



A Hybrid T-A Field Formulation for the Magnetoquasistatic Analysis of HTS Magnets

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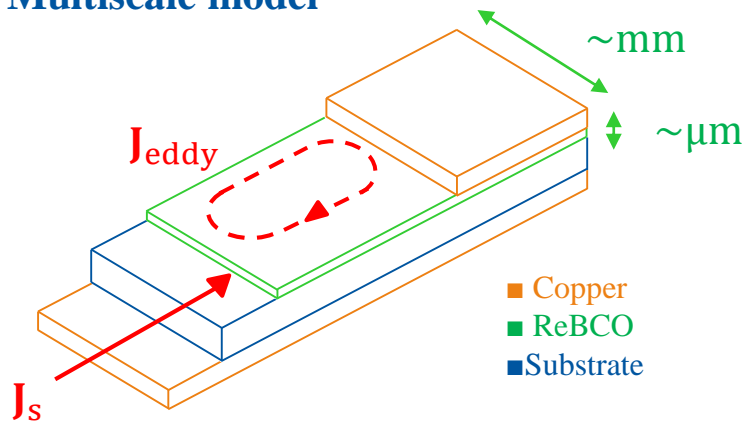
Special Thanks:

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M. Prioli, E. Ravaioli, J. Van Nugteren

Rationale

- 20+ Tesla dipoles for future high-energy particle accelerators
- Simulation of the electrodynamics in HTS tapes and cables (then magnets, and circuits)

1) Multiscale model

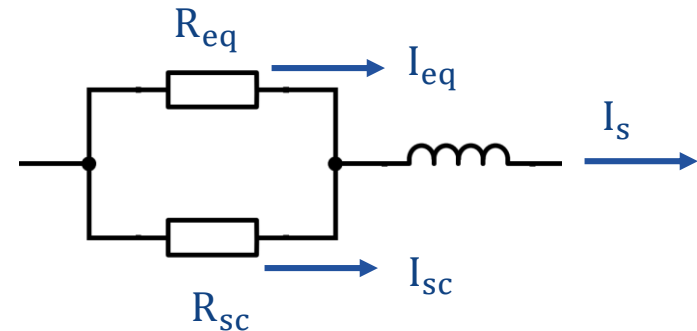


2) HTS resistivity

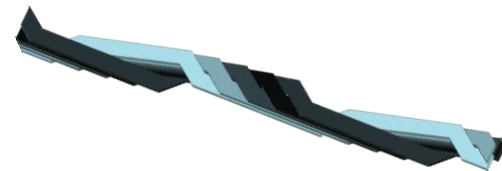
Nonlinear, field dependent, anisotropic

$$\sigma_{SC}^{-1} = \frac{E_c}{J_c(B)} \left(\frac{J}{J_c(B)} \right)^{n-1}$$

3) Current sharing regime

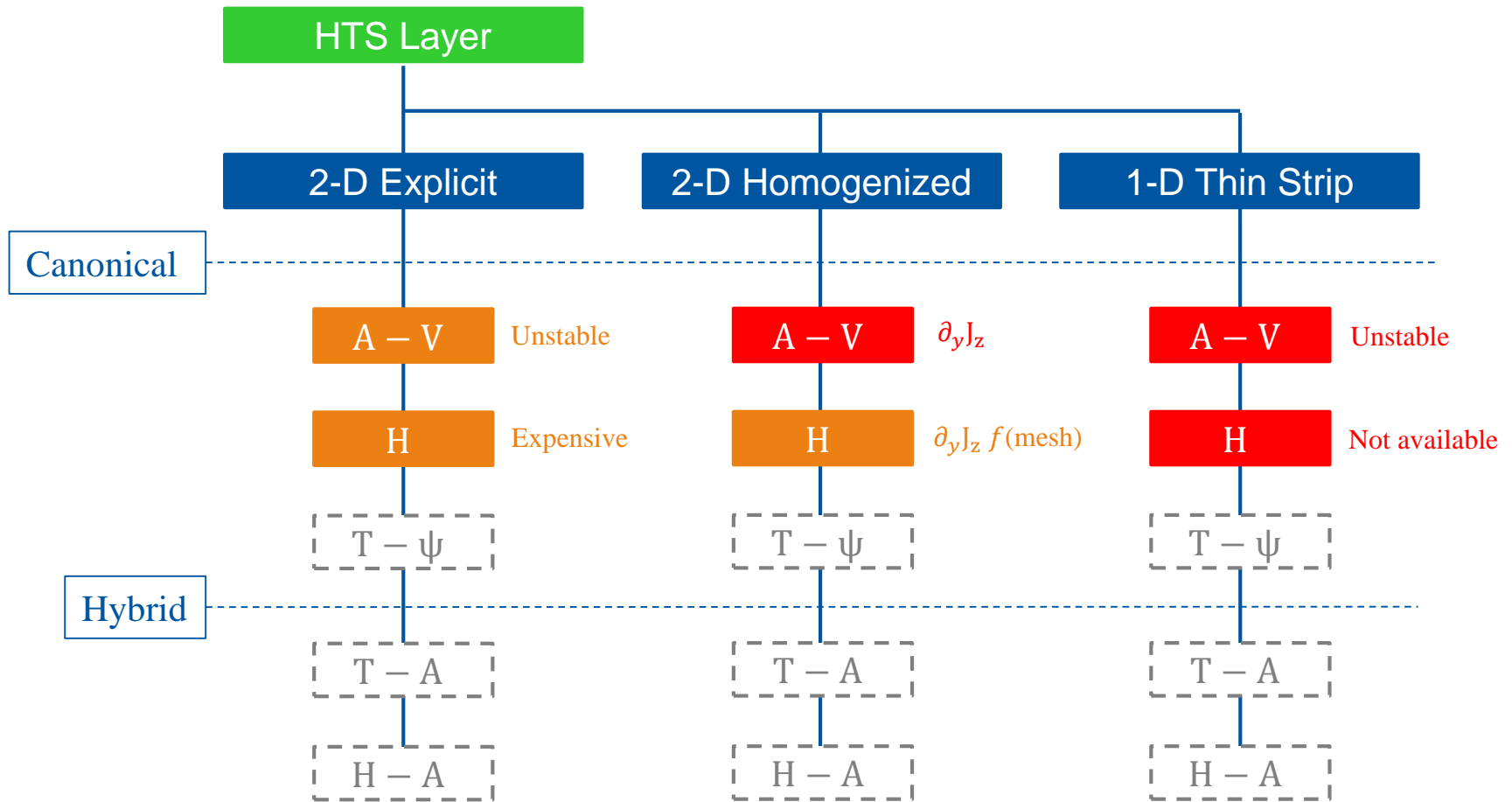


4) Complex cable geometry

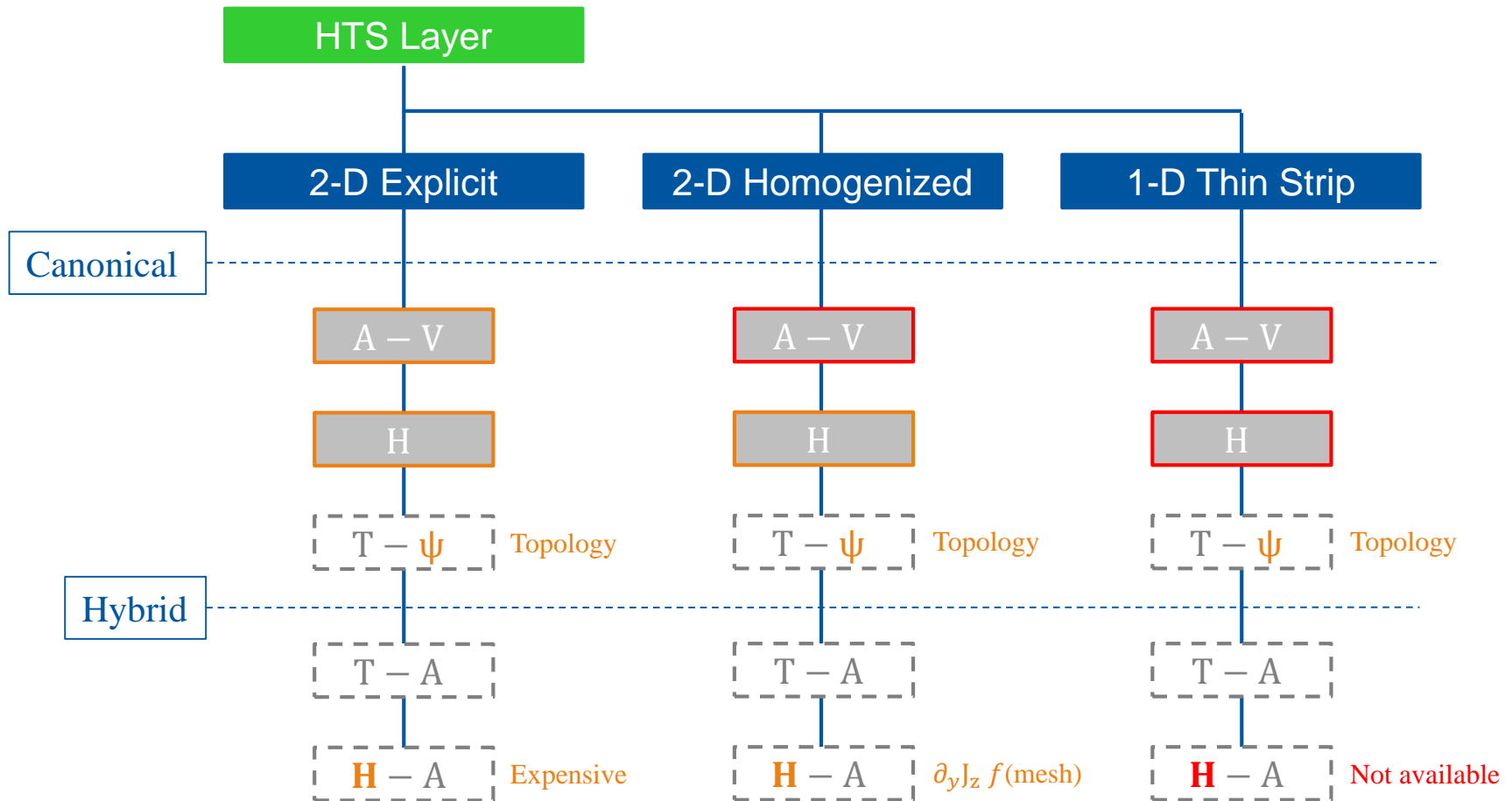


An ideal numerical formulation should be accurate, robust, computationally fast

Last Time... [Link](#)



...Some Steps Forward



- A unstable
 - H expensive
 - ψ complex for nontrivial geometries
- One does not simply choose a T-A hybrid form (Semicit.)



Hybridisation via Domain decomposition

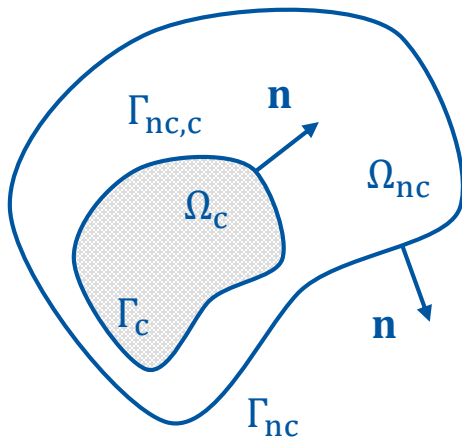
The following approach might answer the simulation needs:

HTS Layer

1-D Thin Strip

T – A

Domain decomposition:



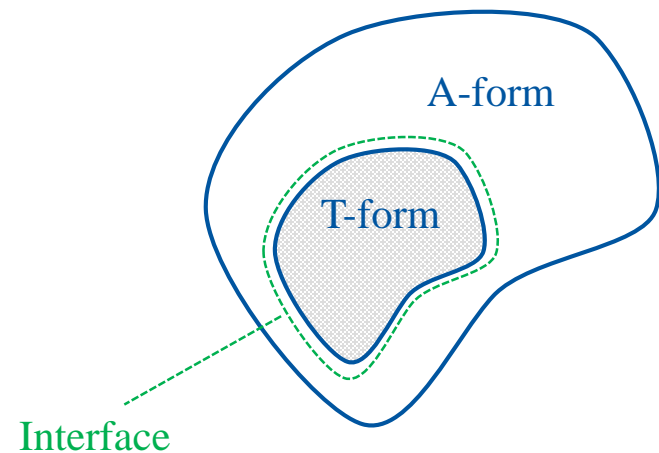
Domains $\Omega_{nc}, \Omega_c \in \mathbb{R}^3$,

- $\Omega_{nc} : \sigma = 0$ (e.g. iron yoke)
- $\Omega_c : \mu = \mu_0$ (e.g. magnet coil)

Boundaries $\Gamma_{nc}, \Gamma_c \in \mathbb{R}^2$

Interface $\Gamma_{nc,c} \in \mathbb{R}^2$

Hybrid form:



Outline

- ❑ Fundamentals of Vector Fields Theory
- ❑ Hybrid T-A Field Formulation
- ❑ Numerical Implementation
- ❑ Applications
- ❑ Conclusions and Outlook

01 - Fundamentals

T-A Form in a Nutshell

Reformulation of Maxwell equations in terms of current (**T**) and magnetic (**A**) vector potentials.

What is needed:



Maxwell Equations

- Magnetoquasistatic Hypothesis
- Uniqueness of Solution

Vector Potentials

- Helmholtz decomposition (curl + divergence)
- Interface conditions
- Gauge fixing



Discretization technique

- Finite Element Method

Numerical solver

- Galerkin Method (Weighted residuals)

.. and, of course, a volunteer sorcerer





Maxwell Equations

In vacuum (*):

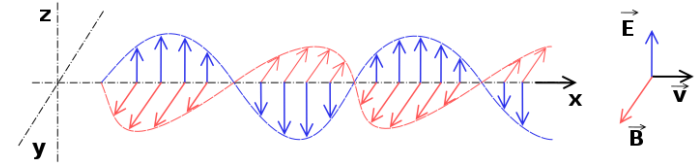
$$\nabla \times \mathbf{E} = -\partial_t \mathbf{B}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \varepsilon_0 \partial_t \mathbf{E}$$

$$\nabla \cdot \mathbf{E} = \rho \varepsilon_0^{-1}$$

$$\nabla \cdot \mathbf{B} = 0$$

+ material laws $\mathbf{B} = \mu_0 \mathbf{H}$, $\mathbf{D} = \varepsilon_0 \mathbf{E}$, $\mathbf{J} = \sigma \mathbf{E}$



Solution for $\mathbf{J} = \mathbf{0}$, $\rho = 0$

Symbols:

\mathbf{E}, \mathbf{D} electric field strength / density

\mathbf{H}, \mathbf{B} magnetic field strength / density

ρ, \mathbf{J} electric charge / current density

μ_0 vacuum magnetic permeability

ε_0 vacuum electric permittivity

σ electric conductivity

Features:

- 4 independent variables (x, y, z, t)
- 2 equations (Faraday, Ampere-Maxwell) in 6 unknowns $B_{x,y,z}$ $E_{x,y,z}$
- 2 time-boundary conditions (Gauss laws)
- known field sources (\mathbf{J}, ρ)



(*) The vacuum hypothesis makes the equations linear and elegant.
Relaxing it would make the math more complex, without adding any new concept.



Magnetoquasistatic Hypothesis

- Dimensional analysis for arbitrary vector field \mathbf{F}

$$\mathbf{F} = f \cdot \mathcal{F}$$

$$\nabla \mathbf{F} \approx \mathbf{F}/\ell$$

$$\partial_t \mathbf{F} \approx \mathbf{F}/\tau$$

f, \mathcal{F} reference quantity / non dimensional vector
 ℓ, τ characteristic spatial dimension / time constant
 $c = (\epsilon\mu)^{-1/2}$ speed of light

- Ampere-Maxwell Law: $\mathbf{J} = \mathbf{J}_f + \mathbf{J}_d$ (free and displacement currents). One can obtain [1]:

$$\frac{H_d}{H_f} \approx \left(\frac{\ell}{\tau c} \right)^2, \quad \frac{J_d}{J_f} \approx \frac{\epsilon}{\tau \sigma}$$

- If, compared to the dynamics of the device
 - $\tau \gg \ell/c$ “instantaneous” light propagation
 - $\tau \gg \epsilon/\sigma$ “instantaneous” charge relaxation

$$\text{Then } \mathbf{J}_d = \partial_t \mathbf{D} \approx 0$$

(Always true for small, conductive devices at power frequencies)



Uniqueness of Solution

Domain $\Omega \in \mathbb{R}^3$ with Γ as contour

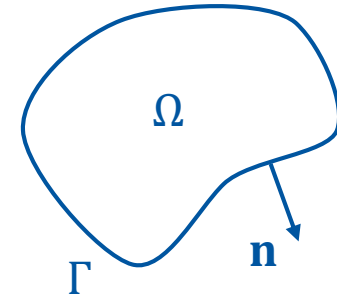
Poynting vector: $\mathbf{P} = \mathbf{E} \times \mathbf{H}$

Conservation of energy: $\nabla \cdot \mathbf{P} = -\mathbf{E} \cdot \partial_t \mathbf{D} - \mathbf{H} \cdot \partial_t \mathbf{B} - \mathbf{E} \cdot \mathbf{J}$

Uniqueness Theorem, using the properties of \mathbf{P} (e.g. [1]):

\mathbf{E}, \mathbf{B} unique on Ω if

- $\mathbf{E}_0, \mathbf{B}_0$ known on Ω at $t = t_0$
- $\mathbf{E} \times \mathbf{n}$ OR $\mathbf{H} \times \mathbf{n}$ known on $\Gamma, \forall t$



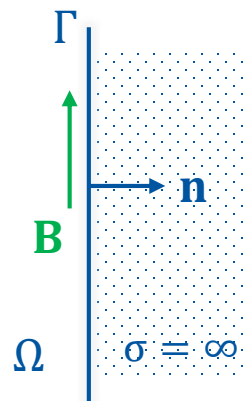
Two boundary conditions (BC) of practical importance, PEW and PMW

Perfect Electric Wall

$$\sigma = \infty$$

$$\mathbf{E} \times \mathbf{n} = 0$$

$$(\mathbf{B} \cdot \mathbf{n} = 0)$$

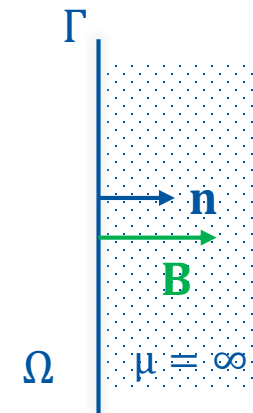


Perfect Magnetic Wall

$$\mu = \infty$$

$$\mathbf{H} \times \mathbf{n} = 0$$

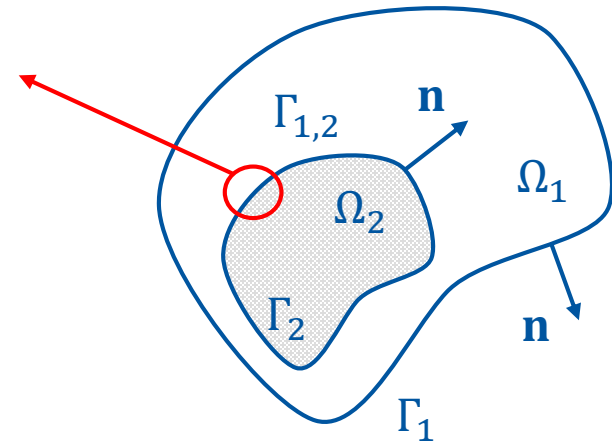
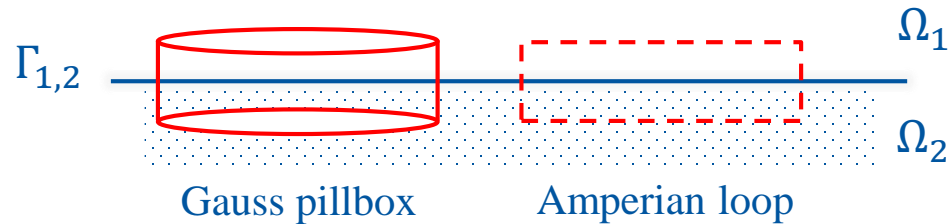
$$(\mathbf{B} \times \mathbf{n} = 0)$$



Interface conditions

Domains $\Omega_1, \Omega_2 \in \mathbb{R}^3$ with Γ_1, Γ_2 as contour and $\Gamma_{1,2}$ as interface

Magnetic charge / current densities ignored (weakly related with the known universe)



- Gauss pillbox for **flux conservation**

$$(\mathbf{B}_1 - \mathbf{B}_2) \cdot \mathbf{n} = 0$$

$$(\mathbf{D}_1 - \mathbf{D}_2) \cdot \mathbf{n} = \sigma_q$$

- Amperian loop for **potential conservation**

$$(\mathbf{H}_1 - \mathbf{H}_2) \times \mathbf{n} = \mathbf{K}_s$$

$$(\mathbf{E}_1 - \mathbf{E}_2) \times \mathbf{n} = 0$$

σ_q, \mathbf{K}_s surface electric charge / current density.

Interface conditions [1] (IC) must always hold true!



Helmholtz decomposition

- If $\mathbf{F} \in \mathbb{R}^3$ well-behaving field (sufficiently smooth, rapidly decaying at $\mathbf{r} \rightarrow \infty$) then [1] :

$$\mathbf{F} = \mathbf{F}_T + \mathbf{F}_L$$

\mathbf{F}_T curling, non diverging (i.e. $\nabla \cdot \mathbf{F}_T = 0$)

\mathbf{F}_L diverging, non curling (i.e. $\nabla \times \mathbf{F}_L = 0$)

- Vice-versa, given a scalar field $\phi \in \mathbb{R}^3$ and a solenoidal vector field $\mathbf{A} \in \mathbb{R}^3$, both well behaving, then it exists a field \mathbf{F} such that

$$\nabla \cdot \mathbf{F} = \phi, \quad \nabla \times \mathbf{F} = \mathbf{A}$$

→ \mathbf{F} determined by knowing its curl and divergence

- Curiosity: What if $\nabla \cdot \mathbf{F} = 0, \nabla \times \mathbf{F} = 0$?

$$\nabla \times \nabla \phi = 0 \rightarrow \mathbf{F} = -\nabla \phi$$

$$\nabla \cdot (-\nabla \phi) = 0 \rightarrow \nabla^2 \phi = 0$$

- Laplacian (relaxed) nature of the field
- “Hidden” in both \mathbf{F}_T and \mathbf{F}_L , and determined only by BC.
- Caveat: A non-curling, non-diverging field can still contain energy!





Potentials – Gauge invariance

B, E fields fulfil Helmholtz criteria, rewritten as

$$\mathbf{B} = \nabla \times \mathbf{A}_B - \nabla \phi_B - \partial_t \mathbf{A}'_B$$

$$\mathbf{E} = \nabla \times \mathbf{A}_E - \nabla \phi_E - \partial_t \mathbf{A}'_E$$

Potentials gauging (fixing the “integration constants”):

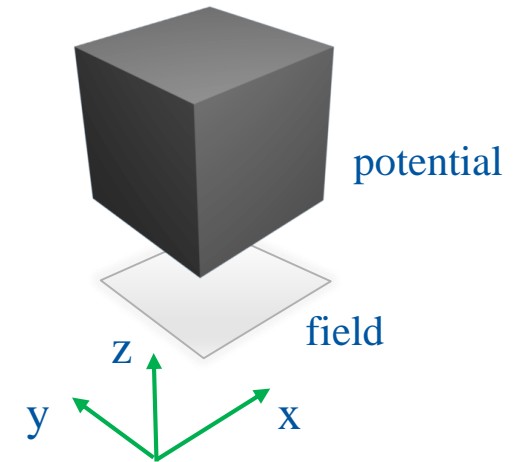
- 6 new equations (traditionally $\mathbf{A}_E = 0, \mathbf{A}_B = \mathbf{A}'_E$)
- BC for ϕ on $\Gamma, \nabla \cdot$ for \mathbf{A} on Ω
- (IC reformulated in terms of potentials)

Any gauge is fine! (though some are “numerically” better)

e.g. classic Coulomb gauge $\nabla \cdot \mathbf{A}_B = 0, \phi_B = 0$

- Why potentials? (*)
 - More variables, equations, conditions
 - IC: **B, D** tangent and **H, E** normal are discontinuous.
 - potentials continuous, discontinuities embedded in their derivative

Example:



Invariance to:

- z coordinate
- axial rotations of $\pi/2$



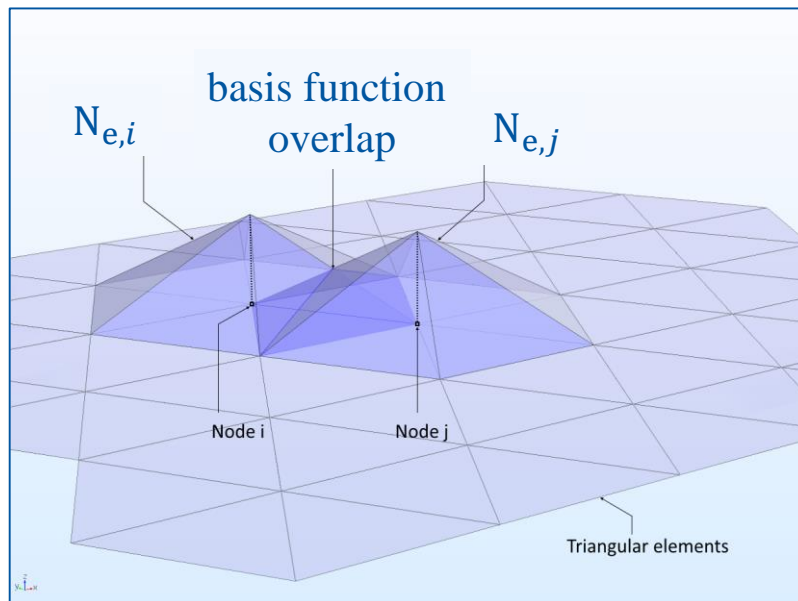
Discretization Technique

Fundamental lemma of calculus of variations [1] (variational formulation):

$$f = 0 \Leftrightarrow \int f \cdot w \, d\Omega = 0 \quad \forall w \in C_0(\mathbb{R})$$

$f = 0$ generic field equation (e.g. Laplacian)

w weighting (test) function: continuous, vanishing at infinity



Source: COMSOL blog

FEM approach (e.g.[2]):

1. $f \approx F \cdot N_e$
2. $w = N_e \rightarrow$ Galerkin method
3. We solve $\int (F \cdot N_e) \cdot N_e \, d\Omega = R$
(R =residual) looking for R_{\min}
4. Discretization (equations assembled per node)
5. Algebraic problem $[N_e] \cdot F = 0$
6. Numerical solver (Newton-Raphson)

N.B.

If $\Omega_{N_e} \rightarrow 0$, then $F \cdot N_e \rightarrow f$

02 - Hybrid T-A field formulation

Domain decomposition

Domains $\Omega_{nc}, \Omega_c \in \mathbb{R}^3$, $\Omega_{nc} : \sigma = 0$, $\Omega_c : \mu = \mu_0$
 Γ_{nc}, Γ_c as contour and $\Gamma_{nc,c}$ as interface

- Equations on Ω_{nc}

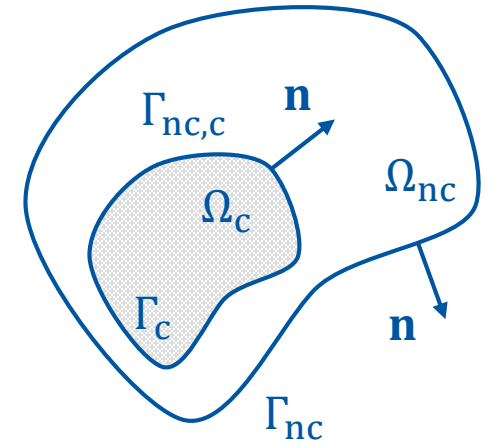
$$\begin{aligned} \rho &= 0, \mathbf{J} = \mathbf{0} && \text{(no sources)} \\ \mathbf{B} &= \nabla \times \mathbf{A} && \text{(magnetic vector potential)} \\ \mathbf{E} &= -\partial_t \mathbf{A} && \text{(Faraday law)} \\ \nabla \cdot \mathbf{A}_B &= 0, \phi_B = 0 + \phi_E = 0 && \text{(radiation gauge [1]) (*)} \end{aligned}$$

$$\begin{aligned} \nabla \times \mu^{-1} \nabla \times \mathbf{A} &= \mathbf{0} && \text{on } \Omega_{nc} \\ \mathbf{A} \times \mathbf{n} &= \mathbf{0} && \text{on } \Gamma_{nc} \end{aligned}$$

- Equations on Ω_c

$$\begin{aligned} \mathbf{H} &= \mathbf{T} - \nabla \psi && (\psi \text{ is the magnetic scalar potential [2]}) \\ \nabla \times \mathbf{T} &= \mathbf{J} && \text{(electric vector potential [3])} \\ \nabla \cdot \mathbf{T} &= \nabla^2 \psi && \text{(Gauss law)} \end{aligned}$$

$$\begin{aligned} \nabla \times \sigma^{-1} \nabla \times \mathbf{T} &= -\mu_0 \partial_t (\mathbf{T} - \nabla \psi) && \text{on } \Omega_c \\ \psi &= f(x, y, z, t) && \text{on } \Gamma_{nc} \end{aligned}$$



[1] Arfken, G. B., et al. "Mathematical methods for physicists." (1999).

[2] Biro, O., et al. "On the use of the magnetic vector potential in the finite-element analysis of three-dimensional eddy currents." *IEEE Trans Mag* (1989).

[3] Carpenter, C. J. "Comparison of alternative formulations of 3-dimensional magnetic-field and eddy-current problems at power frequencies." *Proceedings of the Institution of Electrical Engineers*. 1977.

(*) Unclear naming, among the others: Coulomb-Weyl, Coulomb-Hamilton. Coulomb-Gibbs, Coulomb-temporal

Thin Strip approximation

$$\Omega_c \rightarrow \Gamma_c \in \mathbb{R}^2, \mathbf{J} \cdot \mathbf{n} = 0, \mathbf{J} \in \mathbb{R}^2$$

$\psi = 0$ on Γ_{nc} (gauge choice, ψ on a surface)

\mathbf{T} as stream function, $\mathbf{T} = T \mathbf{n}$:

$$\nabla \times \mathbf{T} = \nabla \times (T \mathbf{n}) = T (\nabla \times \mathbf{n}) + \nabla T \times \mathbf{n}$$

but $\nabla \times \mathbf{n} = 0$ (true for any surface unit normal vector)

$$\text{hence } \nabla \times \mathbf{T} = \nabla T \times \mathbf{n} \quad (*)$$

- Equations for Γ_c

$$\nabla \times \sigma^{-1}(\nabla T \times \mathbf{n}) = -\mu_0 \partial_t (T \mathbf{n})$$

$$\nabla \times \mathbf{T} = \mathbf{J}$$

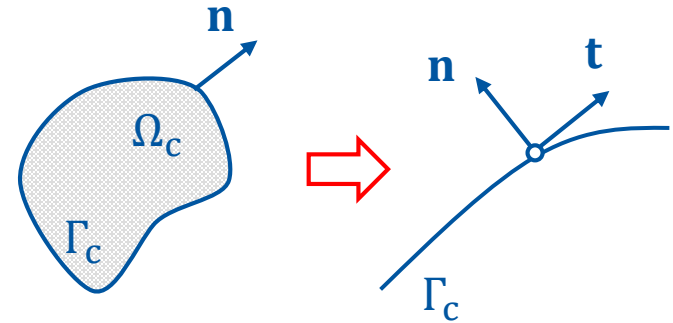
$$\nabla \cdot \mathbf{T} = 0 \quad \text{remember Helmholtz, well posed field}$$

- IC on $\Gamma_{nc,c}$

Formulations “welded” via the continuity of $\mathbf{B} \cdot \mathbf{n}$ and $\mathbf{E} \times \mathbf{n}$, in terms of T and \mathbf{A}

$$\mu_0 \partial_t T \mathbf{n} = \partial_t (\mathbf{B} \cdot \mathbf{n}) \mathbf{n} = \partial_t (\nabla \times \mathbf{A} \cdot \mathbf{n}) \mathbf{n}$$

$$\sigma^{-1}(\nabla T \times \mathbf{n}) = \mathbf{E} \times \mathbf{n} = -\partial_t \mathbf{A} \times \mathbf{n}$$



(*) Carpenter (1977) relied on $\nabla \times \mathbf{T}$.

Rodger (1988) introduced $\partial_t(\nabla T \times \mathbf{n})$, where ∂_t brings symmetry to the weak form.

Biro (1992) used $\partial_t(\nabla \times T \mathbf{n})$, a hybrid version of Carpenter- Rodger

Zhang (2017) followed Carpenter with $\nabla \times \mathbf{T}$, but he claimed no IC are needed in his approach.

External Source: Current Excitation

$$\Omega_c \rightarrow \Gamma_c \in \mathbb{R}^2, \mathbf{J} \cdot \mathbf{n} = 0, \mathbf{J} \in \mathbb{R}^2$$

External current excitation i_s . One can show that [1]:

$$\begin{aligned} i_s &= \int \mathbf{J} \cdot \mathbf{z} \, d\Omega_c \\ &= \int \nabla \times \mathbf{T} \cdot \mathbf{z} \, d\Omega_c \text{ (Stokes)} \\ &= \int \mathbf{T} \cdot \mathbf{t} \, d\Gamma_c \\ &= \int (\mathbf{Tn}) \cdot \mathbf{t} \, d\Gamma_c \quad \text{(stream function)} \end{aligned}$$

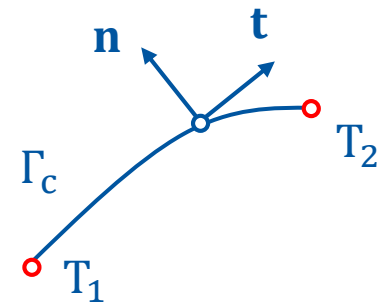
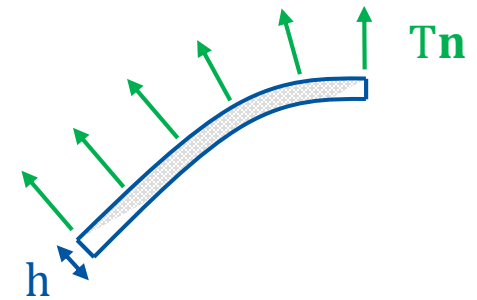
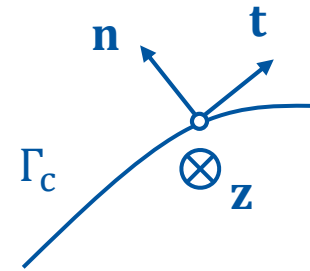
Now, $(\mathbf{Tn}) \cdot \mathbf{t} = 0 \quad \forall$ point, except edges

$$\int (\mathbf{Tn}) \cdot \mathbf{t} \, d\Gamma_c = h(T_1 - T_2)$$

Two Dirichlet conditions per tape:

$$\begin{aligned} T_1 &= \alpha, \alpha \in \mathbb{R} \\ T_2 &= i_s/h - T_1 \end{aligned}$$

Stokes + thin strip allows to
Surface integral \rightarrow two scalar, linear equations



To Sum Up...

Hybrid T-A form – Thin Strip Approximation
 $\Omega_c \rightarrow \Gamma_c \in \mathbb{R}^2, \mathbf{J} \cdot \mathbf{n} = \mathbf{0}, \mathbf{J} \in \mathbb{R}^2$

- Equations on Ω_{nc}

$$\nabla \times \mu^{-1} \nabla \times \mathbf{A} = \mathbf{0}$$

$$\mathbf{A} \times \mathbf{n} = \mathbf{0} \text{ on } \Gamma_{nc} \text{ (PEW)}$$

with gauge

$$\nabla \cdot \mathbf{A} = 0, \phi = 0$$
- Equations on Γ_c

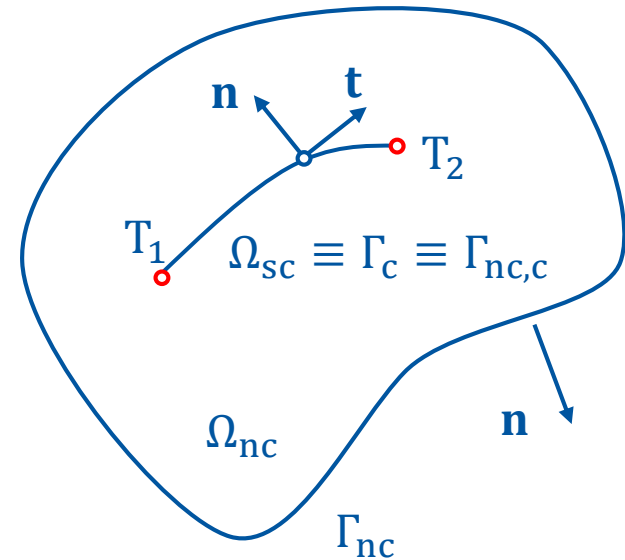
$$\nabla \times \sigma^{-1} (\nabla T \times \mathbf{n}) = -\mu_0 \partial_t T \mathbf{n}$$

with gauge

$$\nabla \cdot \mathbf{T} = 0, \psi = 0$$
- Equations on interface $\Gamma_{nc,c}$

$$\mu_0 \partial_t T \mathbf{n} = \partial_t (\nabla \times \mathbf{A} \cdot \mathbf{n}) \mathbf{n}$$

$$\nabla T \times \mathbf{n} = -\sigma \partial_t \mathbf{A} \times \mathbf{n}$$
- External source
$$i_{\text{source}} = h(T_1 - T_2)$$



Compatible with the STEAM co-sim framework [1]:

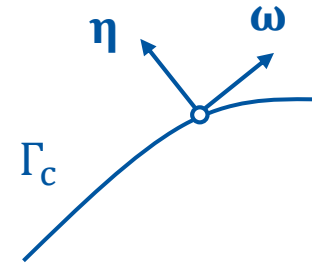
- Current-driven, via i_{source}
- Flux linkage as $\varphi(\mathbf{A})$

03 – Numerical Implementation

Formulation in 2D

The general T-A form is characterized for a 2D domain

Local reference frame (ω, η) on $\Gamma_c \rightarrow T: T(\omega)$



Faraday law:

$$\nabla \times \sigma^{-1}(\nabla T \times \boldsymbol{\eta}) = -\mu_0 \partial_t T \boldsymbol{\eta}$$

Vector calculus identity:

$$\nabla \times (\mathbf{F} \times \mathbf{G}) = \mathbf{F}(\nabla \cdot \mathbf{G}) - \mathbf{G}(\nabla \cdot \mathbf{F}) + (\mathbf{G} \cdot \nabla)\mathbf{F} - (\mathbf{F} \cdot \nabla)\mathbf{G}$$

Faraday law, left hand part:

$$\sigma^{-1} \nabla T (\nabla \cdot \boldsymbol{\eta}) - \boldsymbol{\eta} (\nabla \cdot \sigma^{-1} \nabla T) + (\boldsymbol{\eta} \cdot \nabla) \sigma^{-1} \nabla T - (\sigma^{-1} \nabla T \cdot \nabla) \boldsymbol{\eta}$$

- | | |
|--|--|
| 1) $\nabla \cdot \boldsymbol{\eta} = 0$ | true for any surface unit normal vector |
| 2) $(\boldsymbol{\eta} \cdot \nabla) \sigma^{-1} \nabla T = 0$ | $T \neq T(\boldsymbol{\eta})$ |
| 4) $(\sigma^{-1} \nabla T \cdot \nabla) \boldsymbol{\eta} = 0$ | $\boldsymbol{\eta} \neq \boldsymbol{\eta}(\omega)$ |

$$-\boldsymbol{\eta} (\nabla \cdot \sigma^{-1} \nabla T) = -\mu_0 \partial_t T \boldsymbol{\eta}$$

Elliptic partial differential equation of type $\nabla \cdot \alpha \nabla u = f$

The weak form is easily implementable in a numerical solver

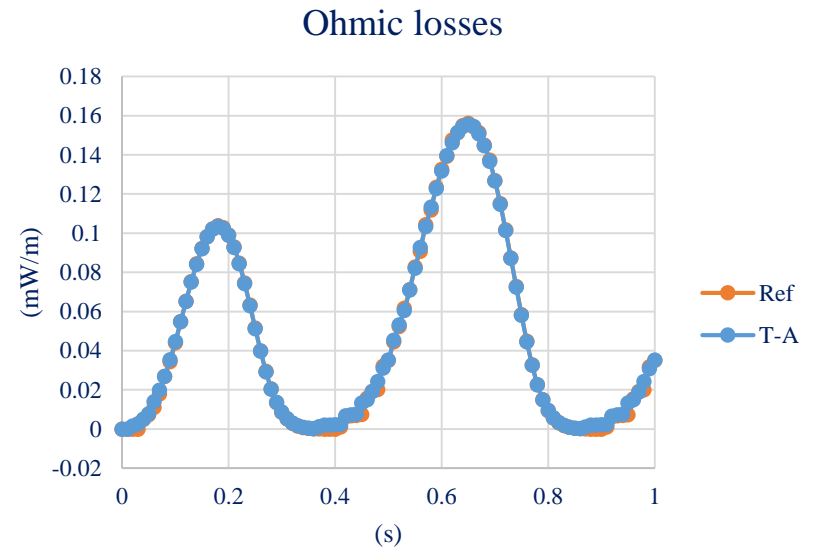
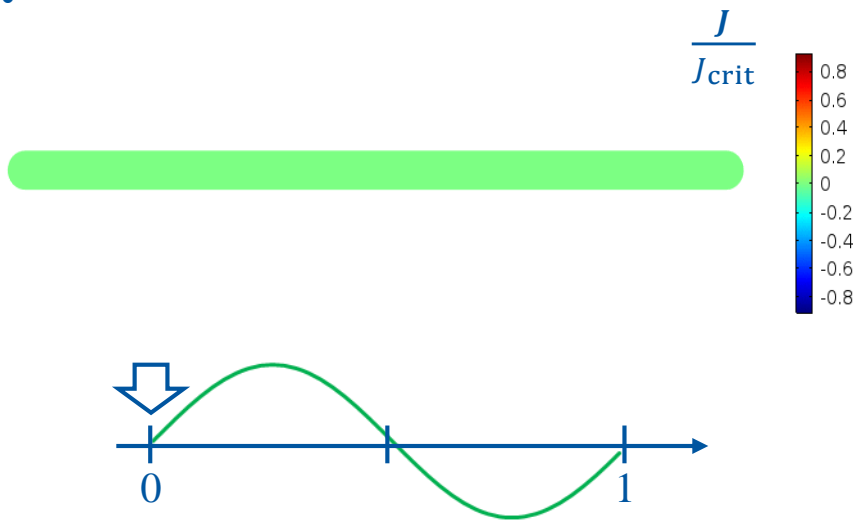
Validation

Active community in the field of HTS modeling



Reference models are available. Here, [Link](#) is used for crosscheck

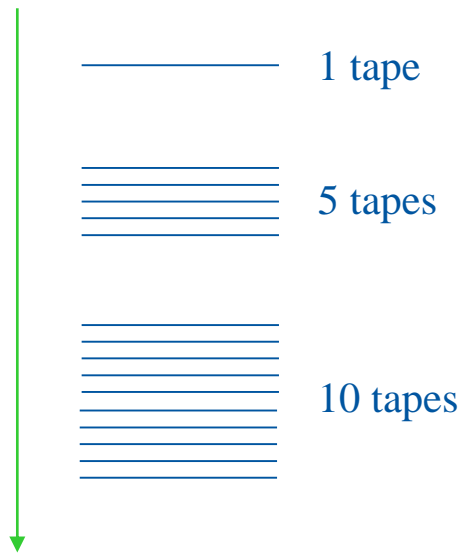
- Single HTS tape in self-field
- Source: $I_s = I_0 \sin(2\pi t)$, $I_0 = 0.5I_{crit}$ $t \in [0; 1]$
- $2e^3$ unknowns, simulation time 9 s
-



Scalability: H vs T-A Form

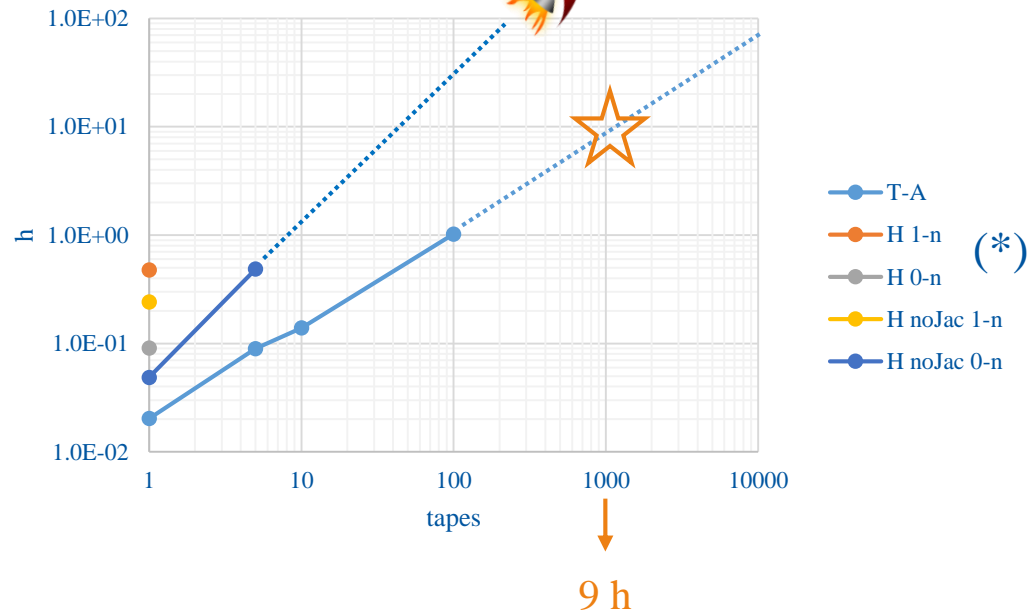
Forecasts on expected computational time (Disclaimer: forecasts may not match reality!)

Same physics



Increased computational cost

Computational Time



Results of qualitative analysis:

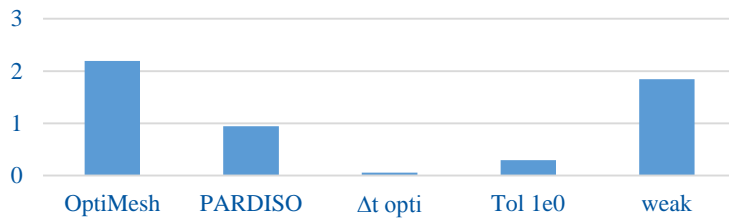
- H-form: well...
- T-A form: humm...

Scalability: T-A Form Optimization

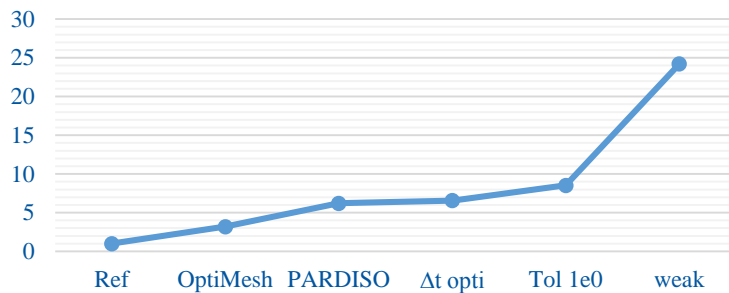
Optimization implemented on:

1. Mesh - OptiMesh
2. Solver - PARDISO, Δt opti, tol $1e^0$
3. Formulation - Weak form b-PDE

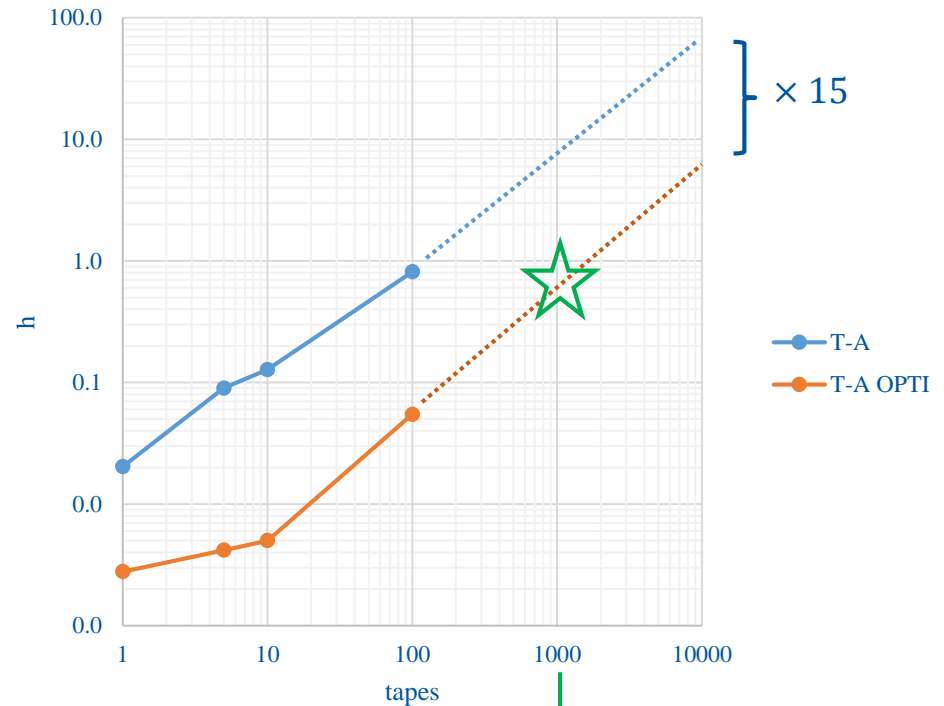
Incremental Speed-up



Cumulative Speed-up



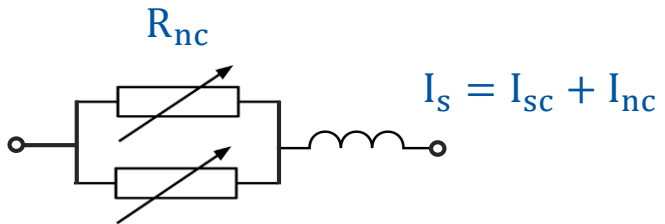
Computational Time



0.5 h
Way better!

Current Sharing in Tape

In HTS, the Stekly approximation [1] is no longer valid [2] (slow quench propagation):

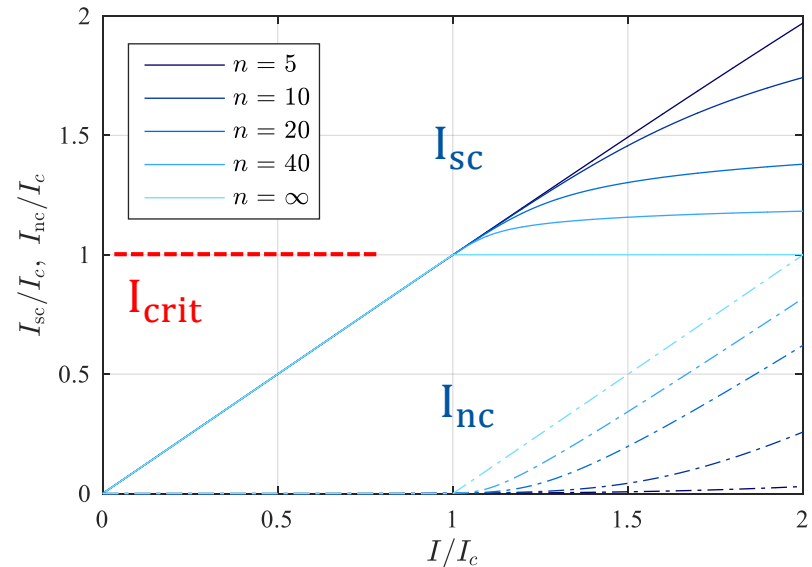


$$R_{sc}(I_{sc}) = \frac{\ell_{sc}}{\Omega_{sc}} \int \frac{E_c}{J_c} \left(\frac{J}{J_c} \right)^{n-1} d\Omega$$

$$I_{sc} = \frac{R_{nc}}{R_{sc}(I_{sc}) + R_{nc}} (I_{sc} + I_{nc})$$

$$I_{nc} = \frac{R_{sc}(I_{sc})}{R_{sc}(I_{sc}) + R_{nc}} (I_{sc} + I_{nc})$$

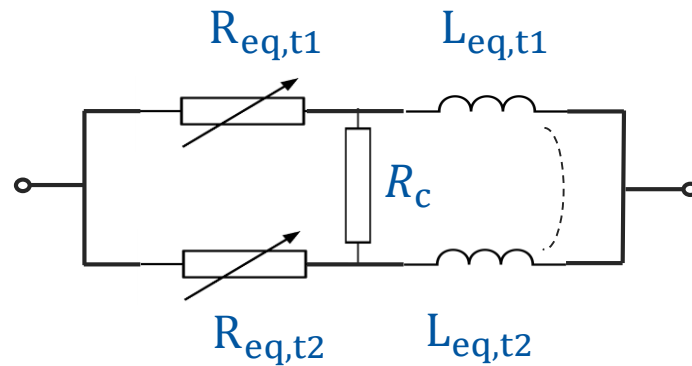
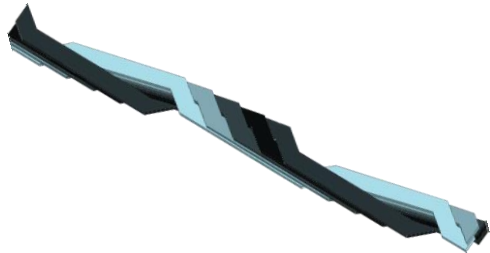
- Stekly $\approx n = \infty$
- $n_{HTS} \approx 20$



Implicit equations \rightarrow Algebraic constraints in the solver

Current Sharing in Roebel Cable

- Roebel cable (only 2 tapes represented in the network model)



$$I_s = \sum_{i=1}^n I_{ti}$$

$$I_{ti} = I_{sc,i} + I_{nc,i}$$

Full transposition assumption:

- $R_{eq,t1} = R_{eq,t2} = R_{eq}$
- $L_{eq,t1} = L_{eq,t2} = L_{eq}$

No current redistribution, (as $R_c = +\infty$), conservative
Even distribution of I_s between the tapes

Should be good for:

- Localized quenches (small normal zone, slow propagation velocity)
- Homogeneously distributed losses (e.g. quench-back)

Rationale (cont'd)

- 20+ Tesla dipoles for future high-energy particle accelerators
- Simulation of the electrodynamics in HTS tapes and cables (then magnets, and circuits)

Main challenges

- 1) Multiscale model
 - Domain decomposition
 - Thin strip approximation, model order reduction
- 2) HTS resistivity
 - \mathbf{T} vector potential for conductive domains
- 3) Current sharing regime in tape
 - Algebraic constraints in the solver
- 4) Complex geometries
 - Full transposition assumption

04 – Applications

Solenoid

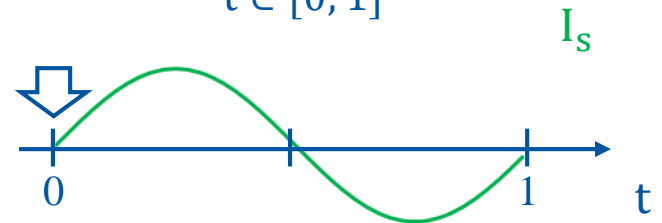
$$I_s = I_0 \sin(2\pi t)$$

$$I_0 = 0.8 I_{\text{crit}}$$

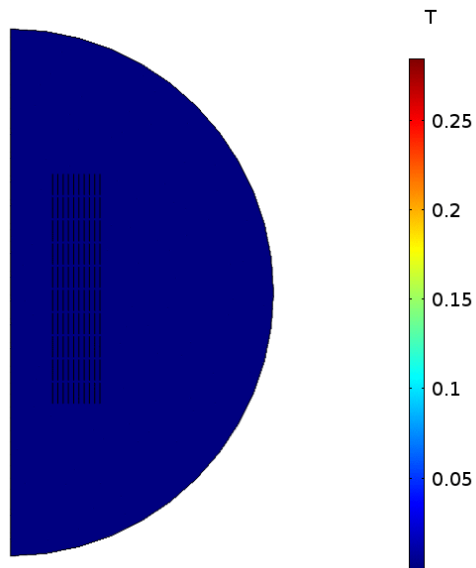
$$t \in [0; 1]$$

Model features

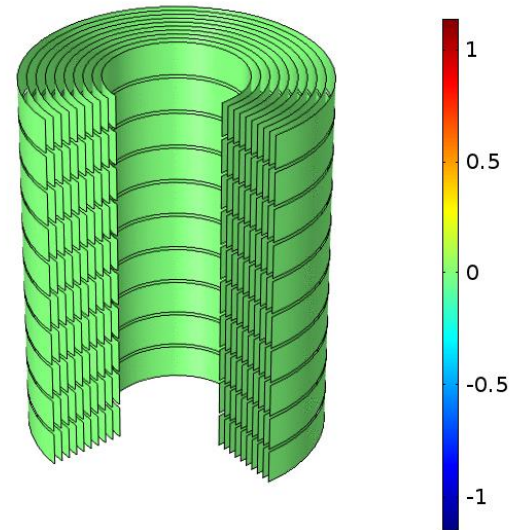
- 2D - Axisymmetric
- 100 tapes, aspect ratio $1e^4$
- $J_{\text{crit},0} = 1e^{10} [\text{Am}^{-2}]$
- $20e^3$ unknowns



Magnetic flux density (T)



Current density (p.u.)

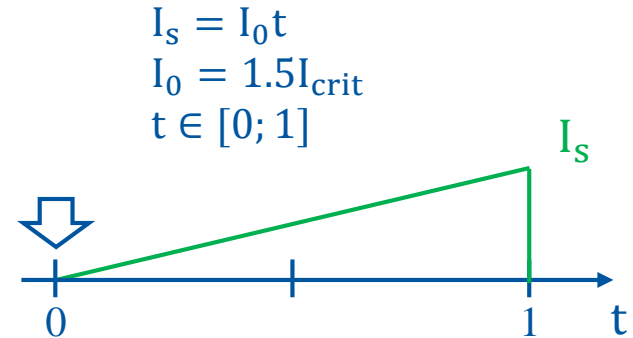


Simulation time: 200 s

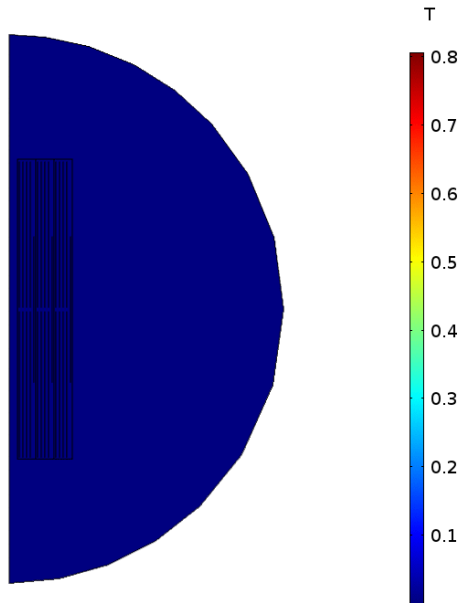
Roebel cable

Model features

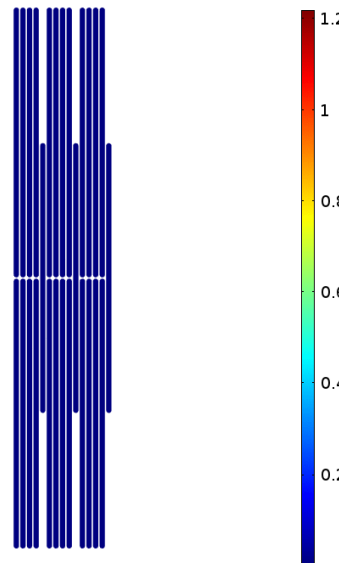
- 2D
- 3 cables (27 tapes), aspect ratio $1e^4$
- $J_{crit,0} = 1e^{10} [Am^{-2}]$
- $12e^3$ unknowns



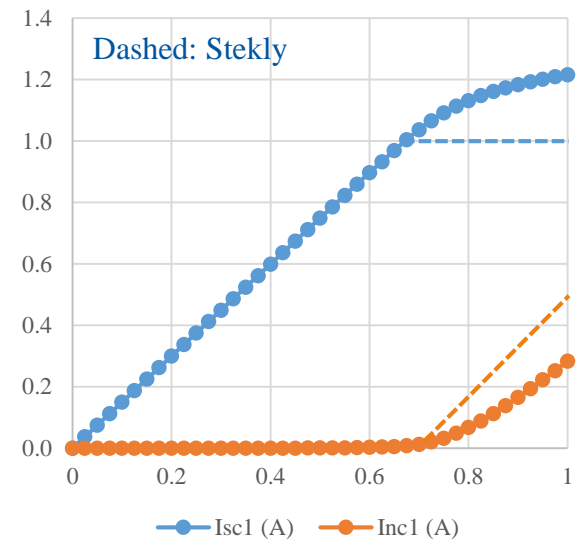
Magnetic flux density (T)



Current density (p.u.)



Current (p.u.) - tape 01



Hybrid T-A: Summary and Outlook

Formulation

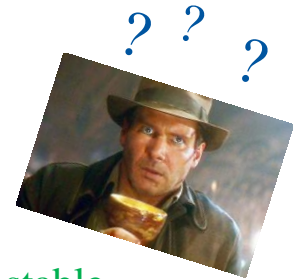
1. Field and interface equations
2. Thin line approximation

Implementation

1. \mathbb{R}^2 domain
2. Current sharing regime
3. Applications (solenoids, Roebel cables)



- Numerically stable
- Computationally efficient
- Reasonably simple



What is next

- Rigorous mathematical assessment (e.g. de Rahm currents)
- HTS material database
- Thermal equations
- Crosscheck with other codes
- 2D model of FRESKA2 + FEATHER2 insert
- FEM 2 LUMPED modeling, for circuital analysis
- Co-simulation interface
- Automatic model generation (SIGMA-HTS module)
- 3D modelling (equations are in place)
- ...

Thank you
for your attention!



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Annex 01 – A form

Domain decomposition

Domains $\Omega_{nc}, \Omega_c \in \mathbb{R}^3$, $\Omega_{nc} : \sigma = 0$, $\Omega_c : \mu = \mu_0$
 Γ_{nc}, Γ_c as contour and $\Gamma_{nc,c}$ as interface

$$\mathbf{B} = \nabla \times \mathbf{A} \quad (\text{magnetic vector potential})$$

$$\mathbf{E} = -\partial_t \mathbf{A} \quad (\text{Faraday law})$$

$$\nabla \cdot \mathbf{A}_B = 0, \quad \phi_B = 0 + \phi_E = 0 \quad (\text{radiation gauge})$$

- Equations on Ω_{nc}

$$\rho = 0, \quad \mathbf{J} = \mathbf{0} \quad (\text{no sources})$$

$$\nabla \times \mu^{-1} \nabla \times \mathbf{A} = \mathbf{0} \quad \text{on } \Omega_{nc}$$

$$\mathbf{A} \times \mathbf{n} = 0 \quad \text{PEW on } \Gamma_{nc}$$

- Equations on Ω_c

$$\rho = 0, \quad \mathbf{J} = \sigma \mathbf{E}$$

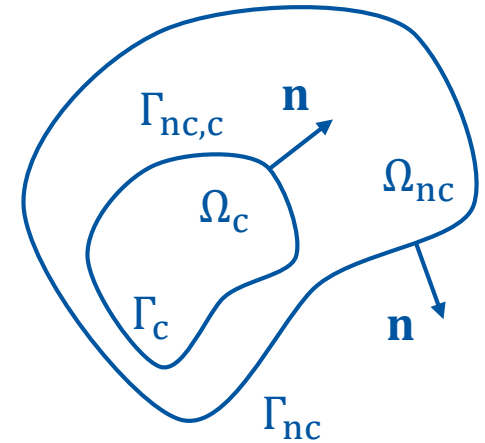
$$\nabla^2 \mathbf{A} = \mu_0 \sigma \partial_t \mathbf{A} \quad \text{on } \Omega_c$$

- Equations on interface $\Gamma_{nc,c}$

$$(\nabla \times \mathbf{A}_1 - \nabla \times \mathbf{A}_2) \cdot \mathbf{n} = 0$$

$$(\mu_1^{-1} \nabla \times \mathbf{A}_1 - \mu_2^{-1} \nabla \times \mathbf{A}_2) \times \mathbf{n} = \mathbf{0}$$

$$\partial_t (\mathbf{A}_1 - \mathbf{A}_2) \times \mathbf{n} = 0$$



A form – Thin Line Approximation

$$\Omega_c \rightarrow \Gamma_c \in \mathbb{R}^2, \mathbf{J} \cdot \mathbf{n} = 0, \mathbf{J} \in \mathbb{R}^2$$

- Equations on Ω_{nc}

$$\nabla \times \mu^{-1} \nabla \times \mathbf{A} = \mathbf{0}$$

$$\mathbf{A} \times \mathbf{n} = \mathbf{0} \text{ PEW on } \Gamma_{nc}$$
- Equations on Γ_c

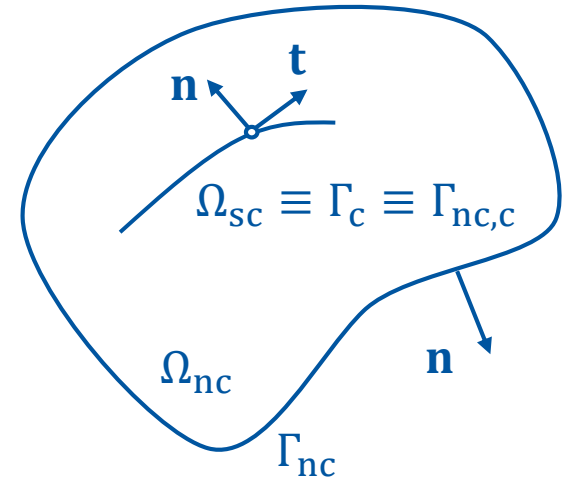
$$\mathbf{A} = A\mathbf{t}$$

$$\nabla^2(A\mathbf{t}) = \mu_0 \sigma \partial_t(A\mathbf{t}) \quad \text{on } \Omega_c$$
- Equations on interface $\Gamma_{nc,c}$

$$(\nabla \times \mathbf{A}_1 - \nabla \times \mathbf{A}_2) \cdot \mathbf{n} = 0$$

$$(\mu_1^{-1} \nabla \times \mathbf{A}_1 - \mu_2^{-1} \nabla \times \mathbf{A}_2) \times \mathbf{n} = h\mathbf{J}$$

$$\partial_t(\mathbf{A}_1 - \mathbf{A}_2) \times \mathbf{n} = 0$$
- Field source
$$i_{\text{source}} = h \int \sigma \partial_t(A\mathbf{t}) d\Gamma_c$$



Annex 02 – H form

Domain decomposition

Domains $\Omega_{nc}, \Omega_c \in \mathbb{R}^3$, $\Omega_{nc} : \sigma = 0$, $\Omega_c : \mu = \mu_0$
 Γ_{nc}, Γ_c as contour and $\Gamma_{nc,c}$ as interface

- Equations on Ω_{nc}

$$\begin{aligned} \rho &= 0, \mathbf{J} = \mathbf{0} && \text{(no sources)} \\ \nabla \times \sigma \nabla \times \mathbf{H} - \mu \partial_t \mathbf{H} &= \mathbf{0} && \text{on } \Omega_{nc} \\ \nabla \cdot (\mu \mathbf{H}) &= 0 && \text{on } \Omega_{nc} \\ \mathbf{E} \times \mathbf{n} &= 0 && \text{PEW on } \Gamma_{nc} \end{aligned}$$

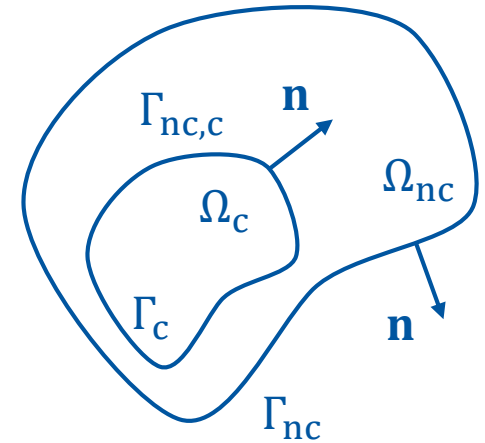
N.B. numerically, $\sigma \neq 0 \forall \Omega$

- Equations on Ω_c

$$\begin{aligned} \rho &= 0, \mathbf{J} = \nabla \times \mathbf{H} \\ \nabla \times \sigma \nabla \times \mathbf{H} - \mu \partial_t \mathbf{H} &= \mathbf{0} && \text{on } \Omega_c \\ \nabla \cdot (\mu \mathbf{H}) &= 0 && \text{on } \Omega_c \end{aligned}$$

- Equations on interface $\Gamma_{nc,c}$

$$\begin{aligned} (\mu_1 \mathbf{H}_1 - \mu_2 \mathbf{H}_2) \cdot \mathbf{n} &= 0 \\ (\mathbf{H}_1 - \mathbf{H}_2) \times \mathbf{n} &= h \mathbf{J} \\ (\sigma_1 \nabla \times \mathbf{H}_1 - \sigma_2 \nabla \times \mathbf{H}_2) \times \mathbf{n} &= 0 \end{aligned}$$



H form – Thin Line Approximation

$$\Omega_c \rightarrow \Gamma_c \in \mathbb{R}^2, \mathbf{J} \cdot \mathbf{n} = 0, \mathbf{J} \in \mathbb{R}^2$$

- Equations on Ω_{nc}

$$\rho = 0, \mathbf{J} = \mathbf{0} \quad (\text{no sources})$$

$$\nabla \times \sigma \nabla \times \mathbf{H} - \mu \partial_t \mathbf{H} = \mathbf{0} \quad \text{on } \Omega_{nc}$$

$$\nabla \cdot (\mu \mathbf{H}) = 0 \quad \text{on } \Omega_{nc}$$

$$\mathbf{E} \times \mathbf{n} = 0 \quad \text{PEW on } \Gamma_{nc}$$

N.B. numerically, $\sigma \neq 0 \forall \Omega$

- Equations on Γ_c

$$\rho = 0, \mathbf{J} = \nabla \times \mathbf{H}$$

$$\nabla \times \sigma \nabla \times \mathbf{H} - \mu \partial_t \mathbf{H} = \mathbf{0} \quad \text{on } \Gamma_c$$

$$\nabla \cdot (\mu \mathbf{H}) = 0 \quad \text{on } \Gamma_c$$

- Interface $\Gamma_{nc,c}$

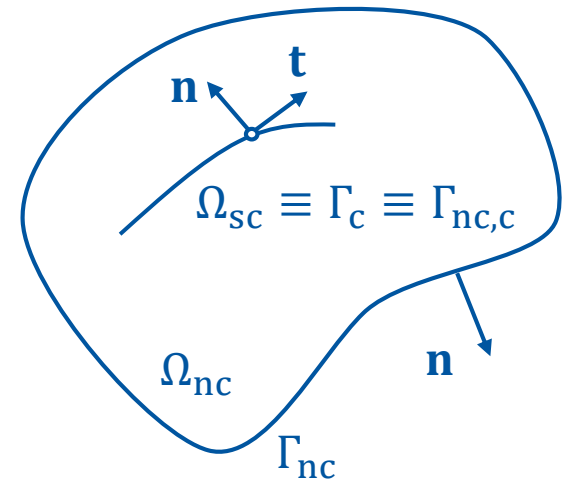
$$(\mu_1 \mathbf{H}_1 - \mu_2 \mathbf{H}_2) \cdot \mathbf{n} = 0$$

$$(\mathbf{H}_1 - \mathbf{H}_2) \times \mathbf{n} = h\mathbf{J}$$

$$(\sigma_1 \nabla \times \mathbf{H}_1 - \sigma_2 \nabla \times \mathbf{H}_2) \times \mathbf{n} = 0$$

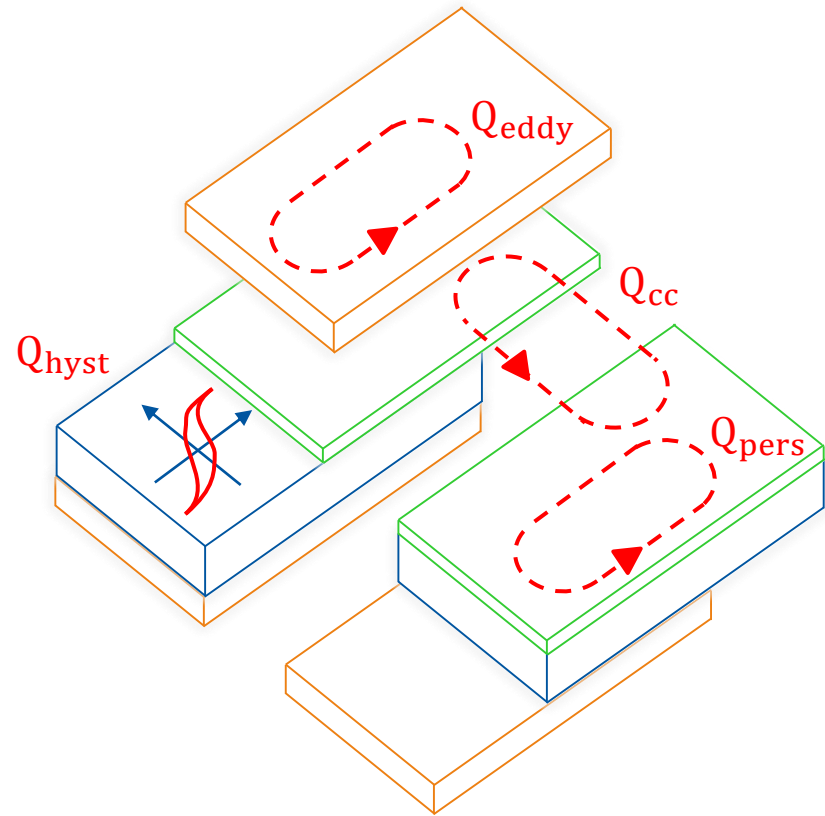
- Field source

$$i_{\text{source}} = \int \nabla \times \mathbf{H} \, d\Gamma_c$$

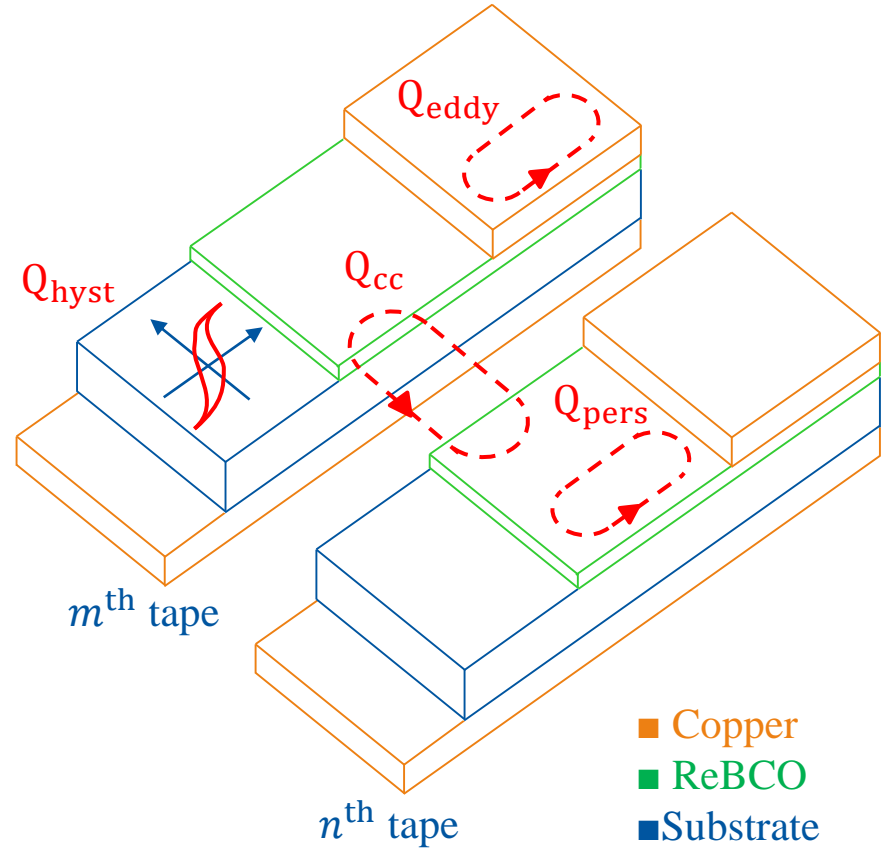


Incompatible conditions:
on Γ_c , \mathbf{H} cannot be both
divergence-free and discontinuous!

Backup Slides



■ Copper ■ ReBCO ■ Substrate



■ Copper
■ ReBCO
■ Substrate