



Recent progress in accelerating avalanche simulation using Garfield++

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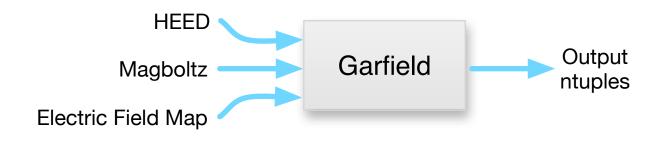
Outline

- Simulation setup
- Processing time
- Parallelization
- Optimization
- Future work

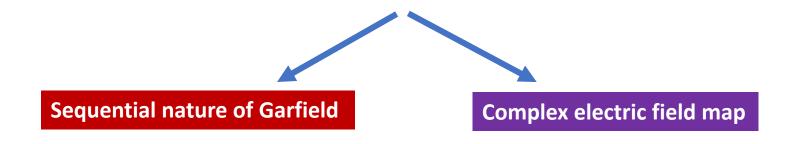




Simulation workflow



Excessively CPU and wall time consuming (when simulating large volumes/high gain)



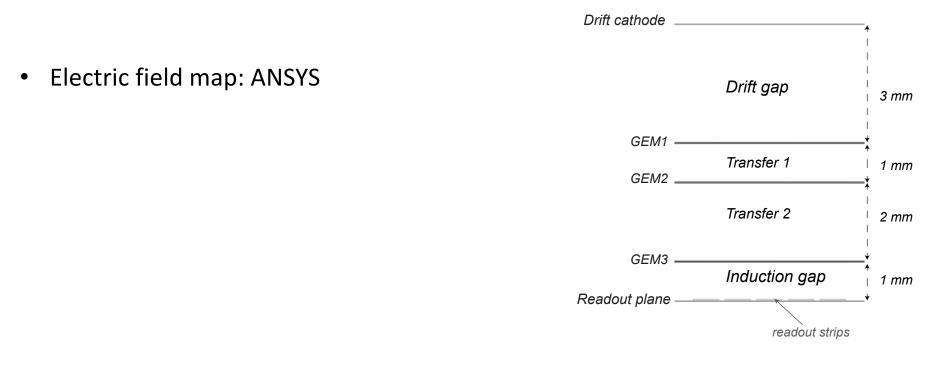
This work tackles both problems





Simulation setup

- Single GEM gap dimensions: Drift gap (1mm), Induction field (1mm)
- Triple GEM gap: Drift (3mm), TF1(2mm), TF2(1mm), Induction () (similar to CMS GE1/1 configuration)

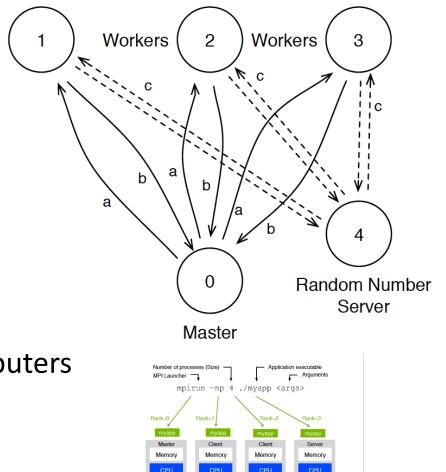






Sequential problem: event based parallelization

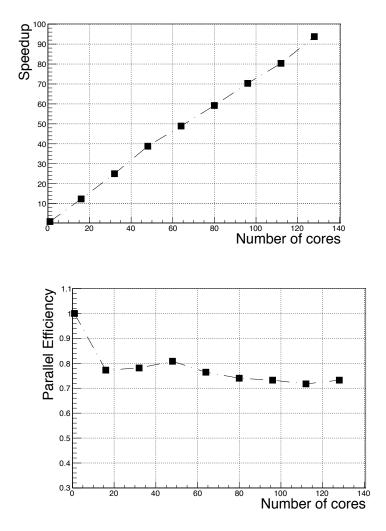
- Solution based on MPI
- Random number server
- Master distributes the workload and gathers results back
- Work distributed over N cores
- Using Raad and Raad2 supercomputers at Texas A&M university at Qatar







Sequential problem: event based parallelization



 $speedup = \frac{execution \ time \ in \ sequential \ mode}{execution \ time \ on \ parallel \ mode}$

• Almost linear increase with the number of cores

Parallel efficiency is:

speedup factor

number of cores in the parallel process

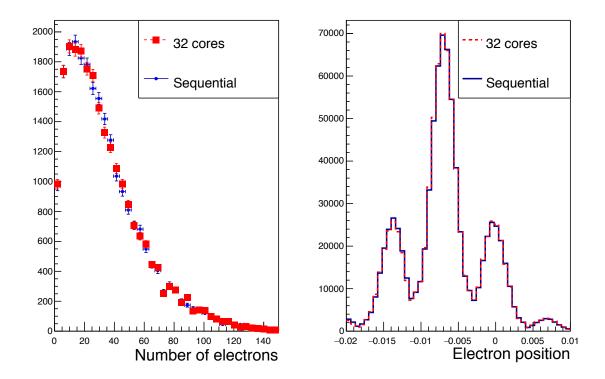
• Measures how well processors are utilized





Sequential problem: event based parallelization

Comparison: same simulated conditions



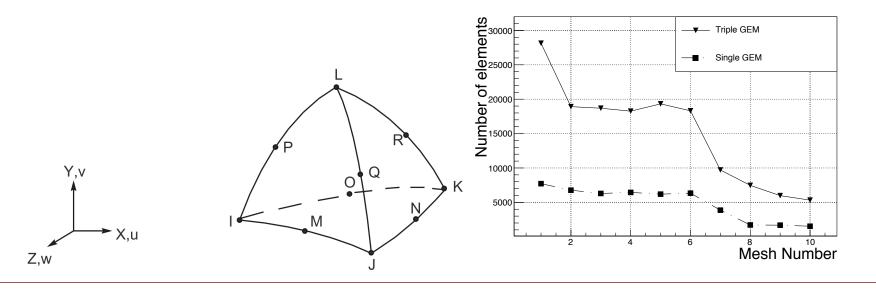




Electric field map in ANSYS

ANSYS:

- Mesh based on tetrahedral nodes
- field map mesh depends on the accuracy needed
- Mesh numbering: 1 (highest accuracy) and 9 (lowest accuracy)
- Complexity increases with the geometry



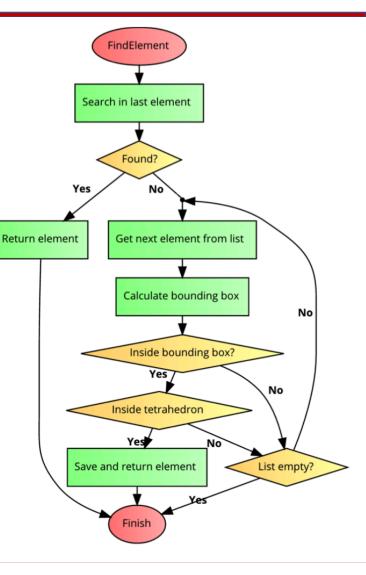




Time consuming operation

FindElement is an algorithm in Garfield++

- Finds tetrahedral node containing the 3D points associated with the electron position
- **90%** of processing time is spent in this operation
- Processing time increases with mesh complexity

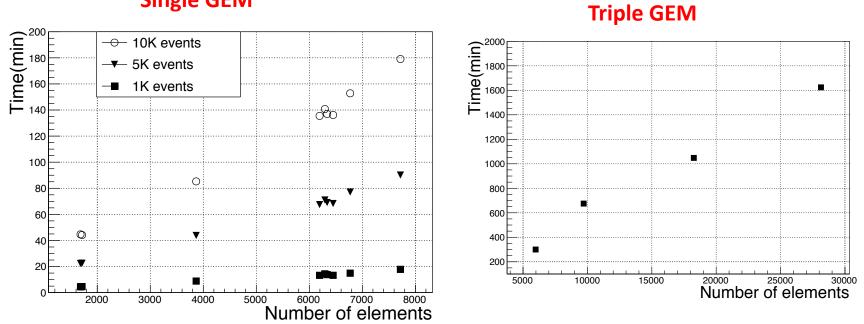






Template

Processing time increases with mesh complexity •



Single GEM

 \rightarrow Search technique in FindElement Needs optimization





Optimizing FinElement

Three methods are introduced:

- Caching bounding boxes
- Search over neighbors
- Spatial indexing using Octree





- At each iteration the last mesh element (e position) is calculated and the program starts looking for the next location.
- A bounding box that englobes the element is defined and the program checks if the electron resides inside.
- if it is found, then it checks whether the electron is inside the mesh elements,
- if not it will go to the next element, defines the bounding box and checks again.
- \rightarrow This prevents iterating over all mesh elements as it is in the original version





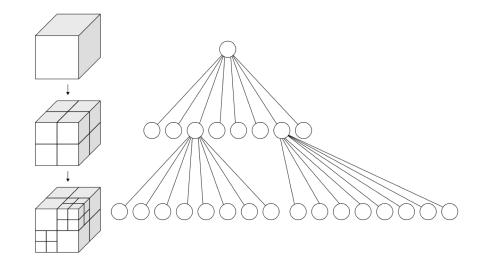
- Starting from the actual position of the electron, its next position is most likely to be within one of the neighboring elements.
- This method searches through the neighbors elements first.
- The scan over non-neighbors is performed only if the search in neighbors fails.





Search using Octree structure

• Based on spatially indexed data structure (Octree)



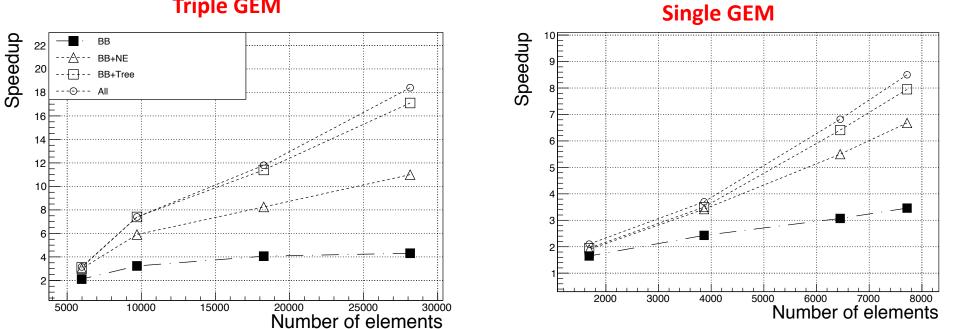
• subdivides the space in eight octants of equal dimensions and store the nodes of the tetrahedrons in a hierarchical fashion.





Optimization results

Triple GEM

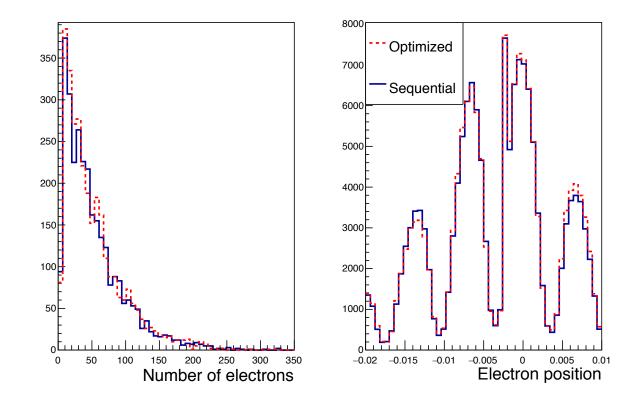


- Almost 20 times increase in speed up factor
- Speedup is even more important in complex geometries (single versus triple GEM)





Comparison: optimized-sequential



• 5000 events in triple GEM with gain over 30,000 takes around 30 hours.





Summary and future work

- The parallel version provides a linear speedup factor
- The optimization of the search technique reduces the execution time by a factor up to 20
- Work published last week: NIMA 901 (2018) 92-98. (also in proc. CHEP16)
 The github link is: <u>https://github.com/alisheharyar/pGarfield-toolkit</u>

Future:

- Extend it to other field solvers
- Trying other hardware (accelerators): GPU, ARM...