

# The results of the work collaboration during summer practice in JINR 2018

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For the Slow control Warsaw 2018

# Fire extinguishing system development for the Slow Control System

*Project developer: Dunin Nikita  
Supervisor: Krystian Roslon*

# Structure schematic



"Firesi FRS-RACK (Master)"

"Firesi FRS-RACK (Slave)"

RS-485

Ethernet / RS-232

PC



# FRS-RACK

Ведущий модуль  
"Master"



Ведомый модуль  
"Slave"



## Firesi FRS-RACK™ interfaces

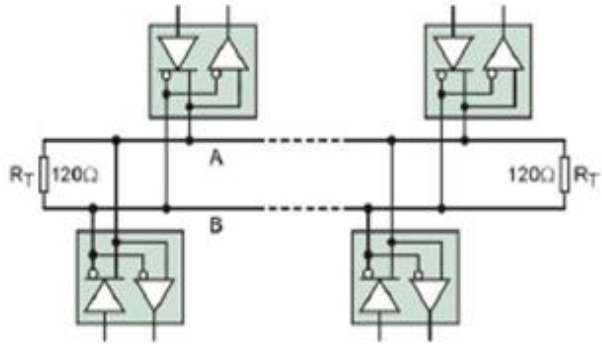


RS232



Ethernet

# Master-Slave communication



## Interface RS-485



Ведущий модуль - Master



Ведомый модуль - Slave

# UDP protocol

```
//Examples UDP ethernet communication
//*****
request:
***** Description UDP ethernet communication from RACK to PC *****
*****
01 30 41 71 02
01 Start
30 Adr '0'
41 Command 'A'
71 30+41=71 Sum
02 End

byte 0 : 3 Start packet //1
byte 1 : address always char 0 //1
byte 2 : typ A,B,C,D... A = response for request //1
byte 3 : data n* (TypDat: tGlobStav) //n=283
byte n+4 : Sum (Address+Type+N*data) //1
byte n+5 : 2 End packet //1

sum bytes 288
```

response 288 байт

```
*****
03 30 41 53 14 b8 09 00 00 00 00 54 00 e8 03 c4
55 b9 12 8d 55 84 12 cb 55 93 12 b9 5f 69 57 f9
34 44 03 31 29 fd 00 05 01 ee 00 a3 35 00 00 00
01 01 00 00 00 00 00 00 00 10 00 00 00 00 00
00 00 b6 d8 a8 08 00 00 42 55 14 13 3e 55 fd 12
bd 18 96 1c f4 61 d3 56 56 35 67 03 76 23 08 01
05 01 ef 00 58 36 00 ee 00 00 00 01 00 00 00 00
00 00 00 10 00 00 00 00 af cd 10 0a 00 00 97
54 c0 12 9a 54 7a 12 97 18 17 1c b2 61 5f 56 b5
35 60 03 f1 23 12 01 0f 01 fc 00 1b 3a 00 4d 00
00 00 01 00 00 00 00 00 00 10 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 01 10 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
01 10 00 00 00 00 00 00 00 00 00 00 00 02 02
```

\*\*\*\*\*

```

03 30 41 53 14 b8 09 00 00 00 00 54 00 e8 03 c4
55 b9 12 8d 55 84 12 cb 55 93 12 b9 5f 69 57 f9
34 44 03 31 29 fd 00 05 01 ee 00 a3 35 00 00 00
01 01 00 00 00 00 00 00 00 10 00 00 00 00 00
00 00 b6 d8 a8 08 00 00 42 55 14 13 3e 55 fd 12
bd 18 96 1c f4 61 d3 56 56 35 67 03 76 23 08 01
05 01 ef 00 58 36 00 ee 00 00 00 01 00 00 00 00
00 00 00 10 00 00 00 00 00 af cd 10 0a 00 00 97
54 c0 12 9a 54 7a 12 97 18 17 1c b2 61 5f 56 b5
35 60 03 f1 23 12 01 0f 01 fc 00 1b 3a 00 4d 00
00 00 01 00 00 00 00 00 00 00 10 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 01 10 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
01 10 00 00 00 00 00 00 00 00 00 00 00 02 02
    
```

```

03 Start
30 adr '0'
41 command 'A'
    
```

```

tGlobStav:
53 14 b8 09 00 00 //id=000009b81453
00 00 //pZac=0 -> (start=0)
54 00 //pKon= 0x0054 -> (end=84)
e8 03 //Max = 0x3e8 ->(Max=1000)
    
```

```

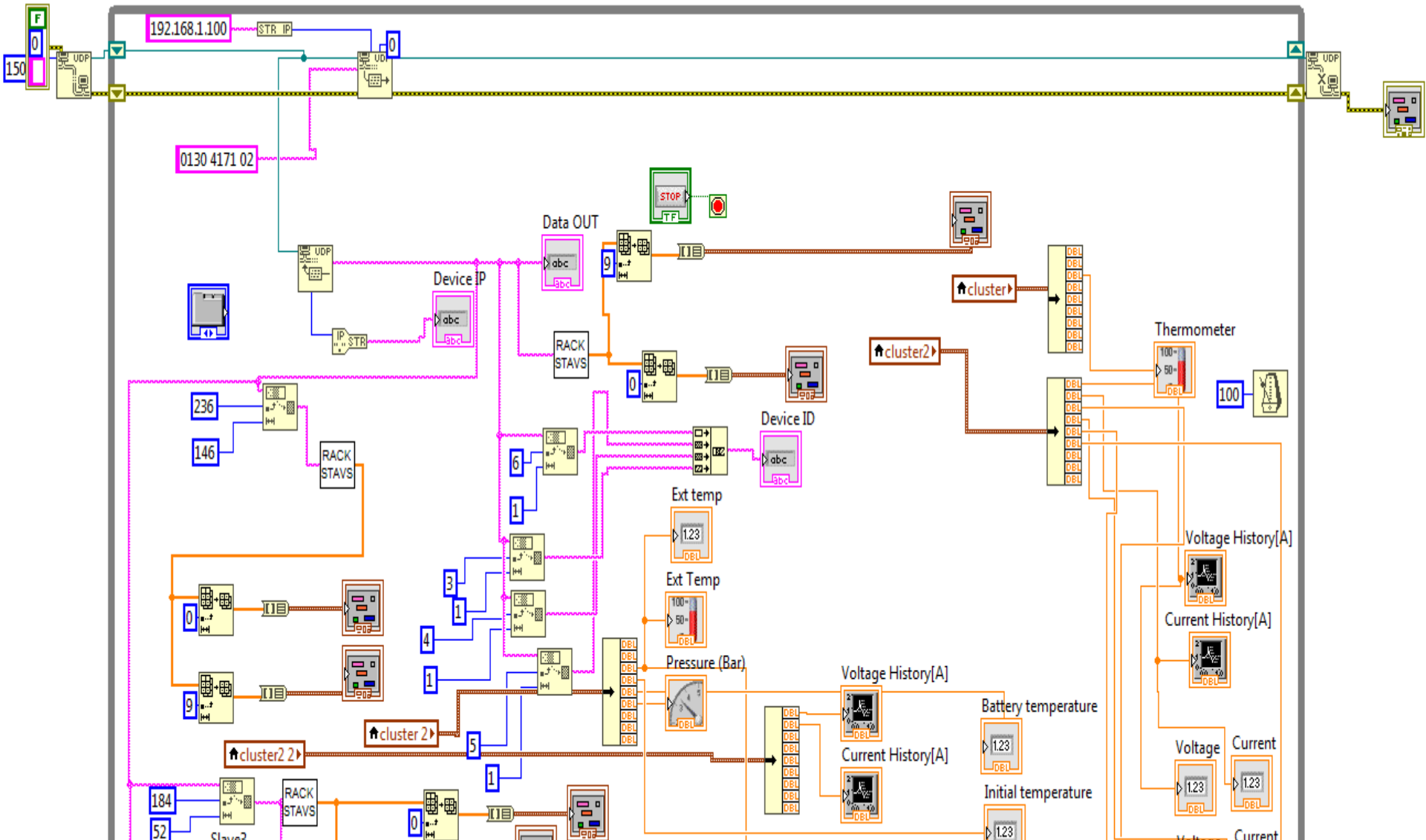
c4 55 b9 12 8d 55 84 12 cb 55 93 12 b9 5f 69
57 f9 34 44 03 31 29 fd 00 05 01 ee 00 a3 35
    
```

```

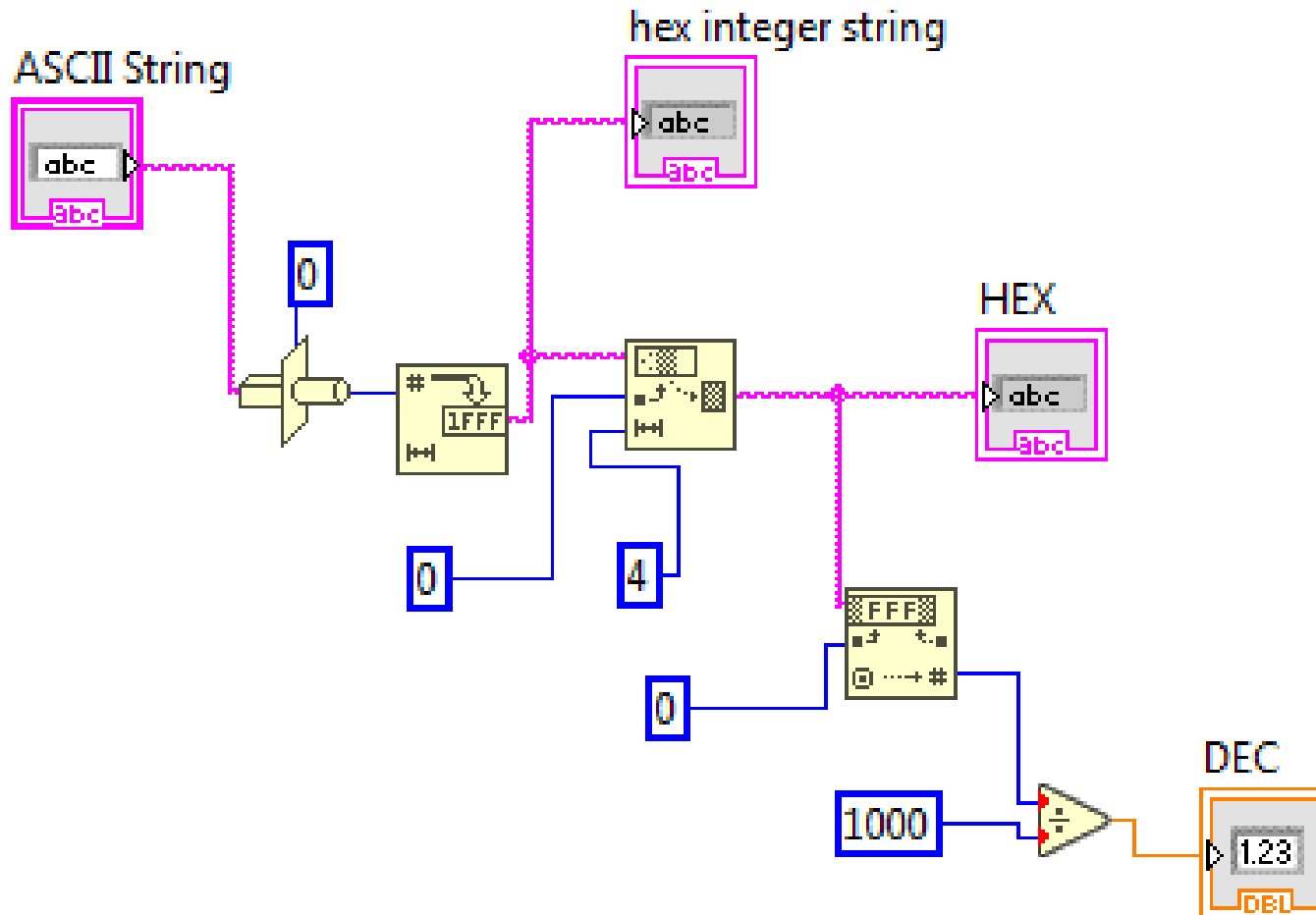
tGlobStav:
53 14 b8 09 00 00 //id=000009b81453
00 00 //pZac=0 -> (start=0)
54 00 //pKon= 0x0054 -> (end=84)
e8 03 //Max = 0x3e8 ->(Max=1000)

MerA:
c4 55 //VA =0x55c4 -> 21 956 mV
b9 12 //IA =0x12B9 -> 4 793 uA
8d 55 //VB
84 12 //IB
cb 55 //VC
93 12 //IC
b9 5f //VNET =0x5fb9 -> 24 505mV (mains)
69 57 //VDet
f9 34 //VBat
44 03 //VRelHas
31 29 //VRelSir
fd 00 //ExtTemp =0x00fd = 253 = 25.3 grC
05 01 //TInt = 0x0105 = 261 = 26.1 grC
ee 00 //TBat
a3 35 //Tlak = 0x35a3 = 13 731 mBar
    
```

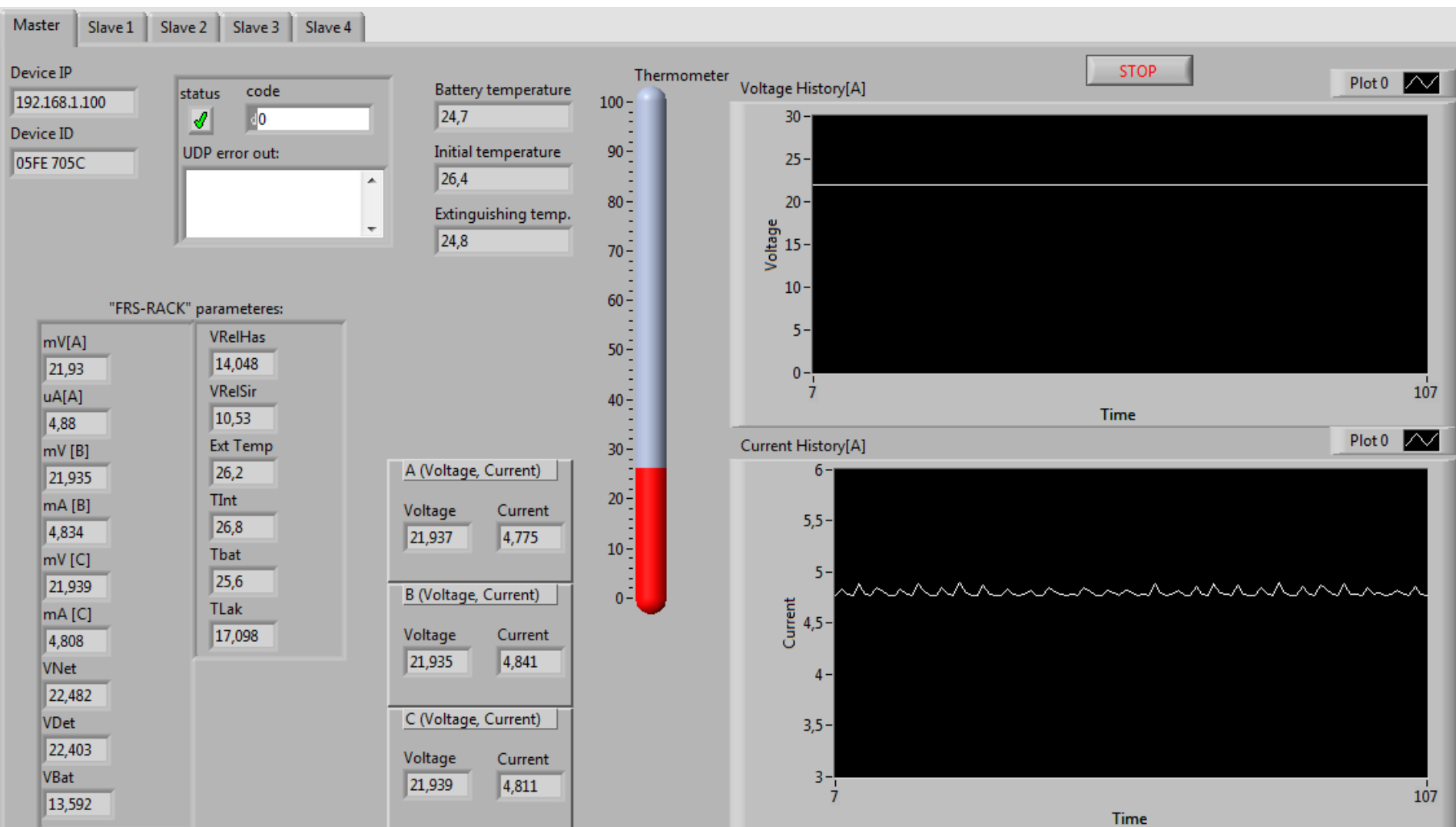
# Source code written in "G" (LabVIEW2016)



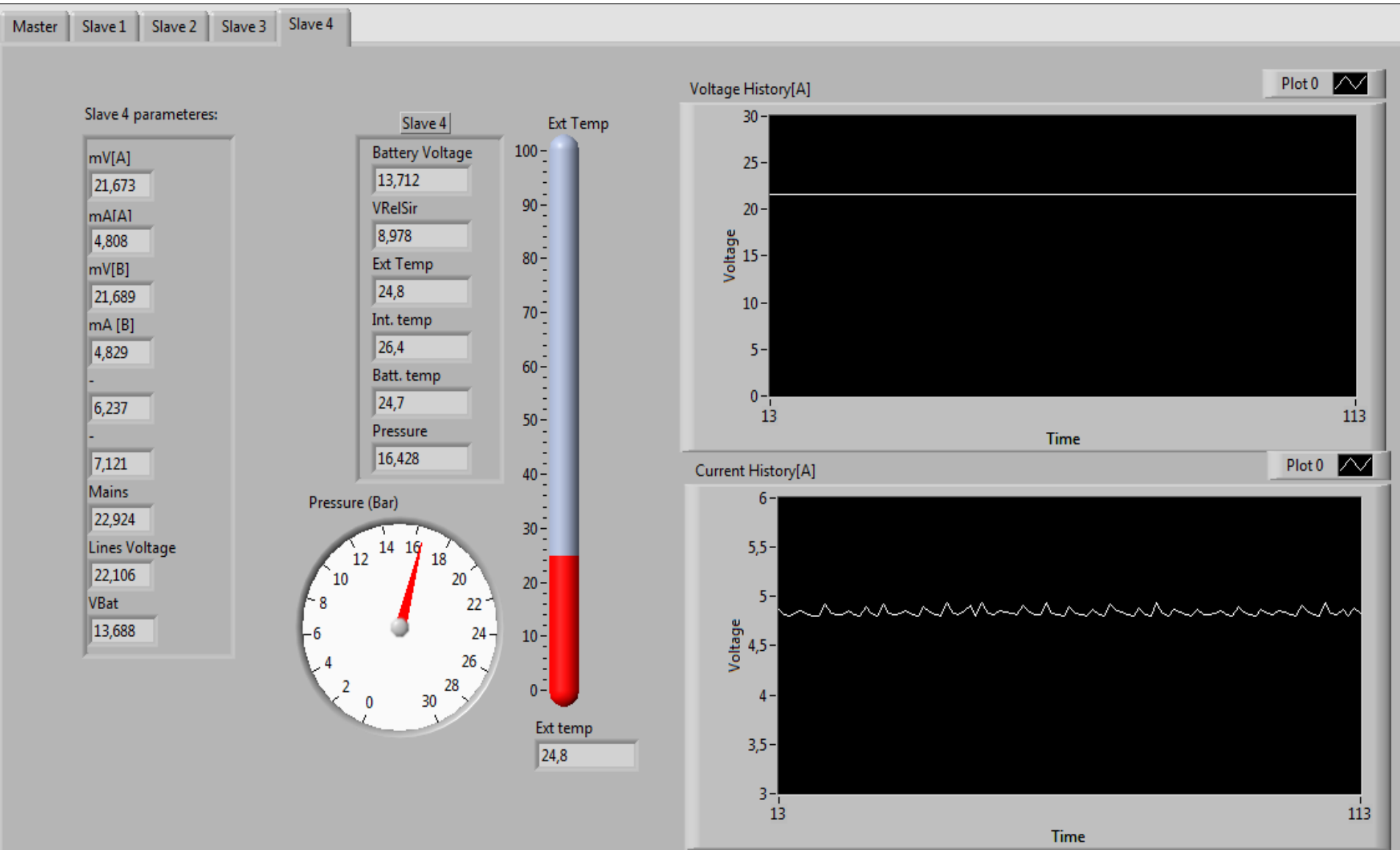
# “ASCII to HEX” converting



# Software interface for Master module



# Software interface for Slave module



# Advantages of the system

- The possibility of using cables up to 500 meters.
- Using three temperature sensors (internal, external and measuring t batteries)
- Measuring of pressure gauge.
- Possibility to connect more slave devices (up to 4 PCs.);
- Using of visualization tools in the form of indicators and graphs.

# Future improvements

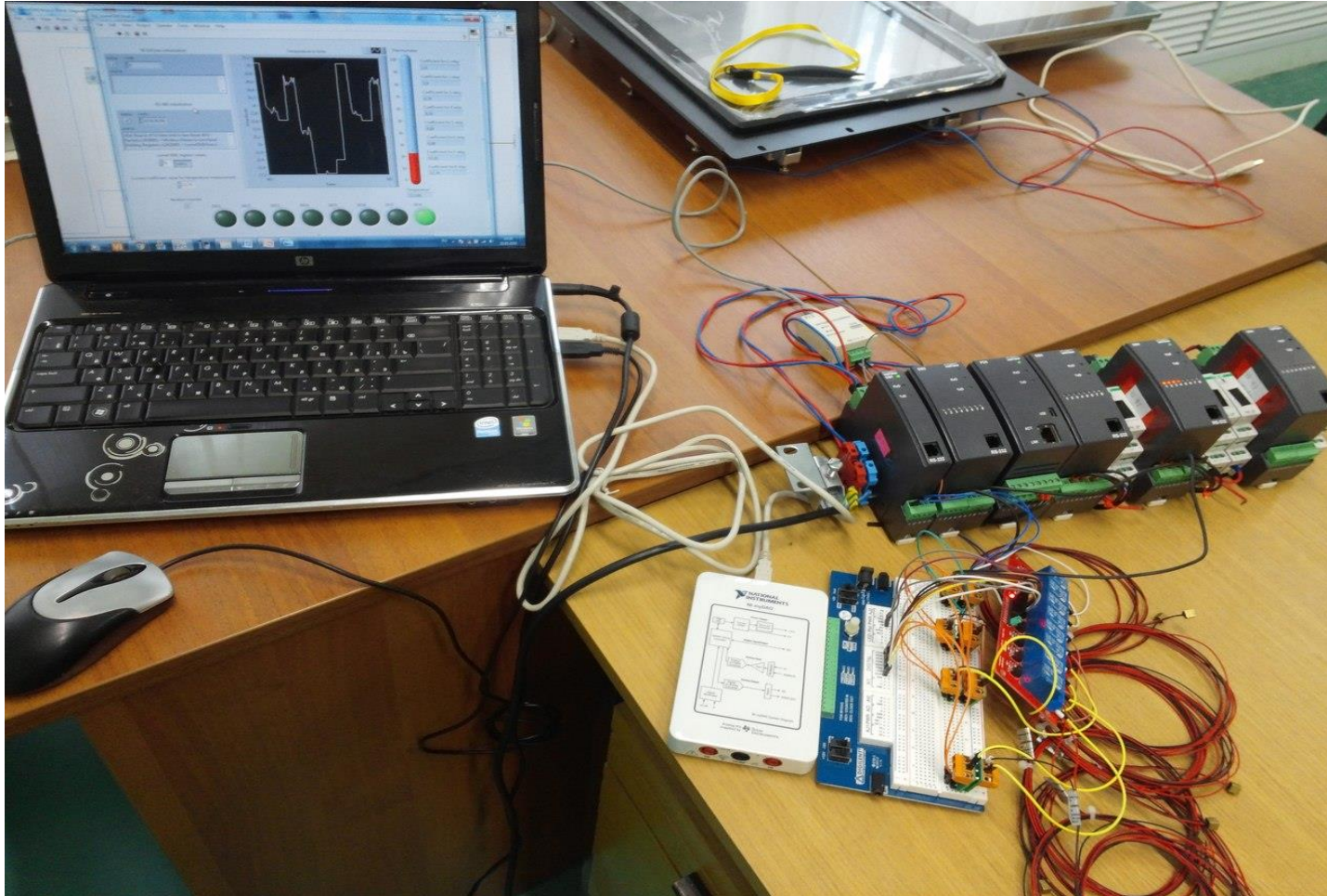
- Data acquisition from new 1u device (TCP/IP)
- SMS-alert for JINR fire department



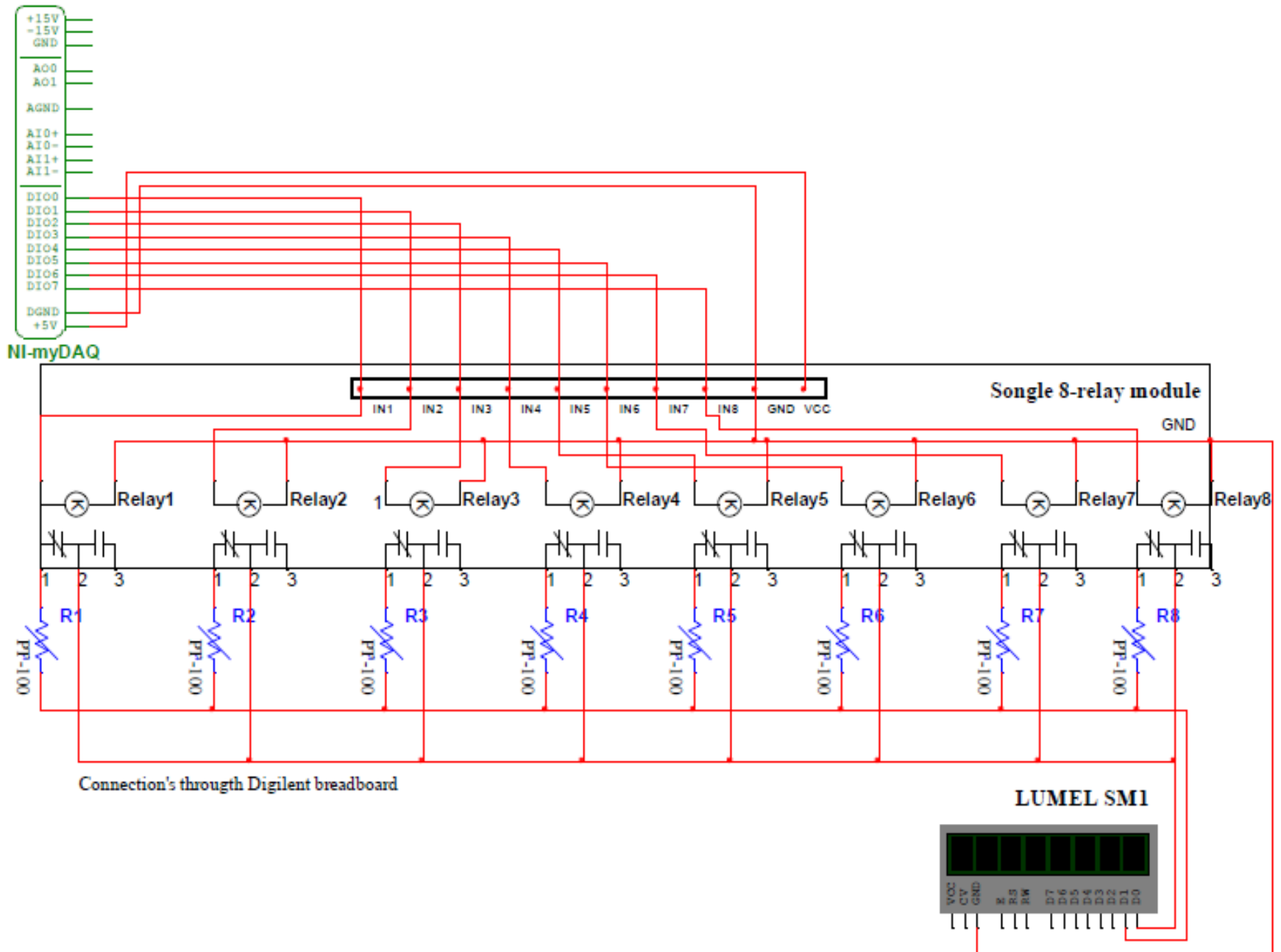
# Temperature measurements prototype system for ToF-MPD.

*Project developer: Dunin Nikita  
Supervisors: Marek Peryt, Krystian Roslon*

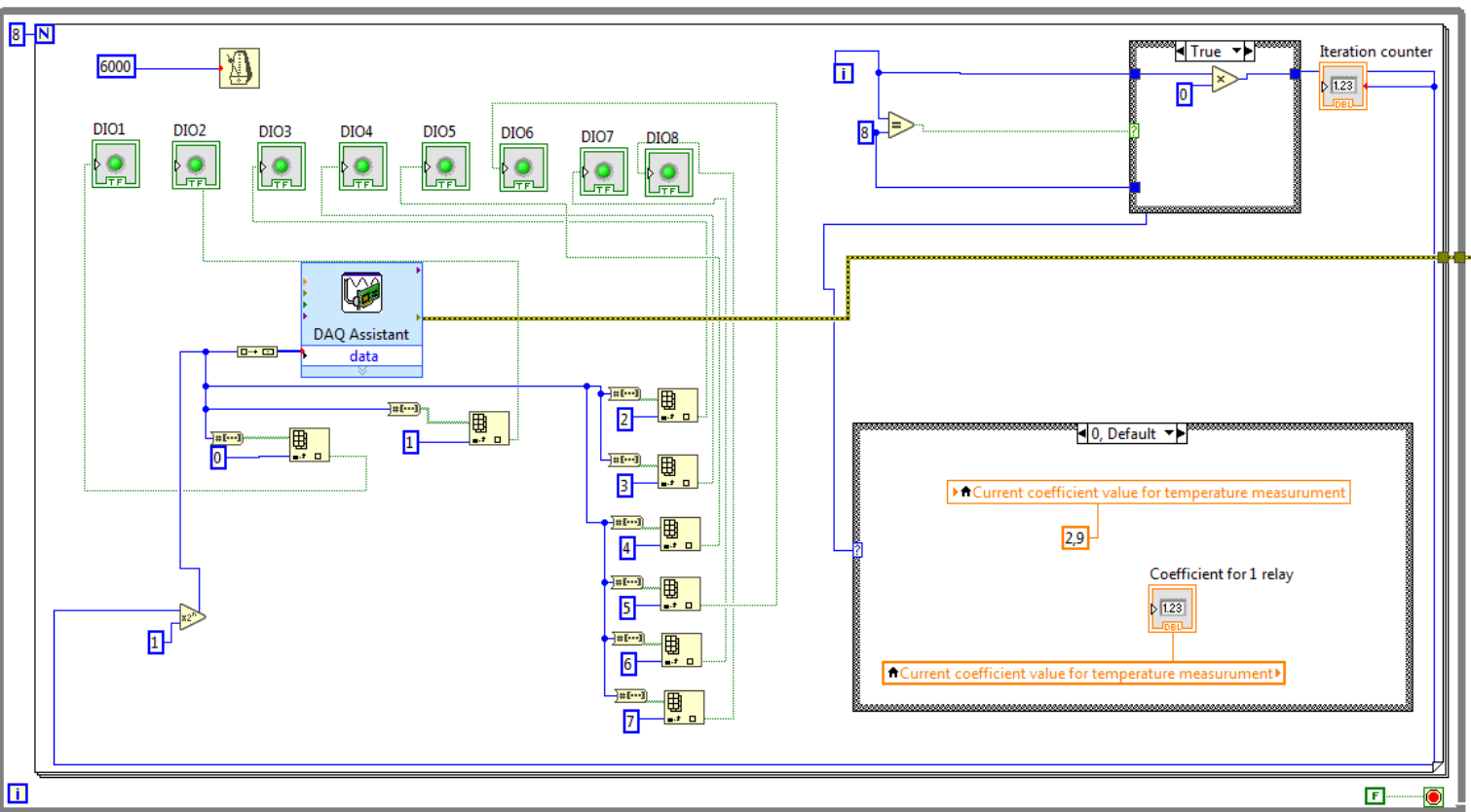
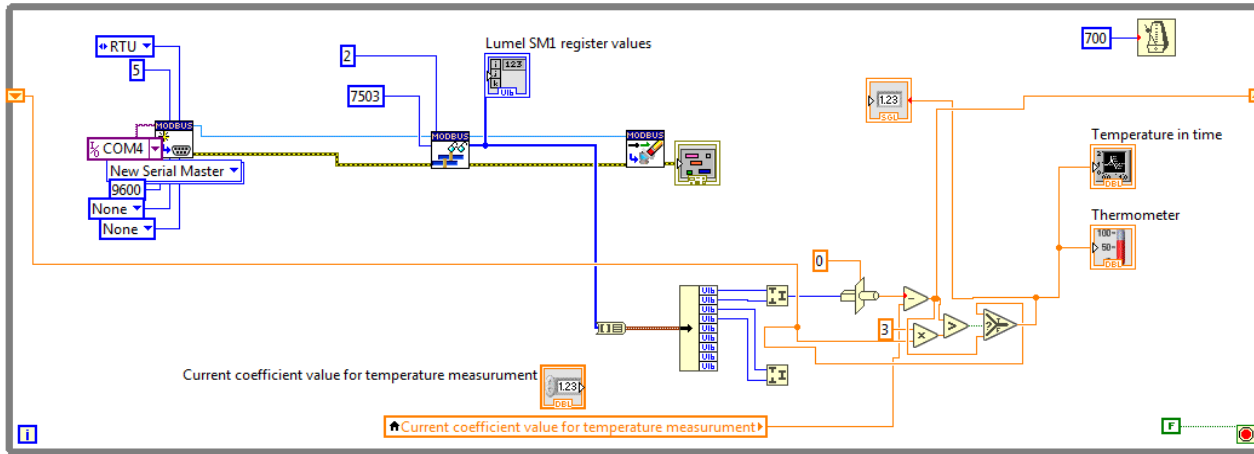
# The view of the system



# Schematic of the system



# Source code



# Interface

The interface is titled "LumelSM1final.vi" and includes a menu bar (File, Edit, View, Project, Operate, Tools, Window, Help) and a toolbar with icons for run, stop, and pause. The main area is divided into several sections:

- NI DAQmx initialization:** Contains a status indicator (green checkmark), a code field with value "0", and a source dropdown menu.
- RS-486 initialization:** Contains a status indicator (green checkmark), a code field with value "1073676294", and a source dropdown menu listing "VISA Read in RTU Data Unit.lvclass:Read ADU Packet.vi:5030001->Modbus Master.lvclass:Read Holding Registers.vi:2420001->LumelSM1final.vi".
- Lumel SM1 register values:** Features a rotary knob set to "0" and a numeric display showing "16908".
- Current coefficient value for temperature measurement:** Features a rotary knob set to "9,99".
- Iteration counter:** A numeric display showing "5".
- Temperature in time:** A graph with "Amplitude" on the y-axis (ranging from 24,4 to 25,5) and "Time" on the x-axis (ranging from 1231 to 1331). The graph shows a signal that fluctuates between approximately 24,4 and 25,4.
- Thermometer:** A vertical thermometer with a scale from 0 to 100. The liquid level is at approximately 25,0355. To the right of the thermometer are eight input fields for relay coefficients: "Coefficient for 1 relay" (2,9), "Coefficient for 2 relay" (2,9), "Coefficient for 3 relay" (6,79), "Coefficient for 4 relay" (8,56), "Coefficient for 5 relay" (9,89), "Coefficient for 6 relay" (9,99), "Coefficient for 7 relay" (11,41), and "Coefficient for 8 relay" (12,74).
- Temperature:** A numeric display showing "25,0355".
- DIOs:** A row of eight circular indicators labeled DIO1 through DIO8. DIO6 is illuminated in bright green, while the others are dark green.

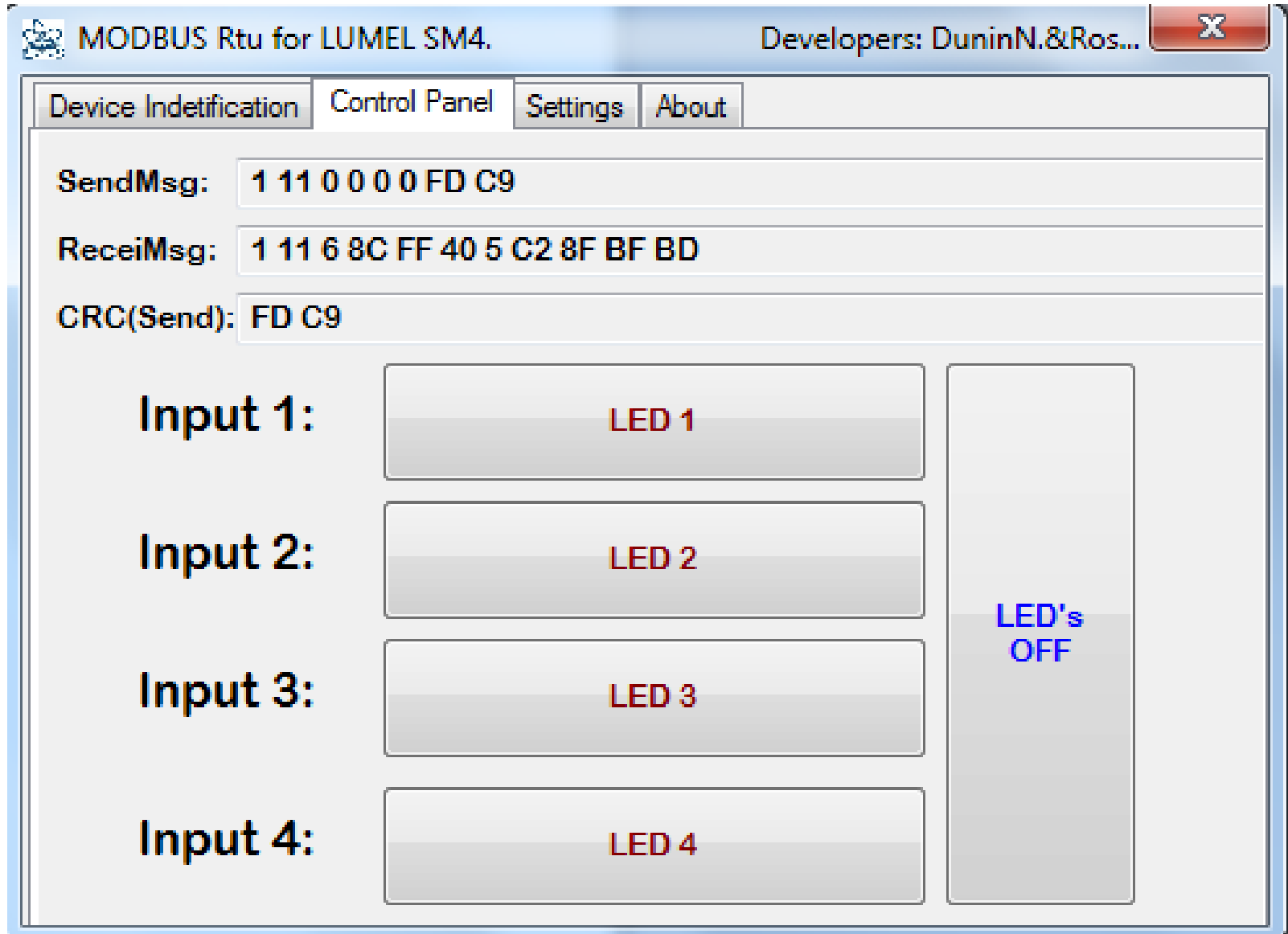
# Smart relay control

*Project developer: Dunin Nikita*  
*Supervisor: Krystian Roslon*

# Tools

- Microsoft Visual Studio 2015 (C#) for RS-232
- LabVIEW 2016 (VISA library) for RS-232
- LabVIEW 2016 (Modbus library) for RS-485

# C# software with interface





What is the task that unites this projects?

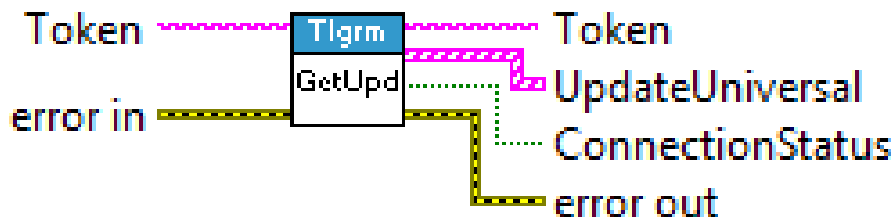


Answer is remote control development

# How we can integrate remote control for data acquisition software in LabVIEW?

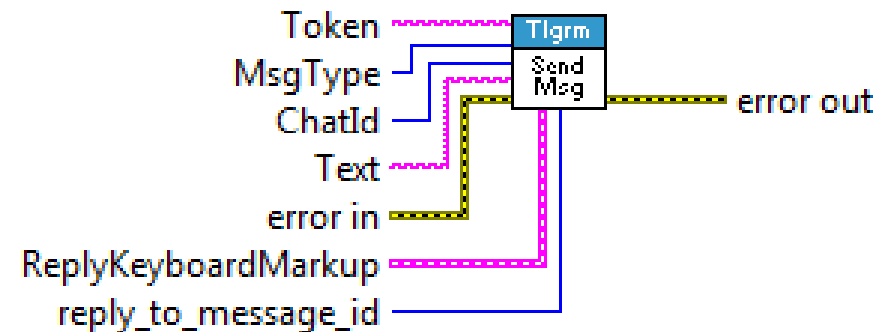
## “get Updates”

getUpdates.vi

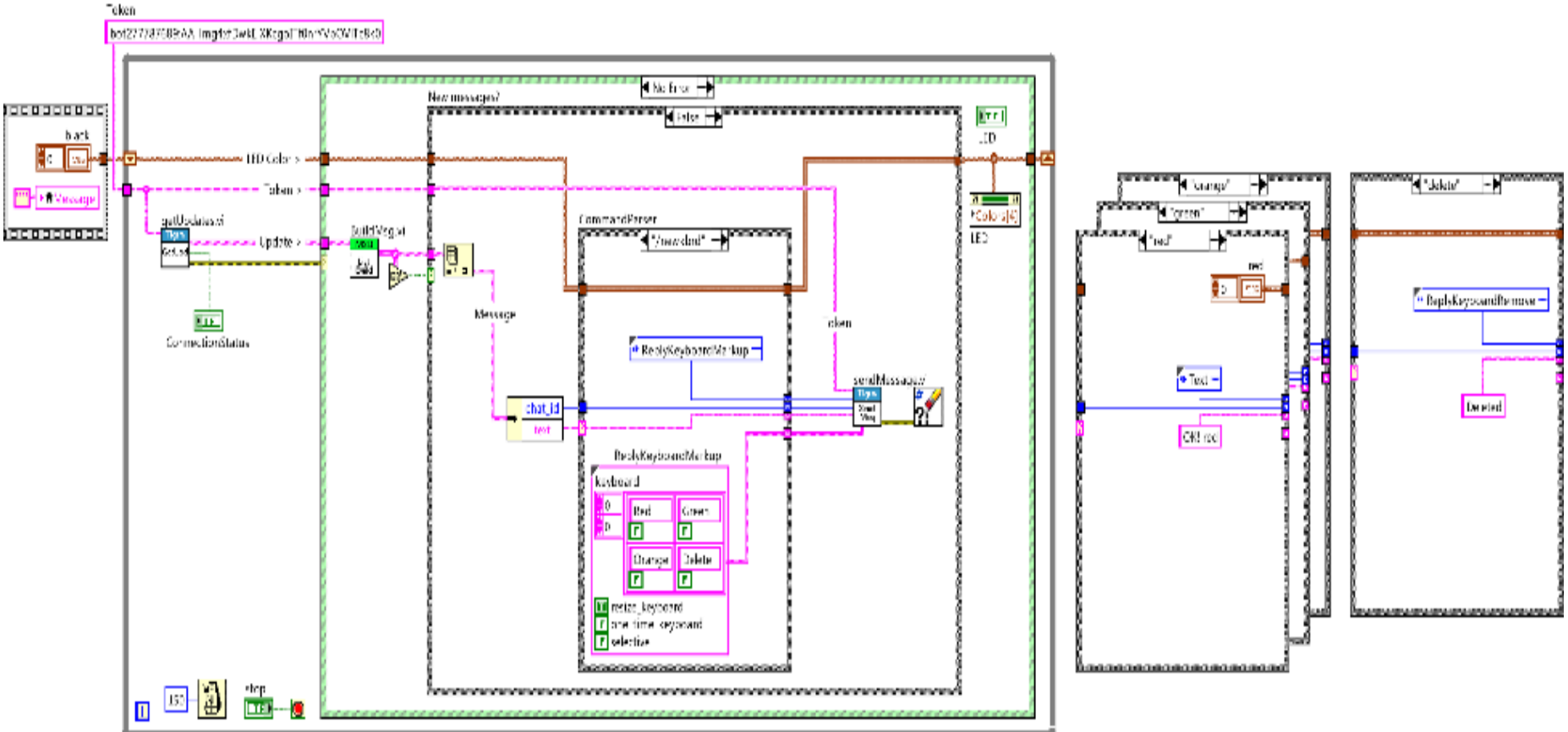


## “send Message”

sendMessage.vi



- I) An initialization takes place.
- II) In an infinite loop with a specified period, occur poll the Telegram servers for new updates. SubVI BuildMsg.vi converts JSON Update objects to messages. If there are new messages, then their text is compared to variants of the Case structure.
- III) At the last stage, the reply message is sent to the active chat.



## **Advantages of messengers using for Labview systems:**

- 1) Software works with any smartphone OS's – Android and iOS;**
- 2) Easy integration with any National Instruments hardware; (MyRIO, cRIO, MyDAQ, etc)**
- 3) Easy integration with other vendors hardware include PLC's, microcontrolles, FPGA's**

Video demonstration

Thank you for your attention!