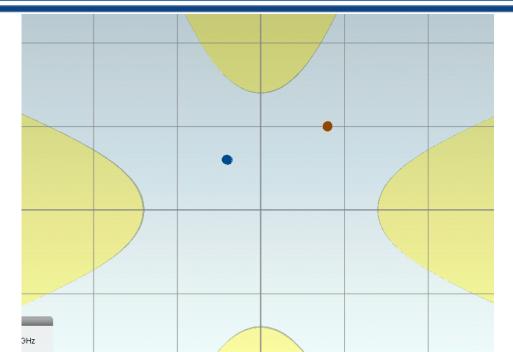
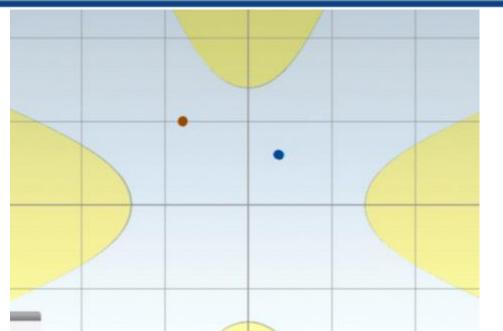


New research strongly indicates the elimination of transverse beam impedance by making beam equipment in the shape of higher order multipoles

Horizontal mirror symmetry gives Z1X=0, Z2B=0 & Z2C=0

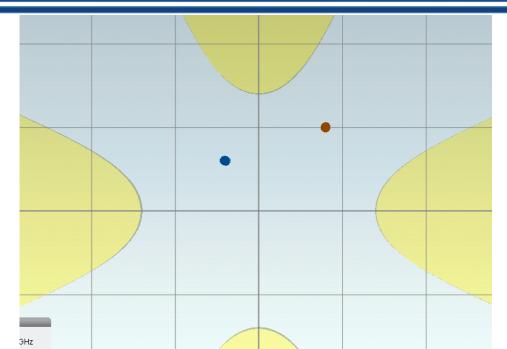


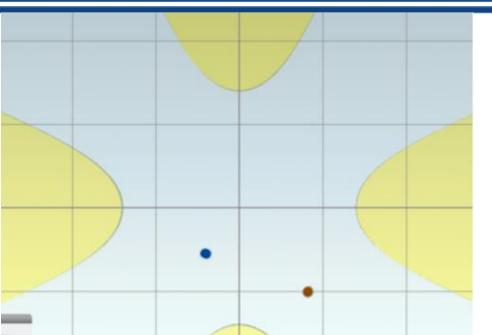


The beam impedance is invariant when the drive and test particles are mirrored in the x-axis: $Z_{||}[xd, xt, yd, yt] = Z_{||}[-xd, -xt, yd, yt]$ 2 Z1X (xd+xt) + 2 Z2B (xd yd+xt yt) + 2 Z2C (xd yt +xt yd) = 0

 $[Z_{||}[xd, xt, yd, yt] = Z0 + Z1X(xd+xt) + Z1Y(yd+yt) + Z2A(xd^{2}+xt^{2}-yd^{2}-yt^{2}) + Z2B(xd yd+xt yt) + Z2C(xd yt + xt yd) + Z2D xd xt + Z2E yd yt]^{2}$

Vertical mirror symmetry gives Z1Y=0, Z2B=0 & Z2C=0

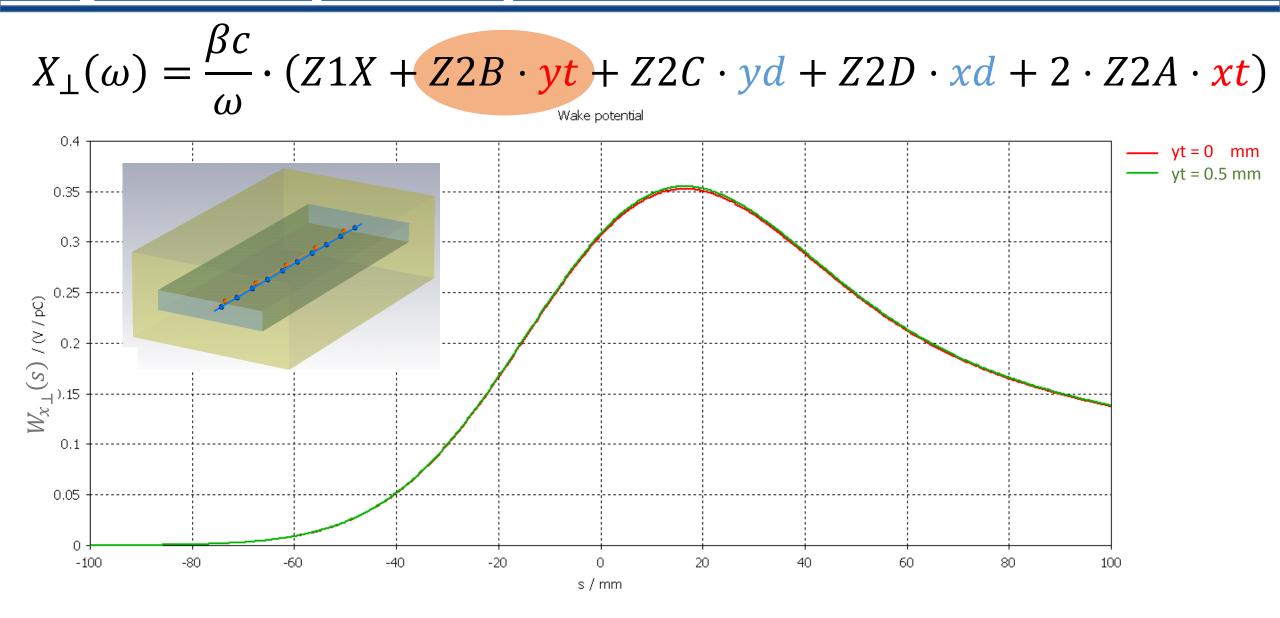




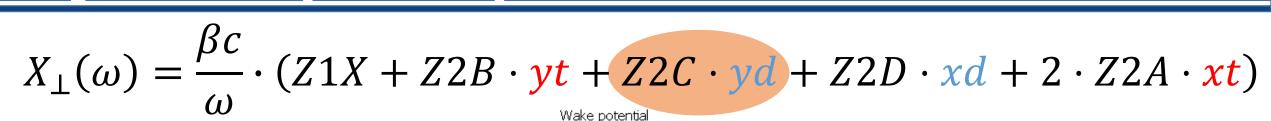
The beam impedance is invariant when the drive and test particles are mirrored in the x-axis: $Z_{||}[xd, xt, yd, yt] = Z_{||}[xd, xt, -yd, -yt]$ 2 Z1Y (yd+yt) + 2 Z2B (xd yd+xt yt) + 2 Z2C (xd yt +xt yd) = 0

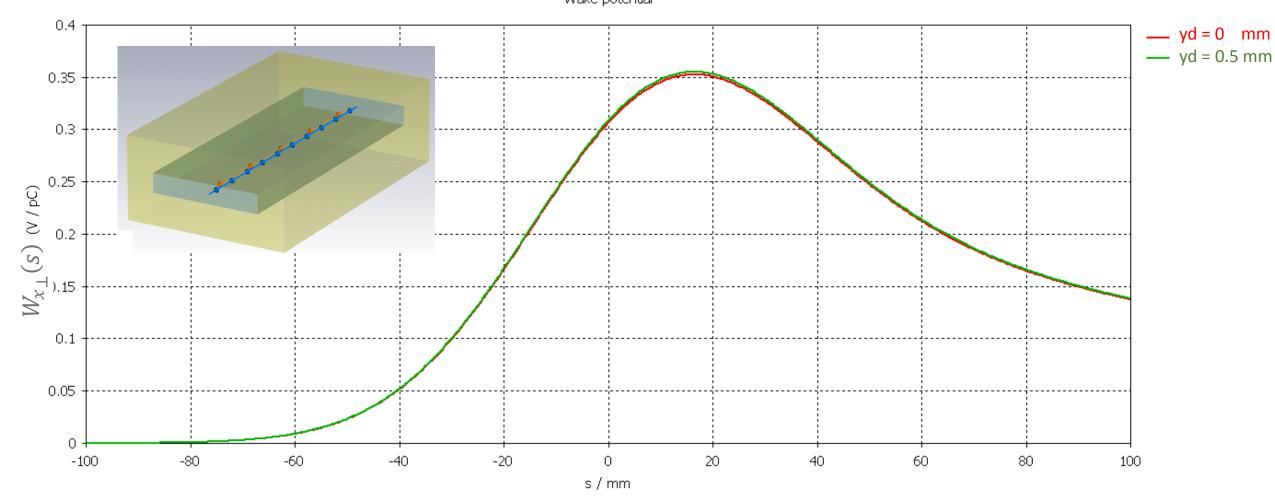
 $[Z_{||}[xd, xt, yd, yt] = Z0 + Z1X(xd+xt) + Z1Y(yd+yt) + Z2A(xd^{2}+xt^{2}-yd^{2}-yt^{2}) + Z2B(xd yd+xt yt) + Z2C(xd yt + xt yd) + Z2D xd xt + Z2E yd yt]^{3}$

Up/down symmetry leads to Z2B=0



Up/down symmetry leads to Z2C=0





90 deg sym. \Rightarrow Z1X=Z1Y=0, Z2A=0, Z2B=0, Z2C=0, Z2D=Z2E

For a 90 degree symmetric structure, the beam impedance is invariant when the drive and test particles are rotated by 90 degrees:

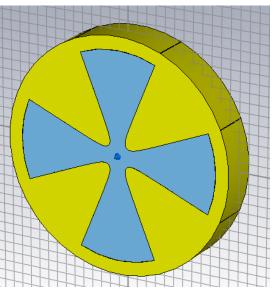
 $Z_{||}[xd, xt, yd, yt] = Z_{||}[xdR, xtR, ydR, ytR]$

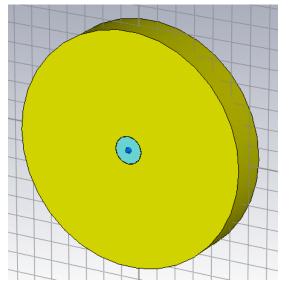
(-Z1X+Z1Y) (xd+xt)+(-Z1X-Z1Y) (yd+yt) -2 Z2A (xd²+xt²-yd²- yt²) -2 Z2B (xd yd+xt yt) - 2 Z2C (xd yt +xt yd) +yd yt (Z2D-Z2E)+xd xt (-Z2D+Z2E) =0

 $Z_{||}[xd, xt, yd, yt] = Z0 + Z1X (xd+xt) + Z1Y (yd+yt) + Z2A (xd^{2}+xt^{2}-yd^{2}-yt^{2}) + Z2B (xd yd+xt yt) + Z2C (xd yt +xt yd) + Z2D xd xt + Z2E yd yt$

 $xdR = xd *Cos[\Theta] - yd*Sin[\Theta]$ $xtR = xt*Cos[\Theta] - yt*Sin[\Theta]$ $ydR = xd*Sin[\Theta] + yd*Cos[\Theta]$ $ytR = xt*Sin[\Theta] + yt*Cos[\Theta]$

Comparison of a 4-pole and a round structure



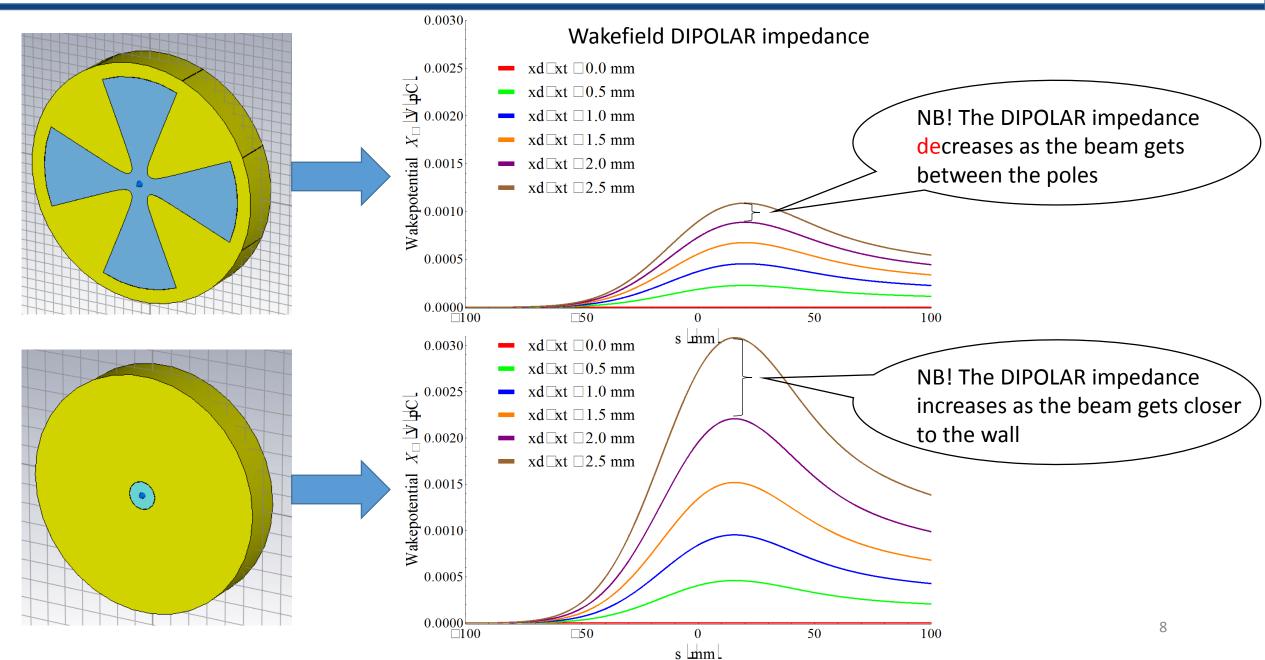


In terms of impedance (up to second order), these two structures are identical in that they have only dipolar impedance. Their only difference is the value of the dipolar impedance.

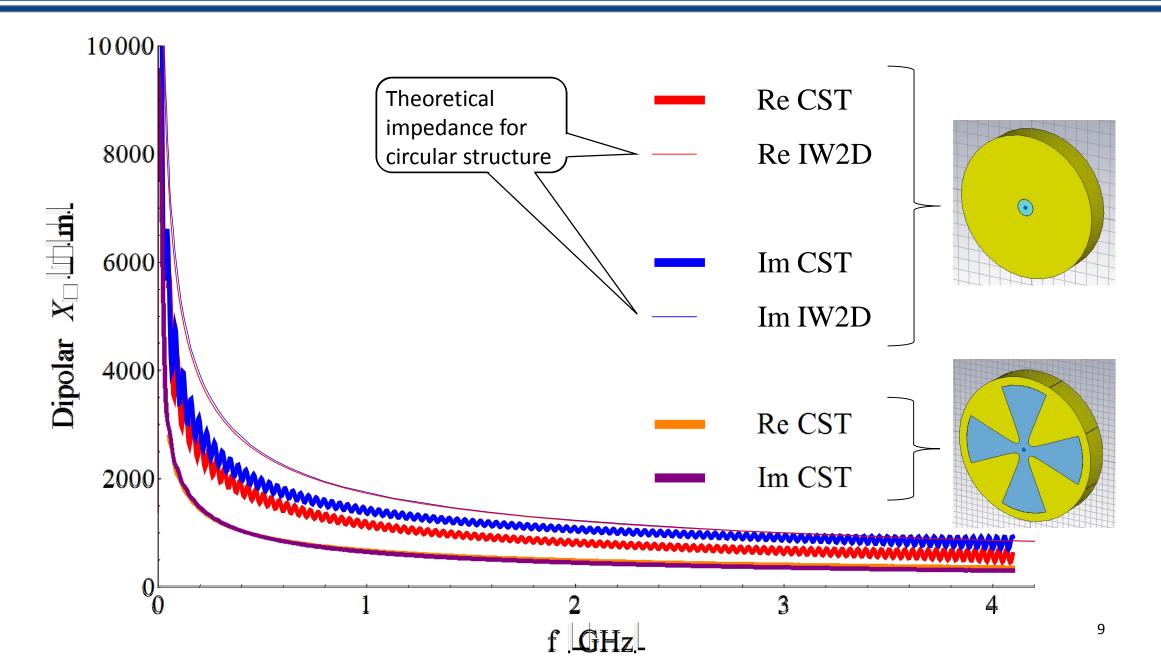
In the 4-pole structure, as the beam moves away from center and goes to the right, it is attracted more and more to the poles. The force on the beam must therefore point to the right. However, when the beam have past the most narrow point between the poles, the force on the beam must be to the left (i.e. attracted to the poles). There must be a point – close to the poles – where the force on the beam is zero and therefore the dipolar impedance is zero at this point. This effect is reflected in the simulation on the next slide.

In general it is easy to see that the forces on the beam will be stronger in the circular structure, leading to a larger dipole impedance. This is reflected in the simulations on the next slide.

Comparison of a 4-pole and a round structure



The 4-pole structure have significantly less impedance



Concluding remarks

- The symmetry analysis show very interesting properties of 90 degree symmetric structures. A counter intuitive property is that these structures have only dipolar impedance
- The 4-pole structure has a significantly lower dipolar impedance than the round structure
- The calculations still needs more sensitivity tests (dependence on number of meshcells, port versus open boundary, comparison with HFSS, etc.)
- Feed-down calculations and even higher multipolar structures still needs to be investigated. Higher multipolar structures might very well have even lower dipolar impedance.

90 deg sym. \Rightarrow The dipolar impedance is the same in all directions

Z_{||}[xdR, xtR, ydR, ytR]=

 $Z0 + yd (Z1Y \cos [\theta] - Z1X \sin [\theta]) + yt (Z1Y \cos [\theta] - Z1X \sin [\theta]) + xd (Z1X \cos [\theta] + Z1Y \sin [\theta]) + xd (Z1X \cos [\theta] + Z1Y \sin [\theta]) + xt (Z1X \cos [\theta] + Z1Y \sin [\theta]) + xd^{2} (Z2A \cos [\theta]^{2} + Z2B \cos [\theta] \sin [\theta] - Z2A \sin [\theta]^{2}) + xt^{2} (Z2A \cos [\theta]^{2} + Z2B \cos [\theta] \sin [\theta] - Z2A \sin [\theta]^{2}) + yt^{2} (-Z2A \cos [\theta]^{2} - Z2B \cos [\theta] \sin [\theta] + Z2A \sin [\theta]^{2}) + yt^{2} (-Z2A \cos [\theta]^{2} - Z2B \cos [\theta] \sin [\theta] + Z2A \sin [\theta]^{2}) + xd yd (Z2B \cos [\theta]^{2} - 4 Z2A \cos [\theta] \sin [\theta] - Z2B \sin [\theta]^{2}) + xt yt (Z2B \cos [\theta]^{2} - 4 Z2A \cos [\theta] \sin [\theta] - Z2B \sin [\theta]^{2}) + xt yd (Z2C \cos [\theta]^{2} - 2ZD \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xt yd (Z2C \cos [\theta]^{2} - Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2C \cos [\theta]^{2} - Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2E \cos [\theta]^{2} - Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2E \cos [\theta]^{2} - Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2E \cos [\theta]^{2} + Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2E \cos [\theta]^{2} + Z2D \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta] - Z2C \sin [\theta]^{2}) + xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \cos [\theta] \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Xd yt (Z2E \cos [\theta]^{2} + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + Z2E \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + ZE \cos [\theta] \sin [\theta] + Z2E \sin [\theta]^{2}) + ZE \cos [\theta] \sin [\theta] + ZE \cos [\theta] \sin [\theta] + ZE \cos [\theta] \sin [\theta] + ZE \cos [\theta] \sin [\theta$

 $Z_{||}[xd, xt, yd, yt] = Z0 + Z1X (xd+xt) + Z1Y (yd+yt) + Z2A (xd^{2}+xt^{2}-yd^{2}-yt^{2}) + Z2B (xd yd+xt yt) + Z2C (xd yt +xt yd) + Z2D xd xt + Z2E yd yt$

 $xdR = xd *Cos[\Theta] - yd*Sin[\Theta] xtR = xt*Cos[\Theta] - yt*Sin[\Theta]$ $ydR = xd *Sin[\Theta] + yd*Cos[\Theta] ytR = xt*Sin[\Theta] + yt*Cos[\Theta]$

90 deg. Symmetry => dipolar imp independent of direction

