

News from the Micro Vertex Detector of CBM

Philipp Sitzmann¹ for the CBM-MVD Collaboration²

¹ Goethe Universität Frankfurt, Germany

² Goethe Universität Frankfurt, Germany / Pusan National University (PNU), Korea / IPHC Strasbourg, France

Compressed Baryonic Matter experiment at FAIR

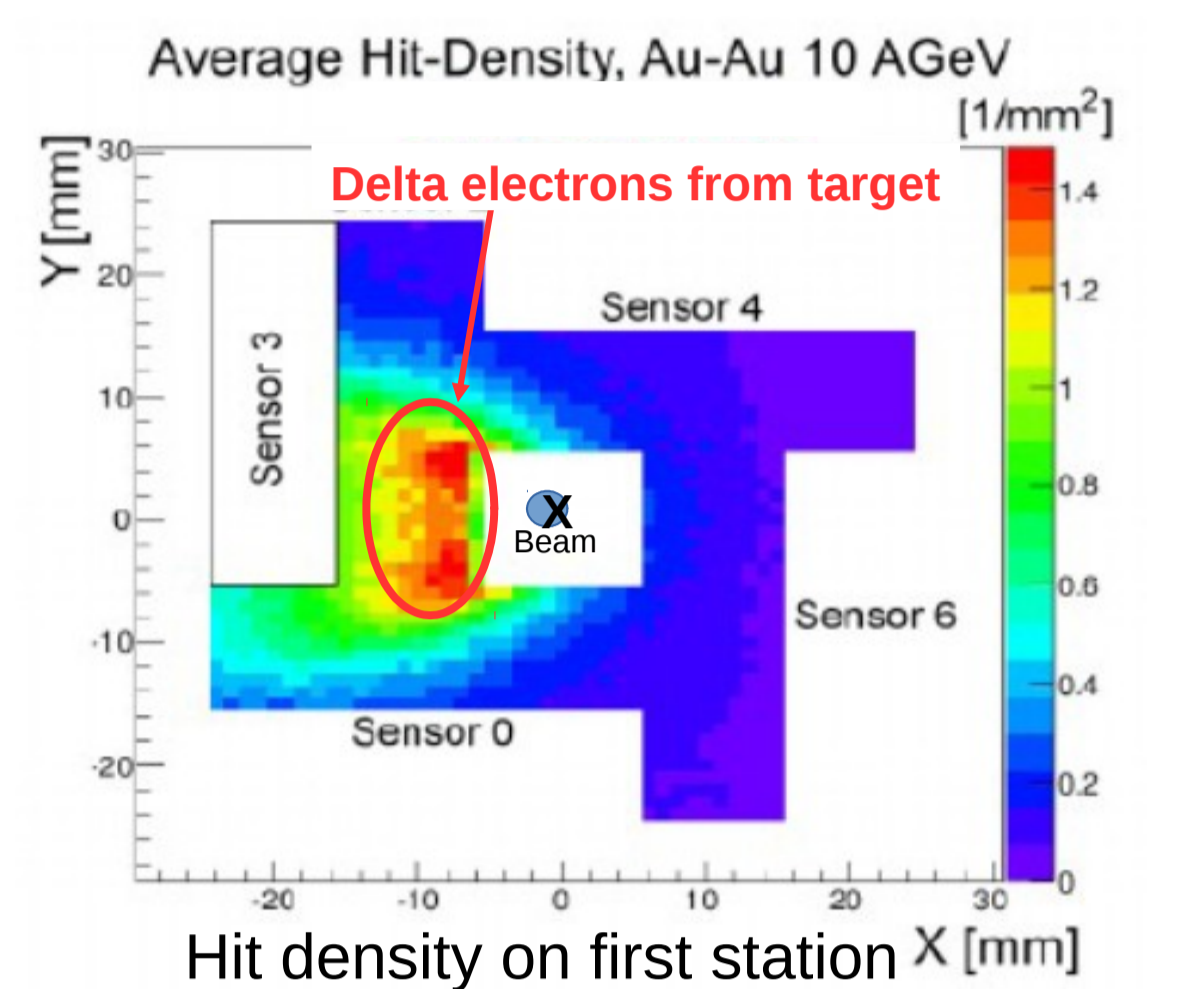
The Micro Vertex Detector (MVD) of CBM

The task of the MVD of CBM

- 1) Open Charm reconstruction → Provide ~50 μm sec. vertex reconstruction.
 - 2) Support e⁺/e⁻ spectroscopy → Provide excellent low momentum tracking.
 - 3) Charged reconstruction in HIC (first time)
- Operate at 100 kHz Au+Au (10 AGeV) and 10 MHz p+Au (30 GeV)

The technological challenge

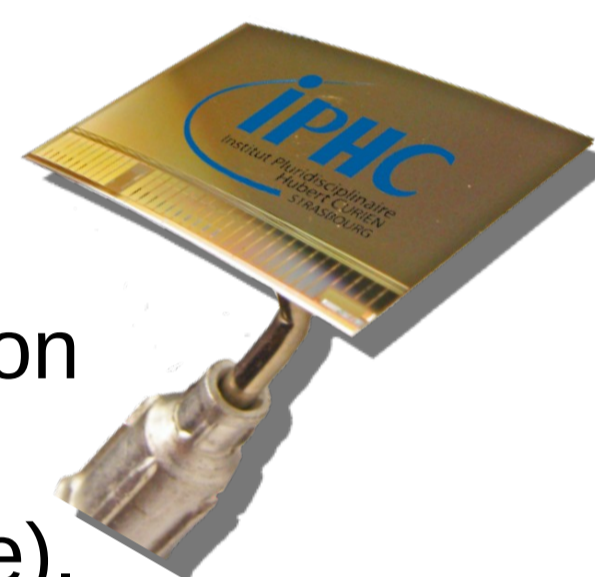
- Needs ultra thin (0.3% X₀) stations.
- Operation in target vacuum needed.
- High track density (700 kHz/mm² peak)
- High radiation load:
 - 3 × 10¹³ n_{eq}/cm²
 - 3 Mrad



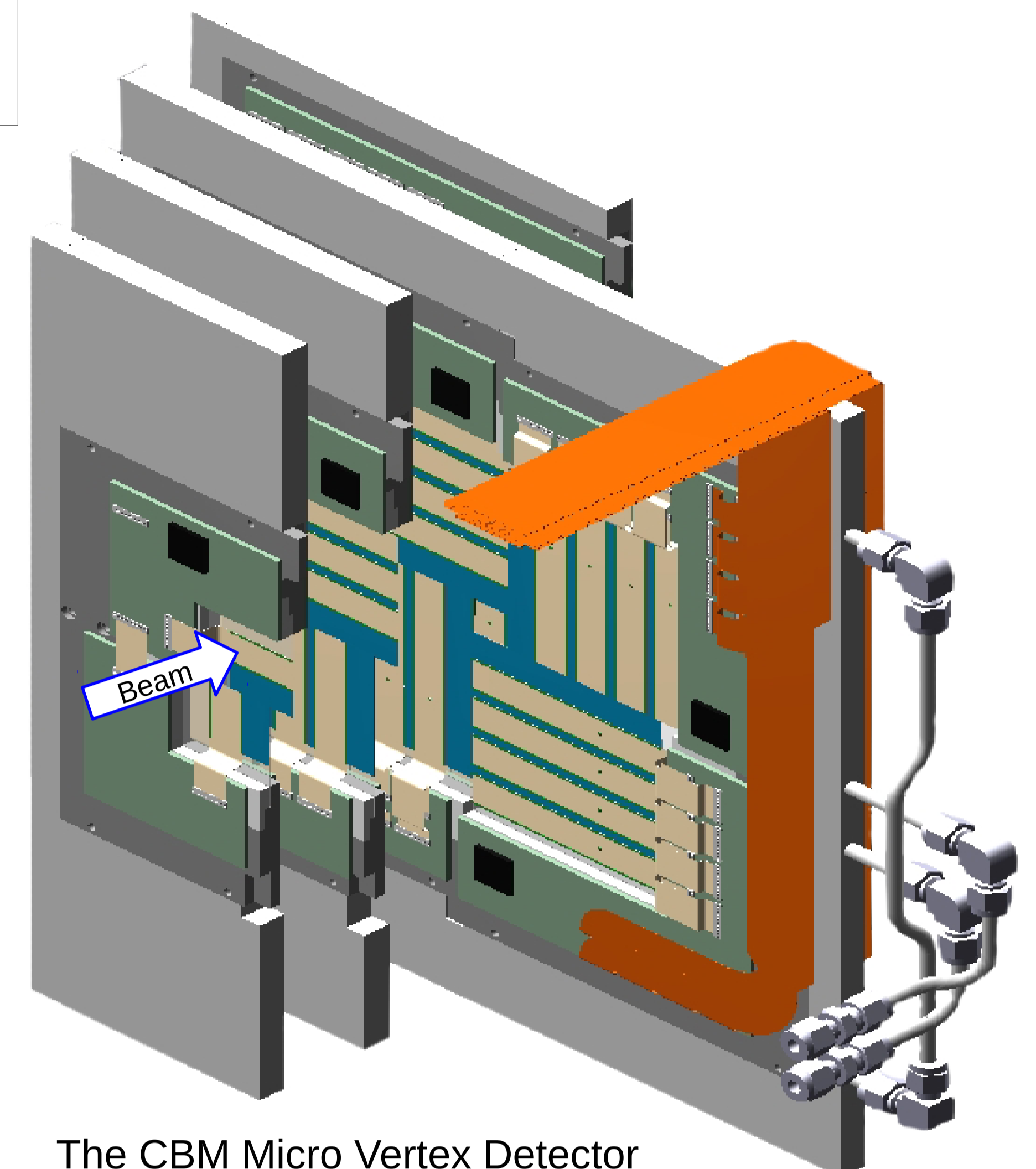
The sensor technology

CMOS Monolithic Active Pixel Sensor

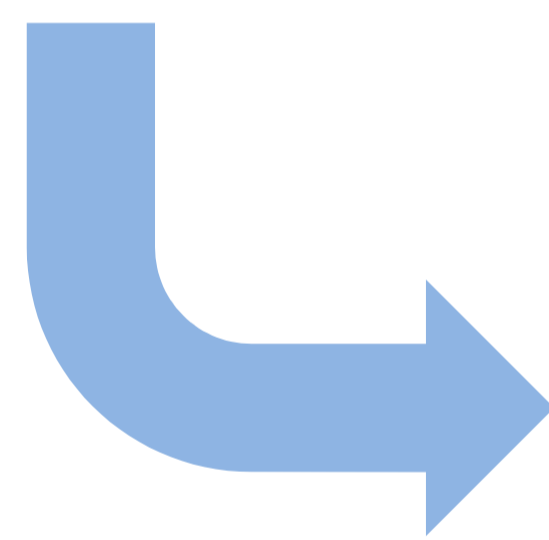
- Excellent compromise between high precision tracking and high rate capability.
- Used in STAR/HFT and ALICE/ITS (upgrade).
- Dedicated sensor required for CBM (MimoSIS):



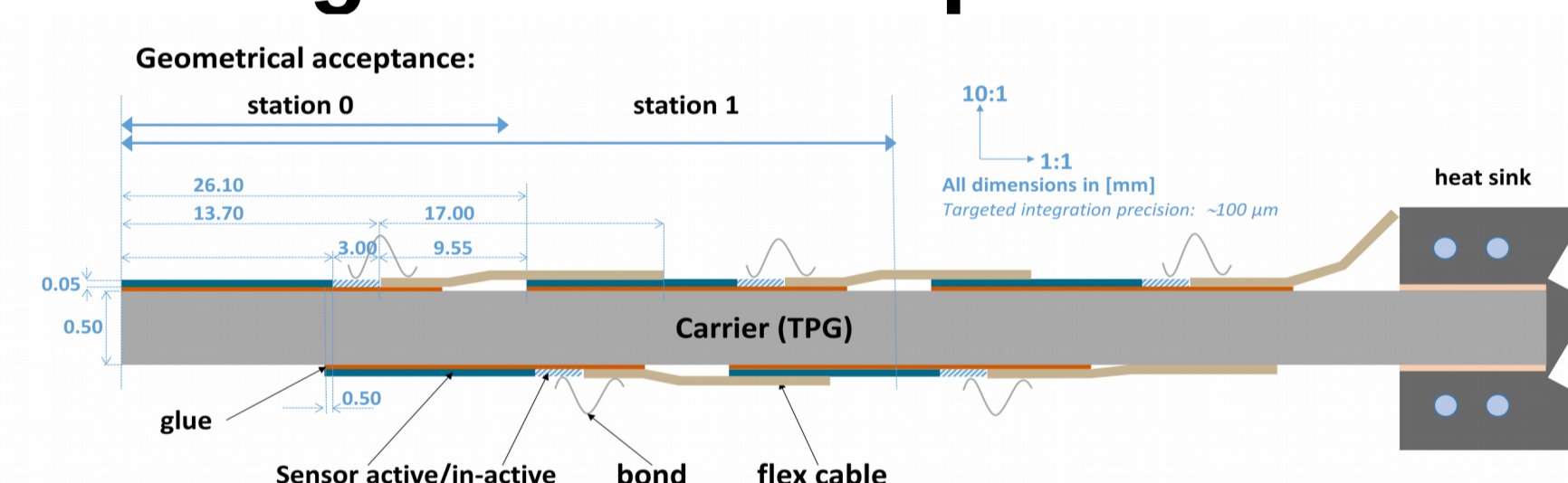
	ALICE ALPIDE (demonstrated)	MimoSIS (design goal)	Improvement factor
Pixel count	512 x 1024	504 x 1024	ok
Pixel pitch	29.2 μm x 26.9 μm	30.2 μm x 26.8 μm	ok
Spacial resolution	< 5 μm	< 5 μm	ok
Time resolution	5 - 10 μs	~5 μs	ok
Radiation load TID	500 krad	3 Mrad	x 6
Radiation load NIEL	1.7 x 10 ¹³ n _{eq} /cm ²	3 x 10 ¹³ n _{eq} /cm ²	x 2
Peak hit rate	> 12 kHz/mm ²	700 kHz/mm ²	x 56



The CBM Micro Vertex Detector

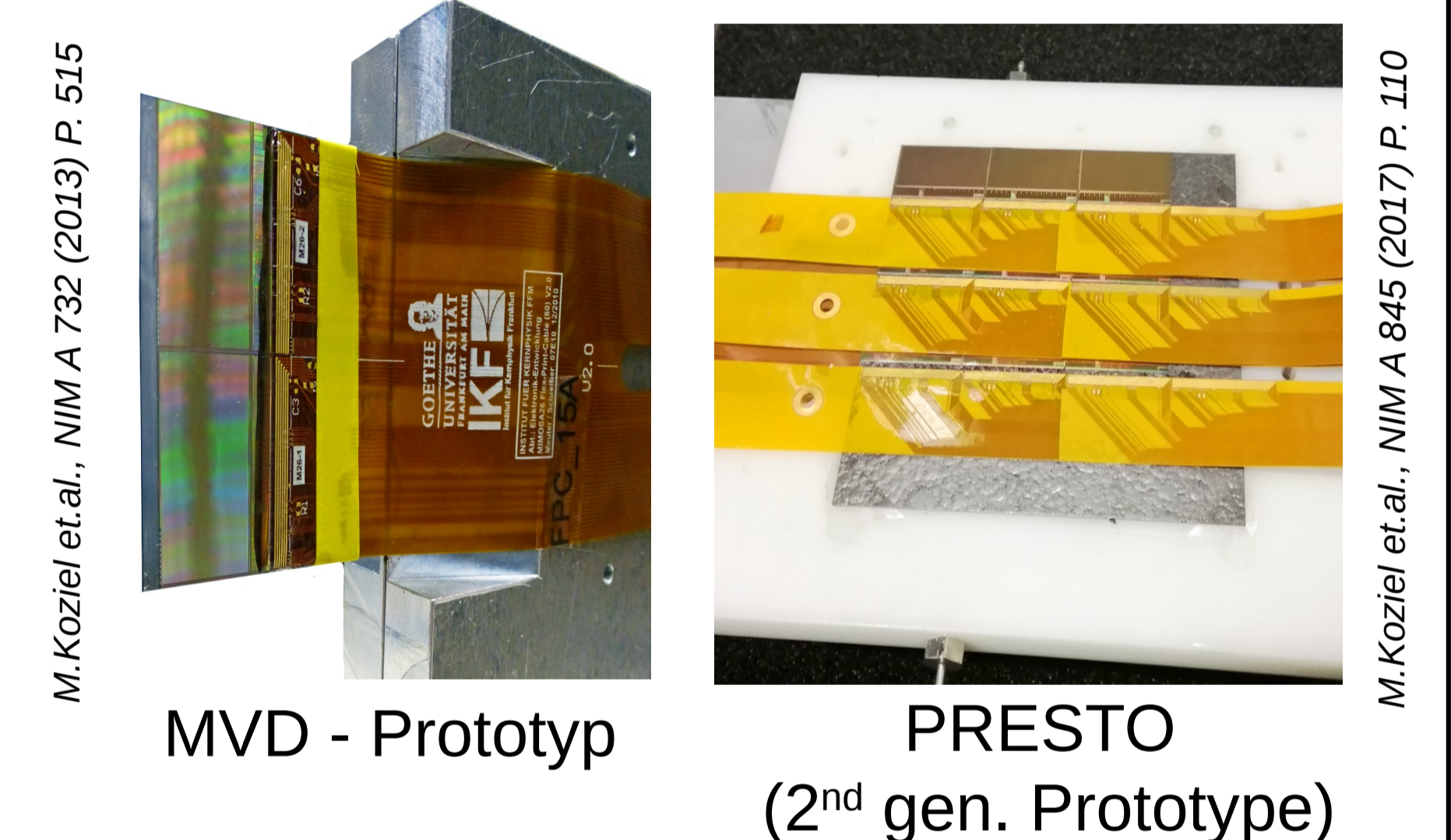


The integration concept



- Place sensors on carbon based cooling support
- Evacuate dissipated power to liquid cooled heat sink outside of acceptance

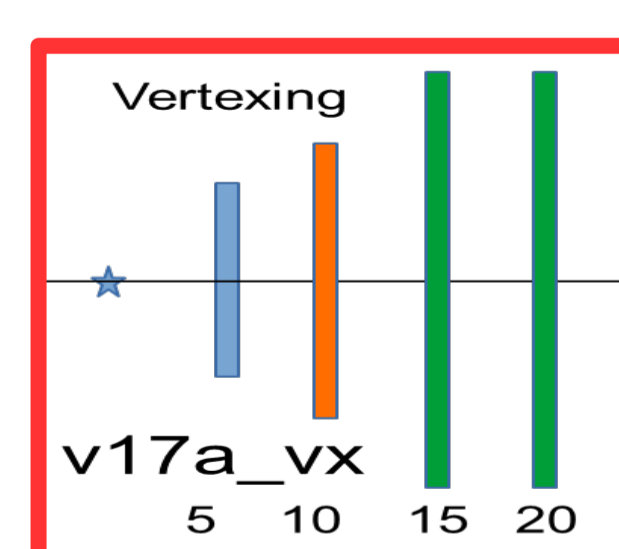
Results of prototyping



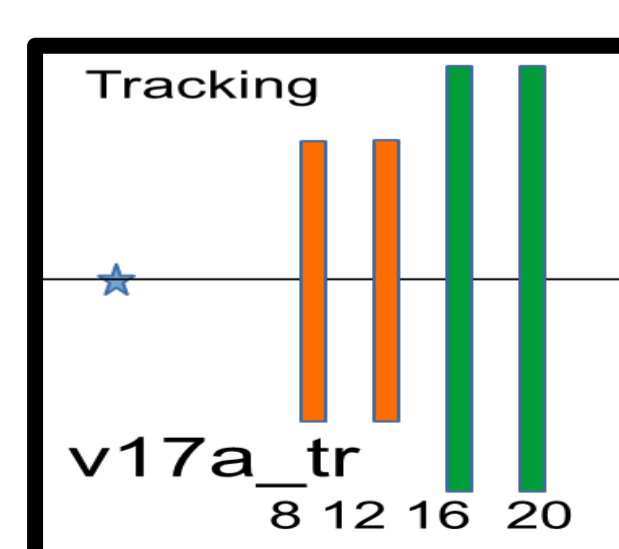
- Integration feasible.
- Excellent tracking performance > 99% det. eff. (with Mimosas26 @ CERN SPS)
- Long term vacuum operation under study

Tracking performance simulations

Aim - Test MVD geometry options

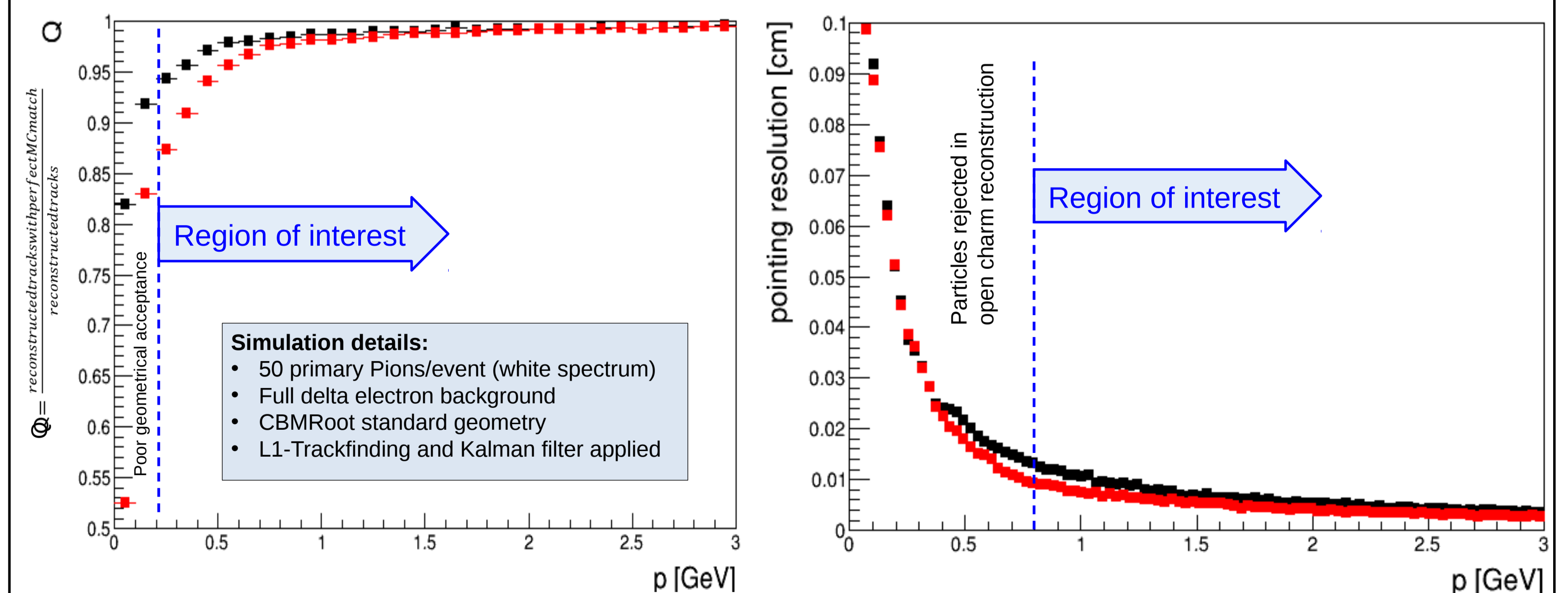


station @ 5 cm
⇒ expect improved IP resolution,
⇒ tracking complicated by high track density.



first station @ 8 cm
⇒ reduced track density
expect robust tracking
⇒ expect reduced pointing resolution

Results



Conclusion: Both geometries provide robust performances.

Next step: Full physics case simulation