



CLIC: The CLIC Accelerator Design and Performance

CERN Academic Training
Wednesday March 7, 2018

Daniel Schulte
For the CLIC collaboration

No names at individual contributions, have to omit many important contributions

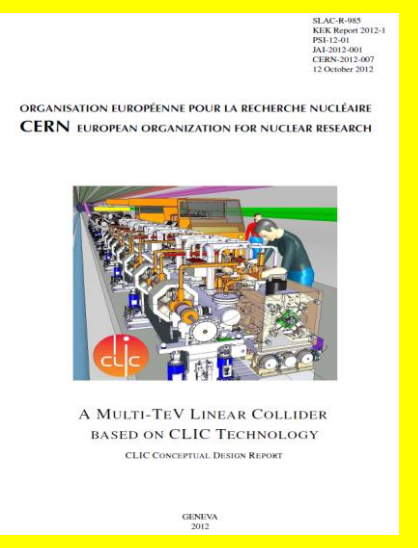


CLIC Introduction



CLIC: Compact Linear Collider

CLIC aims to provide **multi-TeV electron-positron** collisions with high luminosity at affordable cost and power consumption



2012 CDR:
Shows feasibility
of 3 TeV design

2013 - 2019 Development Phase

Development of a Project Plan for a staged CLIC implementation in line with LHC results; technical developments with industry, performance studies for accelerator parts and systems, detector technology demonstrators

2020 - 2025 Preparation Phase

Finalisation of implementation parameters, preparation for industrial procurement, Drive Beam Facility and other system verifications, Technical Proposal of the experiment, site authorisation

2026 - 2034 Construction Phase

Construction of the first CLIC accelerator stage compatible with implementation of further stages; construction of the experiment; hardware commissioning

2019 - 2020 Decisions

Update of the European Strategy for Particle Physics; decision towards a next CERN project at the energy frontier (e.g. CLIC, FCC)

2025 Construction Start

Ready for construction; start of excavations

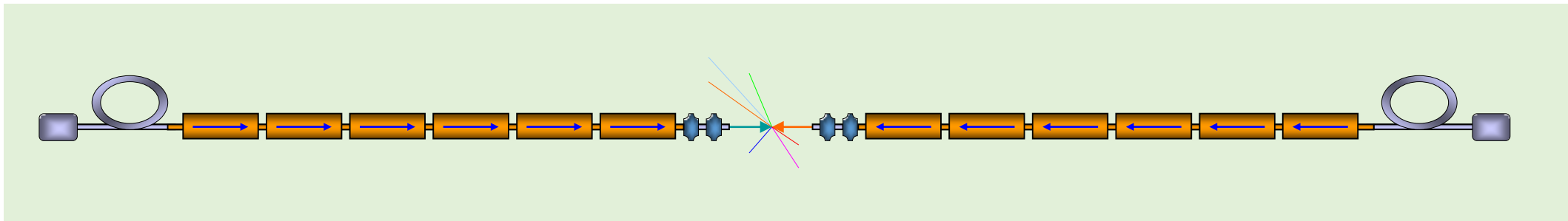
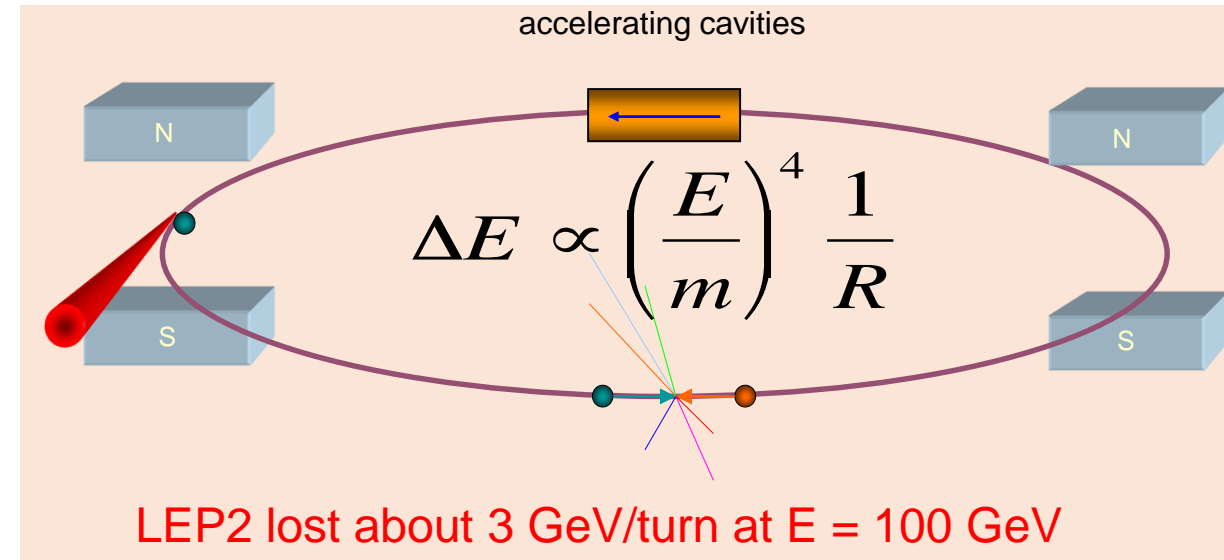
2035 First Beams

Getting ready for data taking by the time the LHC programme reaches completion



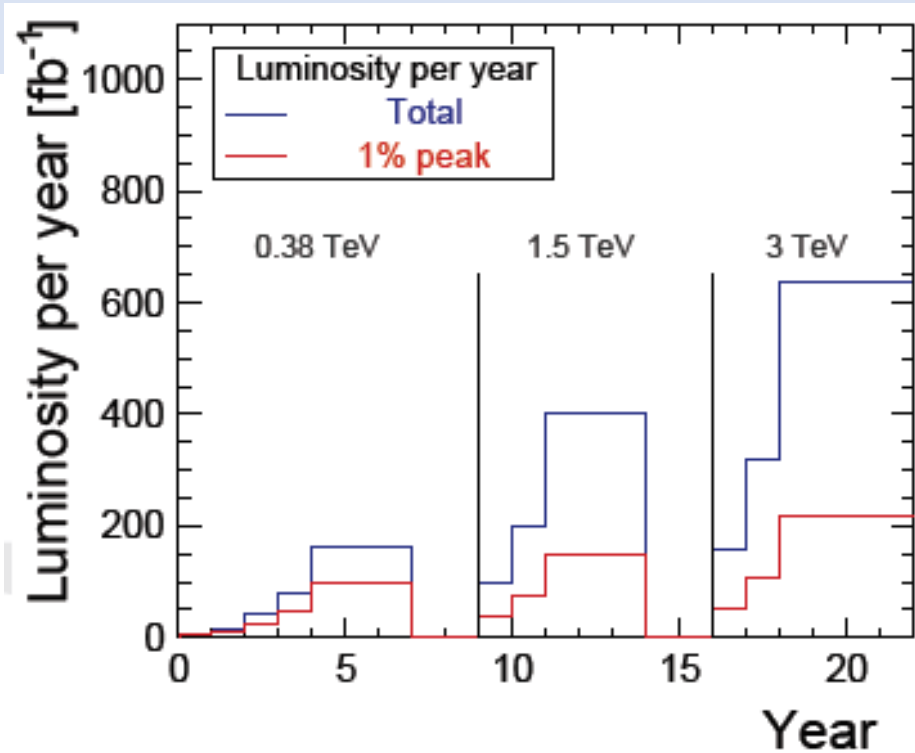
To reach multi-TeV energies:

- Linear collider to avoid synchrotron radiation
- High accelerating field to achieve high energy
 ⇒ Normal conducting accelerating structures
- High beam current and quality to achieve the luminosity
 ⇒ High quality of components
 ⇒ Little imperfections
 ⇒ Fancy beam dynamics



Plenty of physics at low centre-of-mass energies

Energy and luminosity targets from Physics Study Group



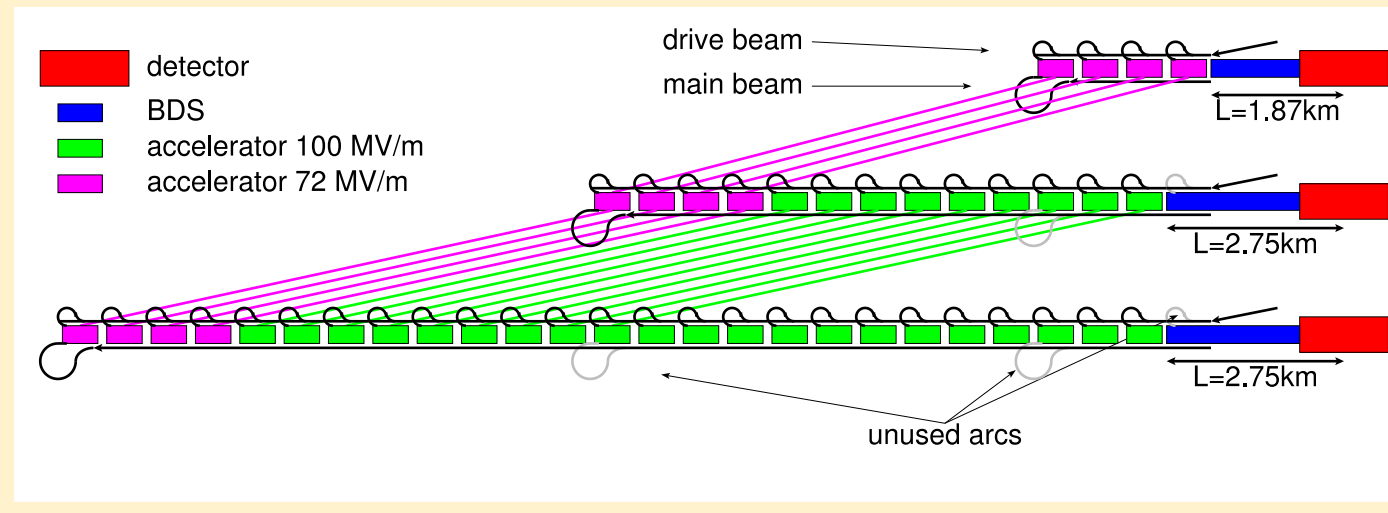
Stage	\sqrt{s} (GeV)	\mathcal{L}_{int} (fb ⁻¹)
1	380	500
	350	100
2	1500	1500
3	3000	3000

Top above threshold
Higgs via Zh and WW fusion

Study top at threshold

To be updated with more input from LHC and stage 1

Implementation in stages

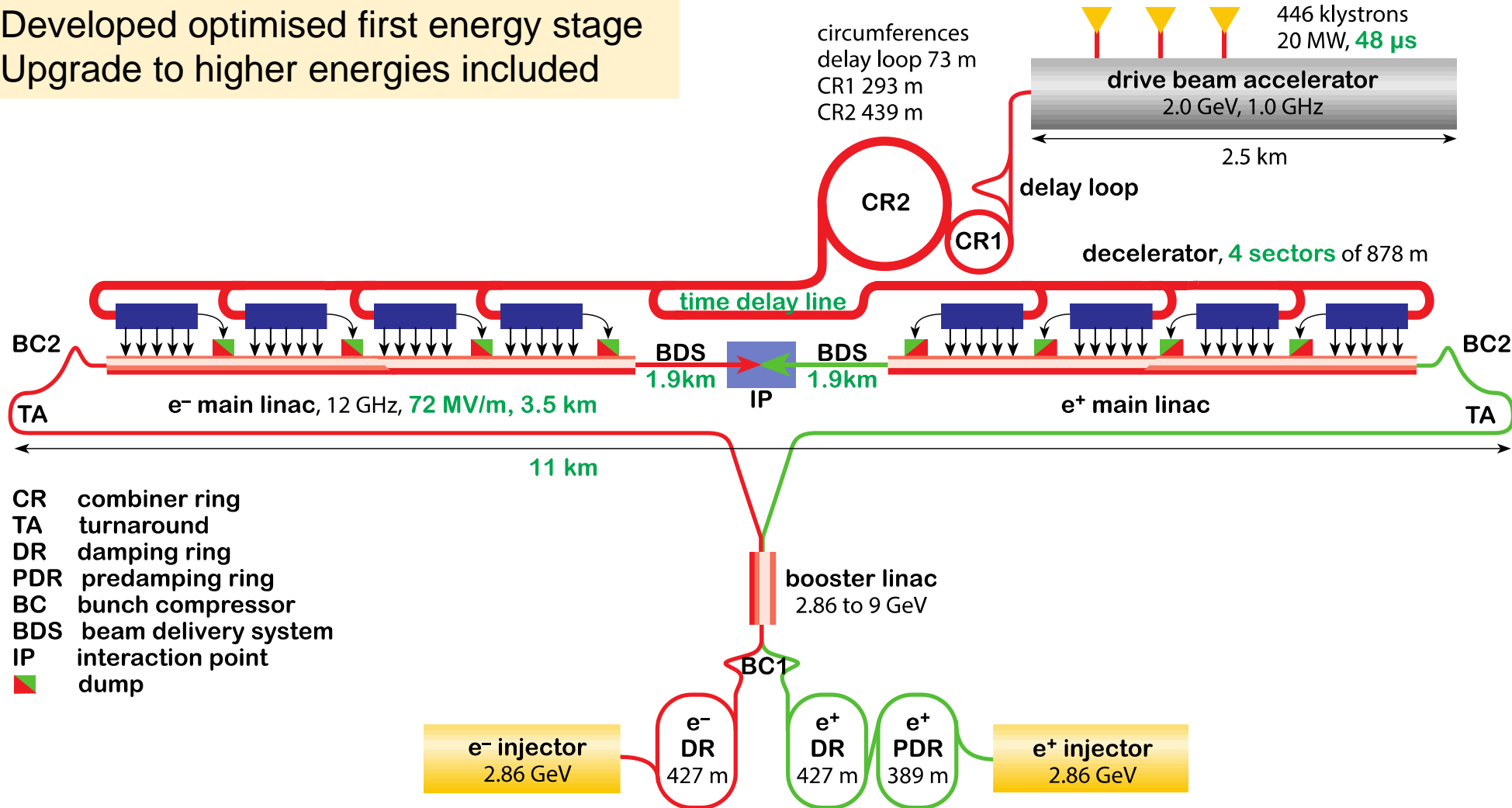




CLIC at 380 GeV



Developed optimised first energy stage
Upgrade to higher energies included





Key Parameters



Parameter	Symbol	Unit	Stage 1	Stage 2	Stage 3
Centre-of-mass energy	\sqrt{s}	GeV	380	1500	3000
Repetition frequency	f_{rep}	Hz	50	50	50
Number of bunches per train	n_b		352	312	312
Bunch separation	Δt	ns	0.5	0.5	0.5
Accelerating gradient	G	MV/m	72	72/100	72/100
Total luminosity	\mathcal{L}	$10^{34} \text{ cm}^{-2} \text{ s}^{-1}$	1.5	3.7	5.9
Luminosity above 99% of \sqrt{s}	$\mathcal{L}_{0.01}$	$10^{34} \text{ cm}^{-2} \text{ s}^{-1}$	0.9	1.4	2
Main tunnel length		km	11.4	29.0	50.1
Charge per bunch	N	10^9	5.2	3.7	3.7
Bunch length	σ_z	μm	70	44	44
IP beam size	σ_x / σ_y	nm	149/2.9	$\sim 60/1.5$	$\sim 40/1$
Normalised emittance (end of linac)	ϵ_x / ϵ_y	nm	—	660/20	660/20
Normalised emittance	ϵ_x / ϵ_y	nm	950/30	—	—
Estimated power consumption	P_{wall}	MW	252	364	589

380 GeV / 3 TeV

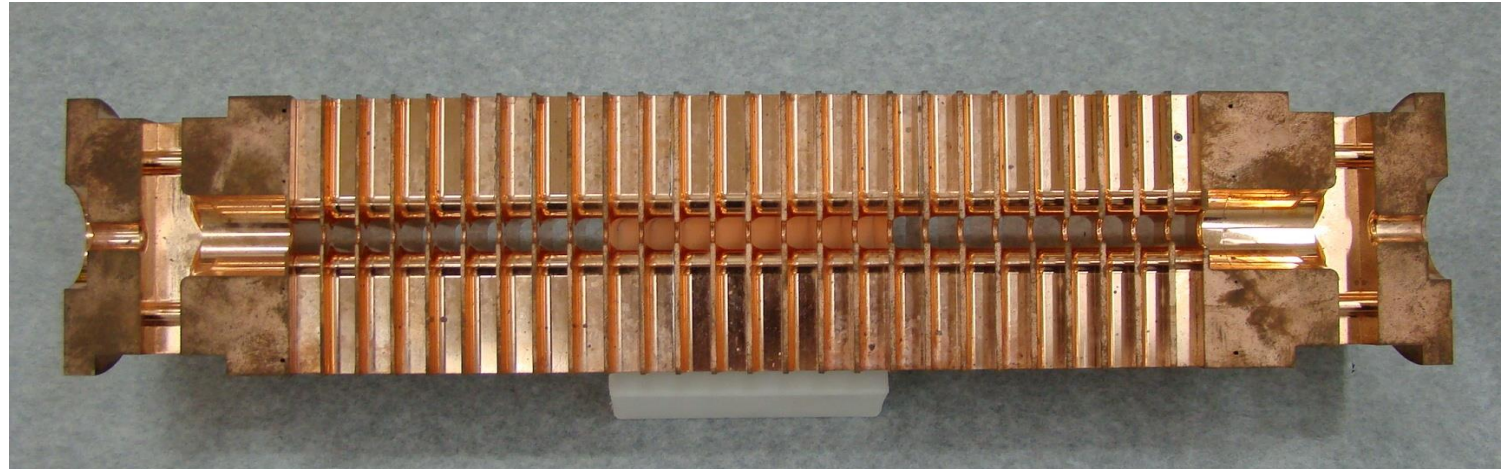
12 GHz

27 / 23 cm long

72 / 100 MV/m

59.5 / 61.3 MW input power

244 ns RF pulses



20600 / 140,000 structures 380 GeV / 3 TeV

Total peak RF power:

1.6 TW (380 GeV) 8.5 TW (3 TeV)

But only 10^{-5} duty factor

- 50 RF bursts per second
- 244 ns long (312 bunches)
- = 12.2 μs / s

Production of peak power is a challenge
Typical 12 GHz klystrons produces O(50 MW)

Solution is drive beam



CLIC Gradient



Breakdowns (discharges during the RF pulse)

- Require $p \leq 3 \times 10^{-7} \text{ m}^{-1} \text{ pulse}^{-1}$

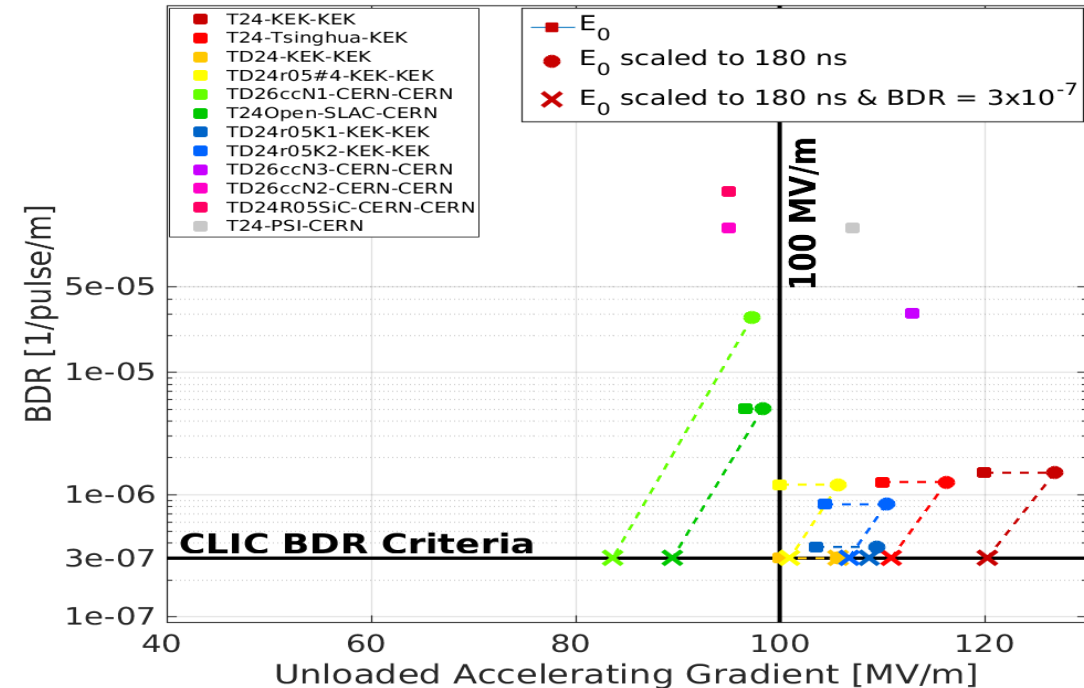
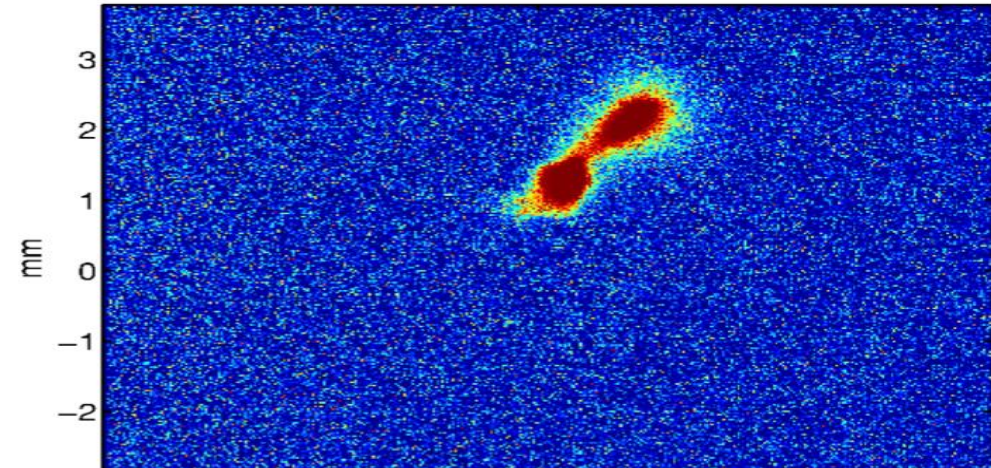
Structure design based on **empirical** constraints, not first principle

- Maximum surface field
- Maximum temperature rise
- Maximum power flow

R&D established gradient $O(100 \text{ MV/m})$

Structure for 380 GeV optimised for cost of first energy stage

$\Rightarrow 72 \text{ MV/m}$





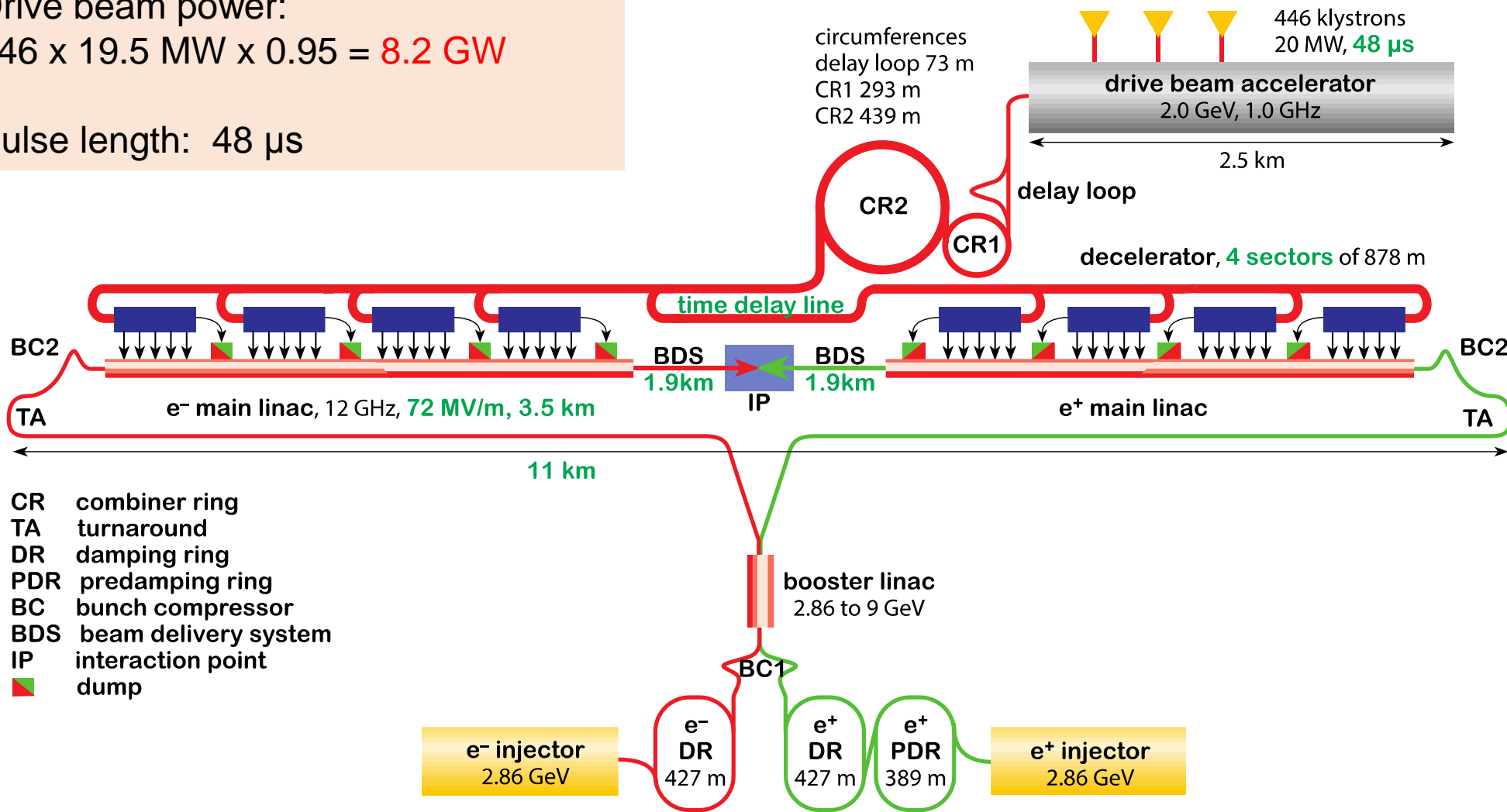
Power Production: Drive Beam Production



Drive beam power:

$$446 \times 19.5 \text{ MW} \times 0.95 = 8.2 \text{ GW}$$

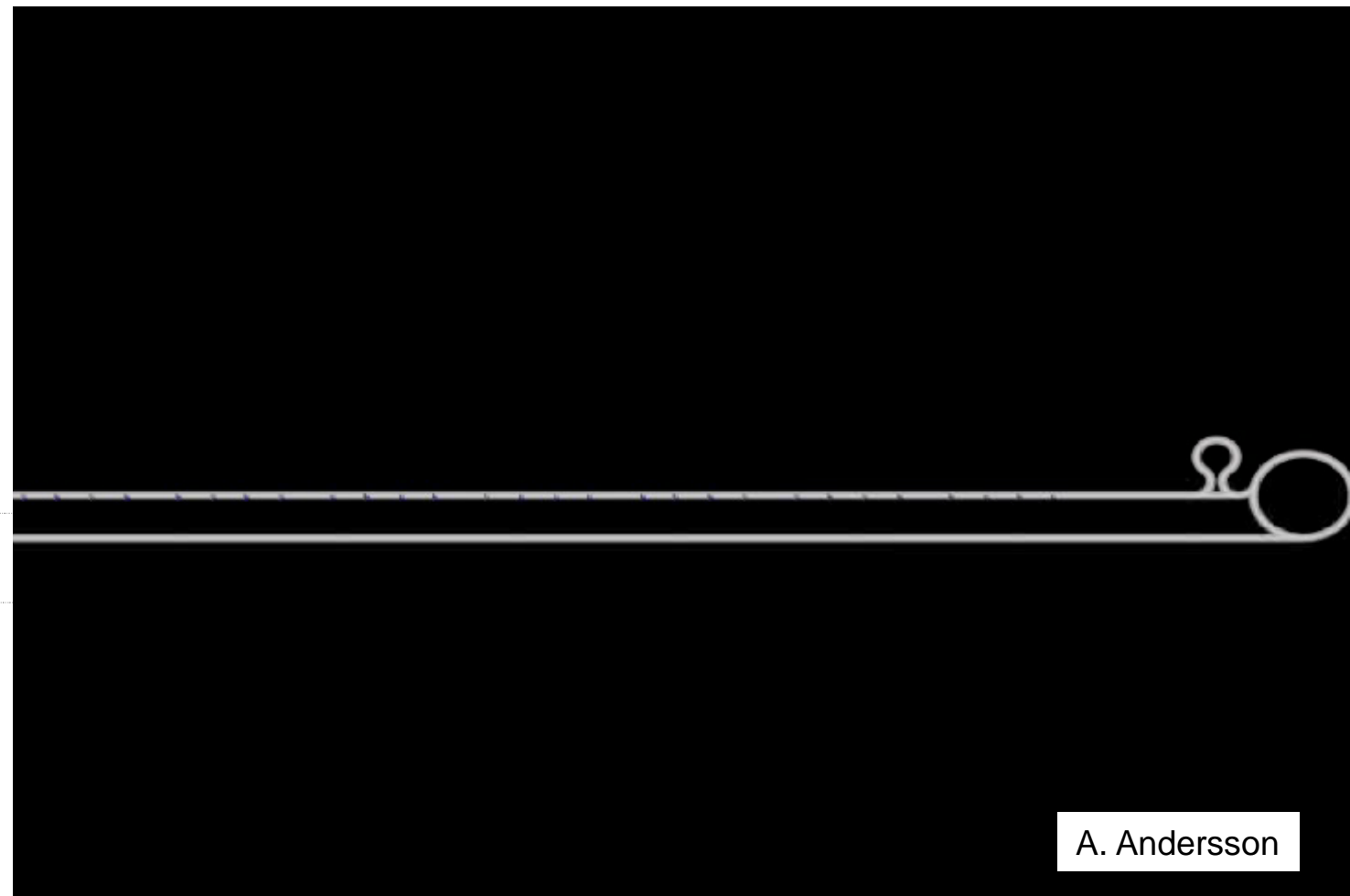
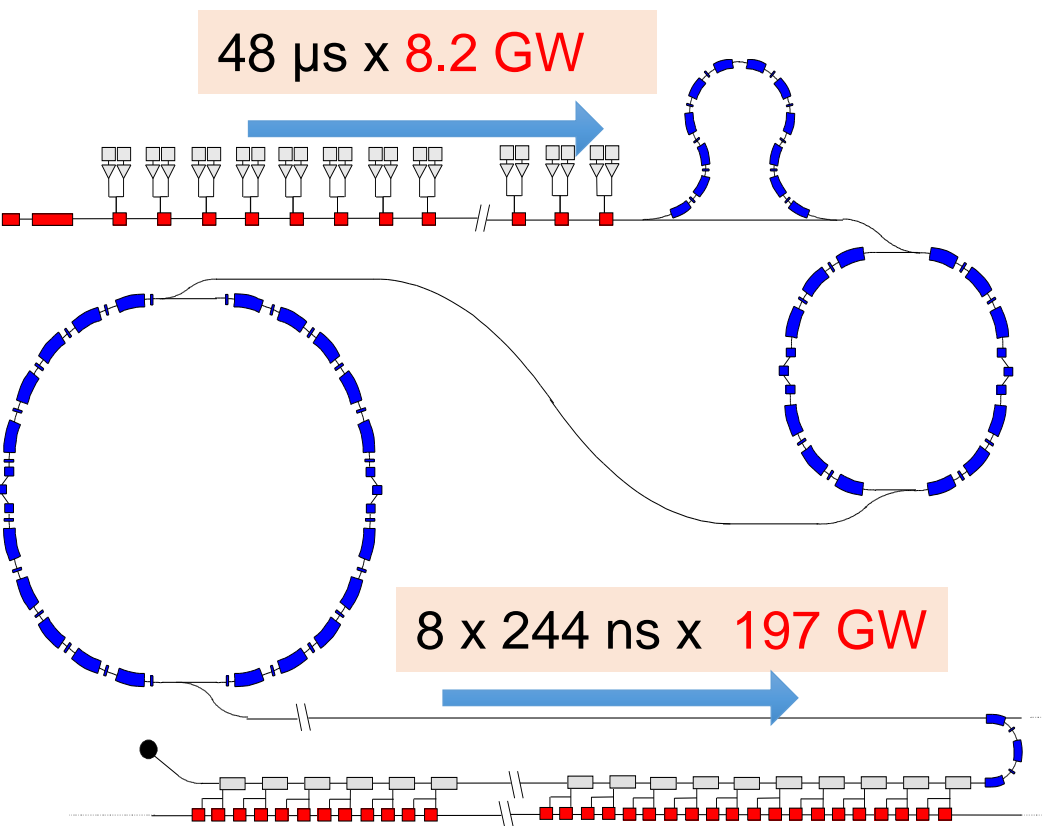
Pulse length: 48 μs



- CR combiner ring
- TA turnaround
- DR damping ring
- PDR predamping ring
- BC bunch compressor
- BDS beam delivery system
- IP interaction point
- █ dump



Drive Beam Combination Concept



A. Andersson

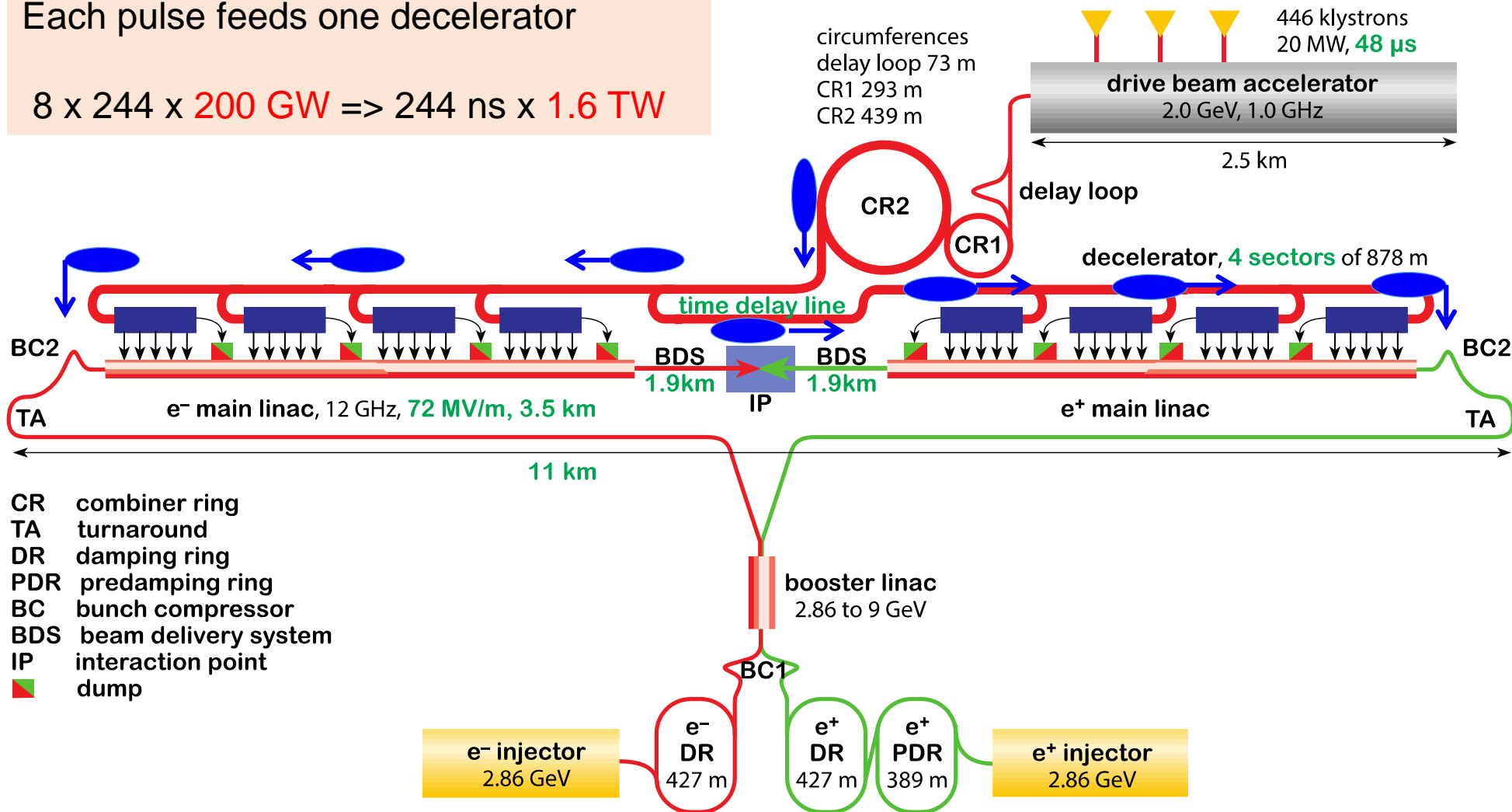


Power Production: Drive Beam Distribution



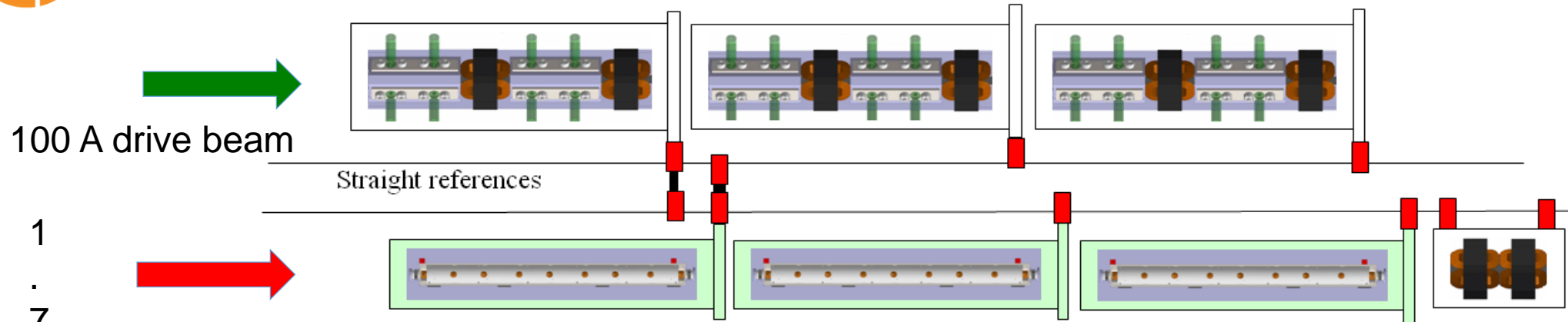
Each pulse feeds one decelerator

$$8 \times 244 \times 200 \text{ GW} \Rightarrow 244 \text{ ns} \times 1.6 \text{ TW}$$





Two-beam Module Concept



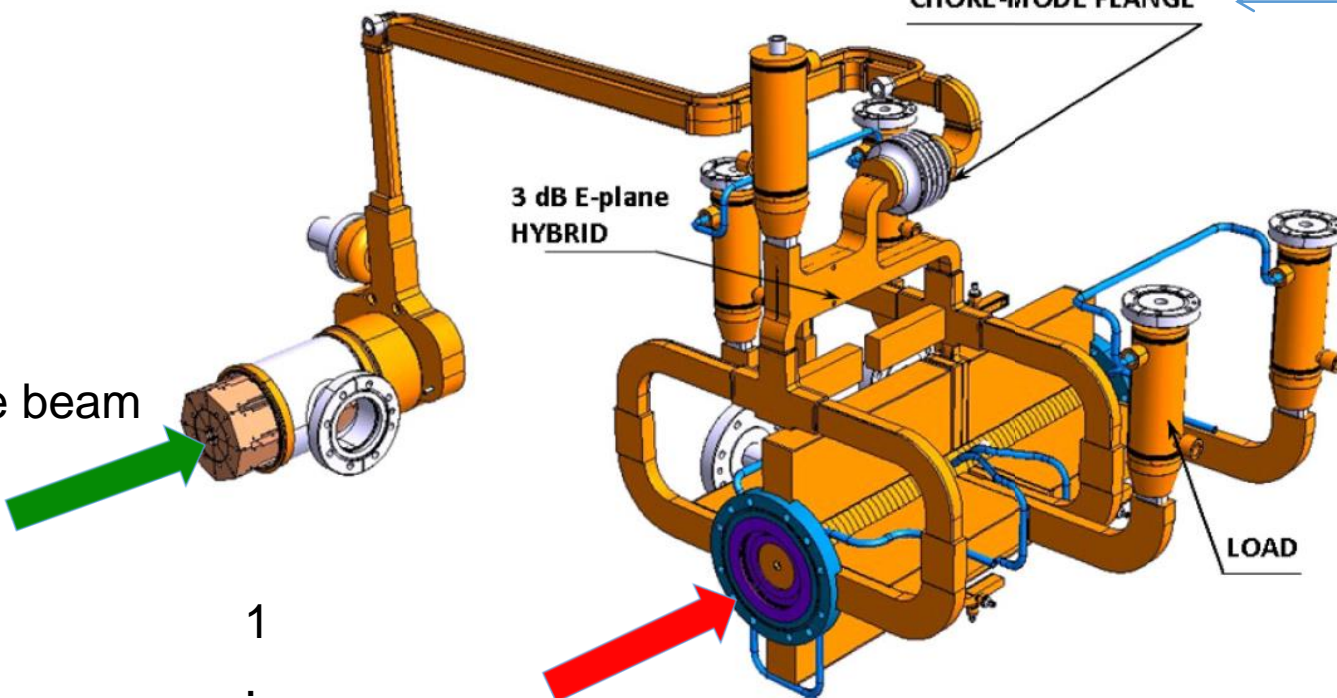
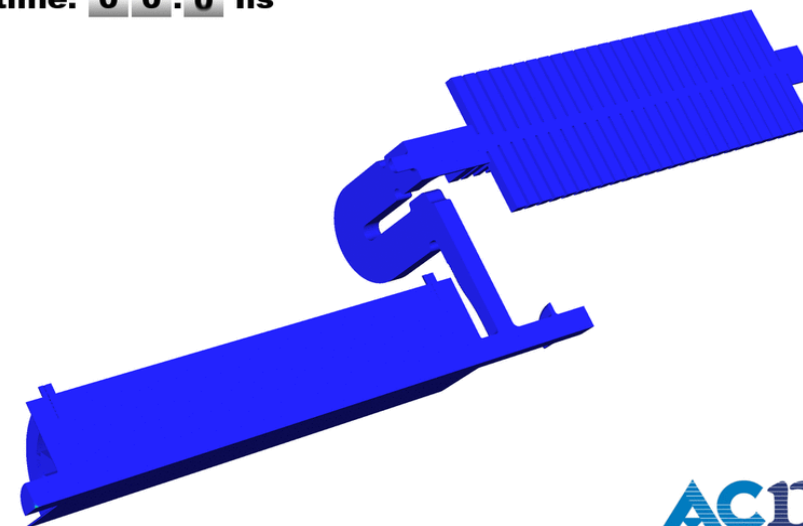
CHOKE-MODE FLANGE

2.2m

time: 00.0 ns

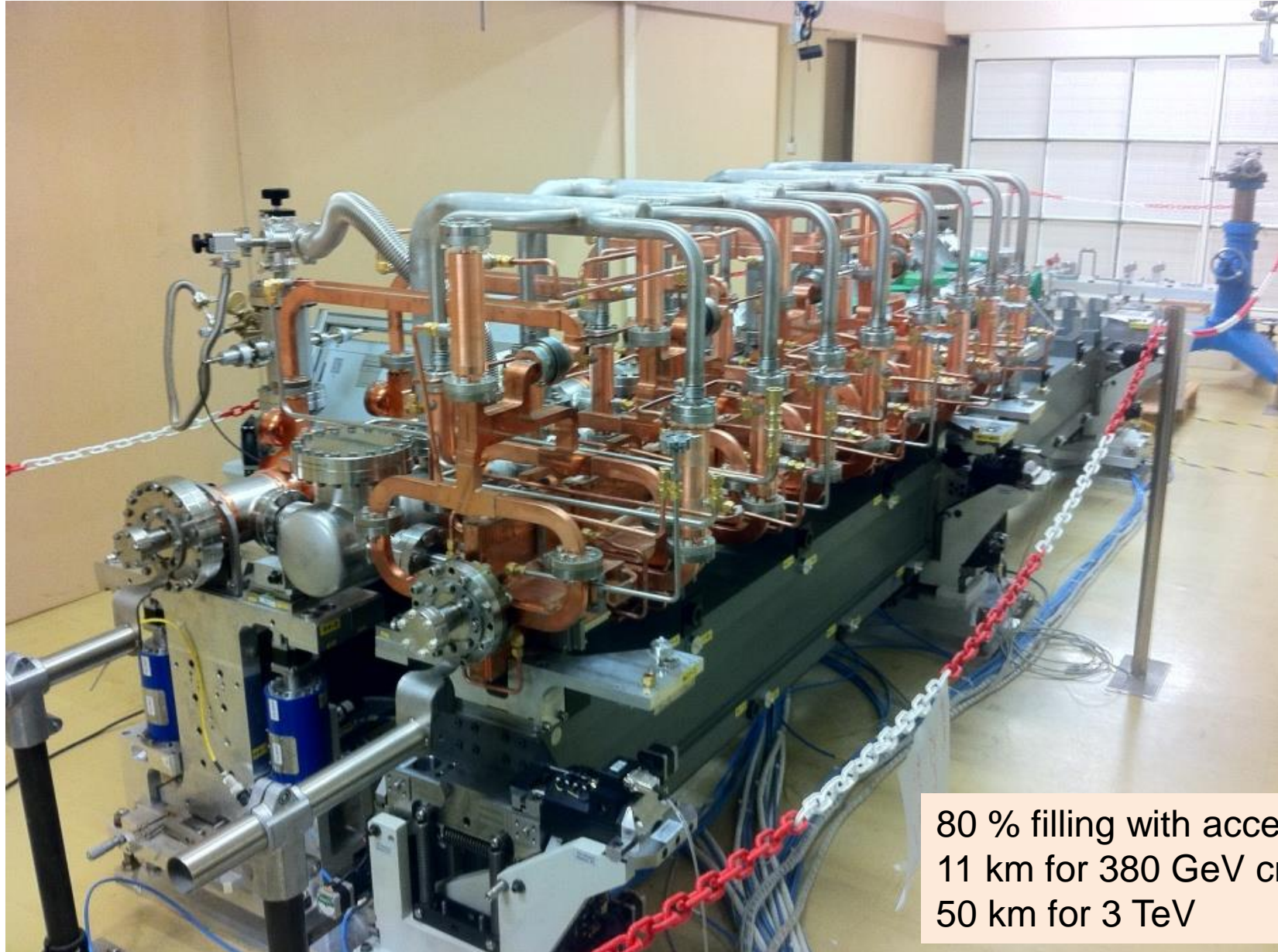
3 dB E-plane HYBRID

LOAD

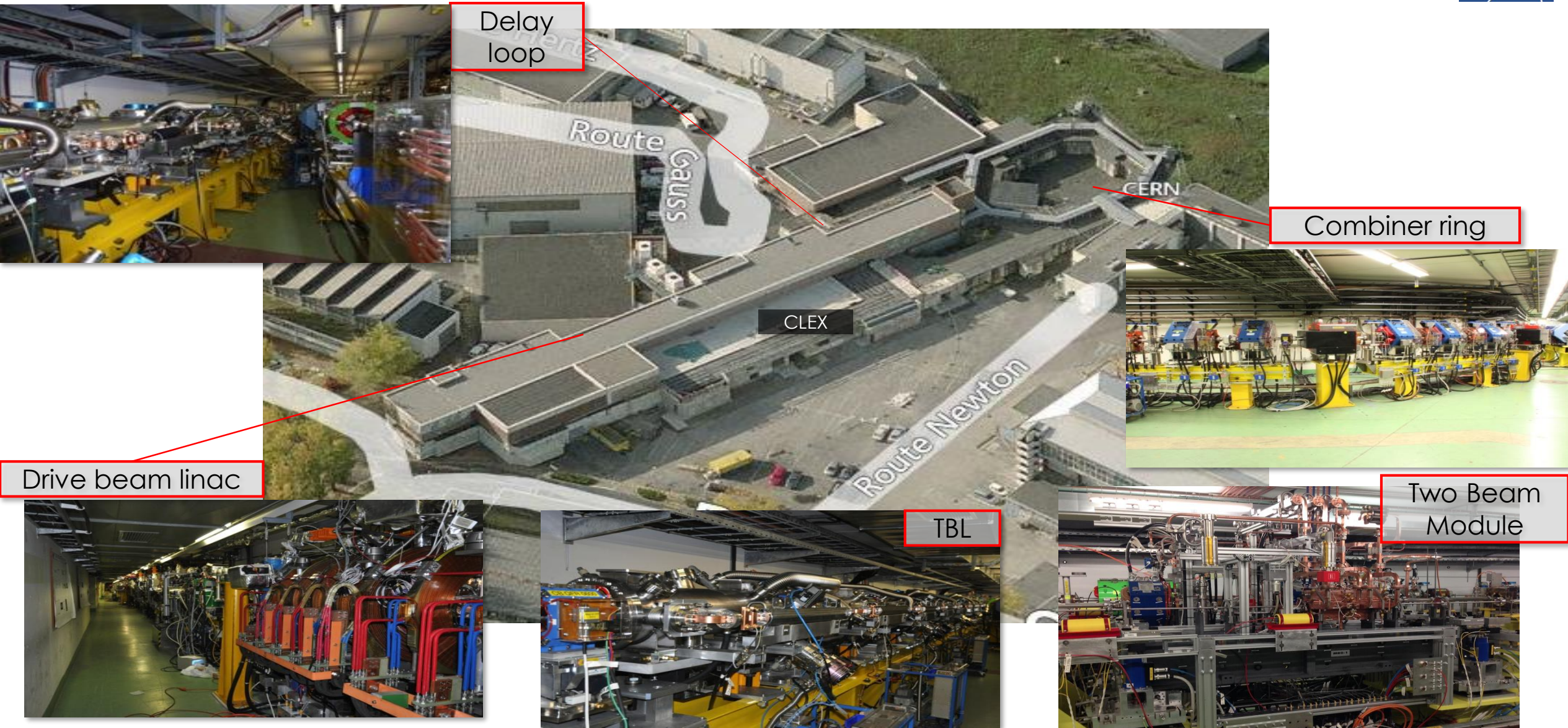


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80 % filling with accelerating structures
11 km for 380 GeV cms
50 km for 3 TeV



Drive beam linac

Delay loop

Combiner ring

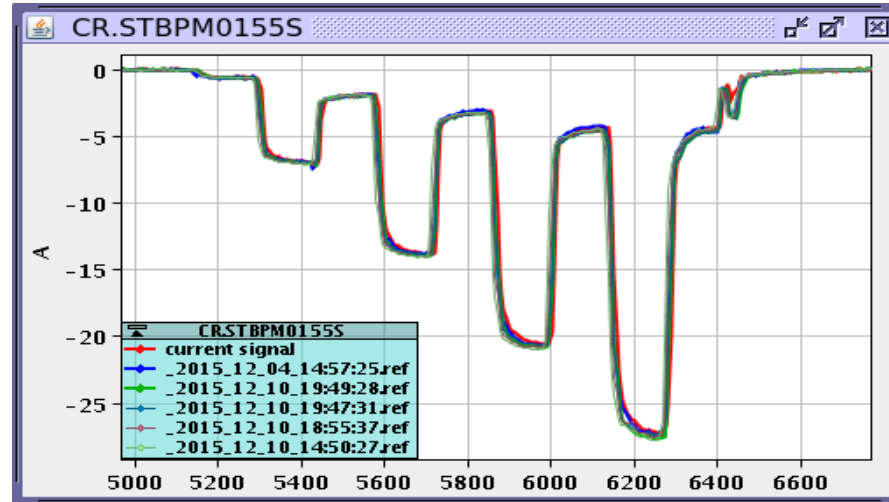
Two Beam Module

TBL

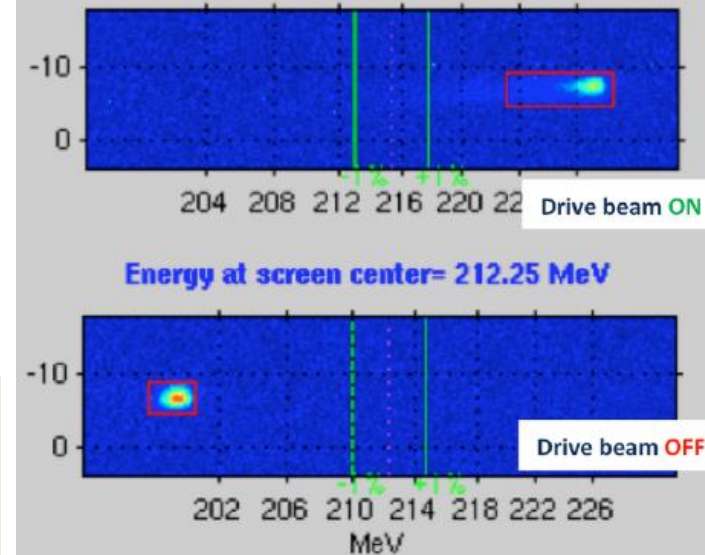
CTF3 measurements:

- RF to drive beam efficiency > 95%
- Current multiplication factor 8
- Most of beam quality
- 145 MV/m X-band acceleration

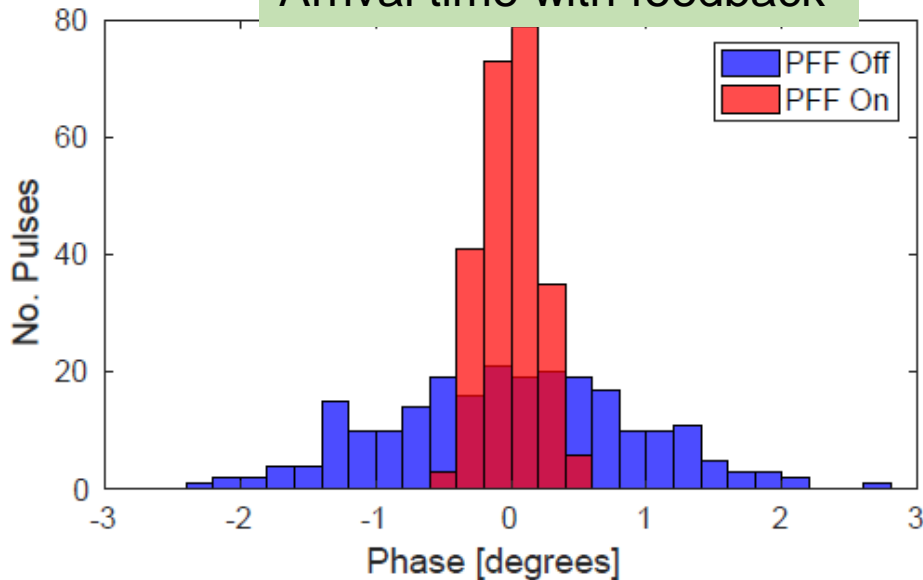
Detailed simulations of drive beam performance in CLIC



Measured 145 MV/m gradient

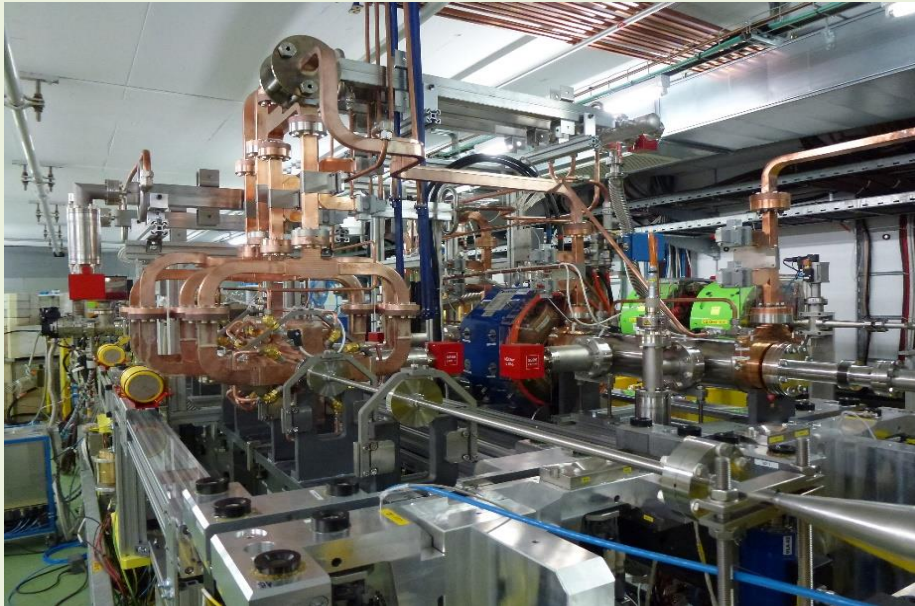


Arrival time with feedback



Current stability affected by very low CTF3 energy, 3 x larger beam and delay loop design different from CLIC

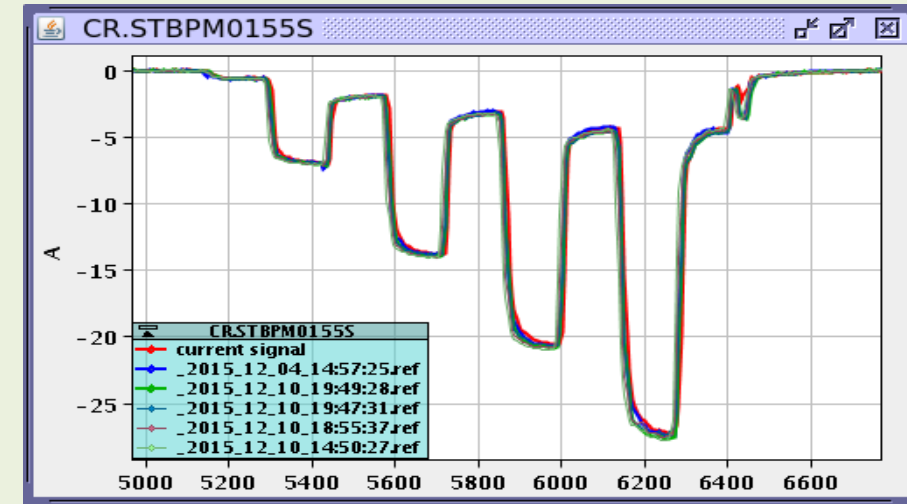
Parameter	CLIC goal	CTF3 measured
Arrival time	50 fs	50 fs
Current after linac	0.75×10^{-3}	$0.2-0.4 \times 10^{-3}$
Current at end	0.75×10^{-3}	$2-18 \times 10^{-3}$
Energy	1.0×10^{-3}	0.7×10^{-3}



CTF3 has demonstrated drive beam production and main beam acceleration

- Technology
- Beam quality
- Operation

Now stopped



New facility is coming online: CLEAR
CERN Linear Electron Accelerator for Research

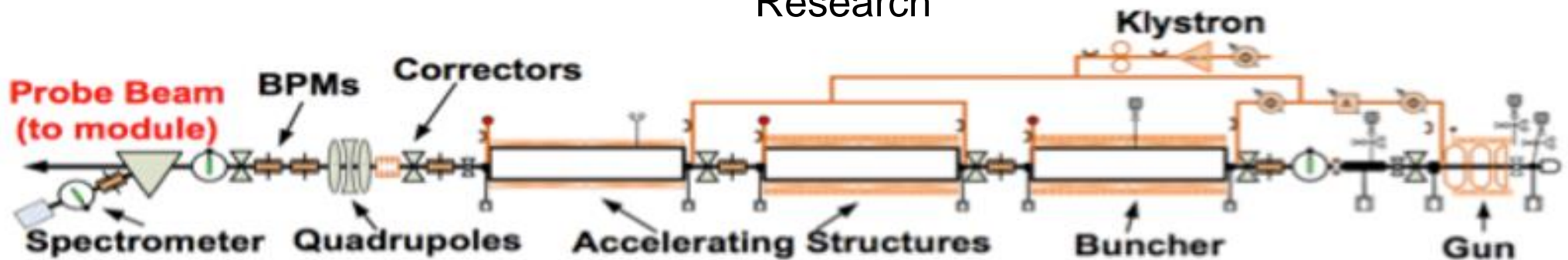


Figure 1: The current CALIFES beam line. The length of the facility (as shown) is ~20m.

Can re-write normal
luminosity formula

$$\mathcal{L} = H_D \frac{N^2}{4\pi\sigma_x\sigma_y} n_b f_r$$

$$\mathcal{L} \propto H_D \frac{N}{\sigma_x} \overset{\text{Beam current}}{N n_b f_r} \frac{1}{\sigma_y} \overset{\text{Beam Quality (+bunch length)}}{}$$

Need to ensure that we can achieve each parameter

Can re-write normal
luminosity formula

$$\mathcal{L} = H_D \frac{N^2}{4\pi\sigma_x\sigma_y} n_b f_r$$

The limit is the beam
stability in the main linac

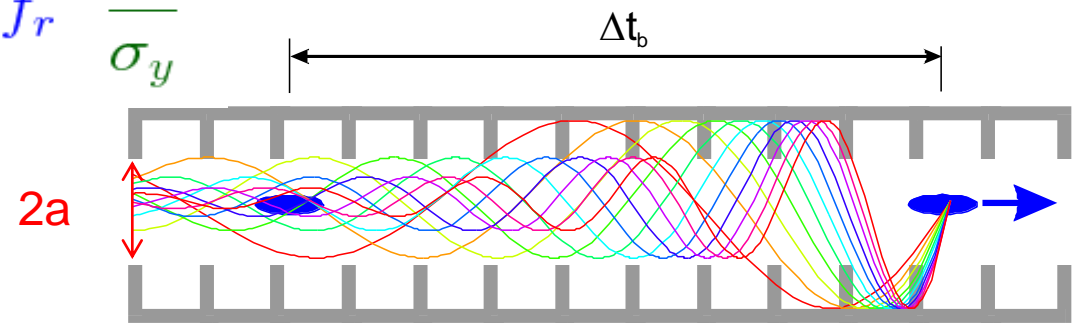
$$\mathcal{L} \propto H_D \frac{N}{\sigma_x} N n_b f_r \frac{1}{\sigma_y}$$

↑ ↑ ↑
Luminosity spectrum Beam current Beam Quality (+bunch length)

Need to ensure that we can achieve each parameter

Goal: maximise beam current
 ⇒ Maximise bunch charge
 ⇒ Minimise distance between bunches

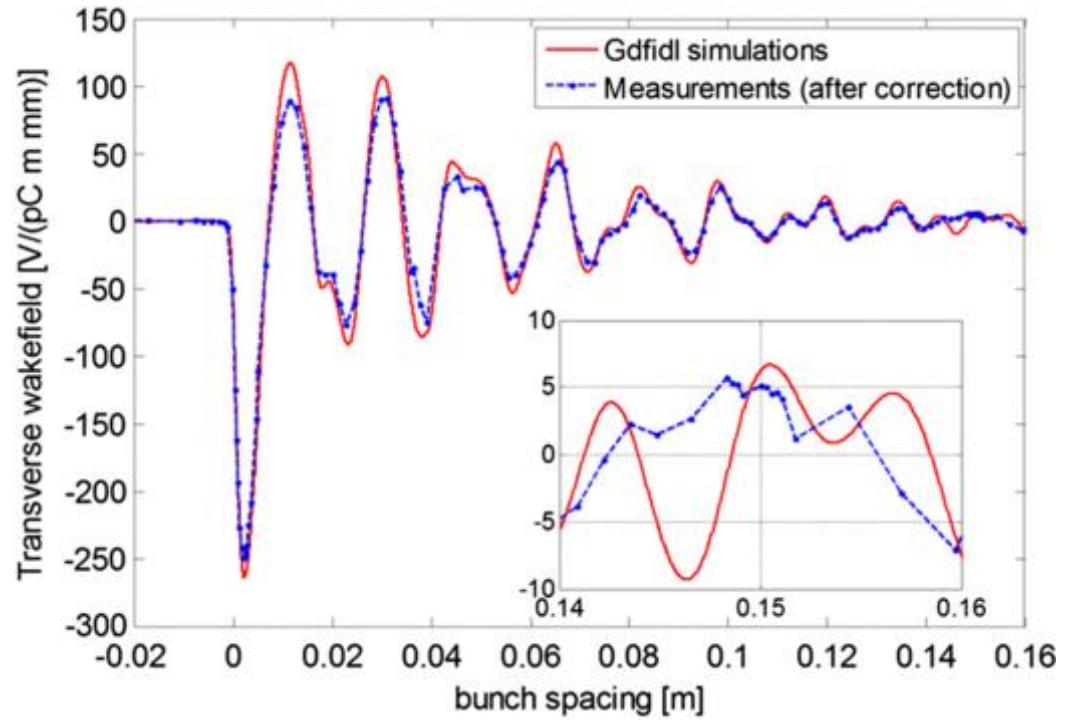
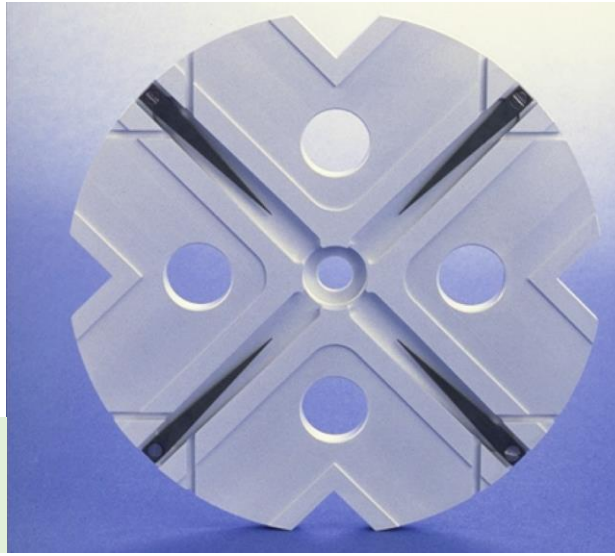
$$\mathcal{L} \propto H_D \frac{N}{\sigma_x} N n_b f_r \frac{1}{\sigma_y}$$



Limits are given by wakefields:
 With an offset particles produce transverse wakefields
 ⇒ The head kicks the tail, force is defocusing
 ⇒ Can render beam unstable

RF team loves small **a**
 Less power
 easier to reach gradient

Beam team hates small **a**
 More wakefields
 Beam less stable



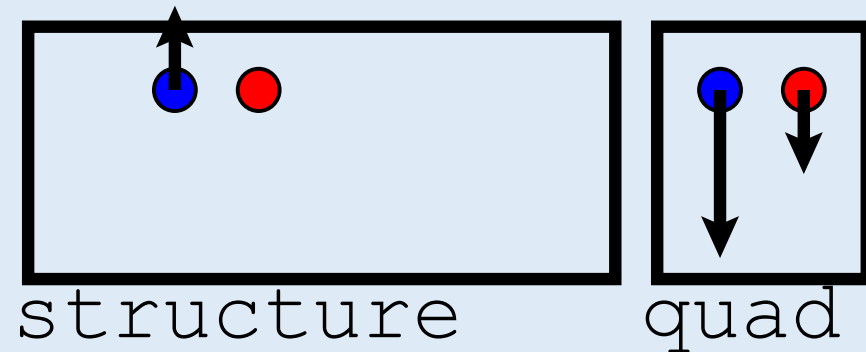
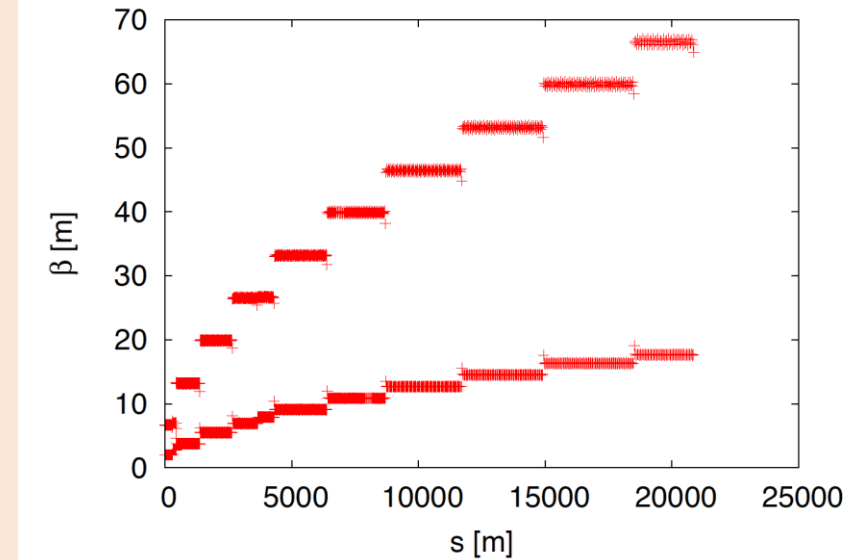
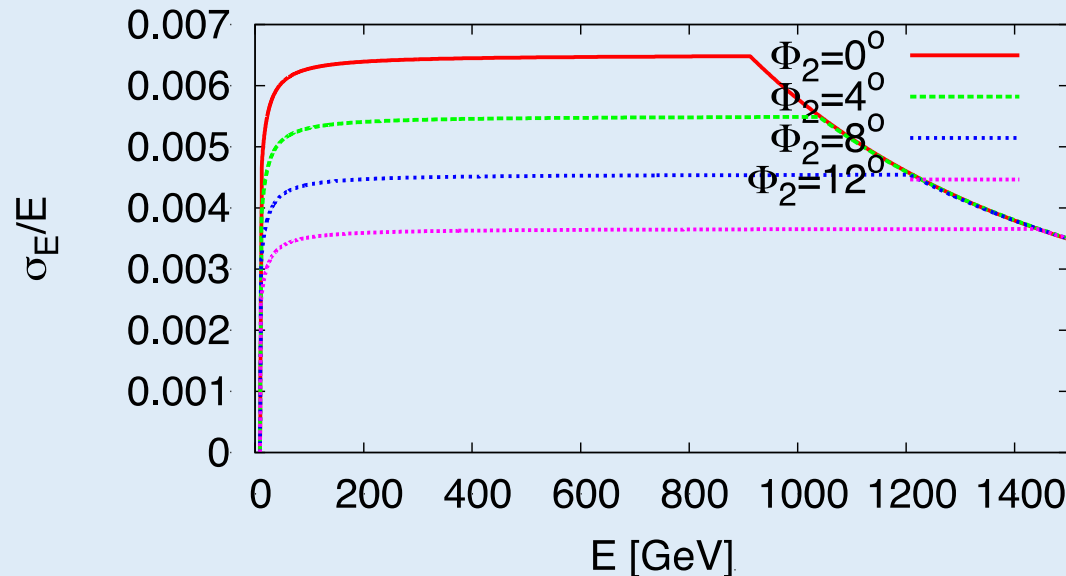
Multi-bunch wakefields minimised
 by damping and detuning

Make the focus strong again

- Use O(10%) of the linac for magnets
- Leads to small beta-function
- Makes the beam stable (strong spring for an oscillator)

For single bunch use BNS damping (Balakin, Novokhatsky and Smirnov)

- Introduce energy chirp that compensates transverse wakefields





Beam Stability, With BNS

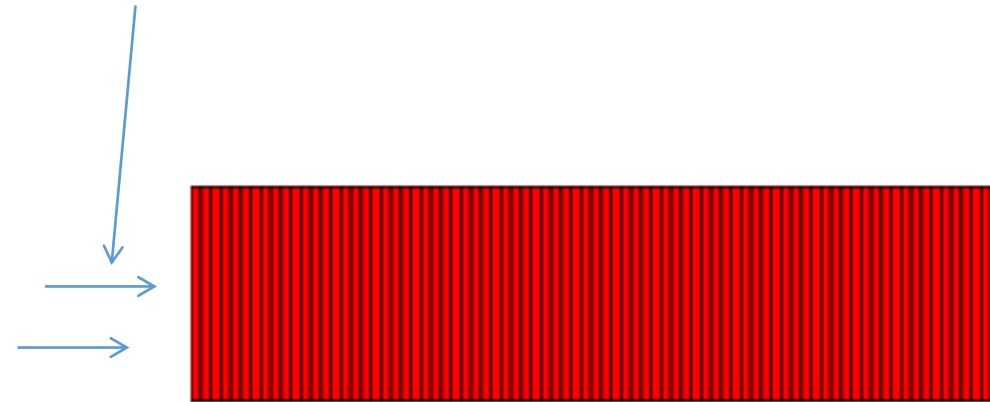
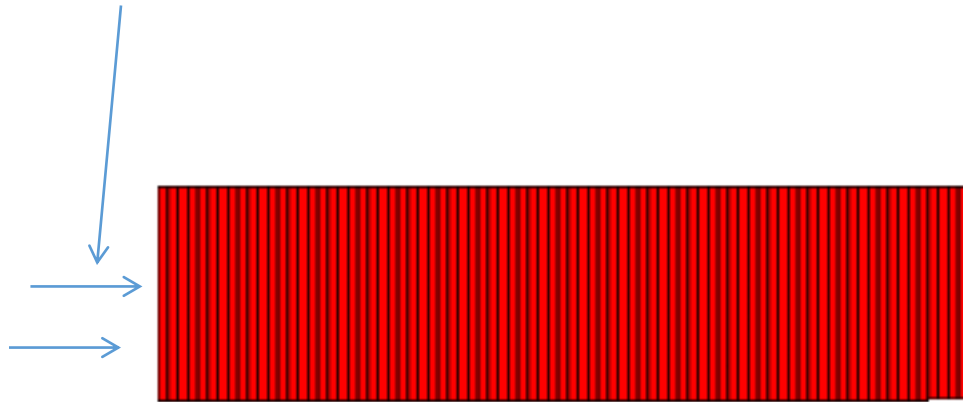


No BNS damping

With BNS damping

Offset beam centre at injection

Offset beam centre at injection



Direction of motion

Direction of motion

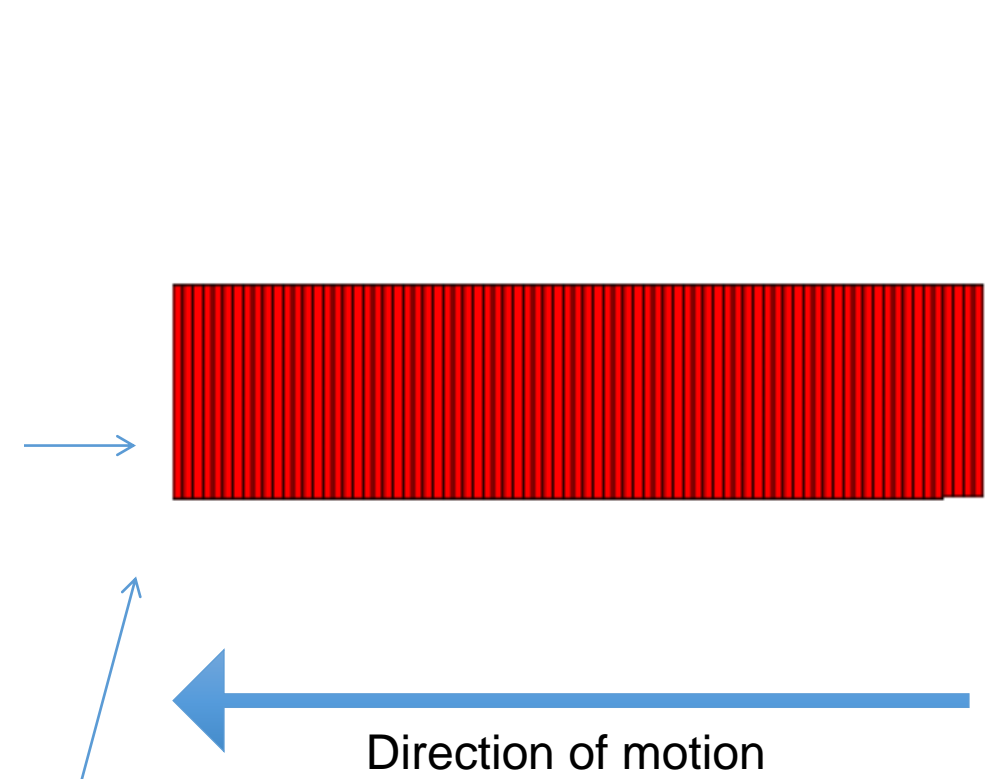


Beam Stability, With BNS



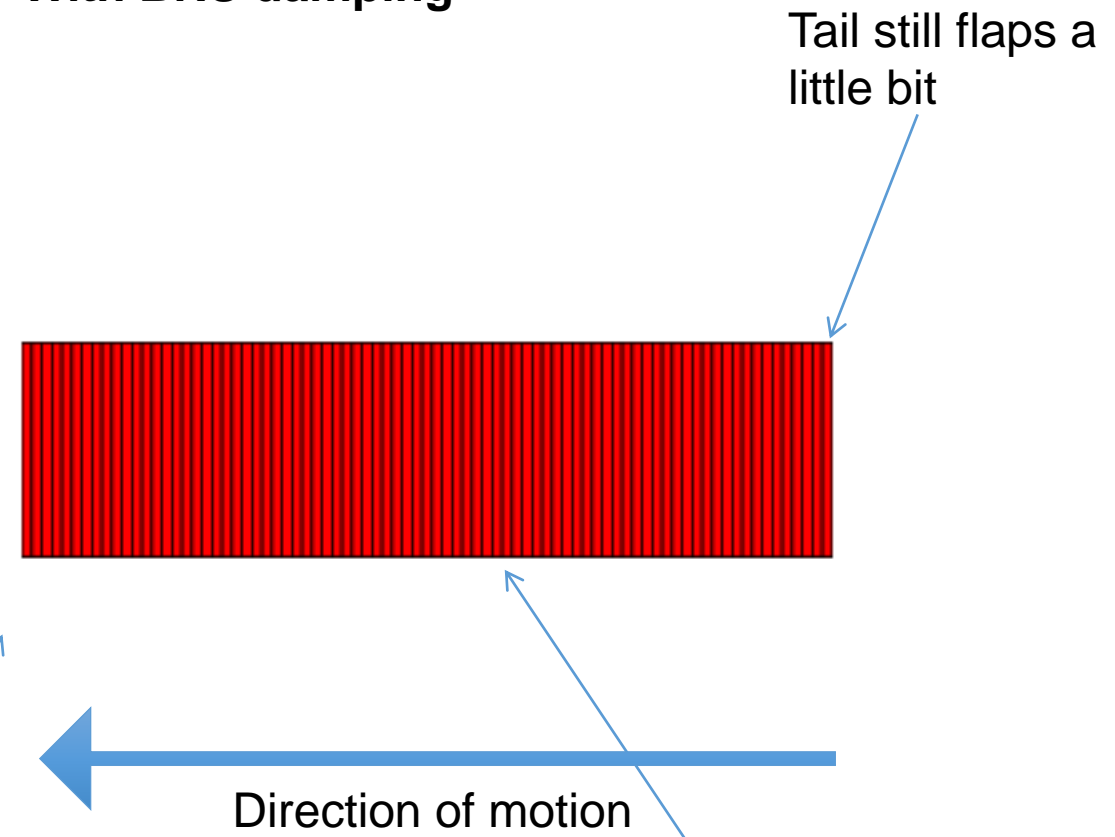
No BNS damping

With BNS damping



Tail and centre flap quite a lot

Simple betatron oscillation



Tail still flaps a little bit

Centre of bunch is much more stable



Damping ring main source of horizontal emittance
But value is OK, as we will see

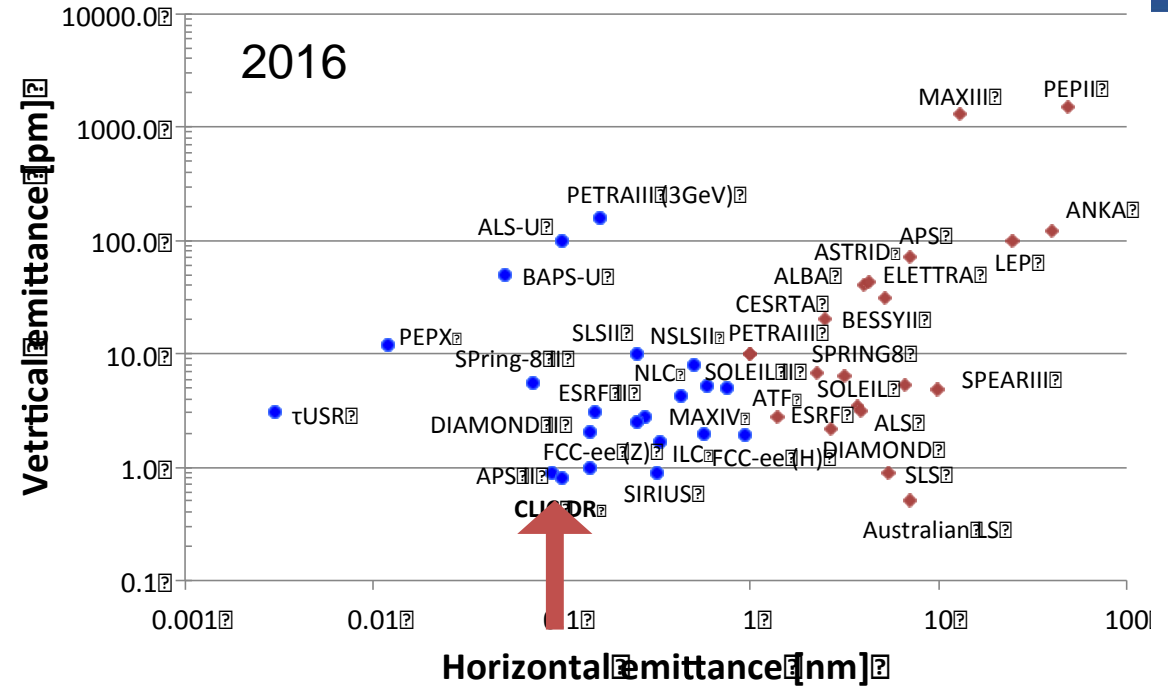
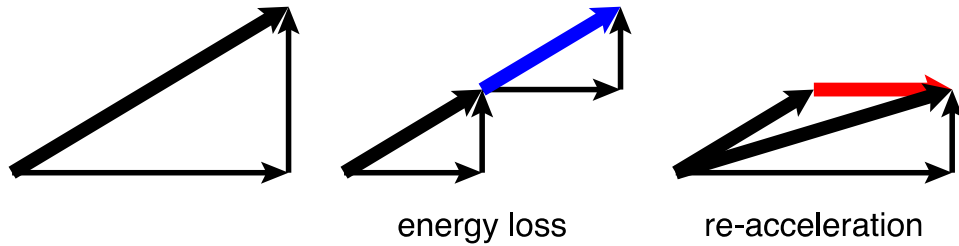
$$\mathcal{L} \propto H_D \frac{N}{\sigma_x} N n_b f_r \left(\frac{1}{\sigma_y} \right) \sigma_y = \sqrt{\beta_y \epsilon_y / \gamma}$$

	$\Delta\epsilon_x$ [nm]	$\Delta\epsilon_y$ [nm]		
	Total contribution	Design limits	Static imperf.	Dynamic imperf.
Damping ring exit	700	5	0	0
End of RTML	150	1	2	2
End of main linac	50	0	5	5
Interaction point	50	0	5	5
sum	950	6	12	12

Imperfections are the main source of final vertical emittance

Require 90% likelihood to meet static emittance growth target

Cool the beams from the sources



Important progress in collaboration with light source community

Studies of lattice and collective effects show that emittance targets can be reached for 3 TeV

Currently optimising for 380 GeV

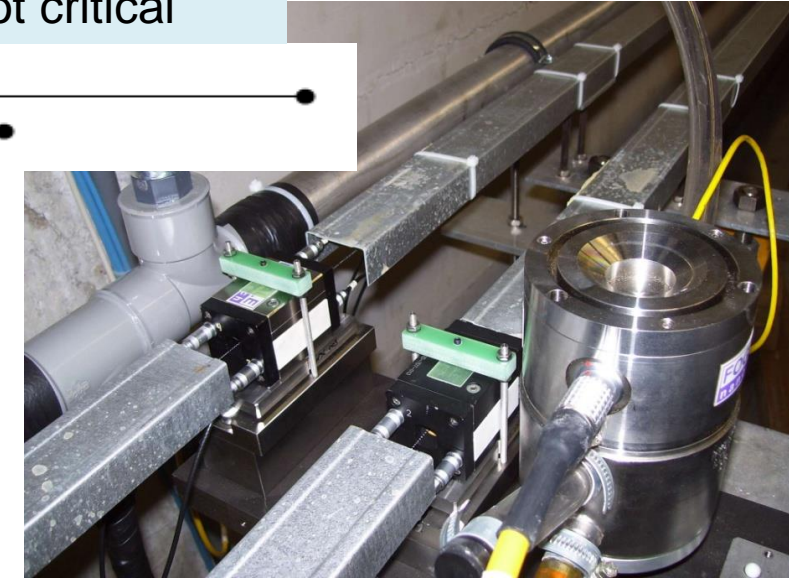
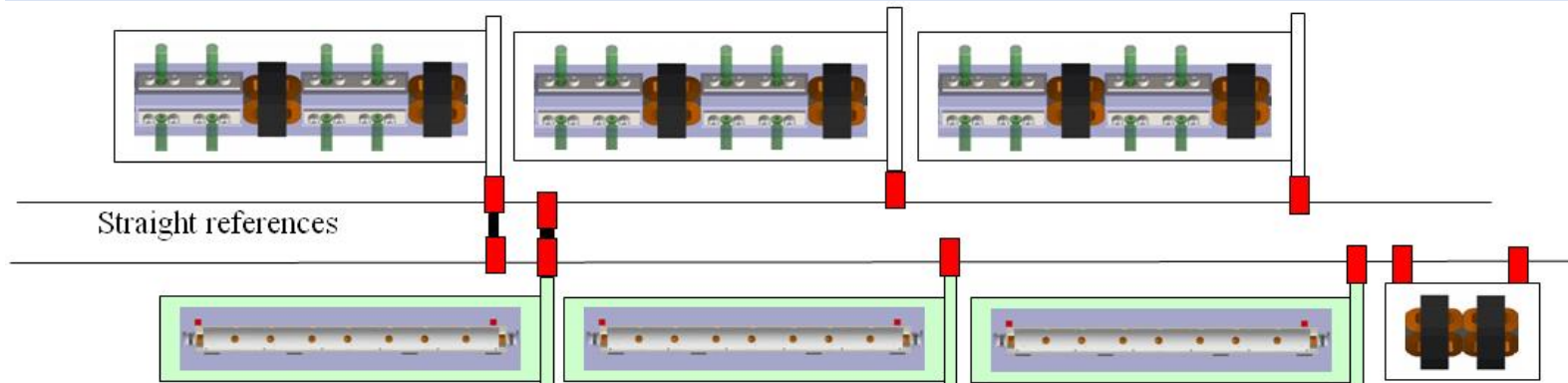


1) Align components accurately on the supporting girders

2) Establish reference system with overlapping wires, has some error but is not critical



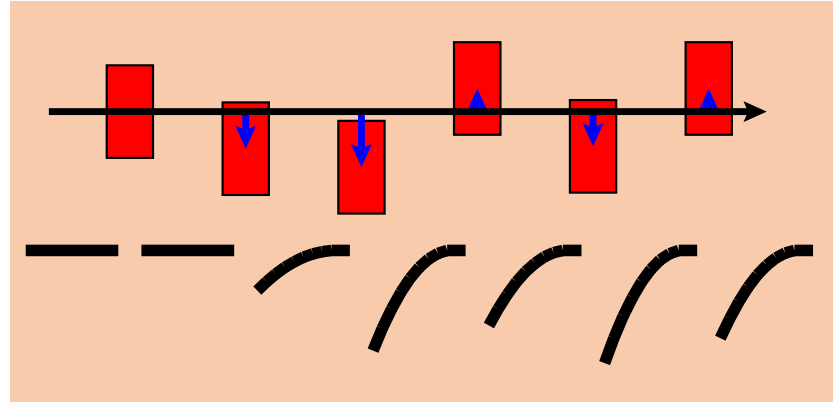
3) Align modules remotely to the wires using their sensors and movers



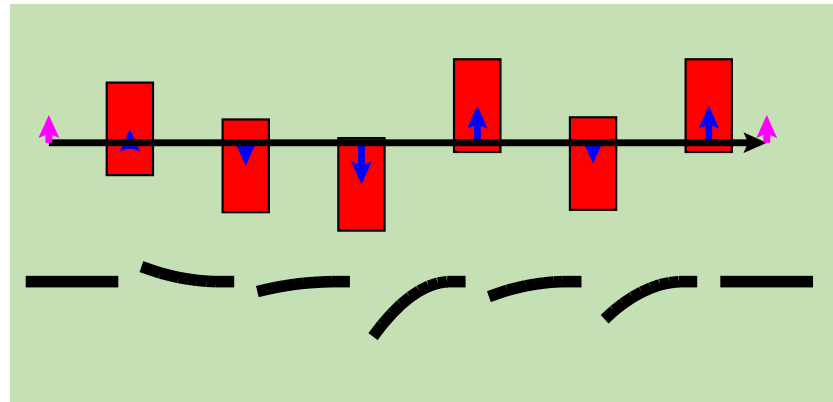
The error for this is most critical misalignment of components is of the order $O(10\mu\text{m})$

4) Use sophisticated beam-based alignment such as dispersion free steering (DFS, i.e. different energy beams) to align components
In particular to align BPMs

Structures scattered on girder
 ⇒ Wakefield kick

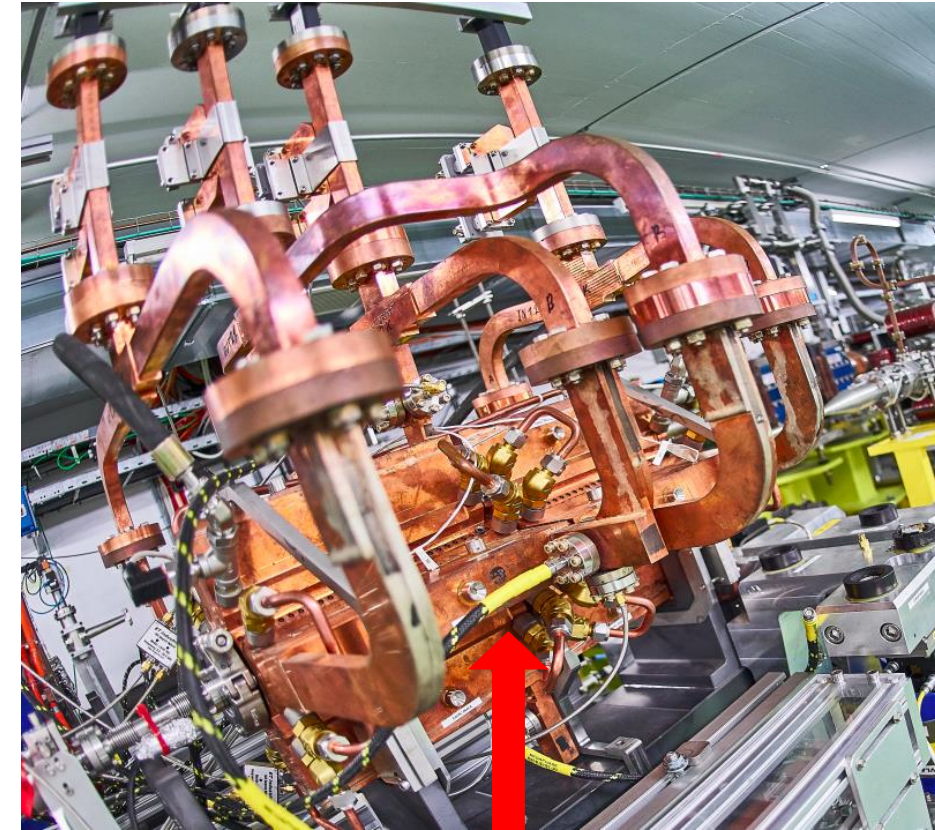


5) Measure beam offset with
 wakefield monitor
 Move girder to remove mean
 offset
 ⇒ No net wakefield kick



Limit mainly from

- wakefield monitor accuracy (3.5 μm)
- reproducibility of wakefield
- tiny variation of betatron phase along girder



Wakefield monitor:
 Measure wakefield in damping waveguide



Main Linac Emittance Growth (3 TeV)



Emittance growth for different imperfections

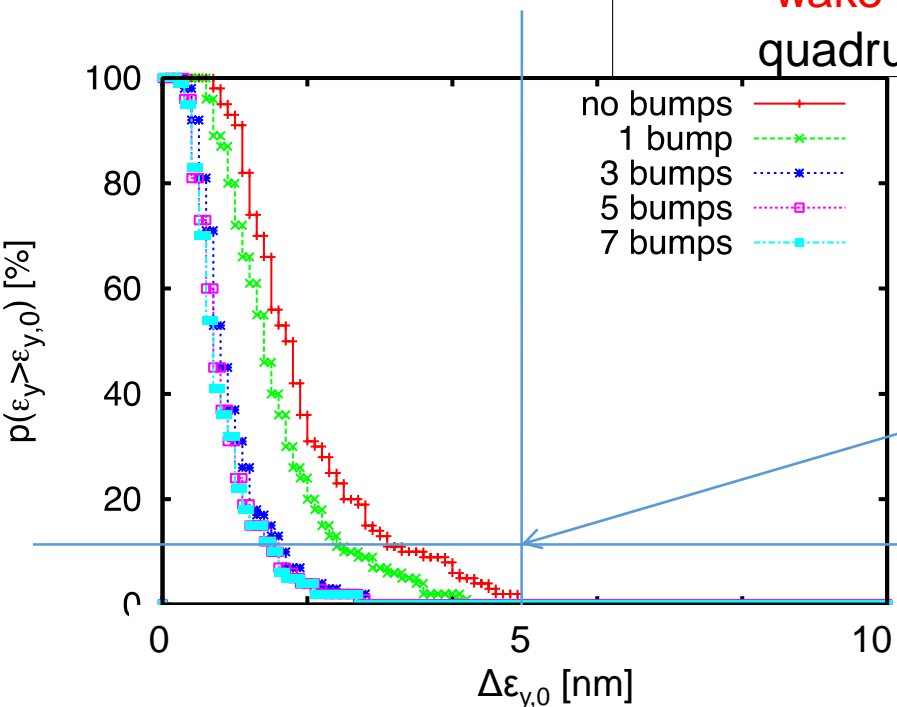
Using sophisticated beam-based methods

imperfection	with respect to	symbol	value	emitt. growth
BPM offset	wire reference	σ_{BPM}	14 μm	0.367 nm
BPM resolution		σ_{res}	0.1 μm	0.04 nm
accelerating structure offset	girder axis	σ_4	10 μm	0.03 nm
accelerating structure tilt	girder axis	σ_t	200 μradian	0.38 nm
articulation point offset	wire reference	σ_5	12 μm	0.1 nm
girder end point	articulation point	σ_6	5 μm	0.02 nm
wake monitor	structure centre	σ_7	3.5 μm	0.54 nm
quadrupole roll	longitudinal axis	σ_r	100 μradian	≈ 0.12 nm

Note: The tight tolerances are the price for the strong focusing, Which allowed high beam current

Goal: less than 10% above $\Delta\epsilon_y = 5$ nm

Further improvement using tuning bumps





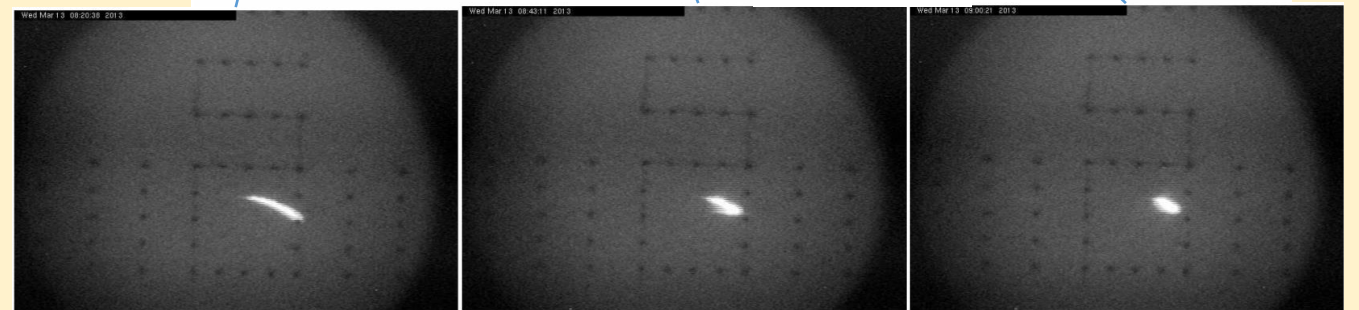
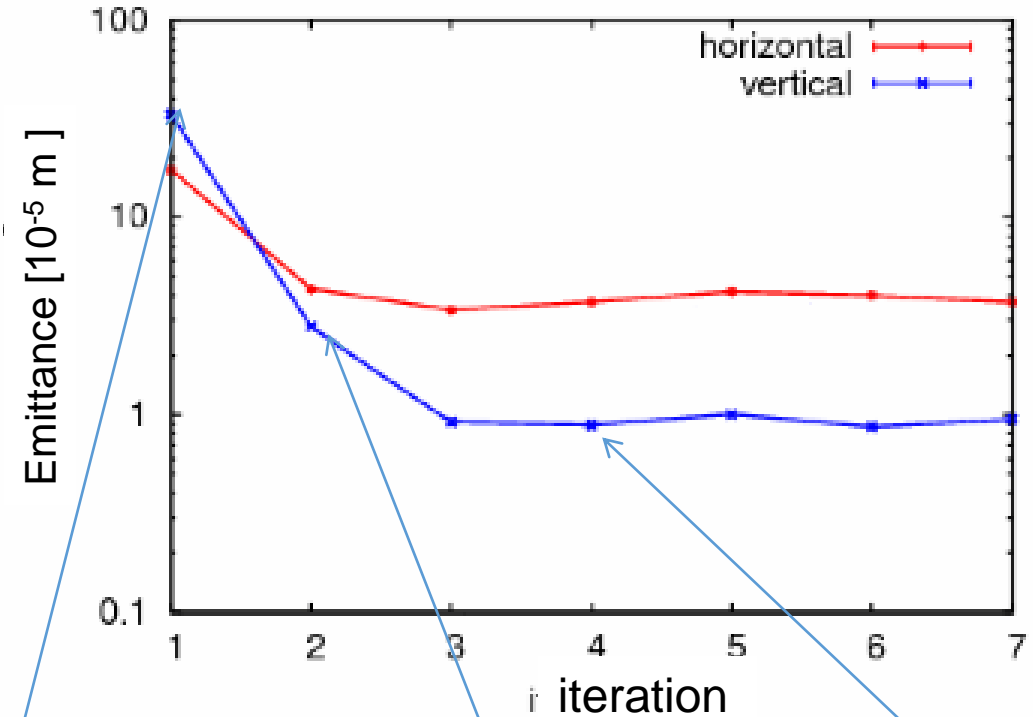
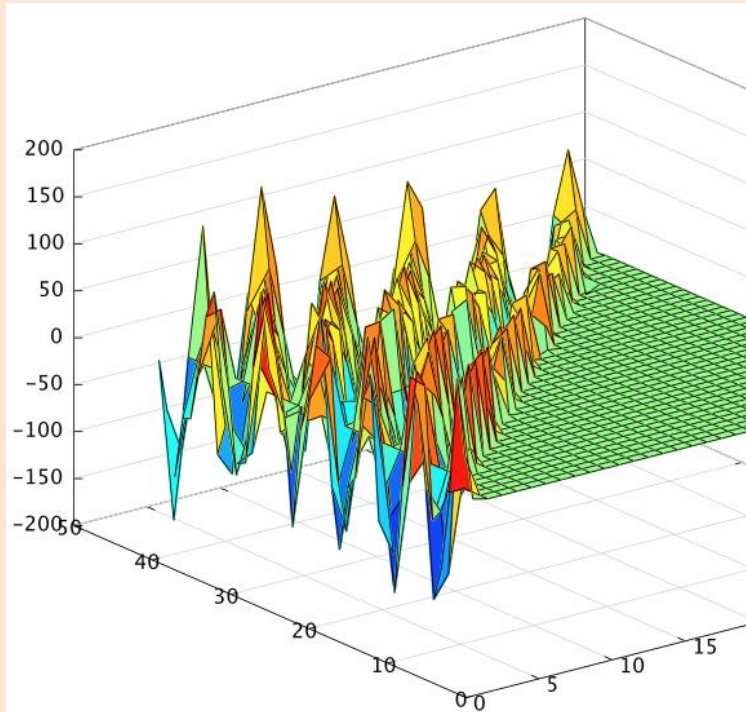
CLIC Beam-Based Alignment Tests at FACET



DFS applied to 500 meters of SLC linac

- System identification algorithms to construct model
- DFS correction with GUI
- Emittance growth is measured

System model

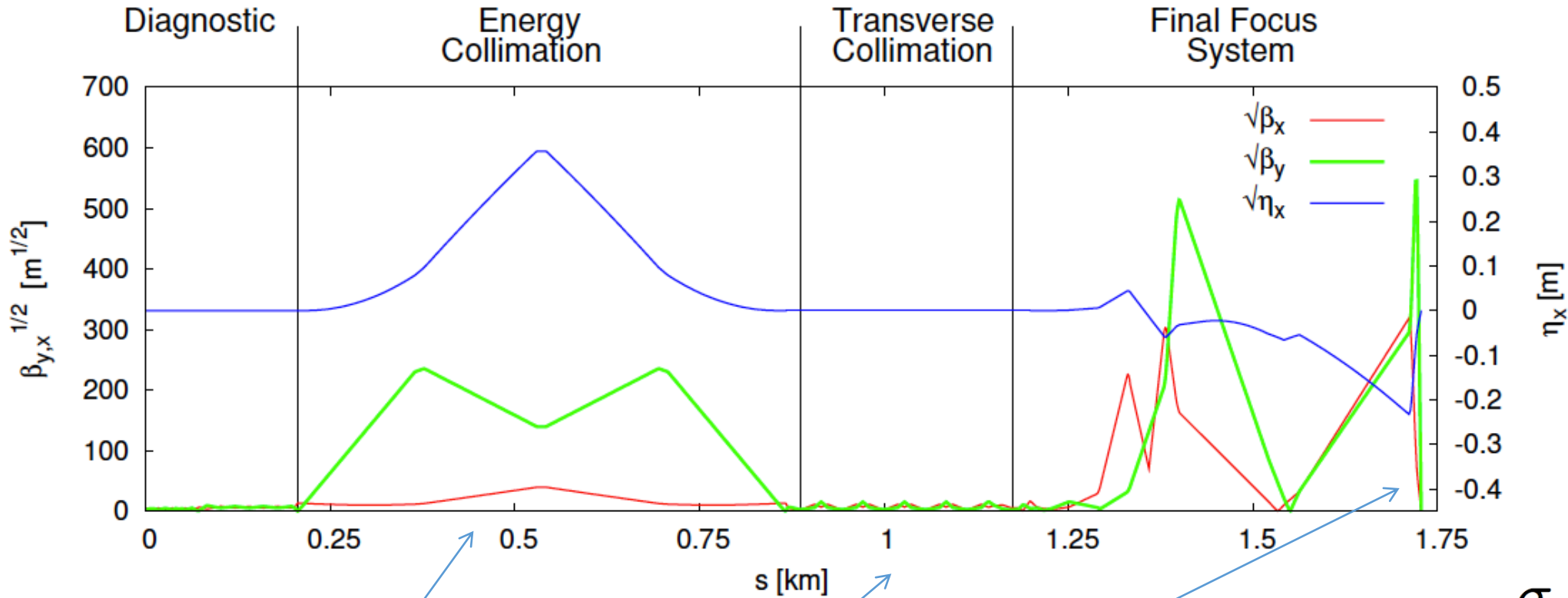


Initial beam

After 1 iteration

After 3 iterations





Removes longitudinal tails
Protection from RF failures

Cleaning transverse halo
Protection from transverse jitter

Squeezing beam to minimum size

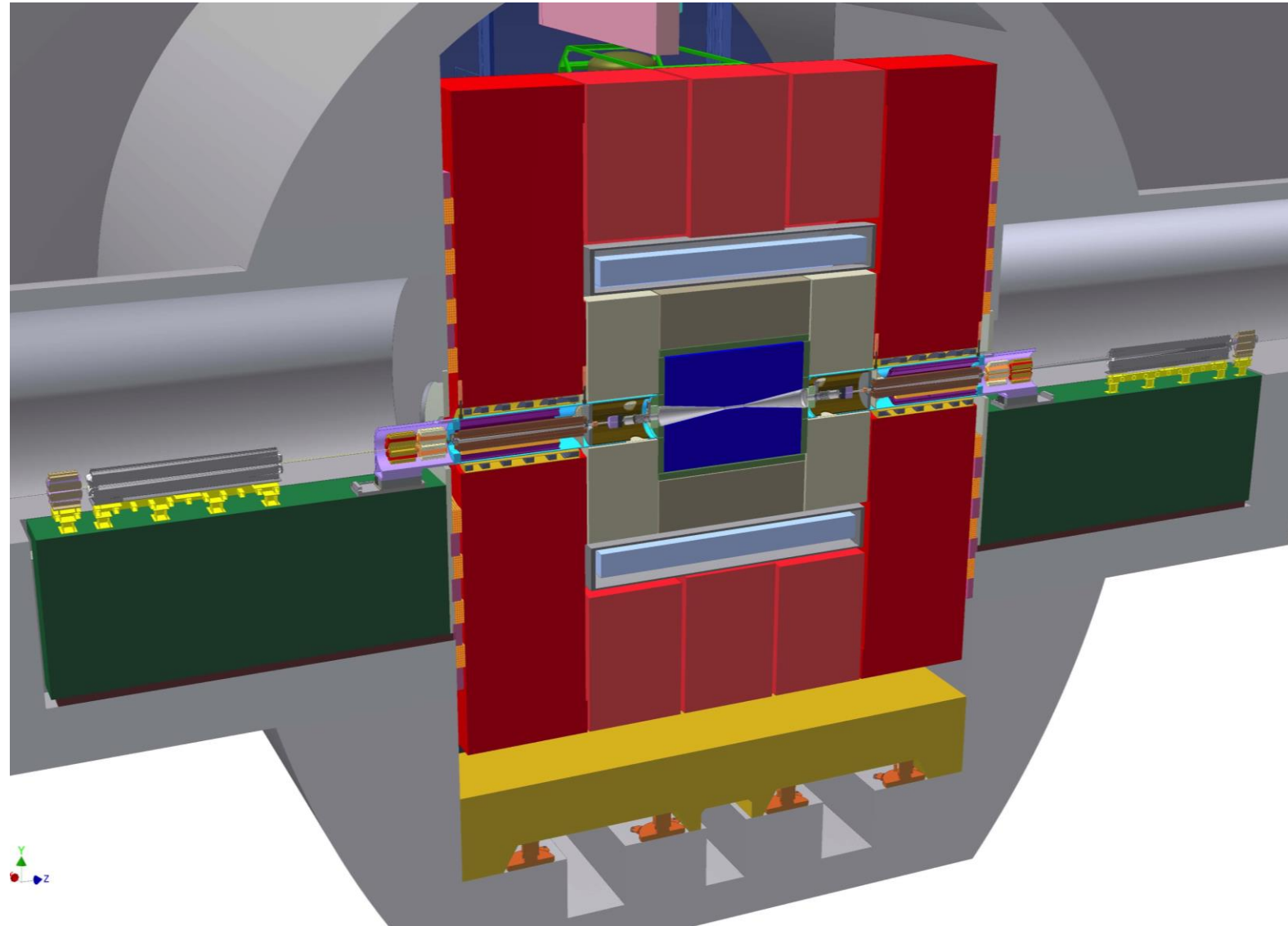
$$\sigma_y = \sqrt{\beta_y \epsilon_y / \gamma}$$

Goal 143 nm x 2.9 nm

$\beta_x = 8$ mm, $\beta_y = 0.1$ mm

First magnet has been at $L^* = 3.5$ m from the interaction point, inside of detector

Short L^* limits chromaticity, the main challenge

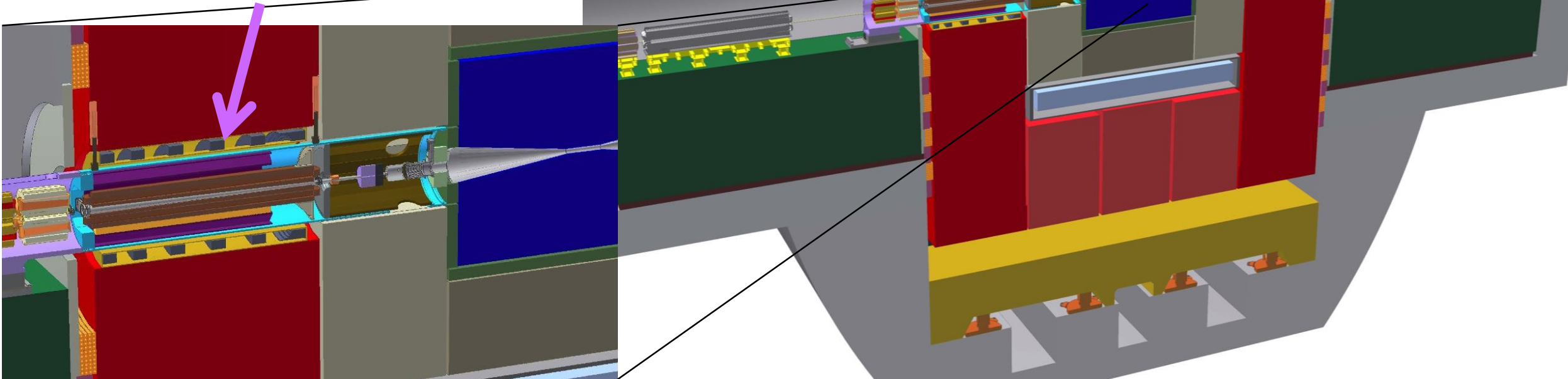


First magnet has been at $L^* = 3.5$ m from the interaction point, inside of detector

Limited angular coverage of detector

Magnet is put on cantilever from tunnel

Magnet needed to be shielded from detector solenoid



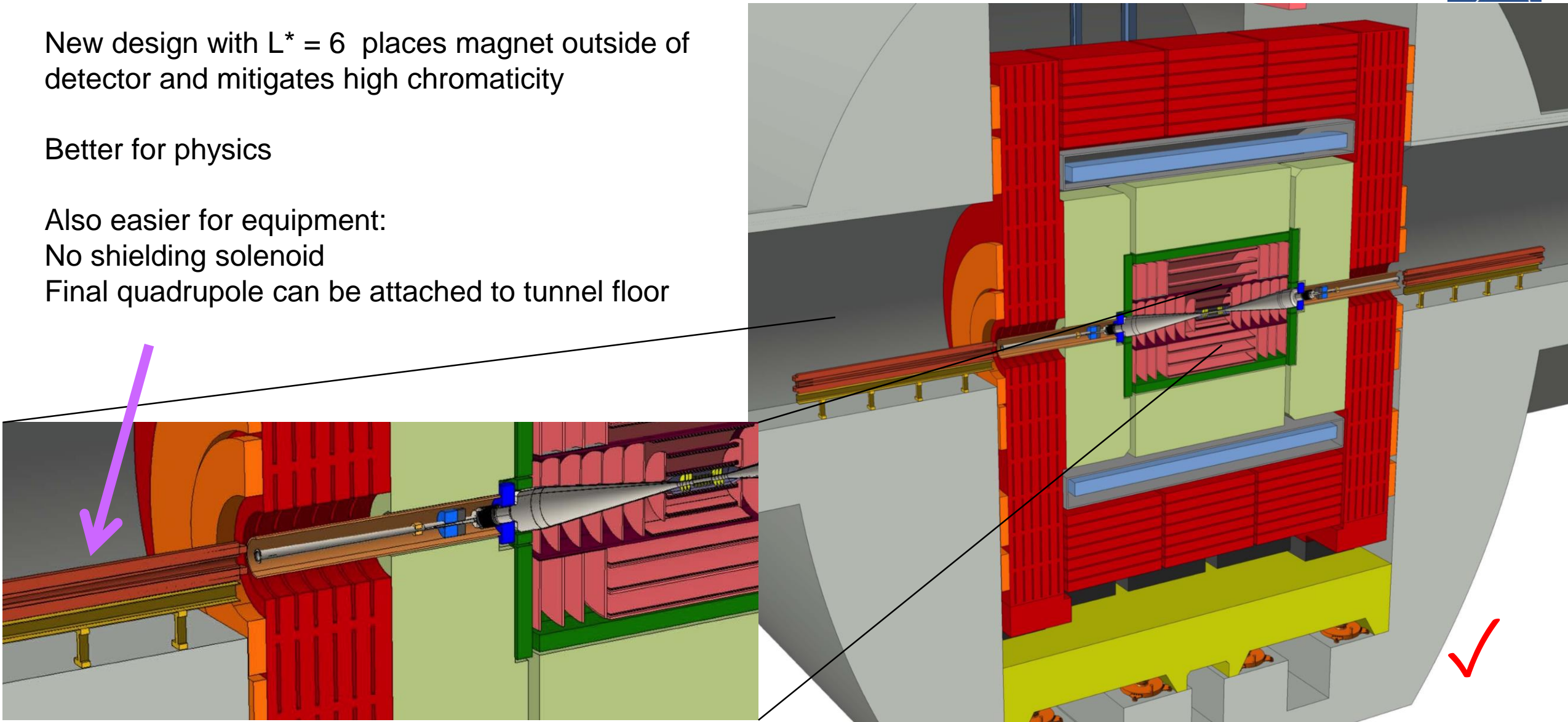
New design with $L^* = 6$ places magnet outside of detector and mitigates high chromaticity

Better for physics

Also easier for equipment:

No shielding solenoid

Final quadrupole can be attached to tunnel floor





Beam-beam Effect



$$\mathcal{L} \propto H_D \left(\frac{N}{\sigma_x} \right) N n_b f_r \frac{1}{\sigma_y}$$



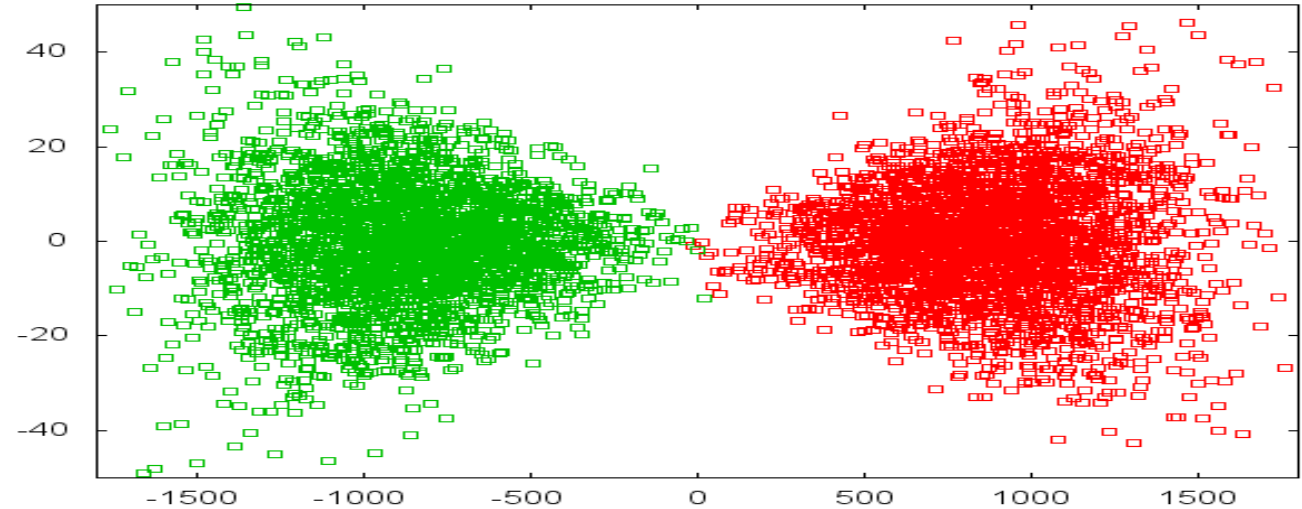
Dense beams to reach high luminosity
Beam focus each other

$$\mathcal{L} \propto \frac{N}{\sigma_x \sigma_y}$$

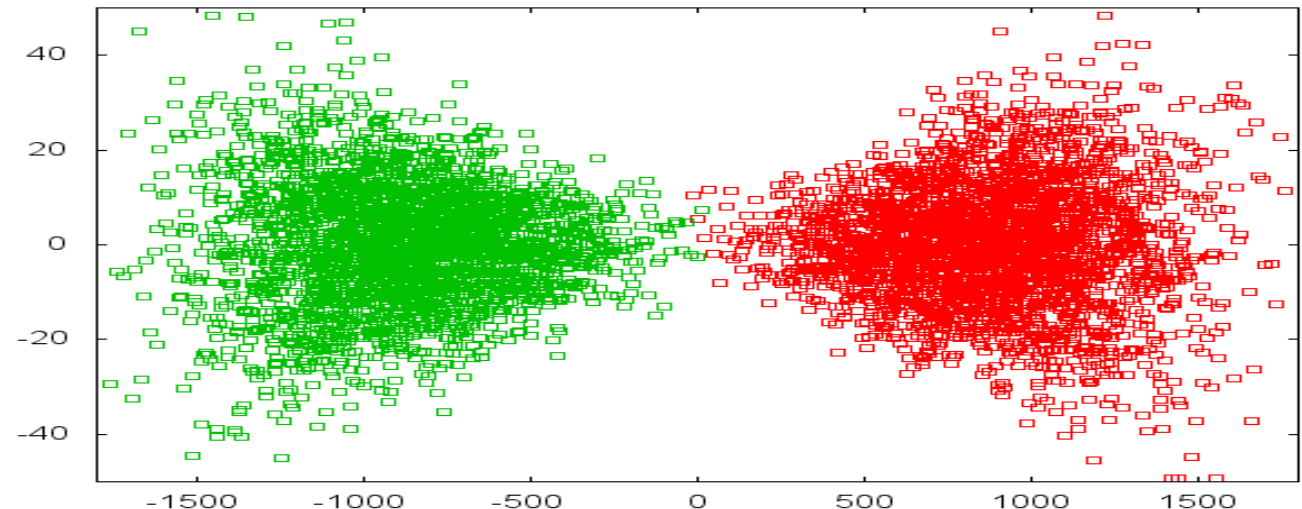
$$\sigma_x \gg \sigma_y \quad \sigma_x + \sigma_y \approx \sigma_x$$

Y direction [nm]

Beam-beam force off

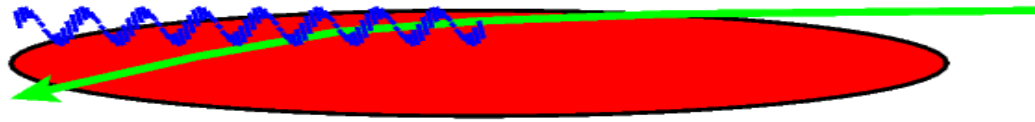


Beam-beam force on

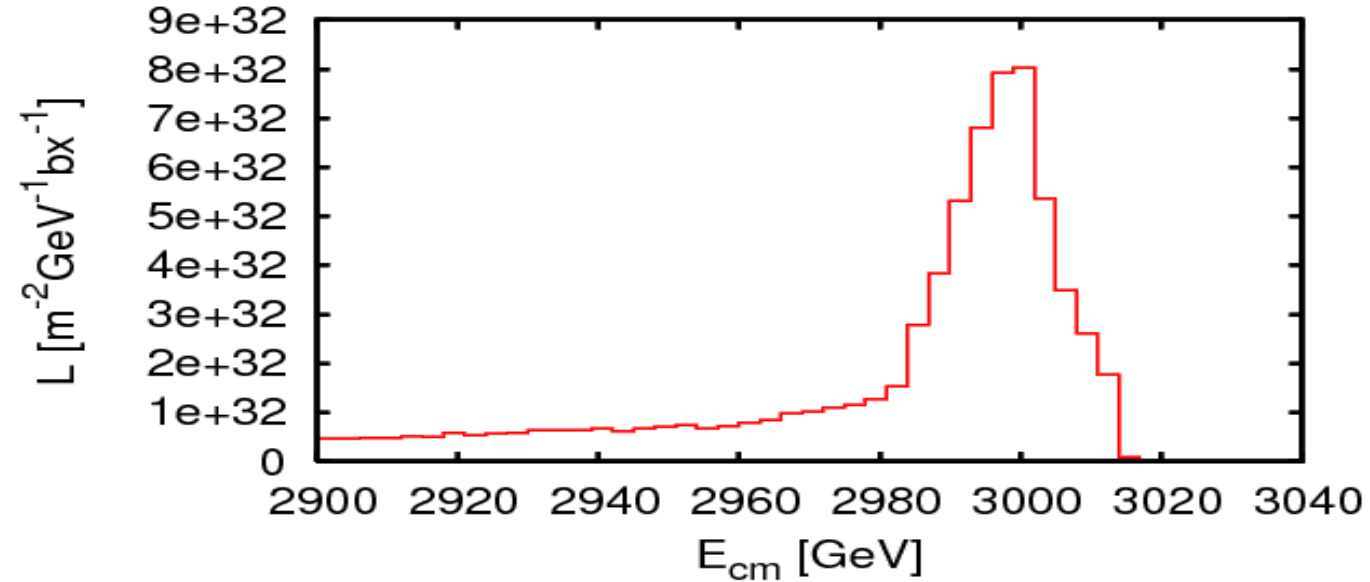


Z direction [μm]

$$\mathcal{L} \propto H_D \left(\frac{N}{\sigma_x} \right) N n_b f_r \frac{1}{\sigma_y}$$



Emitt beamstrahlung
Develop luminosity spectrum

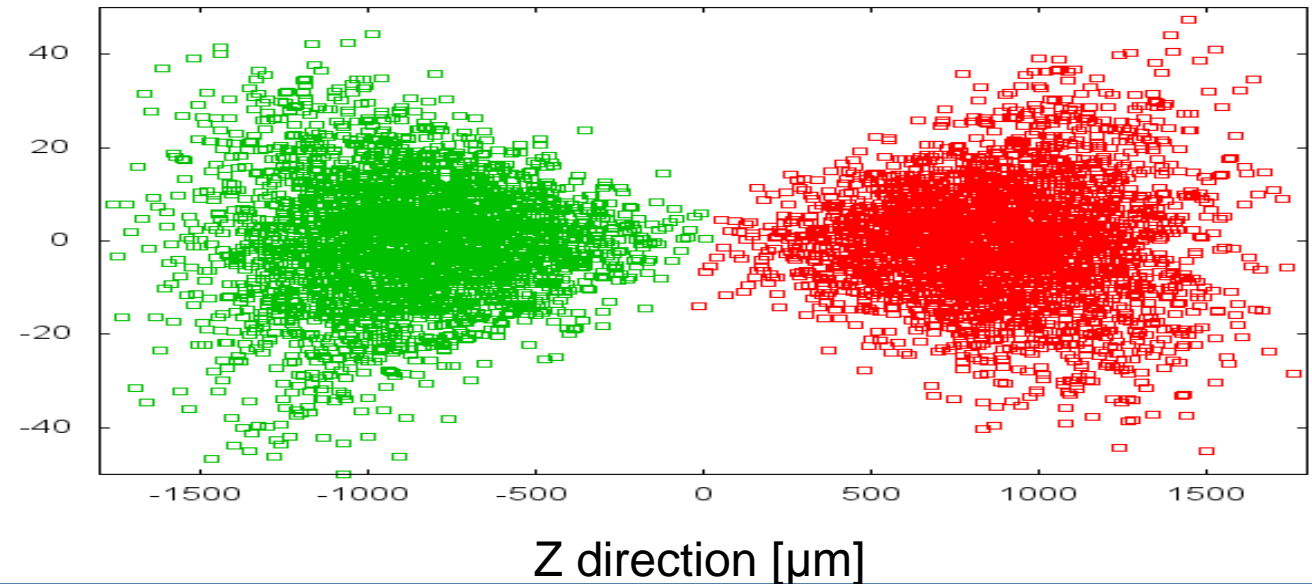


$$\mathcal{L} \propto \frac{N}{\sigma_x \sigma_y}$$

Aim for O(1)
at 380 GeV

$$n_\gamma \propto E_\gamma \propto \frac{N}{\sigma_x + \sigma_y}$$

$$\sigma_x \gg \sigma_y \quad \sigma_x + \sigma_y \approx \sigma_x$$





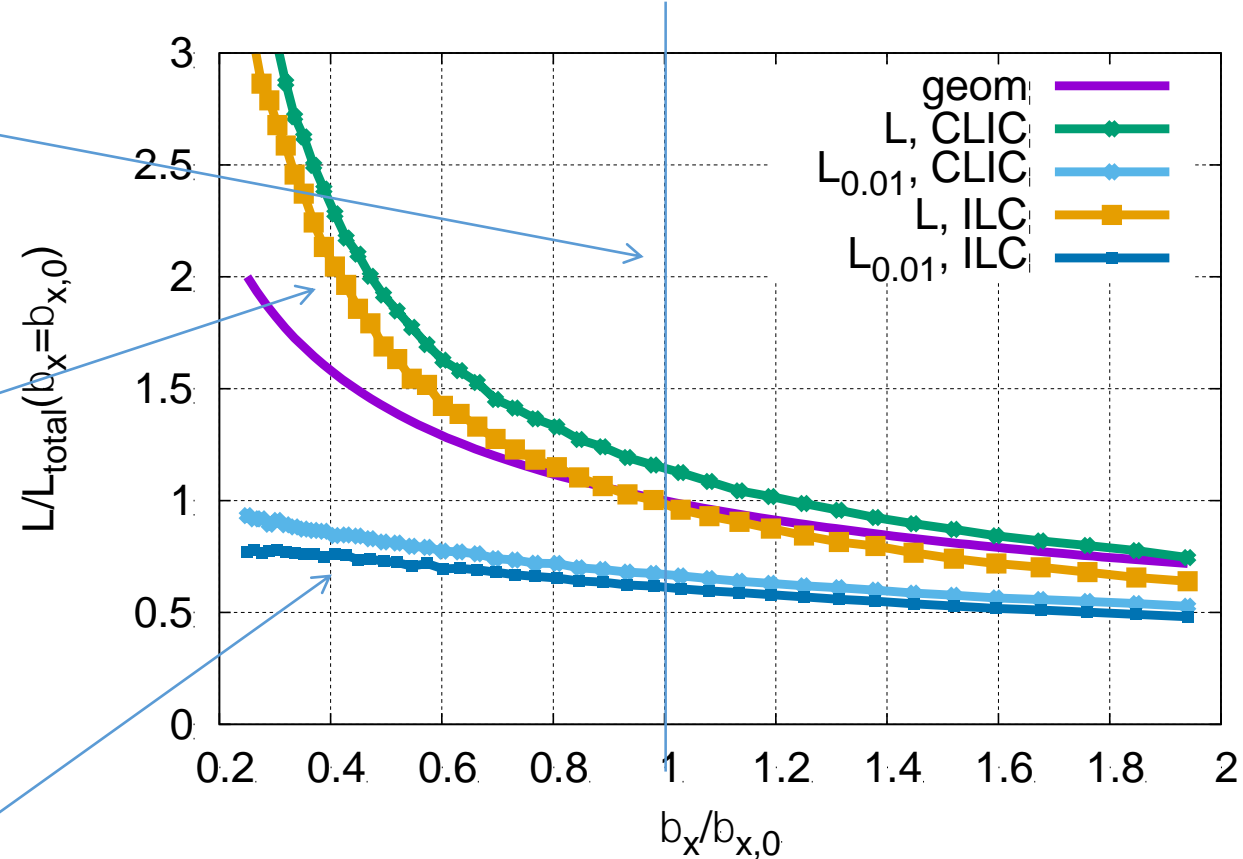
Horizontal Optimum



Design value $\beta_x = 8$ mm

Reaches $L_{0.01}/L=60\%$

The total luminosity L varies strongly with beta-function



But $L_{0.01}$ does not change so much

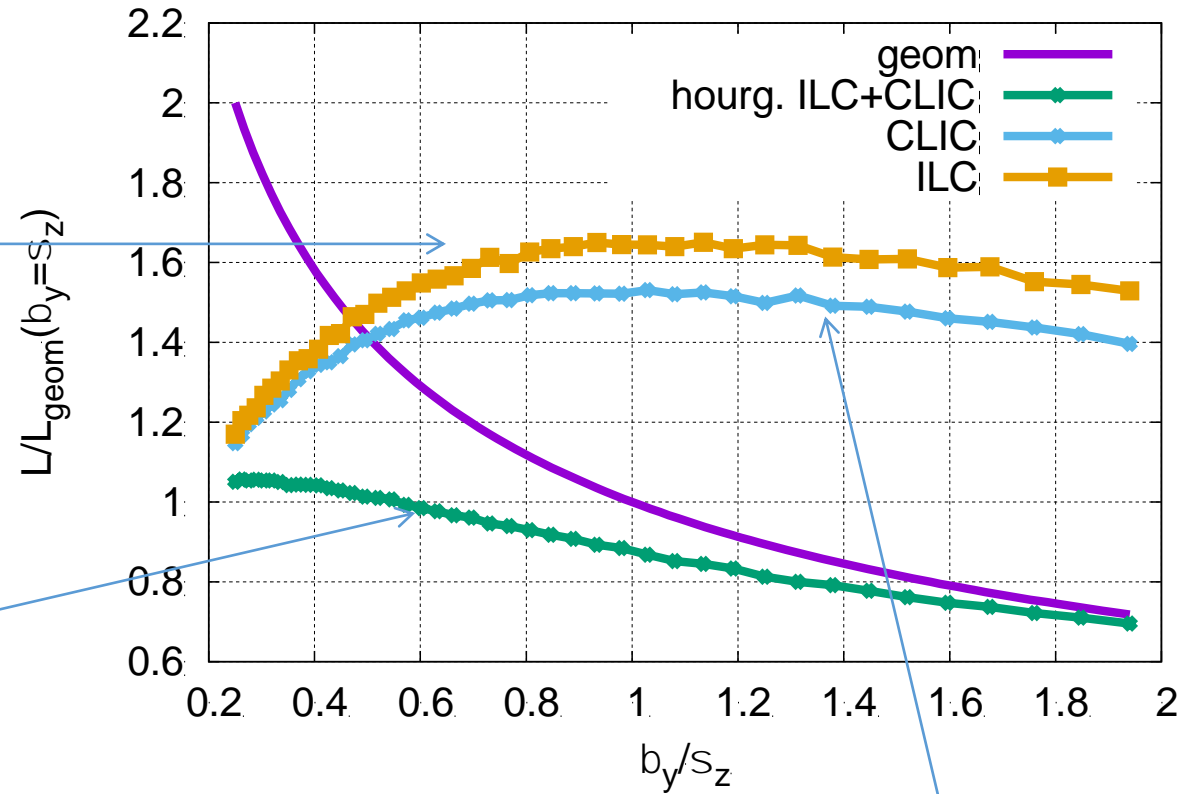
Hard to push beta-functions that low

Use $L_{0.01}/L=60\%$ as criterion
Reasonable compromise for most physics studies

Including pinch effect

$$\mathcal{L} = H_D \frac{N^2}{4\pi\sigma_x\sigma_y} n_b f_r$$

Geometric luminosity
No beam-beam forces



Somewhat above optimum because small beta-functions because it is easier for the machine

CLIC choice 100 μm,
reached by beam delivery system



Beam Delivery System Imperfections

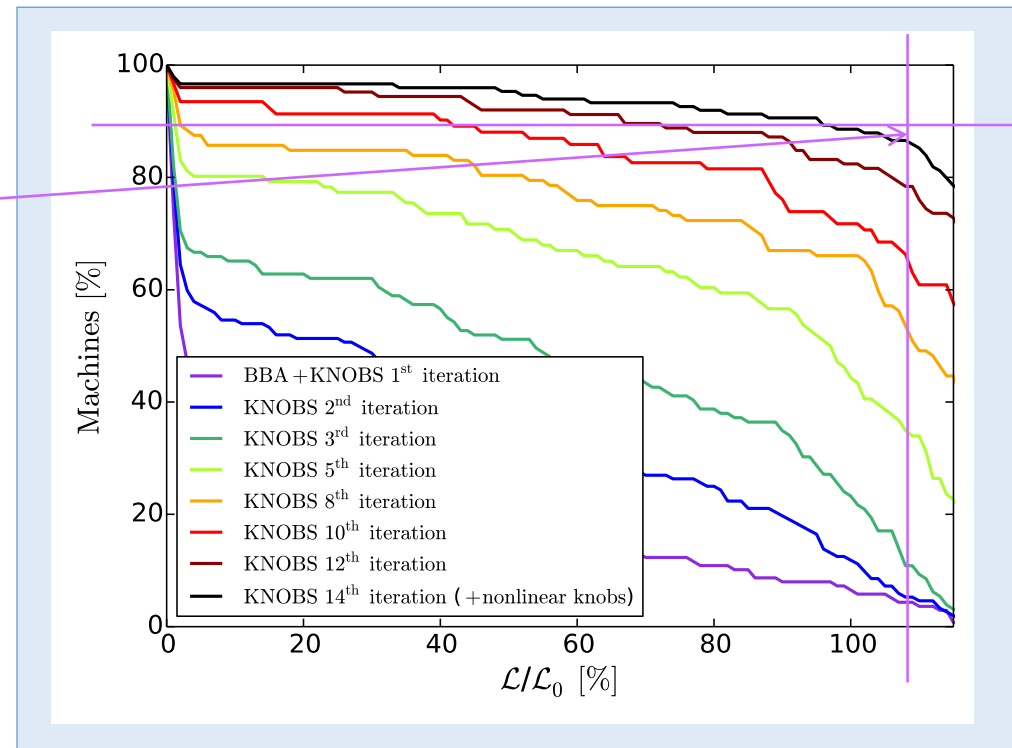


Realistic imperfections in BDS

Beam-based alignment and beam size tuning is used

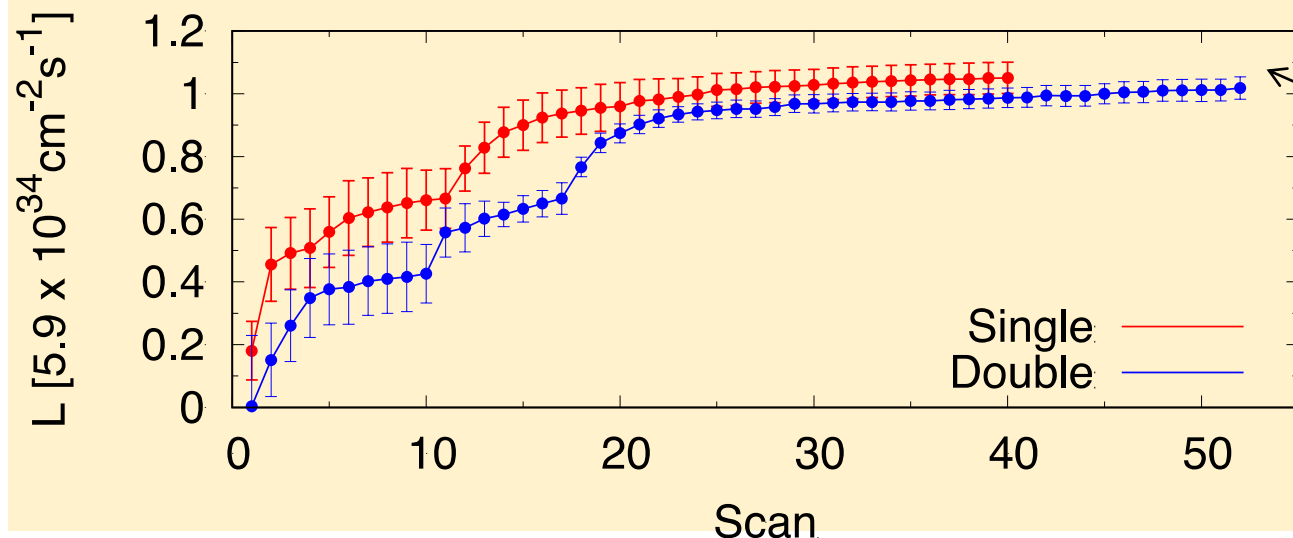
Aim to reach 110% of promised luminosity with 90% likelihood (10% is budget for dynamic imperfections)

Single beam tuning
85% reach 110% of
promised luminosity



Luminosity is still increasing
Simulation is very slow (much slower than reality)
Try to improve speed

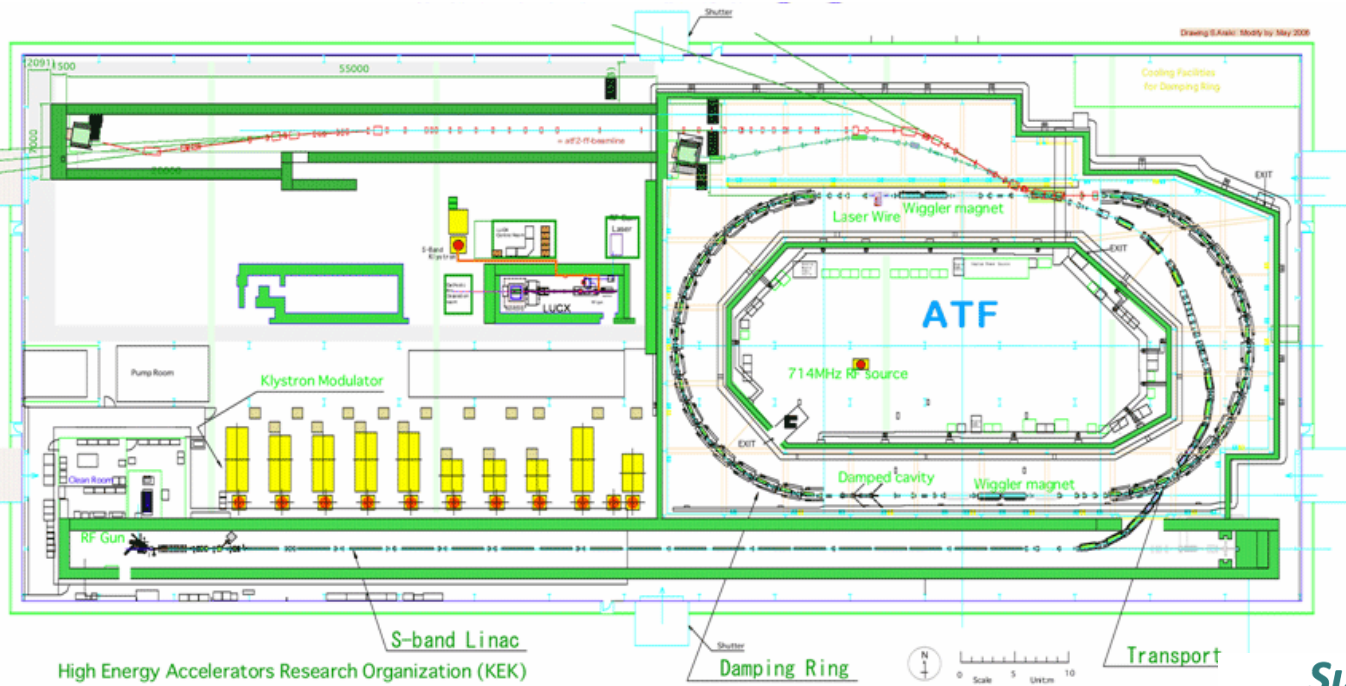
Two-beam study ongoing
Small difference in performance



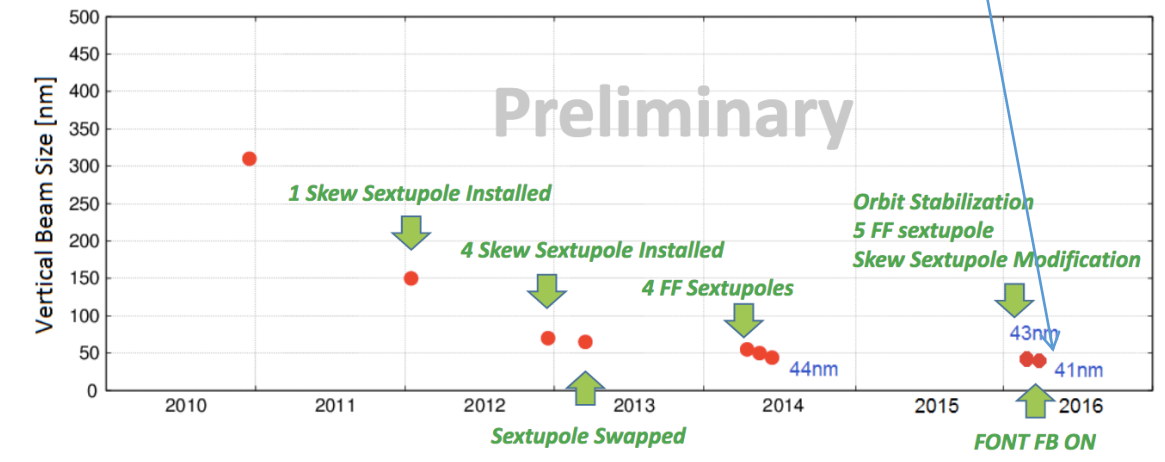
Much learned on instrumentation, tuning, design, ...
 Many practical issues from reused equipment, long bunches, ...

Beam size (41 nm) is close to target (37nm)

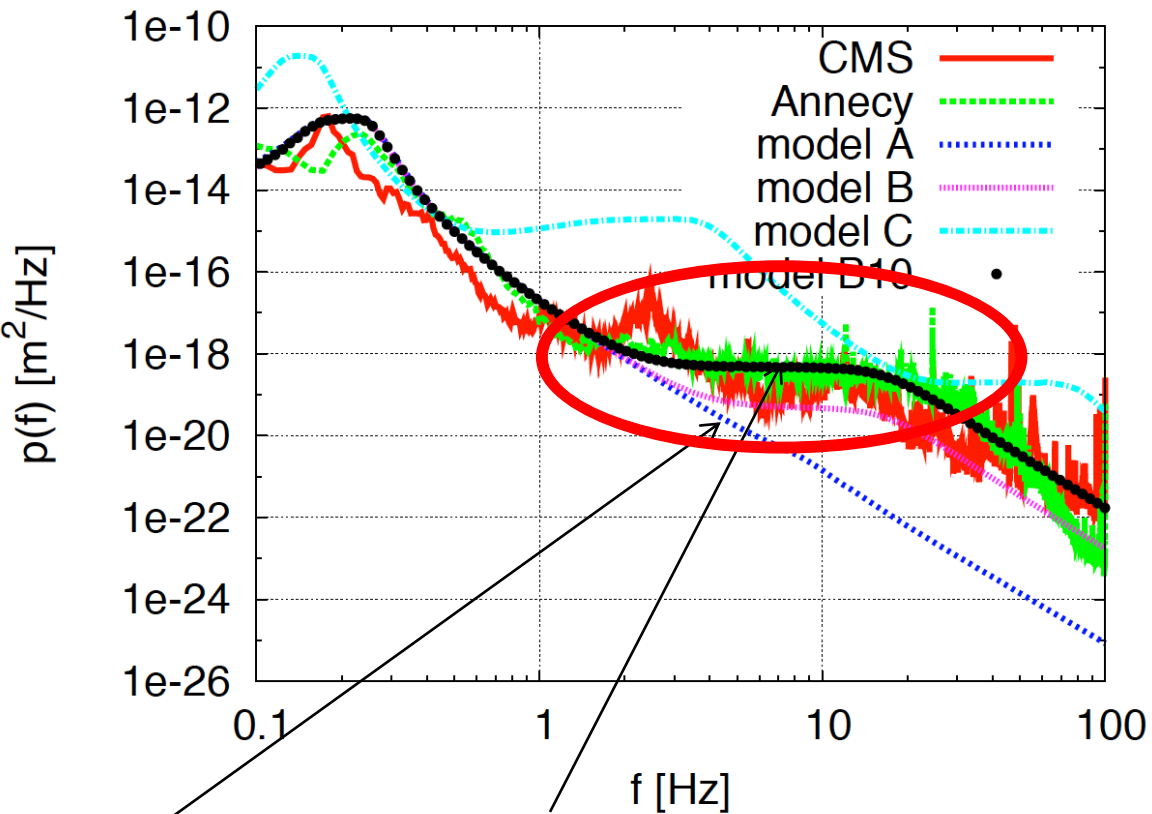
Beam jitter: 0.2 / 0.1 σ
 No feedback / with feedback



Summary of the IP vertical beam size measurement



Ground motion can impact beam trajectory



LEP tunnel

Want to be able to cope with this
(Model B10 similar to CMS hall)

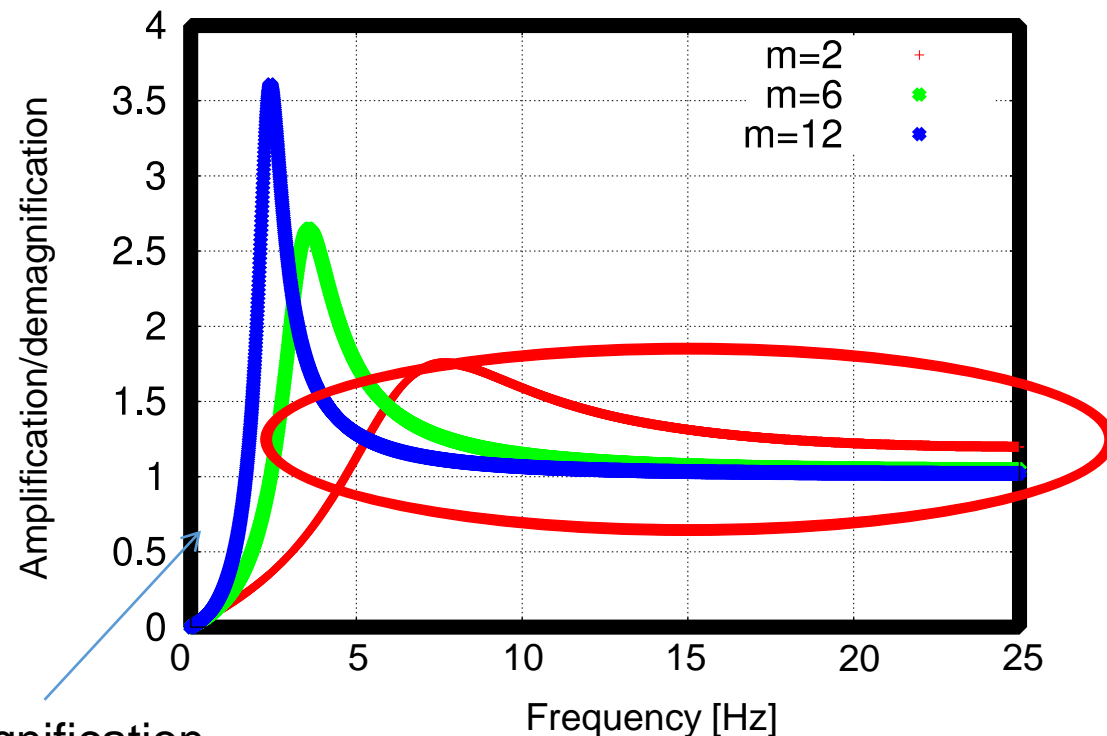
Beam-trajectory feedback corrects pulse-to-pulse (20 ms)

⇒ Cures low frequency ground motion

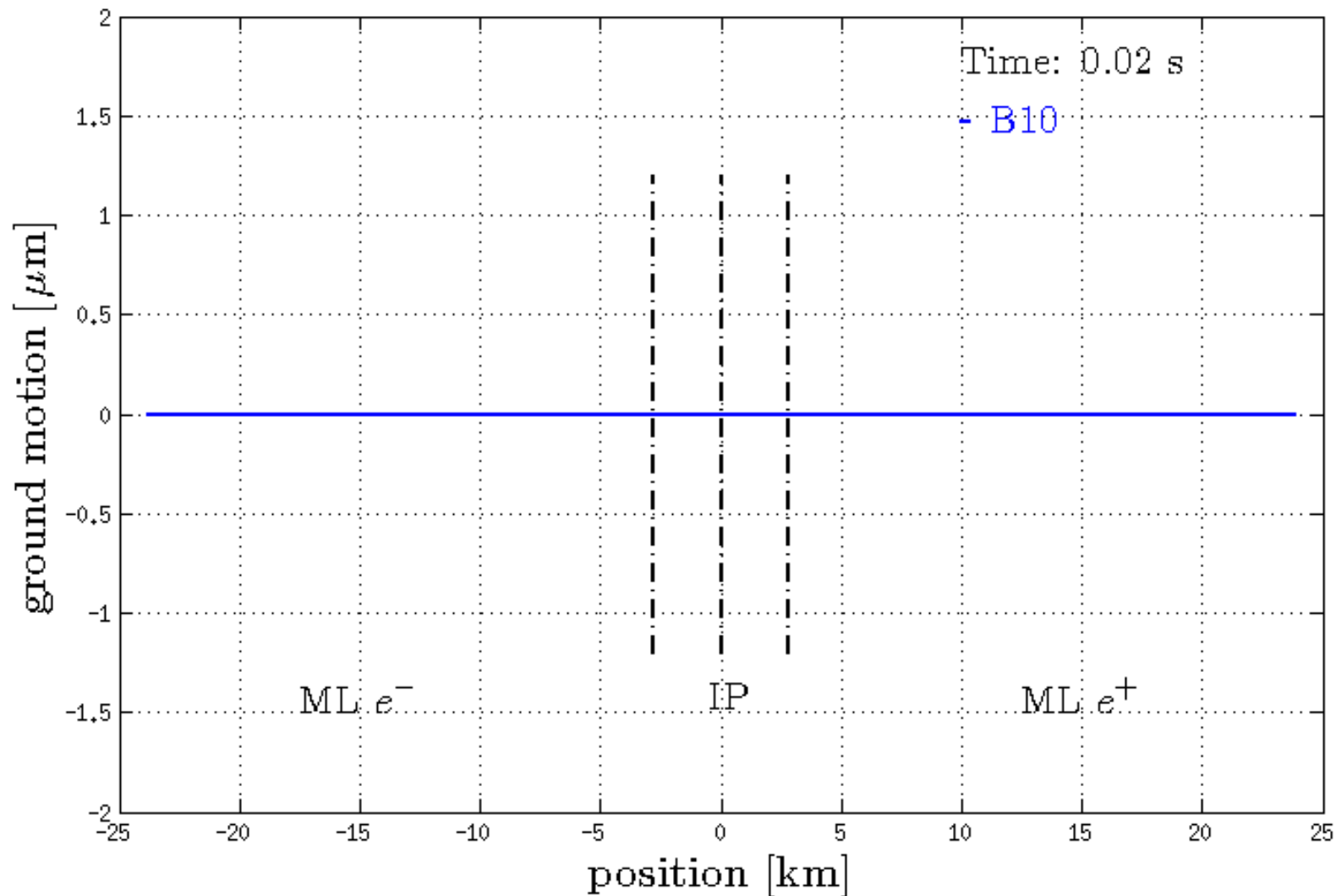
⇒ But not higher frequencies

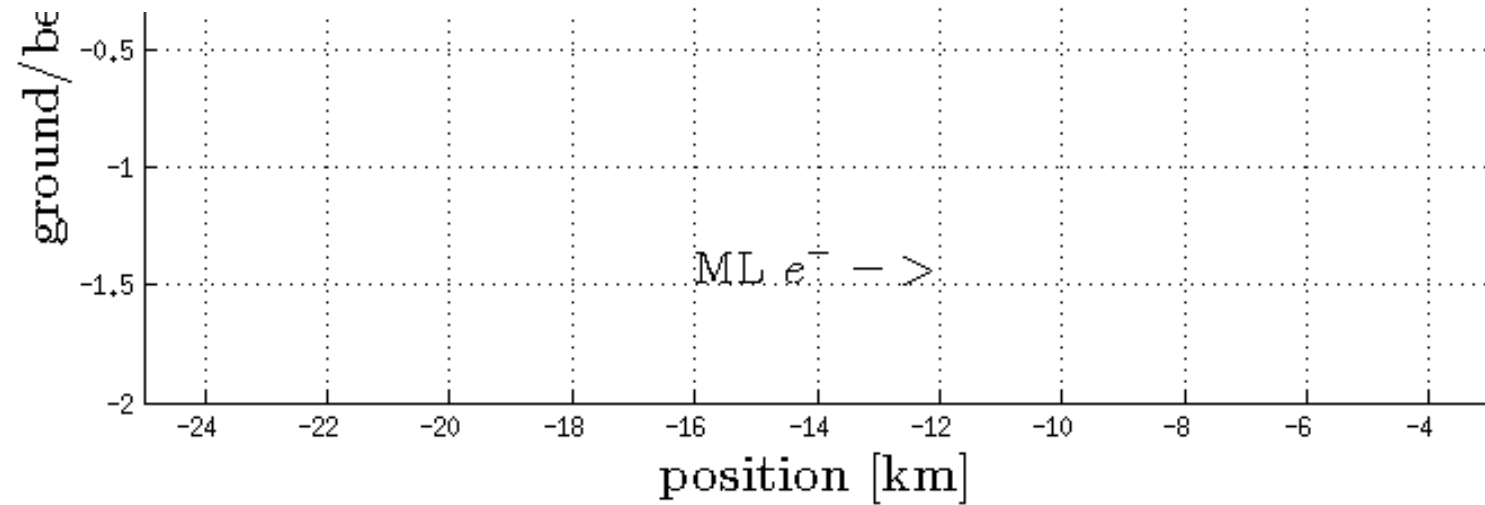
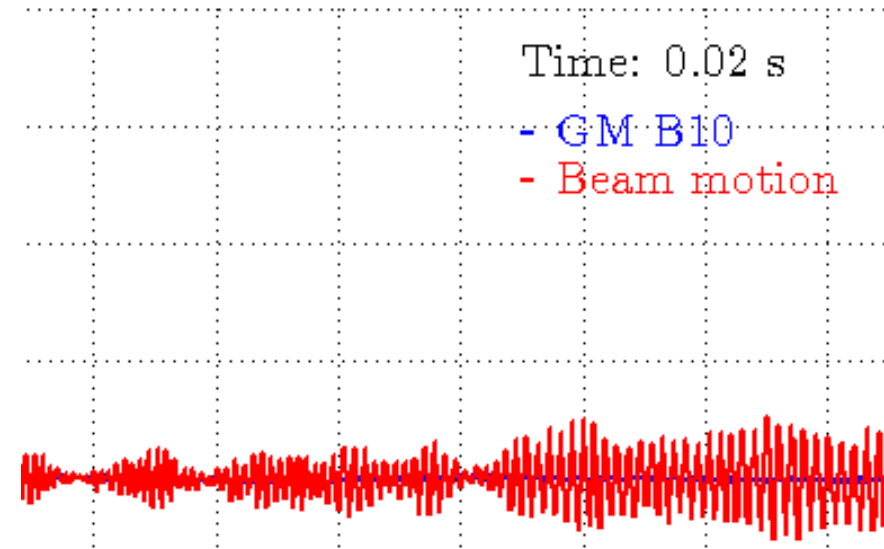
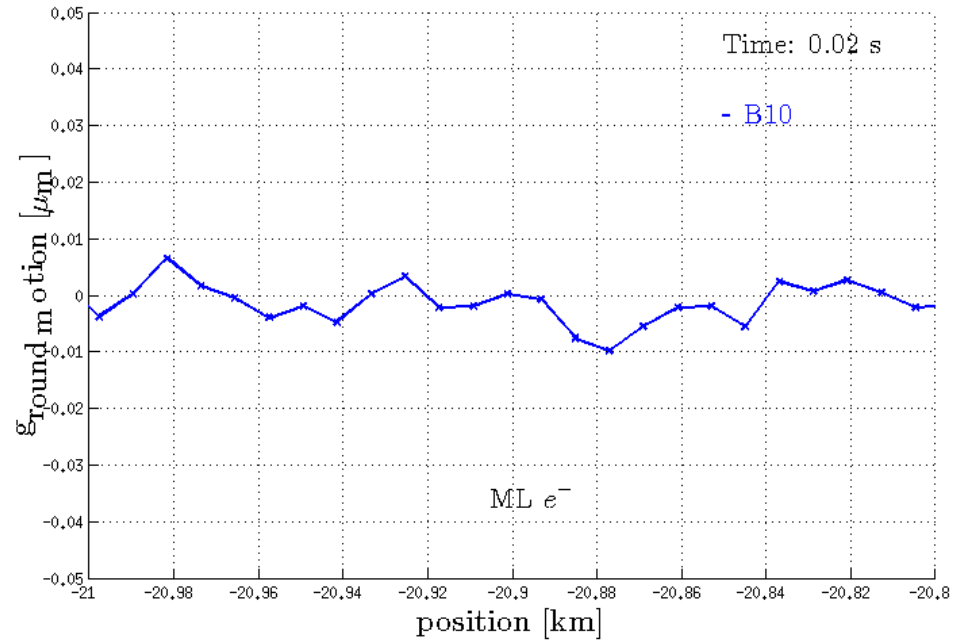
Beam-trajectory feedback:

Example transfer curve (recursive filter)

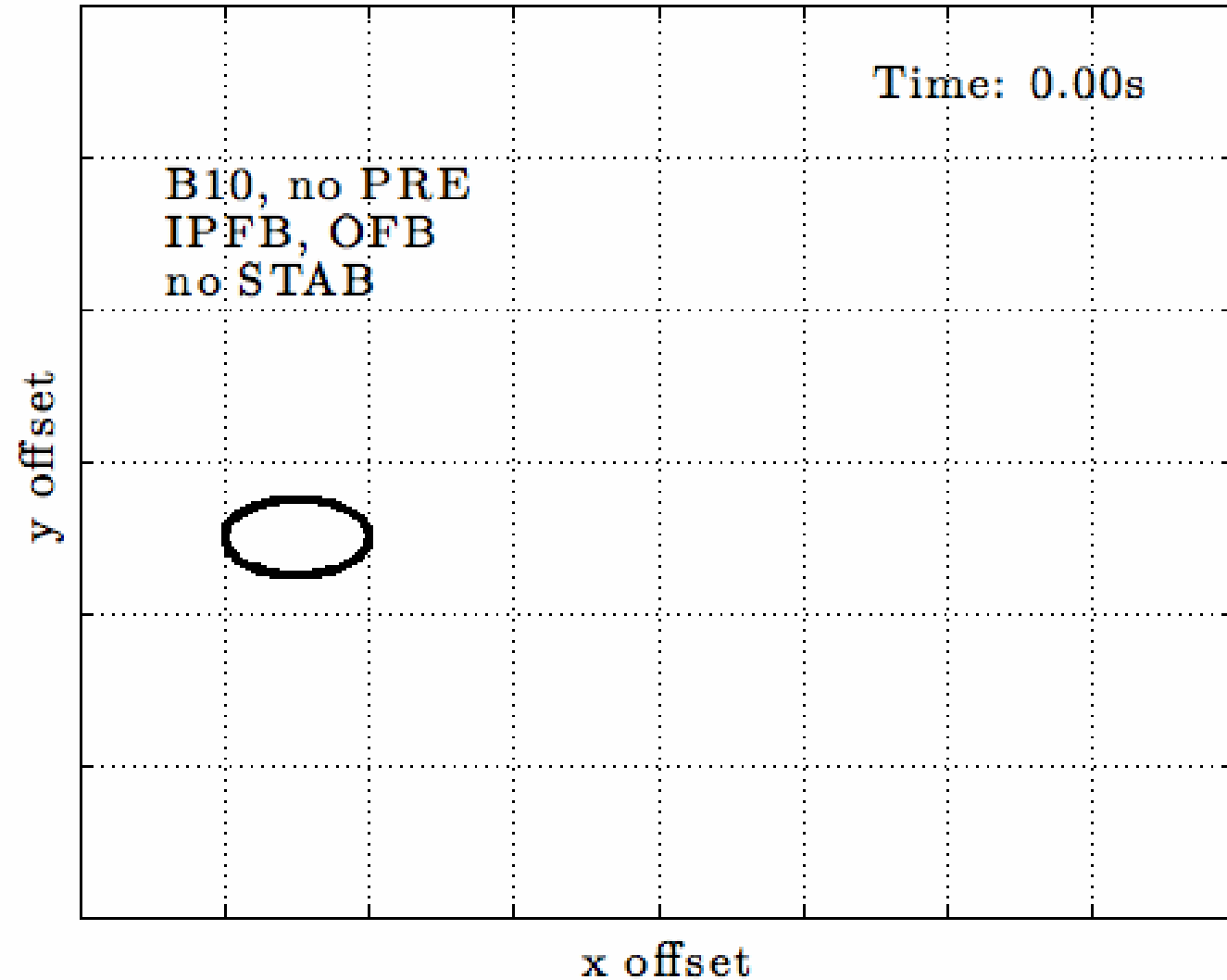


demagnification

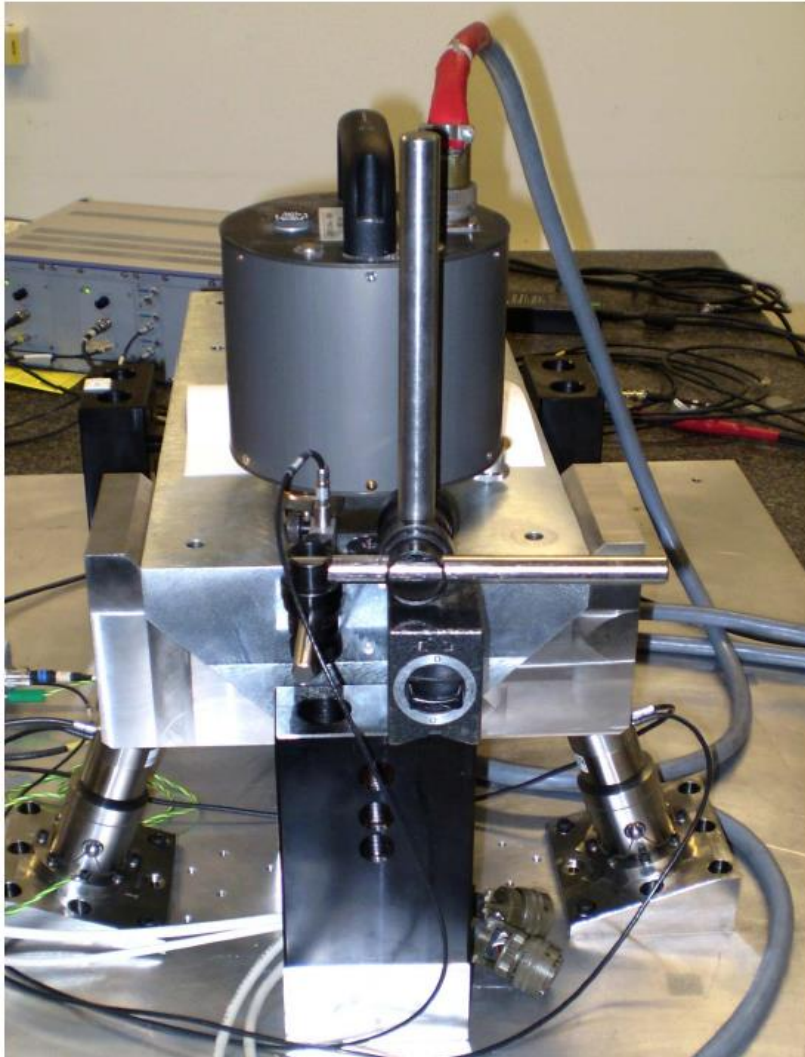




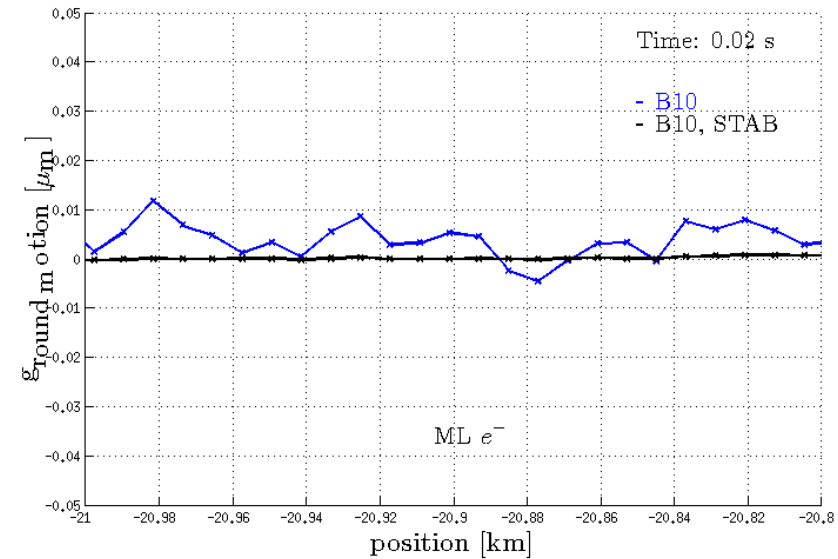
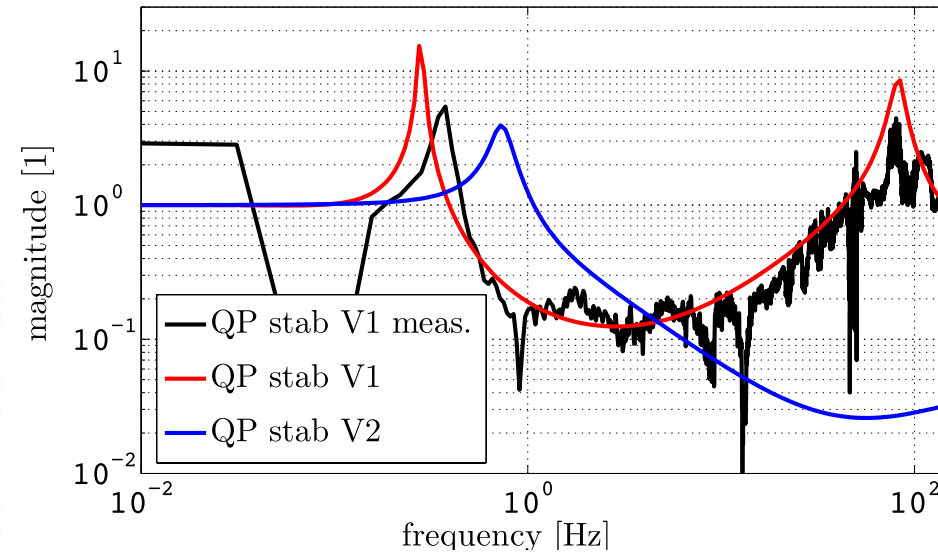
Jitter at IP



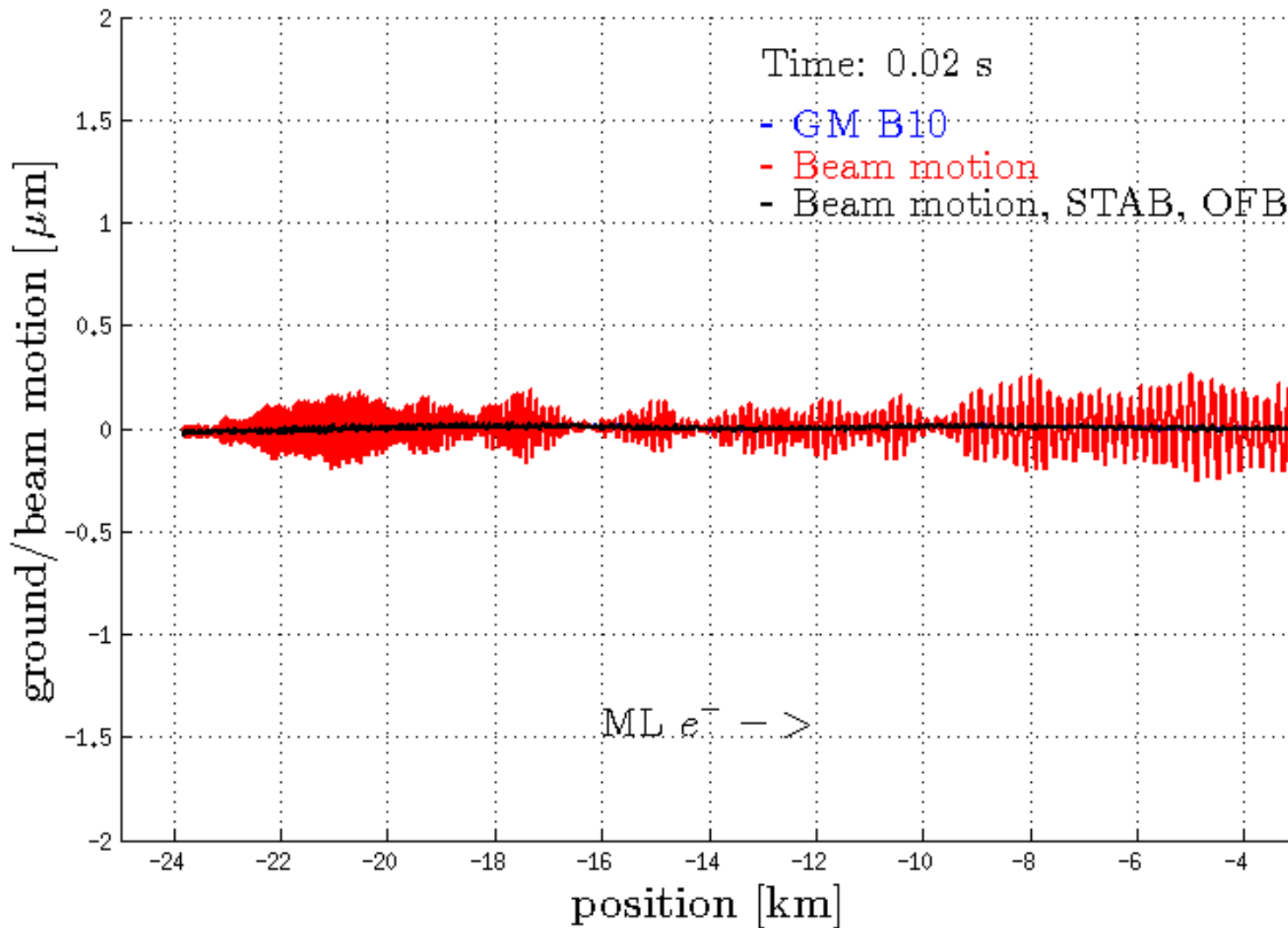
The Stabilisation System



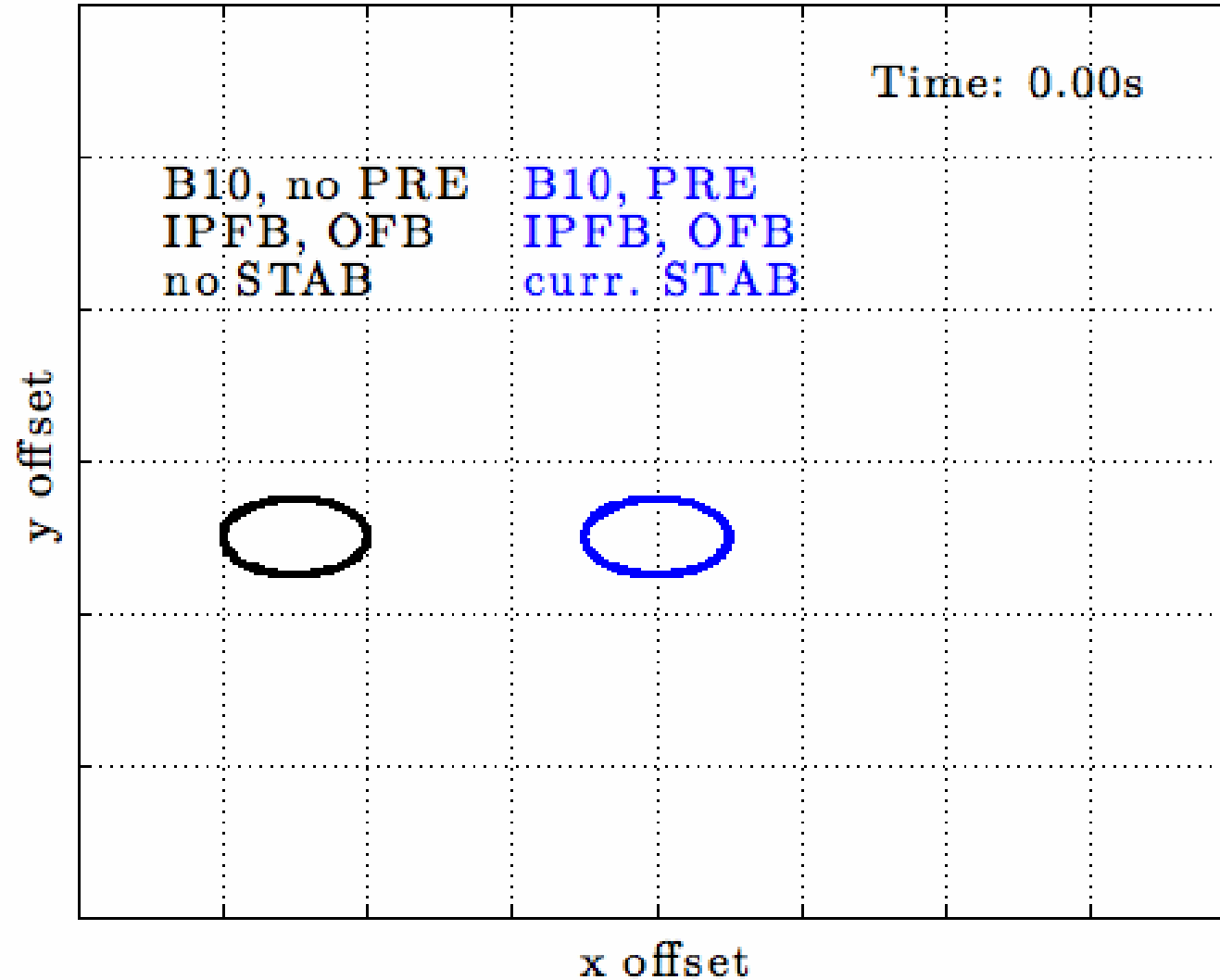
K. Artoos et al.



Beam Trajectory Jitter

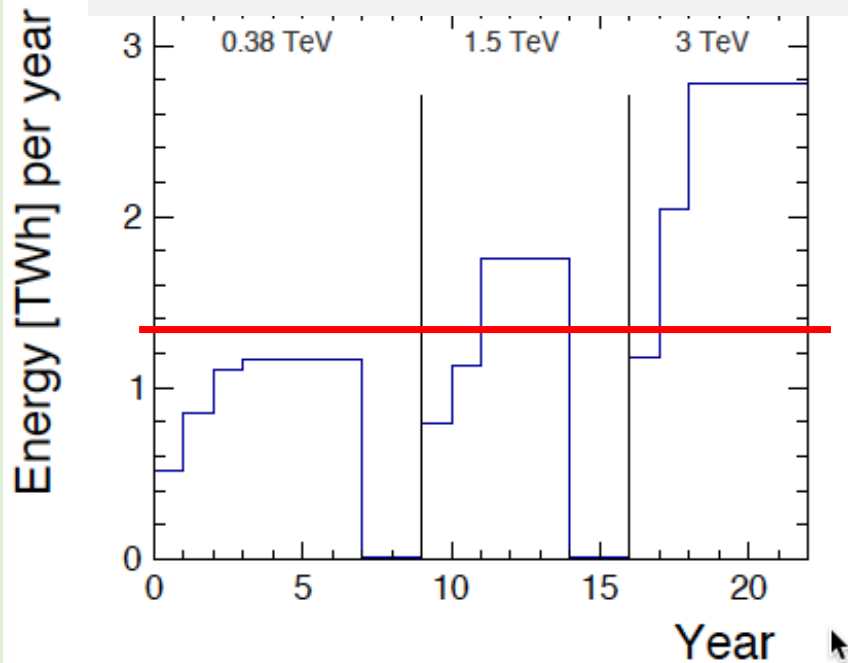


Beam Jitter at IP

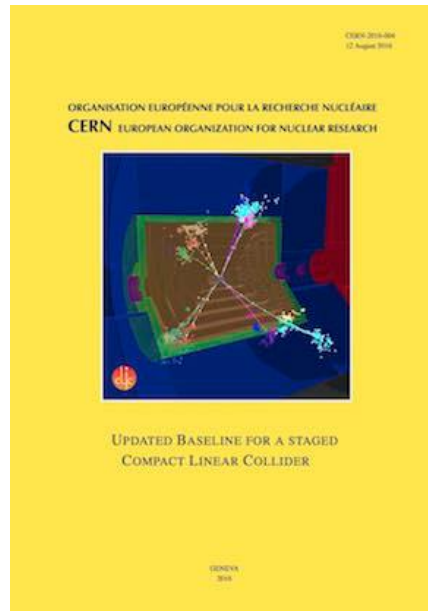


Goals bring cost and power consumption down:
 “reasonable cost”: O(6 GCHF)
 Power < O(200 MW)

CERN energy consumption
 2012: 1.35 TWh



Preliminary
 Estimate 252 MW

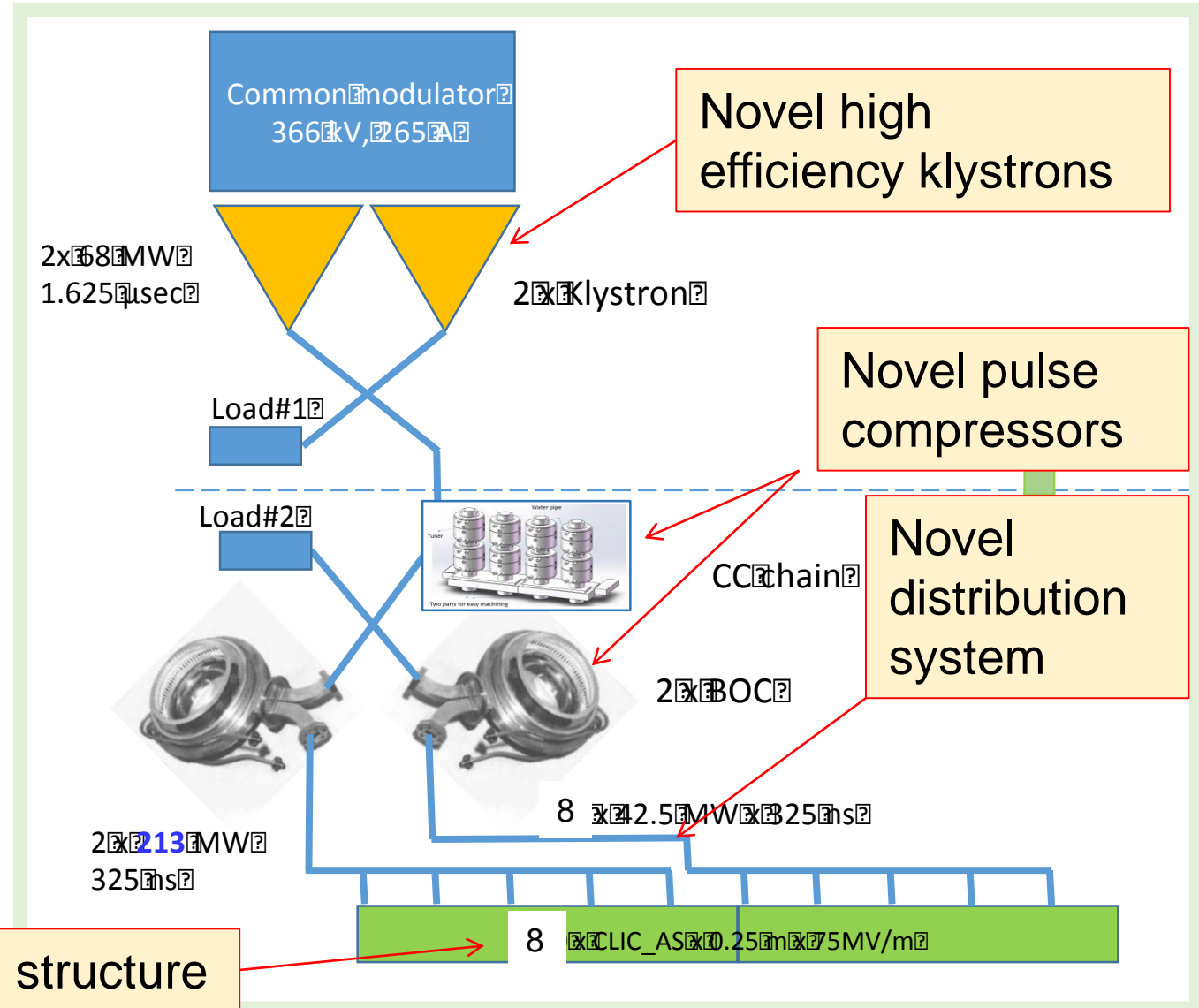
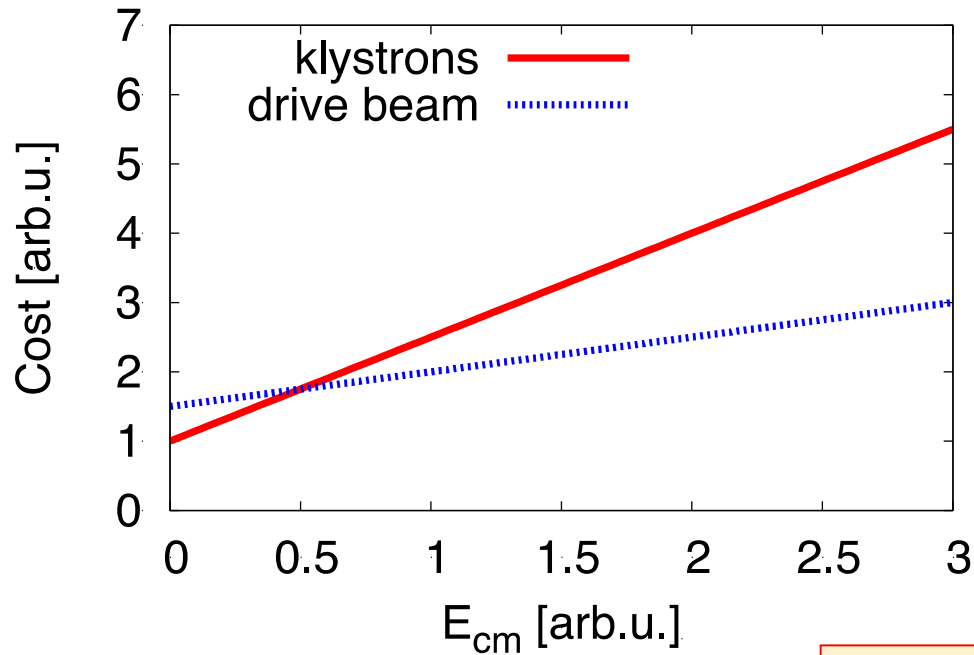


Preliminary value for 380 GeV
 (MCHF of Dec 2010)

Main beam production	1245
Drive beam production	974
Two-beam accelerator	2038
Interaction region	132
Civil engineering etc.	2112
Control & operation	216
TOTAL	6690

Improvement of cost and power is ongoing
 Detailed bottom up estimate
 Already savings

Develop klystron-based alternative
 Expect comparable cost for first energy stage
 But increases faster for high energies





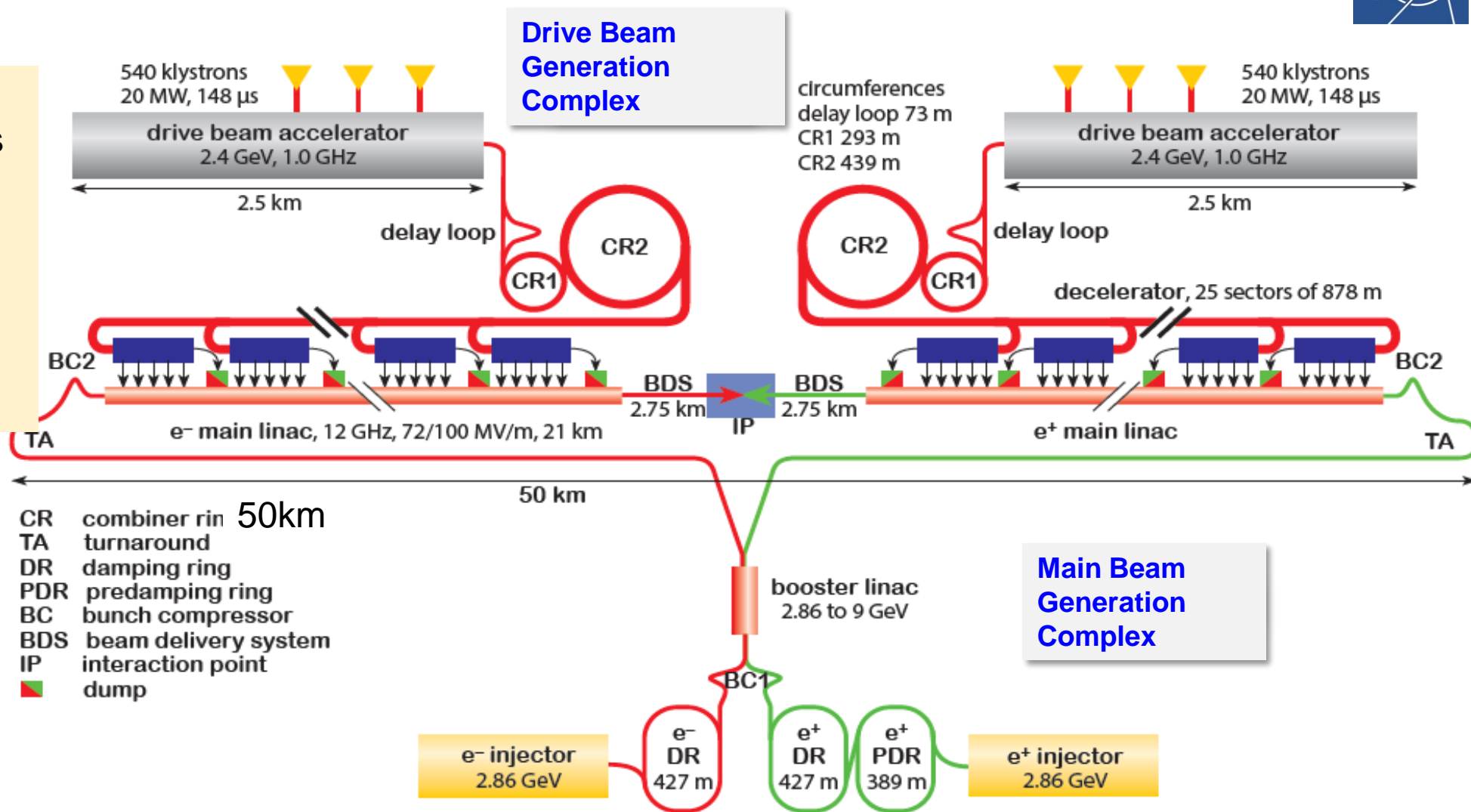
CLIC at 3 TeV



Can re-use previous systems and components

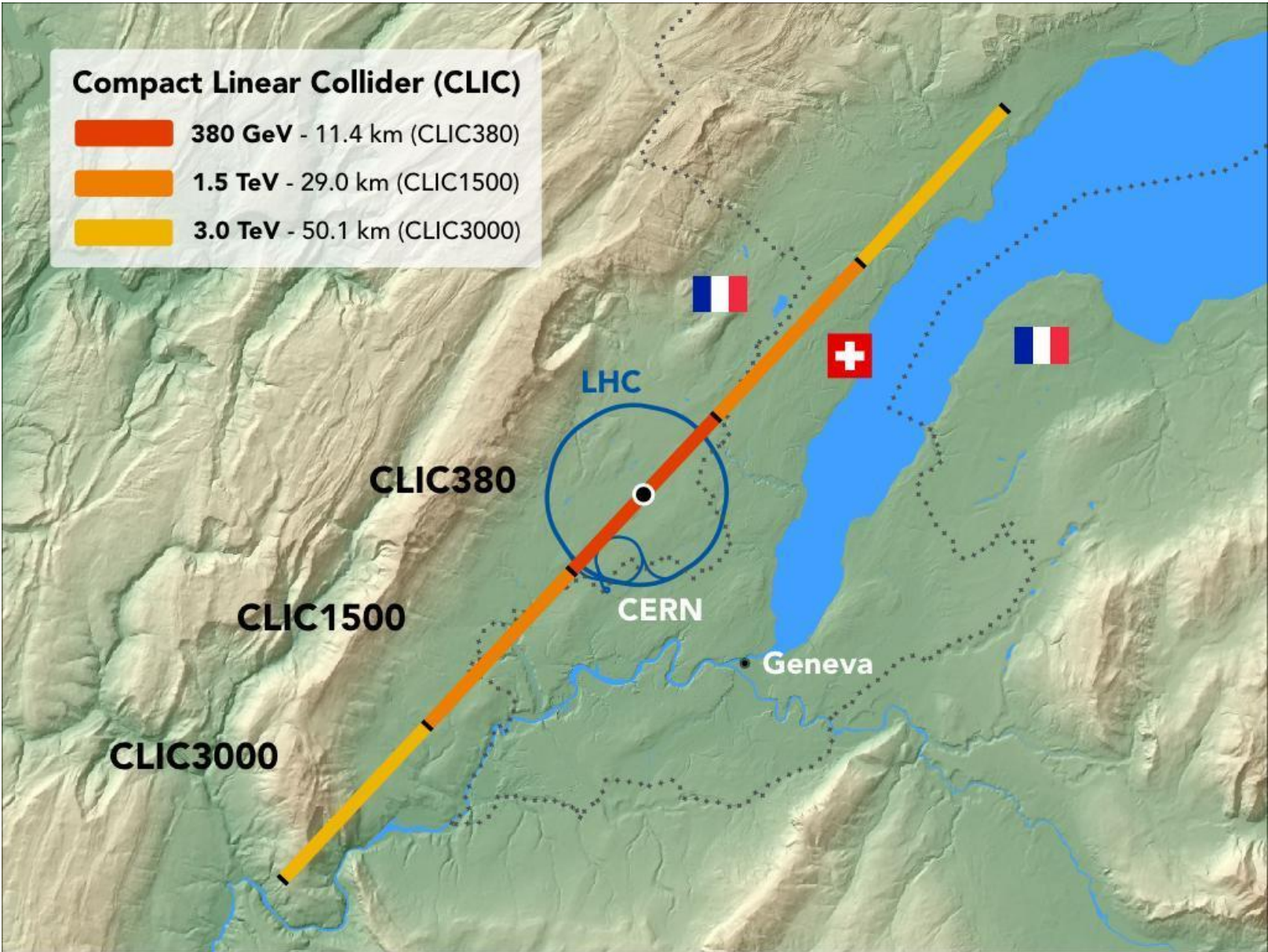
Just add more linac and drive beam pulse length

At 3 TeV add one drive beam



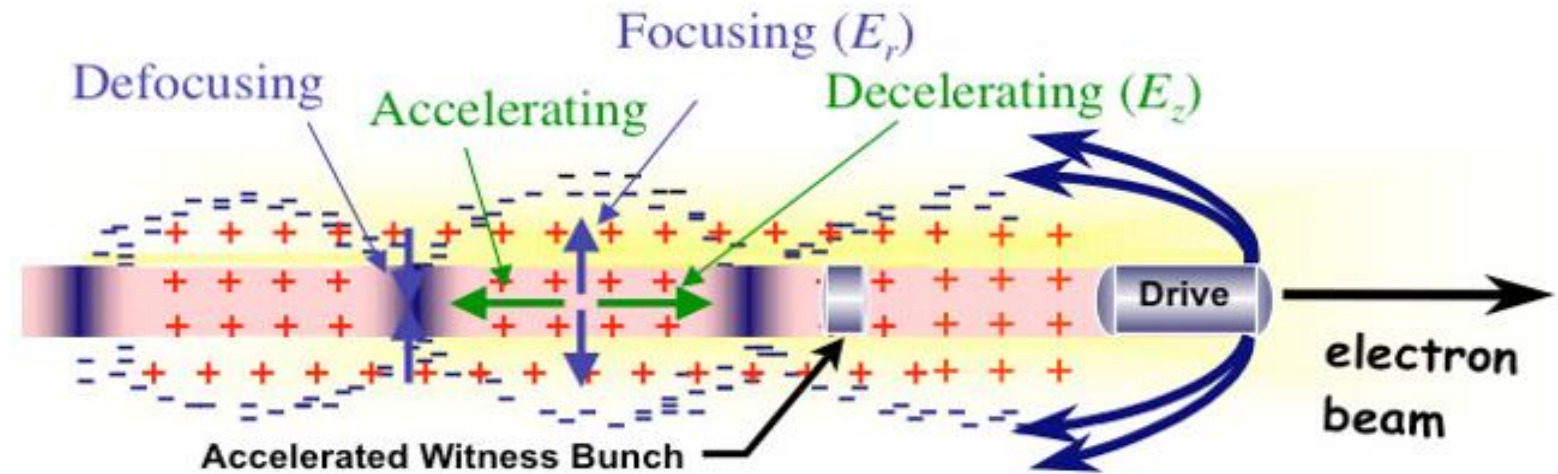


Site Near Geneva



Exploration of novel acceleration methods for lepton collider has started

- Dielectric accelerating structures
- Laser driven plasma
- Beam driven plasma



Plasma-based acceleration demonstrated gradients of 50 GV/m

Application of novel technologies to colliders

- Started a working group for CLIC to understand potential
- Plasma community started a working group on colliders

Main challenge

- Beam quality preservation has to be explored theoretically and experimentally



Conclusion



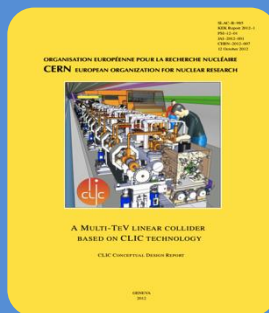
A staged design for CLIC has been developed

- First energy stage at 380 GeV optimised for performance, cost and power
 - Meet the physics performance targets
 - Cost roughly comparable to LHC
 - Power $O(200 \text{ MW})$
- Further energy stages can reuse components
 - Site available for 3 TeV
- In the long run novel acceleration methods may become available

High gradients and high peak power are key to CLIC

Great control of imperfections is second key

- Technical solutions have been demonstrated, see tomorrow
- Beam-based methods have been established



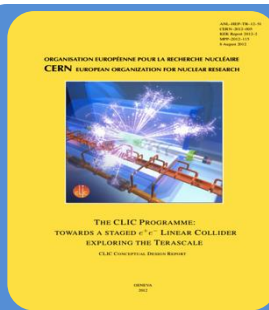
Vol 1: The CLIC accelerator and site facilities

- CLIC concept with exploration over multi-TeV energy range up to 3 TeV
- Feasibility study of CLIC parameters optimized at 3 TeV (most demanding)
- Consider also 500 GeV, and intermediate energy range
- <https://edms.cern.ch/document/1234244/>



Vol 2: Physics and detectors at CLIC

- Physics at a multi-TeV CLIC machine can be measured with high precision, despite challenging background conditions
- External review procedure in October 2011
- <http://arxiv.org/pdf/1202.5940v1>



Vol 3: “CLIC study summary”

- Summary and available for the European Strategy process, including possible implementation stages for a CLIC machine as well as costing and cost-drives
- Proposing objectives and work plan of post CDR phase (2012-16)
- <http://arxiv.org/pdf/1209.2543v1>

In addition a shorter overview document was submitted as input to the European Strategy update, available at: <http://arxiv.org/pdf/1208.1402v1>

Input documents to Snowmass 2013 has also been submitted: <http://arxiv.org/abs/1305.5766> and <http://arxiv.org/abs/1307.5288>



Note: CLIC Optimisation

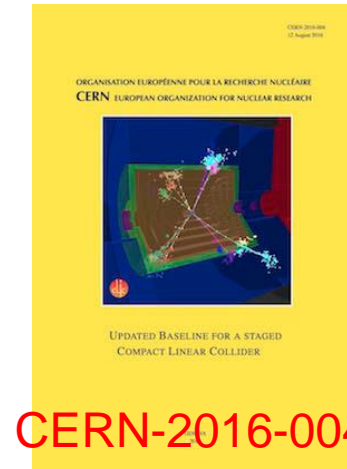
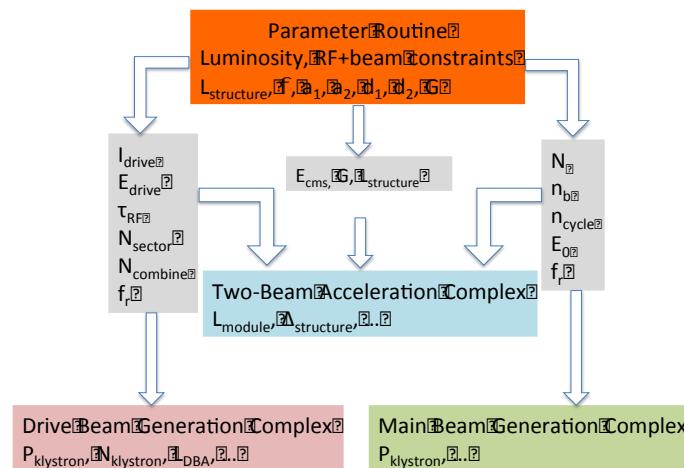


Scan 1.7 billion cases:

Fix structure design parameters:
 $a_1, a_2, d_1, d_2, N_c, f, G$

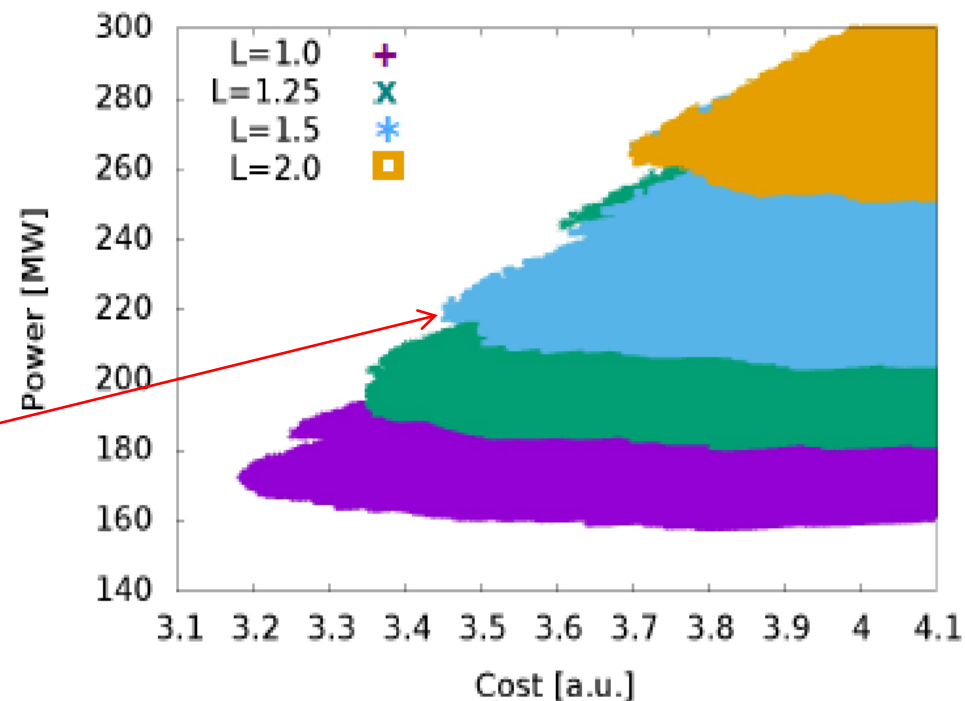
⇒ key beam parameters

⇒ Luminosity, cost and power
(including other systems)



Resulting designs:
Colors indicate luminosities

This is the one that we picked





Reserve



Goal set as “reasonable cost”: 6 GCHF

Preliminary value for 380 GeV
(MCHF of Dec 2010)

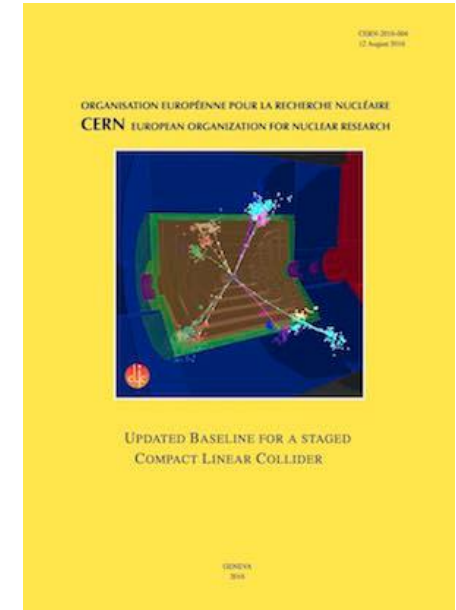
Preliminary cost estimate from
rebaselining

Performing bottom-up cost estimate

Also optimise the cost

- Module design is being improved
- Injector cost has been relatively high, is being reduced substantially by about halving number of klystrons
- Drive beam injector has already been optimised
- Civil engineering is being reviewed
- ...

Main beam production	1245
Drive beam production	974
Two-beam accelerator	2038
Interaction region	132
Civil engineering etc.	2112
Control & operation	216
TOTAL	6690



Goal set as “reasonable power”: 200 MW

Preliminary power estimate from rebaselining

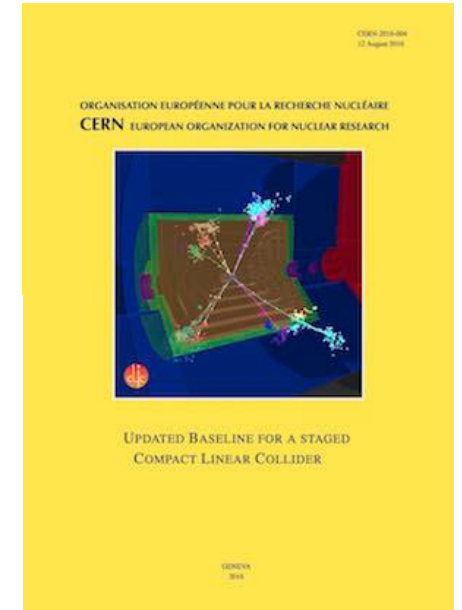
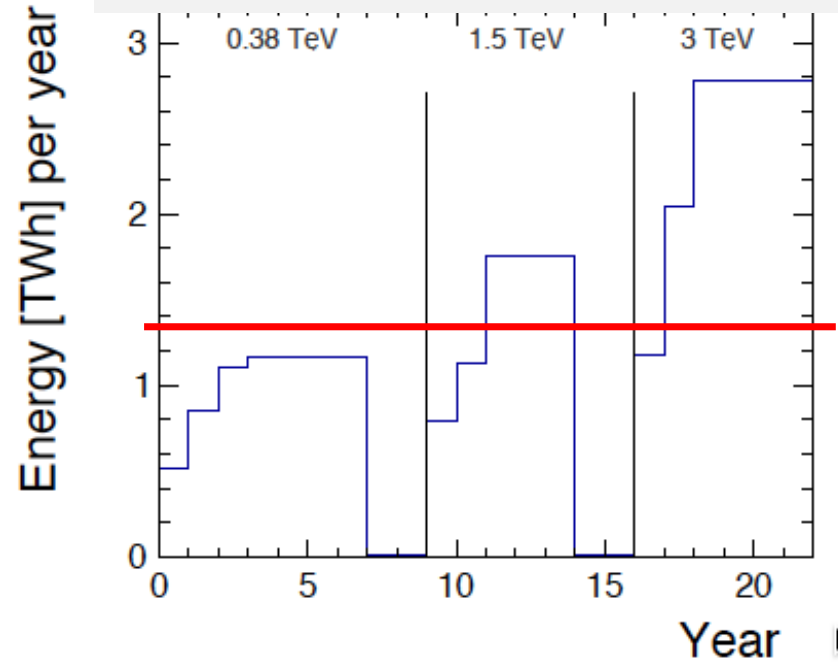
Performing bottom-up power estimate

Also optimise the power

- Use of permanent magnets
- Reduction of injector power
- More efficient klystrons
- Use of green power: Ability to switch on and off to follow electricity availability
- ...

Preliminary Estimate 252 MW

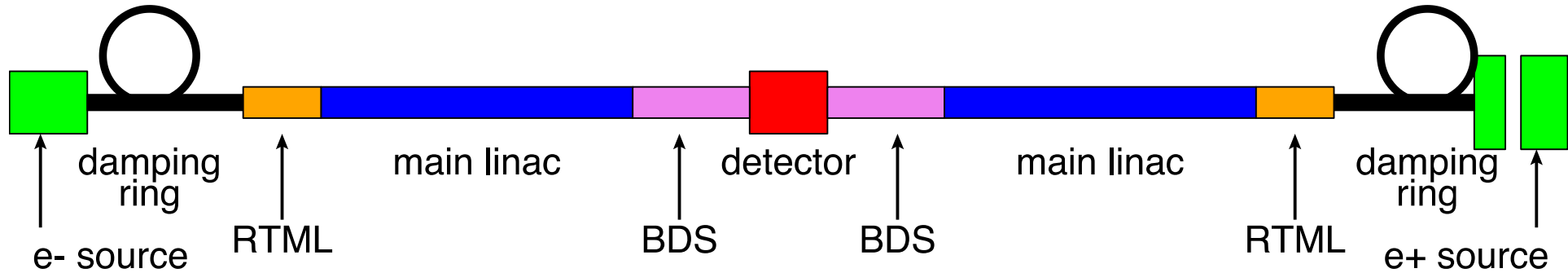
CERN energy consumption
2012: 1.35 TWh





Systems





Damping ring makes flat beams

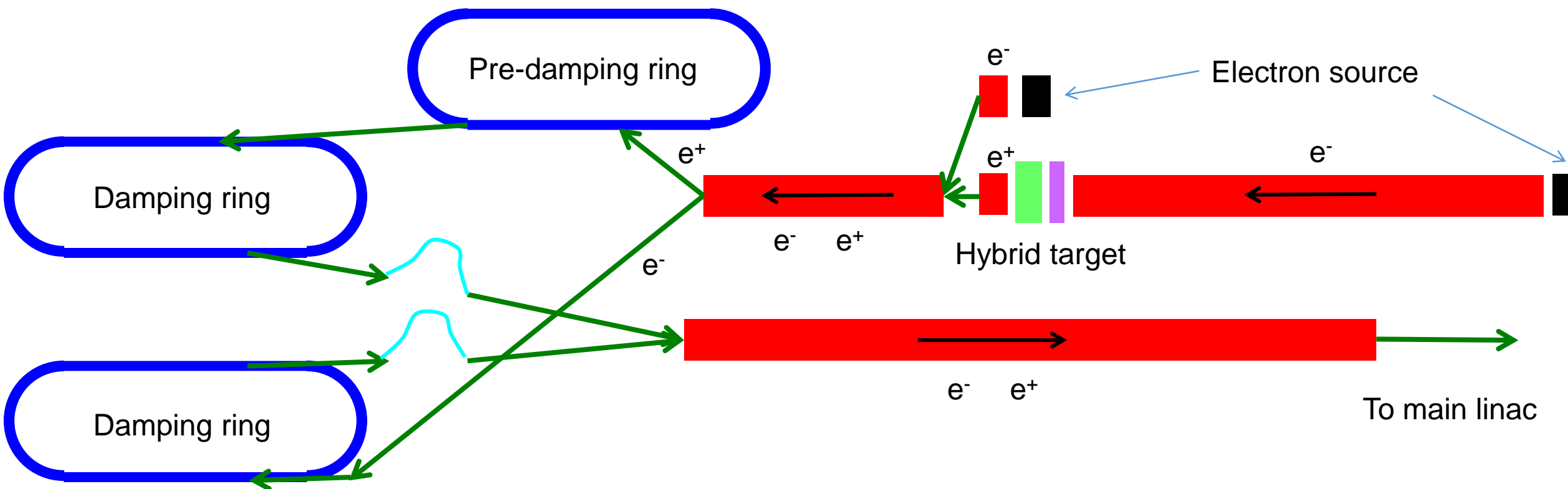
	ϵ_x [nm]	ϵ_y [nm]	σ_z [μm]	N [10^9]	E [GeV]
Damping ring exit	700	5	1600	5.2	2.86
End of RTML	850	10	70	5.2	9.0
End of main linac	920	20	70	5.2	190.0
Interaction point	950	30	70	5.2	190.0

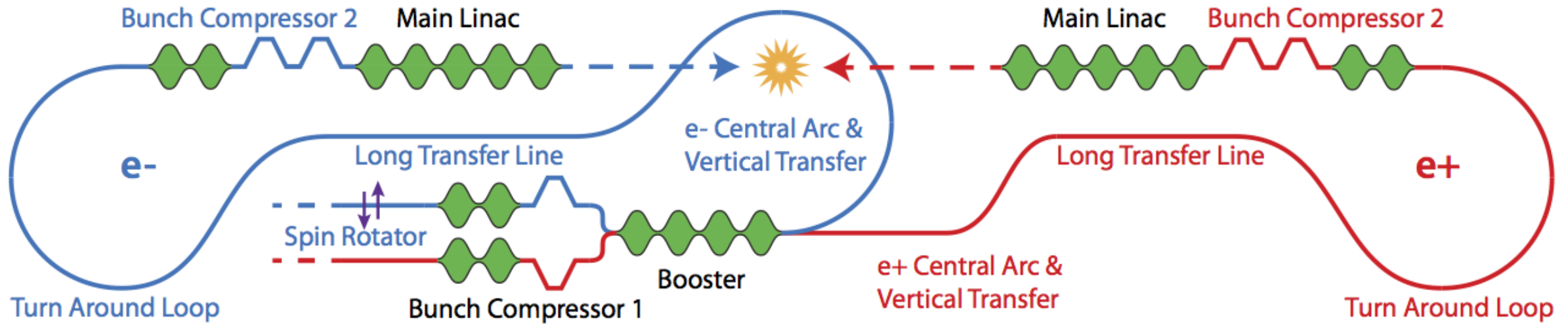
All systems contribute to vertical emittance

Final bunch length defined by main linac

Bunch charge defined by main linac

Bunch energy defined by main linac



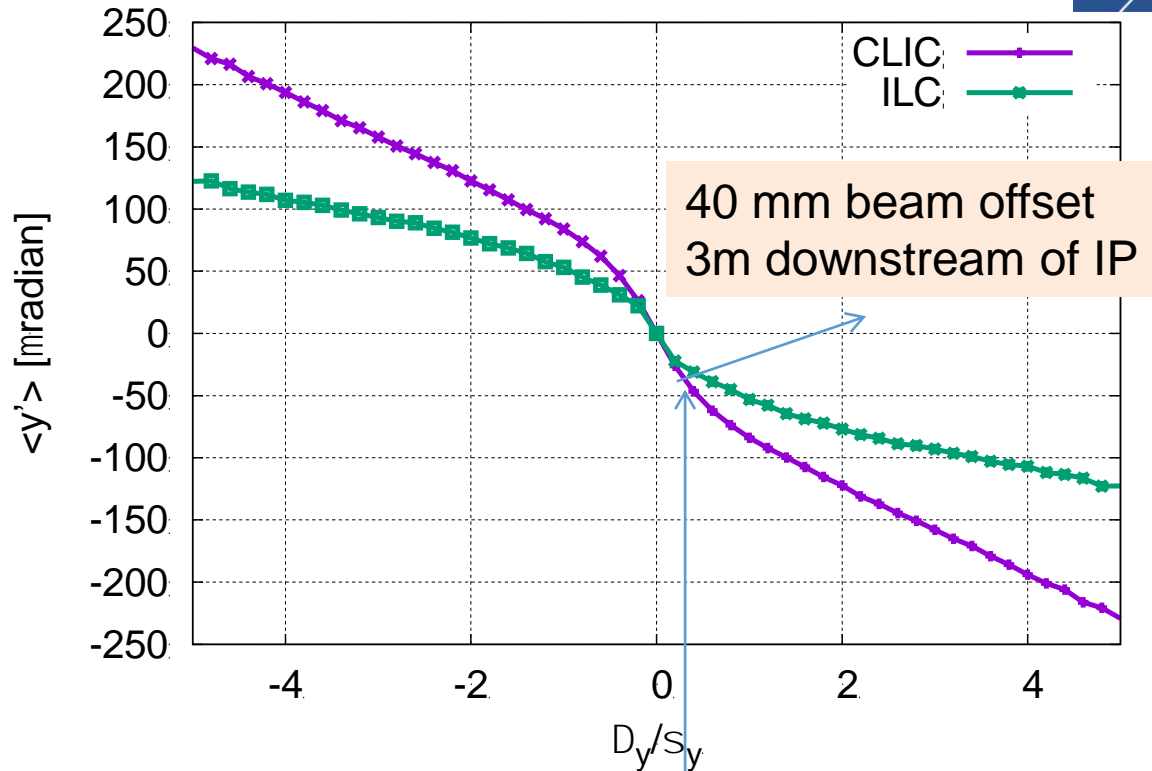


Transports the beam from the damping rings to the main linacs

Shortens the long bunch from the damping ring

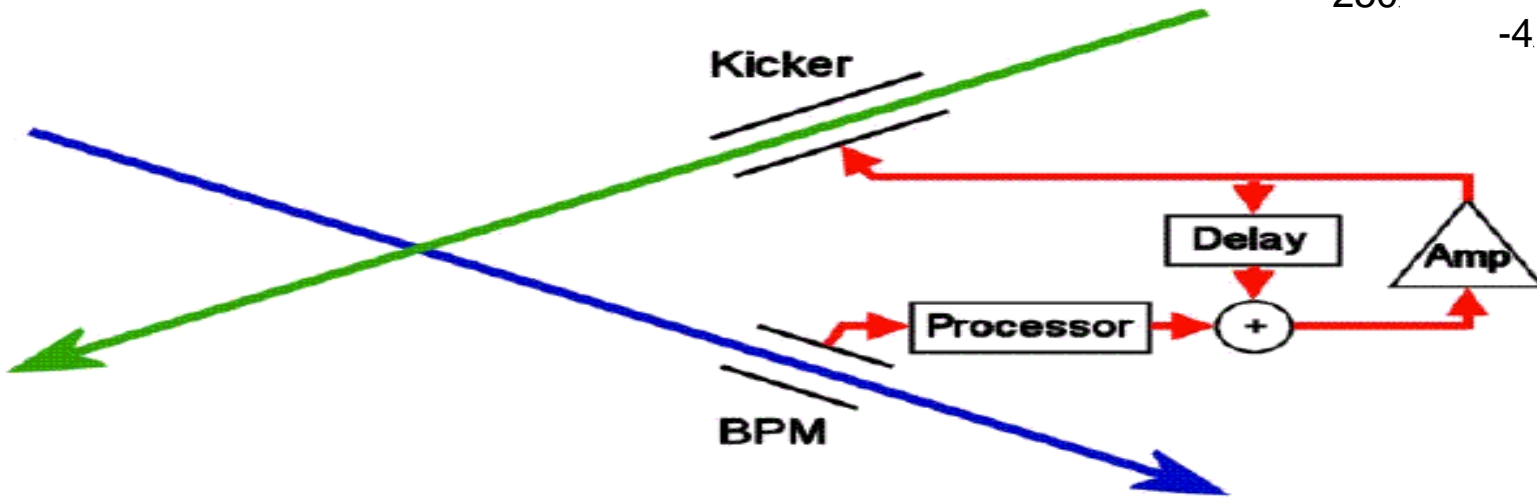
Strong deflection allows to easily measure and correct offset

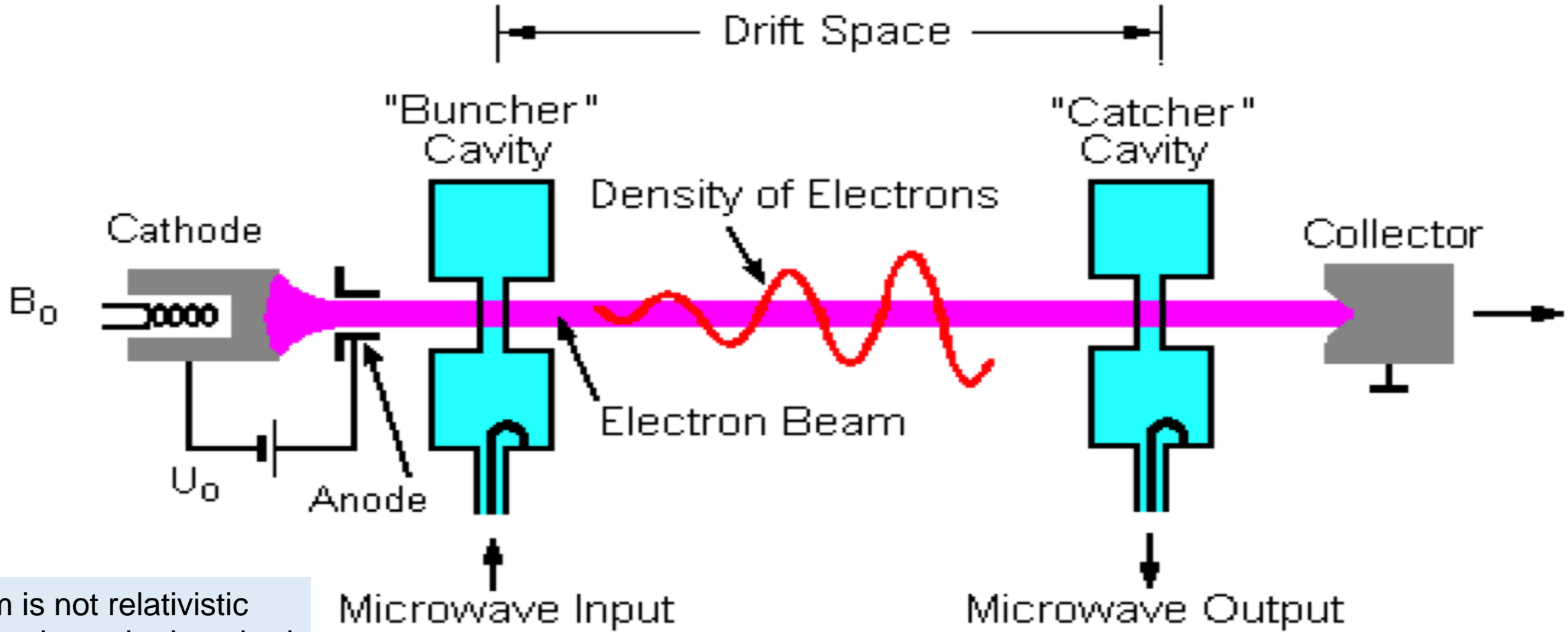
10 ns from IP to BPM
 13 ns to apply correction kick
 10 ns from kicker to IP
 = 33 ns latency vs. 170 ns beam pulse



$\Delta_y = 0.1\sigma_y = 0.3\text{nm}$

FONT system (Oxford)
 tested in ATF 2: 13 ns





Beam is not relativistic
So that it can be bunched

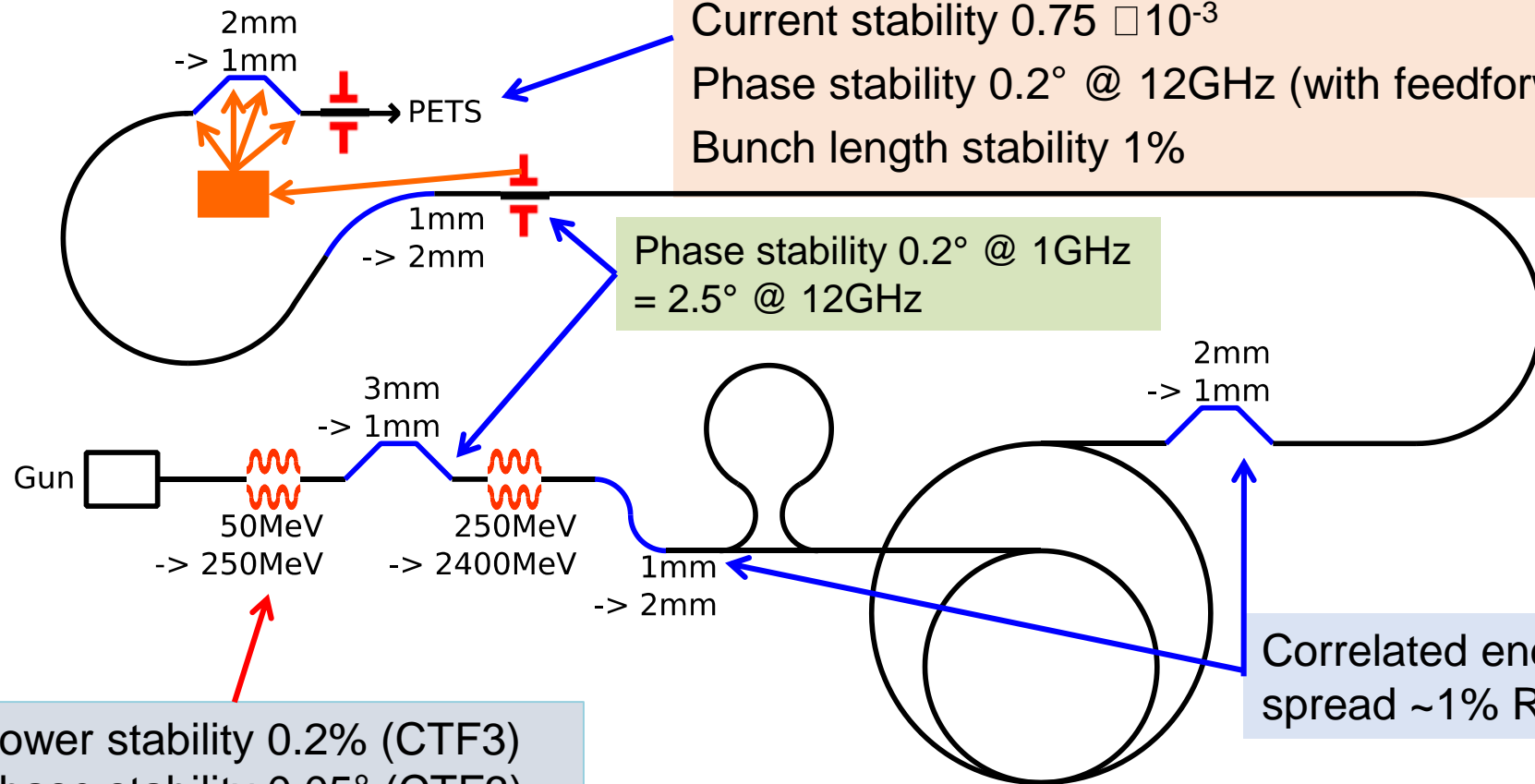


Performances



Feedforward (test in CTF3)
Timing reference (FEL)

Emittance $\epsilon_{x,y} \leq 150\mu\text{m}$
Transverse jitter $\leq 0.3\sigma$
Current stability 0.75×10^{-3}
Phase stability 0.2° @ 12GHz (with feedforward)
Bunch length stability 1%



Phase stability 0.2° @ 1GHz
 $= 2.5^\circ$ @ 12GHz

RF power stability 0.2% (CTF3)
RF phase stability 0.05° (CTF3)

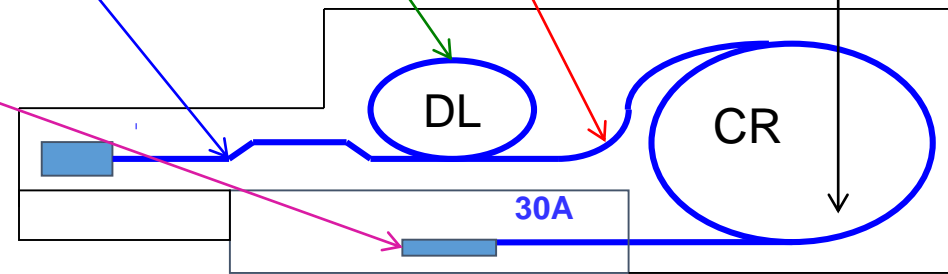
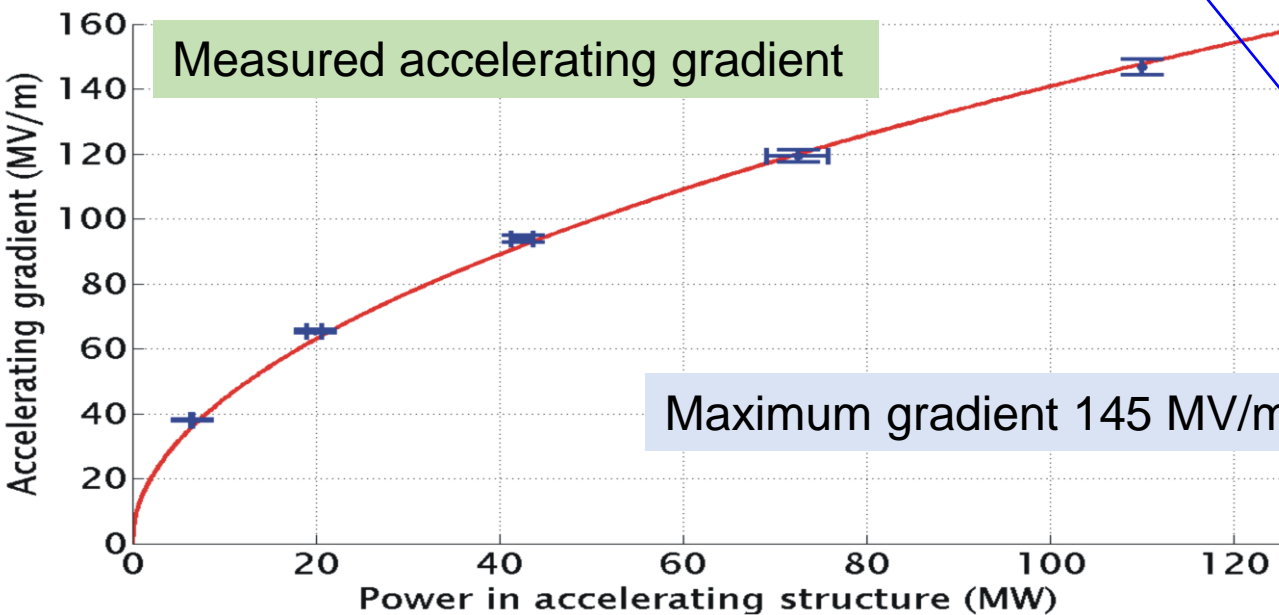
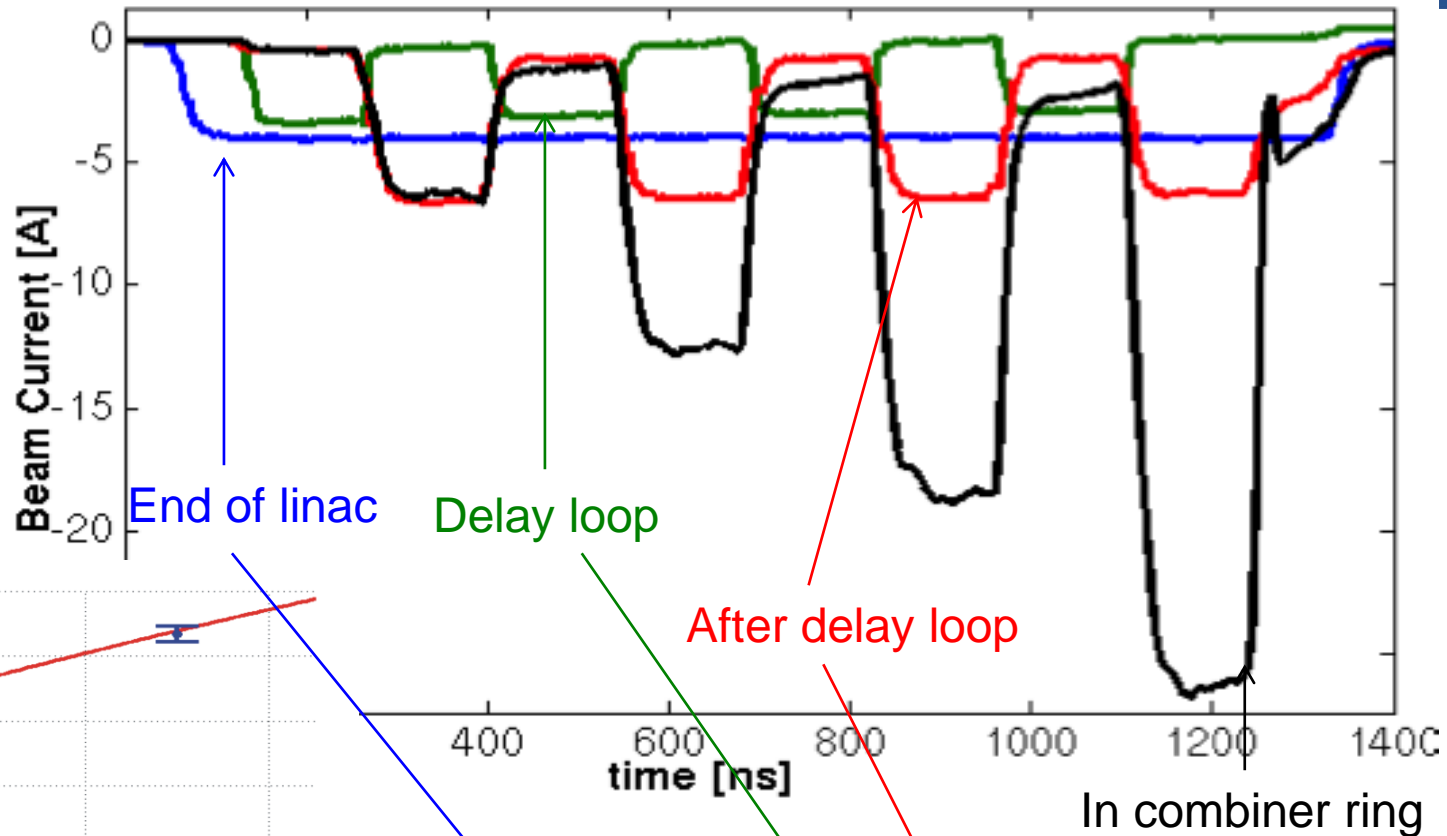
Correlated energy spread $\sim 1\%$ RMS



Drive Beam Combination in CTF3



RF to drive beam efficiency > 95%





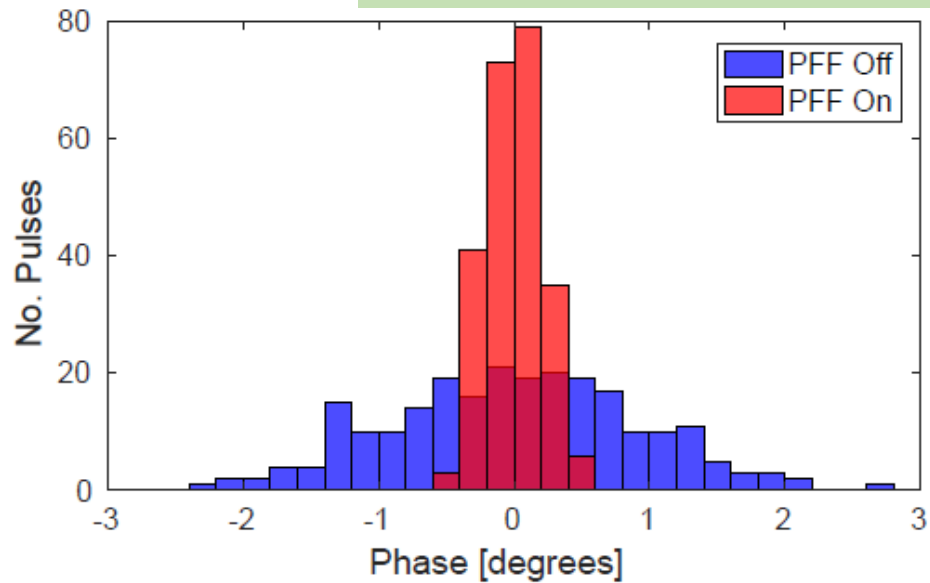
Drive Beam Quality



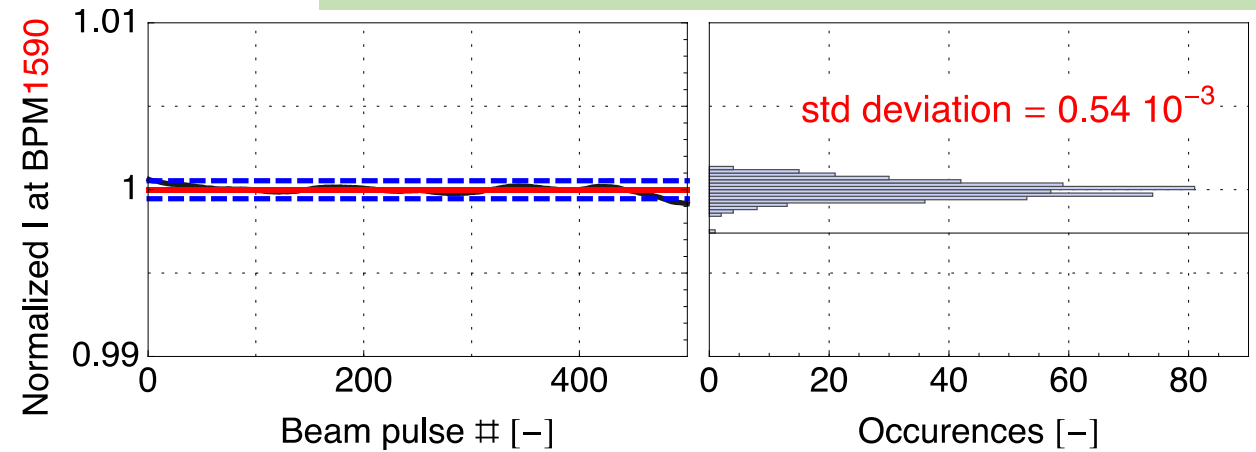
Current stability and phase stability are key

Errors lead to wrong main beam energy

Arrival time with feedback



Pulse current measurement (end of linac)



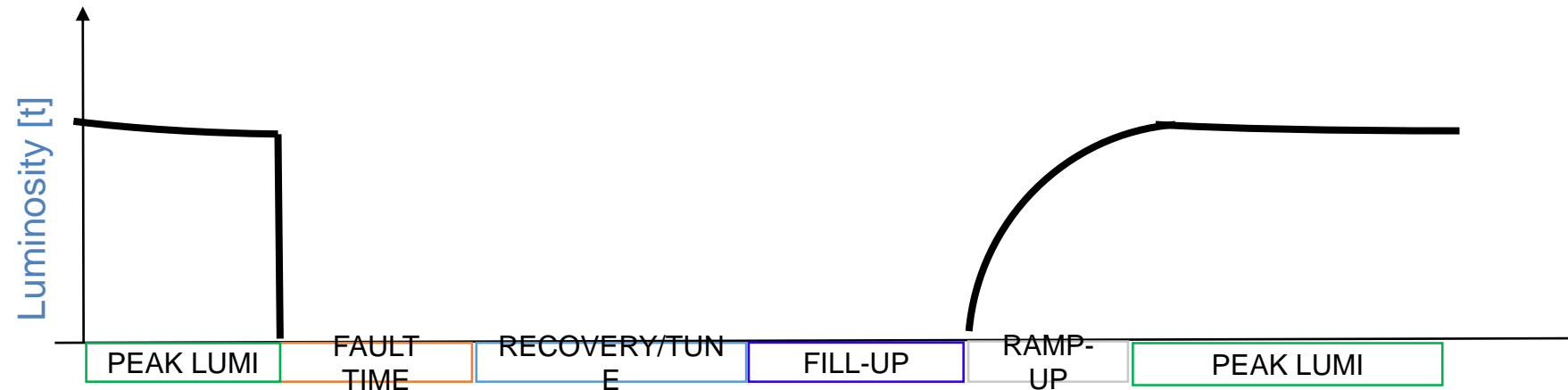
Losses in the delay loop, different design than in CLIC due to space 3 x smaller beam in CLIC should help

Parameter	CLIC goal	CTF3 measured
Arrival time	50 fs	50 fs
Current after linac	0.75×10^{-3}	0.54×10^{-3}
Current at end	0.75×10^{-3}	$2-18 \times 10^{-3}$
Energy	1.0×10^{-3}	0.7×10^{-3}



Aim for 80% availability during scheduled physics runs

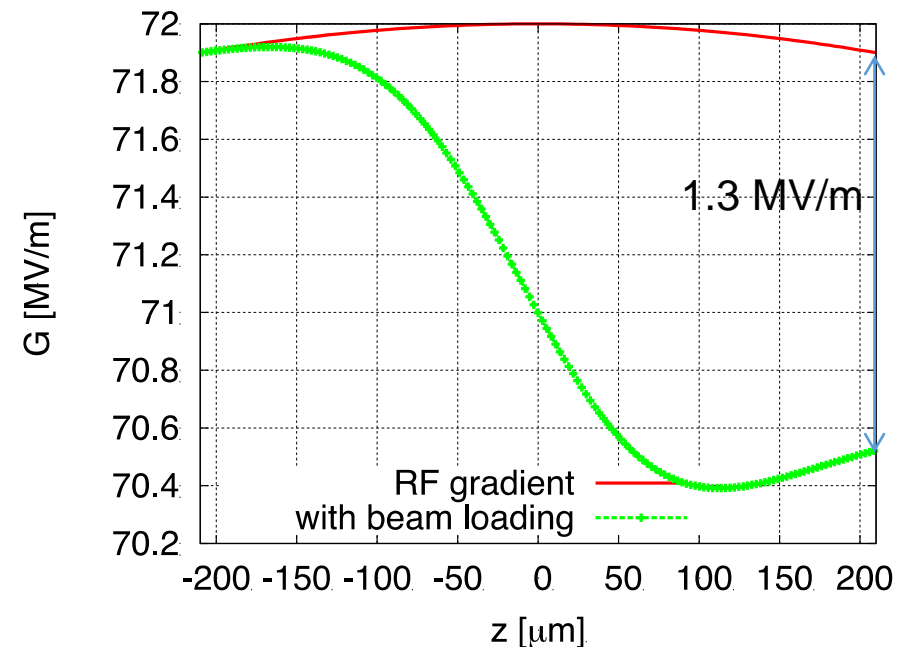
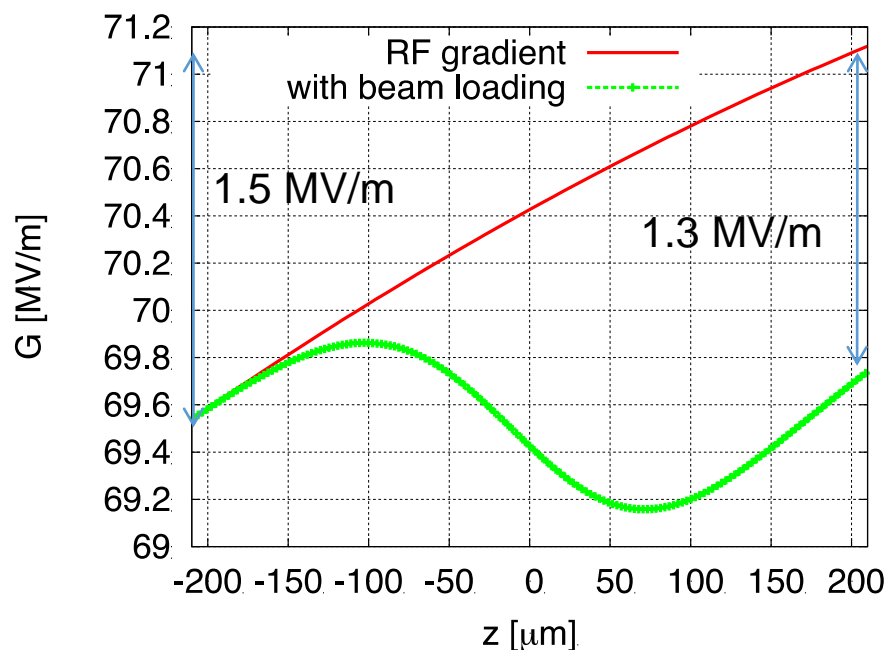
- Identifying the most important failures
- Mitigation concepts
- Repair time
- Operation schedule to optimise timing of stops



Loaded gradient along bunch

On-crest acceleration:

- more than 2% full gradient spread
- 0.7% RMS energy spread



Off-crest acceleration (12°):

- 1% full gradient spread
- 0.35% RMS gradient spread
- Loose about 2% in gradient



Main Linac: Low Emittance Preservation



Beam stability

- incoming beam can jitter (have small offsets) and become unstable
- lattice design, choice of beam parameters

Static imperfections

- errors of reference line, elements to reference line, elements. . .
- excellent pre-alignment, beam-based alignment, beam-based tuning

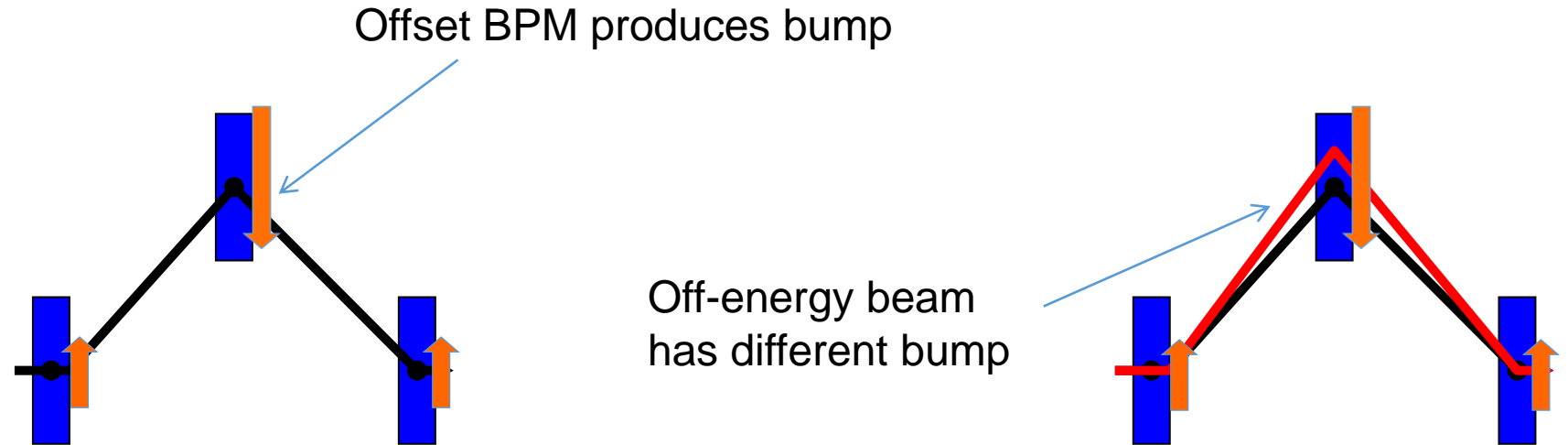
Dynamic imperfections

- Ground motion, cooling water induced jitter, RF jitter, electronic noise,. . .
- lattice design, BNS damping, component stabilisation, feedback, re-tuning, re-alignment
- Combination of dynamic and static imperfections can be severe
- Lattice design needs to balance dynamic and static effects

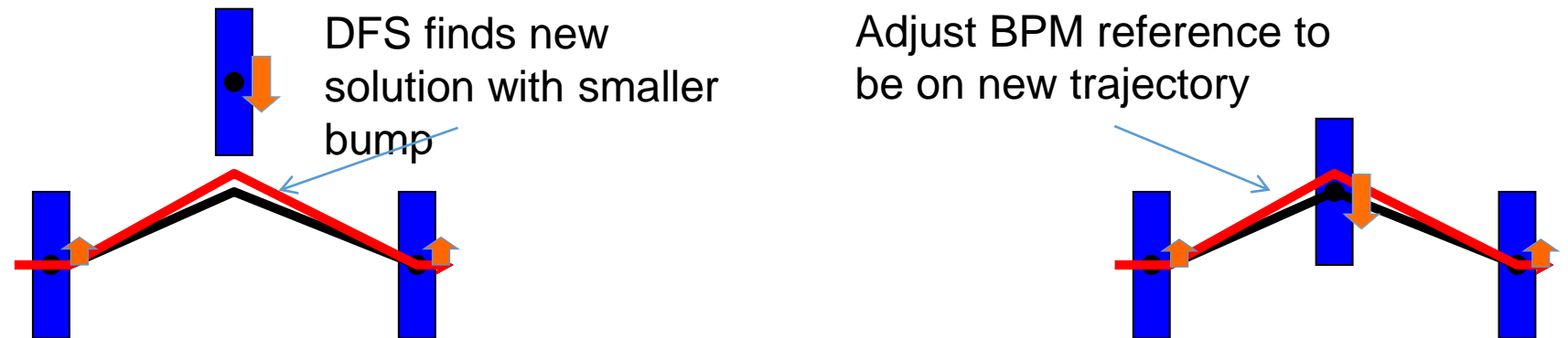
Method reduces dispersion

Use beams of **different energy** to identify offset BPMs

Compromise between offset and difference



Dispersion:
Different energy particles take different trajectories

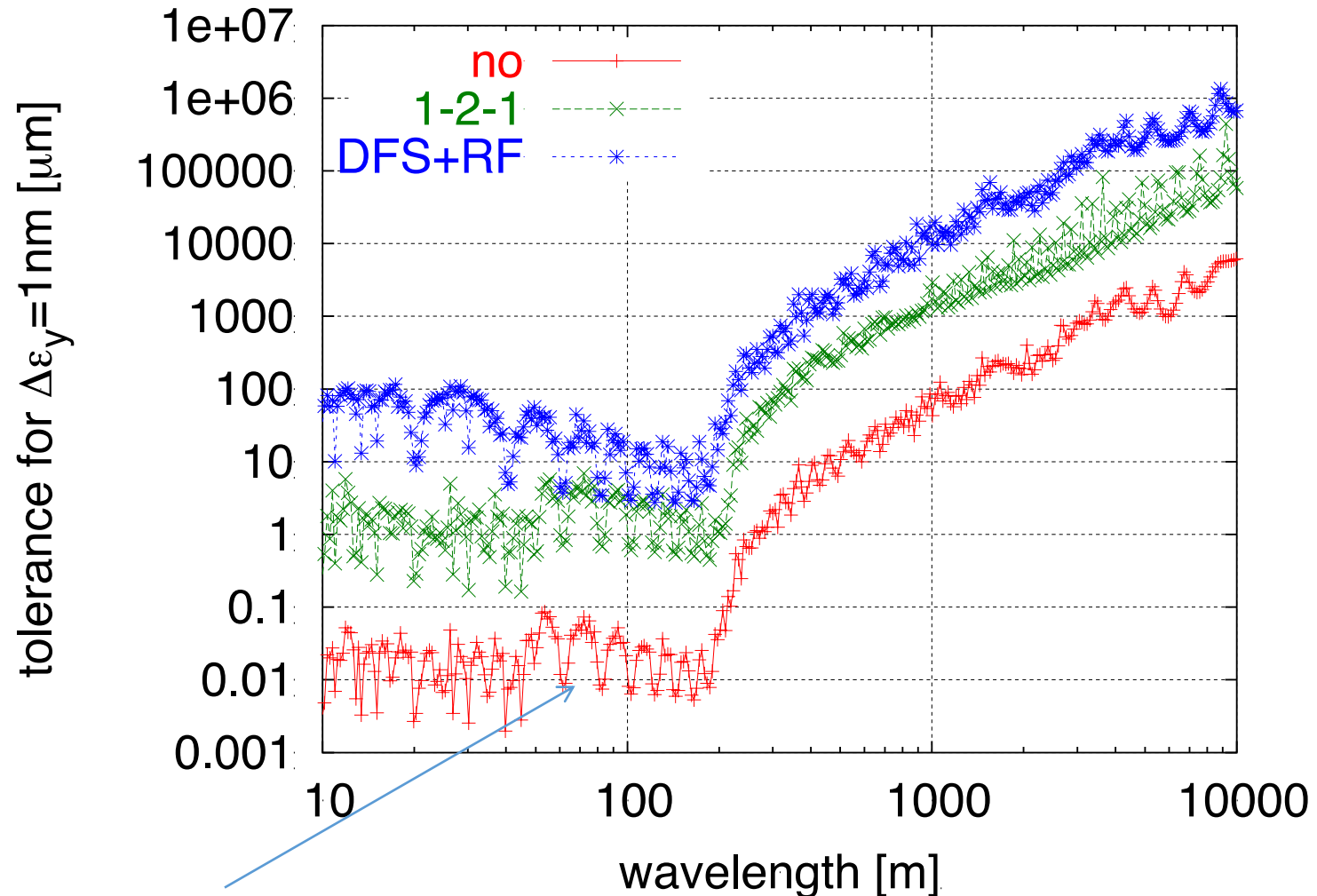




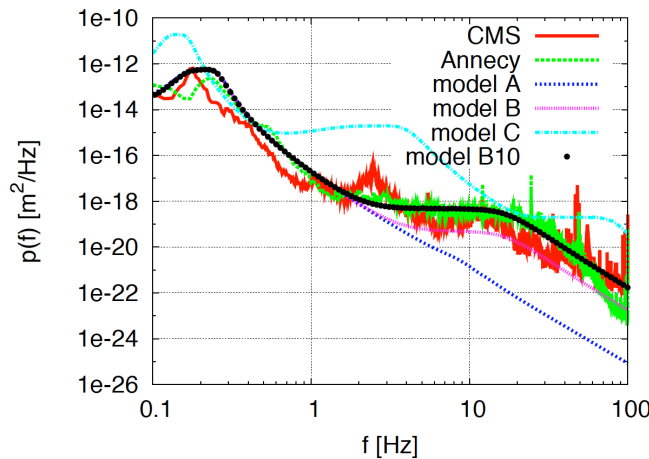
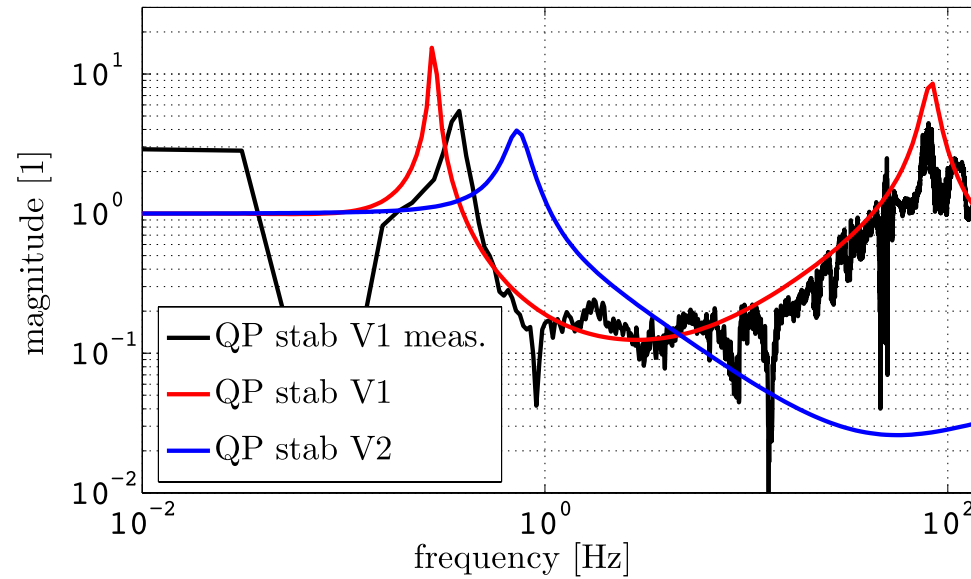
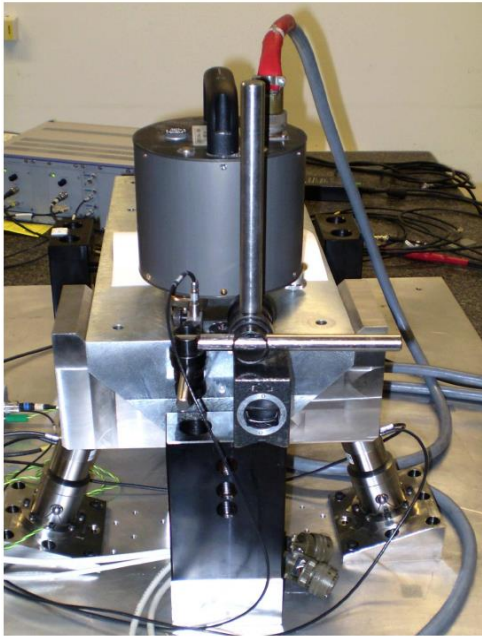
Pre-alignment Wavelength



Reference line error with given wavelength



Betatron wavelengths of the different sectors



Code

Machine model
Beam-based feedback



Luminosity achieved/lost [%]	
	B10
No stab.	53%/68%
Current stab.	108%/13%
Future stab.	118%/3%

Close to/better than target



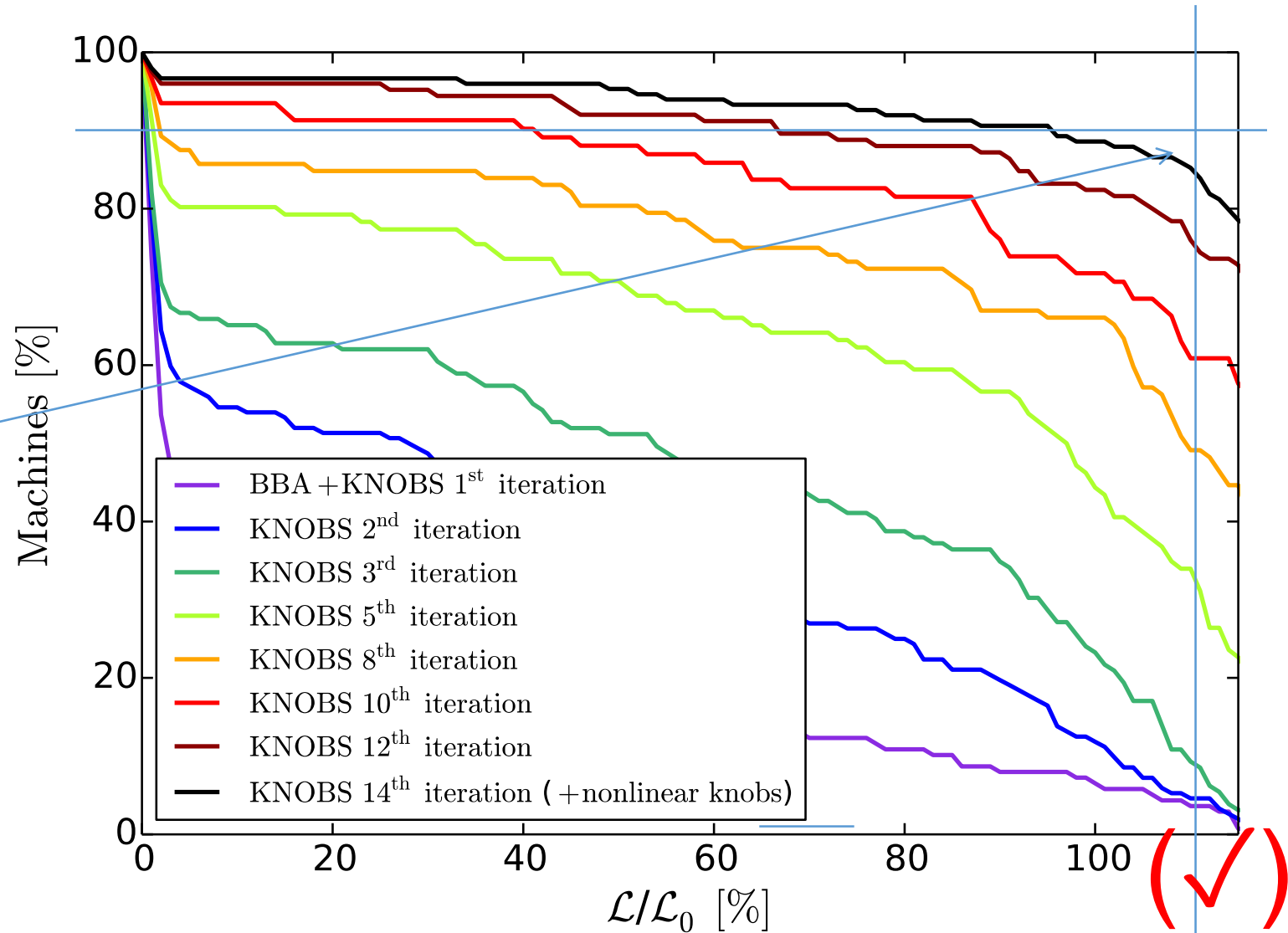
Aim to reach 110% of promised value
(10% is budget for dynamic imperfections)

Single beam study

85% reach 110% of
promised luminosity

Two-beam study ongoing

Small difference in performance





Beam Delivery System Tuning

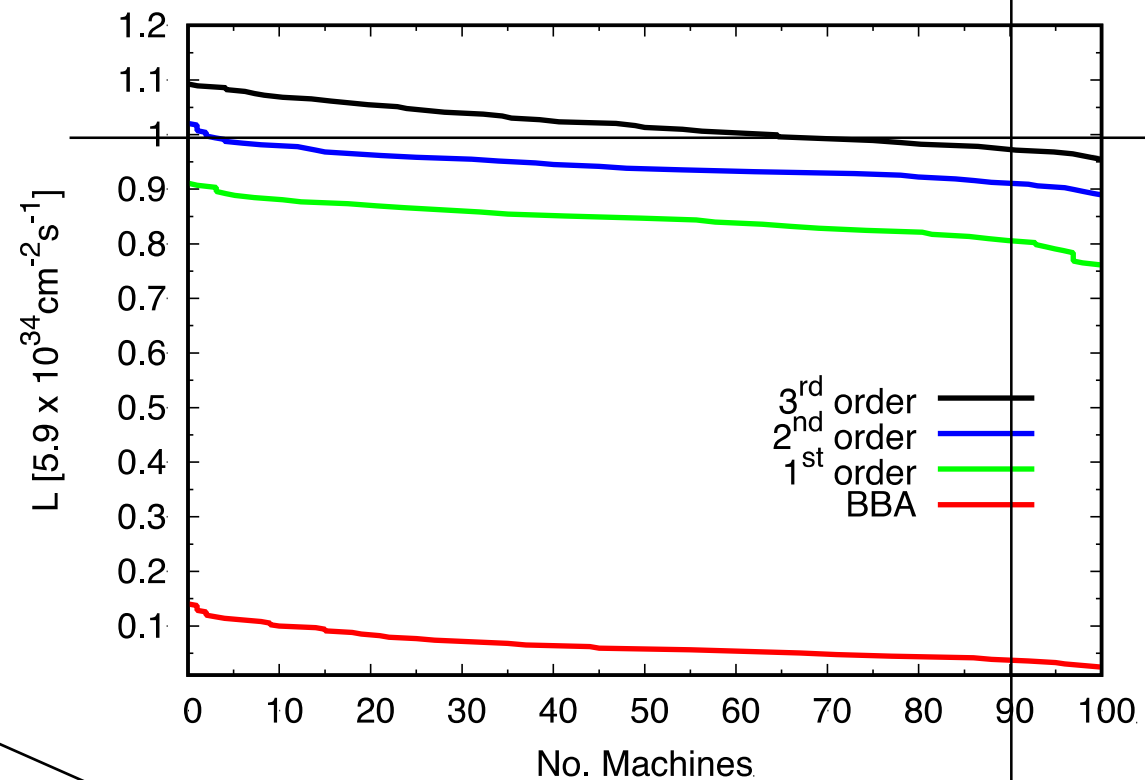
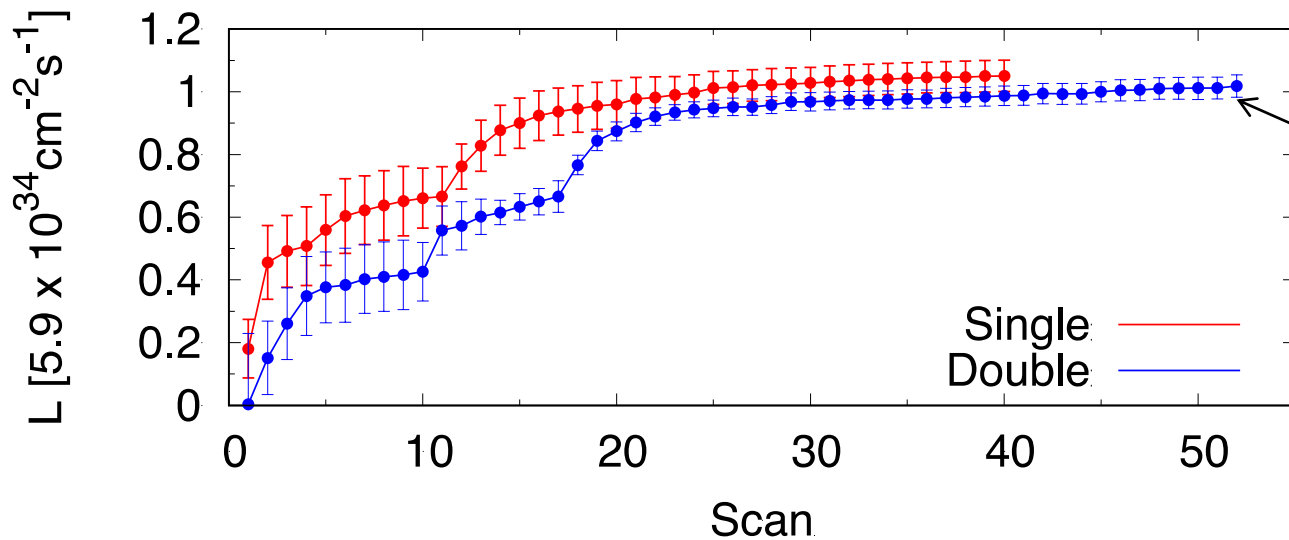


Most demanding case: Full two-beam tuning at 3 TeV

90% of machines achieve more than 97% of promised luminosity

Working on pushing this to 110% of promised luminosity

15000 luminosity measurements required



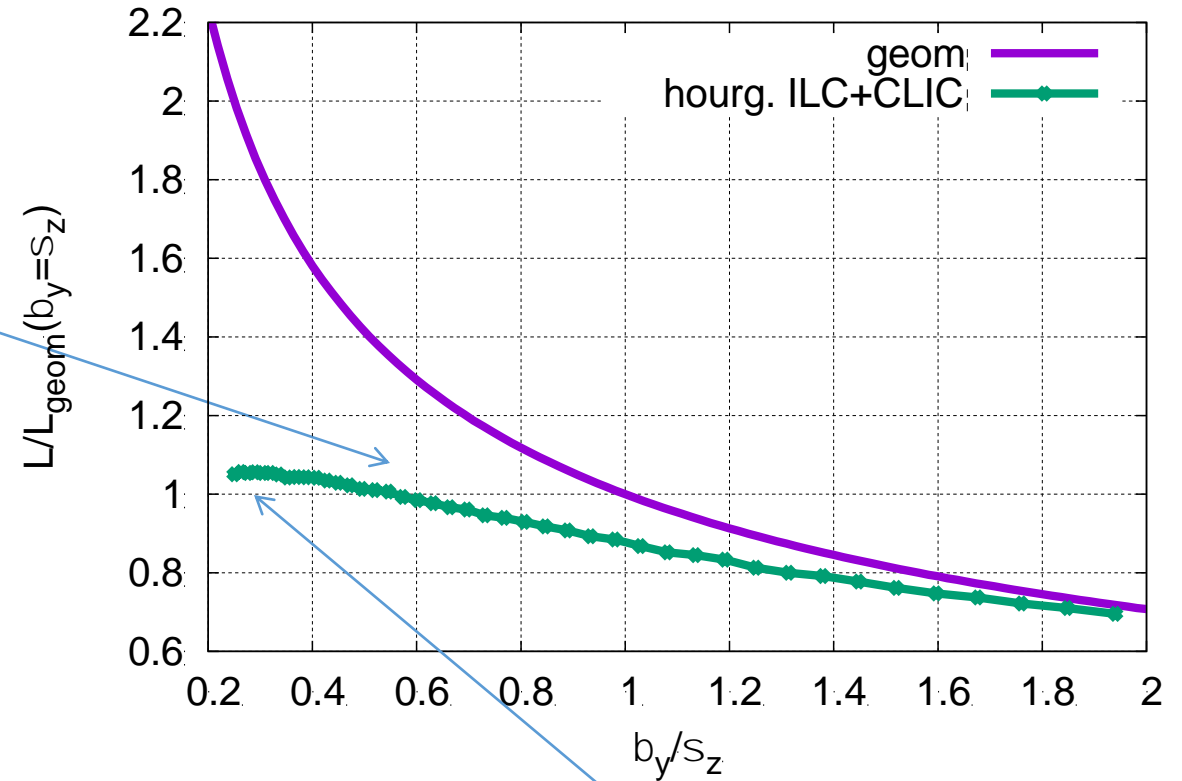
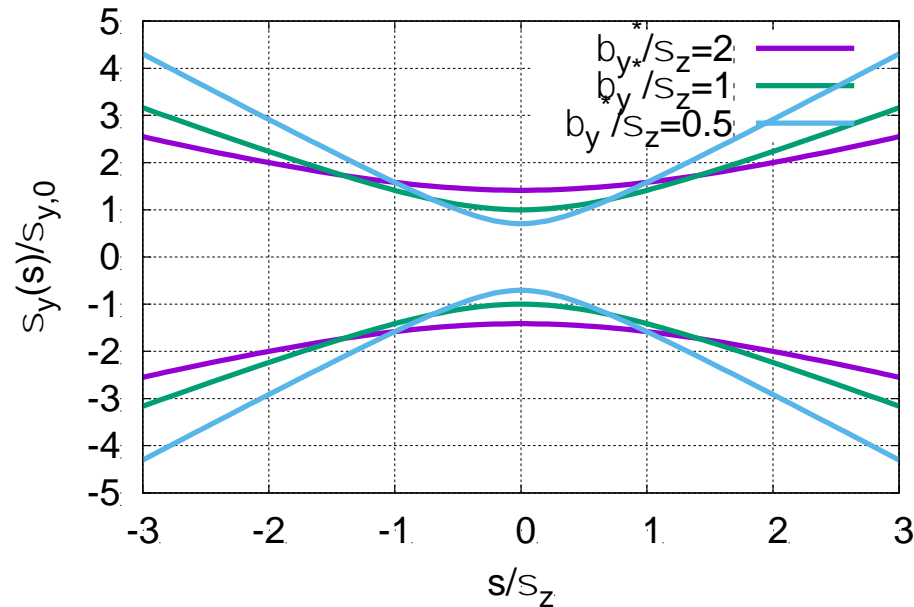
Luminosity is still increasing
 Simulation is very slow (much slower than reality)
 Good luminosity



Taking into account
hourglass effect

$$\beta(s) = \sqrt{\beta(0) + \frac{s^2}{\beta(0)}}$$

Luminosity does not improve
much below $\beta_y < \sigma_z$



For flat beams, the optimum is around $\beta_y = 0.25 \times \sigma_z$

Note: This is different for round beams

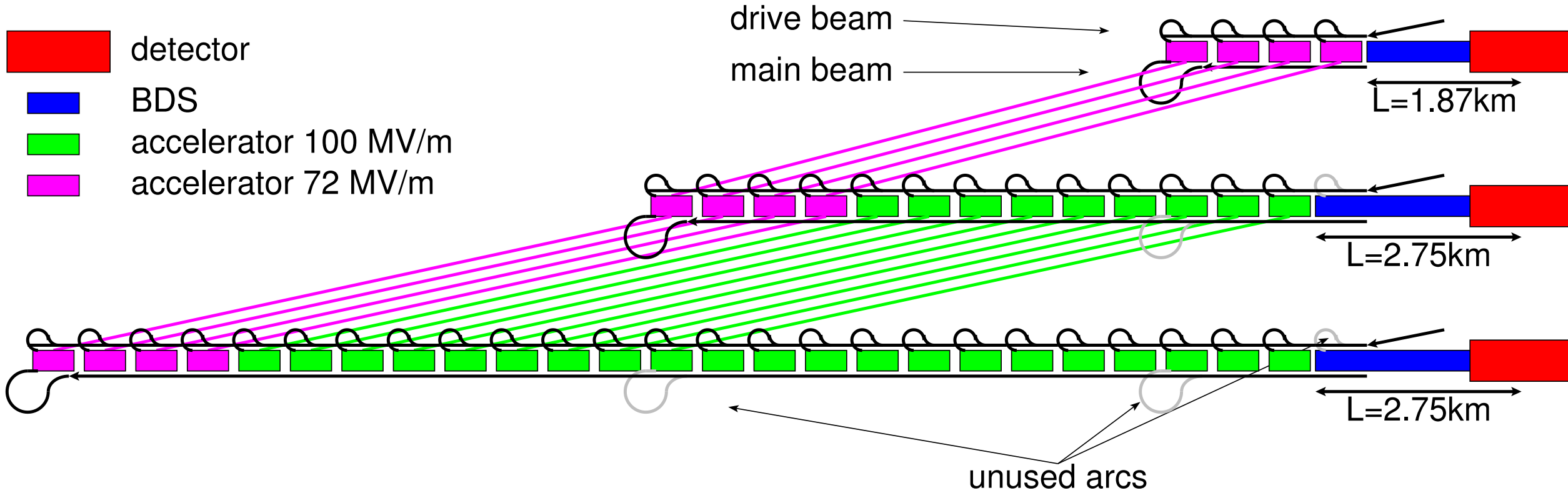


Upgrade



Build a linac that can be extended for further energy stages

- detector
- BDS
- accelerator 100 MV/m
- accelerator 72 MV/m



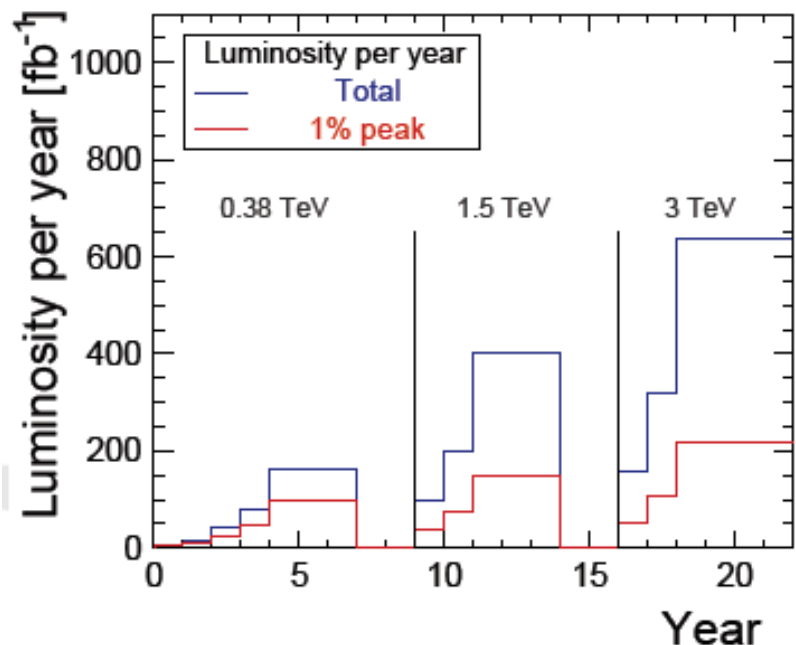
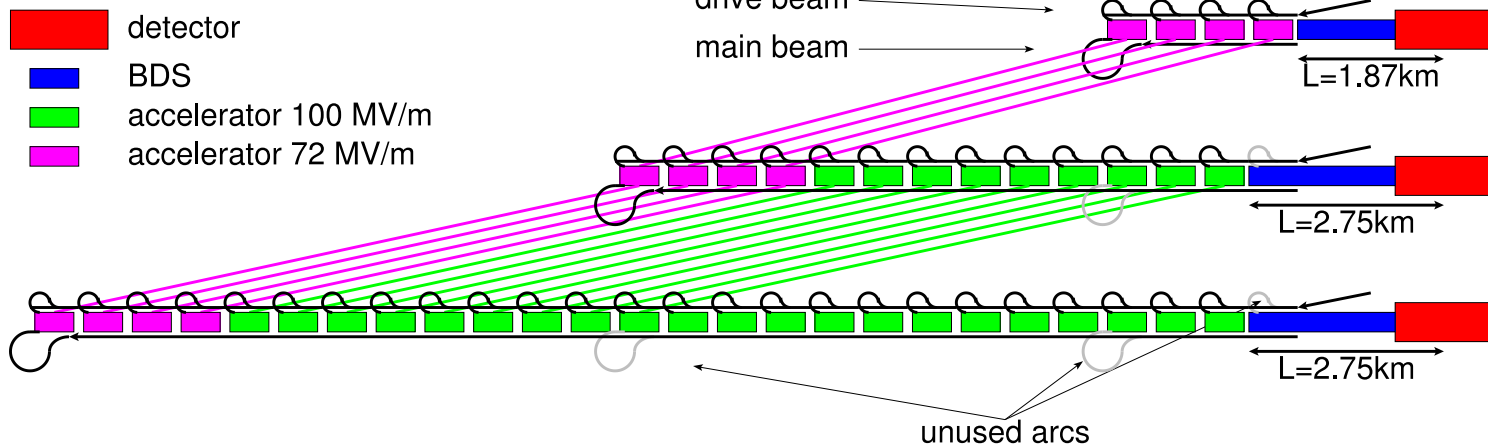
Higher gradient will be beneficial for upgrade



CLIC Staged Design



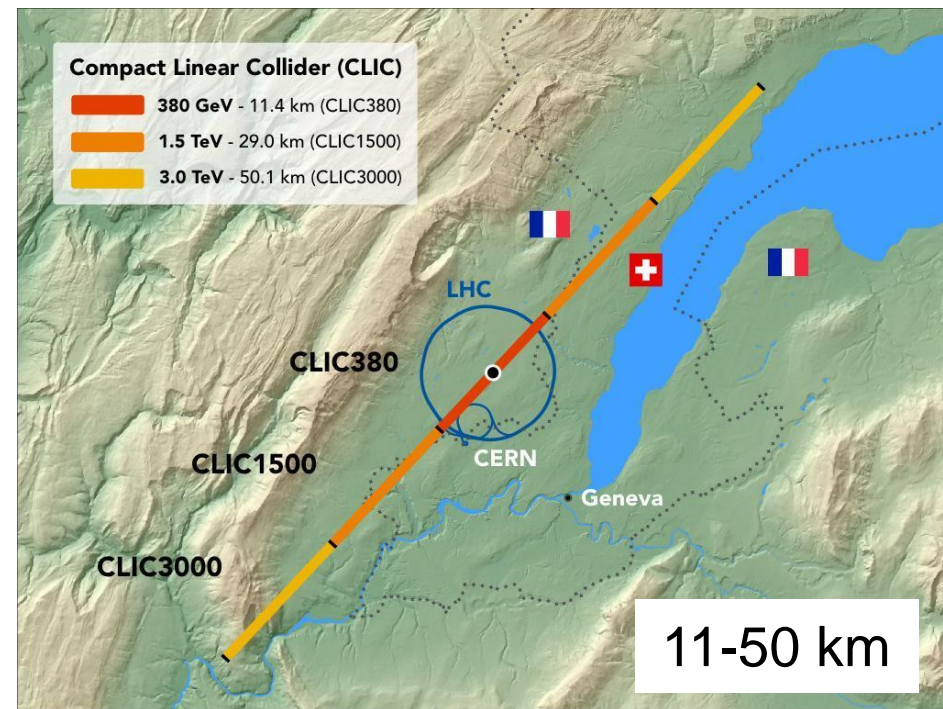
Optimised first energy stage
 380 GeV: HZ, WW fusion, top, ...
 Further stages re-use
 infrastructure and equipment



Stage	\sqrt{s} (GeV)	\mathcal{L}_{int} (fb ⁻¹)
1	380	500
	350	100
2	1500	1500
3	3000	3000

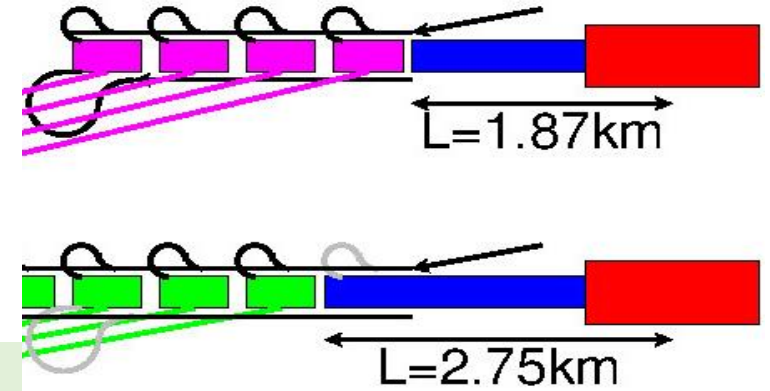
Preliminary value of first stage
 6690 MCHF

Further optimisation ongoing



Hardware will be modified, but try to minimise changes
 At high energy smaller number of bunches and bunch charge

- Should be acceptable in most systems
- But have to allow for longer pulses
- Upgrade of injector and RTML RF systems



Example: BDS takes energy stages into account

