

Managing data with columnar granularity

Jim Pivarski

Princeton University - DIANA-HEP

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This talk isn't about how we manage data in HEP, but how we might.

- ▶ Therefore, it isn't a "how-to" talk but a "what-if" talk.
- If you have experience in this, I want to hear from you!

Columnar data



Serializing data in columns is an old idea in HFP:

- ▶ 1989: Column-Wise-N-tuples (CWN) in PAW
- ▶ 1996: "split" (columnar) C++ objects in ROOT

. . .

- ► 2002: MonetDB
- ► 2005: C-Store (Vertica)
- ▶ 2010: Google Dremel paper
- ▶ 2013: Apache Parquet
- ► 2016: Apache Arrow

| | | Table | |
|-------|---------|-----------|-------|
| | Country | Product | Sales |
| Row 1 | India | Chocolate | 1000 |
| Row 2 | India | Ice-cream | 2000 |
| Row 3 | Germany | Chocolate | 4000 |
| Row 4 | US | Noodle | 500 |

| Ro | w Store | |
|-------|-----------|--|
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| C | Column Store |
|---------|--------------|
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|---------------------------|----|--------|--------|--------|----------|-----|---------|----------|-----|-----------|---|
| outer stops | [| | | | | | | 3, | 3, | 4 |] |
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| 1 st attribute | [| a, | b, | C, | d, | | e, | f, | | g |] |
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Example: vector<vector<pair<char, int>>>

```
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outer stops
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► Each primitive attribute is in an array by itself, with no list boundaries.



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 - ▶ Offsets (Arrow): include *starting* index; can represent interval slices without copying.



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 - ightharpoonup Sizes: sizes = stops starts; compressible, fill in parallel, but no $\mathcal{O}(1)$ lookup.
 - lacktriangle Dremel/Parquet: "repetition level"; packed small integers, but no $\mathcal{O}(1)$ lookup.



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Whether it's ROOT or Parquet, the file structure glues a set of columns together to be downloaded, replicated, versioned, or migrated to colder storage as a unit.



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- "Monojet analysis" only needs jet objects, but it needs jets constructed many different ways to study systematics.
- "Boosted top search" needs jets with substructure variables.
- "Heavy flavor study" needs jets, electrons, and muons with isolation and B-tagging variables.
- "Diphoton Higgs mass" needs photons, electrons for a veto, and converted pair electrons.
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Within each particle object, the kinematic variables (p_T, η, ϕ, m) are needed the most, with "isolation/tagging/matching/..." needed by different analyses to varying degrees.



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Columnar data lets us read relevant attributes from disk one at a time (or with XRootD, over the network), but data management systems are unaware of how to open up a ROOT file and operate on individual columns.

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•

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Case 1: serve the most desirable attributes from RAM or SSD and less desirable attributes of the same dataset from disk or tape.

Currently, we make 2 or 3 levels of "slimmed" copies (AOD/MiniAOD/NanoAOD) to serve with different latencies. Three sizes does not fit all, so individual analysis groups make their own subsets (and have to find their own storage).



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Case 4: speed up filtering with database-style indexing.

Case 1: lower latency for popular columns



Same object-array mapping example:

| logical data | [[| (a,1), | (b,2), | (c,3), | (d, 4)], | [], | [(e, 5), | (f, 6)]], | [], | [[(g,7)]] |
|---------------------------|----|--------|--------|--------|----------|-----|----------|-----------|-----|-----------|
| outer stops | [| | | | | | | 3, | 3, | 4] |
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| 2 nd attribute | [| 1, | 2, | 3, | 4, | | 5, | 6, | | 7] |

If the 2^{nd} attribute is more popular than the 1^{st} attribute, raise the 2^{nd} attribute into warmer cache (on the server).

To the degree that analysts' interests overlap (e.g. the all-popular kinematic variables), one copy in hot cache may be shared by all. This is impossible for private skims.

Case 2: overlapping dataset definitions



Dataset version 1 schema:

Dataset version 2 schema:

(Not all arrays can be combined into datasets; validity determined by provenance.)

Case 3: zero-copy views of selections



| logical data | [[(a,1), | (b,2), | (c,3), | (d, 4)], | [], | [(e,5), | (f,6)]], | [], | [[(g,7)]] | |
|---------------------------|----------|--------|--------|----------|-----|---------|----------|-----|-----------|---|
| outer offsets | [0, | | | | | | 3, | 3, | 4 |] |
| inner offsets | [0, | | | 4, | 4, | | 6, | | 7 |] |
| 1 st attribute | [a, | b, | C, | d, | | e, | f, | | g |] |
| 2 nd attribute | [1, | 2, | 3, | 4, | | 5, | 6, | | 7 |] |
| inner starts (v2) | [0, | | | | | 4 | | | |] |
| inner stops (v2) | [1, | | | | | 5 | | | |] |
| outer starts (v2) | [0, | | | | | | | 2 | |] |
| outer stops (v2) | [2, | | | | | | | 2 | |] |
| logical data (v2) | [[(a,1) | | | 1, | | [(e,5) | 11, | [] | | |

- ▶ inner starts/stops (v2) keeps only the first pair of each sublist: particle selection.
- outer starts/stops (v2) keeps only the first two sublists: event selection.

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- ▶ If a new 2nd attribute is created, we can immediately update the selected data.

Case 4: database-style indexing (only a sorting example)



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| 1 st attribute (v2) | [g, | | е, | f, | | a, | b, | С, | d |] |
| 2 nd attribute (v2) | [7, | | 5, | 6, | | 1, | 2, | 3, | 4 |] |
| inner starts (v2) | [3, | | | | 1, | 1, | | | 0 |] |
| inner stops (v2) | [7, | | | | 1, | 3, | | | 1 |] |
| | | - 41 | | | | | | | | |

logical data (v2) unchanged!

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▶ Different sublists can be sorted differently, e.g. muon attributes by max muon p_T per event and jet attributes by max jet p_T per event.

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- ▶ Different sublists can be sorted differently, e.g. muon attributes by max muon p_T per event and jet attributes by max jet p_T per event.
- ▶ Request for $p_T^{\text{muon}} > X$ AND $p_T^{\text{jet}} > Y$ only touches one end of all the arrays.

How might it be implemented?



This is not an Object-Relational Mapping (ORM): the order of the arrays is important and they should be served in contiguous blocks.

 \rightarrow suggests array database (e.g. SciDB) or object store (e.g. Ceph)

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Option 1: define an Object-Array Mapping (OAM), build an interpretive layer around an object store, and translate HEP data into it.

Option 2: use ROOT's OAM and interpretive layer, but replace its file-backed storage with the object store.

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Option 2: use ROOT's OAM and interpretive layer, but replace its file-backed storage with the object store.

Option 2 is more limited (no start/stop arrays), but less needs to be invented and old analysis scripts would function in the new system.



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► File accessed by a single user contains objects and subdirectories.

ROOT object store

► A server-bound file view would have many users, "home directories."



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- Same baskets would be identified by object store keys. No fragmentation concerns and objects get replicated.
- No artificial boundaries in the dataset: only segmented into baskets, which are hidden from users.
- Need to develop new interfaces to share basket data among versioned datasets and track provenance.



Questions for HEP: any use-case concerns? Missing features?

Questions for others: does this look familiar? Do you have experience with systems like this? If so, what worked/didn't work?