



Power-law Viscoelastic Rheology Controls the Occurrence of Aftershocks

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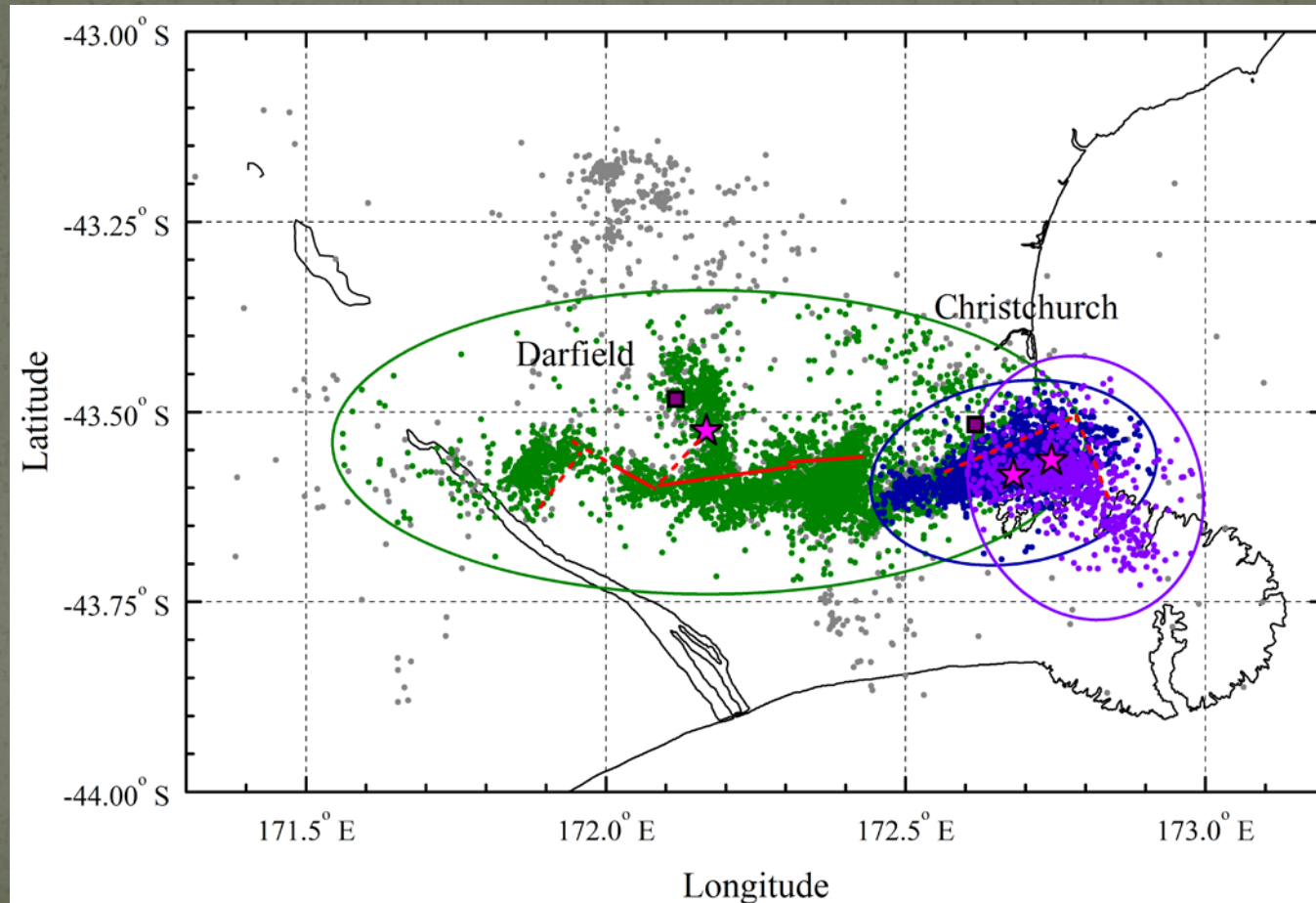
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Aftershocks

- **Aftershocks** are ubiquitous in nature:
- They occur in various physical systems:
 - after large **earthquakes**;
 - in **solar flares**;
 - in **fracture experiments** on porous materials;
 - in **acoustic emissions**;
 - after **stock market** crashes;
 - in the volatility of **stock prices returns**;
 - etc.

2010 Darfield Earthquake, NZ

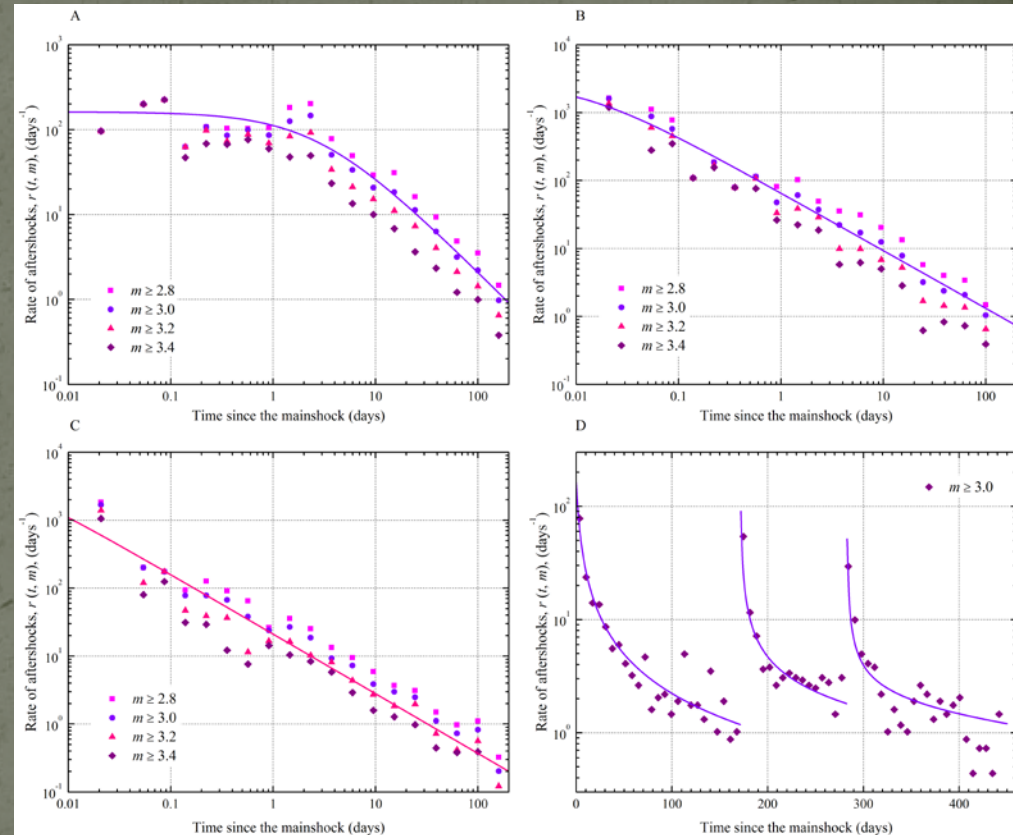
- Mw 7.1 mainshock and its aftershocks (Shcherbakov et al., 2012):



2010 Darfield Earthquake, NZ

- The **decay rate**
(Shcherbakov et al., 2012):
- The **Omori-Utsu law**
(Omori, 1894; Utsu, 1961, Utsu et al, 1995):

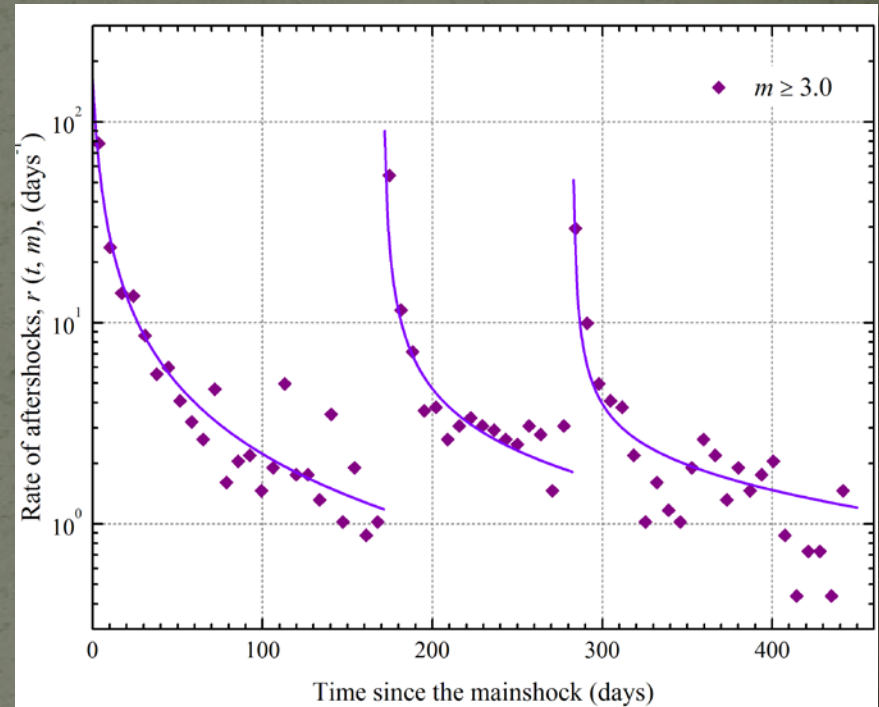
$$r(t) = \frac{K}{(t+c)^p} = \frac{1}{\tau(1+t/c)^p}$$



2010 Darfield Earthquake, NZ

- The **decay rate** (Shcherbakov et al., 2012):
- It was modelled using a **compound rate**:

$$t_2 = 171.3, \quad t_3 = 282.4 \text{ days}$$

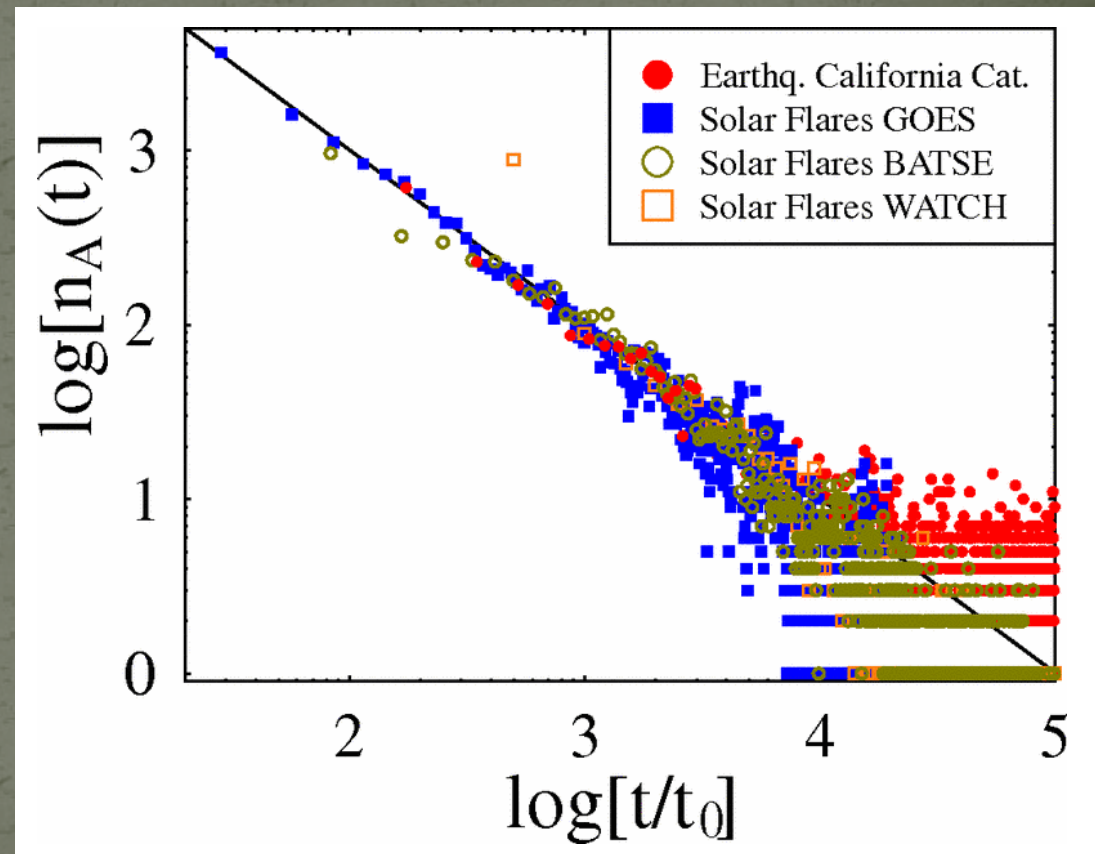


$$r(\geq m_c, t) = \frac{1}{\tau_1 (1 + t / c_1)^{p_1}} + \frac{H(t - t_2)}{\tau_2 [1 + (t - t_2) / c_2]^{p_2}} + \frac{H(t - t_3)}{\tau_3 [1 + (t - t_3) / c_3]^{p_3}}$$

Solar Flares

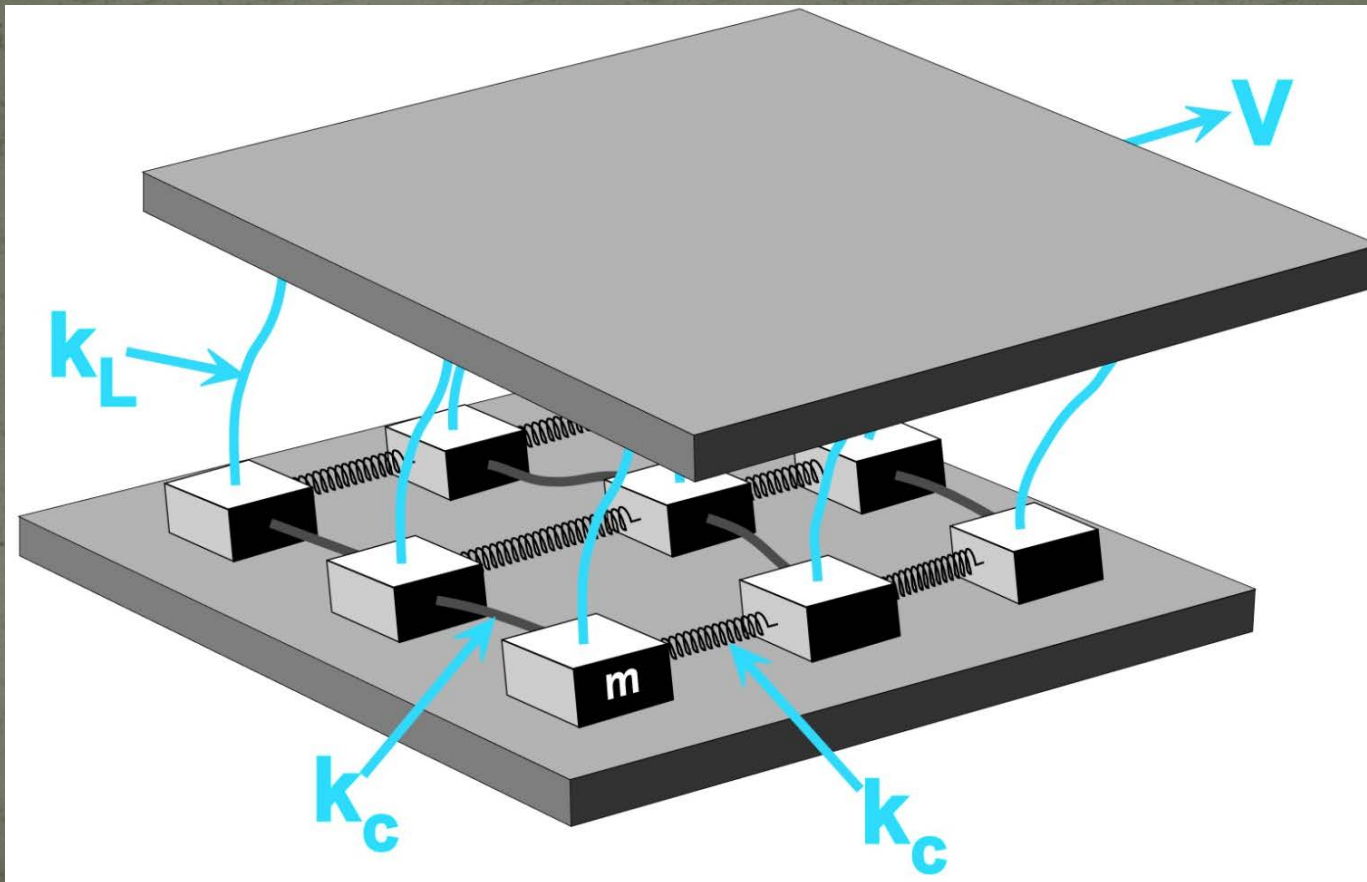
- The decay of **after events** after large **solar flare events** (de Arcangelis et al., PRL, 2006):
- The **decay rate** can be approximated as

$$n_A(t) \sim \frac{1}{t}$$



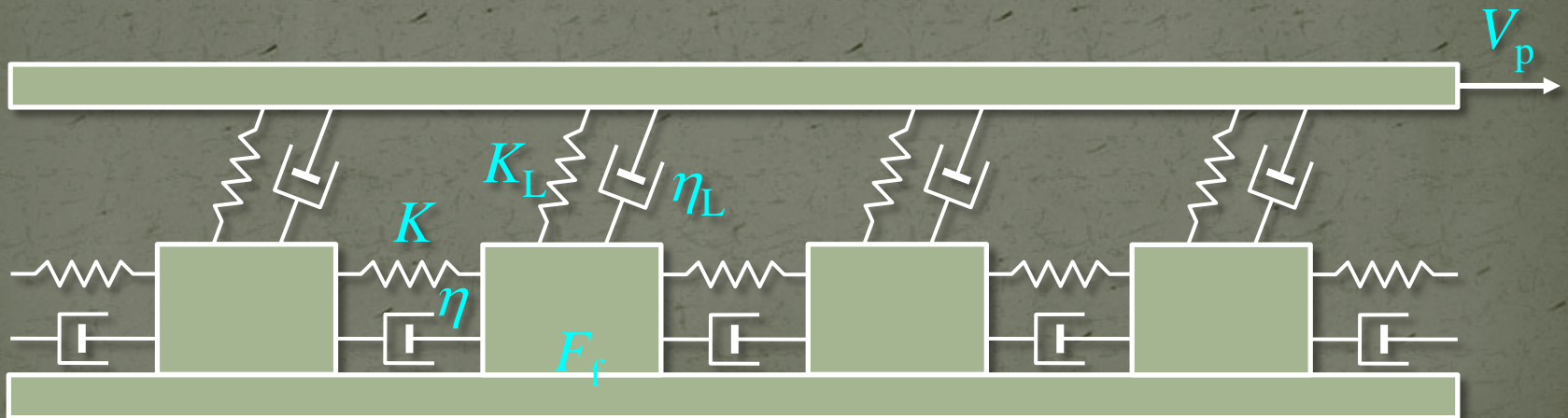
Spring-Block Model

- 2D model of slider-blocks (Burridge and Knopoff, 1967):



Nonlinear Viscoelastic Approach

- The **slider-blocks** are interconnected by **nonlinear Kelvin-Voigt viscoelastic elements**.
- The **blocks** are also connected to the **top plate**, which is driven at a **constant velocity** V_p :



(Zhang and Shcherbakov, 2016)

Nonlinear Viscoelastic Slider-Blocks

- Equations of motion for the 2D system of slider-blocks:

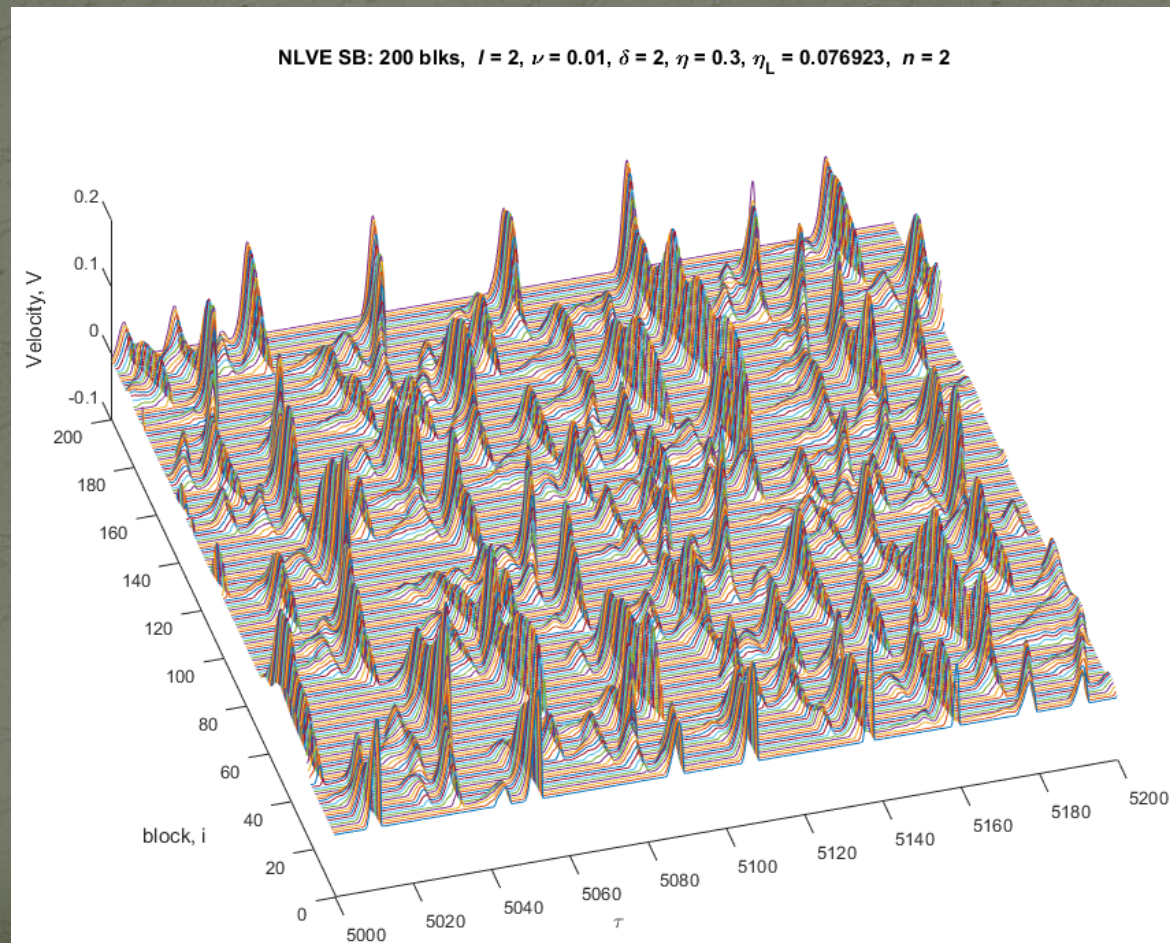
$$m\ddot{x}_{i,j} = -K \sum_{\langle i',j' \rangle} (x_{i,j} - x_{i',j'}) - K_L (x_{i,j} - V_p t) - \eta \sum_{\langle i',j' \rangle} |\dot{x}_{i,j} - \dot{x}_{i',j'}|^{1/n} - \eta_L |\dot{x}_{i,j} - V_p|^{1/n} - F_f \text{sign}(\dot{x}_{i,j})$$

- where K and K_L are elastic constants;
- η and η_L are viscous parameters;
- n – is a power-law exponent;
- F_f – frictional force.

$$\dot{\epsilon} = A\sigma^n \exp\left[-\frac{Q}{RT}\right]$$

Nonlinear Viscoelastic Slider-Blocks

- Model earthquakes:



Mapping into a Cellular Automaton

- Mapping into a **cellular automaton** (Zhang and Shcherbakov, 2016):
 - Consider the **model** on a **2D square lattice** of size $N \times N$;
 - Each **site** is assigned a **continuous stress variable** F_{ij} ;
 - Model is **driven uniformly** with **slow loading**;
 - When the **stress** on a site reaches a **critical value** $F_{ij} \geq 1$, the site becomes **unstable** and begins **transferring stress** to **neighbours**:

$$F_{i,j}(0) = 0,$$

$$\Delta F_{i\pm 1, j\pm 1}(t) = \alpha F_{i,j}^{(b)} + \frac{\beta - \alpha}{\left[\frac{t}{q_0} + \left(F_{i,j}^{(b)} \right)^{1-n} \right]^{\frac{1}{n-1}}}$$

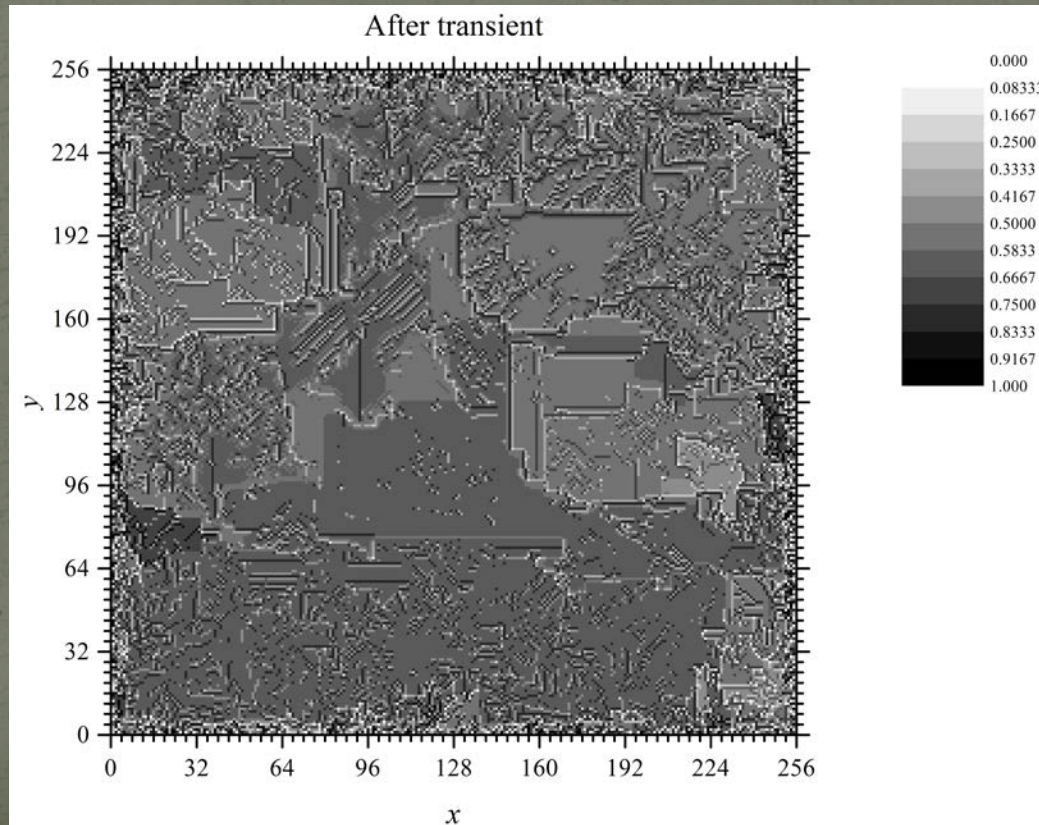
$$\alpha = \frac{K}{K_L + 4K}$$

$$\beta = \frac{\eta}{\eta_L + 4\eta}$$

$$q_0 = \frac{1}{n-1} \frac{(\eta_L + 4\eta)^n}{K_L + 4K}$$

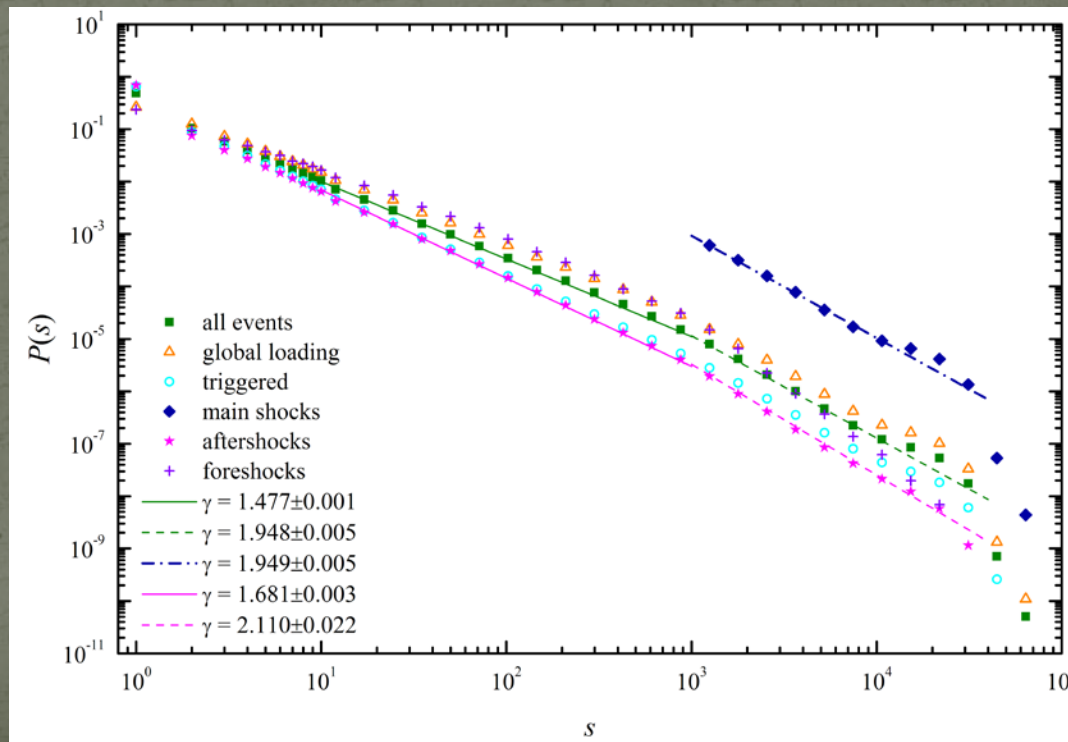
Mapping into a Cellular Automaton

- Snapshot of the **model state** realized and as a **cellular automaton** (Zhang and Shcherbakov, 2016):



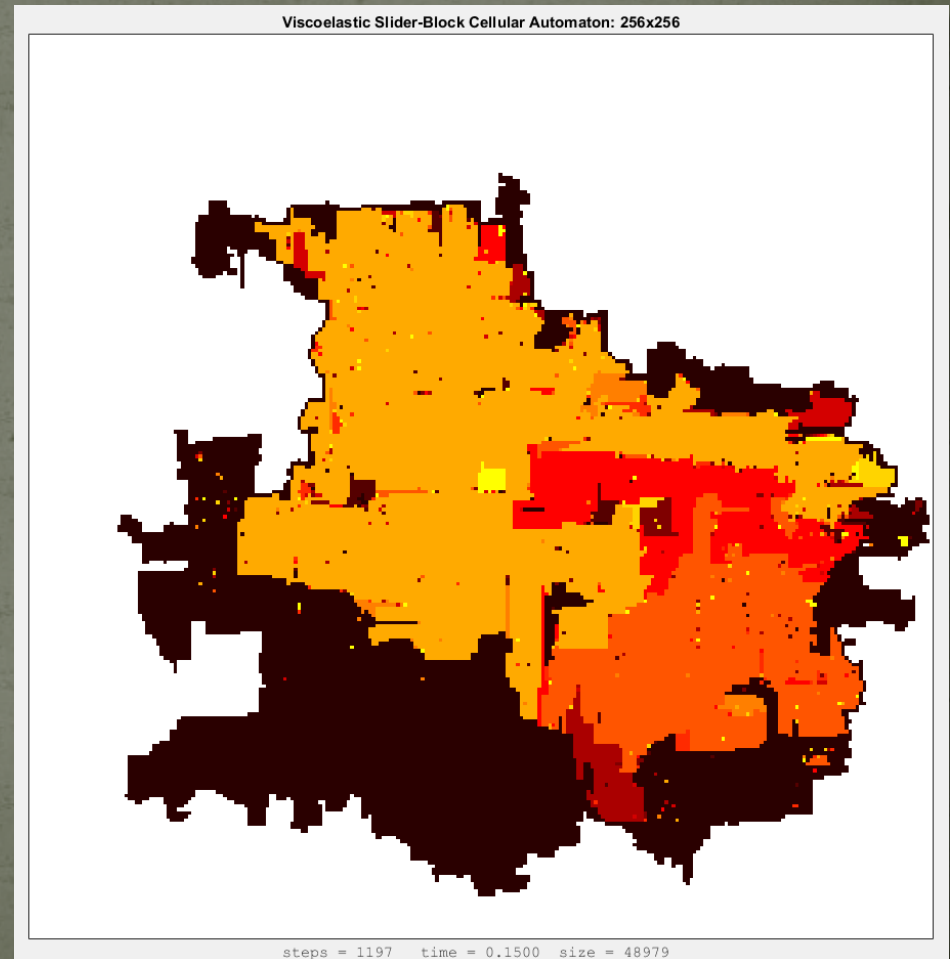
Mapping into a Cellular Automaton

- Frequency size statistics for the cellular automaton on a 256×256 lattice with $\alpha = 0.24$, $\beta = 0.23$, $q_0 = 10.0$, and $1/n = 0.1$ parameters (Zhang and Shcherbakov, 2016):



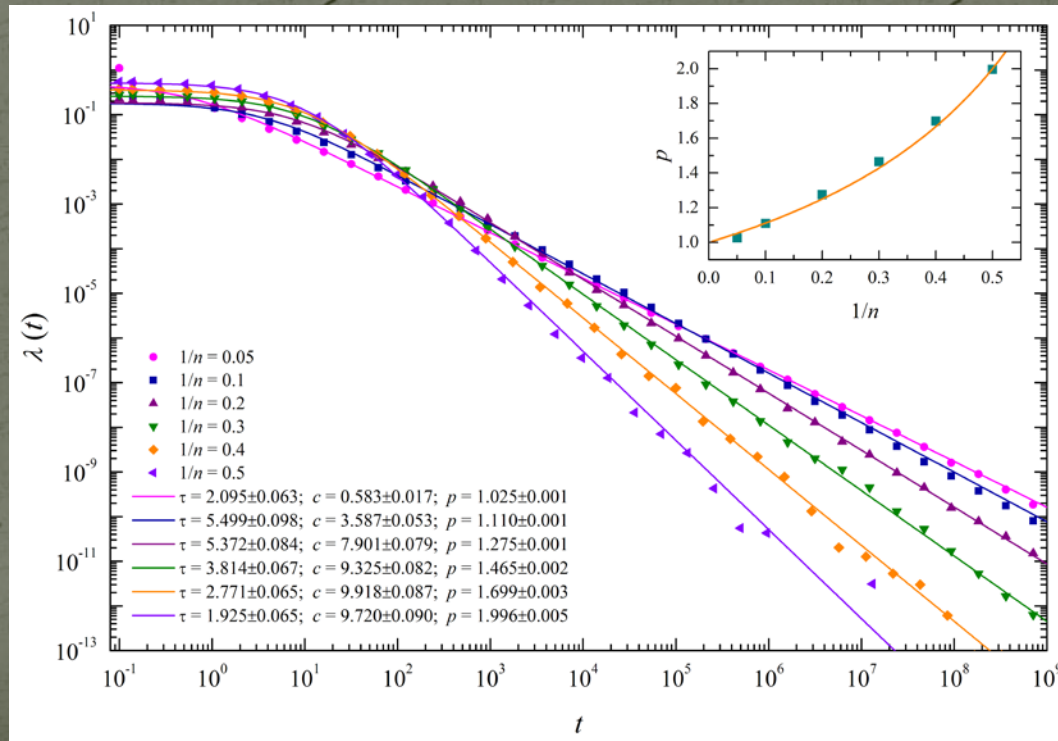
Mapping into a Cellular Automaton

- A large **avalanche** and its **aftershocks**.
- The **model** on a 256×256 lattice with $\alpha = 0.24$, $\beta = 0.23$, $q_0 = 10.0$, and $1/n = 0.1$.



Mapping into a Cellular Automaton

- Aftershock decay rates for the model on a 256×256 lattice with $\alpha = 0.24$, $\beta = 0.23$, $q_0 = 10.0$, and varying $1/n$ parameters (Zhang and Shcherbakov, 2016):



Nonlinear Viscoelastic Approach

- Relation between the power-law exponent n and the p parameter of the modified Omori law (Zhang and Shcherbakov, 2016):

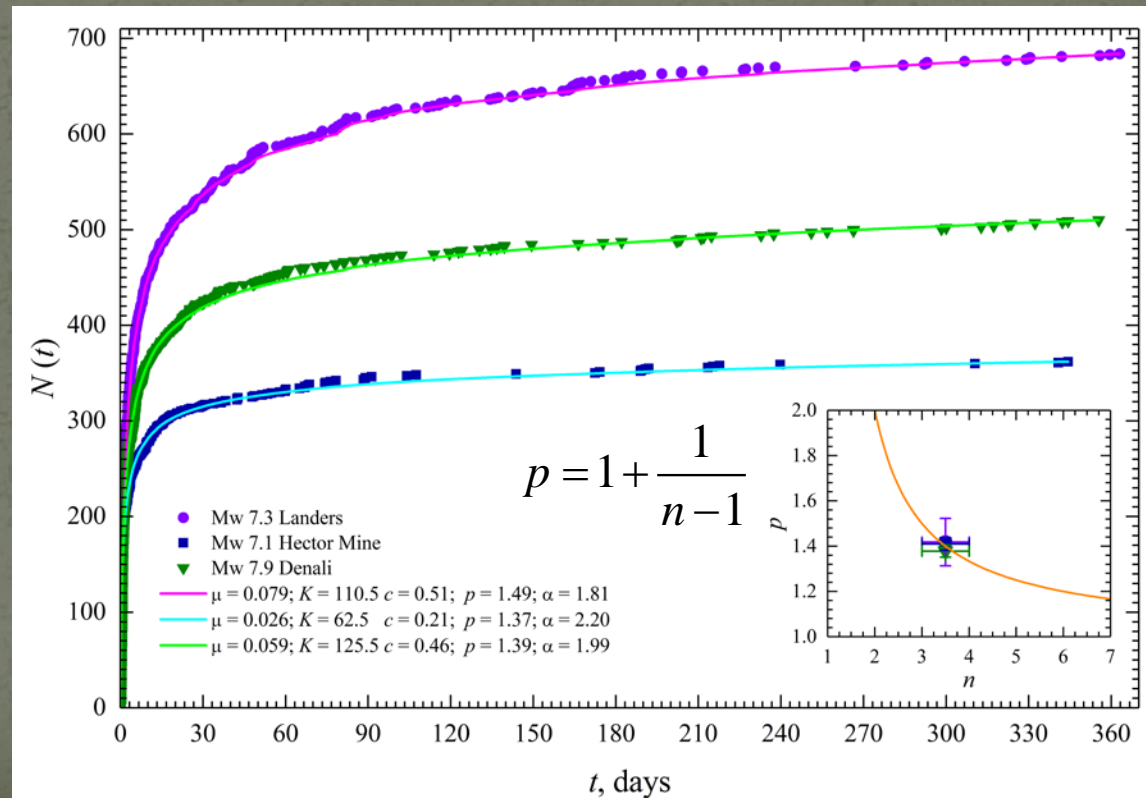
$$p = 1 + \frac{1}{n-1}$$

- Application to the 1992 Landers (California), 1999 Hector Mine (California), 2002 Denali (Alaska) earthquakes.
- The power-law exponent $n = 3.5$ was estimated from the postseismic surface relaxation (Freed, Burgmann, 2004).

$$\dot{\varepsilon} = A\sigma^n \exp\left[-\frac{Q}{RT}\right]$$

Nonlinear Viscoelastic Approach

- Cumulative number of **aftershocks** after several prominent **main shocks** (Zhang and Shcherbakov, 2016):



Conclusions

- We have proposed a **mechanical model** incorporating **power-law rheology** to understand the **mechanisms** of **triggering** and **time delay** in the occurrence of **aftershocks**.
- The derived **mechanism** of **stress relaxation** reproduces the **rate** of aftershocks described by the **Omori-Utsu law**.
- We have showed that the **parameter** p of the **Omori-Utsu law** is related to the **power-law exponent** n :

$$p = 1 + \frac{1}{n-1}$$