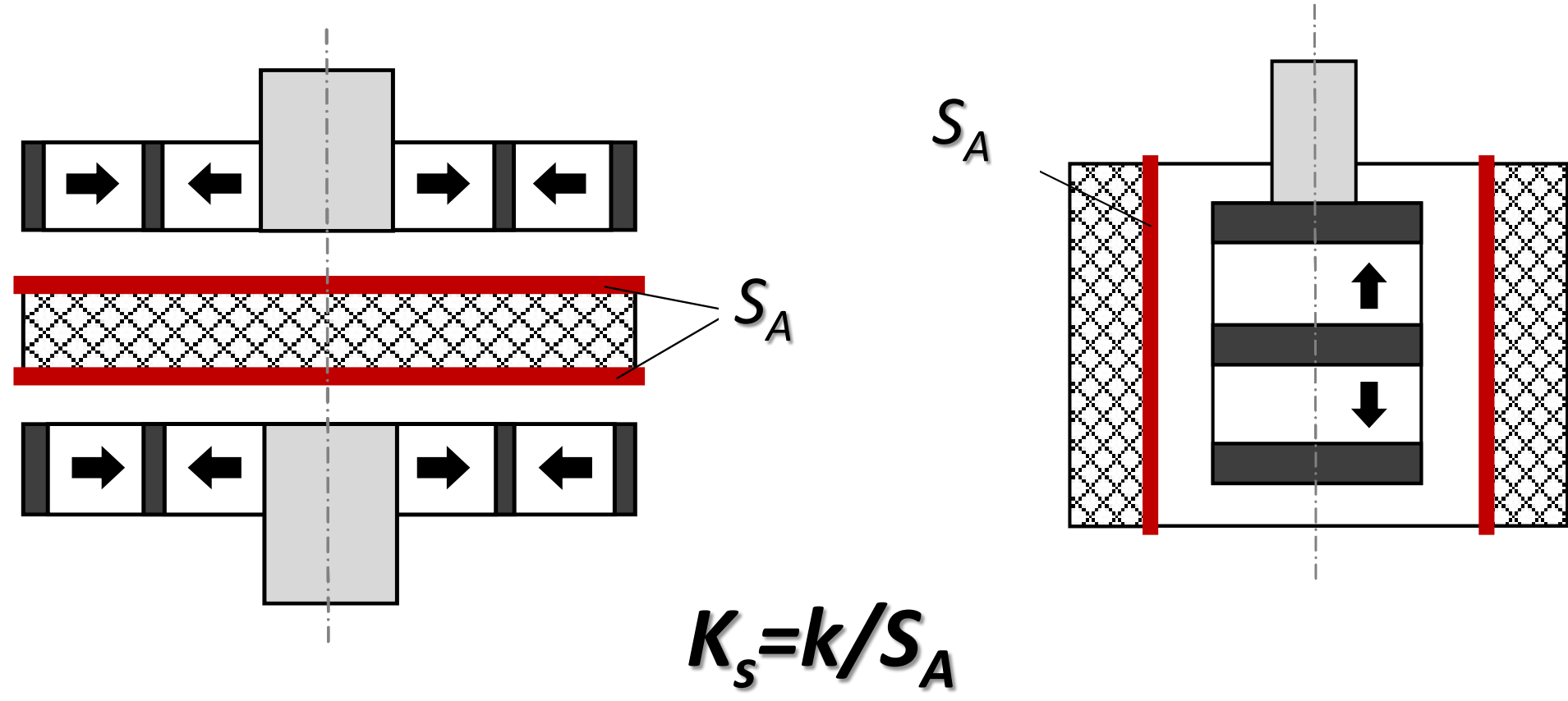


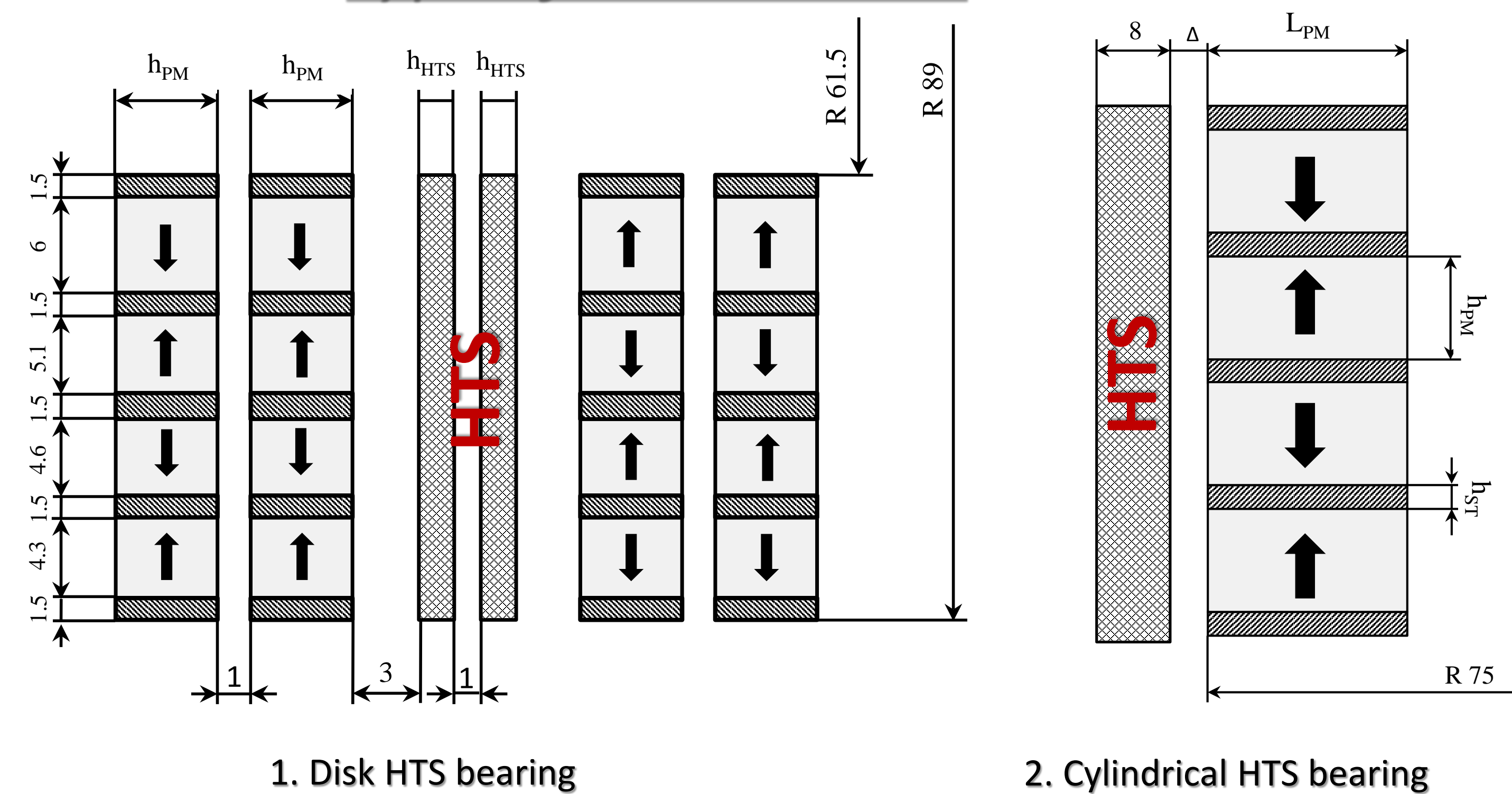
### Specific stiffness



$$K_s = k/S_A$$

where  $k$  – stiffness of the bearing,  $S_A$  – active surface of the HTS (surface acting with permanent magnets)

### Type of construction



1. Disk HTS bearing

2. Cylindrical HTS bearing

1.

$h_{HTS}$ , mm	$h_{PM}$ , mm	Specific axial stiffness, N/(mm*cm <sup>2</sup> )	Specific radial stiffness, N/(mm*cm <sup>2</sup> )
2	4	0.70	0.45
2	8	1.07	0.71
3	4	0.81	0.41
3	8	1.23	0.63
4	4	0.85	0.39
4	8	1.29	0.40

2.

$L_{PM}$ , mm	$h_{PM}/h_{ST}$ , mm	Specific axial stiffness, N/(mm*cm <sup>2</sup> )	Specific radial stiffness, N/(mm*cm <sup>2</sup> )
15	6/2	1.76	0.95
15	8/3	2.06	1.06
15	12/4	2.19	0.90
15	16/5	2.08	0.80
20	6/2	1.99	1.09
20	8/3	2.42	1.14
20	12/4	2.66	1.11
20	16/5	2.63	1.02
25	6/2	2.10	1.17
25	8/3	2.69	1.35
25	12/4	3.00	1.16
25	16/5	3.07	1.22

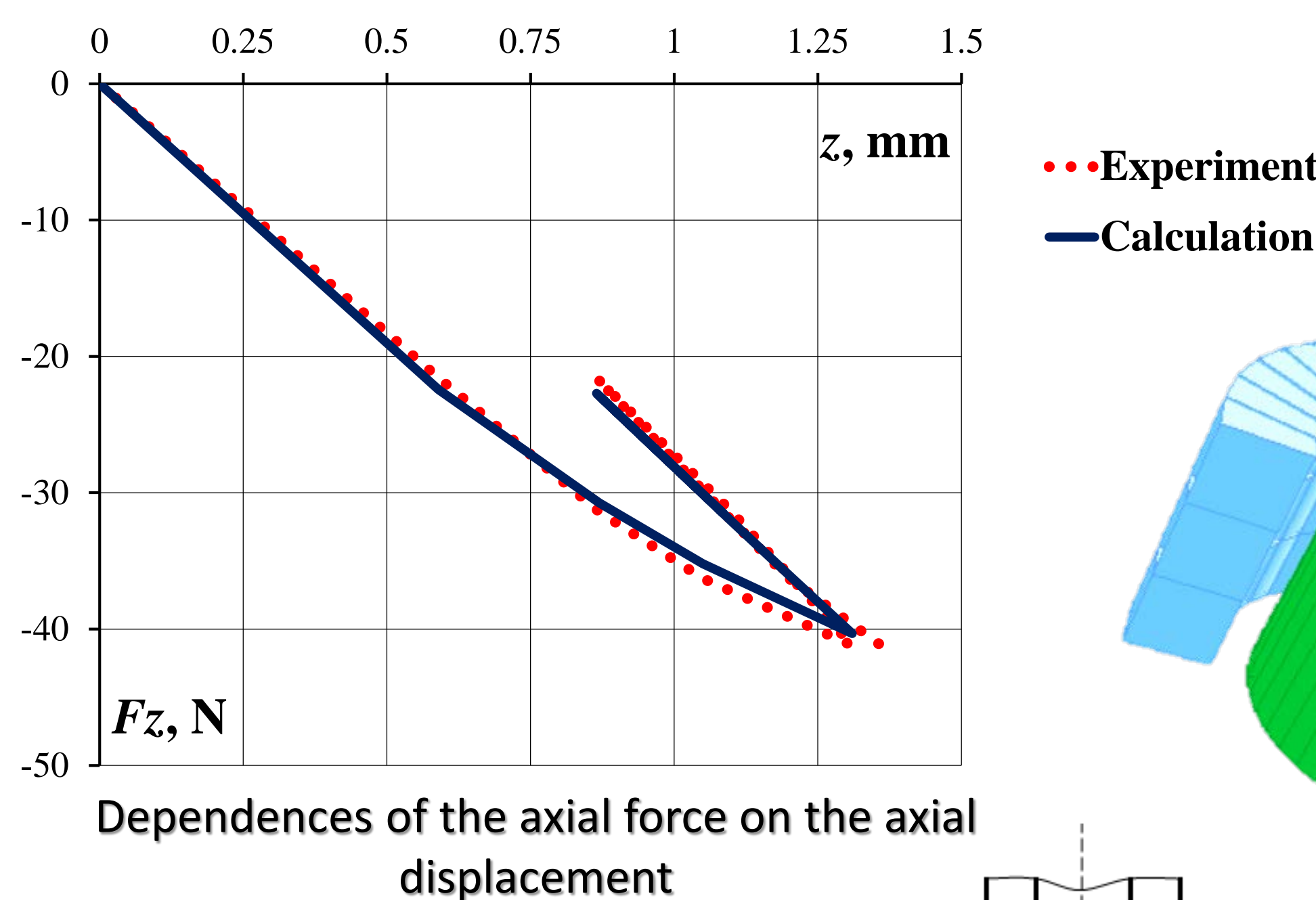
### Conclusion

Theoretical research of the specific parameters of HTS bearing was performed by 3-D analysis of electromagnetic field. Applied method was confirmed by the study of the prototype of HTS bearing.

Two types of HTS bearing with disk and cylindrical superconducting stator were considered. Calculations show the influence of shape of the steel elements in magnetic system of the rotor and the possibility to increase the stiffness of HTS bearing. Also the results of the research confirm the effectiveness of HTS bearing with inner rotor, which may be useful in high speed flywheels.

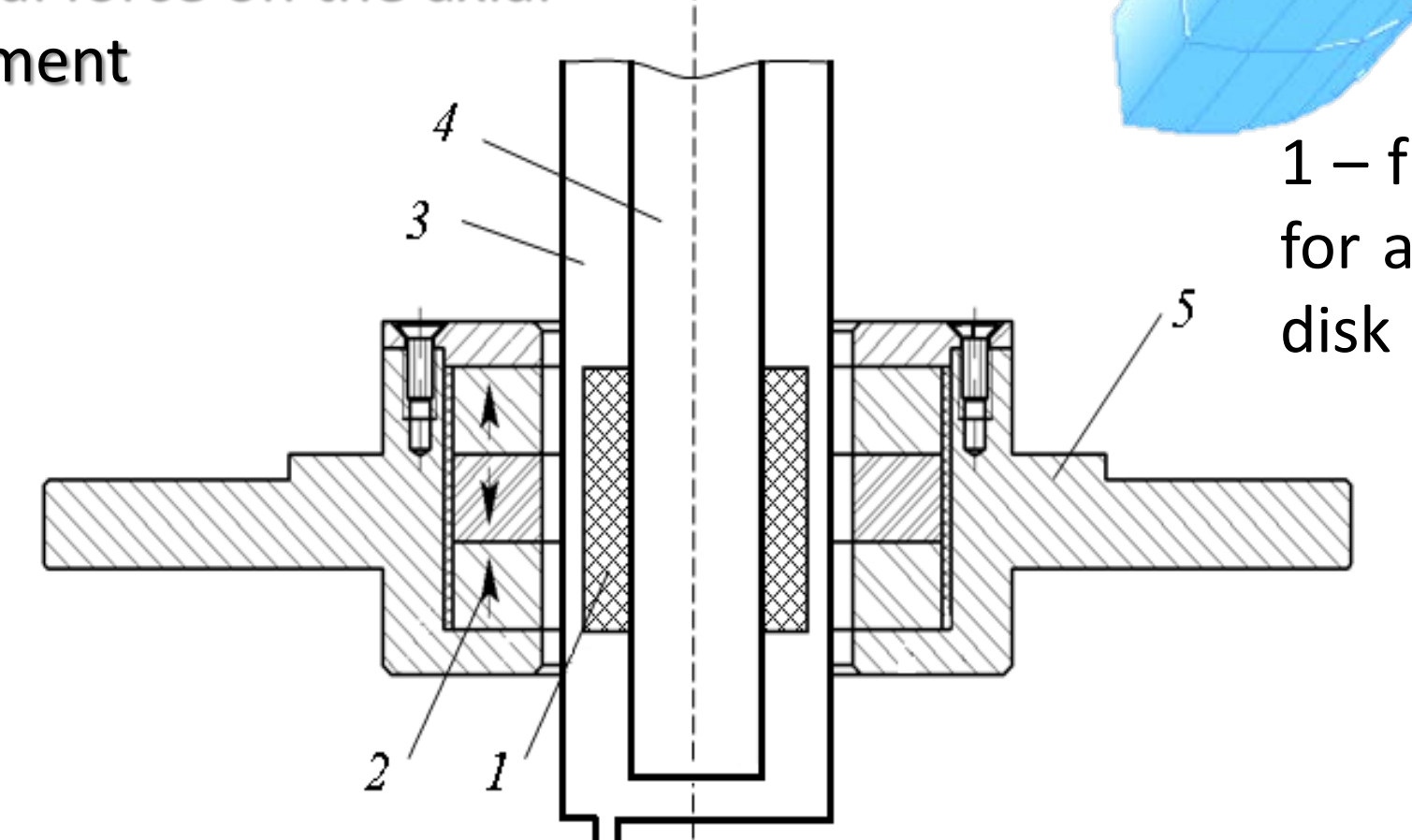
Quantitative evaluation of the specific stiffness for different constructions allows to effectively select the HTS bearing for any device with magnetic suspension.

### Calculation and experiment of the HTS bearing

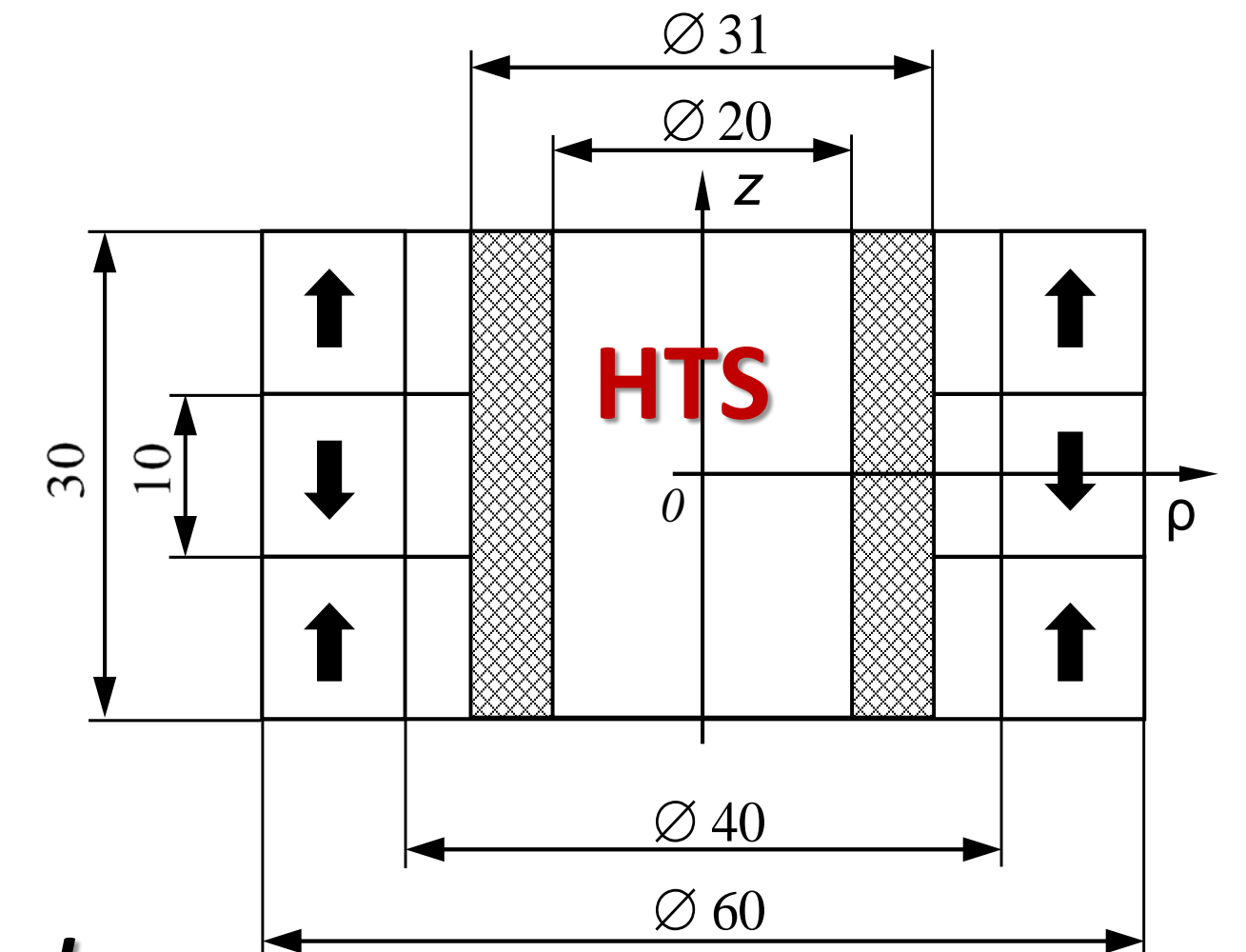


Prototype of HTS bearing

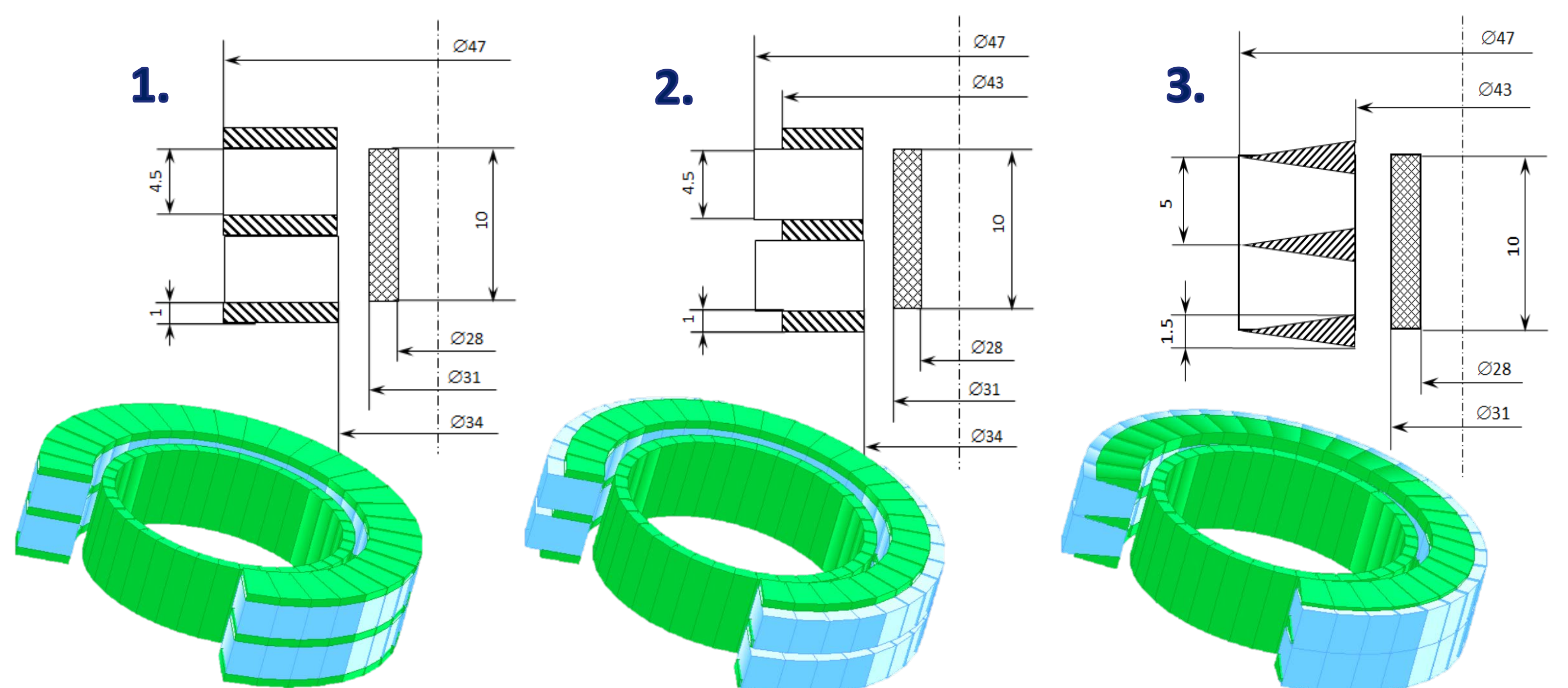
1 – fixed base, 2 – cooling system, 3 – cooper rings for axial load during experiment, 4 – non-magnetic disk (rotor), 5 – motion sensor



1 – HTS rings (stator), 2 – permanent magnets (rotor), 3 – vacuum insulation, 4 – cooling system, 5 – non-magnetic disk

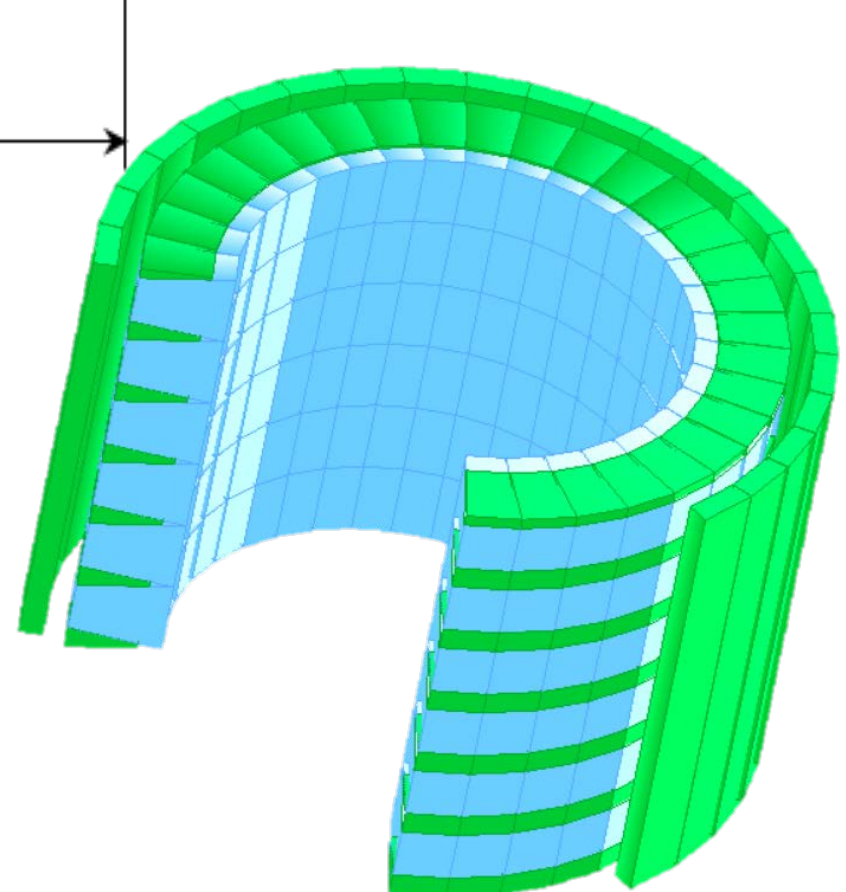
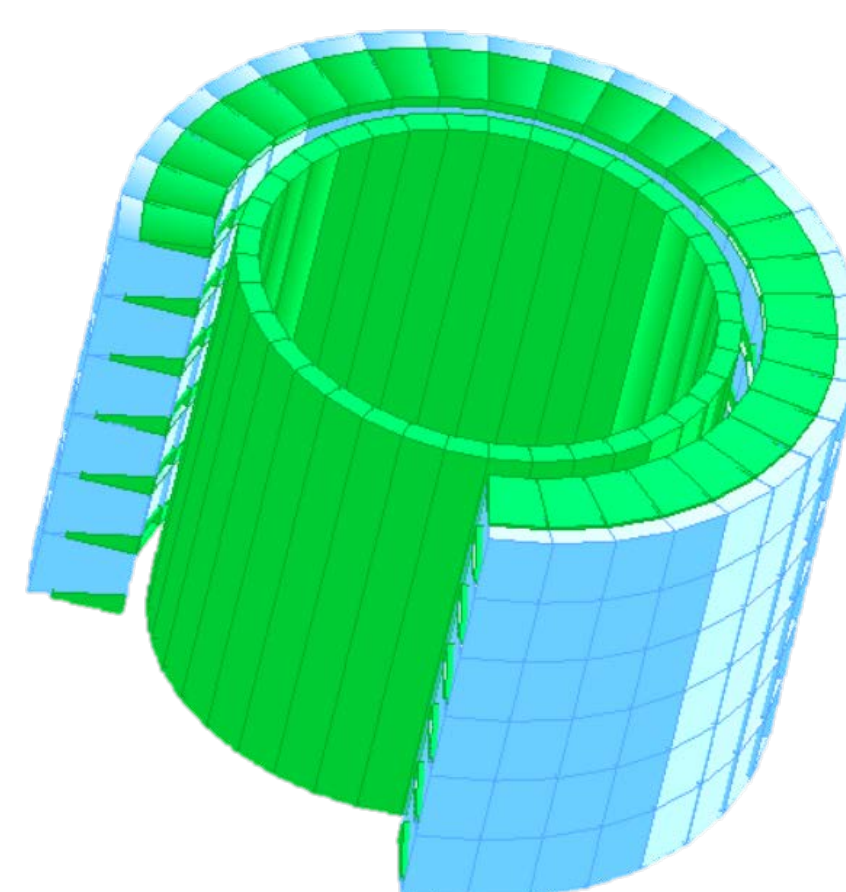
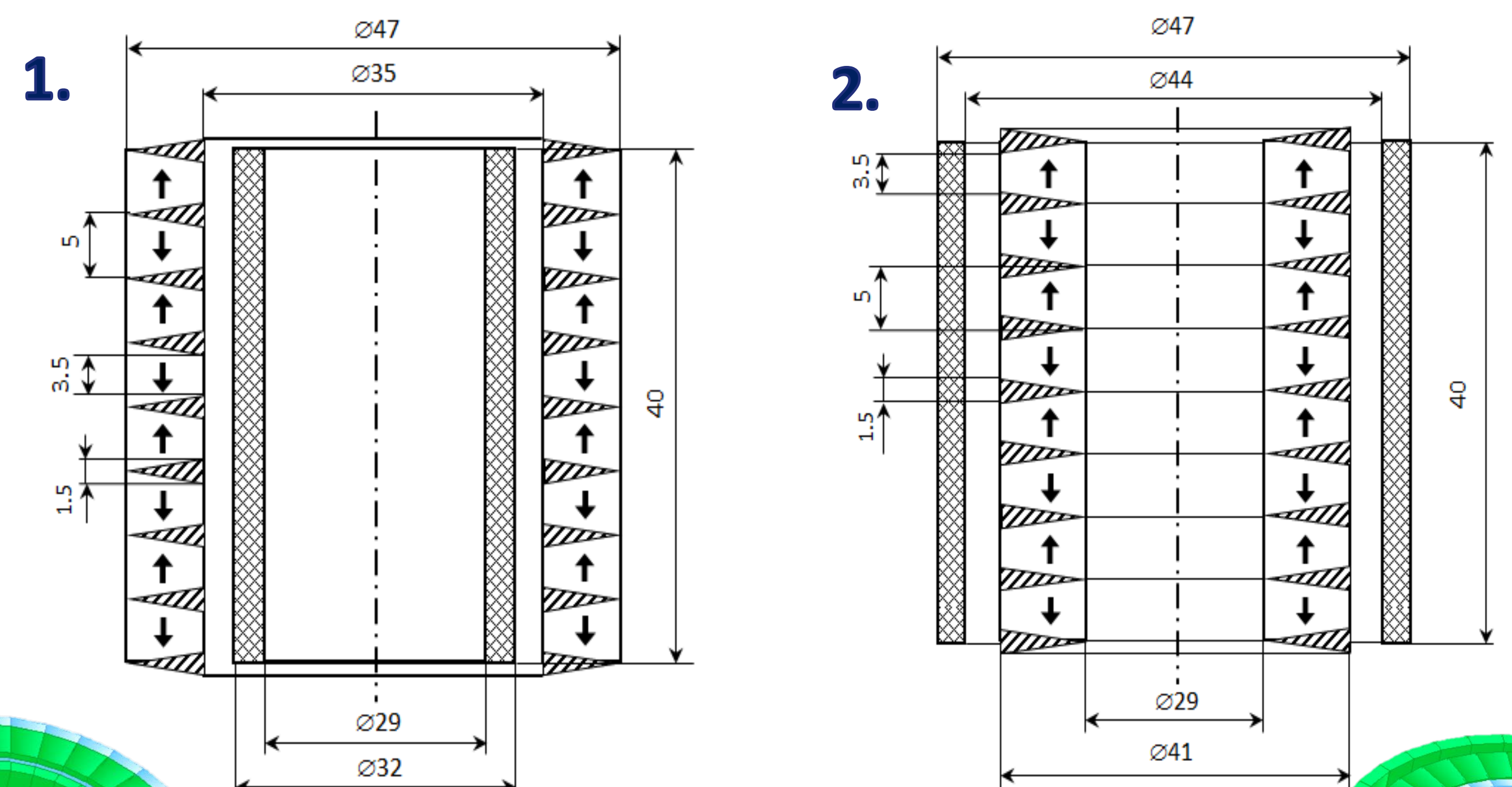


### Shape of the steel elements



Type of the steel elements	Specific axial stiffness, N/(mm*cm <sup>2</sup> )	Specific radial stiffness, N/(mm*cm <sup>2</sup> )
1. Square	2,4	1,64
2. Short square	2,65	1,92
3. Triangular	2,79	1,94

### Inner and outer stator



Type	Specific axial stiffness, N/(mm*cm <sup>2</sup> )	Specific radial stiffness, N/(mm*cm <sup>2</sup> )
1. Inner stator	2.98	1.94
2. Outer stator	2.84	1.86