

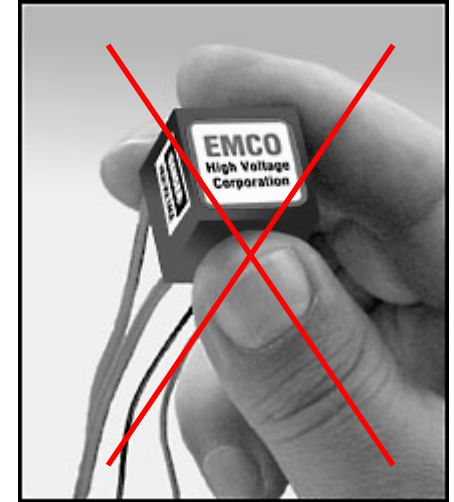


Development of μ HV miniature HV supplies

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Why developing HV power supplies?

- ◆ Putting dedicated HV units in the vicinity of a detector
 - Avoiding long HV cabling
- ◆ Commercially available HV supplies are not suited for this
 - Often too bulky
 - May use iron based transformers
 - => do not operate in a magnetic field
 - Not radhard
 - Mostly designed to deliver substantial power (1 W or more) where powers in the mW region are needed
 - Mostly no trip level in the nA region
- ◆ Need for dedicated HV supplies for HEP detectors



Concept

- ◆ As small as possible
- ◆ Limited output power
- ◆ Small input power (< few mW idle mode)
- ◆ Very radhard (until 1000 Mrad, 10^7 Gy)
- ◆ Minimal noise emittance
- ◆ Output voltage stabilization, low ripple
- ◆ High resolution current measurement (< 1 nA resolution)
- ◆ Adjustable trip level in the nA region
- ◆ External communication like at CAN bus

Two designs for different applications

1. Larger unit, but easy to operate
 - Small scale physics experiments (lab, test beams)
 - In progress: lab version 50 – 500V
 - SHV out

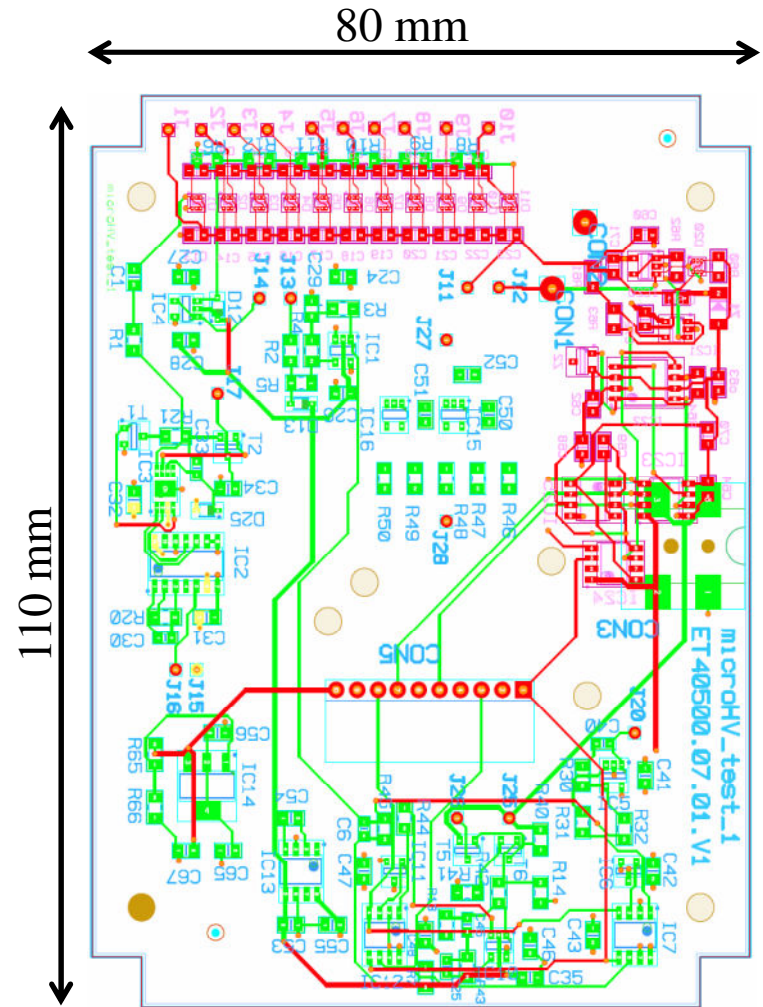
 2. “As small as possible” unit for big scale HEP experiments (LHC)
 - Planned: Atlas upgrade: miniature and radhard version 50 – 1000V
- ◆ Also two power versions foreseen
- a) few mW for MPGDs and diamond

 - b) Up to few 100 mW for silicon

Lab version under development

◆ Intended specs

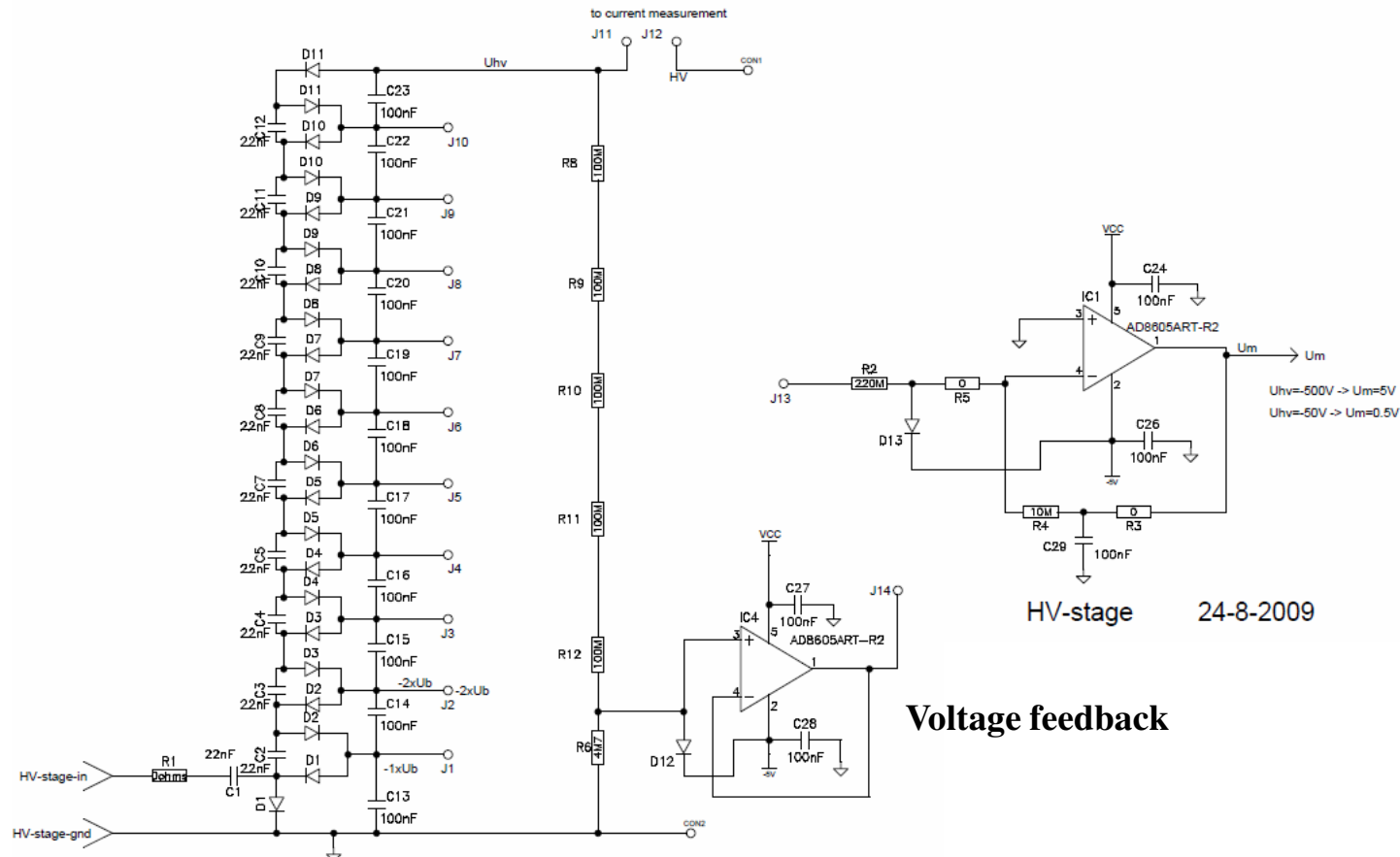
- $50 \text{ V} < V_{\text{out}} < 500 \text{ V}$, SHV connector
- $I_{\text{max}} \approx \text{few } \mu\text{A}$
- Voltage control by 14 bit DAC
- SPI/CAN controller per board providing:
 - Adjustable software trip
 - Adjustable upward ramping speed
 - Rapid downward ramping
- Current measurement with 1 nA resolution or better
 - 14 bit ADC



Creating HV with Cockcroft-Walton circuit

- ◆ 50 V block pulses in (duty cycle modulation)
- ◆ No transformer
- ◆ Voltage divider feedback for stabilisation

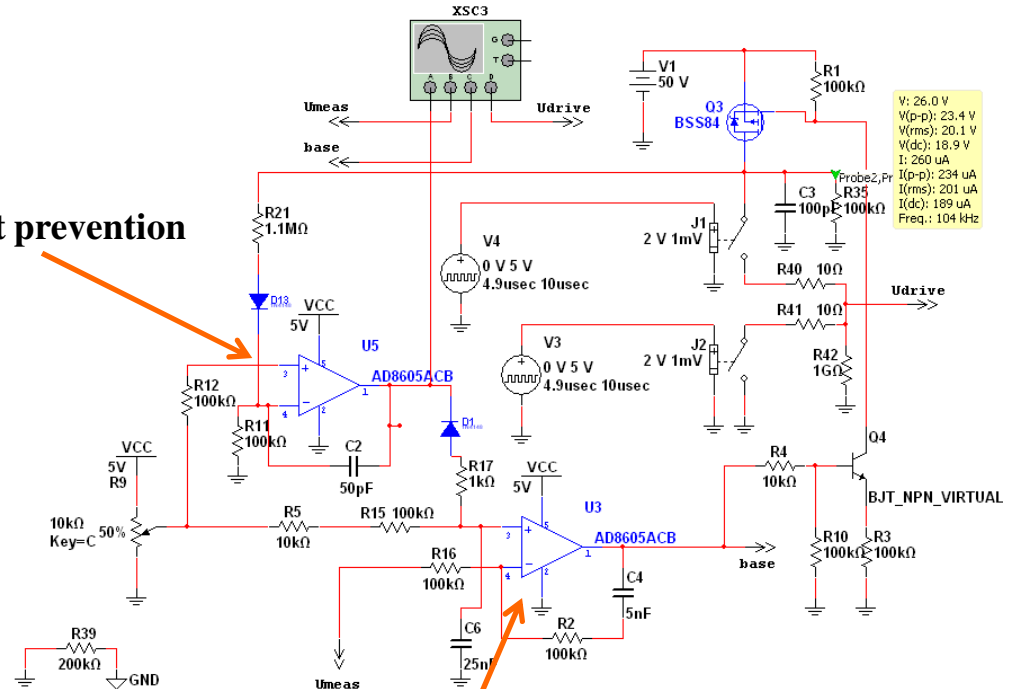
We cannot regulate down to 0V



PID circuit

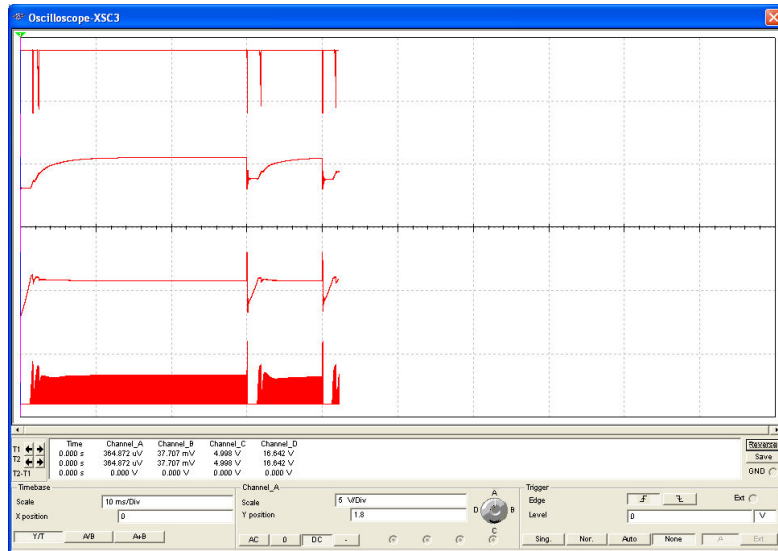
- ◆ Simulated operation
 - FETs represented by switches

Overshoot prevention



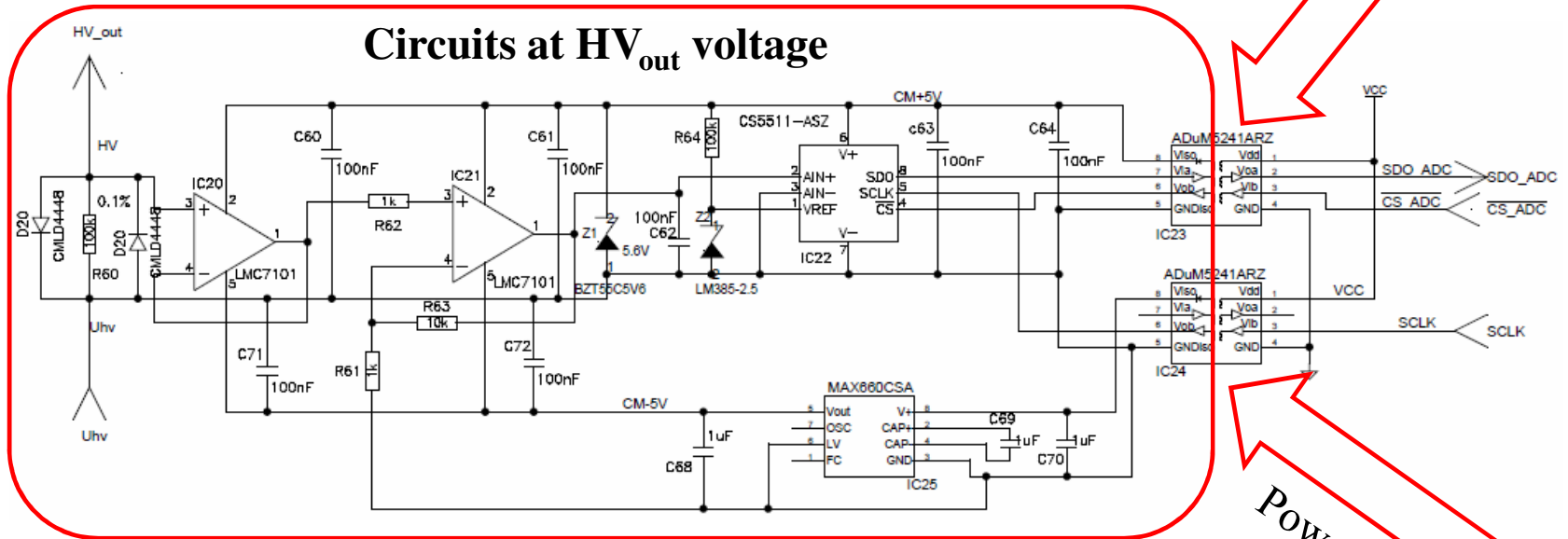
V: 26.0 V
 V(p-p): 23.4 V
 V(rms): 20.1 V
 V(dc): 18.9 V
 I: 260 uA
 I(p-p): 234 uA
 I(rms): 201 uA
 I(dc): 189 uA
 Freq.: 104 kHz

Voltage feedback



Current measurement

- ◆ Done in HV line
- ◆ Using MEMS technology power converters
 - => current measurement at high common mode voltage

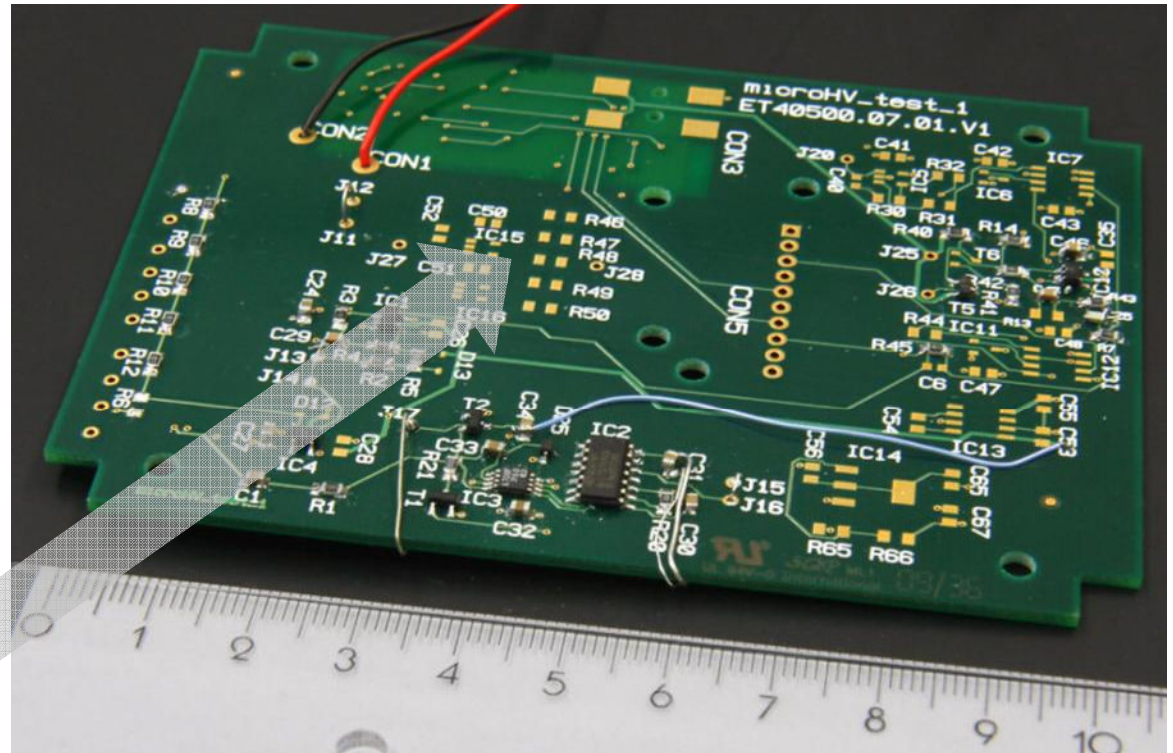


Digital communication

Power level shift

Present prototype PCB

◆ 110 x 80 mm



SPI/ CAN controller



Finally intended geometry of lab version

- ◆ Practical and rugged mechanical box
- ◆ $136 \times 82 \times 40 \text{ mm}^3$
- ◆ for future PCB

