

## Status of the ITS O2 code

- ITS detector geometry
- **Simulations:** Transport, ALPIDE response, digitization
- Reconstruction: Cluster finding, cluster-topology code, track finding (see Maximiliano's slides)
- Quality Control & event display
- Calibration & alignment

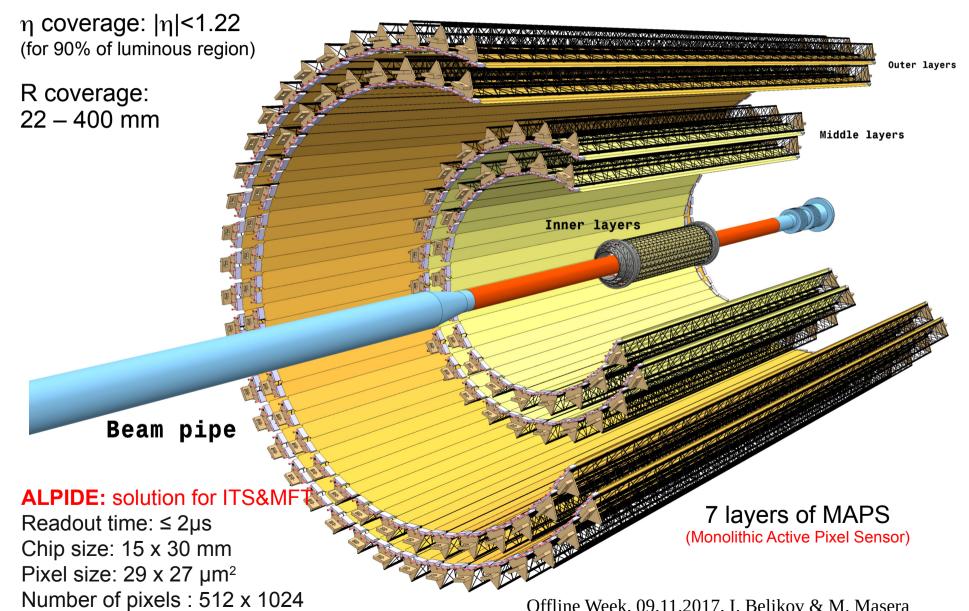




## Layout of the upgraded ITS

12.6 G-pixel camera (~10 m² of Si, ~13.6M CHF)





#### End-of-2017 view on the ITS code



#### Geometry:

- Operational
- Remaining details and changes in the HW design being implemented
- Alignable volumes coming this year (will be the same as in AliRoot)
   Next year: Sagging degrees of freedom, services outside the physics acceptance

#### Simulation:

- "Box" particle generator
- MC transport with Geant3
- ALPIDE response using the output of external "microscopic" chip simulations
- Time-aware digitization: triggered and continuous mode (to be finalised: strobe boundaries, access to the params in CDB)
   Next year: Try also (multi-threaded) Geant4 ?

Synchronization with other detectors in continuous mode?

#### End-of-2017 view on the ITS code



#### Reconstruction:

- Cluster finder (the same for the MC and real data)
- Code to handle the cluster shapes (being ported from AliRoot)
- Track finders
  - CookedTracker ("classical", CPU): functional, reasonably fast, multi-threaded
  - CATracker ("Cellular Automaton", CPU and GPU): see Max's presentation
- MC labels decoupled from clusters and tracks, written to a separate branch, can optionally be suppressed

Next year: Development of the CATracker, cluster compression, Cluster class based on shapeID and expernal LUT, wrapping the reconstruction code in "O2 devices"

#### Quality Control & Event Display:

- An initial estimate of the ITS QC requirements sent to the O2 WP7
- A simplified representation of the ITS geometry for the Event Display provided to the O2 WP9

Next year: All the rest

#### Calibration and alignment:

Next year: Everything

## Tasks & Manpower



1	Task	Contact	People	When
2	General ITS geometry	Mario Sitta	Parinya	> 2017
3	Sagging geometry	Cristina Bedda	Mario, Ruben	2018
4				
5	ALPIDE simulation	Davide Pagano	Stefano, Germano, Enrico	> 2017
6	Time dependent digitiser	Ruben Shahoyan		2017
7				
8	Time dependent clusteriser	Ruben Shahoyan		2017
9	Cluster finder (CPU)	Iouri Belikov		2017
10	Cluster finder (FPGA) ?	Anisa Qazi ?		
11	Cluster topology	Luca Barioglio		2017>
12				
13	CA tracker (CPU, GPU)	Maximiliano Puccio		2017>
14	CA tracker (GPU)	Iacopo Colonnelli		2017>
15				
16	Primary vertex finder	Matteo Concas		2018
17				
18	Compression of clusters			2018
19				
20	Calibration (noise, dead)			2018
21	QC & event display			2018
22				
23	O2 "devices"			2018

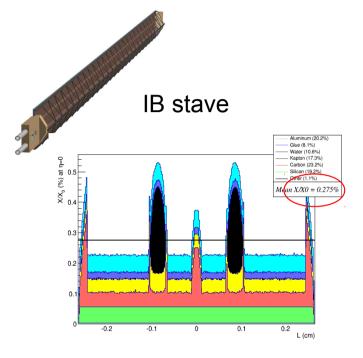
- 5 − 7 active developers (~50 people on the mailing list)
- New young people expressing an interest to join
  - Tsukuba, Japan (Kana Nakagawa)
  - Prague, Czech Republic (Artem Isakov)

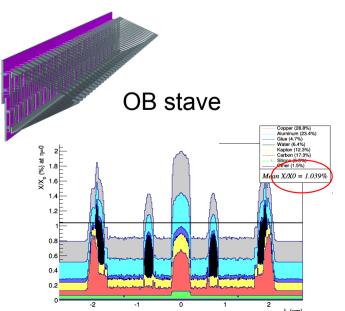


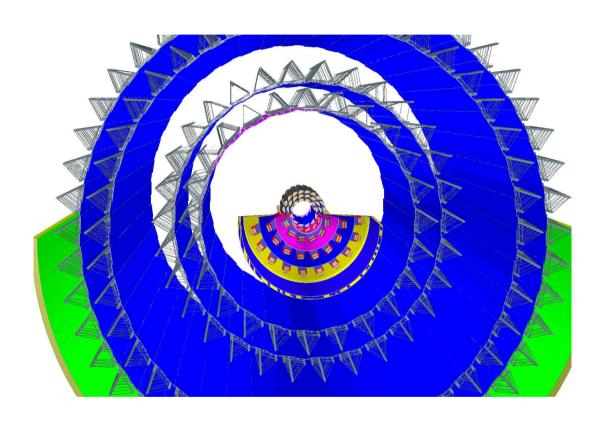
## **Supporting slides**

#### ITS geometry for full simulation & reconstruction (Mario)







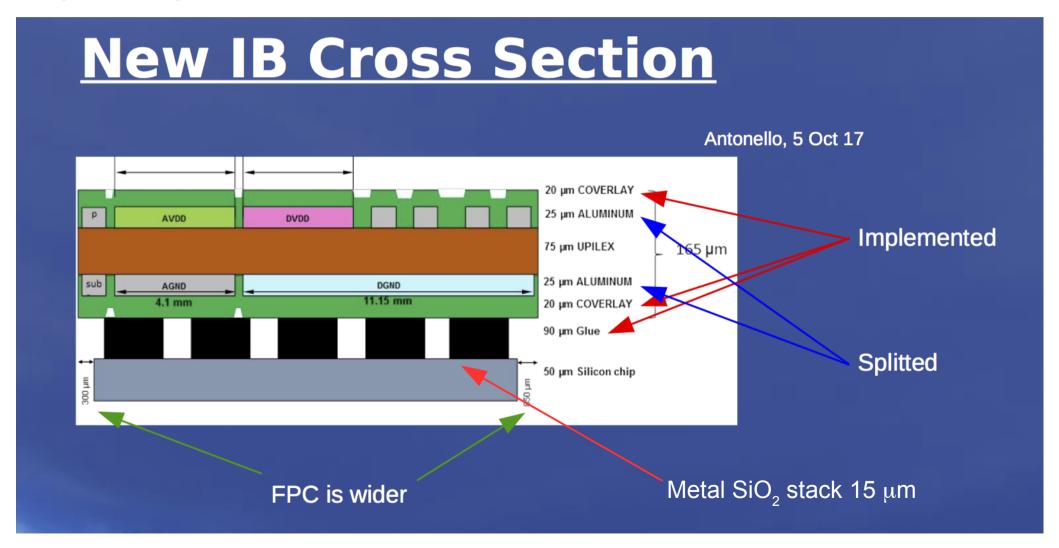


Very detailed and close to the final state. But, no alignment yet.

# ALICE

## Updates in the ITS geometry

(Mario)

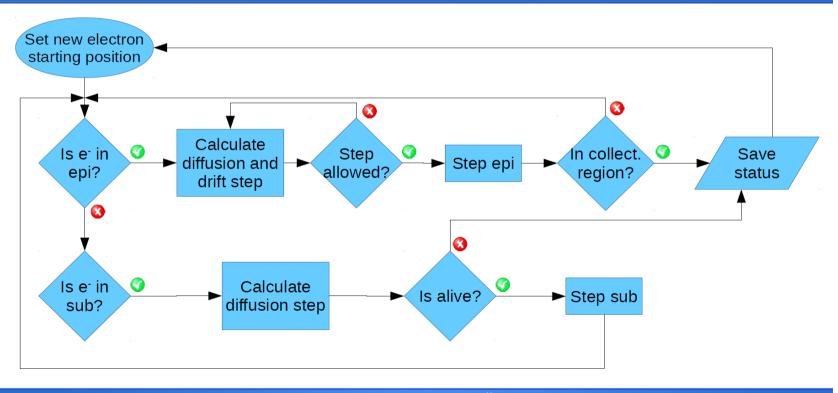




### **ALPIDE** response

(Miljenko Šuljić, Jacobus W. van Hoorne)

#### **Algorithm**



31/05/17

MAPS simulation - Miljenko Šuljić

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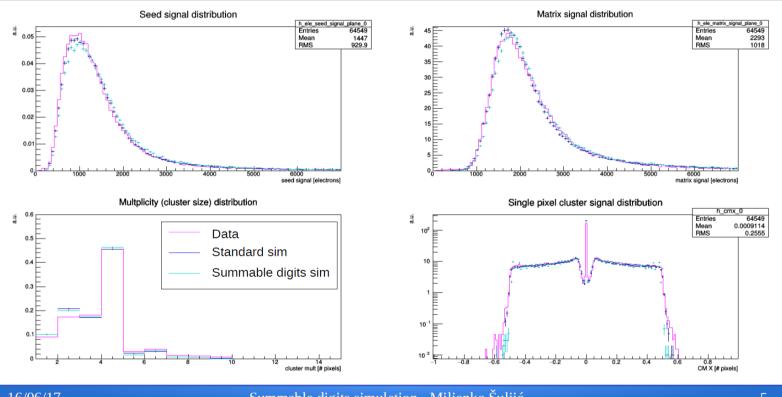
"Microscopic" simulations using the electrical field extracted from TCAD



### **ALPIDE** response compared with data

(Miljenko Šuljić, Jacobus W. van Hoorne)





16/06/17

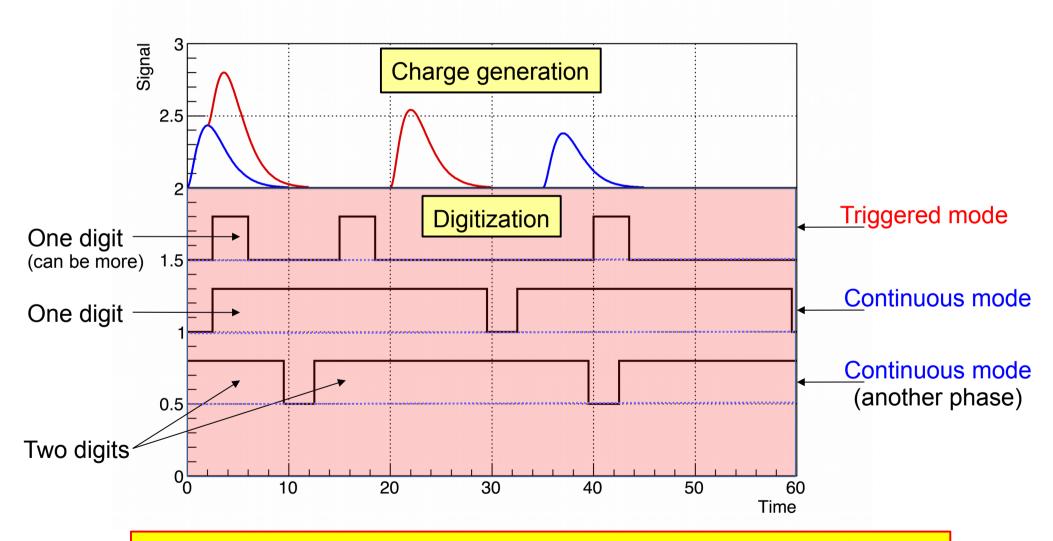
Summable digits simulation - Miljenko Šuljić

The agreement of both "microscopic" and "on-grid" simulations with the data is just amazing!

# ALICE

### Time-aware ITS digitization

(Ruben)

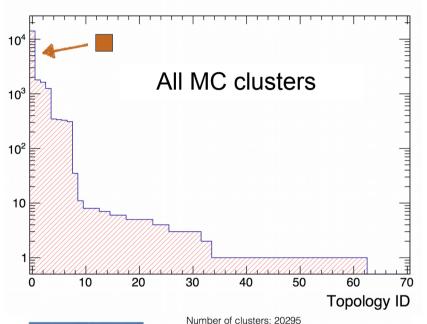


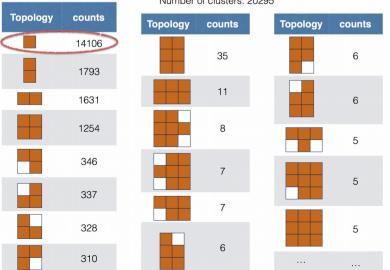
At the end, we want to be able to generate the data in TimeFrame format

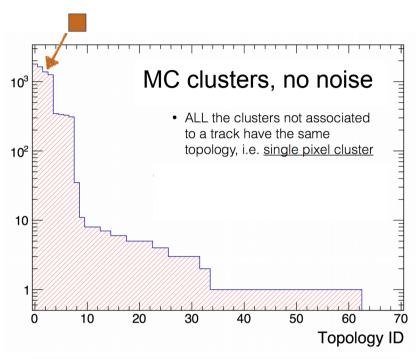


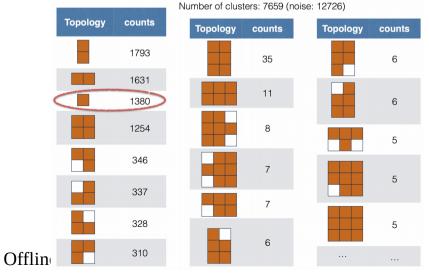
## Porting the cluster-topology code

(Luca Barioglio)



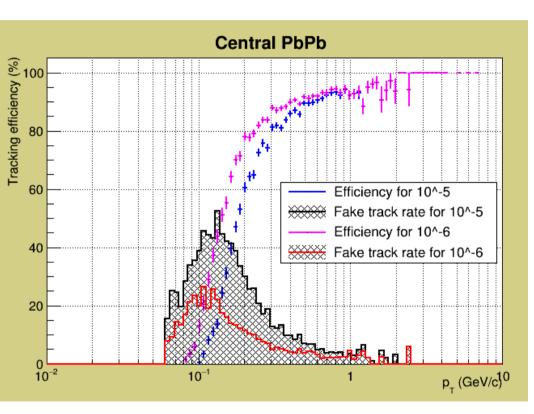


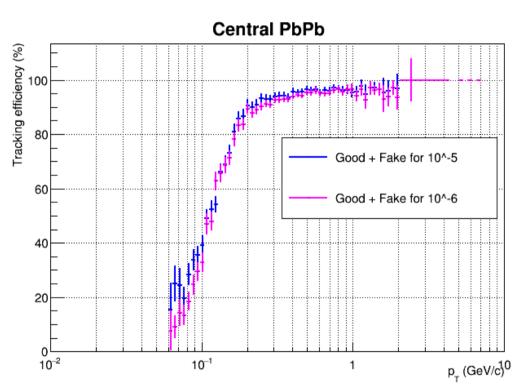




#### Tracking time vs the level of noise (louri)

Number of fake hits: 12.6x10<sup>9</sup>x10<sup>-5</sup>=1.26x10<sup>5</sup> (compare: dN/dy ~2000 for central PbPb)





"Cooked Matrix" tracker:

Noise "hit rate" 10⁻⁻ : real time 23 s/ev (4 threads on 4-core 2.66 GHz CPU)

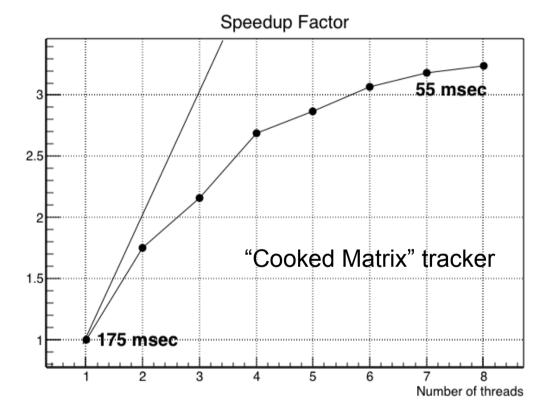
Noise "hit rate" 10-6: real time 1.5 s/ev (4 threads on 4-core 2.66 GHz CPU)

(Compare: the interaction rate is 50 kHz)



## Tracking time vs # of threads (louri)

- 2011 mac, 2 GHz Intel Core i7
  - 4 cores, 8 threads
- 4000 pions in |η|<0.9</li>
  - 0.2<p<sub>⊤</sub><2.0 GeV/c, flat</li>
  - No noise
  - Constant 0.5 T mag. field



#### C++11 multi-threading works!

Linux/gcc and macOS/clang

(bottle neck of the moment – cluster sorting)

# ALICE

## Comparison with MC (louri)

#### basic but functional

Average tracking efficiency (7-cluster tracks):

Event 0/10

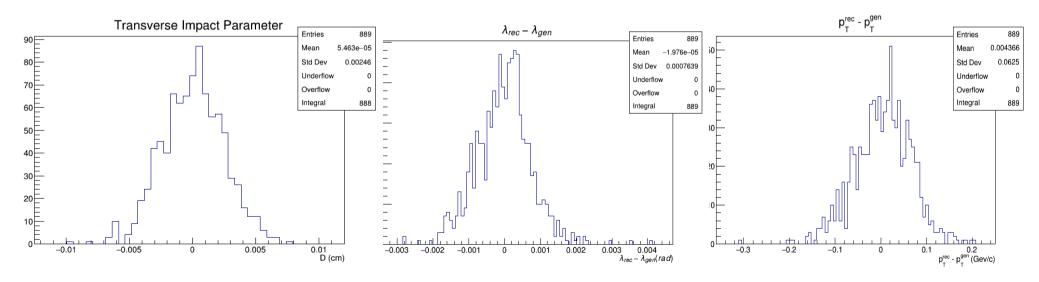
Good found tracks: 2897, efficiency: 0.869187

Event 1/10

Good found tracks: 2888, efficiency: 0.866487

...

"rec – gen" plots (integrated over p<sub>⊤</sub>) :



## **Upgraded ITS in AliEve**



An event with 35 MC and 29+4 reconstructed vertices (ITSU stand-alone, Pythia6 @ 14 TeV)

