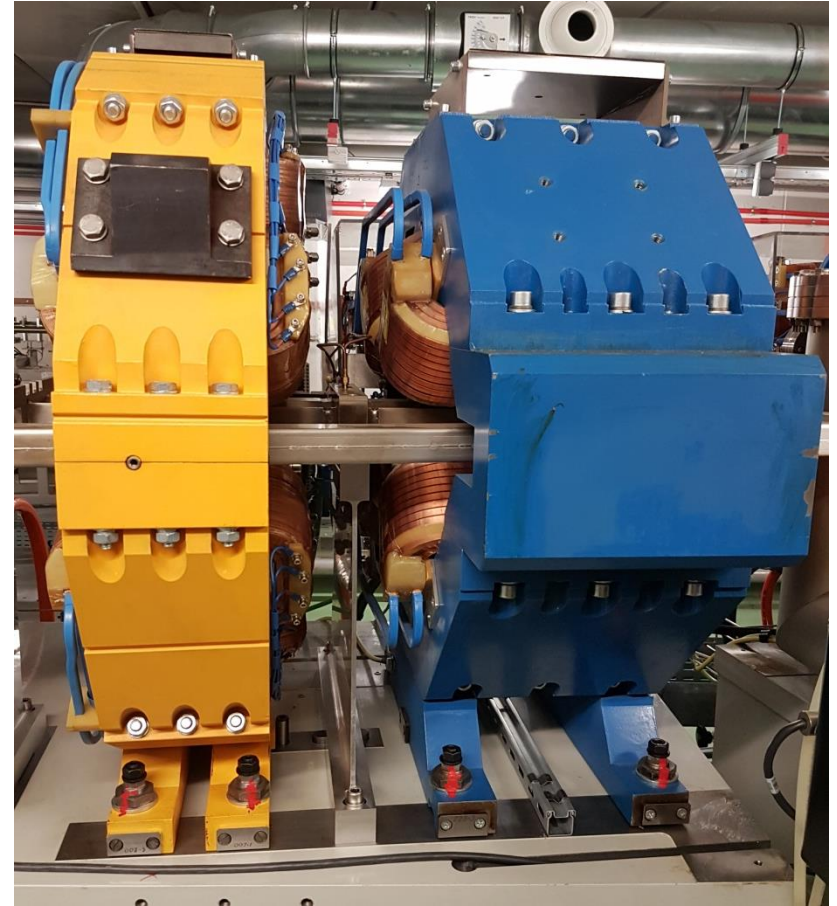


Fast Quadrupole Beam Based Alignment Using AC Corrector Excitations

Z.Martí, G.Benedetti, U.Iriso

TW-DULER

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BBA

FBBA

ALBA set up

Results

It is needed for:

- Minimize **multipole feed down** effect, minimizes the corrector strength needed:
 - **Optic** & coupling errors due to Sextupoles.
 - **Orbit** errors due to Quadrupoles.
- To bring the machine closer to the model in-between BPMs.

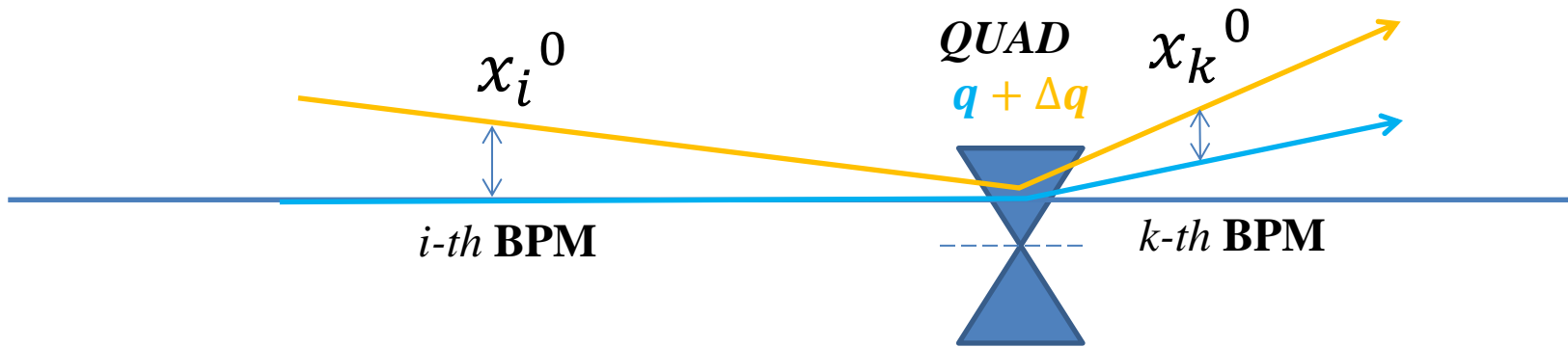
Misalignments come from:

- Real: mechanical
- Apparent: electronic

It can be measured:

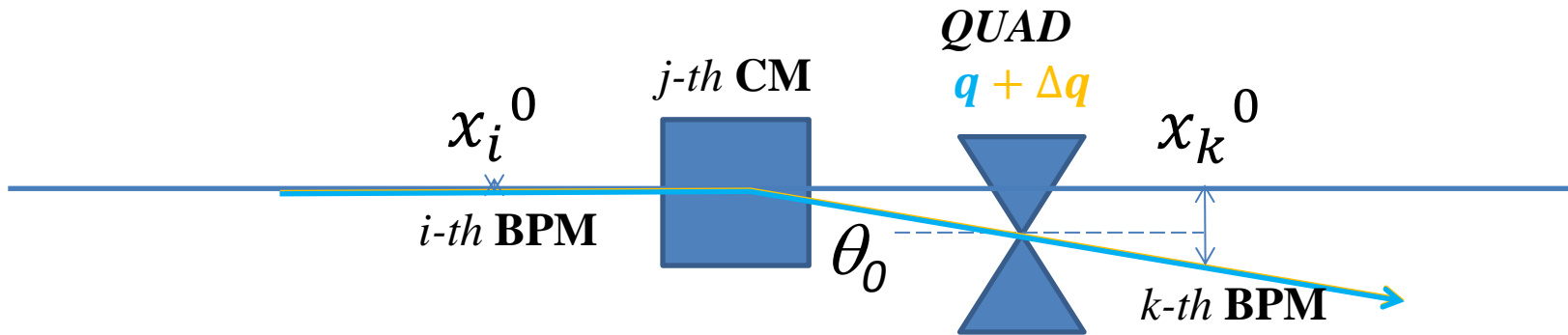
- At the quadrupole: beam2quad
- At the BPM: beam2bpm

Beam2quad:



- **Faster** (only quads varied)
- Linear **Model dependent** (tune and orbit restored after every measurement)
- To ailing we need to translate it to the BPMs.

Beam2bpm:

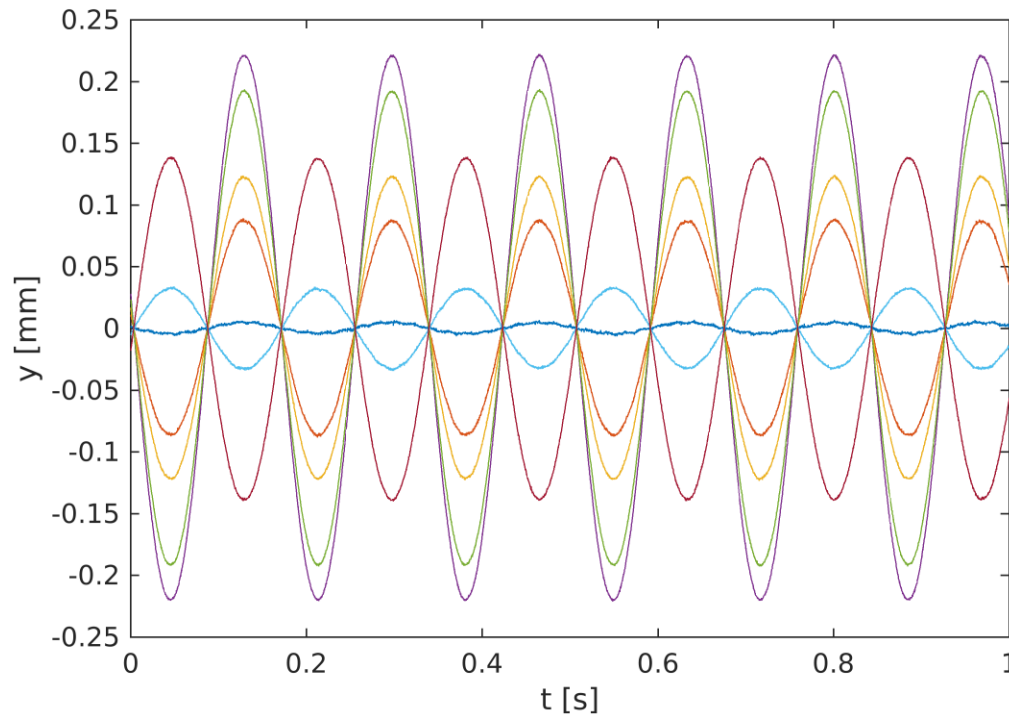


- **Slow** (Both CM and quads are scanned, **$\sim 5h$ at ALBA!**)
- **Model independent**, no need to correct after each measurement.
- There is a systematic error in case of large misalignments depending on the orbit angle.

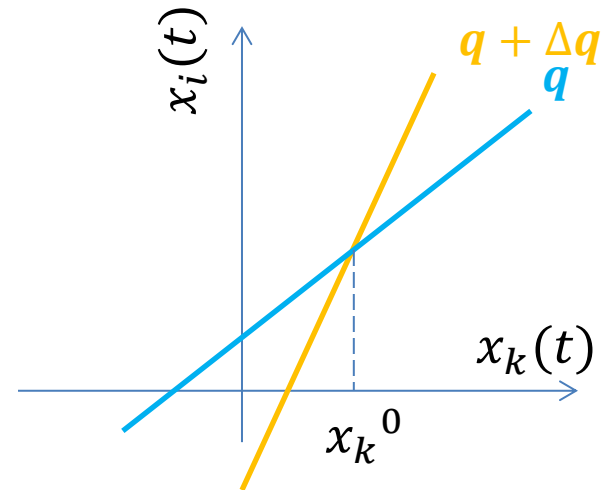
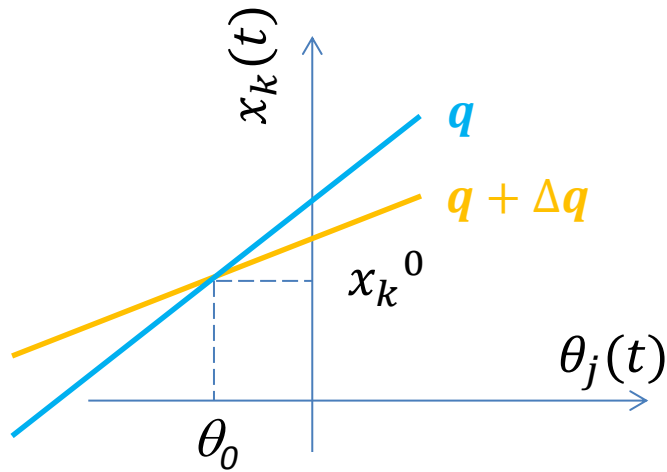
The measurable are the same as for the beam2bpm BBA, with two differences:

- 10kHz **Fast Acquisition Archiver** (thanks DIAMOND)
- **AC** corrector magnets excitation.

While the j -th CM changes the kick $\theta_j(t)$, the BPM readings are linearly related:



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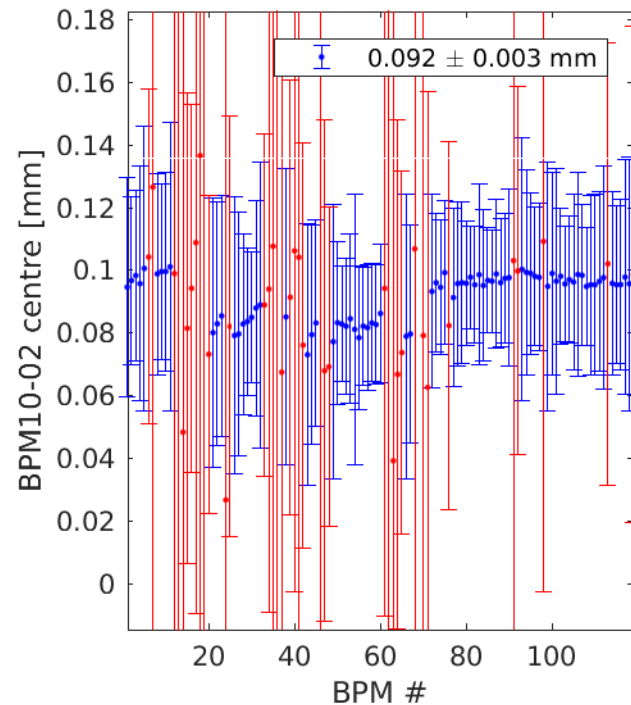
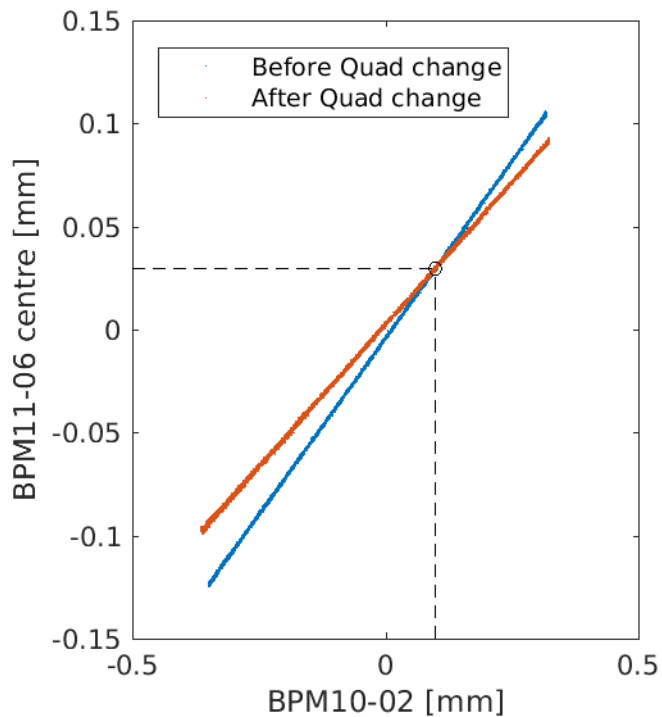
But, unfortunately, in the ALBA case, $\theta_j(t)$ are not stored synchronously nor at 10kHz...

While the j -th CM changes the kick $\theta_j(t)$, the BPM readings are linearly related:

$$\begin{aligned}
 x_i(t) - x_i^0 &= R_{ij}(\theta_j(t) - \theta_0) \\
 x_k(t) - x_k^0 &= R_{kj}(\theta_j(t) - \theta_0) \\
 &\quad \downarrow \\
 x_i(t) - x_i^0 &= \frac{R_{ij}}{R_{kj}}(x_k(t) - x_k^0)
 \end{aligned}$$

Given θ_0 definition, when the **quad changes**, it only changes **R**.

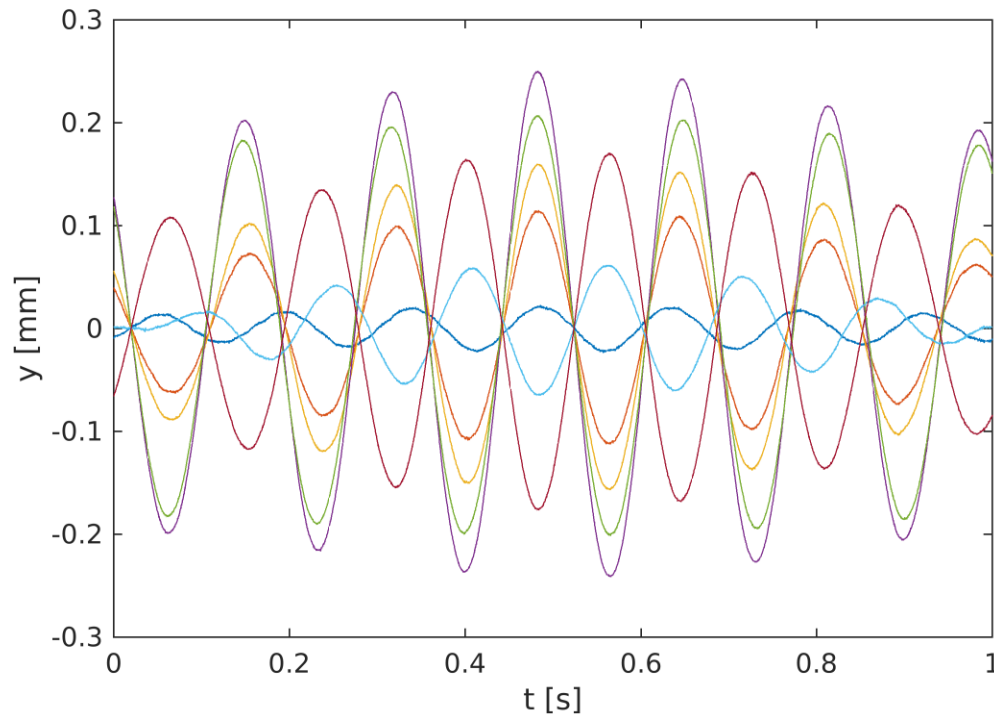
The intersection of each BPM couple relation when the quadrupole is changed is the offset:



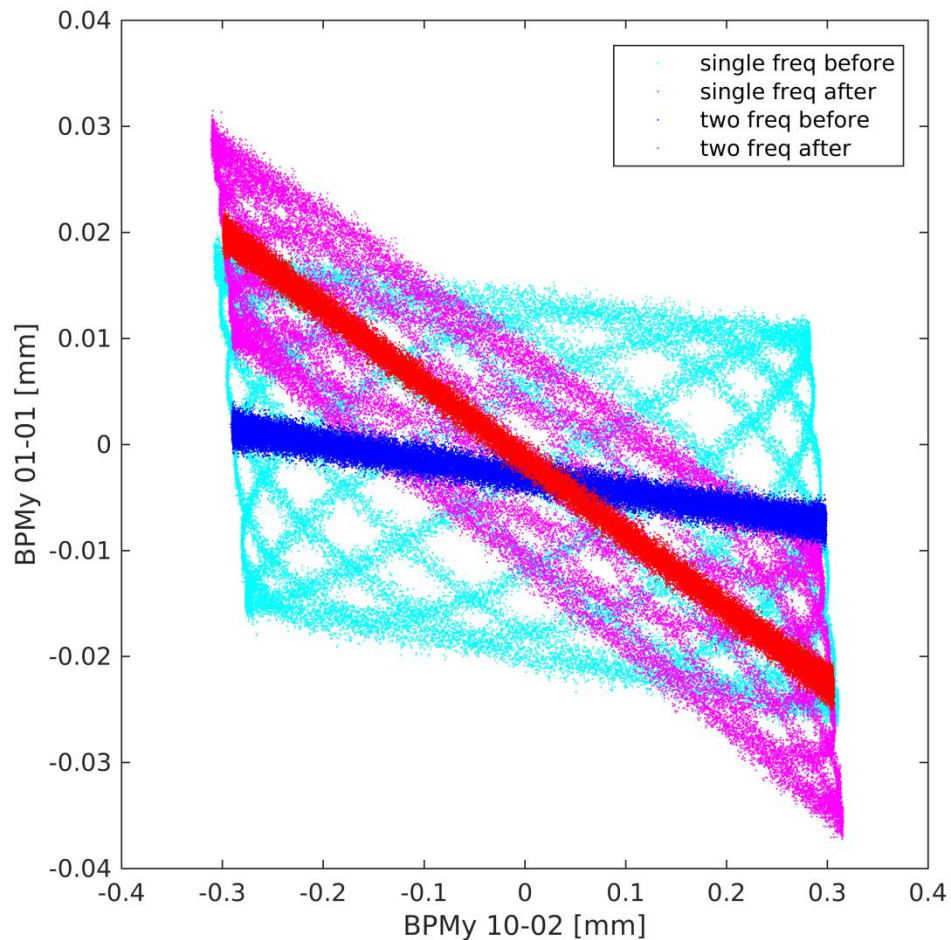
We can make it a **factor 2 faster** if the two planes are measured simultaneously. Different **frequencies** are used in each plane.

In this case the offset is obtained from the **intersection** of the **Fourier components** of each BPM signal.

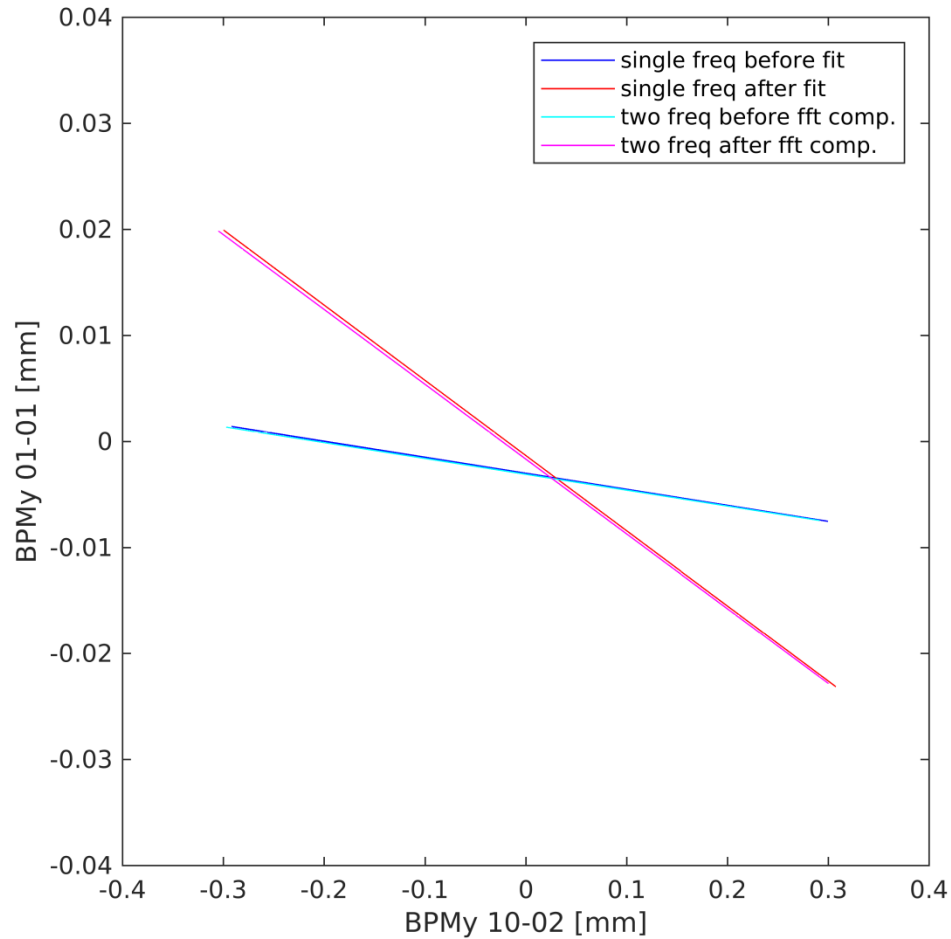
Since the **two plane frequencies** are different, due to **coupling**, the BPMs readings **out of phase** and no longer linearly related:



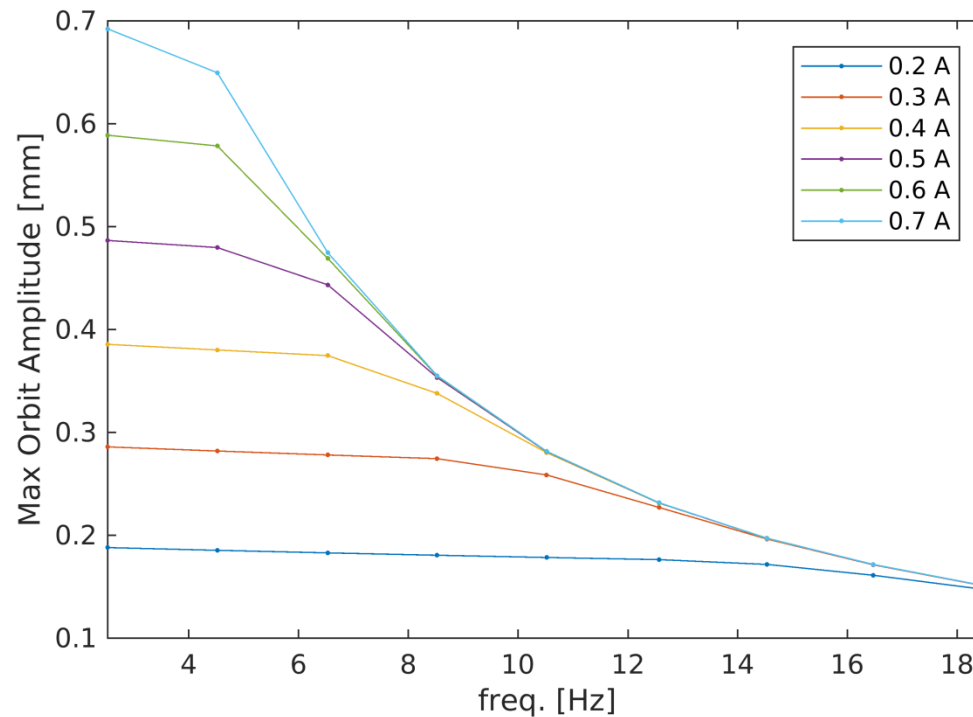
Indeed the two frequencies **spoil the linear correlation**:



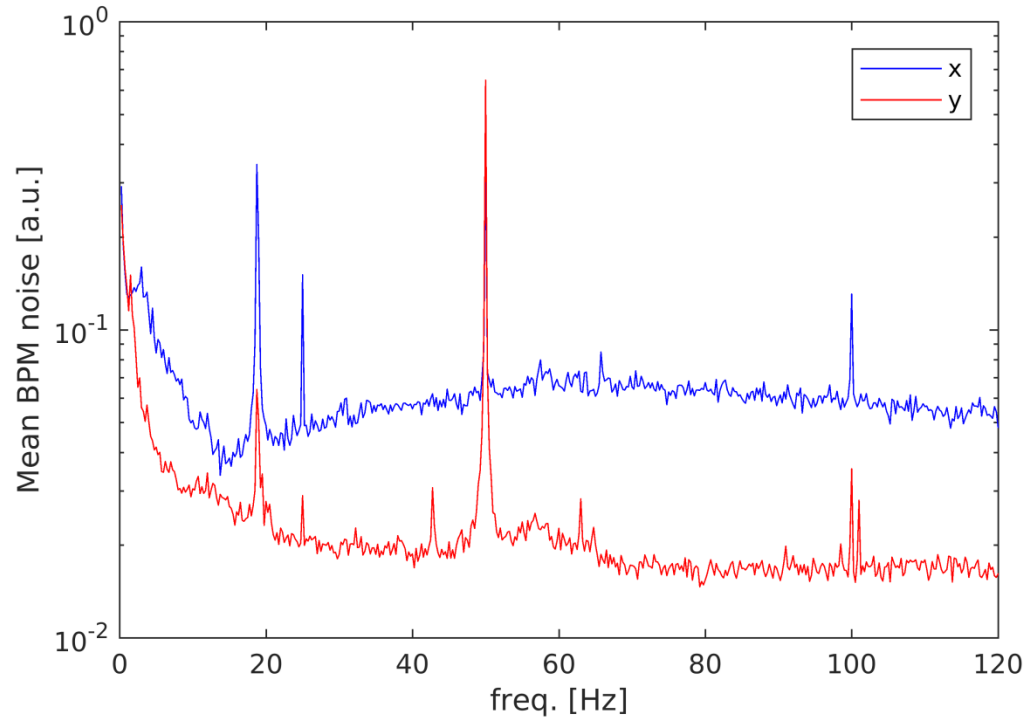
But the linear fit and the Fourier component **agree very well**:



The CM waveforms have a limited effective kick as a function of the frequency:

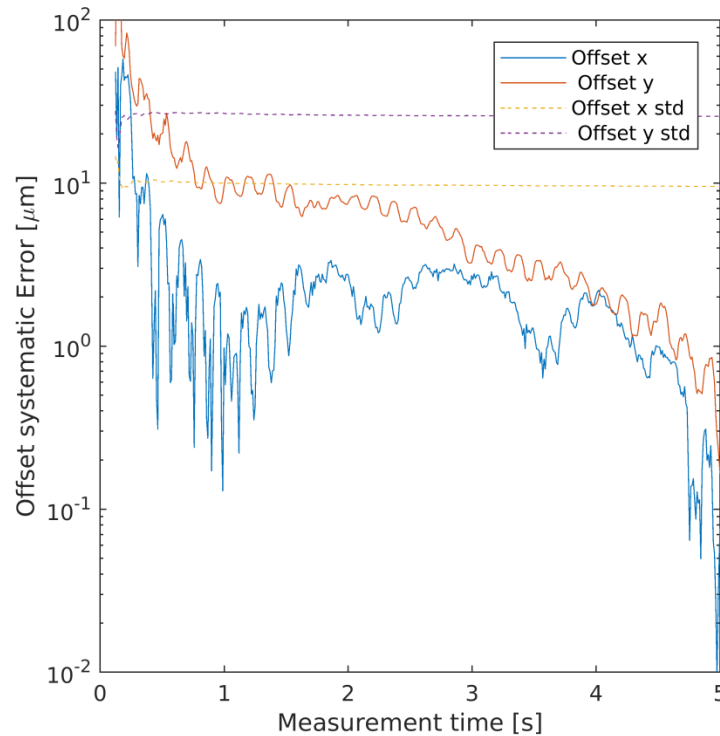


But the BPM noise gets better the higher the frequency, in the 0Hz-18Hz range:

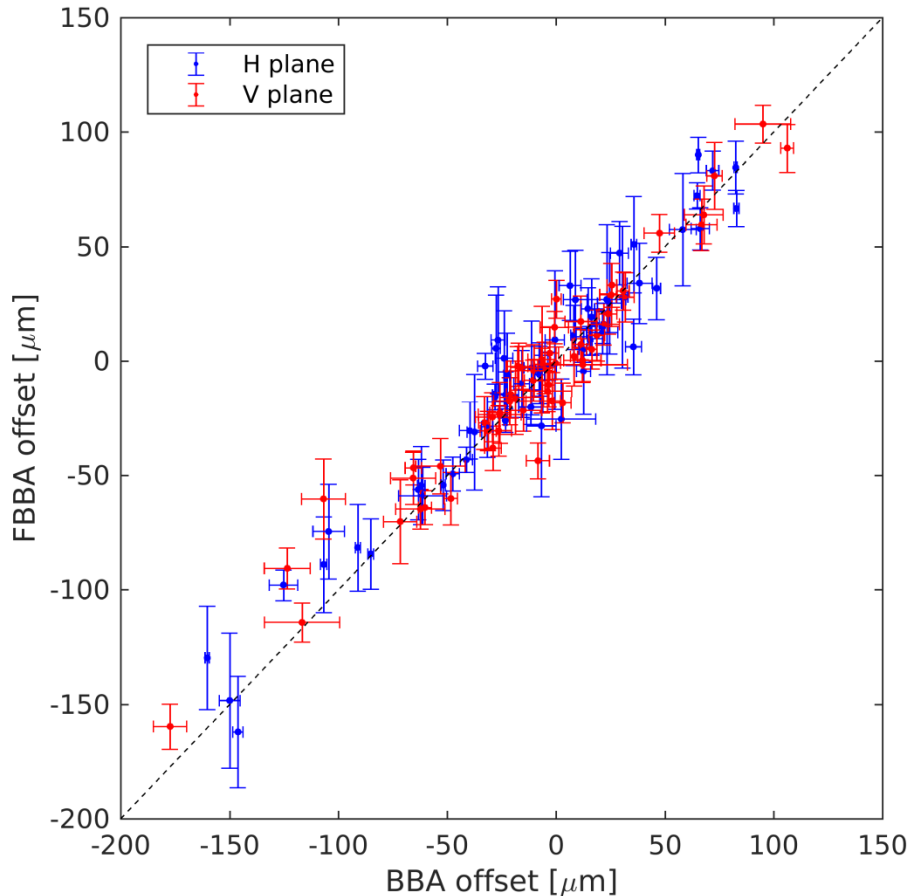


We decided to use 6Hz and 7Hz for the vertical and horizontal plane respectively.

The acquisition time per quad has been optimized:



1.5 seconds are enough to bring the systematic error well below the random error.



- The presented FBBA is **~30 times faster** (10 min vs 5h) than the standard BBA.
- The level of accuracy is similar.