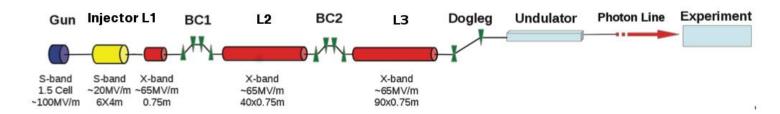
# RF design of an X-band accelerating structure for the CompactLight Project

(on the base of the work done for the EuPRAXIA@SPARC\_LAB project)

#### **XLS** Performance

Presented by G. D'Auria at Compact Light kick-off meeting on Jan. 25 2018

Parameter	Value	Unit		
Minimum Wavelength	0.1	nm		
Photons per pulse	>1012			
Pulse bandwidth	<<0.1	%		
Repetition rate	100 to 1000	Hz		
Pulse duration	<1 to 50	fs		
Undulator Period	10	mm		
K value	1.13			
Electron Energy	4.6	GeV		
Bunch Charge	<250	рС		
Normalised Emittance	<0.5	mrad		



#### Preliminary Parameters and Layout of XLS hard X-ray FEL facility

#### Beyond the state-of-the-art

Presented by G. D'Auria at Compact Light kick-off meeting on Jan. 25 2018

European XFEL (Germany)	24 MV/m	Superconducting L-band
Swiss FEL (Switzerland)	28 MV/m	Normal-conducting C-band
SACLA (Japan)	35 MV/m	Normal-conducting C-band

Examles of Linac gradients of current X-ray free electron

Parameter	Value
Length L	0.75m
Phase advance per cell $\phi$	120°
First iris aperture a1/ $\lambda$	0.15
Last iris aperture a2/ $\lambda$	0.1
First iris thickness d1	0.9mm
Last iris thickness d2	1.7mm
Fill time τ	150ns
Operational gradient G	65MV/m
Input power Pin	41.8MW

# Preliminary parameters of an optimized RF structure (x-band)

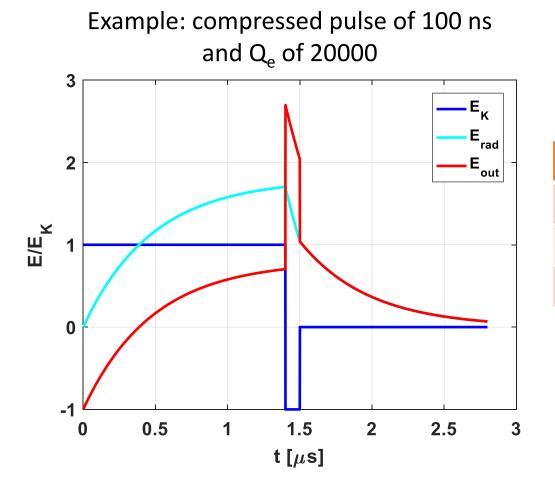
	unit	XLS X-band	SwissFEL C-band
Structures per RF unit		10	4
Klystrons per RF unit		2	1
Structure length	m	0.75	1.98
Allowed gradient	MV/m	80+	
Operating gradient	MV/m	65	27.5
Energy gain per RF unit	MV	488	203
Klystron nominal power	MW	50	50
Power in operation	MW	45	40
Klystron pulse length	μs	1.5	3
RF energy/pulse/GeV	J	277	591

#### Preliminary parameters for the X-band RF unit, compared with the C-band SwissFEL technology.

Our task in WP4 is to draw the final version of these tables. We need inputs from WP2, 5 and 6 to proceed. We will use the same approach as for the design of the X-band accelerating structure for EUPRAXIA@SPARC\_Lab

# RF design of the linac for the EuPRAXIA@SPARC\_LAB project

# SLED TYPICAL PULSE SHAPE



RF system parameters						
Frequency [GHz]	11.9942					
t <sub>k</sub> [μs]	1.5					
Q <sub>0</sub> of SLED	180000					

# Effective shunt impedance of Acc. Structure + Pulse Compressor

Time - dependent accelerating gradient :  $E_{acc}(z,t') = G(z,t') = G_0[t'-\tau(z)]g(z)$  [2]; Signal time delay :  $\tau(z) = \int_0^z \frac{dz'}{v_g(z')}$ ; Filling time :  $t_f = \tau(L_s)$ ;  $t' = t - t_1$ ;  $G_0(t') = G(z = 0, t') = \sqrt{\frac{\omega}{2} \frac{R(0)}{R}} P_{acc}(t') = \sqrt{\frac{\omega}{2} \frac{R}{R}} P_{acc}(t') = \sqrt{\frac{\omega}{2} \frac{R}{R}} P_{acc}(t = 0) \frac{E_{out}}{R}(t)$ 

$$G_{0}(t') = G(z = 0, t') = \sqrt{\frac{\omega}{v_{g}(0)}} \frac{R(0)}{Q(0)} P_{in_{s}}(t') = \sqrt{\frac{\omega}{v_{g0}}} \frac{R}{Q} P_{in_{s}}(t') = \sqrt{\frac{\omega}{v_{g0}}} \frac{R}{Q} P_{K}(t = 0) \frac{E_{out}}{E_{K}}(t)$$
[2]

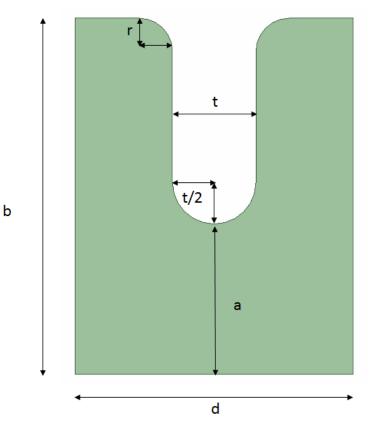
with R shunt impedance per unit lenght and Q quality factor

Attenuation per unit lenght : 
$$\alpha(z) = \frac{1}{2} \left[ \frac{1}{v_g} \frac{dv_g}{dz} - \frac{1}{R/Q} \frac{d(R/Q)}{dz} + \frac{\omega}{v_g Q} \right]$$
 [2]  

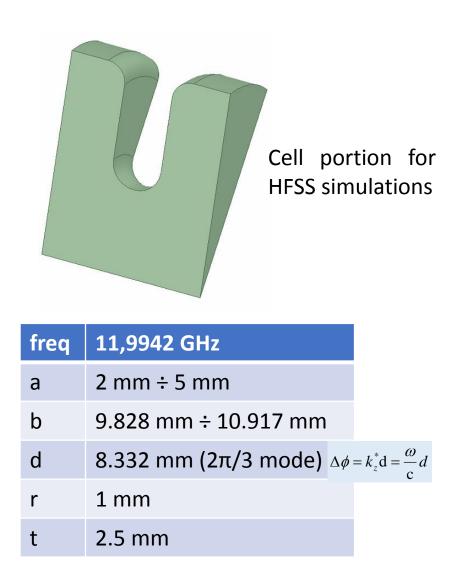
$$g(z) = e^{-\frac{1}{0}\alpha(z)dz'} = \sqrt{\frac{v_g(0)}{v_g(z)}} \sqrt{\frac{R(z)}{Q(z)} \frac{Q(0)}{R(0)}} e^{-\frac{1}{2} \int_{0}^{1} \frac{\omega}{v_g(z)} \frac{dz'}{dz'}}$$
[2]  

$$Hyp : \frac{R}{Q} \text{ constant along } z \Rightarrow g(z) = \sqrt{\frac{v_{g0}}{v_g(z)}} e^{-\frac{1}{2} \frac{\omega}{Q_0} \int_{v_g(z)}^{1} \frac{dz'}{v_g(z)}} = \sqrt{\frac{v_{g0}}{v_g(z)}} e^{-\frac{1}{2} \frac{\omega}{Q_0} \tau(z)}$$
Section attenuation :  $\tau_s = \int_{0}^{L_s} \alpha(z)dz$   
Accelerating Voltage :  $V_a = \int_{0}^{L_s} dz' G(z', t'=t_f = t_2 - t_1);$   
Effective shunt impedance:  $R_s = \frac{V_a^2}{P_K(t=0)L_s} [\Omega/m]$  [3]; PRS  
[3] Total Power :  $P_{tot} = \frac{V_{tot}\langle G \rangle}{R_s}$ 

[2] A. Lunin, V. Yakovlev, A. Grudiev, PRST-AB 14, 052001, (2011)
[3] R. B. Neal, Journal of Applied Physics, V.29, pp. 1019-1024, (1958)

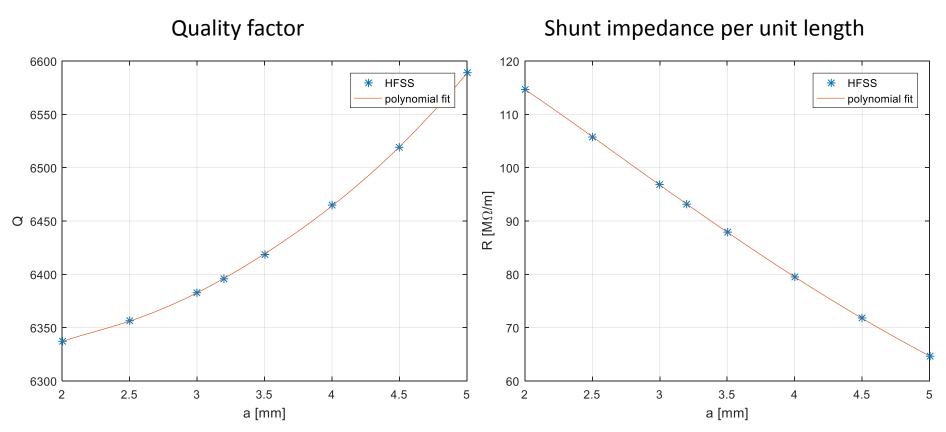


A scan of the iris radius from 2 mm to 5 mm a has been performed with HFSS in order to obtain the single cell parameters  $(\mathbf{R}, \mathbf{v}_g/\mathbf{c}, \mathbf{Q}, \mathbf{Sc}_{max}/\mathbf{E}_{acc}^2)$  as a function of the iris radius. Also the related polynomial fits have been derived.



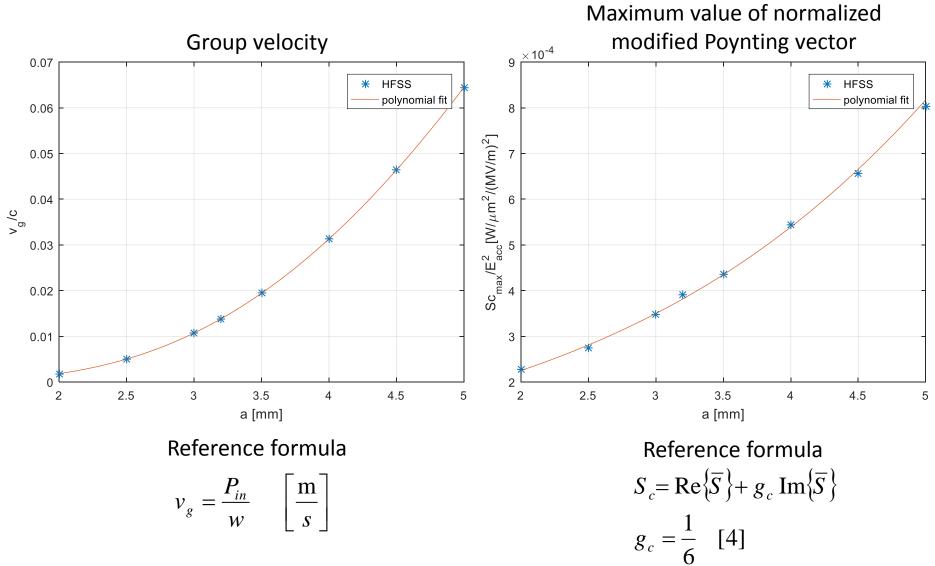
#### Single cell formulas

 $V_{z} = \left| \int_{0}^{D} E_{z} \cdot e^{j\omega_{RF} \frac{z}{c}} dz \right|$ single cell accelerating voltage [V]:  $E_{acc} = \frac{V_z}{D}$ average accelerating field in the cell  $\left[\frac{V}{m}\right]$  $P_{in} = \int_{-\infty}^{\infty} \frac{1}{2} \operatorname{Re}\left(\vec{E} \times \vec{H}^{*}\right) \cdot \hat{z} dS$ average input power (flux power) [W]  $P_{diss} = \frac{1}{2} R_s \int_{\substack{cavity \\ wall}} \left| H_{tan} \right|^2 dS$ average dissipated power in the cell [W] $R_{s} = \sqrt{\frac{\pi f_{RF} \mu_{0}}{\sigma}} = \frac{1}{\sigma \delta}$ surface resistance  $[\Omega]$  $\delta = \frac{1}{\sqrt{\pi f_{PF} \mu_0 \sigma}}$ skin depth [m]  $p_{diss} = \frac{P_{diss}}{D}$ average dissipated power per unit length  $[\frac{W}{-}]$  $W = \int_{\substack{\text{cavity}\\\text{volume}}} \left( \frac{1}{4} \varepsilon \left| E \right|^2 + \frac{1}{4} \mu \left| H \right|^2 \right) dV$ stored energy in the cell [J] $w = \frac{W}{D}$ average stored energy per unit length  $\begin{bmatrix} J \\ - \end{bmatrix}$  $Q = \omega_{RF} \frac{W}{p_{diss}}$ quality factor [arb. units]

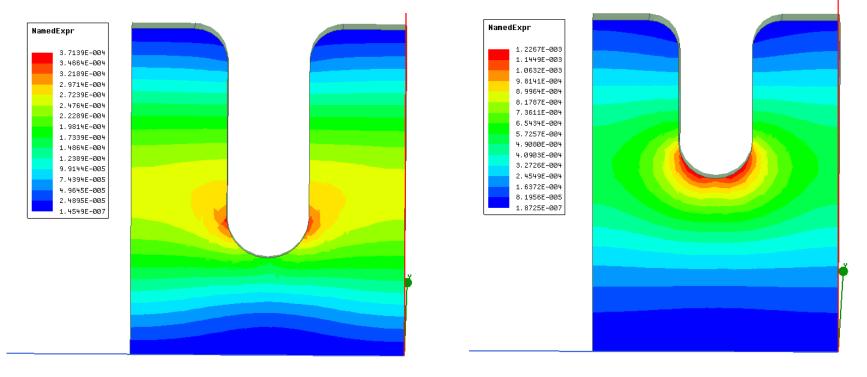


#### **Reference formula**

$$R = \frac{E_{acc}^2}{p_{diss}} \qquad \left[\frac{\Omega}{m}\right]$$



[4] A. Grudiev, S. Calatroni, and W. Wuensch, New local field quantity describing the high gradient limit of accelerating structures, PhysRevSTAB.12.102001 (2009)



#### Maximum value of normalized modified Poynting vector

a=3 mm

a=6 mm

## Single cell parameters for EUPRAXIA@SPARC\_LAB project

We do need the corresponding specification for the Compact Light project to proceed with the TW section design and optimization

WP2, WP5 -> q<sub>b</sub>, σ<sub>z</sub>

WP6 -> beam dynamics

The **average iris radius** <**a>** has been fixed equal to **3.2 mm**, according to the beam dynamics calculations and single bunch beam break up limits.

Single cell parameters (a=3.2 mm)					
b [mm]	10.139				
R [MΩ/m]	93				
v <sub>g</sub> /c [%]	1.382				
Q	6396				
Sc <sub>max</sub> /E <sup>2</sup> <sub>acc</sub> [A/V]	3.9x10 <sup>-4</sup>				

Analytical study:

-Constant impedance w pulse compression -"Constant gradient" w pulse compression

#### Constant Impedance (CI) AS formulas

$$v_{g}(z) = v_{g0}; \quad \tau(z) = \int_{0}^{z} \frac{dz'}{v_{g}(z')} = \frac{z}{v_{g0}}$$

$$t' = t - t_{1}; \quad \tau_{s} = \alpha L_{s} = \frac{\omega}{2v_{g0}Q} L_{s}; \quad t_{f} = \tau(L_{s}) = \frac{L_{s}}{v_{g0}} = \frac{2Q\tau_{s}}{\omega} \quad [5];$$

$$g(z) = \sqrt{\frac{v_{g0}}{v_{g}(z)}} e^{-\frac{1}{2Q}\tau(z)} = e^{-\tau_{s}\frac{z}{L_{s}}}, \quad G_{0}(t') = \sqrt{2\tau_{s}\frac{R}{L_{s}}}P_{K}(t=0)\frac{E_{out}}{E_{K}}(t')$$

$$G(z,t') = \sqrt{2\tau_{s}\frac{R}{L_{s}}}P_{K}(t=0)\frac{E_{out}}{E_{K}}(t'-\tau(z))e^{-\tau_{s}\frac{z}{L}}$$

[5] T. P. Wangler, RF Linear Accelerators, John Wiley & Sons, 2008

#### Constant Impedance (CI) AS – With pulse compression

$$\frac{E_{out}}{E_{K}}(t') = \gamma e^{-\frac{t'\omega}{2Q_{L}}} - (\alpha - 1); \qquad G(z, t') = \sqrt{2\tau_{s} \frac{R}{L_{s}}} P_{K}(t = 0) \left(\gamma e^{-\left(t' - \frac{z}{v_{s}}\right)\frac{\omega}{2Q_{L}}} - (\alpha - 1)\right)} e^{-\tau_{s} \frac{z}{L_{s}}} = G_{0}\left(\gamma e^{-\left(t' - \frac{z}{v_{s}}\right)\frac{\omega}{2Q_{L}}} - (\alpha - 1)\right)} e^{-\tau_{s} \frac{z}{L_{s}}}$$

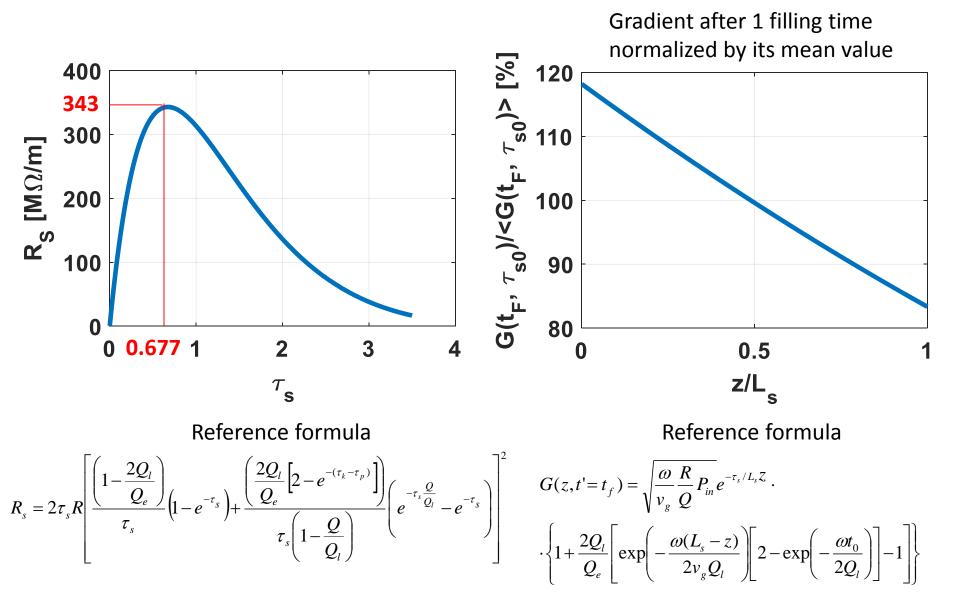
$$V_{a} = \int_{0}^{L_{s}} dz' G(z', t' = t_{f} = t_{2} - t_{1}) = \sqrt{P_{K}(t = 0)RL_{s}} \sqrt{\frac{2}{\tau_{s}}} \left[\gamma \left(\frac{1}{\frac{Q}{Q_{L}} - 1}\right) \left(e^{-\tau_{s}} - e^{-\frac{Q}{Q_{L}}\tau_{s}}\right) + (\alpha - 1)(e^{-\tau_{s}} - 1)\right] = \sqrt{P_{K}(t = 0)RL_{s}} \sqrt{\frac{R_{s}}{R}} \quad [6]$$

$$\frac{R_{s}}{R} = \frac{V_{a}^{2}}{P_{K}(t = 0)RL_{s}} = \left\{\sqrt{\frac{2}{\tau_{s}}} \left[\gamma \left(\frac{1}{\frac{Q}{Q_{L}} - 1}\right) \left(e^{-\tau_{s}} - e^{-\frac{Q}{Q_{L}}\tau_{s}}\right) + (\alpha - 1)(e^{-\tau_{s}} - 1)\right]\right\}^{2}$$

$$\frac{G\left(\frac{z}{L_{s}}, t_{F}, \tau_{s0}\right)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{s0}\right)\right\rangle} = L_{s} \frac{\left(\gamma e^{-\left(1 - \frac{z}{L_{s}}\right)\frac{Q}{Q_{L}}\tau_{s0}} - (\alpha - 1)\right)e^{-\tau_{s0}\frac{z}{L_{s}}}}{\int_{0}^{L} \left(\gamma e^{-\left(1 - \frac{z}{L_{s}}\right)\frac{Q}{Q_{L}}\tau_{s0}} - (\alpha - 1)\right)e^{-\tau_{s0}\frac{z}{L_{s}}}}$$

[6] J. Le Duff, High-field electron linacs, CERN 95-06, (1995)

#### Constant Impedance (CI) AS – With pulse compression



#### Effective Shunt impedance in Const Gradient (CG) AS

# **Beware!** It assumes constant R/Q values along the structure (inaccurate approximation)

$$v_{g}(z) = \frac{\omega L_{s}}{Q} \frac{\left[1 - \left(1 - e^{-2\tau_{s}}\right)\frac{z}{L_{s}}\right]}{\left(1 - e^{-2\tau_{s}}\right)}; \quad \tau(z) = \int_{0}^{z} \frac{dz'}{v_{g}(z')} = -\frac{Q}{\omega} \ln\left[1 - \left(1 - e^{-2\tau_{s}}\right)\frac{z}{L_{s}}\right] \quad [5]$$

$$\tau_{s} = \int_{0}^{L} \alpha(z)dz; \quad t_{f} = \tau(L_{s}) = \frac{2Q\tau_{s}}{\omega} \quad [5];$$

$$g(z) = 1, \quad G_{0}(t') = \sqrt{\frac{R}{L_{s}}}P_{K}(t=0)\left(1 - e^{-2\tau_{s}}\right)\frac{E_{out}}{E_{K}}(t') \quad [5]$$

$$G(z,t') = \sqrt{\frac{R}{L_{s}}}P_{K}(t=0)\left(1 - e^{-2\tau_{s}}\right)\frac{E_{out}}{E_{K}}(t'-\tau(z)) = G_{0}\frac{E_{out}}{E_{K}}(t'-\tau(z))$$

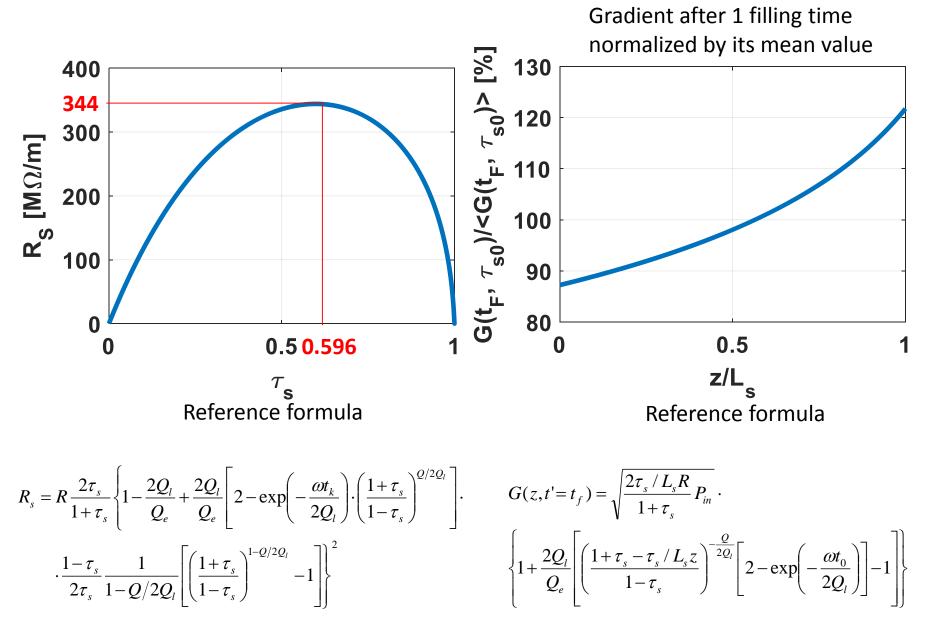
[5] T. P. Wangler, RF Linear Accelerators, John Wiley & Sons, 2008

#### Constant Gradient (CG) AS – With pulse compression

$$\begin{split} & \frac{E_{out}}{E_{k}}(t') = \gamma e^{\frac{-t'\omega}{2Q_{L}}} - (\alpha - 1); \\ & G(z,t') = \sqrt{\frac{R}{L_{s}}} P_{K}(t=0) \left(1 - e^{-2\tau_{s}}\right) \left\{ \gamma e^{-\frac{t'\omega}{2Q_{L}}} \left[ 1 - \left(1 - e^{-2\tau}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1) \right\} = G_{0} \left\{ \gamma e^{-\frac{t'\omega}{2Q_{L}}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1) \right\} \\ & V_{a} = \int_{0}^{L_{s}} dz' G(z', t' = t_{f} = t_{2} - t_{1}) = \sqrt{P_{K}(t=0)RL_{s}} \left(1 - e^{-2\tau_{s}}\right) \left\{ \gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ \frac{1 - \left(e^{-2\tau_{s}}\right) \left(1 - \frac{Q}{2Q_{L}}\right)}{\left(1 - \frac{Q}{2Q_{L}}\right) \left(1 - e^{-2\tau_{s}}\right)} \right] - (\alpha - 1) \right\} = \sqrt{P_{K}(t=0)RL_{s}} \sqrt{\frac{R_{s}}{R}} \quad [1] \\ & \frac{R_{s}}{R} = \frac{V_{a}^{2}}{P_{K}(t=0)RL_{s}} = \left(1 - e^{-2\tau_{s}}\right) \left\{ \gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ \frac{1 - \left(e^{-2\tau_{s}}\right) \left(1 - \frac{Q}{2Q_{L}}\right)}{\left(1 - \frac{Q}{2Q_{L}}\right) \left(1 - e^{-2\tau_{s}}\right)} \right] - (\alpha - 1) \right\}^{2} \\ & \frac{G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2Q_{L}}} - (\alpha - 1)}{\left\langle G\left(\frac{z}{L_{s}}, t_{F}, \tau_{30}\right)\right\rangle} = L_{s} \frac{\gamma e^{-\frac{Q}{Q_{L}}\tau_{s}} \left[ 1 - \left(1 - e^{-2\tau_{s}}\right) \frac{z}{L_{s}} \right]^{-\frac{Q}{2}} \left[ \frac{Q}{Q_{L}} - (\alpha - 1) \right]^{-\frac{Q}{2}} \left[ \frac{Q}{Q_{L}} + \frac{Q}{Q_{L}} \right$$

[1] Z. D. Farkas et al. SLED. A METHOD OF DOUBLING SLAC's ENERGY, Proc. 9<sup>th</sup> Int. Conf. on High Energy Accelerators, Stanford, 1974, (SLAC, Stanford, 1974).

#### Constant Gradient (CG) AS – With pulse compression



#### Analytical study results

Fixed the quality factor **Q** of the cells it is possible to calculate the effective shunt impedance  $R_s$  as a function of the section attenuation  $\tau_s$ . The choice of  $\tau_s$  fixes the filling time of the structure  $t_f$  and hence the compressed pulse length after the SLED  $t_p$ . The value of the external quality factor  $Q_e$  of the SLED has been chosen in order to maximize  $R_s$ . If we consider the optimum  $\tau_s$  value ( $\tau_{s0}$ ) it is possible to calculate the accelerating gradient profile after one filling time  $G(z,t'=t_f)$ . Once calculated the optimum  $\tau_s$  it is possible to calculate the main LINAC parameters: structure length  $L_s$ , number of structures  $N_s$ ,  $t_p$ , total required RF power  $P_{RF}$ , maximum value of modified Poynting vector Sc<sub>max</sub>.

CIAS parar	neters	CGAS para	neters
$R_{s} [M\Omega/m]$	343	R <sub>s</sub> [MΩ/m]	344
L <sub>s</sub> [m]	0.474	L <sub>s</sub> [m]	0.432
t <sub>f</sub> [ns]	114	t <sub>f</sub> [ns]	118

#### Numerical study for the linac optimization

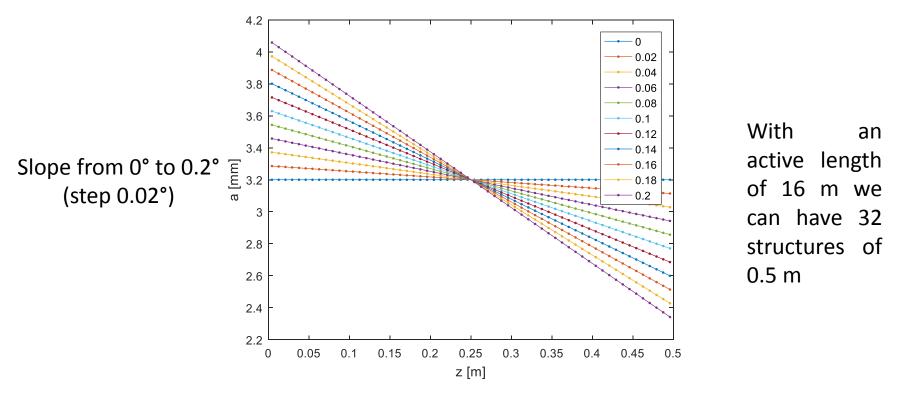
Using the theoretical formulas (constant impedance and constant gradient) we are able to find the optimal length of the structure (and the value Qe of the SLED) in order to maximize the Rs.

But the constant gradient formulas are not exact, there is the approximation of constant R/Q along the structure.

Considering this fact and the fact that we have a **constraint in terms** of active length, we thought a different approach: <u>fixing several</u> <u>lengths of the structure we want investigate several angles of iris</u> <u>tapering (linear tapering for the moment) using non-approximated</u> <u>formulas [2] and find the optimal tapering</u>.

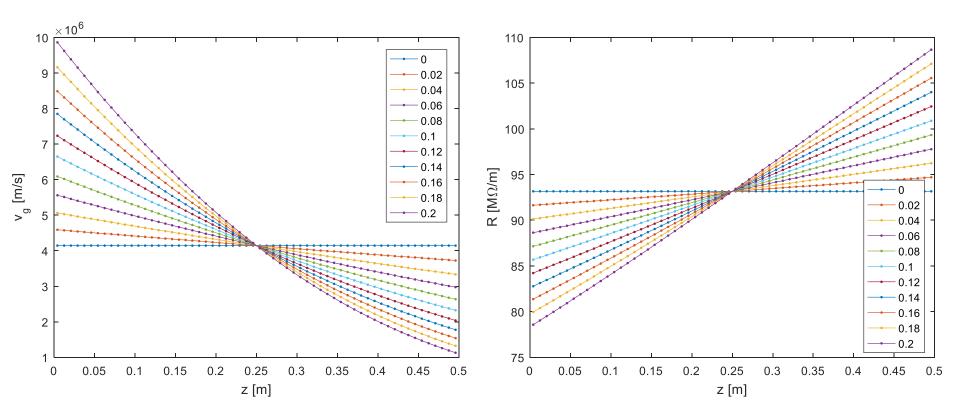
To do this we used the polynomial fits of the single cell parameters calculated with HFSS.

Ls=0.5m (60 cells), Ns=32



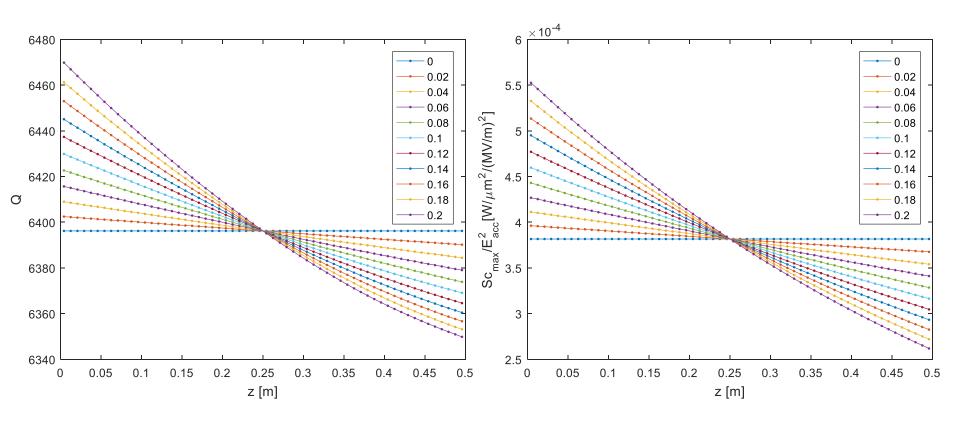
Fixing the length of the structure (60 cells for example) and the slope of the tapering (from 0° to 0.2° for the moment, <a>=3.2 mm) it is possible to find the iris radius of each cell (every  $\cdot$  is a cell) and then the related values of vg, R, Q, normalized modified Poynting vector using the polynomial fits.

#### Ls=0.5m (60 cells), Ns=32

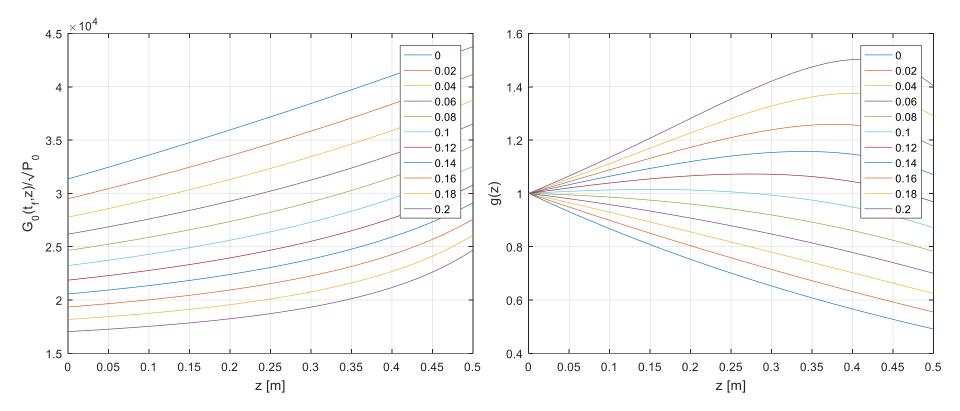


With a linear tapering there is a non-linear behavior of the group velocity along z.

#### Ls=0.5m (60 cells), Ns=32



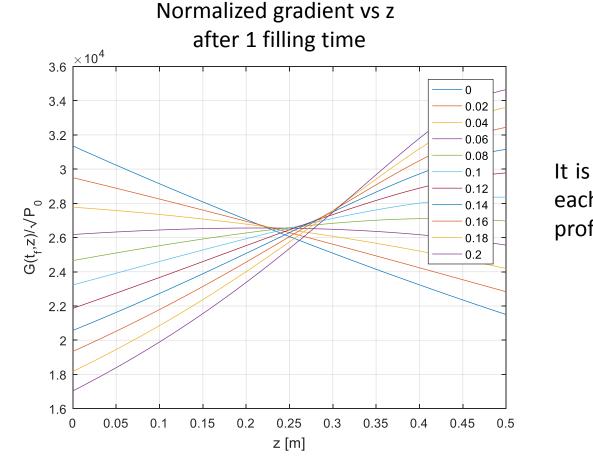
Since now we have the parameters of every cell it is possible to apply the general formulas in order to find the optimal slope for every fixed length (finding for each slope the optimal value of Qe for the SLED).



$$G_0[t_f - \tau(z)] = \sqrt{\frac{\omega}{v_g(0)} \frac{R(0)}{Q(0)} P_0} \frac{E_{out}}{E_K} (t_f - \tau(z))$$

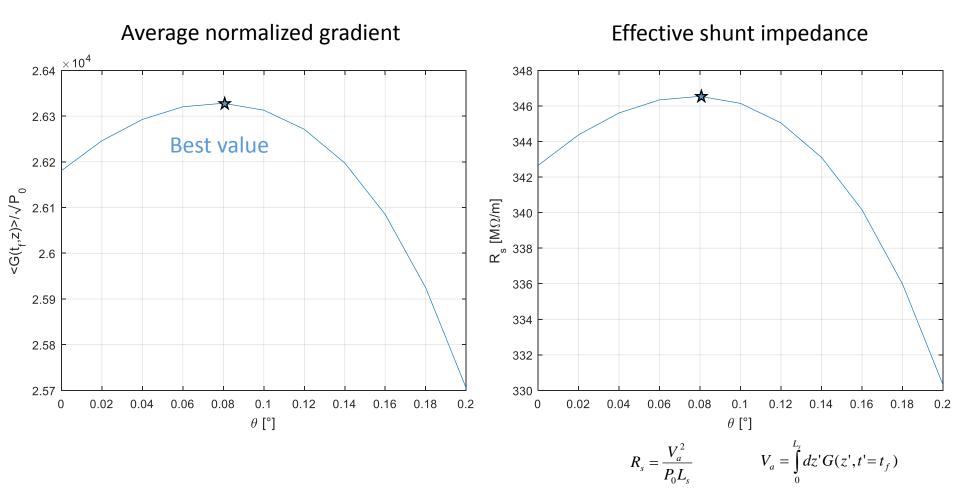
$$g(z) = e^{-\int_{0}^{z} \alpha(z')dz'} = \sqrt{\frac{v_g(0)}{v_g(z)}} \sqrt{\frac{R(z)}{Q(z)}} \frac{Q(0)}{R(0)} e^{-\frac{1}{2}\int_{0}^{z} \frac{\omega}{v_g(z')Q(z')}dz'}$$

$$\alpha(z) = \frac{1}{2} \left[ \frac{1}{v_g} \frac{dv_g}{dz} - \frac{1}{R/Q} \frac{d(R/Q)}{dz} + \frac{\omega}{v_g Q} \right]$$

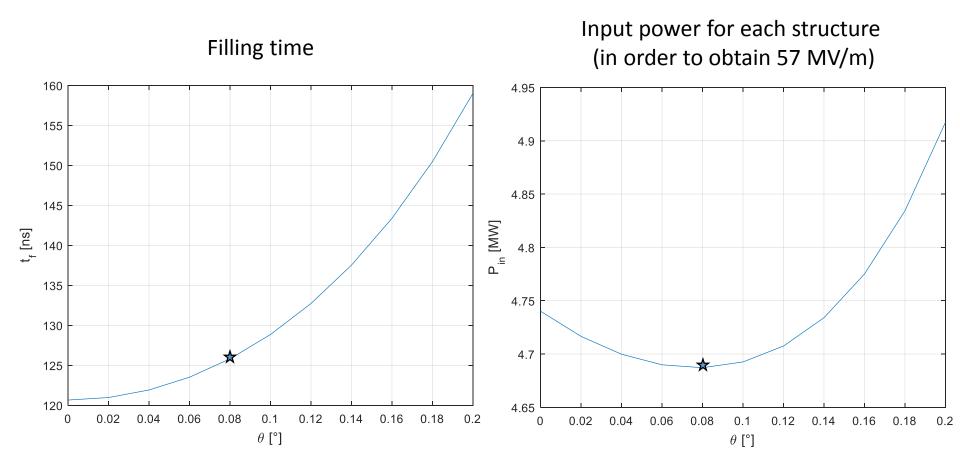


It is possible to observe that for each slope we obtain different profiles of the gradient.

$$G(z,t_{f}) = G_{0}[t_{f} - \tau(z)]g(z) = \sqrt{\frac{\omega}{v_{g}(0)}} \frac{R(0)}{Q(0)} P_{0} \frac{E_{out}}{E_{K}}(t_{f} - \tau(z)) \sqrt{\frac{v_{g}(0)}{v_{g}(z)}} \sqrt{\frac{R(z)}{Q(z)}} \frac{Q(0)}{R(0)} e^{-\frac{1}{2} \int_{0}^{z} \frac{\omega}{v_{g}(z)Q(z)} dz}$$



Considering the average (normalized to the input power) gradient or the effective shunt impedance we find that the optimal slope is 0.8° (corresponding to an iris radius variation from 3.5 mm to 2.9 mm).



$$\tau(L_s) = \int_0^{L_s} \frac{dz'}{v_g(z')}$$

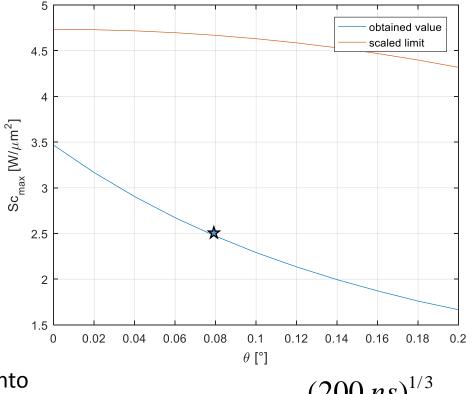
#### Ls=0.5m (60 cells), Ns=32, Q0=180000, <G>=57 MV/m

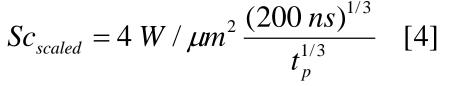
#### Modified Poynting vector (calculated at the first cell)

The modified Poynting vector should not exceed 4 W/um<sup>2</sup> in order to have BDR below 1x10<sup>-6</sup> bpp/m at pulse length of 200 ns

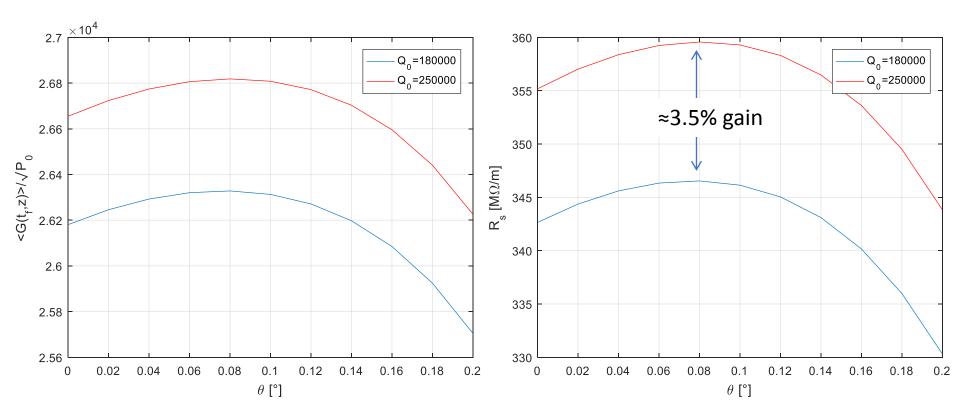
For each slope we are below the scaled limit (for an average gradient of 57 MV/m)

With this formula we take into account the fact that for every slope the filling time is slightly different

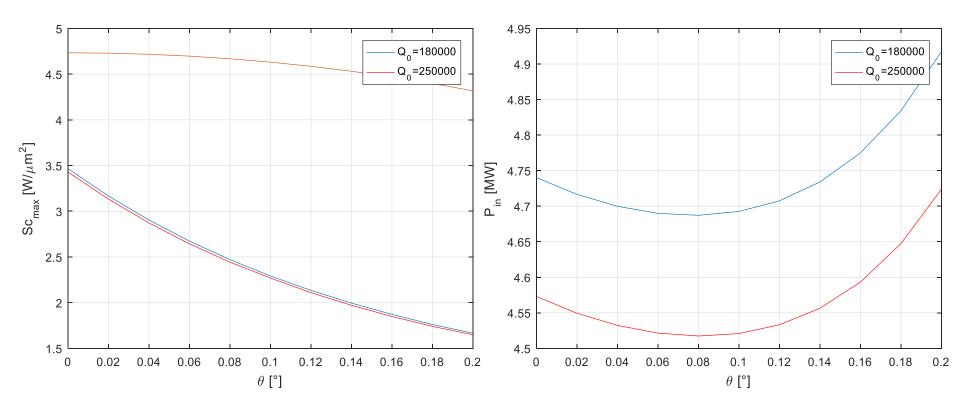




[4] A. Grudiev, S. Calatroni, and W. Wuensch, New local field quantity describing the high gradient limit of accelerating structures, PhysRevSTAB.12.102001 (2009)



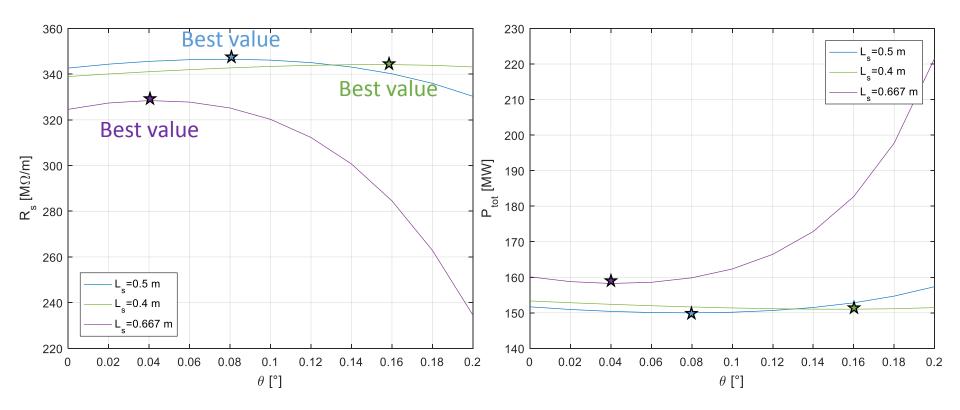
We can repeat the same exercise with a Q0 of 250000 (barrel open cavity - **BOC solution**) and compute the gain in terms of average gradient (or Rs).



#### Other structure lengths

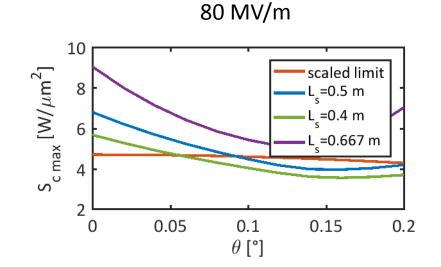
We can repeat the calculation considering other structure lengths: **0.4 m** (48 cells, 40 structures) and **0.667 m** (80 cells, 24 structures) for example. I fixed a **Q0 of 180000**.

#### Other structure lengths



From this two plots we obtain that the best solutions are: 0.8° for 0.5 m (2.851mm<a<3.549mm) and 0.16° for 0.4 m (2.642mm<a<3.758mm). The longest option seems not so good as the other two.

#### Other structure lengths



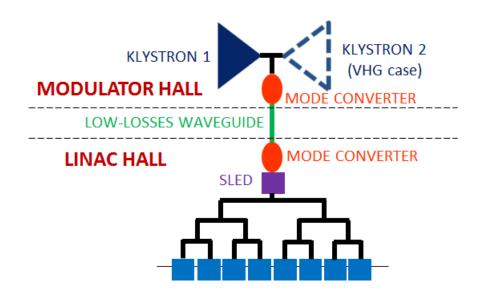
Considering the best solutions for 0.5m and 0.667m cases, the modified Poynting vector is above the scaled limit in the 80 MV/m scenario, anyway it is possible to move towards harder tapering in order to stay below. The 0.5 m solution with an angle of slope of 0.1° has been chosen.

### **Results and RF layout**

LINAC parameters					
<a> [mm]</a>	3.2				
a first-last cell [mm]	3.636 -	- 2.764			
L <sub>s</sub> [m]	0.	.5			
No. of cells $N_c$	6	0			
L <sub>t</sub> [m]	1	6			
No. of structures $\rm N_s$	3	2			
Q <sub>e</sub>	218	300			
v <sub>g</sub> /c [%]	2.2 - 0.78				
t <sub>p</sub> [ns]	129				
$R_{s} [M\Omega/m]$	346				
Available RF power / klystron	50 MW (@ klystron output coupler) 40 MW (@ section input couplers)				
	HG option	VHG option			
<g> [MV/m]</g>	57	80			
W <sub>gain</sub> [MeV]	912 1280				
P <sub>RF</sub> [MW]	150 296				
No. of klystrons $N_k$	4	8			

X-band The TW accelerating sections optimized for the EuPRAXIA@SPARC LAB application are **0.5 m** long and show an effective shunt impedance per unit length value of **346**  $M\Omega/m$  including the peak power gain provided by the pulse compressor. Commercially available X-band klystrons provide up to 50 MW peak power in 1.5  $\mu$ s long pulses. **RF** losses in the waveguide distribution system reduce the klystron available power to the accelerating sections by  $\approx$  20%, so that a single tube can actually deliver ≈ **40 MW** and power 8 TW structures in parallel up to the required gradient. The **basic RF module** of the EuPRAXIA@SPARC LAB Xband LINAC can be conveniently composed by a group of 8 TW sections assembled on a single girder and powered by a **one (for HG) or** two (for VHG) klystrons by means of one pulse compressor system and a waveguide network splitting and transporting the RF power to the input couplers of the sections.

### **Results and RF layout**



RF MODULE FOR EUPRAXIA@SPARCLAB

- 8 TW sections (60 cells 50 cm active length each)
- 4 m active length, ≈5 m actual length
- 57 MV/m gradient with 1 klystron + pulse compressor
- 80 MV/m gradient with 2 klystrons + pulse compressor (VHG option)

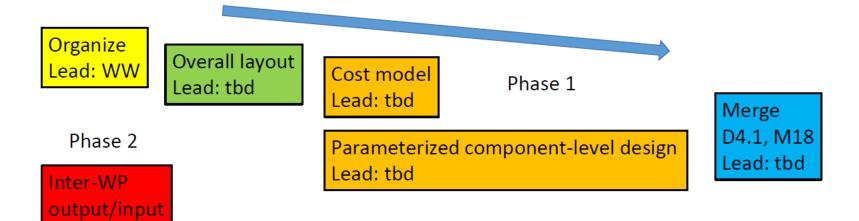
### Compact Light Accelerating Structure Design Workflow

- Define an average iris value
- Find the highest effective shunt impedance structure by scanning the total length, iris tapering and pulse compressor characteristics
- Chose a reference value of the accelerating field
- Verify the max modified Poynting vector values @ nominal gradient
- Design power distribution networks on the base of existing klystrons. Propose a limited number of alternatives.
- Elaborate a cost model to compare different configurations providing different (but still well beyond the present state of the art) operational accelerating gradients.
- Finalize the electromagnetic (input and output couplers) and mechanical design of the structures
- Design a realistic RF module

Iterations among these various steps will be very likely needed, as a consequence of discussions and data exchange with others WPs.



#### Tasks, workflow and responsibilities



		Technical area					Activity			
	Modulator	Power source	Waveguide network	Accelerating structures	Module	LLRF/control/ diagnostics	rf design/ optimization	Mechanical design	Layout/ integration	Costing/ industrialization
CERN										
CNRS-LAL										
INFN Frascati										
Institute of Accelerator Technology, Ankara										
SINAP										
Sincrotrone Trieste										
University of Helsinki/HIP										
University of Melbourne/ANSTO										
University of Strathclyde										
Uppsala University										
VDL										

INFN-LNF contribution to WP4 (towards D4.1, M18)≈ 6 months FTE (to be more precisely defined)

Persons involved:

- A. Gallo / D. Alesini (supervision)
- M. Diomede (RF design: calculations and simulations)
- F. Cardelli / L. Piersanti (support to RF design)
- B. Buonomo / M . Bellaveglia (support and discussion)