Hello/Goodbye FPGA

3rd Patatrack Hackathon 25/05/18 Final Scram Sioni Summers, Lukas Arnold, Shahzad Muzaffar

Aims & Overview

- Newest Intel devices have the best floating point performance of any FPGAs
- OpenCL promises fast kernel design, convenient packaging of compute code with host-FPGA interfaces
- Aimed to execute OpenCL code on a Intel FPGA, called from CMSSW
- → Towards porting real computation in a heterogeneous future
- Wanted to gain experience with these devices and this way of designing

Challenges

- Sioni:
 - New to Intel FPGAs and OpenCL
- Lukas:
 - New to OpenCL and CMSSW
- Shahzad
 - Never worked with FPGAs
- Working with FPGAs is slow, what can we achieve in 4 days?
- We had never met before!

How we worked

- Split work between host-side and device-side
 - Lukas on device-side
 - Sioni on host-side
- Shahzad on the compile flow
- All:
 - Worked through Intel's example codes

What we achieved

Begin processing the 1st record. Run 1, Event 1402, LumiSection 29 on stream 3 at 25-May-2018 14:32:45.430 CEST Thread #2: Hello from Altera's OpenCL Compiler!

- 'Hello world' from CMSSW
- 'scram b' compiles OpenCL kernels for Intel FPGAs and C++ with OpenCL wrappers
- Designed kernels for Kalman Filter state update
 - Compiled for Hardware
 - Standalone testing

<bin name="hello_fpga" file="hello_world/host/src/main.cpp common/src/AOCLUtils/*.cpp">
#Added OpenCL dependency
<use name="opencl"/>
#Set OpenCL Device file path
<flags OPENCL_DEVICE_FILES="hello_world/device/hello_world.cl"/>
#To get the example compiled in cmssw env
<flags REM_CXXFLAGS="-Werror=unused-but-set-variable"/>
#Add hello_world specific include path
<include_path path="common/inc"/>
</bin>



What we achieved

• Started evaluating compiled kernels

- Thinking about resource usage, data flow

incureport (source view)						kalman_kernels.cl		
(area utilization values are estimated) Notation <i>file:X</i> > <i>file:Y</i> indicates a function call on line	X was inlined using code	e on line Y.				3 4 5 ~ {	global float *restrict r_out)	
	ALUTs	FFs	RAMs	DSPs	Details	<pre>6 // equivalent to 7 // r -= rMeas; 8 // get index of</pre>	the work item	
• Static Partition	107600	215200	326	74		9 //int index = ge 10	et_global_id(θ);	
• Kernel System (Logic: 31%)	124771 (17%)	235222 (16%)	333 (14%)	115 (8%)		12 - for (int i = 0; 13 r_out[i] = 0	i < 2; i++) { r[i] - rMeas[i];	
Board interface	107600	215200	326	74	• Platform i	14 } 15 } 16		
♥ matrix_add	1963 (0%)	2154 (0%)	0 (0%)	4 (0%)	• Number of	17kernel void matrix 18g ¹	x_add(global const float *V, lobal const float *VMeas,	
Data control overhead	Θ	Θ	Θ	Θ	• State + Fe	20 21 - {)	
Function overhead	1570	1505	Θ	Θ	• Kernel dis	22 // equivalent to 23 // SMatDD R = V + V/ 24 + for (int i = 0;	Meas; i < 2; i++) {	
✓ kalman_kernels.cl:26	393	649	Θ	4		25 - for (int j 26 R[i*2+j	= 0; j<2; j+) {] = V[i*2+j] + VMeas[i*2+j];	
State	384	384	Θ	Θ		28 } 29 }		
Hardened Floating-Point Add(x4)	Θ	Θ	Θ	4		30 31 32kernel void matri:	x_invert(global const float *R,	
Load(x2)	8	264	Θ	Θ		33 34 35 - (global float *restrict Rinv)	
Store	1	1	Θ	Θ		36 // equivalent to 37 // bool ok = inverti	PosDefMatrix(R);	
♥ matrix_invert	2192 (0%)	2463 (0%)	5 (0%)	11 (1%)	• Number of	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	0]"R[3]-R[1]"R[2]); [3]; -R[1]);	
Data control overhead	Θ	Θ	Θ	Θ	• State + Fe	41 Rinv[2] = c * (- 42 Rinv[3] = c * R	-R[2]); [0];	
Function overhead	1570	1505	Θ	Θ	• Kernel dis	44 // get index of 45 //int index = get	the work item et_global_id(θ);	
<pre>kalman_kernels.cl:38</pre>	413	765	5	7		46 } 47 48 kernel void matri:	x project(
kalman karnala al.20	48	48	Θ	1		49g 50g	lobal const float *R, lobal float *restrict K	

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What we achieved

- Started evaluating compiled kernels
 - Thinking about resource usage, data flow



What we learned

- Lukas
 - Some OpenCL (by designing some kernels), CMSSW, tracking
- Sioni
 - Some OpenCL and the C++ Wrapper (that it's a bit ugly)
- Shahzad
 - About FPGAs, Intel's FPGA tools, and running them!
- All
 - Intel OpenCL FPGA compiler is pretty slow... (~3 hrs for a design that adds 2 numbers)

The future...

- We want to continue working together with these devices
- Towards a real algorithm (Kalman Filter)
- Tighten the integration with CMSSW

• Thanks to all the organisers!