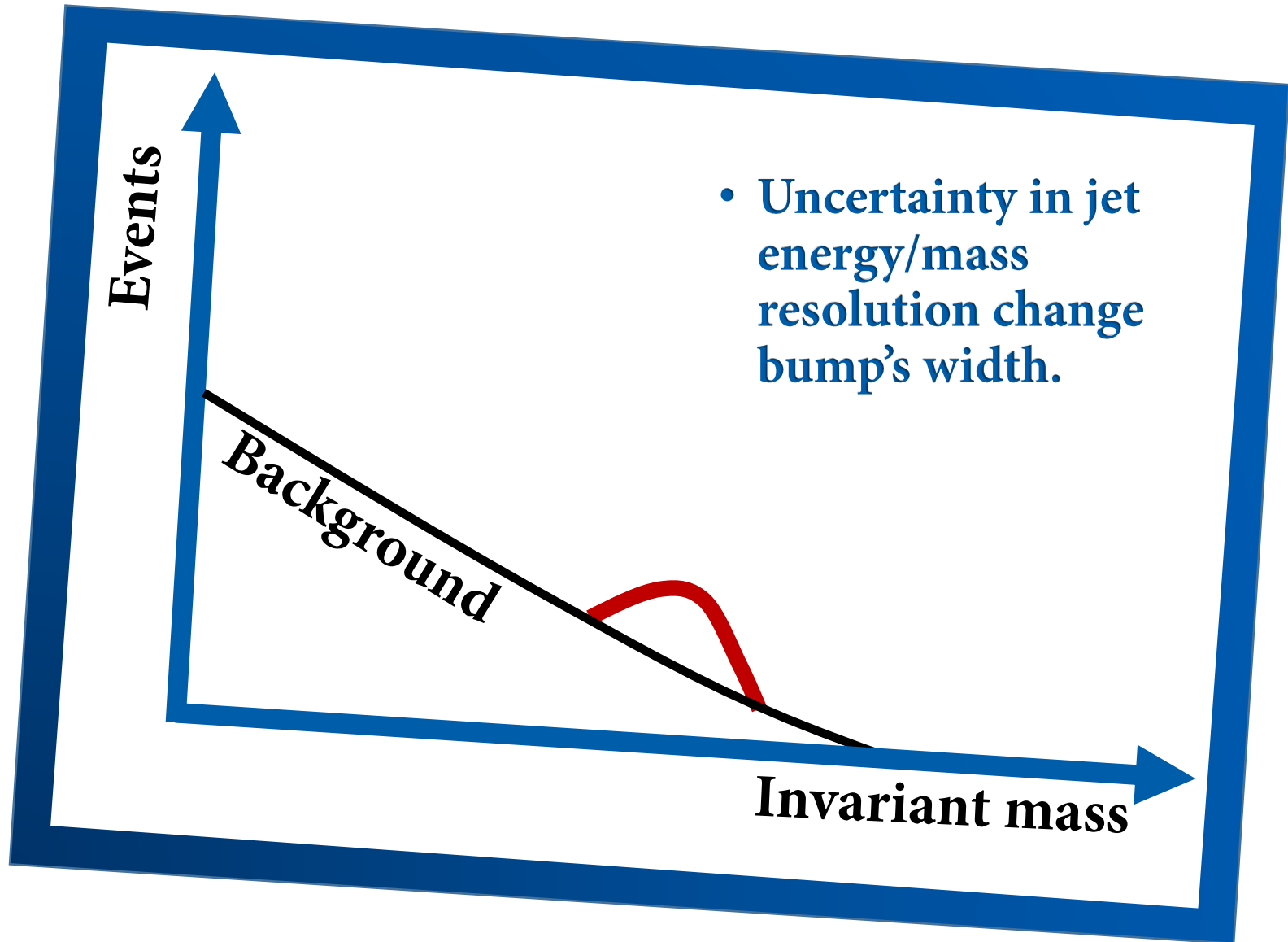
- Arise from **uncertainties associated with the measurement apparatus**
- What are the assumptions underlying the measurement?
  - How accurate is the Monte Carlo Simulation?
  - Models for the signal and the background
  - E.g. acceptance, model parameters
  - What can we think of that has the potential to affect our measurement?



# Systematic Uncertainties

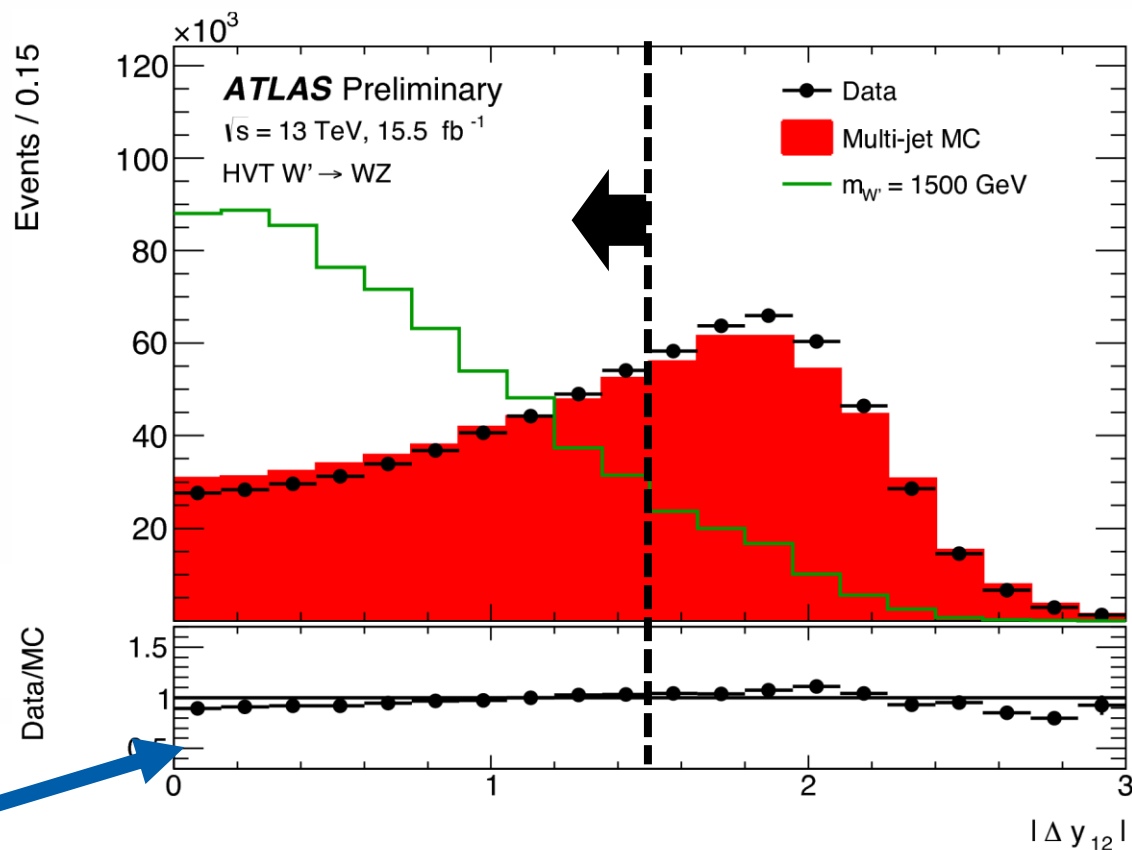






- Try to maximize fraction of signal events versus background events.
- One example is the use of kinematic cuts.

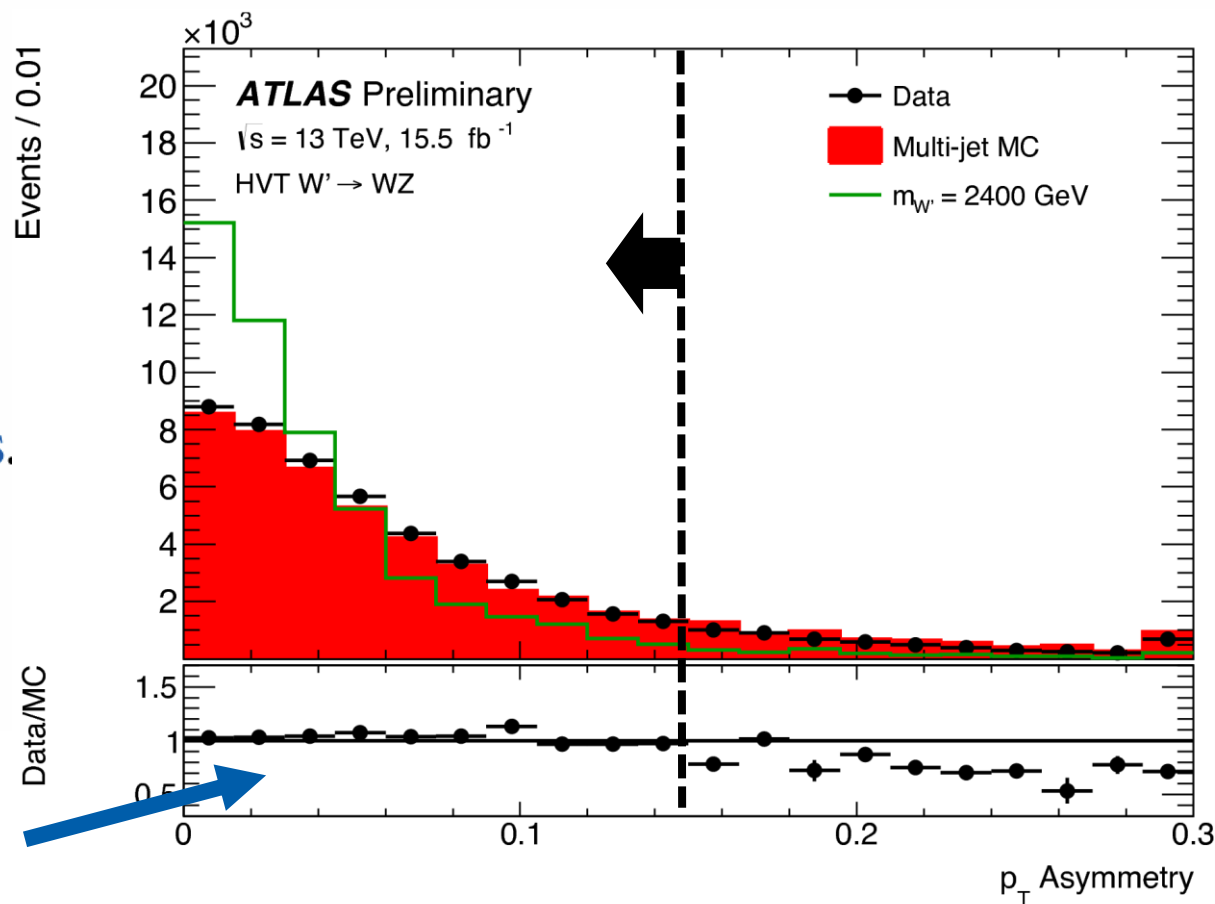
Cut on separation of two jets in rapidity

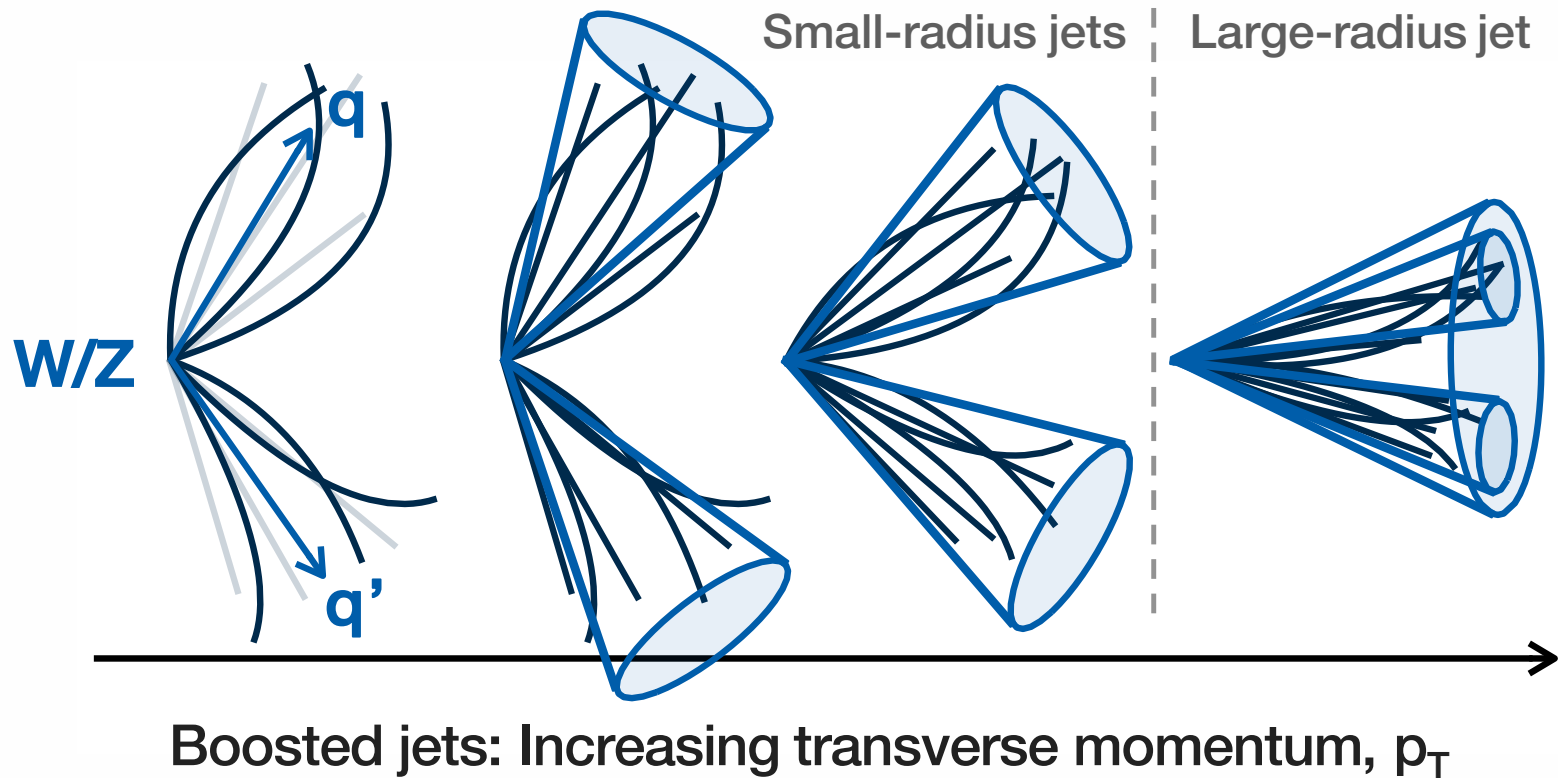




- Try to maximize fraction of signal events versus background events.
- One example is the use of kinematic cuts.

**Cut on momentum asymmetry between two jets**

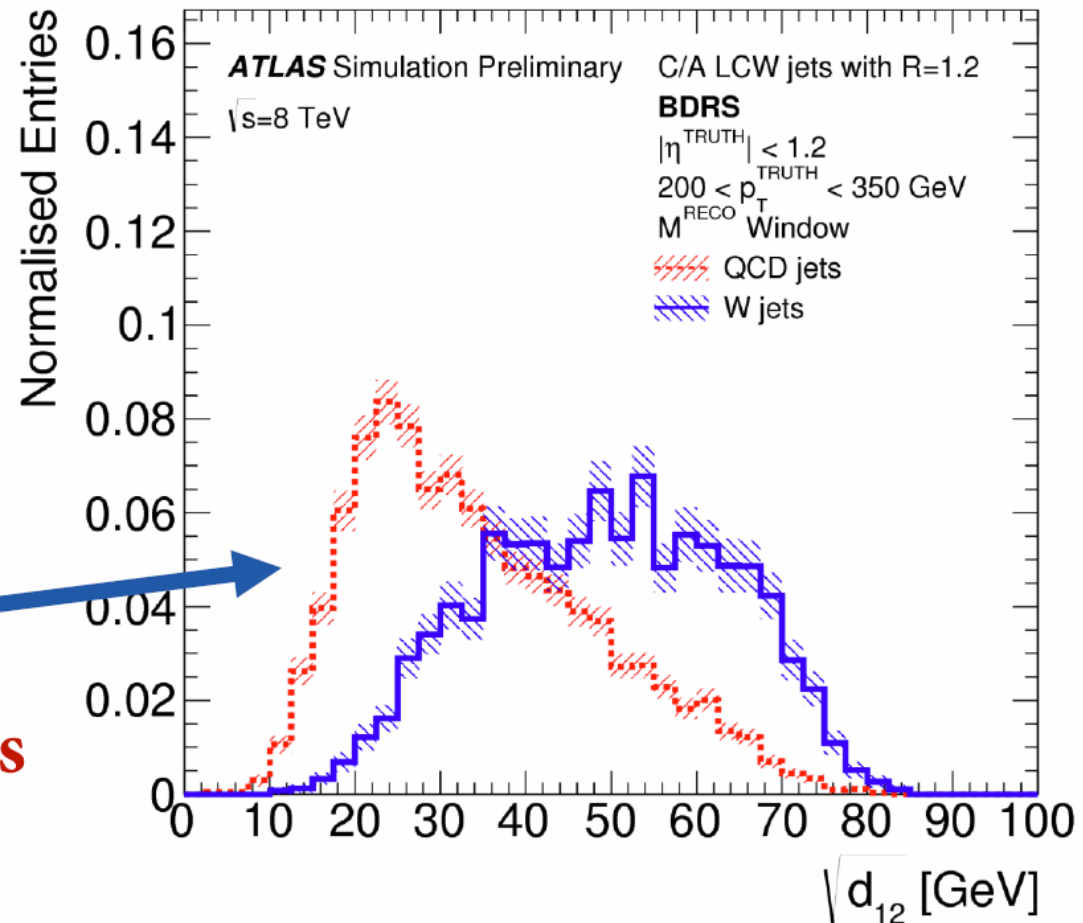




# Boson tagging

- Utilize different properties of jets from **W/Z-bosons** with respect to the background to “tag” them.

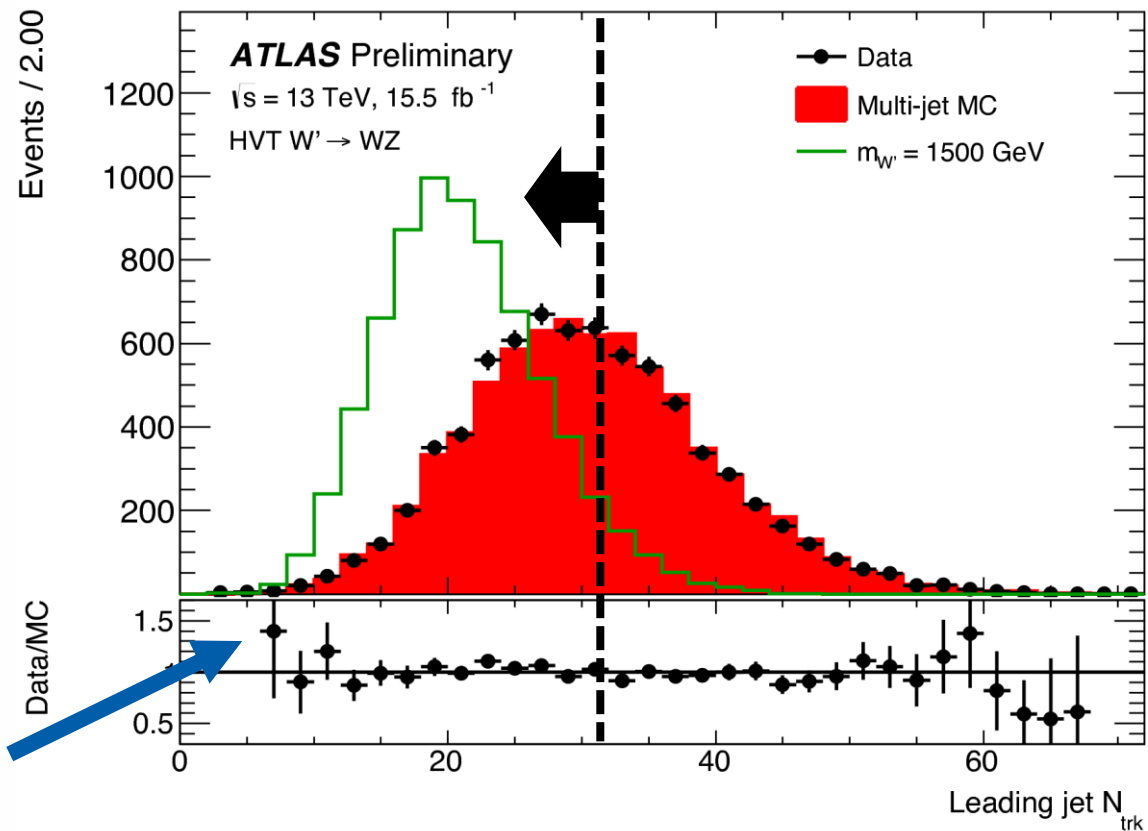
**Cut on jet substructure (calculated from energy distributions inside fatjet)**



# Boson tagging

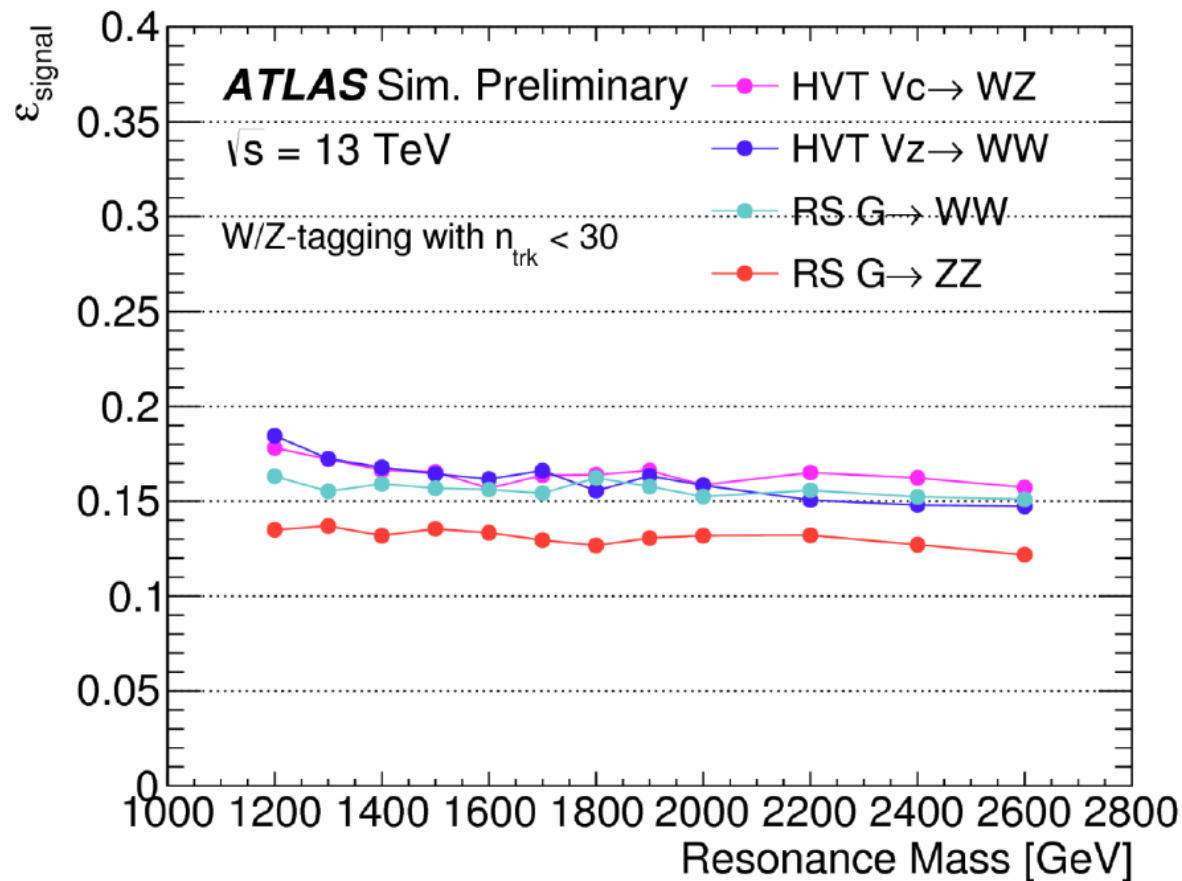
- Utilize different properties of jets from  $W/Z$ -bosons with respect to the background to “tag” them.

**Cut on number of tracks in jet**



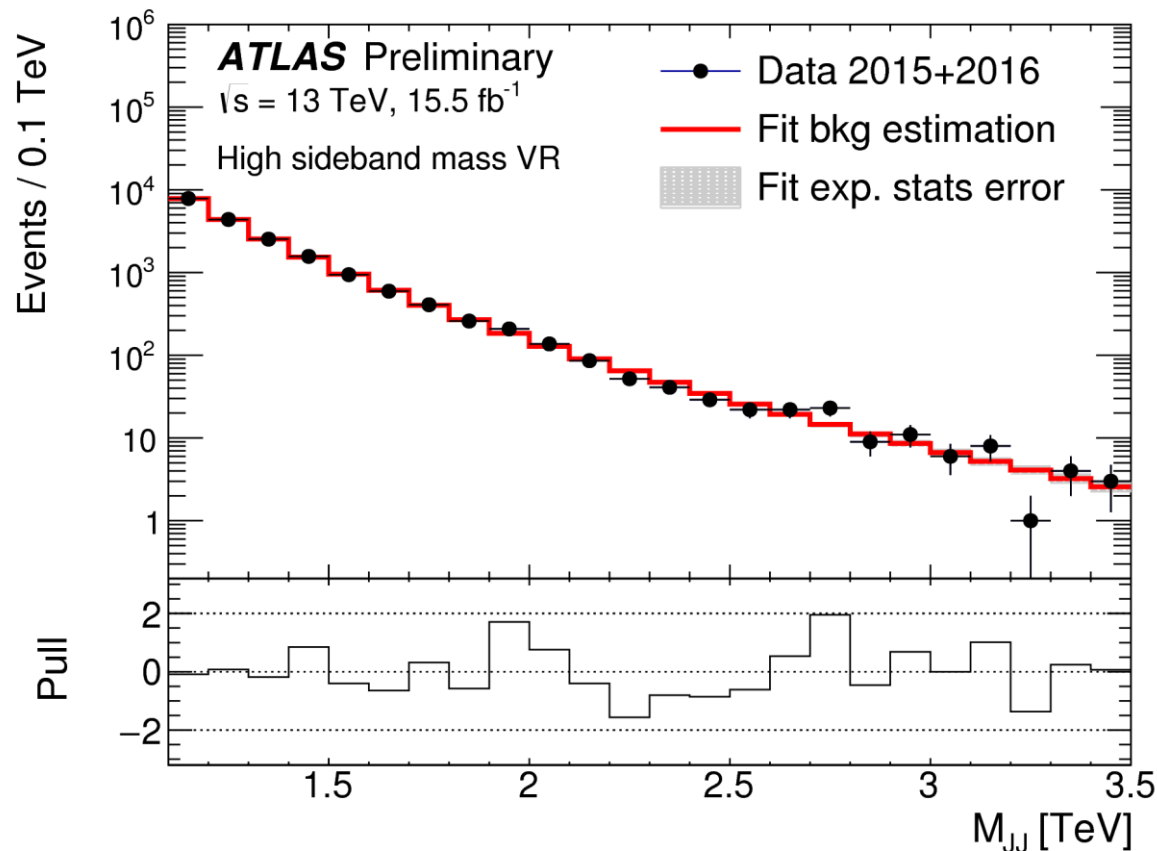
- Selection on jet mass: require to be at  $W/Z$  mass!

- After fixing selections of analysis, calculate expected **signal efficiency** and **yield**.



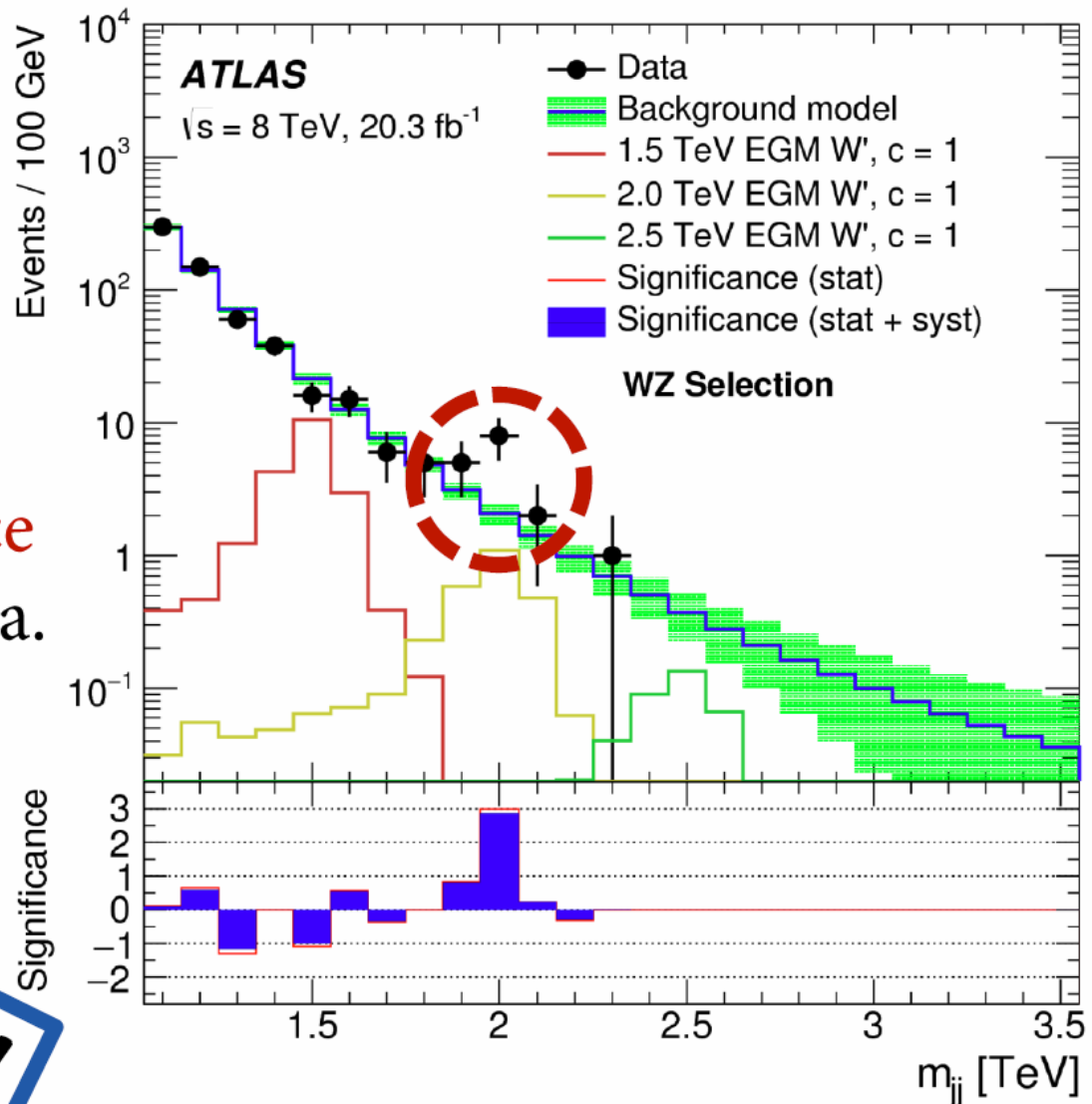


- Before looking at the data, validate analysis in **control regions** (e.g. mass sidebands).
- Check that **background** is **smoothly falling** and not sculpted by selections.



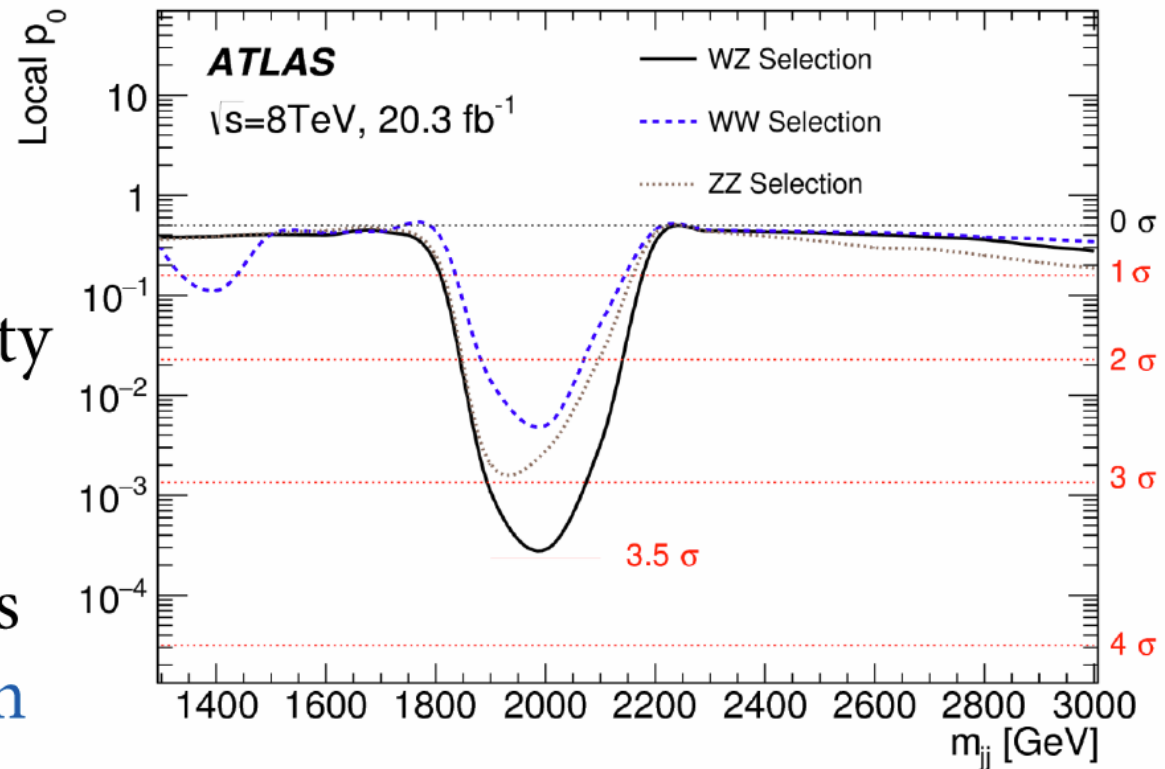
# Results!

1. Finally, look at signal region
2. Fit background
3. Check for **difference** between fit and data.



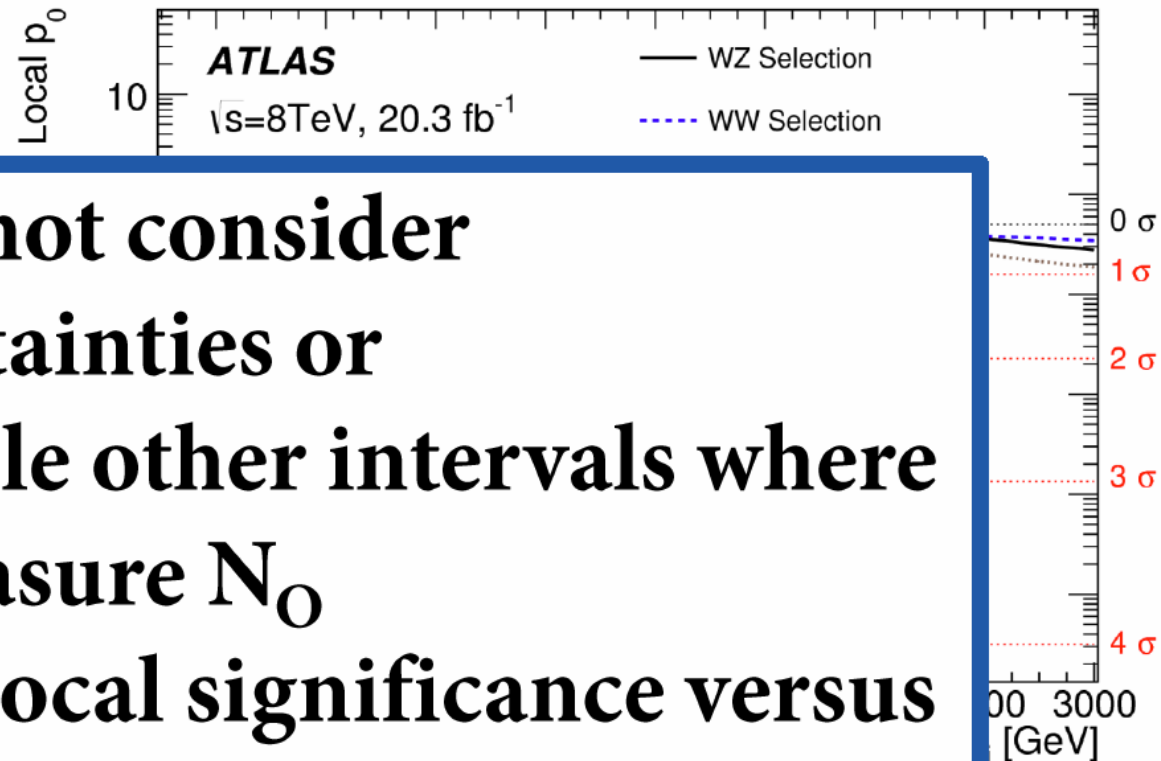
**Result from run 1!**

- Estimate of  $p$ -value/significance of observed events, assuming probability density for random variable
- Assume:  $N_O$  follows Poisson distribution



- Poisson probability:  $\alpha = \sum_{n=N_O}^{\infty} \frac{\exp(-N_b) (N_b)^n}{n!}$ .

- Estimate of  $p$ -value/significance



- Does not consider uncertainties or possible other intervals where to measure  $N_o$
- $\rightarrow$  local significance versus global significance

- Poisson probability:  $\alpha = \sum_{n=N_o} \frac{\exp(-N_b) (N_b)^n}{n!}$ .



**$1-2\sigma$**



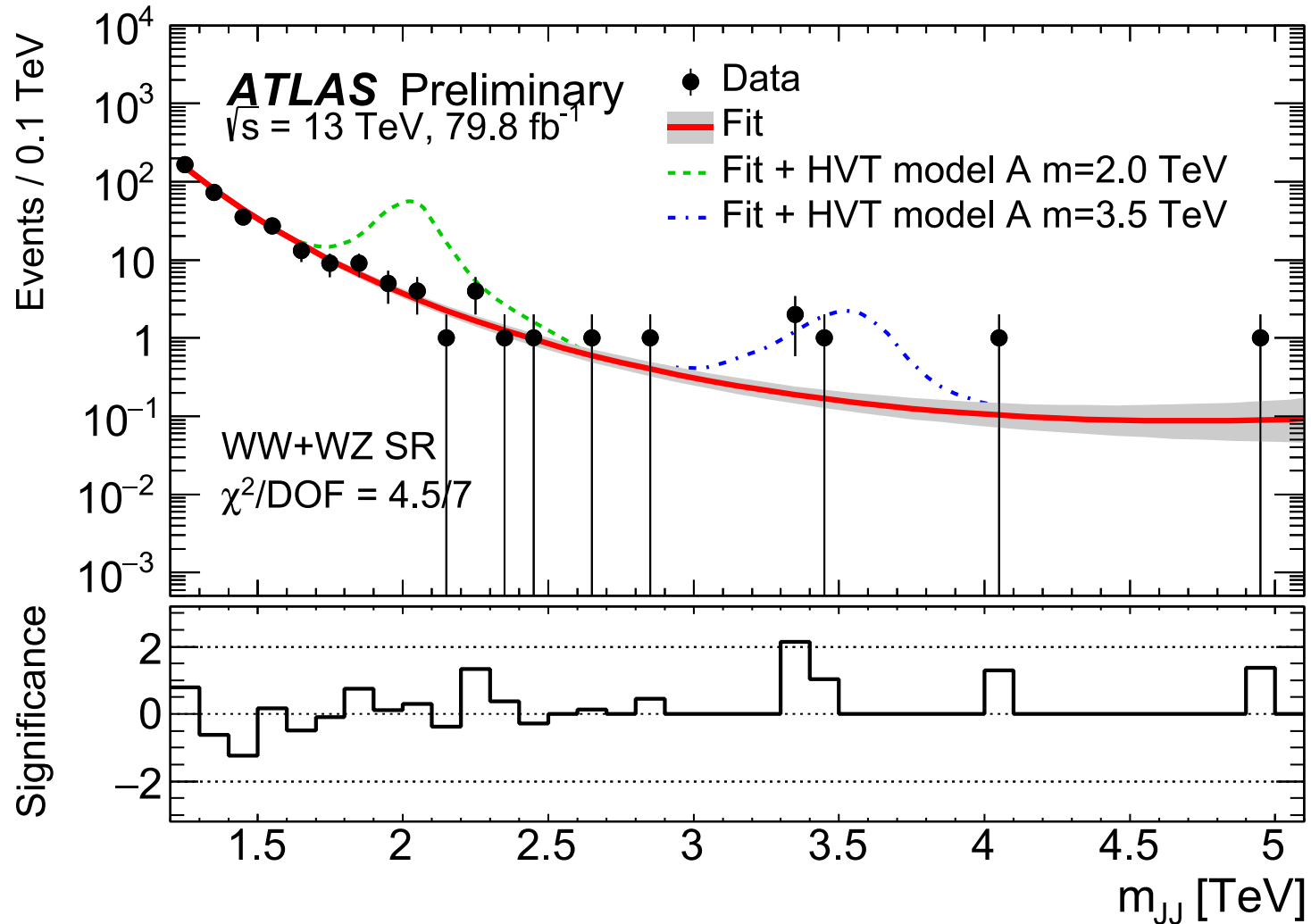


$3\sigma$



$5\sigma$

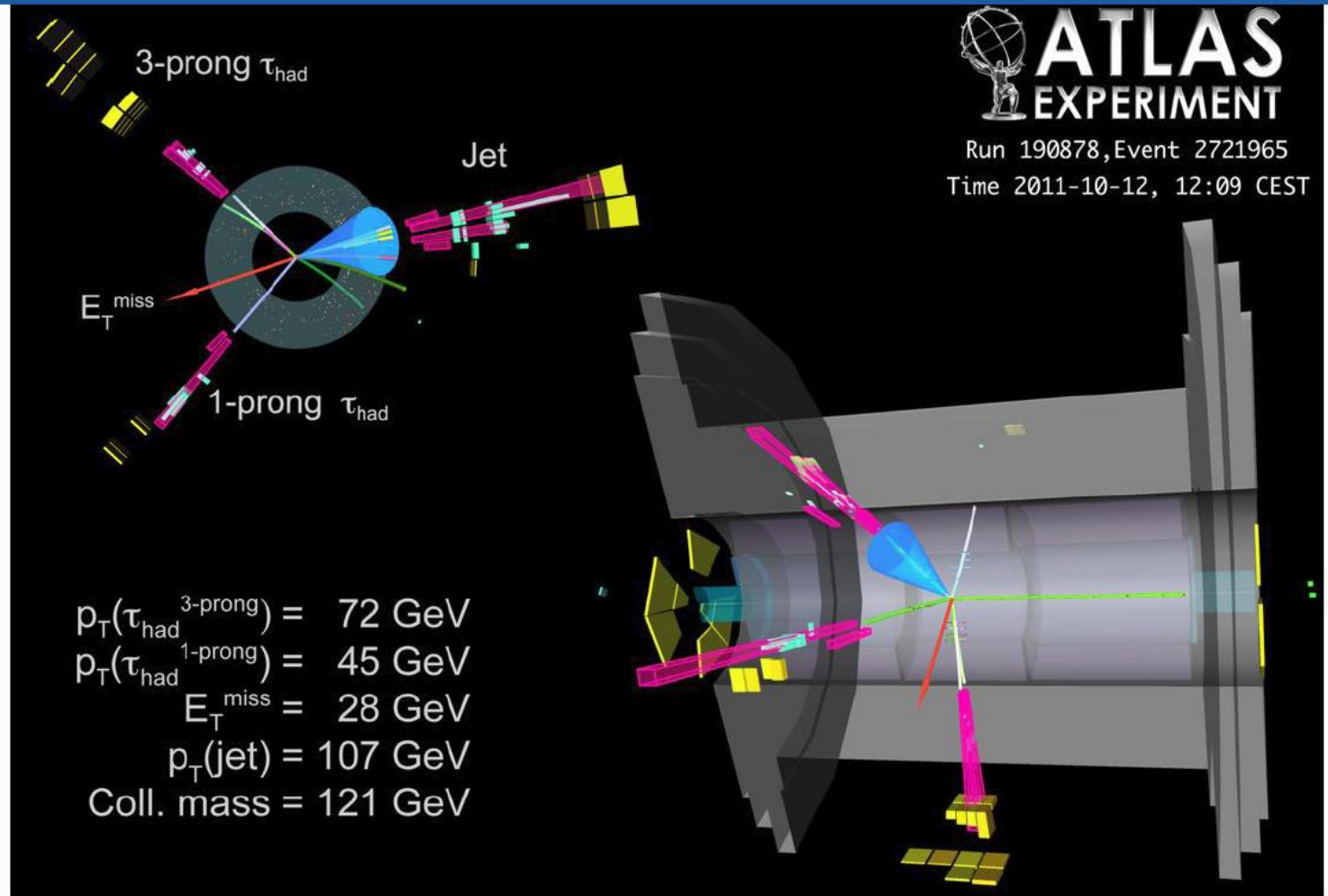
# More Results!



**Thank you – Discussion!**

# BACKUP





- Essentially thin jets  $\tau^+ \rightarrow \pi^+ \nu_{\tau}$   $\tau^+ \rightarrow \pi^+ \pi^+ \pi^- \nu_{\tau}$