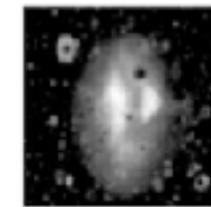
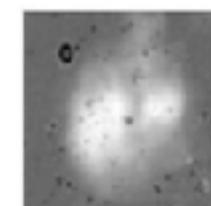
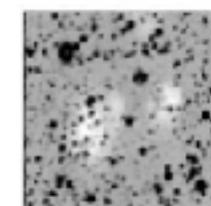
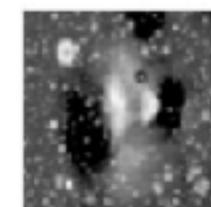
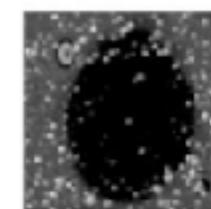
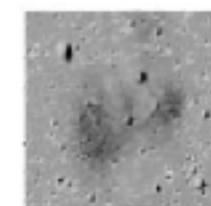
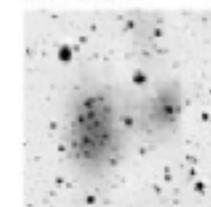
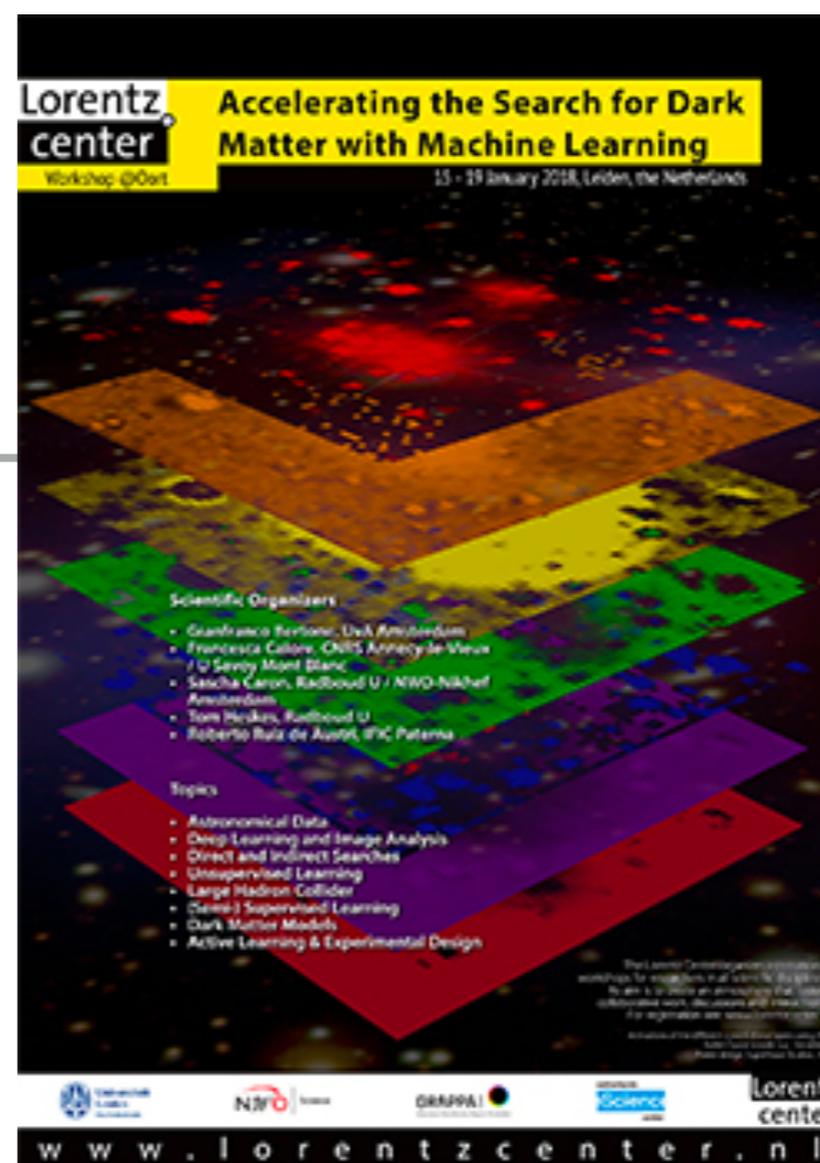


CNN
block 1



INDIRECT DETECTION & MACHINE LEARNING

LUC HENDRIKS
Radboud University Nijmegen



Lorentz center Accelerating the Search for Dark Matter with Machine Learning
Workshop @Dart 15 - 19 January 2018, Leiden, the Netherlands

Scientific Organizers

- Gianfranco Bertone, UvA Amsterdam
- Francesca Calore, CNRS Armeville-Vieux / U Savoie Mont Blanc
- Saïche Caron, Radboud U / NWO-Nikhef Amsterdam
- Tom Hockley, Radboud U
- Roberto Ruiz de Austri, IFIC Paterna

Topics

- Astronomical Data
- Deep Learning and Image Analysis
- Direct and Indirect Searches
- Unsupervised Learning
- Large Hadron Collider
- (semi-) Supervised Learning
- Dark Matter Models
- Active Learning & Experimental Design

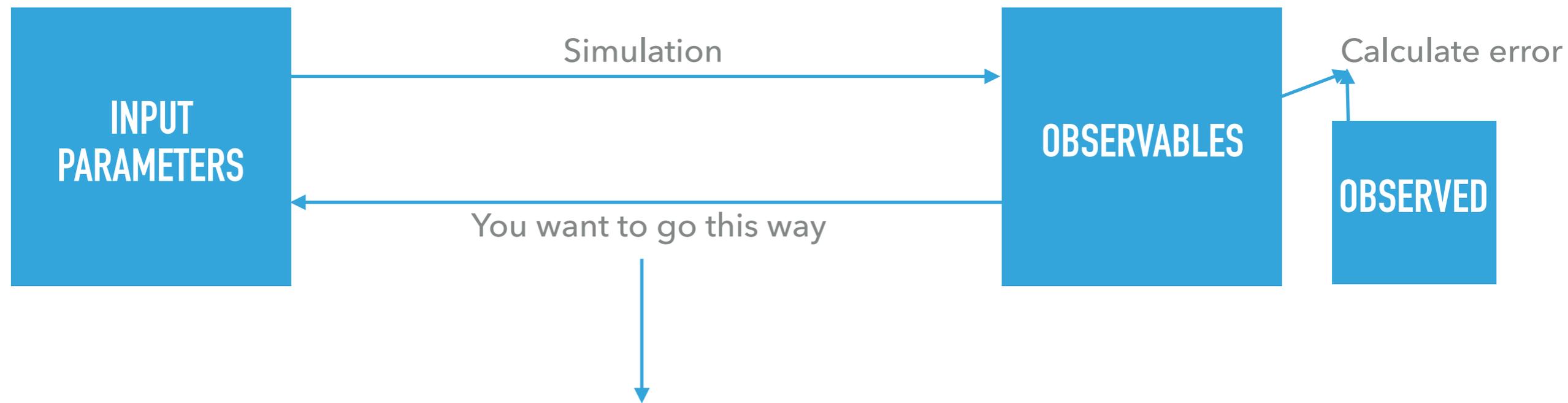
www.lorentzcenter.nl

OUTLINE

- ▶ Inverse problem
- ▶ Different approaches to deal with γ -ray data for indirect detection
 - ▶ SkyFACT / D3PO
 - ▶ Deep learning
- ▶ Some ways to use deep learning with simulations
 - ▶ Inverting inverse problem
 - ▶ Simulating simulations

INVERSE PROBLEM

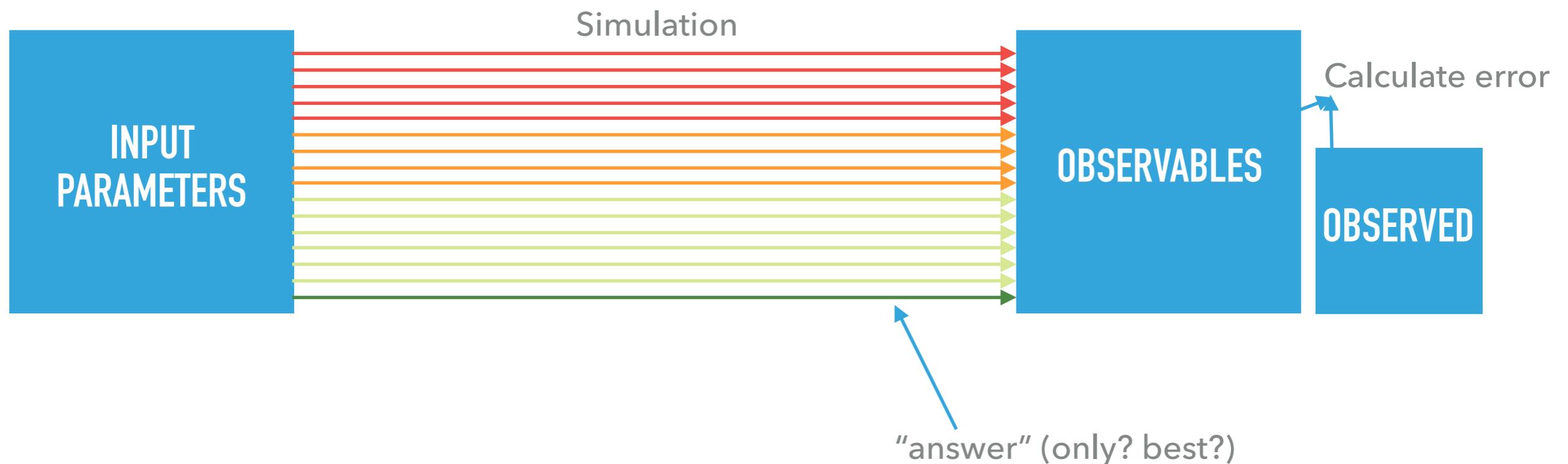
- ▶ Many problems in (astro)physics are an **inverse problem**



What are the input parameters of my simulation, given observables and observations?
(=model point)

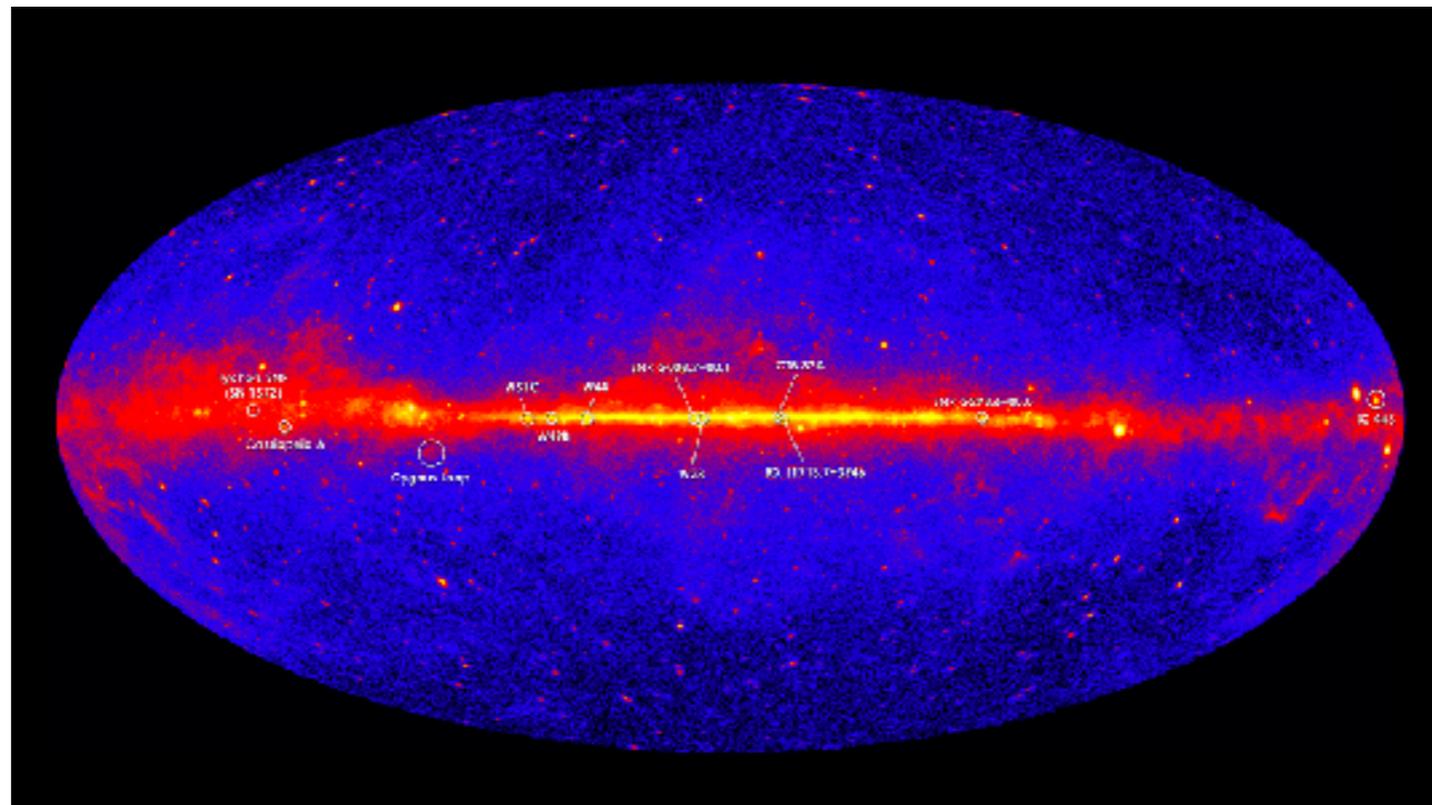
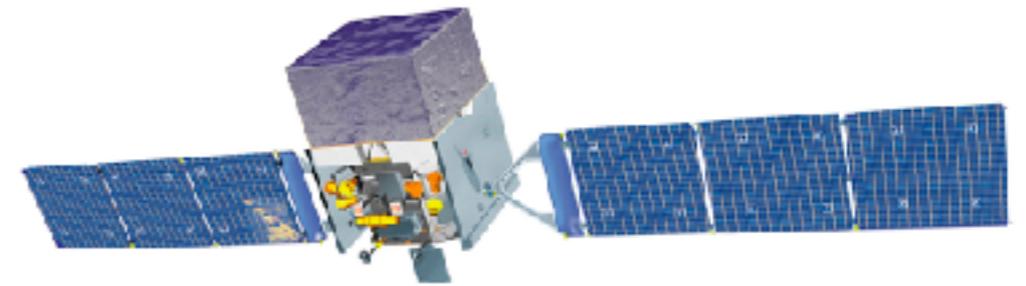
INVERSE PROBLEM

- ▶ You cannot go from observables to input parameters
- ▶ Need to scan the input parameter space for regions that predict observables that agree with observations
- ▶ Methods: random sampling, gradient descent, MCMC, nested sampling, ...
- ▶ Computationally very expensive



INDIRECT DETECTION

- ▶ Detection of decay or annihilation products of DM
- ▶ Focus on γ -rays
- ▶ Fermi-LAT is the go-to instrument

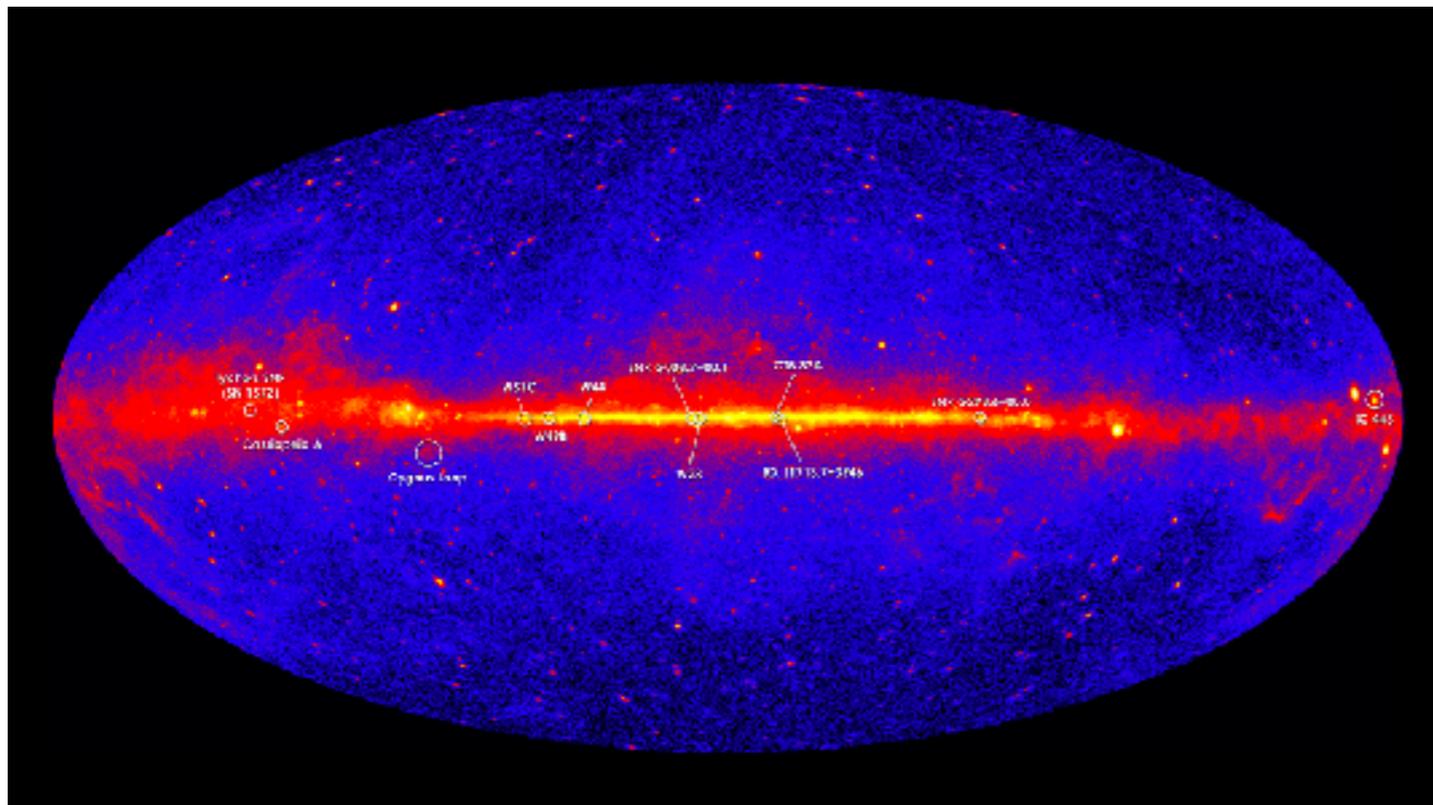


SKYFACT

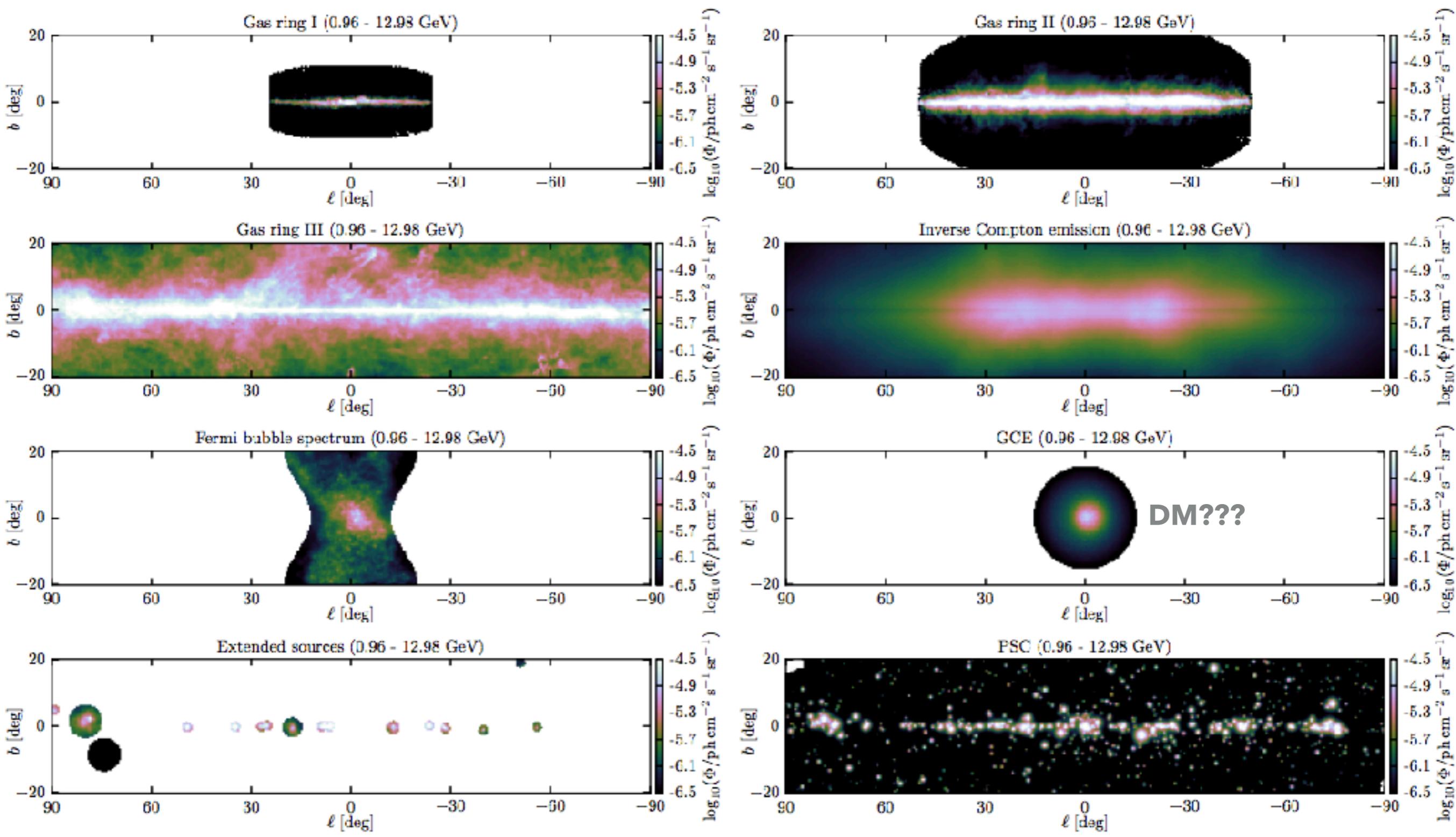
- ▶ Assume uncorrelated error in pixels
(lots of imperfections in models and measurements)
- ▶ Modify models (all energy bin / pixel values) to reduce errors
- ▶ You will find zones with high error that cannot be fixed with nuisance parameters
 - ▶ Add new component

Add nuisance parameters
+ regularisation

$$\phi_{pb} = \sum_k T_p^{(k)} \tau_p^{(k)} \cdot S_b^{(k)} \sigma_b^{(k)} \cdot \nu^{(k)}$$



SKYFACT



INFORMATION FIELD THEORY & D3PO

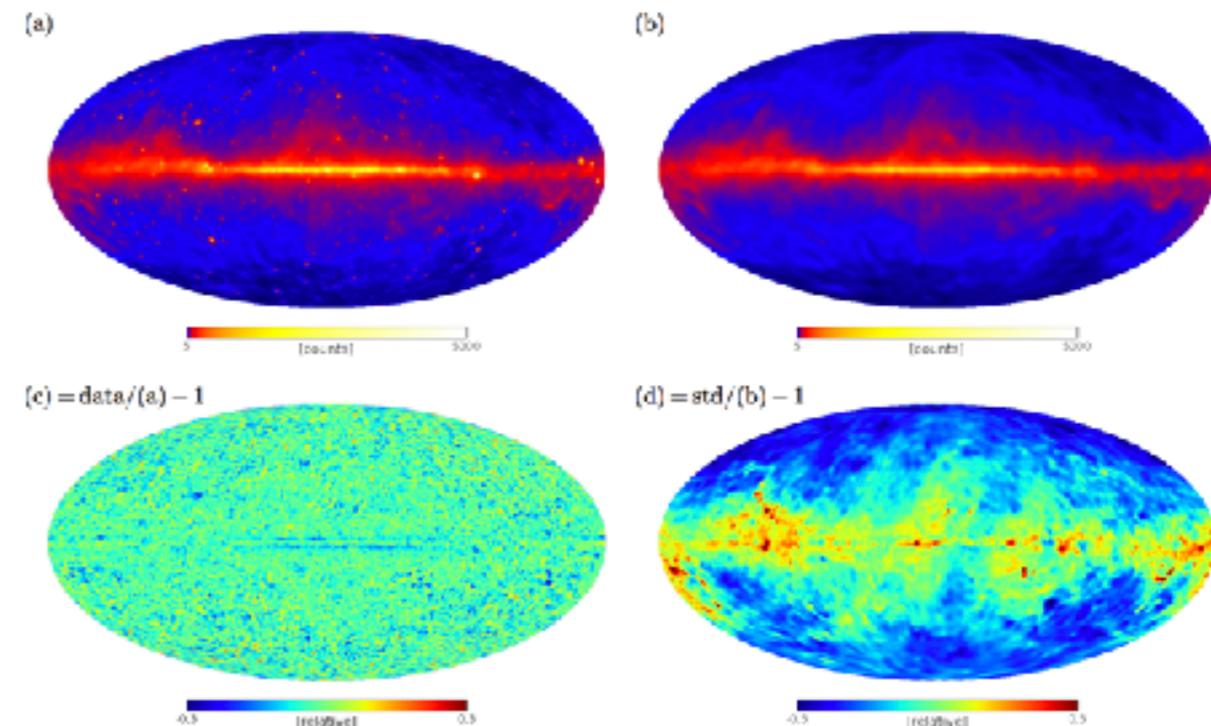
- ▶ Connect Bayesian analysis to statistical physics & QFT
- ▶ Deconvolve, denoise, decompose photon observations
 - ▶ Use IFT to get information out of photon observations
 - ▶ Open source code: <http://wwwmpa.mpa-garching.mpg.de/ift/d3po/>

$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d|s) \mathcal{P}(s)}{\mathcal{P}(d)}$$

$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d, s)}{\mathcal{P}(d)} \equiv \frac{e^{-\mathcal{H}(d, s)}}{\mathcal{Z}(d)}$$

$$\mathcal{H}(d, s) \equiv -\ln \mathcal{P}(d, s) = -\ln \mathcal{P}(d|s) - \ln \mathcal{P}(s) \equiv \mathcal{H}(d|s) + \mathcal{H}(s)$$

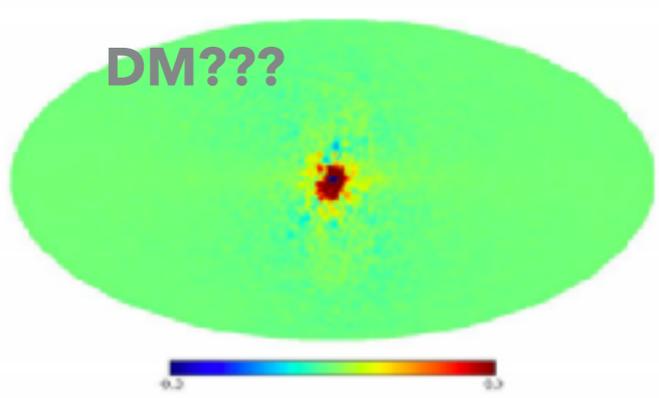
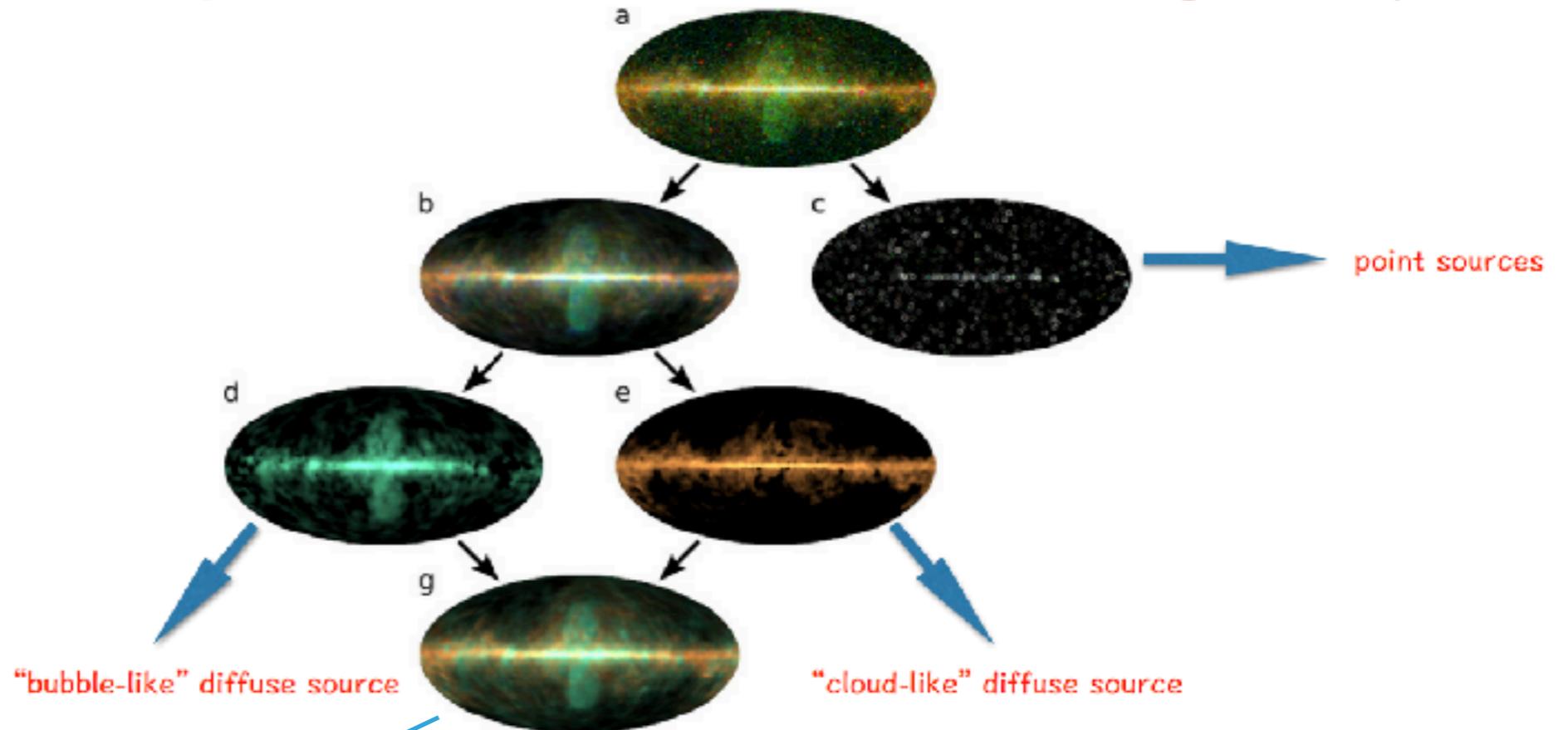
$$\mathcal{Z}(d) \equiv \mathcal{P}(d) = \int \mathcal{D}s \mathcal{P}(d, s)$$



PHENOMENOLOGICAL DECOMPOSITION

Selig+ 2014

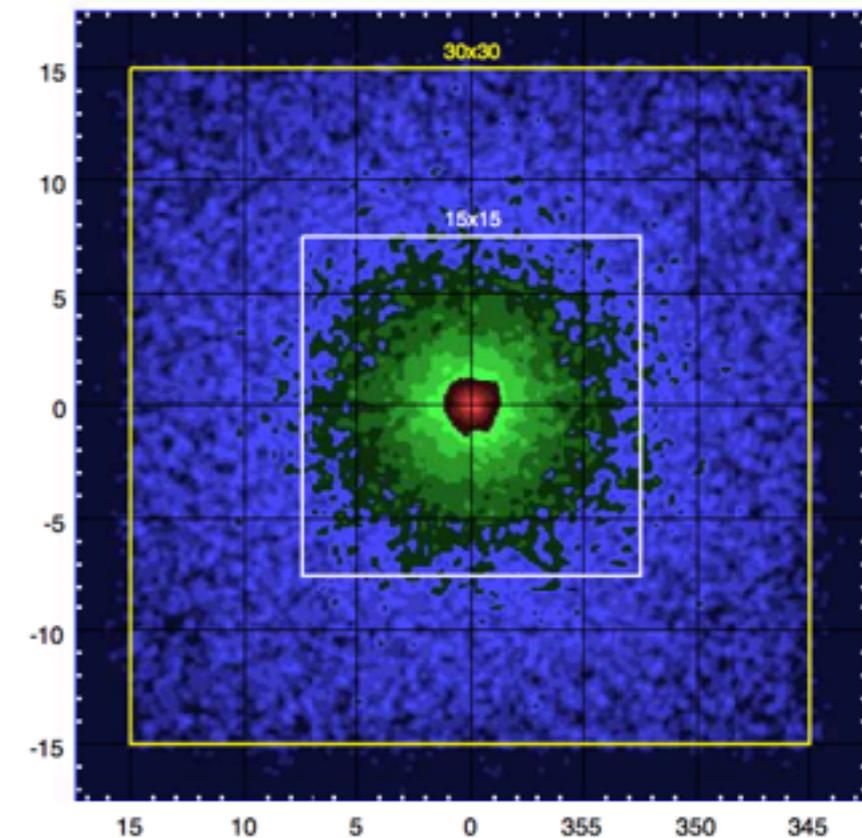
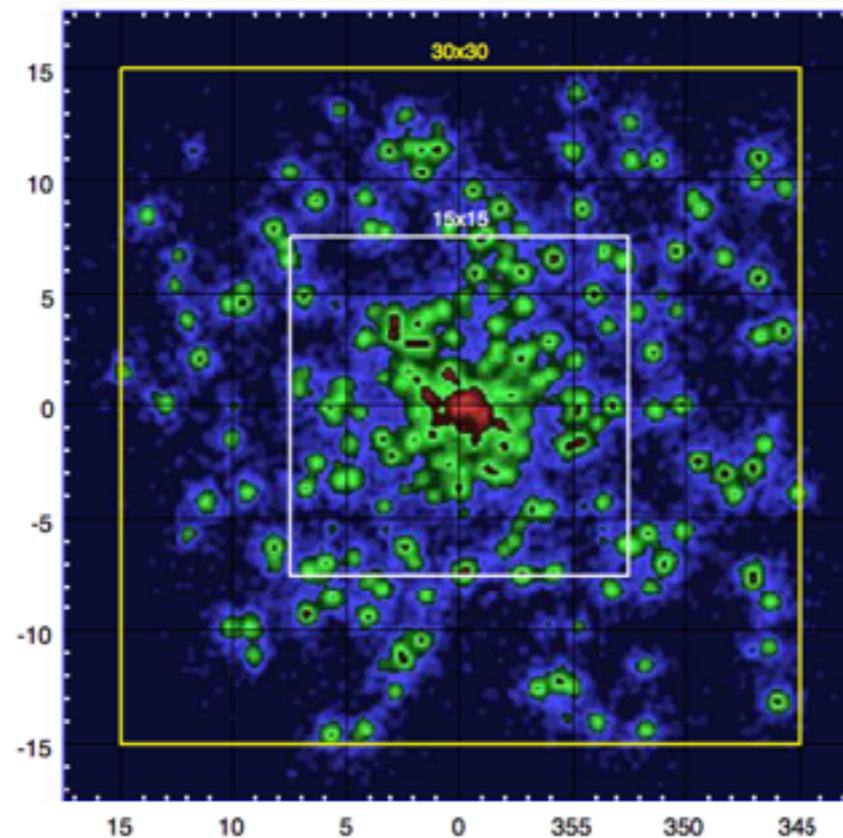
Phenomenological Decomposition



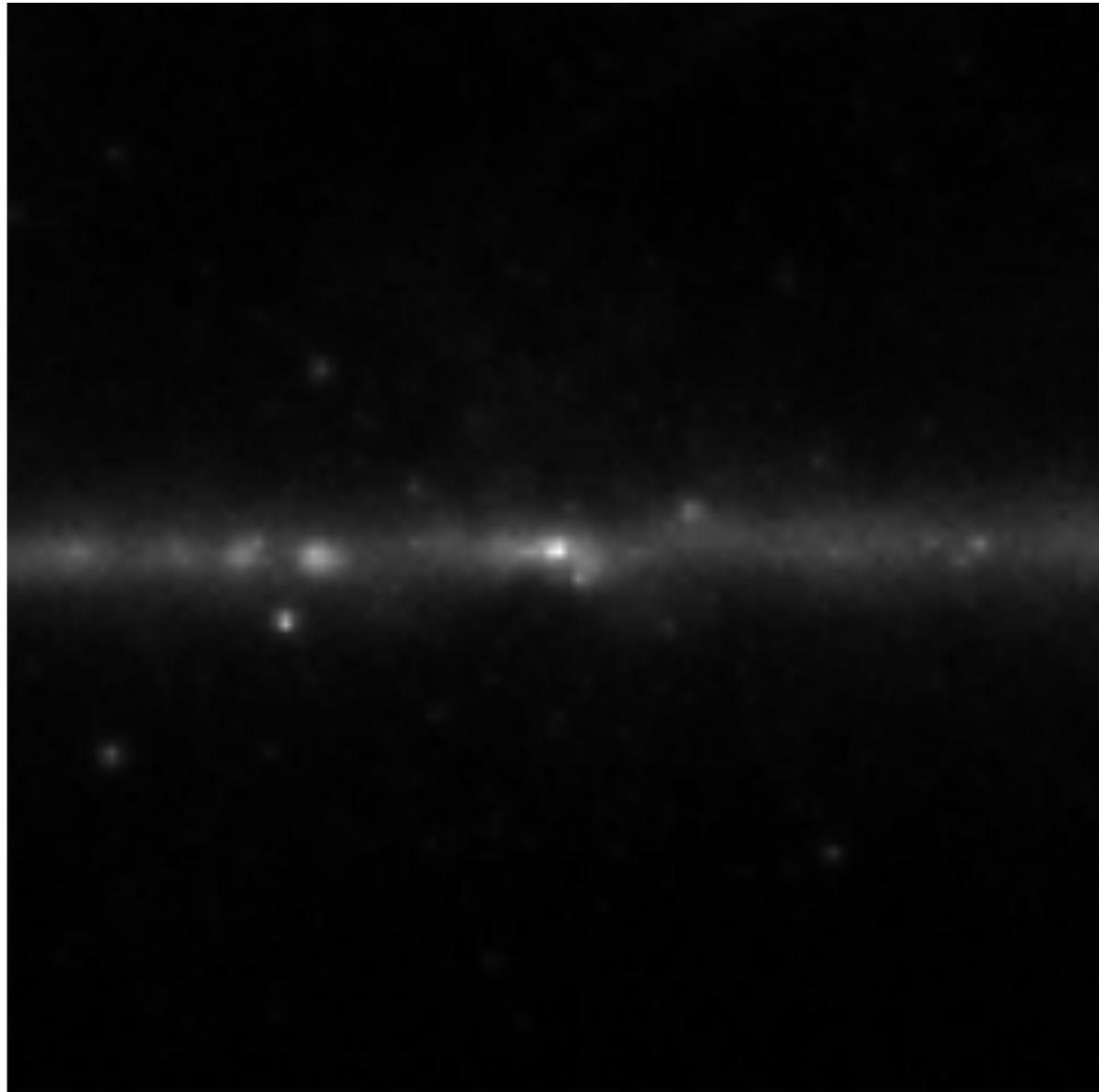
"GC excess" template

DEEP LEARNING

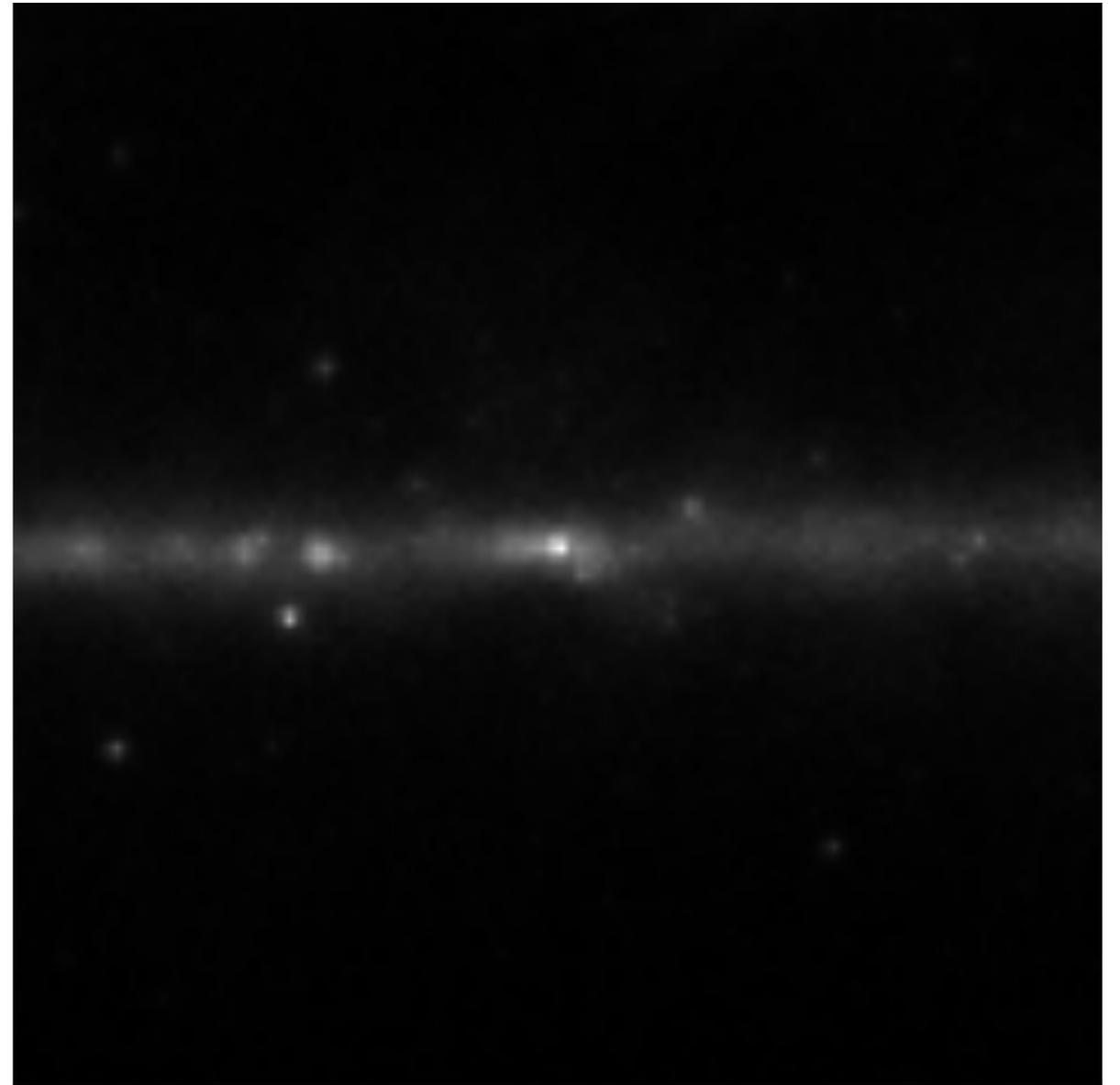
- ▶ Question: Is the GC excess from a diffuse source or collection of unresolved point sources?
- ▶ Can we answer this question with deep learning?
- ▶ Assume diffuse and point source component distributed by gNFW profile



EXAMPLE OF TWO SIMULATIONS



$$f_{\text{src}} = 0.9883$$



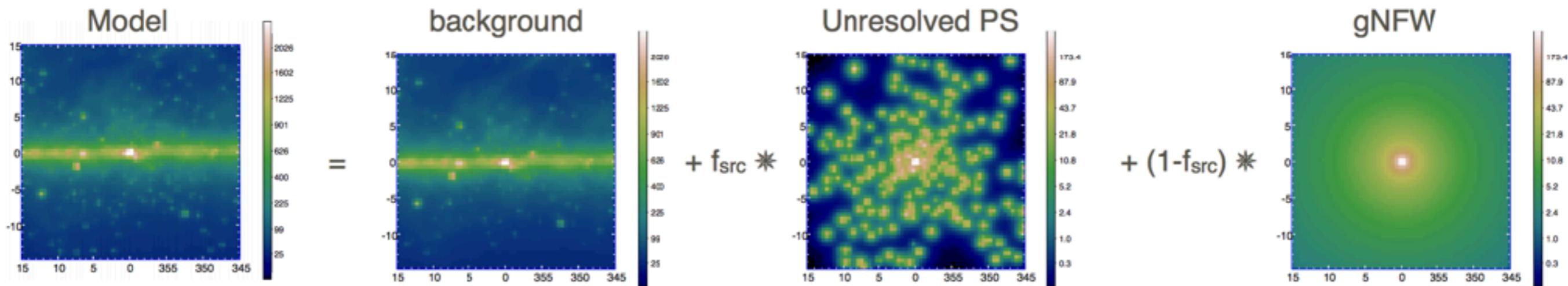
$$f_{\text{src}} = 0.0275$$

Try yourself! <http://fermi.ai.s3-website-eu-west-1.amazonaws.com/>

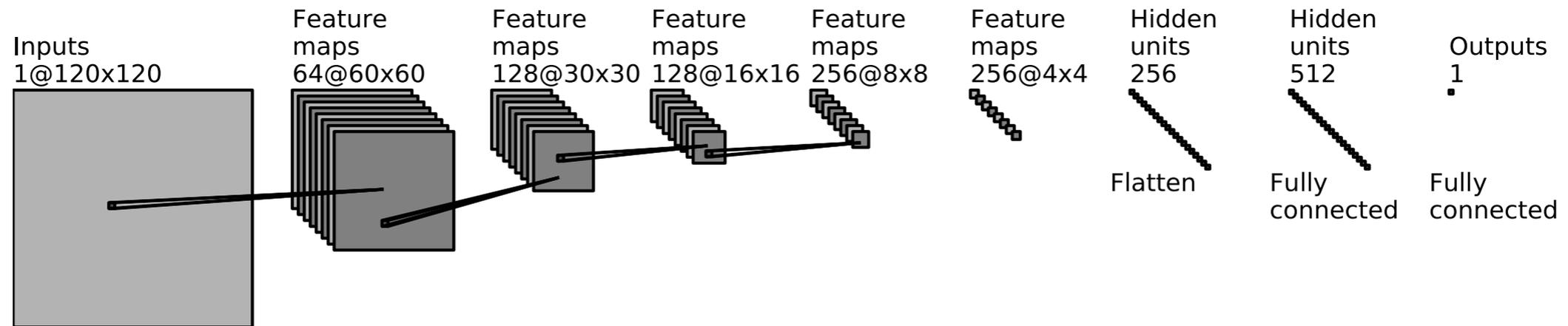
HOW TO APPLY DEEP LEARNING TO γ -RAY DATA?

- ▶ Goal: determine the component of point sources vs diffuse source of the GC excess – f_{src}
- ▶ Simulate GC using Fermi tools (5 parameters)
 - ▶ Output is photon count map of photons between 1-6GeV (no spectrum information, will be improved in new version)
- ▶ Sample from simulations in 5D parameter space
- ▶ Train network to predict f_{src} accurately in all scenarios of the other components
- ▶ Apply on real data – sample big enough so that reality is somewhere in 5D space
- ▶ Network trained on simulated data to predict f_{src}

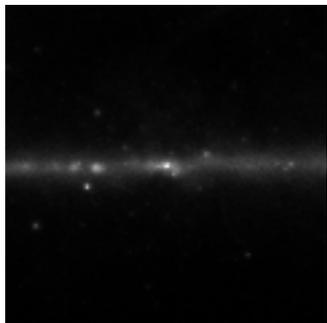
GC Excess



CONVOLUTIONAL NEURAL NETWORK



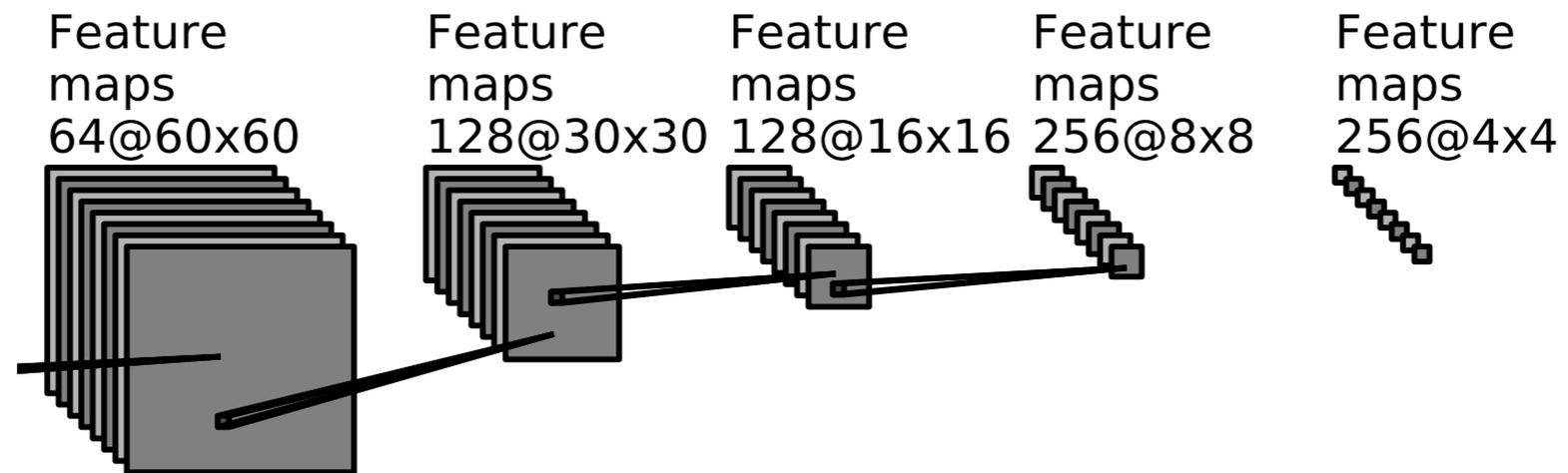
Max-pooling after every convolution
Local response normalization after every other convolution



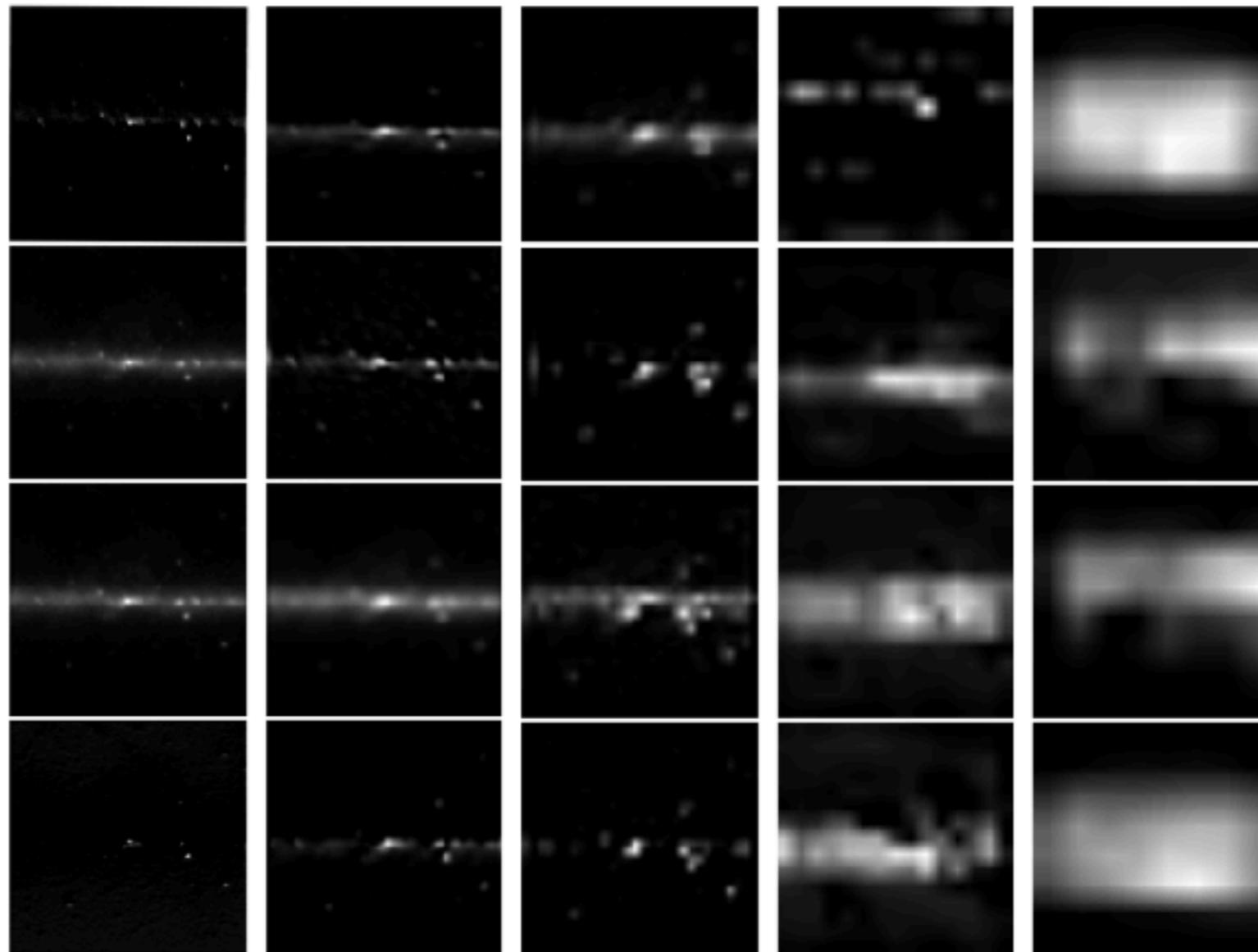
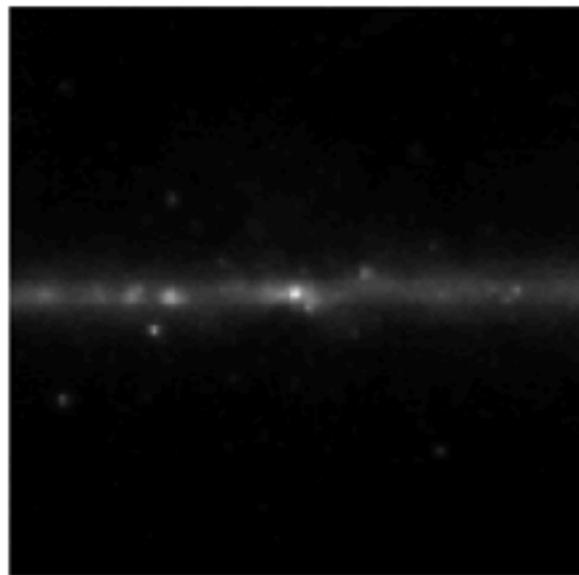
$f_{\text{src}} = 0.89$

- ▶ Next version:
 - ▶ More input parameters in simulations
 - ▶ Output of network are all input parameters instead of only point source fraction

DEEP LEARNING



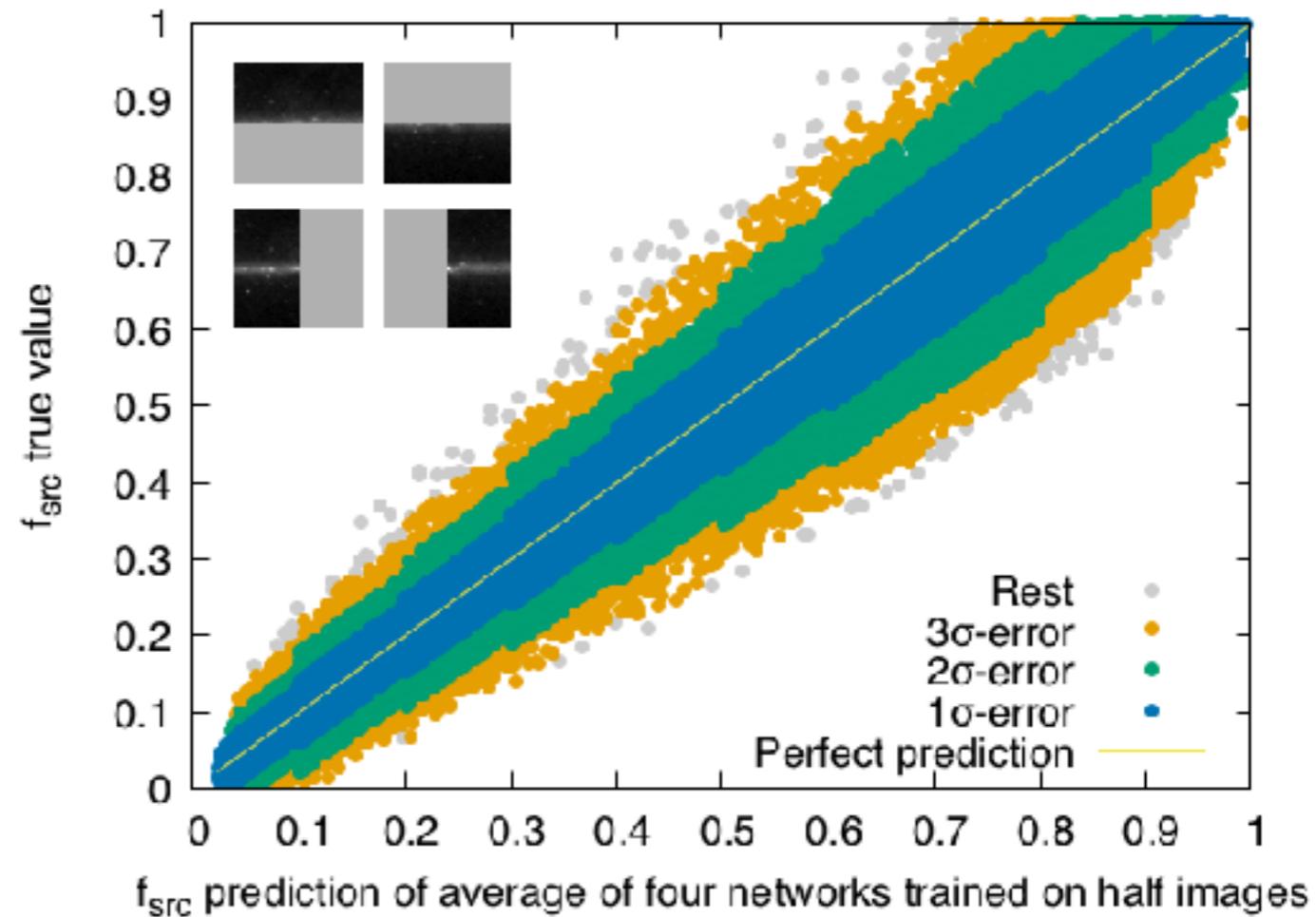
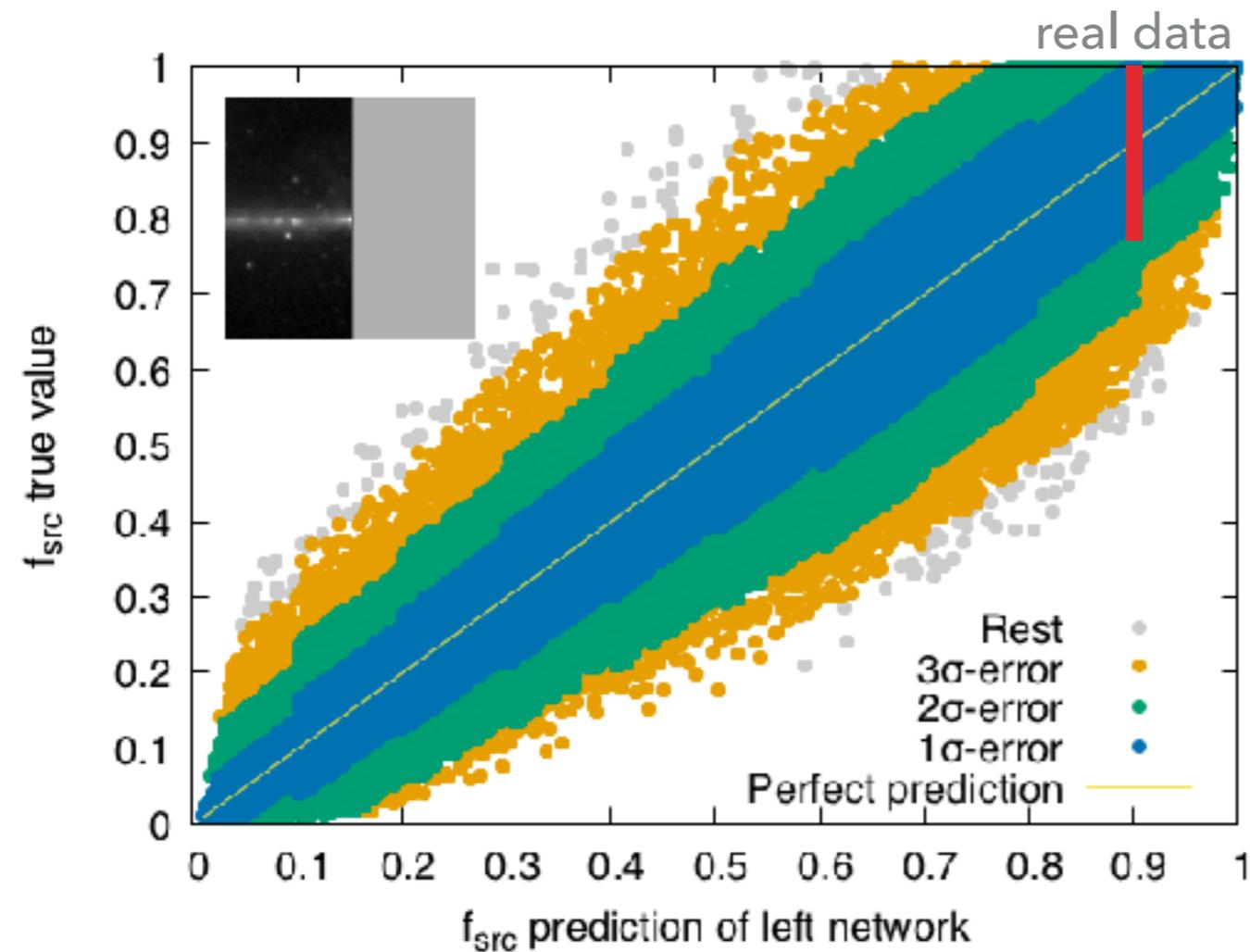
Input



Prediction: 0.86
Truth: 0.82

RESULTS

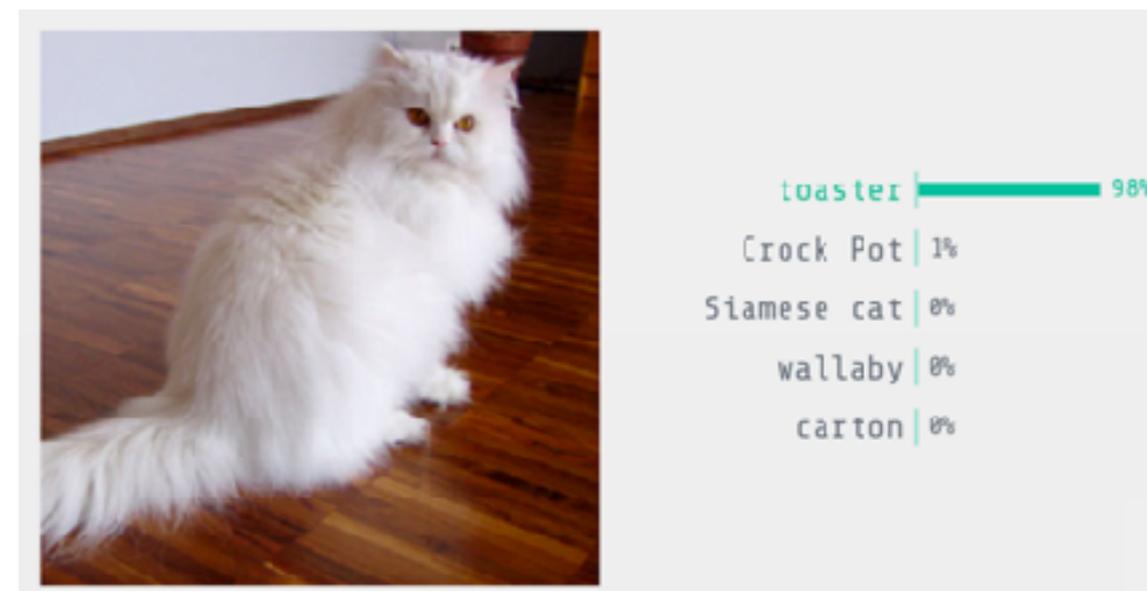
- ▶ Train using 3 background models, test on 2 others
- ▶ Test data: 2x30000 test points



Because we are doing a followup study, real result is only evaluated on the left network to not bias ourselves

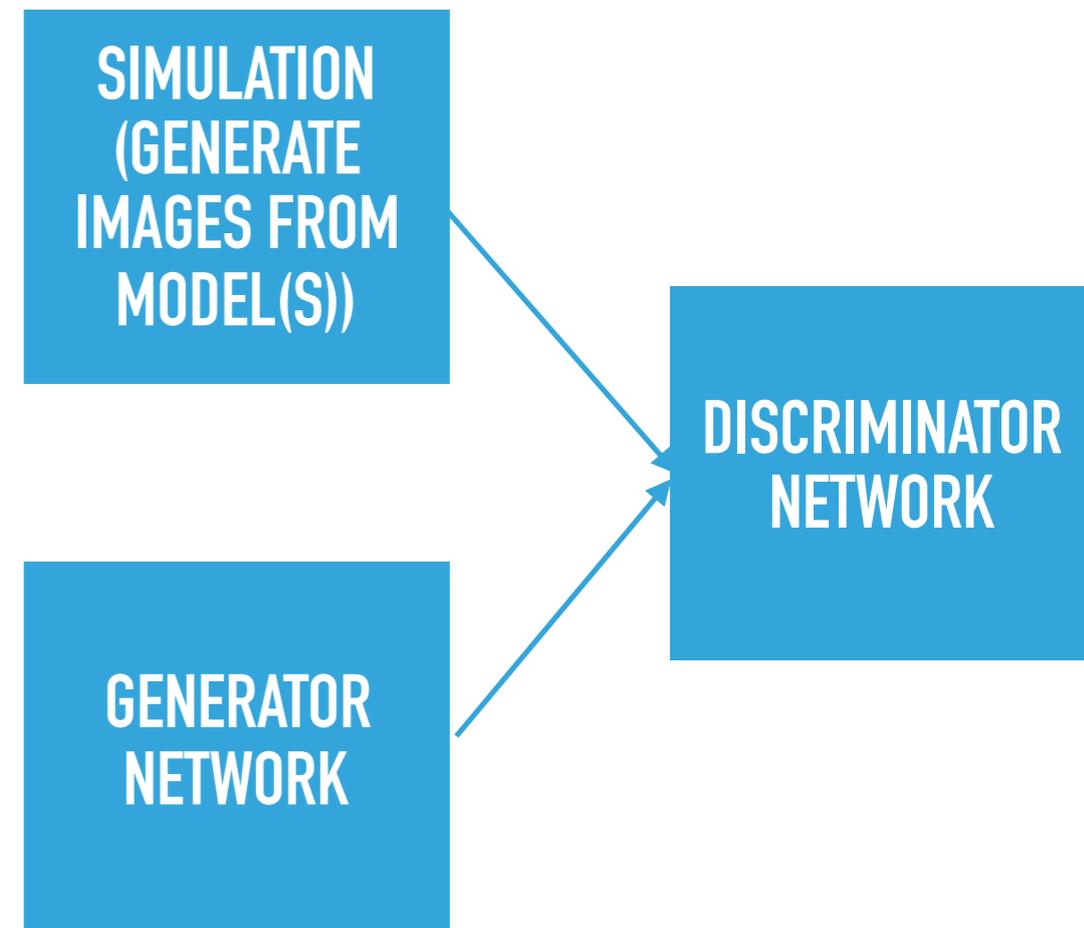
INVERTING INVERSE PROBLEM

- ▶ Use simulation to generate dataset
 - ▶ Observable = network input
 - ▶ Network output = model input
- ▶ No inverse problem anymore!
- ▶ However:
 - ▶ Network assumes simulation is reality
 - ▶ Even putting in a cat photo will return a value between 0 & 1, while we know it makes no sense
 - ▶ CNNs are known to be easily tricked
 - ▶ How to be able to trust this?



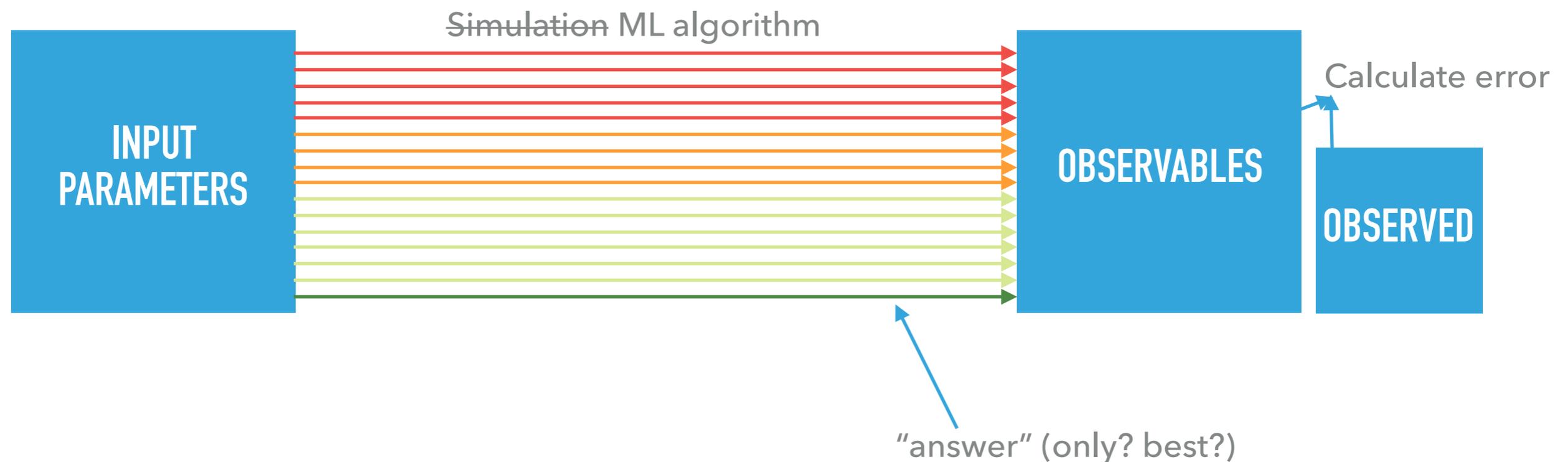
DEEP LEARNING APPROACH

- ▶ Adversarial model
- ▶ Generator network learns to generate images the model can generate
- ▶ Discriminator tries to distinguish
- ▶ When it cannot anymore, generator network is as good as your model
- ▶ Can the model generate images that are identical to real data?
- ▶ Which generator from which model can do this better / easier: compare models with each other



SIMULATING THE SIMULATION

- ▶ Another way to use deep learning to find input parameters is to simulate the simulation
- ▶ Use dataset from simulation to train a network
 - ▶ Network does the same as the simulation



SIMULATING THE SIMULATION

- ▶ Example from asteroseismology
- ▶ Train network on precomputed grid
- ▶ 10 input parameters
- ▶ 30 mins to find minimum

CONCLUSIONS

- ▶ Indirect detection methods can benefit greatly from ML methods
- ▶ Methods already used to deal with the Fermi-LAT data
 - ▶ SkyFACT
 - ▶ D3PO
 - ▶ ConvNets / deep learning
- ▶ Deep learning can be used to invert the inverse problem, or simulate simulations
 - ▶ Speed up simulations greatly