





### STATUS AND UPGRADE PLANS FOR A 20 MUON DETECTORS NETWORK AT LSBB.

Ignacio Lázaro Roche on behalf of T2DM2 collaboration





## **OBJECTIVES**

Development of a new non-destructive, compact tool based on the measurement of cosmic muons for imaging and monitoring large volumes of matter

Monitor the temporal density variations

New geophysics' tool based on a thin Time Projection Chamber read by a resistive Micromegas plane





### **INTRODUCTION - LSBB**



Low background noise environment

Introduction

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- Clean room to assemble detectors
- The layout of the galleries allows to deploy the camera network easily both on the surface and underground

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**Rustrel**, France

- Easy access and access to network, electricity, etc.
  - Measurements synergy: gravimetry, MRS, hydrogeology, hydromechanical tilt, GPR...



# INTRODUCTION — DETECTOR MUST<sup>2</sup>

MUon Survey Tomography based on Micromegas detectors for Unreachable Sites Technology







### **INTRODUCTION - DATA ACQUISITION** Example of signal acquired with an





- Reconstruction of a single channel signal shape, allows to retrieve:
  - Let time of passage (res. few ns)

- 27 measures of V from 128 channels, 25 ns sampling rate
- The vertical bars separate the different time windows
- Every time window contains the V of 128 channels

### Example of signal fit with a Fermi-Dirac function for 1 isolated channel





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Y axis

## **INTRODUCTION - DATA ACQUISITION**



**Trajectories** 



- Cluster: Association of adjacent tracks hit within a fix interval
- The projection of the muon-induced electrons hits several contiguous tracks
- Reduces the number of fake events (less instrumental noise)

The combination of X & Y clusters allows reconstructing 2D points with an accuracy better than mm



Reconstruction of the retrieved points in the detector plane.



Raw data

**Points** 

**Trajectories** 

# **INTRODUCTION - DATA ACQUISITION**

- The arrival time of e<sup>-</sup> is distance-dependent
- The e<sup>-</sup> drift speed is known and constant for a given  $\vec{E}$
- The time difference provides information about the original height of the ionization point







- The analysis of 3D points allows to define the trajectory of the particle
- The trajectory is characterized by its
   Zenith (θ) and Azimuth (φ) angles





### **DETECTOR CALIBRATION**

Aerial view of the top of the mountain hosting the LSBB, test site for open air measurements.



Number of muons:
Expected according to Tang model (translucid)
Experimental measurement (opaque)

1400





### **DETECTOR CALIBRATION**

Ratio =  $\frac{\text{Muons per azimuth deg } OPEN SKY}{\text{Muons per azimuth deg } EXP. MEASUREMENT}$ 



**Detector** location



 Objectives
 Introduction
 Calibration
 Measurements
 Conclusion

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## **DETECTOR CALIBRATION**

Approximation of the 360° view around the detector





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## <u>MEASUREMENTS — STUDY SITE</u>



Known topology



#### Monitored parameters:

Temperature, humidity and atmospheric pressure inside the valve house

Level, temperature and conductivity of reservoir's water

Precipitations (only known water source)

□High atmosphere pressure

Earth tides





of Muons

Temporal Tomography of rock mass density by the Measure

2DM2

MEASUREMENTS - DIGITAL MODEL



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Source: Société du canal de Provence

\*Thanks to K. Jourde, member of T2DM2 collaboratio Pracio LÁZARO for RD51 meeting 2018 12

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**Measurements** 

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Conclusions

### MEASUREMENTS - RESULTS







Ignacio LÁZARO for RD51 meeting 2018 13



### MEASUREMENTS — RESULTS

Integration time = 3d17h



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\*Bin = Representation of the hemisphere over the detector in a matrix of pixels of dimension 360x360 Measurements Cor



### MEASUREMENTS — RESULTS

Temporal evolution of muon flux and water level



- Strong sine-wave behaviour due to the effect of the temperature in both the barometer used to determine the water level and the MUST<sup>2</sup> detector
- The linear regression of the whole data shows that the emptying trend of the dam is related to a rise of the muon flux



## OUTLOOK

 Monitor the water transfer in the non-saturated zone above the galleries

Construction and deployment of a network of 20 autonomous detectors

Roughly the same design as the previous version, but smaller and squared (50x50cm<sup>2</sup>)

Versatile set up configurations: isolated, clustered, stacked, aligned surface/underground...



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Conclusions



### CONCLUSIONS

 $\checkmark$ Very encouraging results from the first acquisition test under real field conditions

Field transportability and reliability demonstrated : possibility to do long term campaigns

 $\checkmark$  The track reconstruction algorithm and noise filtering has room for improvement in order to enhance the robustness of the results

Next step: more experimental data and further data analysis development is required to support the numerical model and resolve the inversion and obtain the medium density





### Acknowledgements

### PhD leading institutions:



### **PhD collaborators:**









### **Project sponsors:**













## **SPARE SLIDES**

View of the detector inside the valve house of the dam the during the data acquisition

