



# GANs for simulation: development for distributed computing systems

Elena Orlova, Higher School of Economics, Moscow, Russia

Advised by Sofia Vallecorsa, Andrei Gheata

14 August, 2017

# Outline

- Introduction
  - Generative Adversarial Networks
- Implementation
- Summary

# Introduction

Experiments need tools for fast simulation. Currently available solutions depend on the experiments.

We want to:

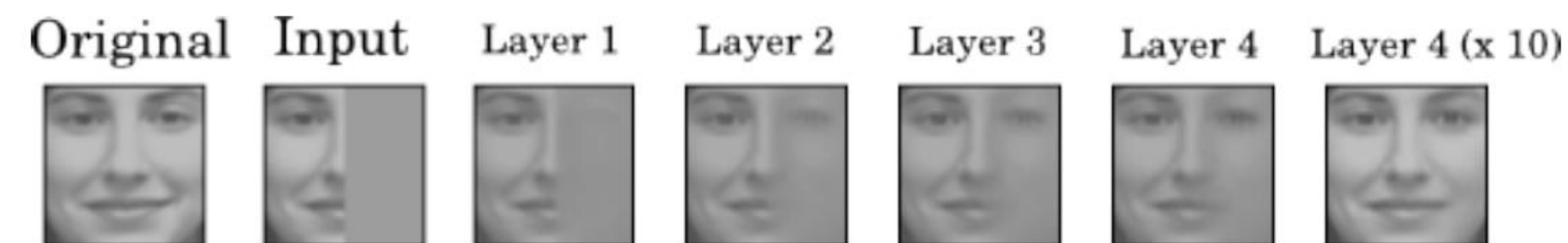
- have a generic interface in GeantV capable of using different fastsim options including ML based
- reproduce particle interactions with matter in a detector and provide related quantities such as energy or particle type

**Generative Adversarial Networks!**

# DL for simulation

Generative models (Generative Stochastic Networks, Variational Auto-Encoders, Generative Adversarial Networks, ..) can be used for simulation:

- Realistic generation of samples
- Use complicated probability distributions
- Optimize multiple output for a single input
- Work well with missing data



<https://arxiv.org/pdf/1605.05396.pdf>



# GAN results



Samples of images of bedrooms generated by a DCGAN trained on the LSUN dataset.



Samples drawn trained on the CIFAR-10 dataset

<https://arxiv.org/pdf/1701.00160v1.pdf>



# Generative Adversarial Networks

**Generator**

vs.

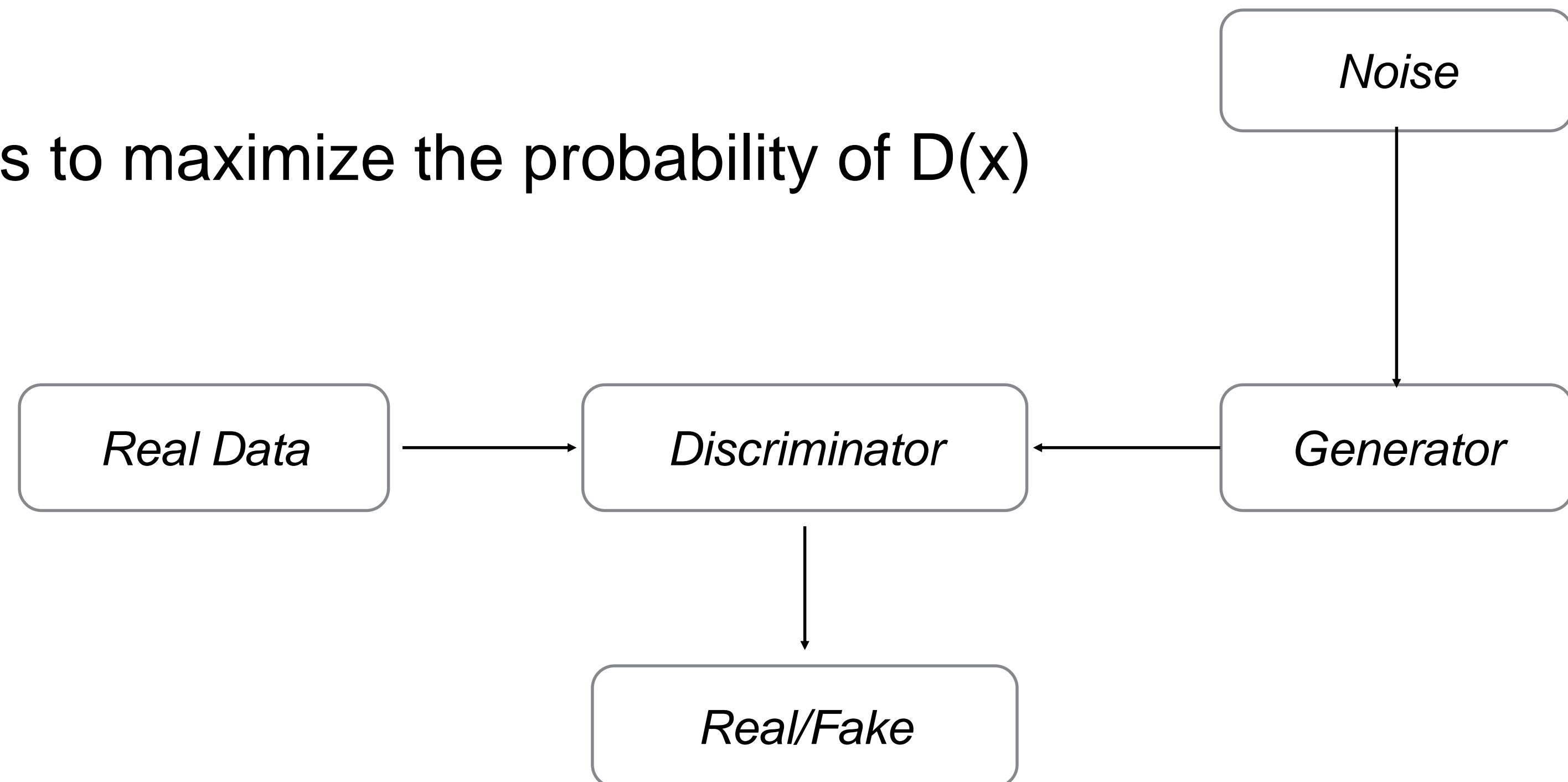
**Discriminator**

# Generative Adversarial Networks

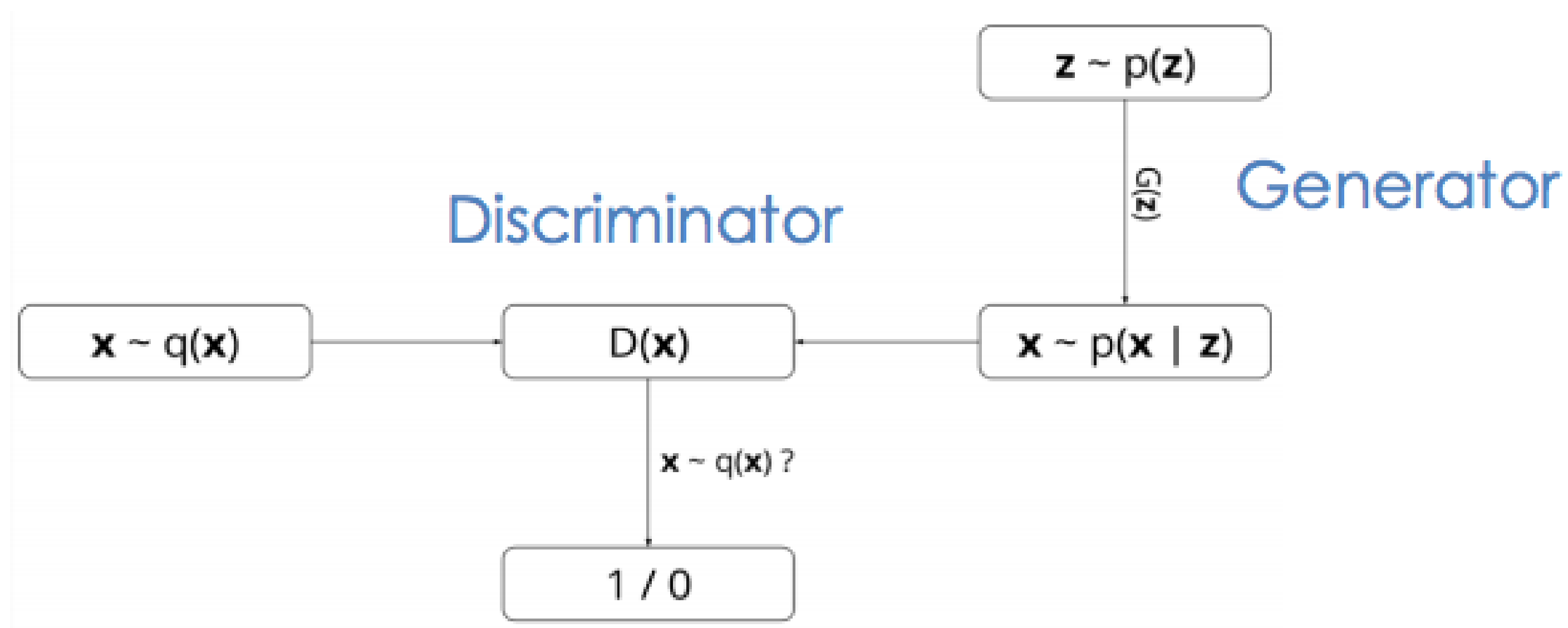
Two models:

- $D(x)$  classifies images: fake or real
- $G(x)$  produces images taking as input some random noise

Training procedure for  $G(z)$  is to maximize the probability of  $D(x)$  making a mistake



# Generative Adversarial Networks

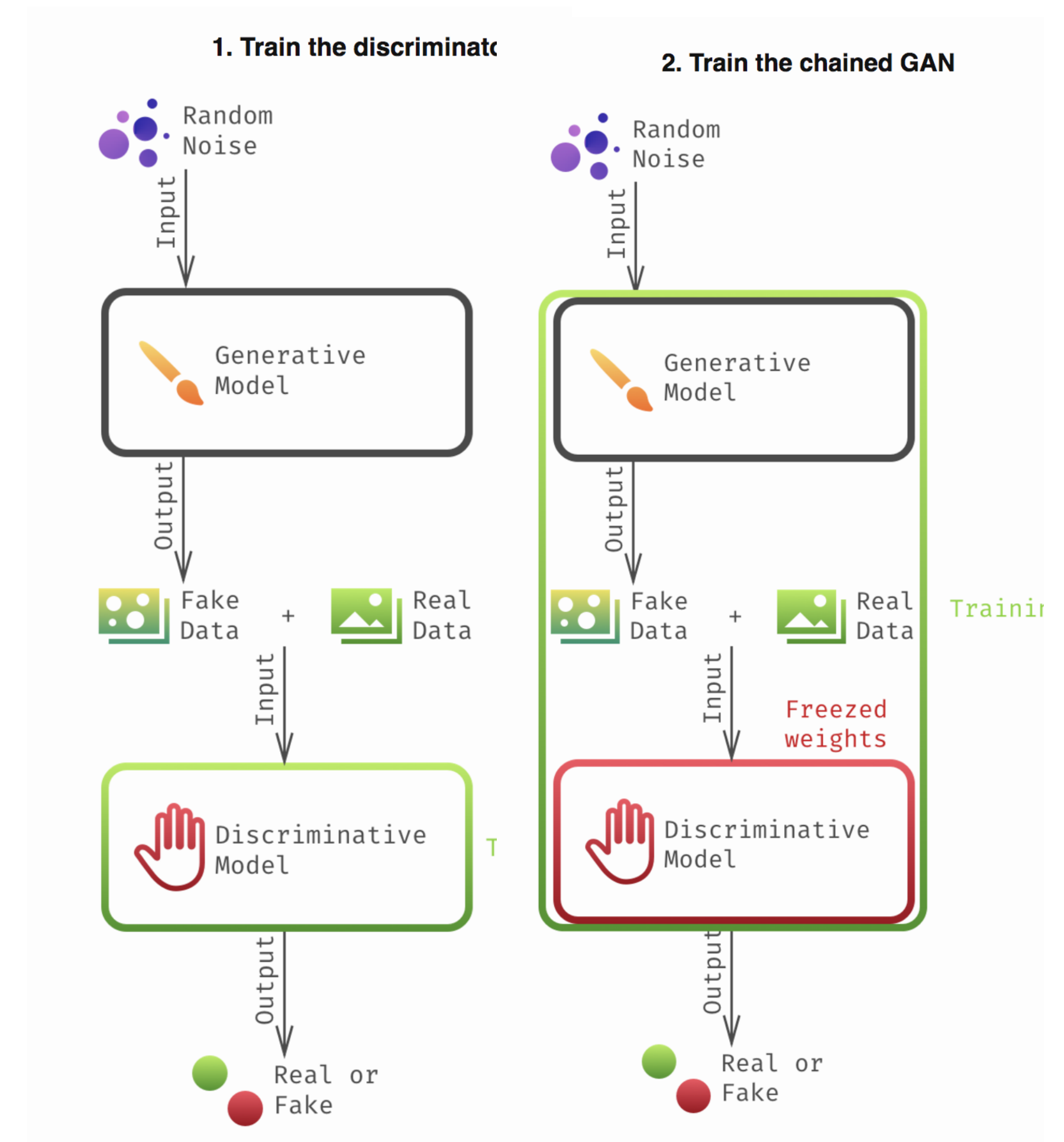


$$\min_G \max_D V(D, G) = \mathbb{E}_{\mathbf{x} \sim p_{\text{data}}(\mathbf{x})} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{z} \sim p_{\mathbf{z}}(\mathbf{z})} [\log(1 - D(G(\mathbf{z})))]$$



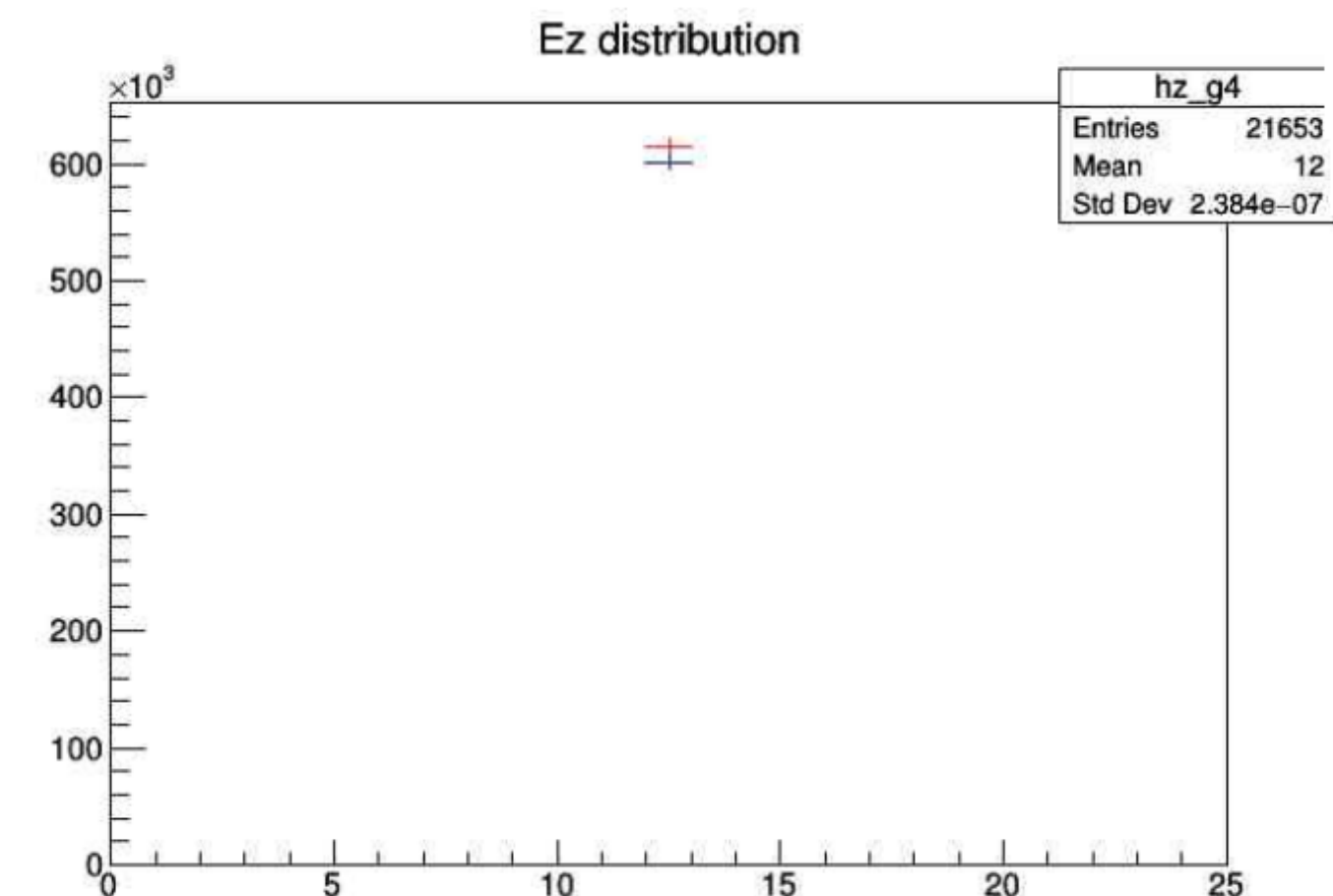
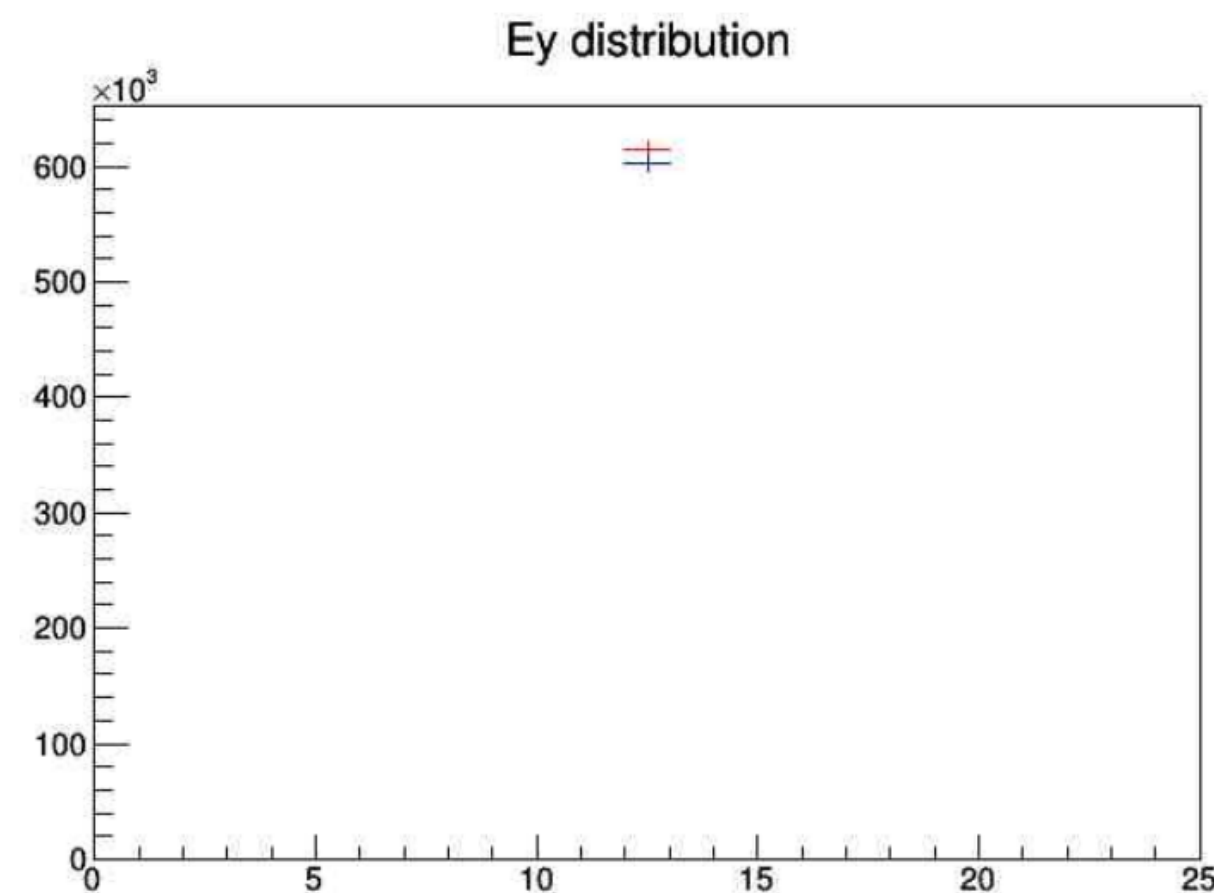
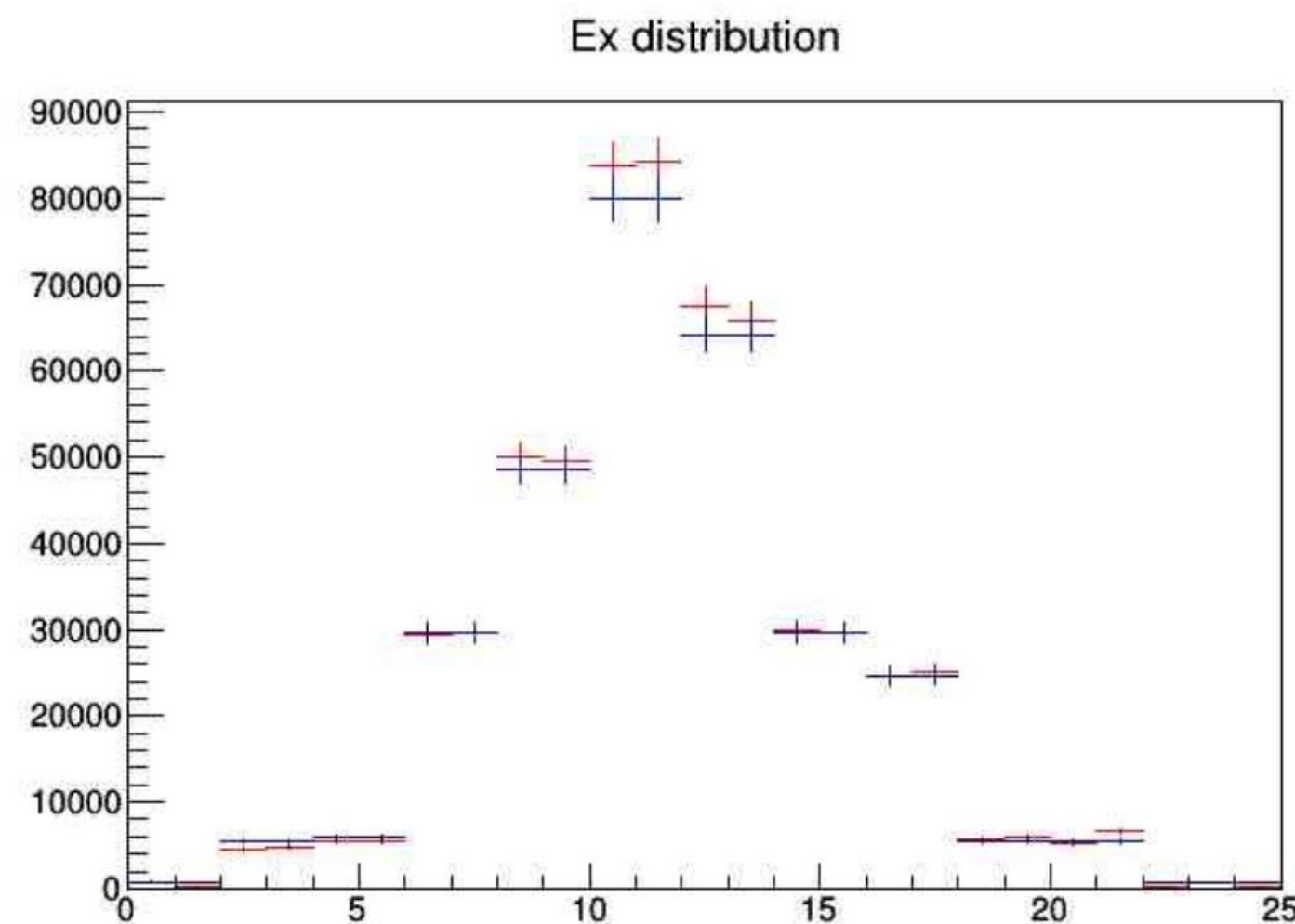
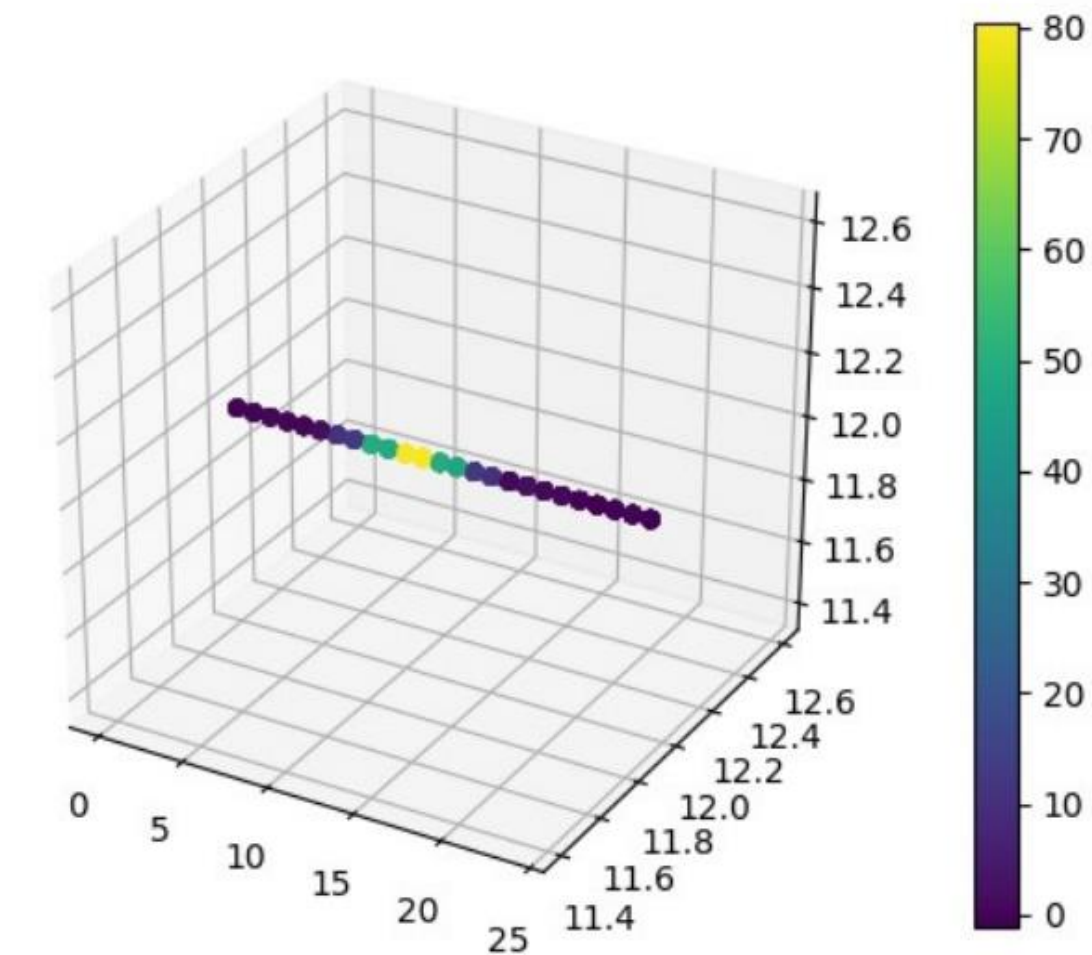
# Train procedure

- Sample noise and generate images with G
- Sample images from training dataset and train the D to recognize G data from real data
- Train combined G + D to tell you that G data it is real
- At this stage D weights are frozen.
- Back feed info to discriminator and repeat for as many epochs as needed



# Toy gaussian test

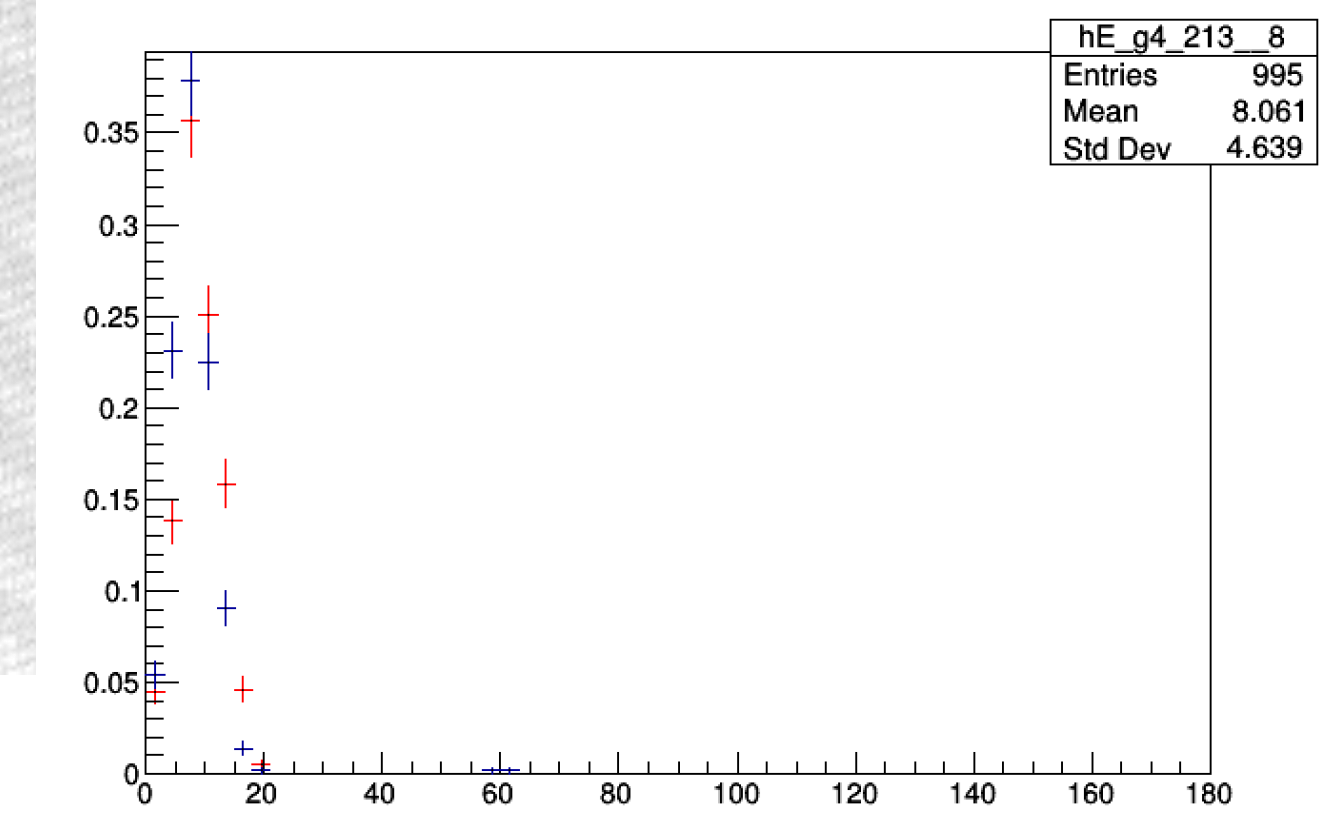
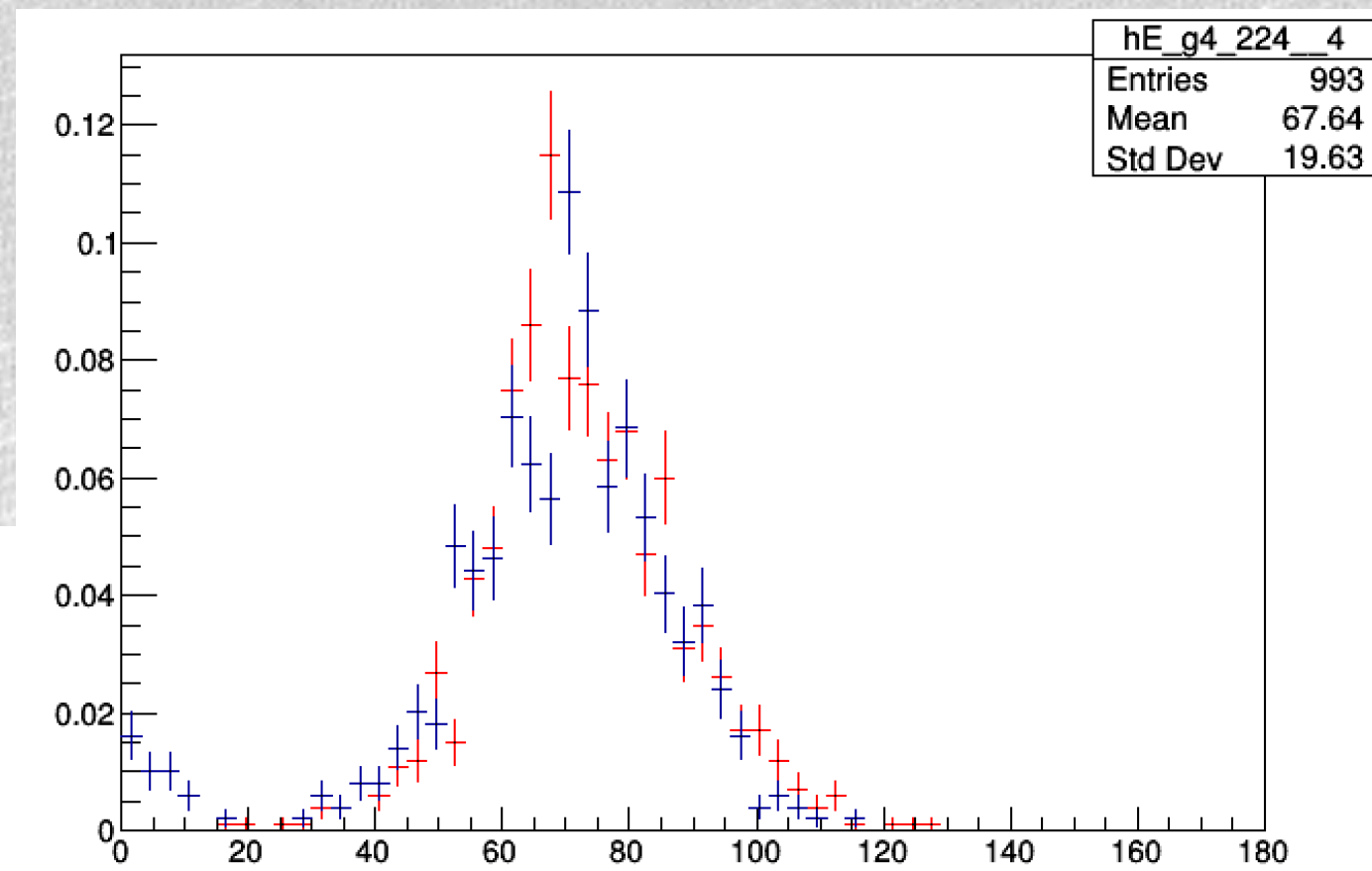
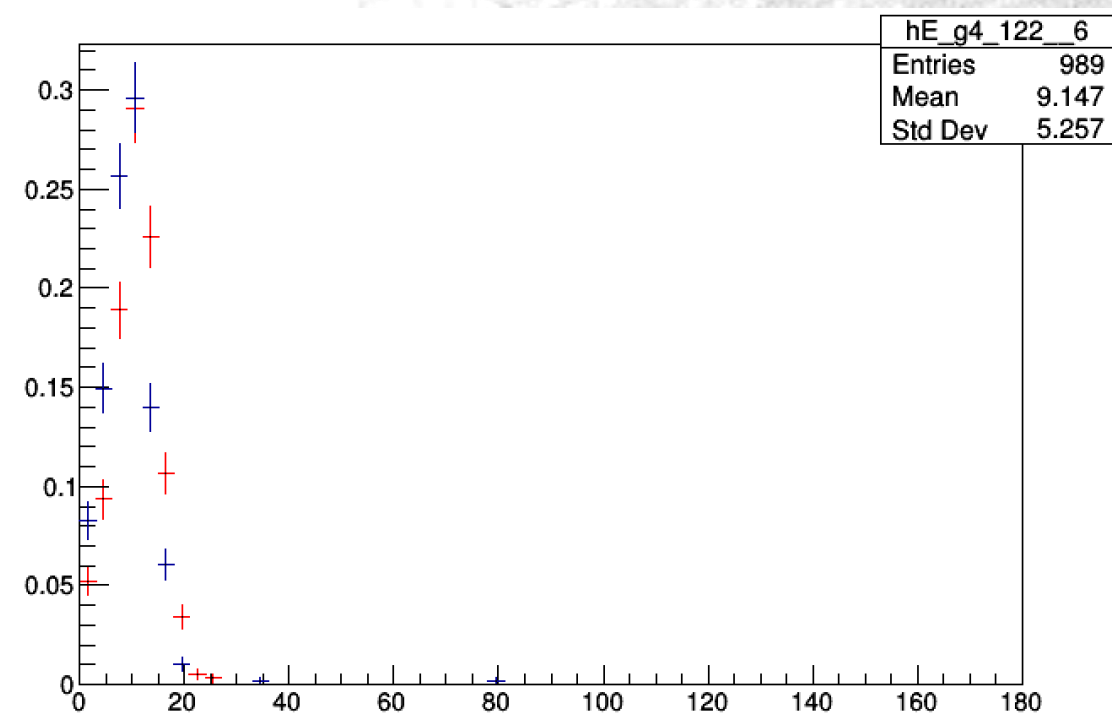
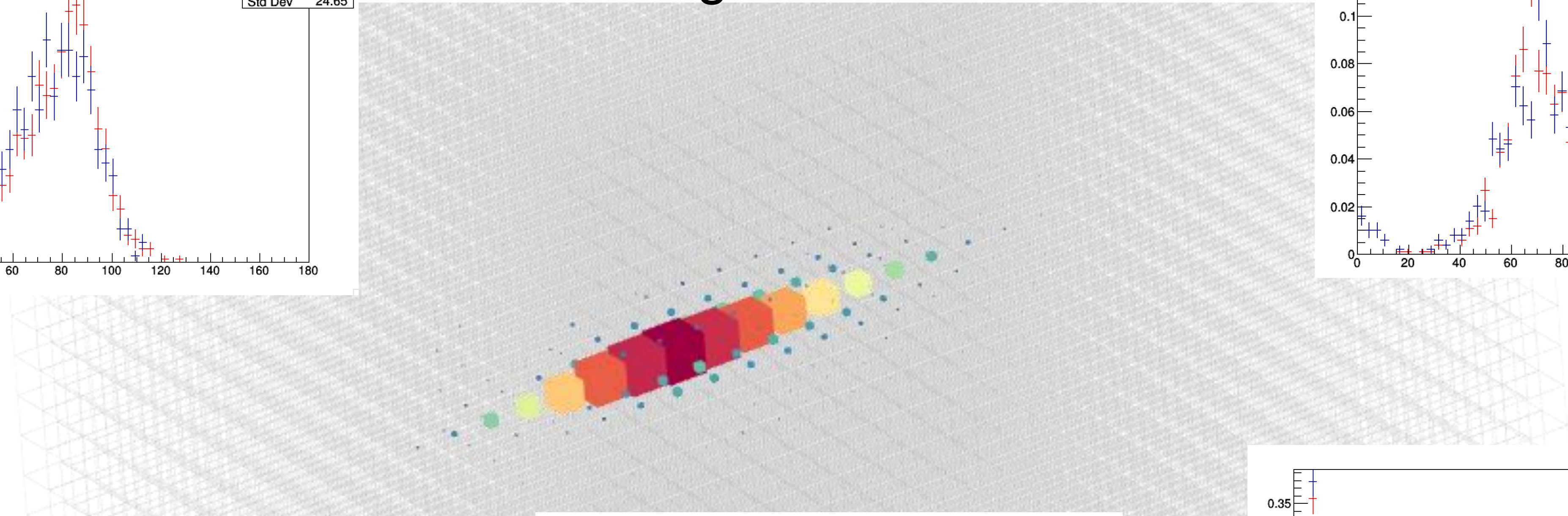
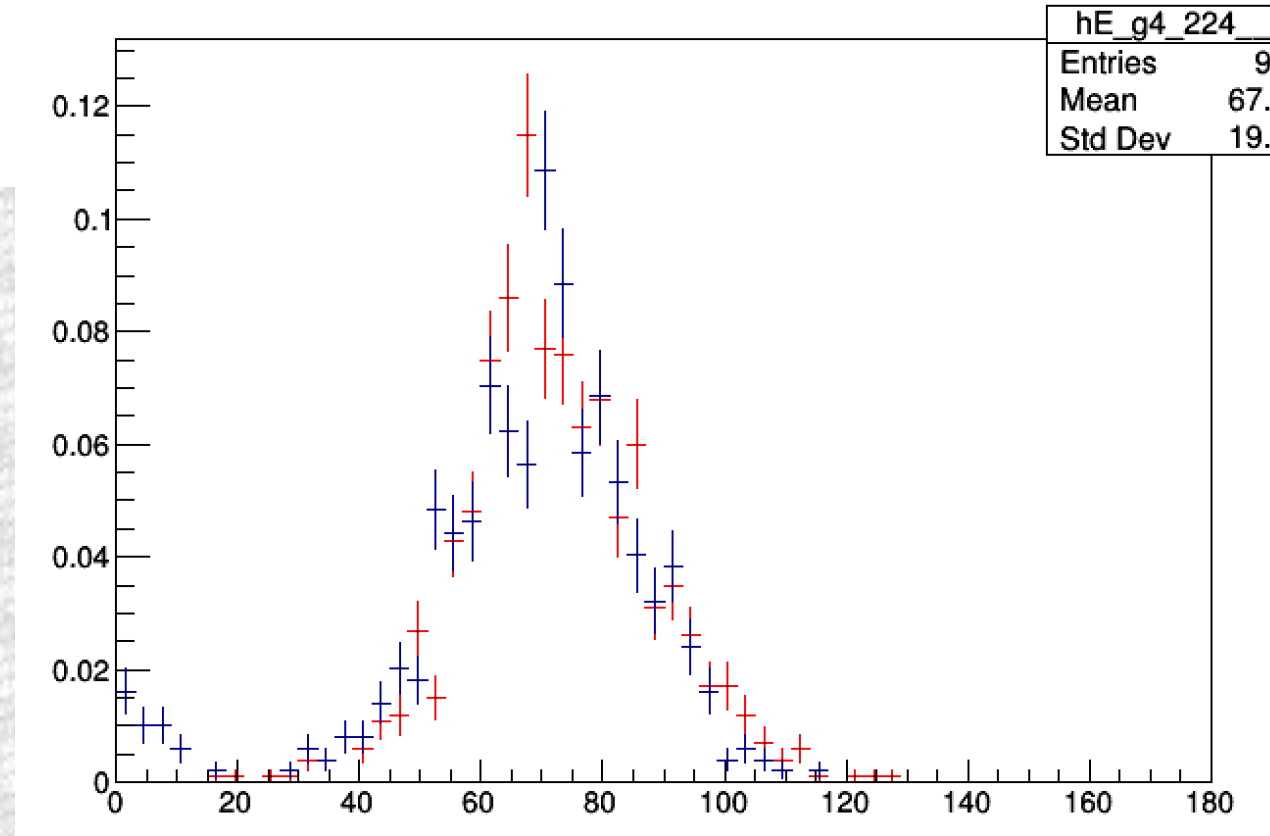
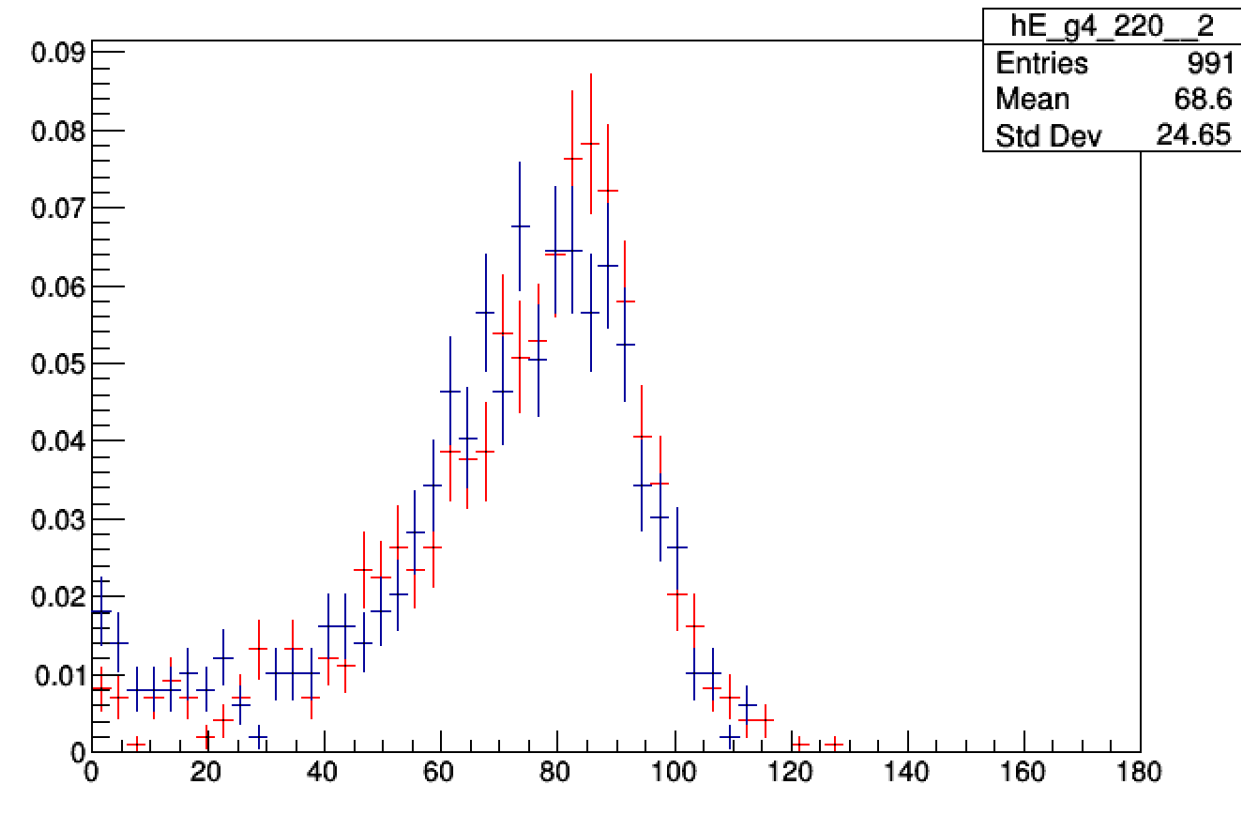
- Generate simplified 1D distribution to test GAN behavior
- Two gaussians centered at  $x=0$ .
- Fake a two classes (particles) signal
- Reproduce distribution with GAN



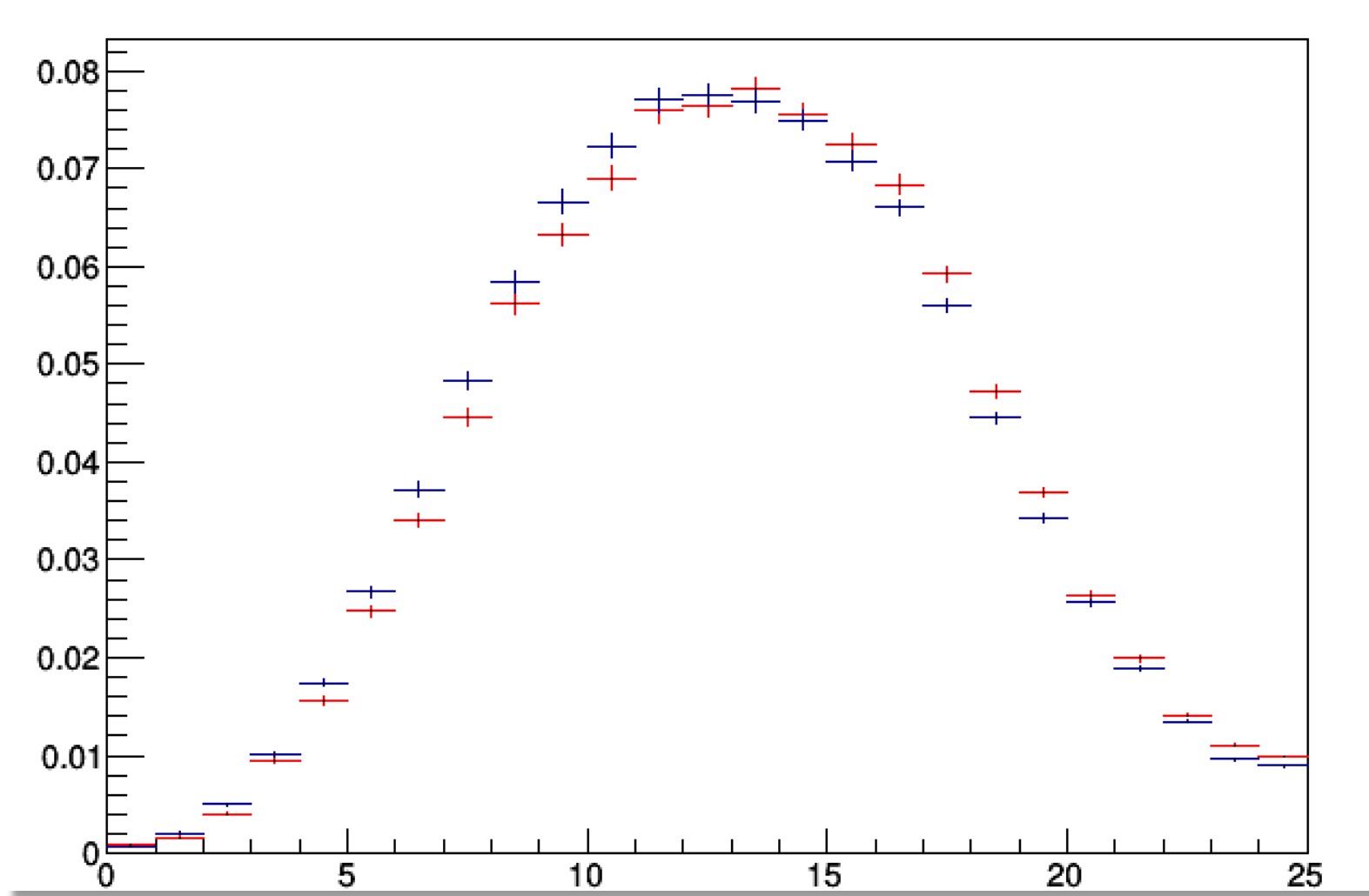


# LCD calorimeter showers

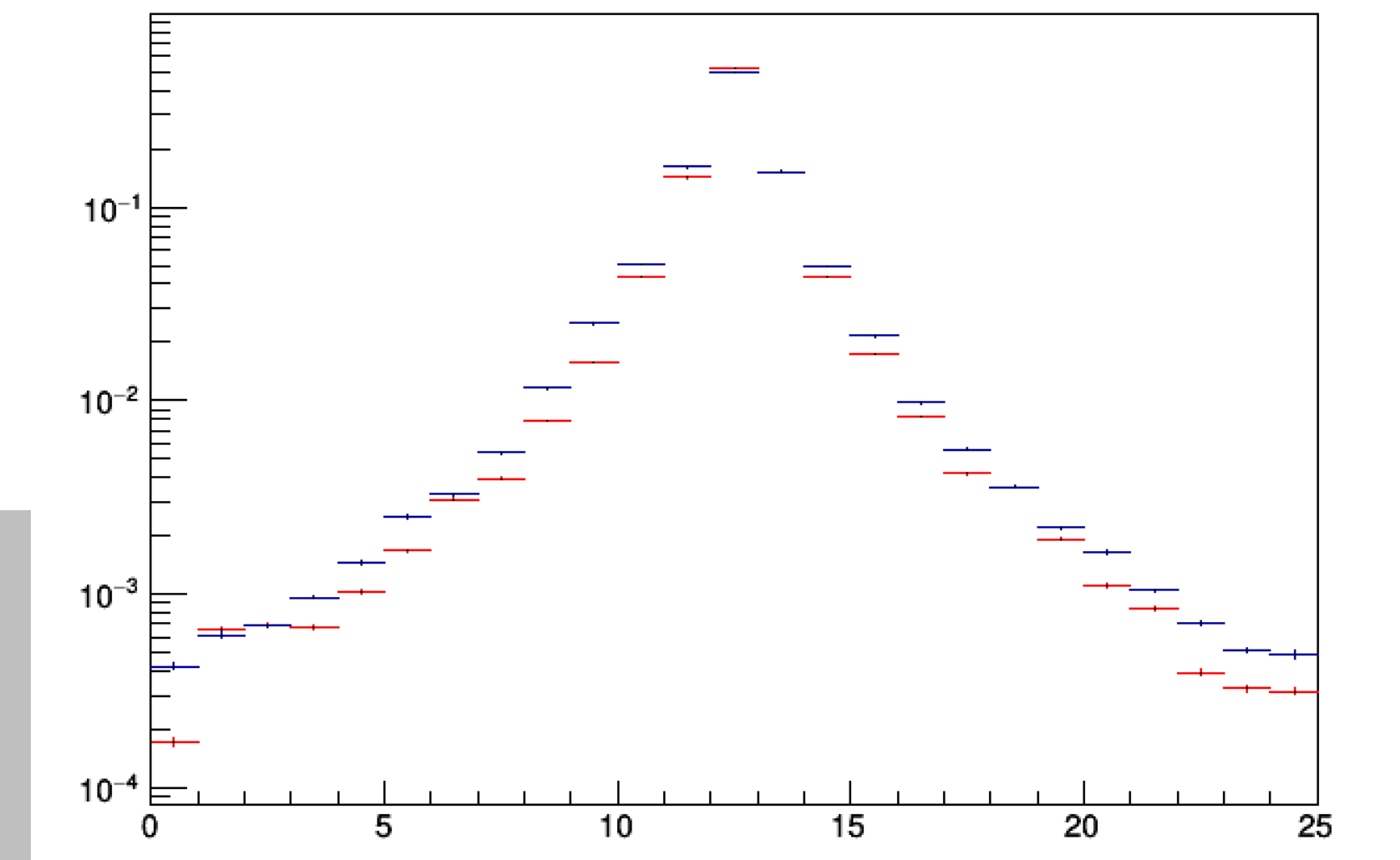
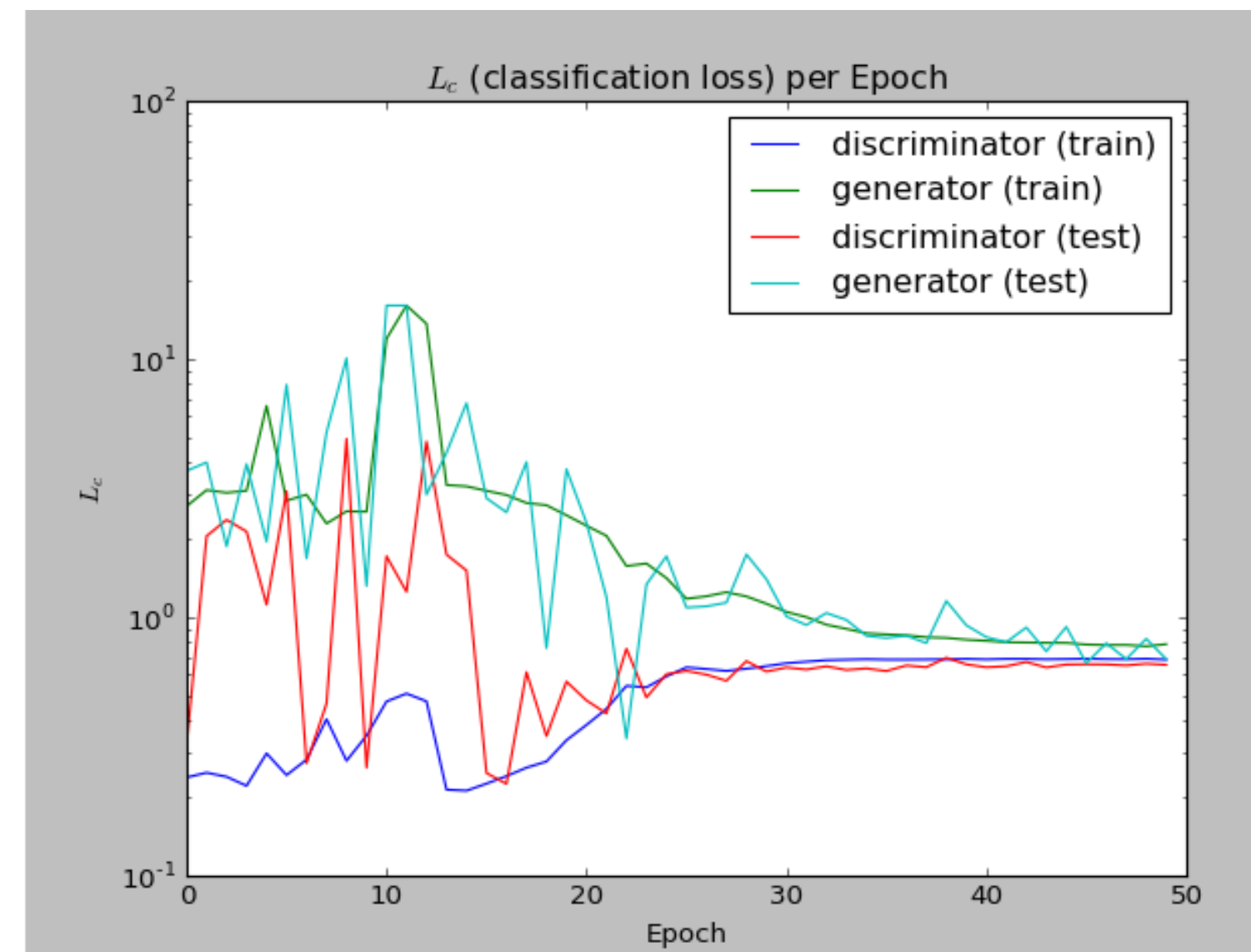
## Single electrons



# LCD calorimeter showers



Shower longitudinal section



Shower transverse section



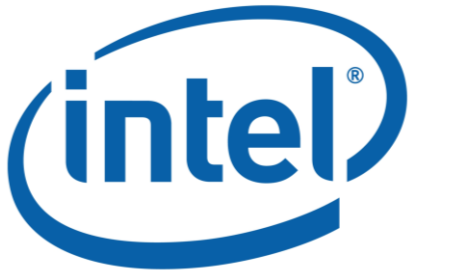
# Improving training

1 day on GTX1080

Improving performance:

- hyperparameters
- train on CPU clusters not only GPU clusters

**neon**



# neon

- new deep learning framework committed to best performance on all hardware
- designed for ease-of-use, extensibility and « out-of-the-box » scaling through multiple nodes.

<http://neon.nervanasys.com/index.html/>

# Keras/neon

## Keras

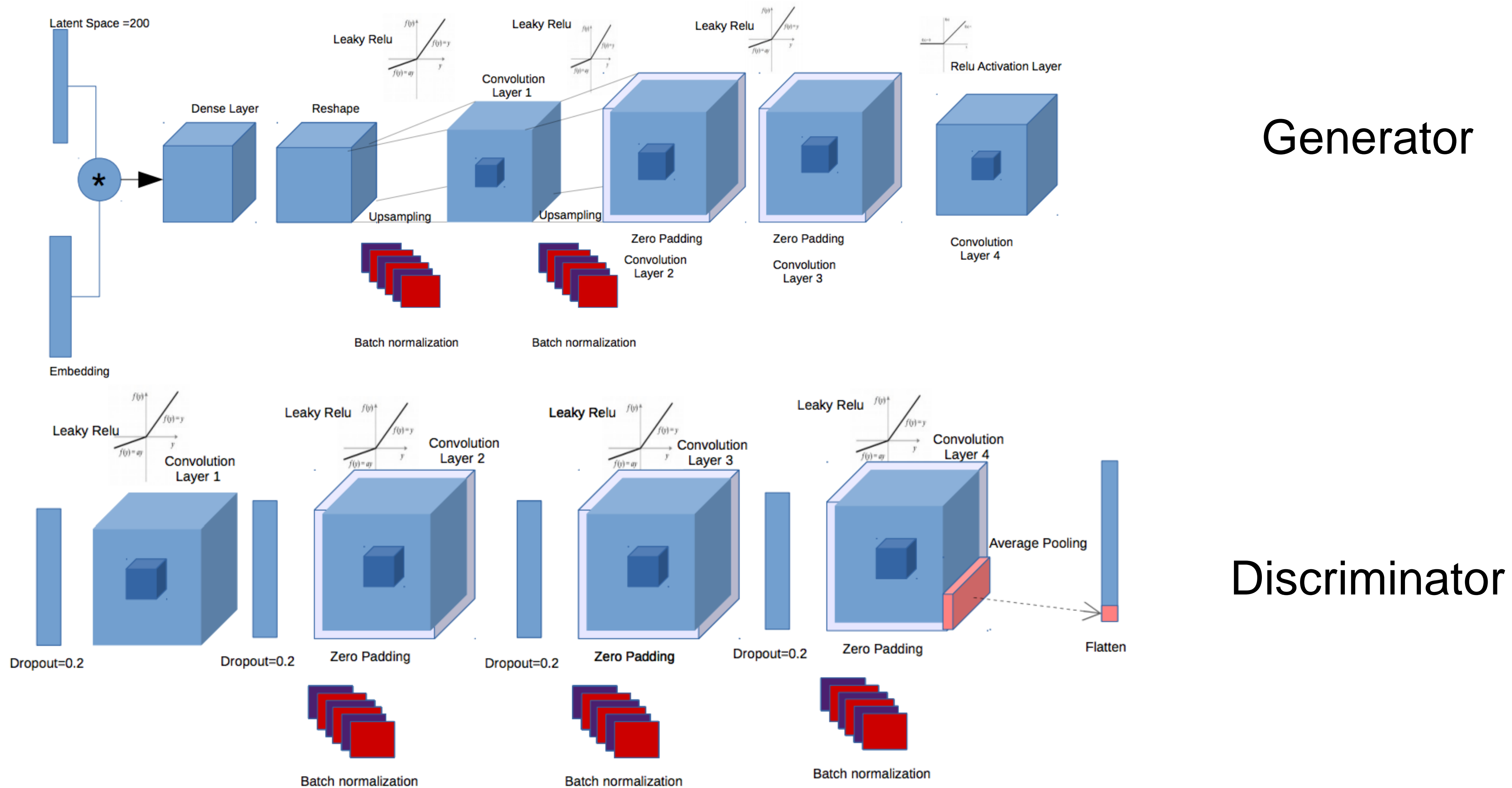
## Neon

- No 3D transpose convolutional layer:
  - Conv + Upsampling
- Transpose convolutional layer in 3D
  - GAN model is implemented

Output:  $1 + (W - F + 2P) / S$ ,  
where  $W$  - input volume,  $F$  - filter size,  $P$  - padding,  $S$  - stride

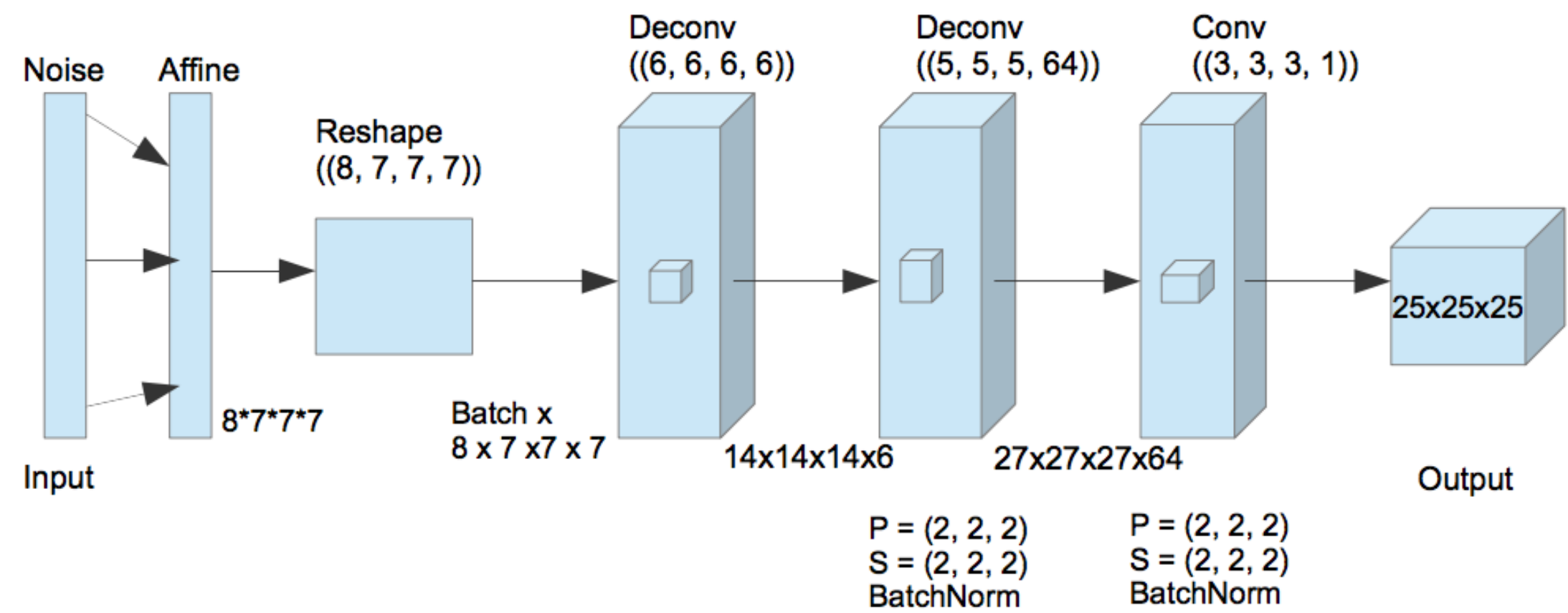
# GAN in 3D

- Generator and Discriminator are based on 3D convolutions

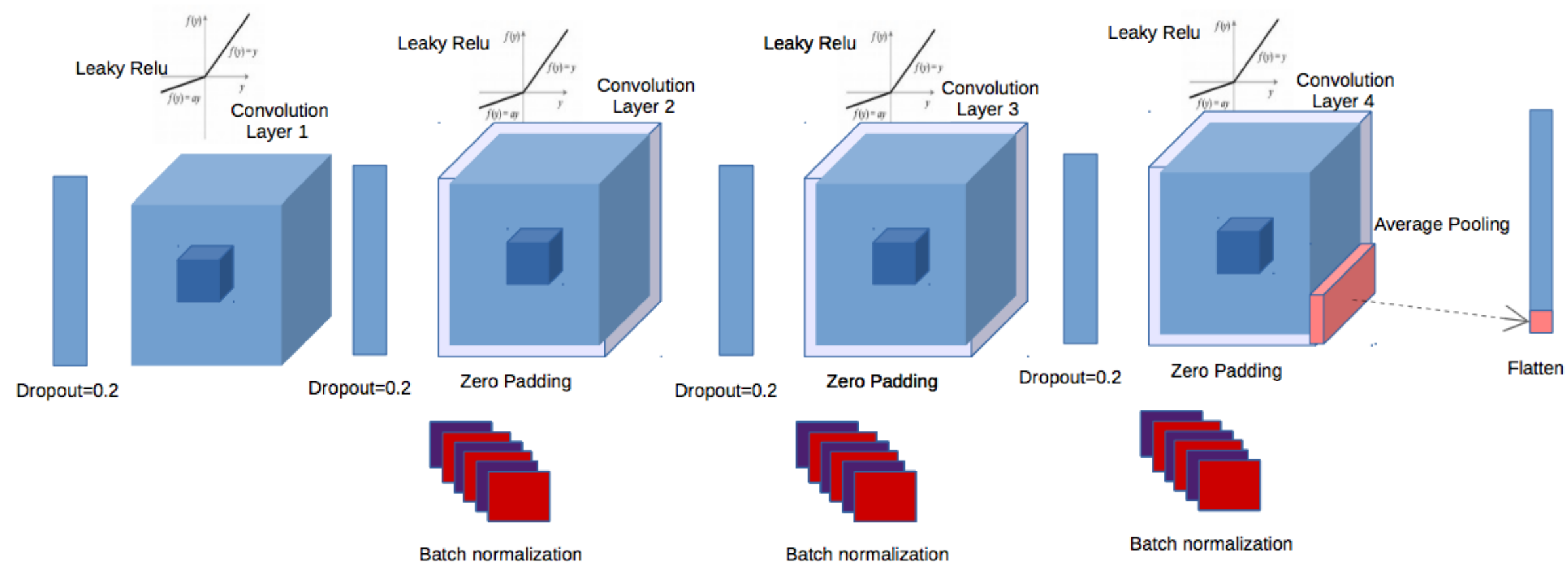




# neon model



Generator



Discriminator

# Current state

Our case is non standard and common framework might not be optimised for it: we have to work in collaboration with developers to fix issues:

- 3D deconv
- “mkl” backend
- no embedding layer

# Conclusion and plans

- keep working on implementation
- add parametrisation
- testing with different parameters on different architectures

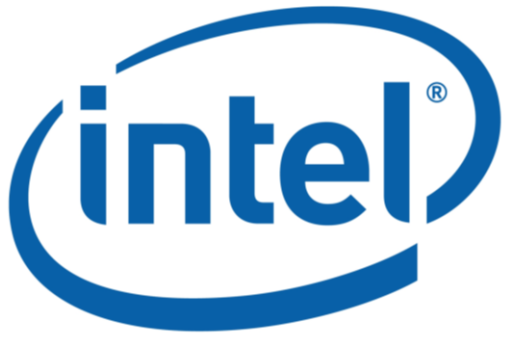
# Motivation

Historically simulation in particle physics has relied on Monte Carlo methods. Deep learning is a completely new approach.

It will allow physicist to produce a huge amount of simulated data , needed by the next high luminosity LHC experiments, using limited computing resources .



Thank you!



# Intel Competiton

## **The Modern Code Developer Challenge**

- The goal for Intel is to give budding developers the opportunity to use modern programming methods to improve code that helps move science forward.

<https://software.intel.com/en-us/articles/the-modern-code-developer-challenge>