# Unified Halo-Independent Formalism for Direct Detection Experiments

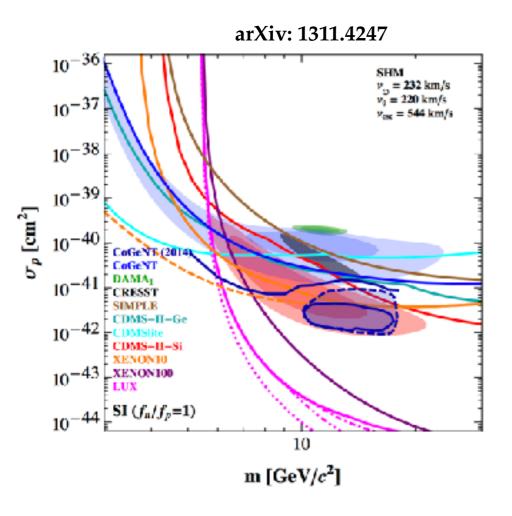




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Based on JCAP12(2017)039, in collaboration with G. Gelmini, J.H. Huh

### Direct Detection Circa 2013



Various dark matter 'hints' juxtaposed against strong upper limits

Viability of a given signal dependent upon various assumptions

$$\frac{dR}{dE_{\rm R}} = \underbrace{\rho_{\chi} C_T}_{m_{\chi} m_T} \int_{v \ge v_{\rm min}(E_{\rm R})} d^3v f(\vec{v}, t) v \underbrace{\frac{d\sigma_T}{dE_{\rm R}}(E_{\rm R}, \vec{v})}_{}$$

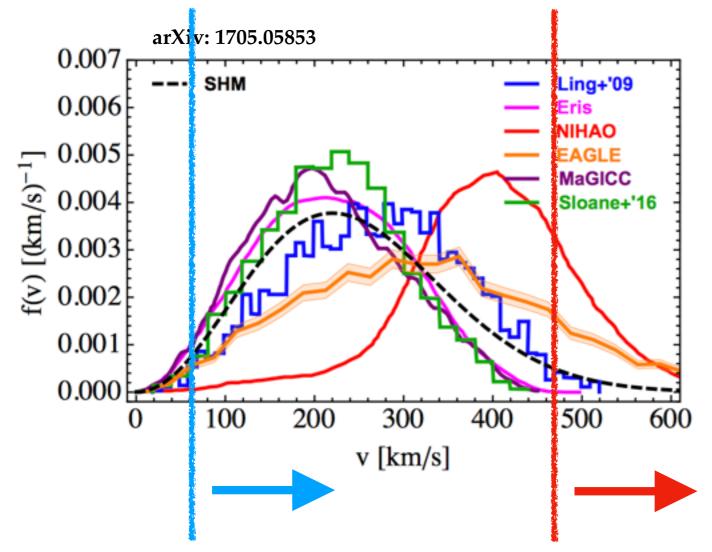
#### <u>Astrophysics</u>

- Local dark matter density
- Dark matter velocity distribution

#### Particle Physics

- SI, SD, Magnetic (Electric) Dipole, etc.
- Proton/neutron couplings
- Scattering kinematics

## Astrophysical Uncertainties



Much of what we know comes from simulations

Most problematic when experiments probe the tail of the distribution

E.g. light WIMPs, inelastic scattering, etc

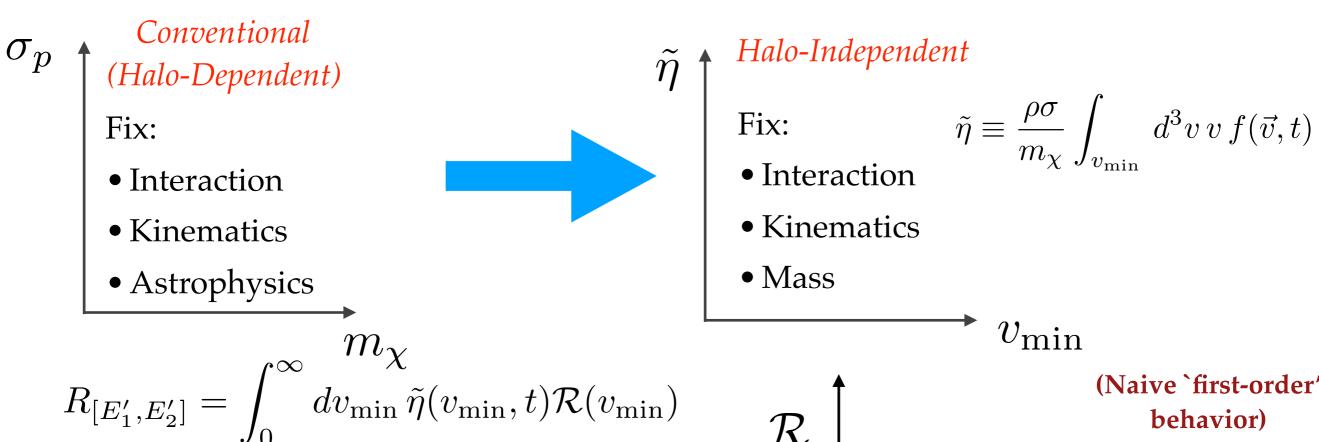
$$\frac{dR}{dE_{\rm R}} = \frac{\rho_{\chi} C_T}{m_{\chi} m_T} \int_{v > v_{\rm min}(E_{\rm R})} d^3 v f(\vec{v}, t) v \frac{d\sigma_T}{dE_{\rm R}} (E_{\rm R}, \vec{v})$$

Experiments sensitive to v > v\_min(Target, DM mass)

Considering different halo functions (i.e. f(v)) can alter the sensitivity of an experiment by orders of magnitude...

## Halo-Independent Analyses

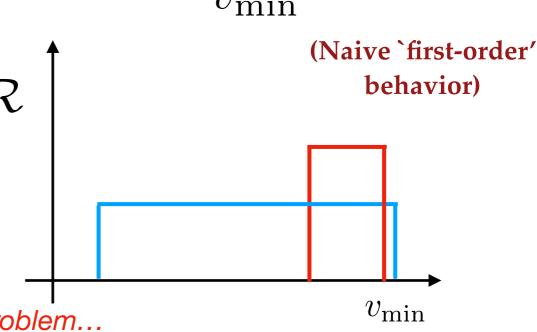
Can we analyze direct detection data without making any assumptions on the underlying astrophysical distribution?



Early Issues related to putative signals:

- Required `ideal experiments'
- Statistical interpretations quite ambiguous (at best)
- Required unbinned measurements of data and background
- Could only be applied to time-averaged rate

Problems because this is effectively an infinite dimensional problem...



### New Halo-Independent Formalism

(Derived from Convex Hulls)

#### Goal:

Develop a new halo-independent formalism that can be applied to any experiment/dataset with a concrete and meaningful statistical interpretation

JCAP12(2017)039 Gelmini, Huh, SJW

(Frequentist method based on use of likelihood ratio)

$$\mathcal{L}(R_1,R_2,\cdots)$$

#### Road Map:

- 1. Prove all likelihoods are necessarily strictly convex functions of the predicted rate
  - Likelihood maximized by  $\ \hat{ec{R}}=(\hat{R}_1,\hat{R}_2,\cdots,\hat{R}_{\mathcal{N}})$
- 2. Use theorems from convex geometry to argue that the set of rates that maximize the likelihood can always be obtained from very simple halo functions

• Either 
$$f_G(\vec{u}) = \sum_{i=1}^{\mathcal{N}} f_i \, \delta^3(\vec{u} - \vec{u}_i)$$
 or  $F(v) = \sum_i^{\mathcal{N}} F_i \, \delta(v - v_i)$ 

- 3. Use point (2) to reduce the infinite dimensionality problem
  - Construct halo-independent confidence bands

## Aside into Convex Geometry

#### **Convex Set**

Let A be a convex set in a D-dimensional vector space.

For any collection of  $\vec{x}_i$  vectors in  $\mathcal{A}$ , and semi-positive definite coefficients  $\lambda_i$  w/  $\sum_i \lambda_i = 1$ 

$$\sum_{i} \lambda_{i} \ \vec{x}_{i} \in \mathcal{A}$$

$$A$$

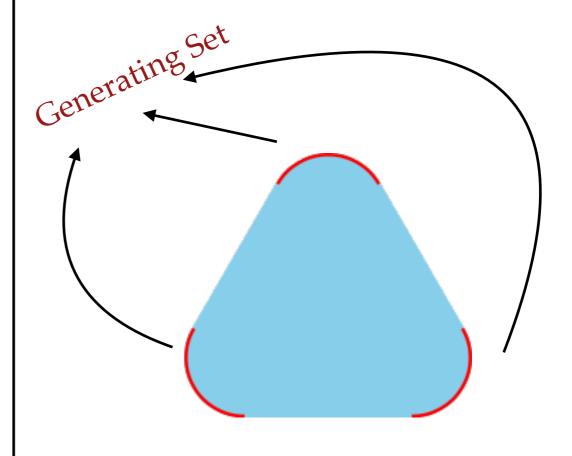
$$X$$

$$Convex Set$$

$$Not a Convex Set$$

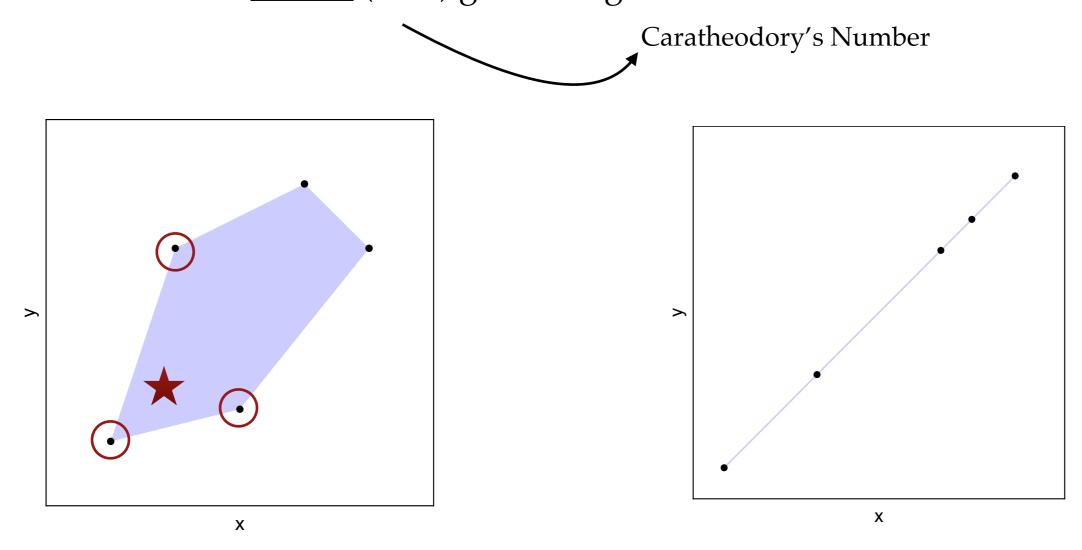
#### **Convex Hull**

Given `generating set' *Y*, the convex hull is the minimal (unique) convex set containing *Y* 



## Caratheodory's Theorem (1907)

Lets say we have a convex hull in dimension D defined by generating set X Any element in the convex hull can be expressed as a convex combination of <u>at most</u> (D+1) generating vectors

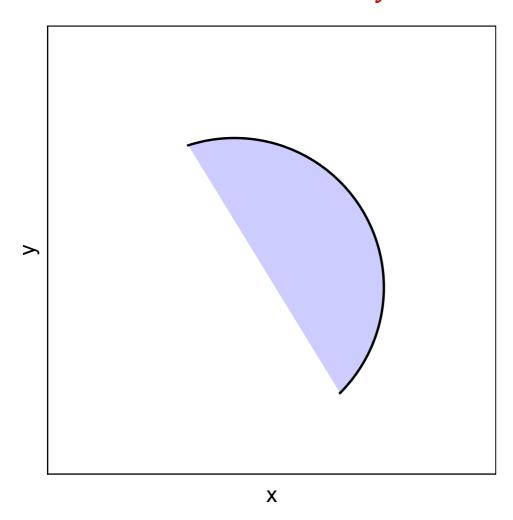


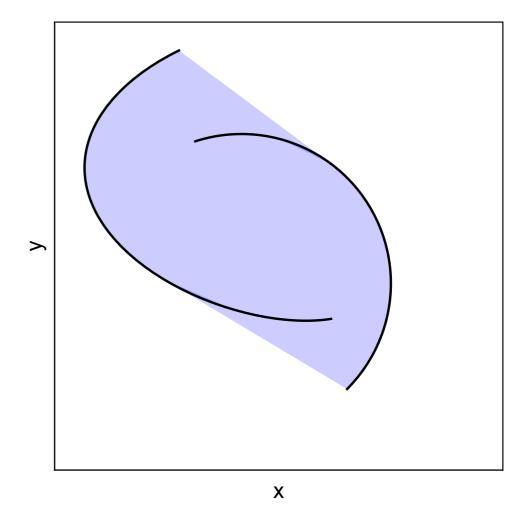
Reminder: Convex combination implies coefficients are semi-positive definite and sum to 1

## Fenchel-Eggleston Theorem (1953/58)

Consider Caratheodory's theorem, but in the limiting case where the generating set consists of at most D connected sets

#### Caratheodory's number is reduced from (D+1) to D





### So... why did I make you learn that...?

$$\vec{R} = \mathcal{C} \int_0^\infty dv \frac{\vec{\mathcal{H}}(v)}{v} F(v) \to \sum_i \mathcal{C} \frac{\vec{\mathcal{H}}(v_i)}{v_i} F(v_i) dv_i$$

$$\vec{\mathcal{H}}(v) = (\mathcal{H}_1(v), \mathcal{H}_2(v), \cdots)$$

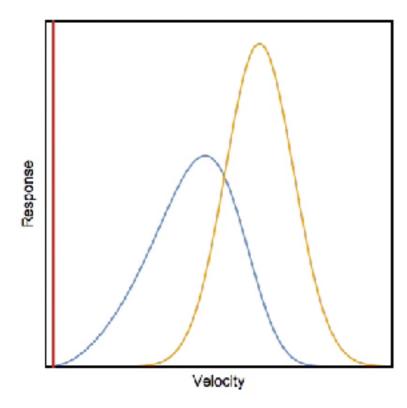
#### With requirements:

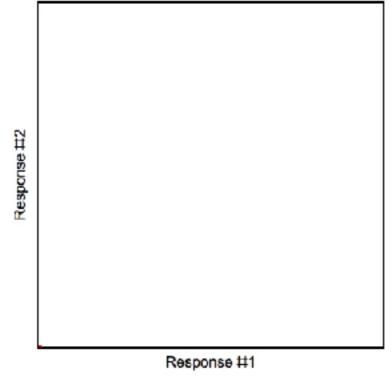
$$\forall v, F(v) \geq 0$$

$$\left(\sum_{i} dv_{i} F(v_{i}) = 1\right)$$

Define a convex hull all possible rate vectors using the infinite generating set:

$$\left\{ \mathcal{C} \frac{\vec{\mathcal{H}}(v_i)}{v_i} \right\} \in \mathcal{A}$$





Rate vector maximizing likelihood

$$\hat{\vec{R}} = (\hat{R}_1, \hat{R}_2, \cdots, \hat{R}_{\mathcal{N}})$$

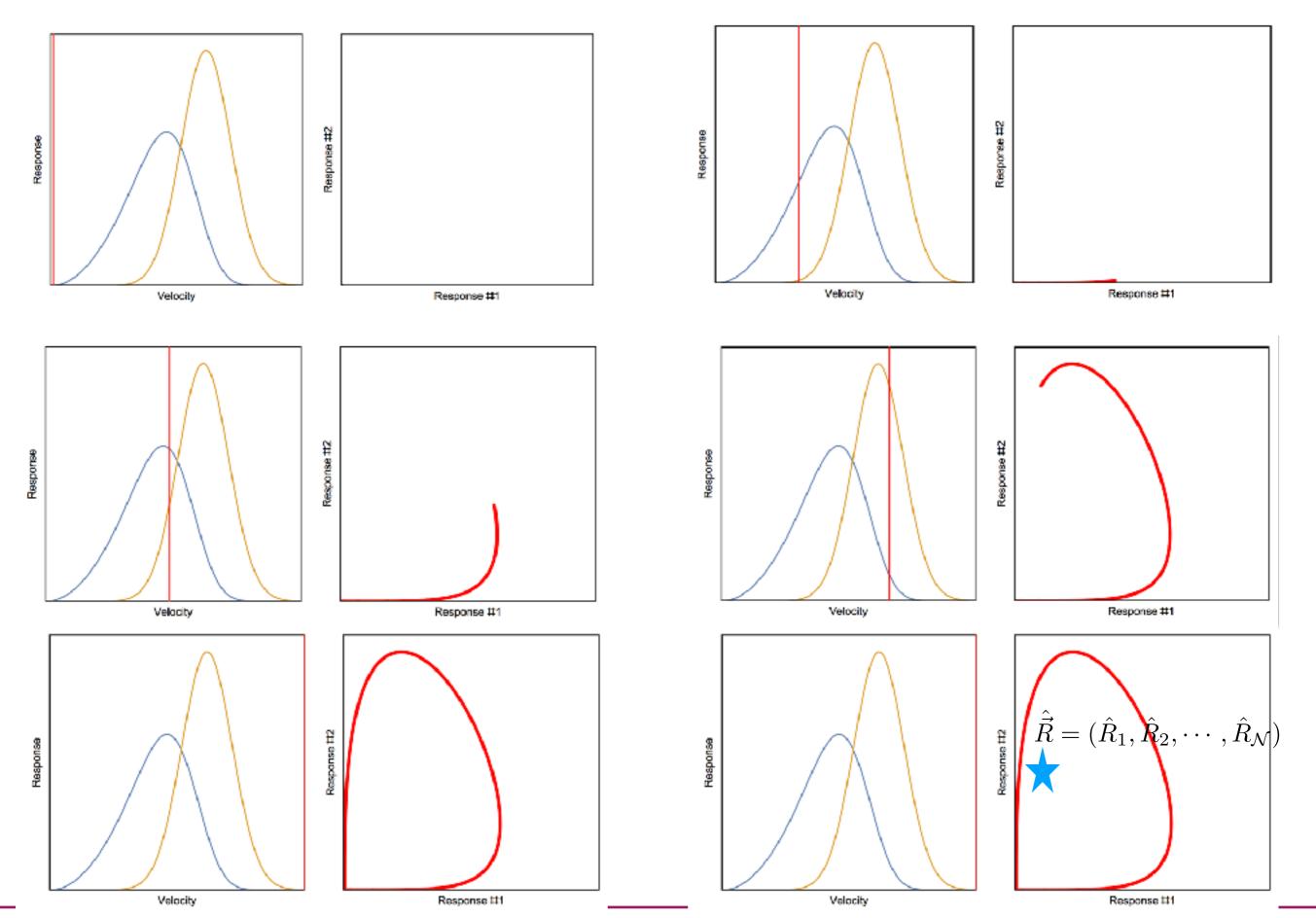
is contained in convex hull

$$\hat{\vec{R}} = \sum_{i} \lambda_{i} \times \mathcal{C} \frac{\vec{\mathcal{H}}(v_{i})}{v_{i}}$$

$$\sum_{i} \lambda_i = 1$$

Consequently:

$$F(v) = \sum_{i}^{N} F_i \, \delta(v - v_i)$$

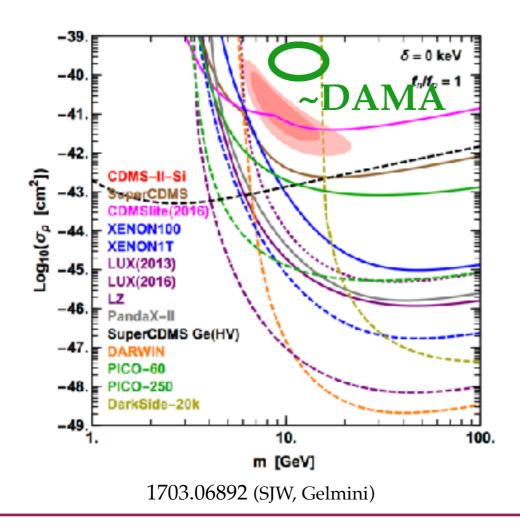


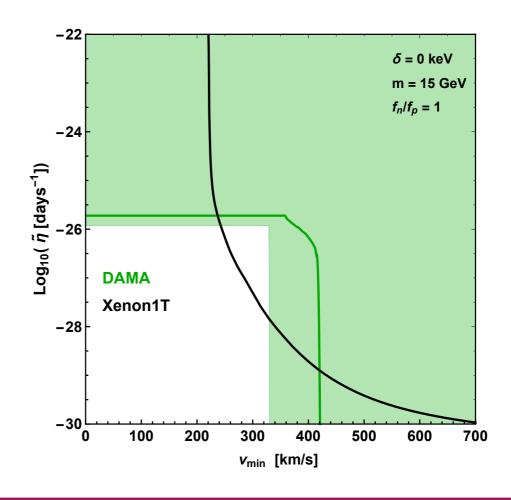
RENATA Thematic Meeting on Dark Matter February 6 2018

### Halo-Independent Method from Convex Hull

#### Additional Comments (that I don't have time to describe in detail):

- Can apply similar logic to measurements of annual modulation
- Can enforce additional symmetries (e.g. isotropy in galactic frame, triaxial symmetry, etc)
- Allows for joint analysis with indirect detection
  - Capture rate in Sun depends on halo model, see e.g. Ibarra and Rappelt 2017





# Back-up Slides

### Developing a Confidence Band

Conventional Neyman-Pearson Likelihood Ratio:

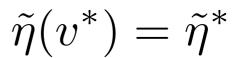
$$\Delta L[\tilde{\eta}] \equiv L[\tilde{\eta}] - L_{\min} \le \Delta L^*$$

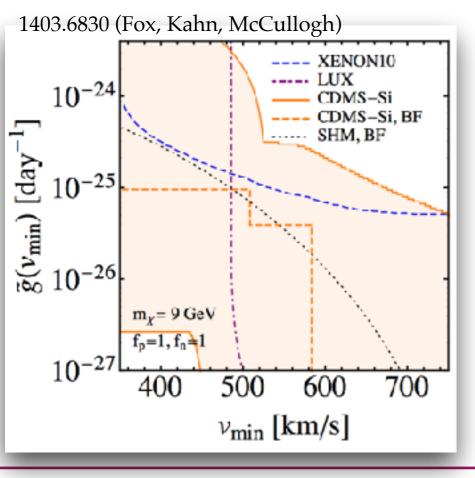
(Impossible on practical level)

New Question: Does there exist at least one halo function compatible at the desired CL?

$$\Delta L_{\min}^c(v^*, \tilde{\eta}^*) \equiv L_{\min}^c(v^*, ]\tilde{\eta}^*) - L_{\min} \leq \Delta L^*$$

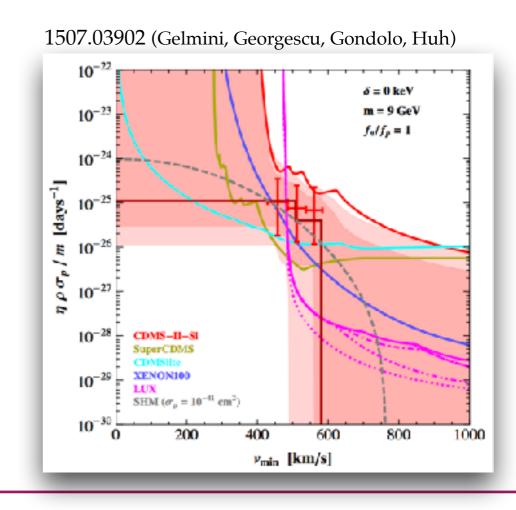
$$L_{\min}^c(v^*, \tilde{\eta}^*) \equiv \min(L[\tilde{\eta}])$$



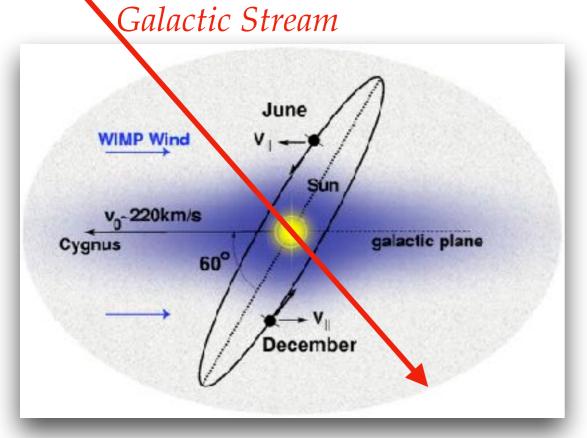


Be careful with interpretation!

This method offers clear interpretation, can we generalize it?



#### Annual Modulation



Earth's rotation about the Sun produces modulation in the scattering rate

Conventionally, assume form of f(v) in Galaxy, use Galilean transformation

$$\vec{u} = \vec{v}_{\odot} + \vec{v}_{\oplus}(t) + \vec{v}$$

Recall:

$$R_{\alpha i}(t) = \int d^3 v \, \mathcal{C} \, \frac{\mathcal{H}_{\alpha i}(\vec{v})}{v} \, f(\vec{v}, t)$$

Let us now change variables to absorb time-dependence in H:

$$R_{\alpha i}(t) = \int d^3 u \, \mathcal{C} \, \frac{\mathcal{H}_{\alpha i}^{\text{gal}}(\vec{u}, t)}{|\vec{u} - \vec{v}_{\odot} - \vec{v}_{\oplus}(t)|} \, f_G(\vec{u})$$

Note we are now working with velocity, not speed, distribution

#### Annual Modulation

Time-averaged halo function:

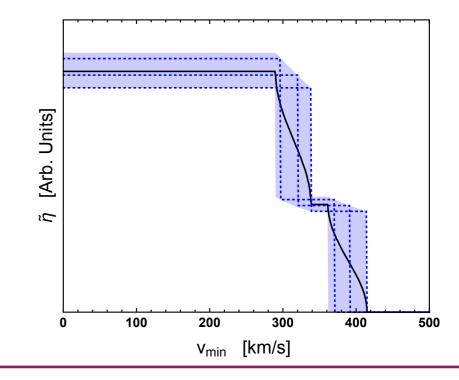
$$\tilde{\eta}_{BF}^{0}(v_{\min}) = \sum_{h=1}^{\mathcal{N}} \frac{\mathcal{C}f_{h}^{\text{gal}}}{\bar{v}_{h}(v_{\min})} \qquad \frac{1}{\bar{v}_{h}(v_{\min})} \equiv \frac{1}{T} \int dt \, \frac{\Theta(|\vec{u}_{h} - \vec{v}_{\odot} - \vec{v}_{\oplus}(t)| - v_{\min})}{|\vec{u}_{h} - \vec{v}_{\odot} - \vec{v}_{\oplus}(t)|}$$

#### A few notes:

- Now working with 3D velocity distribution rather than speed
  - Numerical minimization done done w.r.t. 4N parameters (quickly becomes numerically taxing)
- Best-fit halo function <u>only</u> piecewise constant at fixed times
- Require <u>at most</u> N streams, not (N 1)

#### **Constrained Analysis:**

$$\tilde{\eta}^* = \mathcal{C} \sum_{h=1}^{N+1} f_h^{\text{gal}} \frac{1}{T} \int dt \, \frac{\Theta(|\vec{u}_h - \vec{v}_{\odot} - \vec{v}_{\oplus}(t)| - v^*)}{|\vec{u}_h - \vec{v}_{\odot} - \vec{v}_{\oplus}(t)|}$$



### Isotropy

Enforcing isotropy makes velocity distribution more realistic and eases computation

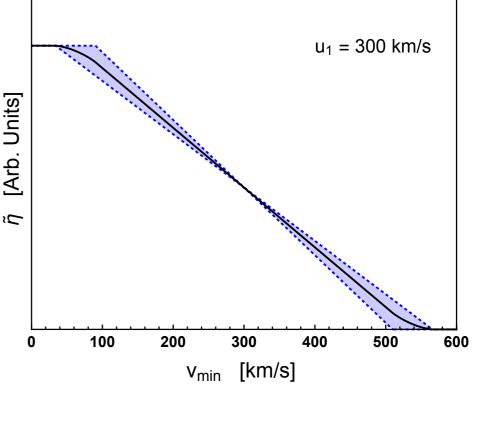
• Numerical simulations expect (more or less) isotropic distributions

$$f_G(\vec{u}) = f_G(|\vec{u}|)$$

$$R_{\alpha i}(t) = \int du \, \bar{\mathcal{H}}_{\alpha I}^{\mathrm{gal}}(u, t) \, F^{\mathrm{gal}}(u)$$

$$\bar{\mathcal{H}}_{\alpha i}^{\mathrm{gal}}(u, t) \equiv \frac{1}{4\pi} \int d\Omega_u \mathcal{H}_{\alpha i}^{\mathrm{gal}}(\vec{u}, t)$$

$$F^{\mathrm{gal}}(u) \equiv 4\pi u^2 f^{\mathrm{gal}}(u)$$



$$\tilde{\eta}_{\mathrm{BF}}(v_{\mathrm{min}},t) = \sum_{h=1}^{\mathcal{N}} \mathcal{C}F_h \times \begin{cases} \frac{1}{u_h} & v_{\mathrm{min}} \leq u_h - u_{\oplus}(t) \\ \frac{u_{\oplus}(t) + u_h - v_{\mathrm{min}}}{2u_{\oplus}(t)u_h} & u_h - u_{\oplus}(t) < v_{\mathrm{min}} < u_h + u_{\oplus}(t) \end{cases}$$

Where:

$$u_{\oplus}(t) = |\vec{v}_{\odot} + \vec{v}_{\oplus}(t)|$$