

SIMBA – A Global Fit Approach to $|V_{ub}|$

Kerstin Tackmann

CERN



SIMBA

Florian Bernlochner (HU Berlin)
Heiko Lacker (HU Berlin)
Zoltan Ligeti (LBL)
Iain Stewart (MIT)
Frank Tackmann (MIT)
KT

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Where Can We Gain?

Room for improvement in current $|V_{ub}|$ determinations at several levels

Theoretical Treatment (see Frank's talk)

- Combination of different phase space regions
- Move away from fixed parametrizations of shape function
 - ★ Instead, systematically constrain shape from data
- Perturbative tail and RGE running of shape function

Combine all available information in one fit

- Determine $|V_{ub}|$, m_b , shape function simultaneously
 - ★ Employ strategy that proved successful for $|V_{cb}|$
- Combine different decay modes, measurements and experiments
 - ★ Different $B \rightarrow X_s \gamma$ spectra
 - ★ Different $B \rightarrow X_u \ell \nu$ partial BFs (and spectra)
 - ★ External constraints on m_b , λ_1 (from $B \rightarrow X_c \ell \nu$ or other)



Factorizing the Shape Function

[Ligeti, Stewart, F Tackmann (2008)]

Factorize nonperturbative and perturbative contributions to shape function:

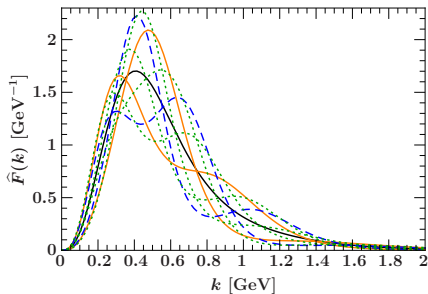
$$S(\omega, \mu_\Lambda) = \int dk \hat{C}_0(\omega - k, \mu_\Lambda) \hat{F}(k)$$

$\hat{F}(k)$ nonperturbative part

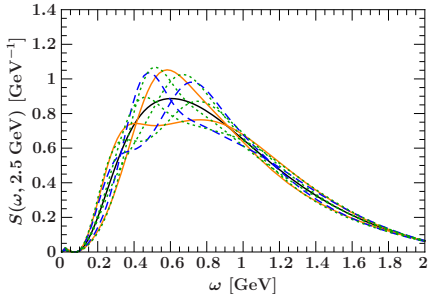
- Determine from data

$\hat{C}_0(\omega, \mu_\Lambda)$ perturbative part

- Compute



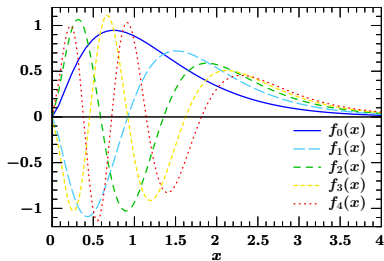
\Downarrow



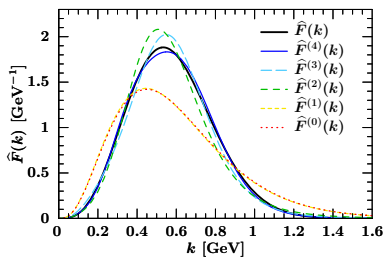


Basis Expansion for $\widehat{F}(k)$

Basis



Expansion of Gaussian $\widehat{F}(k)$



Design suitable orthonormal basis for $\widehat{F}(k)$ (formally model independent)

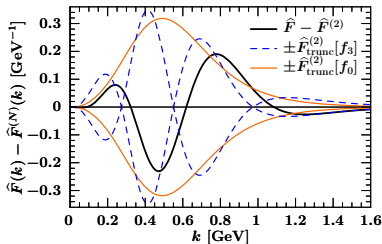
$$\widehat{F}(\lambda x) = \frac{1}{\lambda} \left[\sum_{n=0}^{\infty} c_n f_n(x) \right]^2 \quad \text{with} \quad \int dk \widehat{F}(k) = \sum_{n=0}^{\infty} c_n^2 = 1$$

- Builds an orthonormal basis on top of any given model function
- Keep terms up to $n \leq N$ as required by precision of data
- Experimental uncertainties and correlations can be properly captured by uncertainties and correlations in basis coefficients c_n

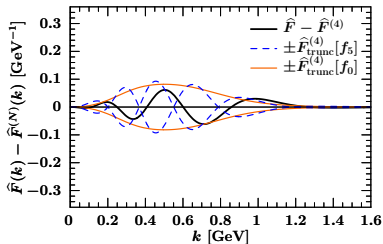


Estimating Residual Model Dependence

Truncation error at $N = 2$



Truncation error at $N = 4$



Truncating series at $n \leq N$ introduces residual dependence on basis model

- Overall size of truncation error scales with $1 - \sum_{n=0}^N c_n^2$
- Can test expansion by varying N and underlying basis model
- Choose final N so that truncation error is small compared to experimental uncertainties in coefficients

⇒ Allows for systematic, fully data driven SF uncertainties



Getting the Inputs: Stumbling Blocks

Dealing with experimental cuts

- $B \rightarrow X_u \ell \nu$ partial BF for $E_{\text{cut}} < E_\ell^{\text{r}} < 2.6 \text{ GeV}$
- Impossible for theory to calculate

Dealing with experimental correlations

- Correlations missing for many sets of partial BFs and spectra
 - ★ *BABAR* leptonic tag $B \rightarrow X_s \gamma$ spectrum, E_ℓ^{r} partial BFs, Belle hadronic tag partial BFs, ...
 - ★ This excludes a lot of valuable inputs

Dealing with experimental smearing

- Cannot use spectra if significantly affected by efficiency and resolution

Wishlist for experimental results

- Correlations between partial branching fractions and spectra
- Efficiency and resolution matrices/corrections for spectra



What I am showing is work in progress

- Some theory parts **still missing** from fit
- **No** theoretical uncertainties or correlations yet

⇒ What follows is a proof-of-concept
(central values and uncertainties subject to change)



$B \rightarrow X_s \gamma$: Fitting for the Shape Function

Experimental inputs

- Belle 605 fb^{-1}
 - ★ Thanks to Belle, especially Antonio Limosani, for providing the covariance matrix, experimental efficiency and resolution!
 - ★ Efficiency and resolution effects folded into theory predictions
- $BABAR$ sum-over-exclusive-modes (80 fb^{-1})
- $BABAR$ hadronic tag (210 fb^{-1})

First test: convergence of expansion ($\lambda = 0.5 \text{ GeV}$)

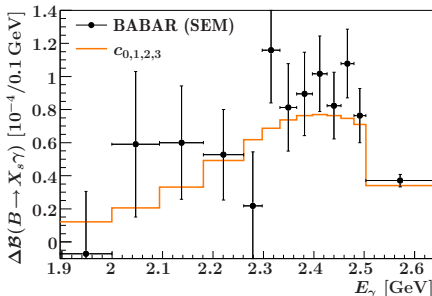
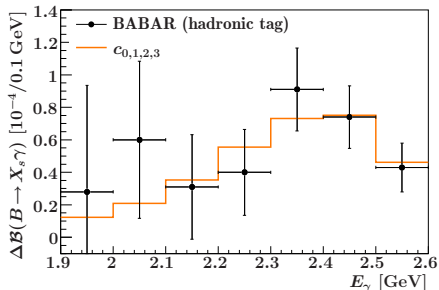
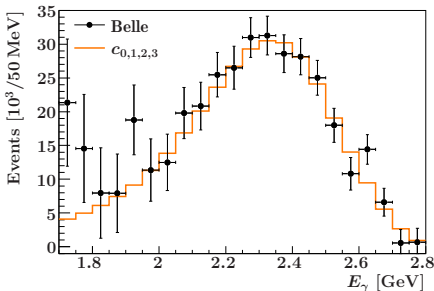
	4 coefficients	5 coefficients
c_0	0.987 \pm 0.008	0.986 \pm 0.009
c_1	0.150 \pm 0.034	0.152 \pm 0.034
c_2	0.052 \pm 0.044	0.057 \pm 0.058
c_3	0.025 \pm 0.061	0.026 \pm 0.062
c_4		0.009 \pm 0.068



$B \rightarrow X_s \gamma$: Fitting for the Shape Function

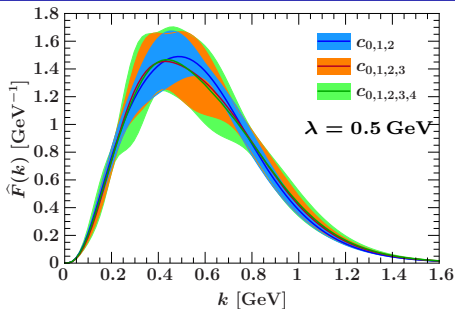
Fit for 4 coefficients

- χ^2 fit including experimental correlations
- Fits validated with pseudo experiments



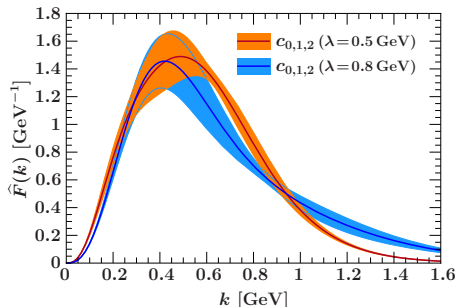
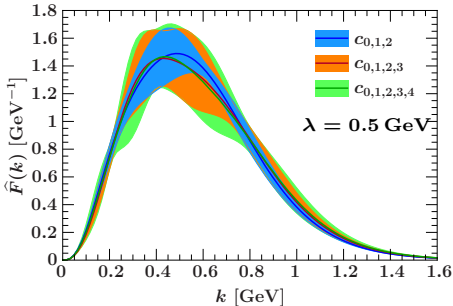
$B \rightarrow X_s \gamma$: Fitting $\hat{F}(k)$ from Data

- $\hat{F}(k)$ with different number of coefficients consistent and converging



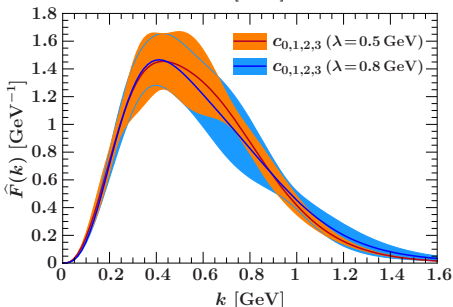
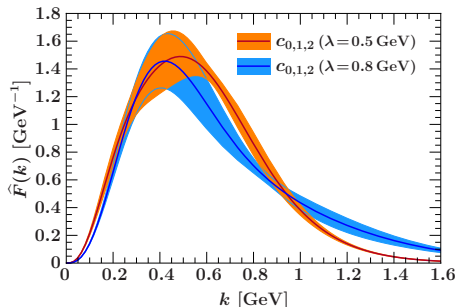
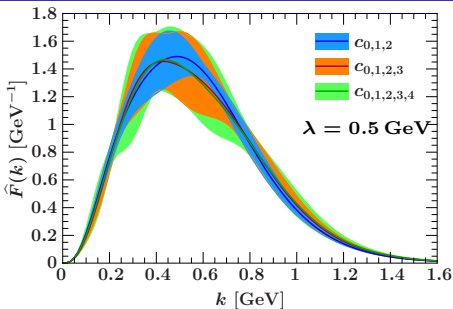
$B \rightarrow X_s \gamma$: Fitting $\hat{F}(k)$ from Data

- $\hat{F}(k)$ with different number of coefficients consistent and converging
- Different bases help to determine truncation error



$B \rightarrow X_s \gamma$: Fitting $\hat{F}(k)$ from Data

- $\hat{F}(k)$ with different number of coefficients consistent and converging
- Different bases help to determine truncation error
 - ★ Here: need 4 coefficients for consistency between bases



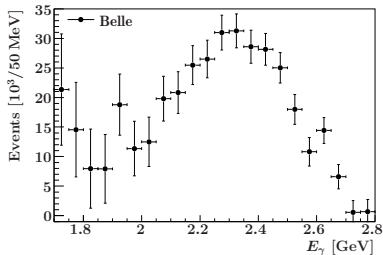
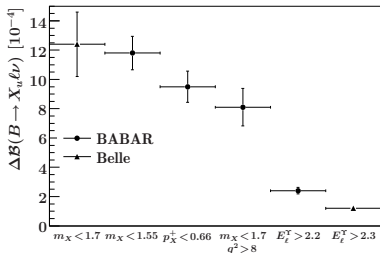


Combining All Inputs: Fitting for $|V_{ub}|$

As proof-of-concept, fit to

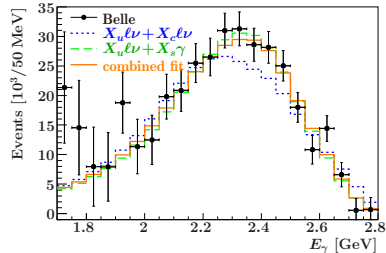
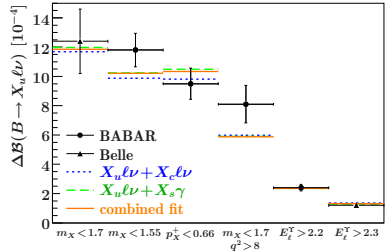
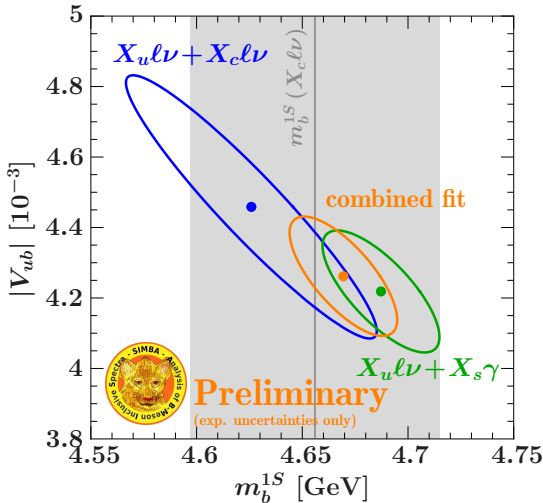
- $B \rightarrow X_u l \nu$ hadronic tag
 - ★ BABAR: $m_X, m_X - q^2, p_X^+$
 - ★ Belle: m_X
- $B \rightarrow X_u l \nu$ lepton endpoint
 - ★ BABAR: $E_\ell^{\text{r}} > 2.2 \text{ GeV}$
 - ★ Belle: $E_\ell^{\text{r}} > 2.3 \text{ GeV}$
- 3 $B \rightarrow X_s \gamma$ spectra
- m_b^{1S}, λ_1 from $B \rightarrow X_c l \nu$
 - ★ Global fit in 1S scheme (fresh from Christoph's talk)
$$m_b^{1S} = (4.66 \pm 0.05) \text{ GeV}$$

$$\lambda_1 = (-0.34 \pm 0.05) \text{ GeV}^2$$





Combining All Inputs: Fitting for $|V_{ub}|$



• No theory uncertainties yet

Wrong E_γ spectrum without $B \rightarrow X_s \gamma$



Conclusions

- Successfully combine partial BFs in $B \rightarrow X_u \ell \nu$, photon spectra from $B \rightarrow X_s \gamma$ and constraints from $B \rightarrow X_c \ell \nu$ to determine $|V_{ub}|$ as well as the shape of the shape function
- What I showed is work in progress, expect details to change
- Competitive experimental uncertainties on both $|V_{ub}|$ and m_b
- Theoretical uncertainties forthcoming
 - ★ Parametric uncertainties (m_b , SF) already included!
- Hardly any gain from m_b and λ_1 constraints from $B \rightarrow X_c \ell \nu$ thanks to new Belle $B \rightarrow X_s \gamma$ spectrum
- First attempt to determine SF shape beyond first moments from data
 - ★ Allows for rigorous treatment of SF uncertainties in $|V_{ub}|$



Backup



Setup for Global $|V_{ub}|$ Fit

Use expansion $\widehat{F}(k) = [\sum_n c_n f_n(k)]^2$:

$$d\Gamma(s\gamma) = |V_{td}V_{ts}^*|^2 \sum_{n,m} c_n c_m K(E_\gamma) \int dk \widehat{W}_{\text{pert}}(E_\gamma, k) f_n(k) f_m(k)$$

$$d\Gamma(u\ell\nu) = |V_{ub}|^2 \sum_{n,m} c_n c_m K(E_\ell, p_X^\pm) \int dk \widehat{W}_{\text{pert}}(p_X^\pm, k) f_n(k) f_m(k)$$

$$M_j(m_b^{1S}, \lambda_1^i) = \sum_{n,m} c_n c_m \int dk k^j f_n(k) f_m(k)$$

Perform combined fit (similar to $|V_{cb}|$)

- $B \rightarrow X_u \ell \nu$ partial rates
 - ★ Normalization determines $|V_{ub}|$
- $B \rightarrow X_s \gamma$ and $B \rightarrow X_u \ell \nu$ spectra
 - ★ Shapes of distributions constrain $\widehat{F}(k)$ through basis coefficients c_n
- Known moments of $\widehat{F}(k)$
 - ★ Consistently combines existing constraints on m_b^{1S} , λ_1^i (from $B \rightarrow X_c \ell \nu$ or anywhere else) with $B \rightarrow X_u \ell \nu$ and $B \rightarrow X_s \gamma$ data