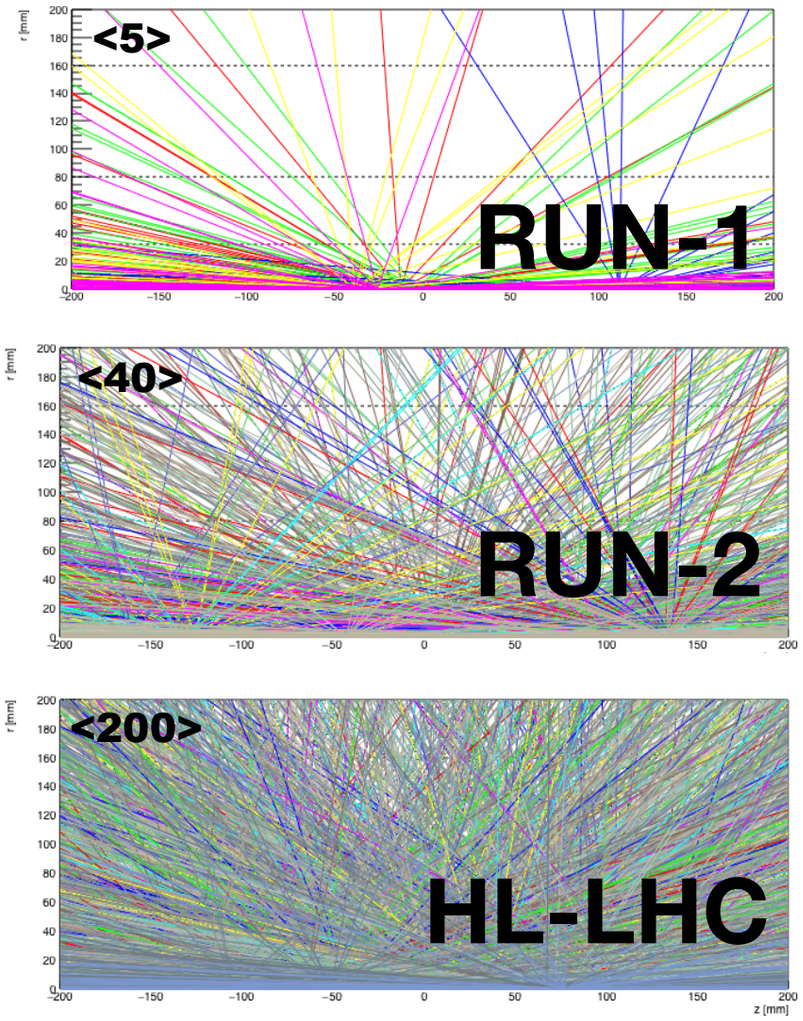
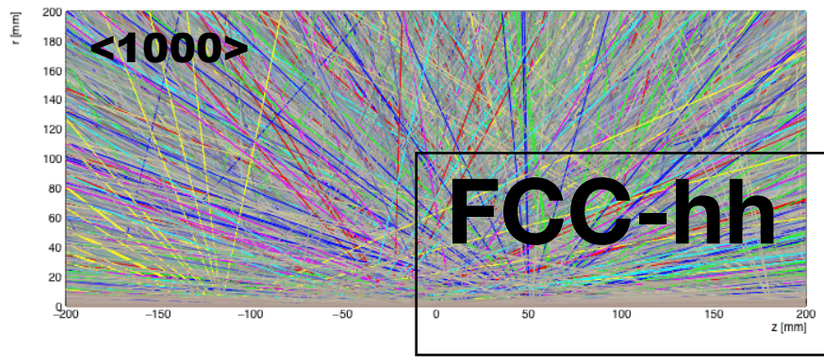
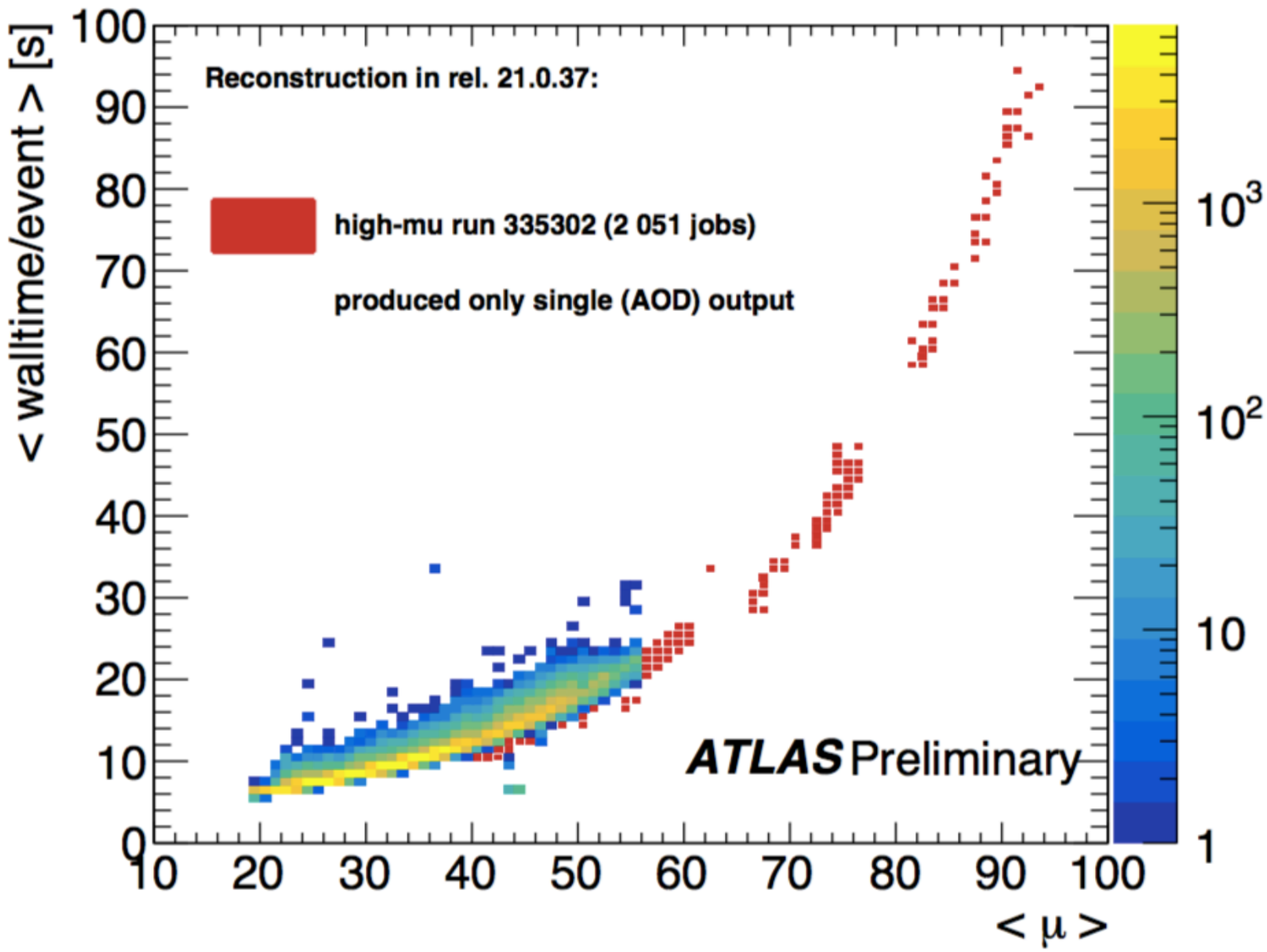


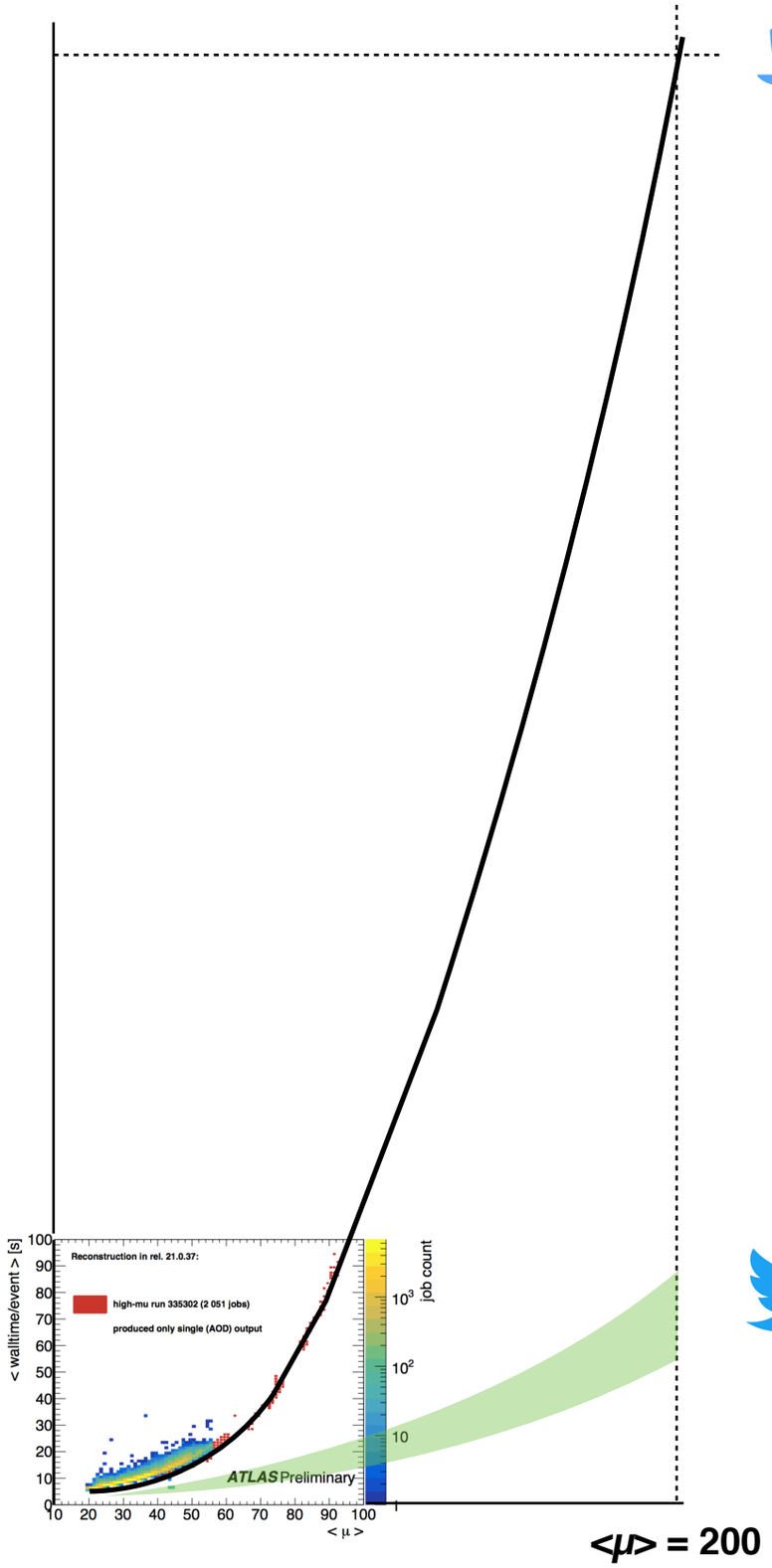




R&D for Future Tracking

A. Salzburger (CERN)

Track reconstruction Extrapolation HL-LHC



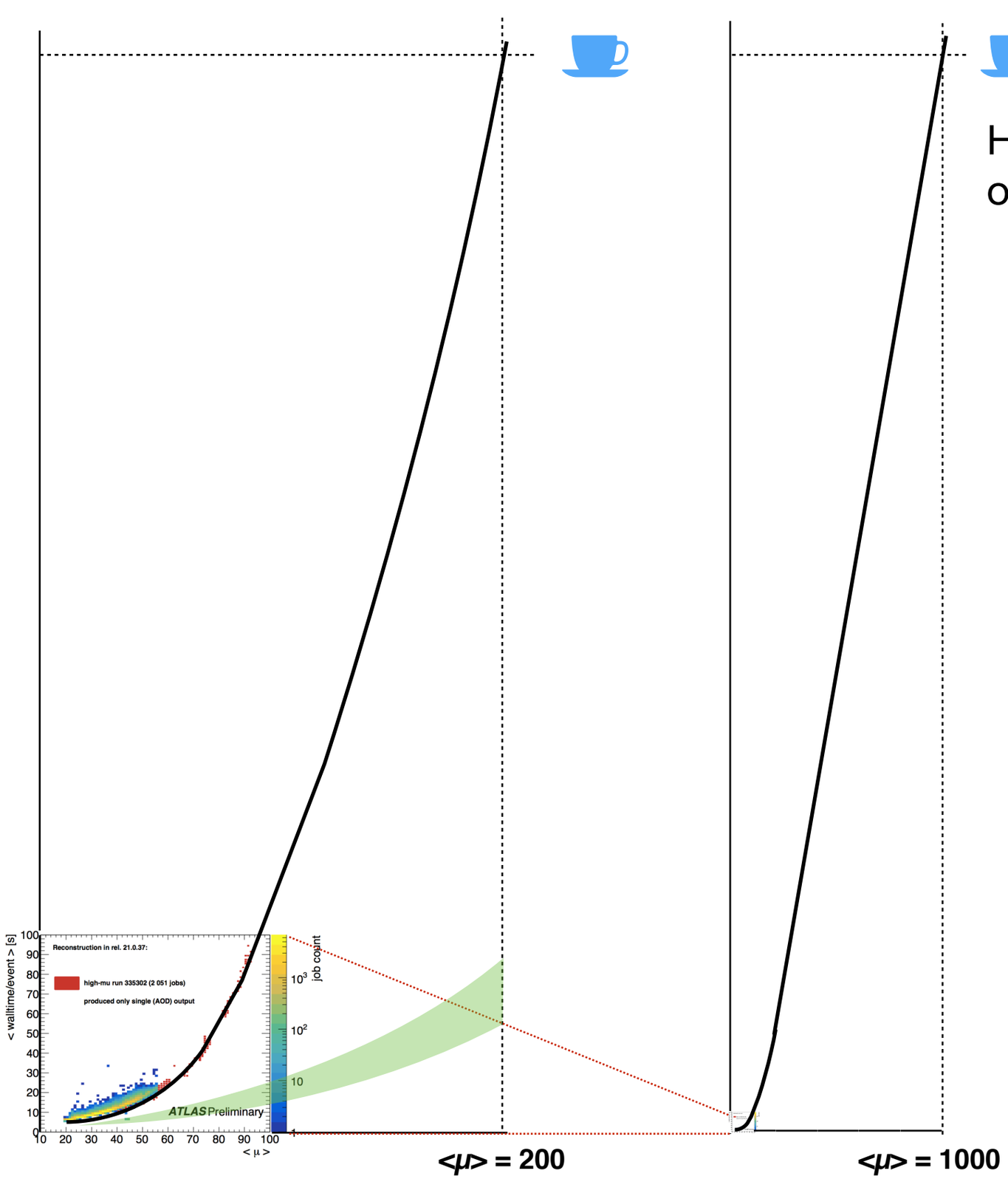
Naive extrapolation of LHC detector
- full reconstruction
- ATLAS/CMS & software designed for <μ>~23

Finding of particle trajectories
- combinatorial problem to solve
- highly non-linear scaling of CPU time with increasing event complexity
- dominant CPU consumer

Current numbers for HL-LHC detector
- track reconstruction only
- detector designed for <μ>=200
- current software adapted/optimized for this environment

Factor 10 increase in readout rate from 1kHz to 10 kHz
only partly compensated by hardware speedup

Track reconstruction Extrapolation HL-LHC / FCC-hh



Hyper-naive extrapolation
of LHC detector

?

What is possible

- needs framework for detector design, performance studies and further software R&D

Risks & Gains

Risk is high

- not solving the computational challenge risks physics potential
- e.g. current LHC analyses saw already the advent of MC statistic limits for certain analyses

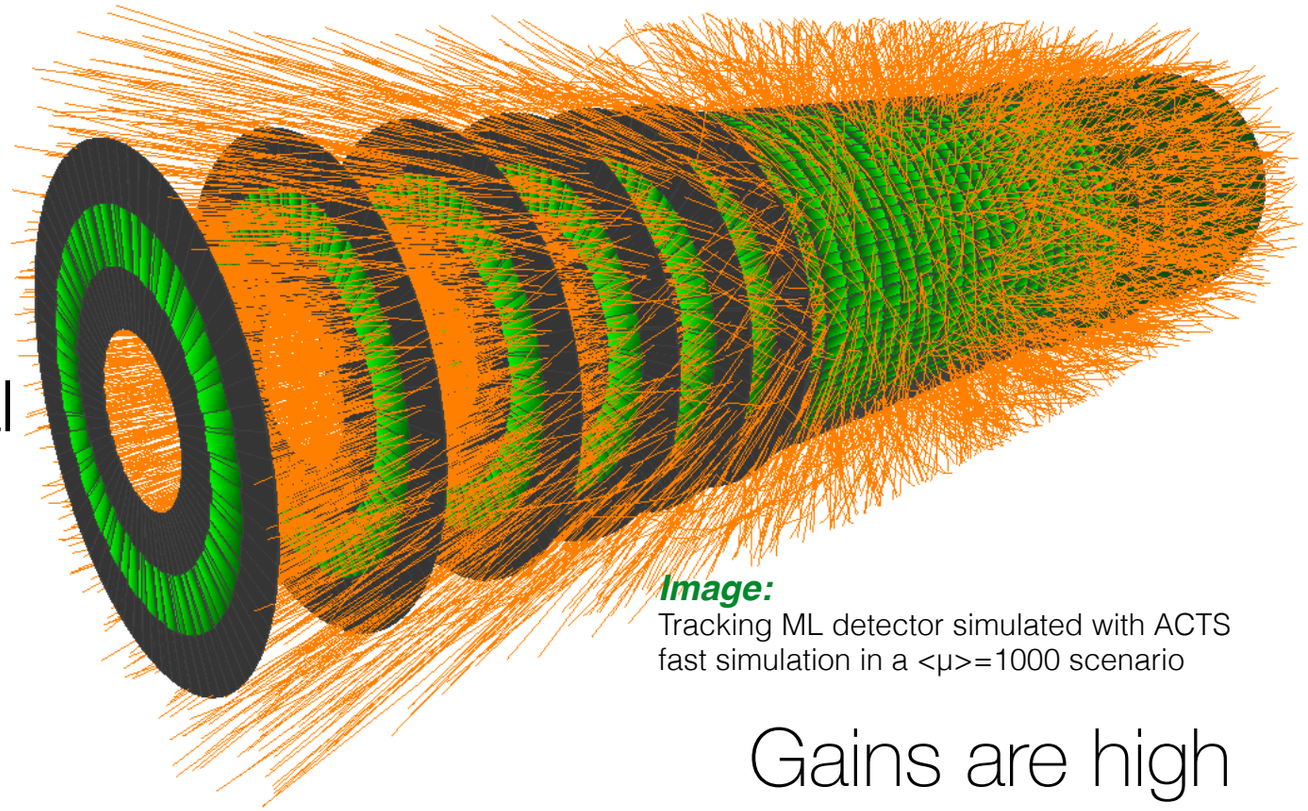


Image:
Tracking ML detector simulated with ACTS fast simulation in a <μ>=1000 scenario

Gains are high

Substantial R&D is needed several areas:

Code optimization	algorithmic R&D	(low n) Concurrency	Hardware acceleration	Machine Learning

- great in-house expertise at CERN that can be fostered
- symbiotic projects with detector R&D, computing & machine learning
- exciting times for software and algorithm design
- strengthen CERN as excellence lab for software

Track reconstruction R&D

Code optimization	algorithmic R&D	Concurrency	Hardware acceleration	Machine Learning

Community driven common software for track reconstruction

- cutting edge algorithmic solutions for "classical pattern recognition"
  preserving the excellent performance *(physics & failure rate) of LHC experiments*
- expert driven code optimization (strong link to SW R&D)

Common effort of online and offline reconstruction software

- incentives towards tracking at L1 trigger level / trigger-less readout

Inclusion of timing information in track finding & fitting

- synergies with detector R&D for timing detectors

On demand track reconstruction

- region or physics driven reconstruction setups

Overall need for an R&D platform for track reconstruction

Track reconstruction R&D

Code optimization	algorithmic R&D	Concurrency	Hardware acceleration	Machine Learning

Adapt track reconstruction
for **concurrent execution**
- most promising approach for current combinatorial track finding
- needs **substantial** work on current algorithms, data structures and data flows (vectorization)

Uncertainty in hardware market
- prepare **flexible toolkits** that allow adaption to several concurrency scenarios

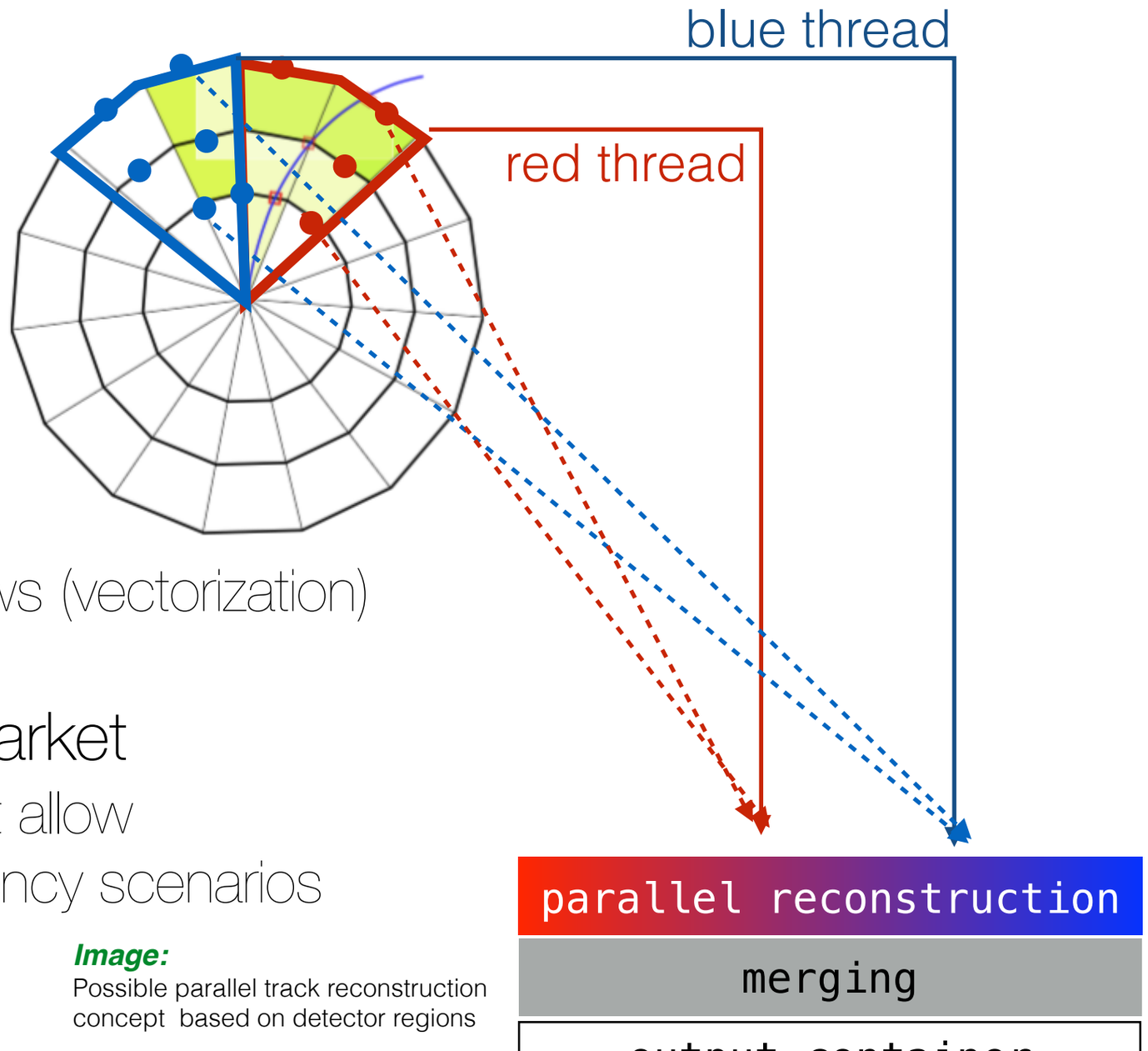


Image:
Possible parallel track reconstruction concept based on detector regions

Example:
ACTS
https://indico.cern.ch/event/699252/contributions/2881457/attachments/1594869/2525543/2018-02-05-ACTS-Lightening.pdf

Track reconstruction R&D

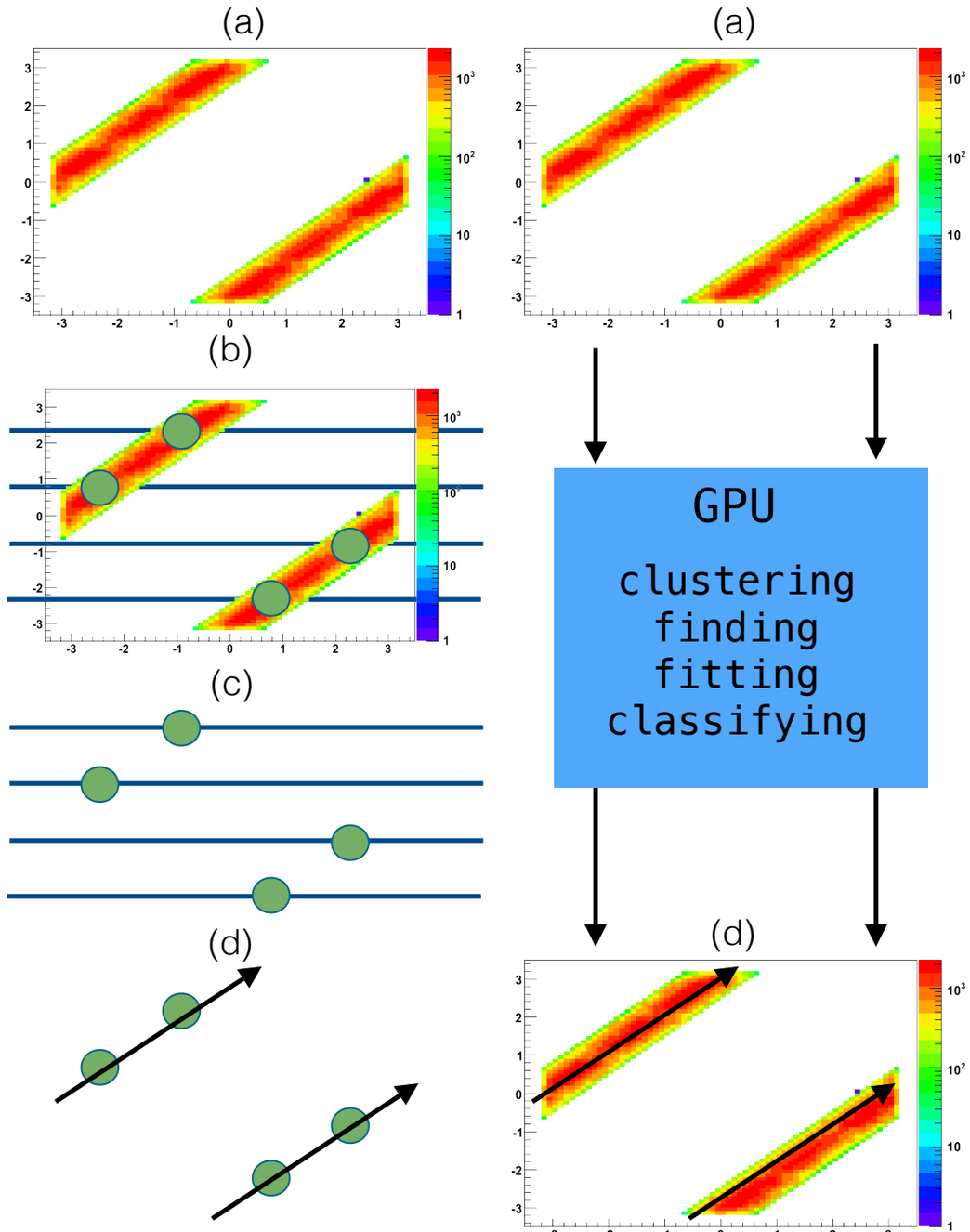
Code optimization	algorithmic R&D	Concurrency	Hardware acceleration	Machine Learning

GPUs in track reconstruction

- several areas where GPUs could be effectively used
- GPUs work extremely well for certain algorithms/data flow
  e.g. clustering, cellular automaton, hough transform, Kalman filter
- Machine learning applications are "designed" for GPUs

Use of FPGAs and associative memory in track reconstruction

- particular in trigger



Examples:

CMS cellular automaton on GPUs
Clustering & Tracking GPUs/ML
https://indico.cern.ch/event/702570/contributions/2905391/attachments/1606480/2549157/2018-02-26_CERN_RnD_Proposal.pdf

Image:
Traditional path to track finding (left), GPU enabled path directly on charge input (right)

Track reconstruction R&D

Code optimization	algorithmic R&D	Concurrency	**Hardware acceleration**	**Machine Learning**

Clustering hits together is typical ‘unsupervised learning’

- take advantage of the recent advances in the field

integrate into current track reconstruction software stacks

Convolutional/Recurrent Neural Networks (CNNs/RNNs)

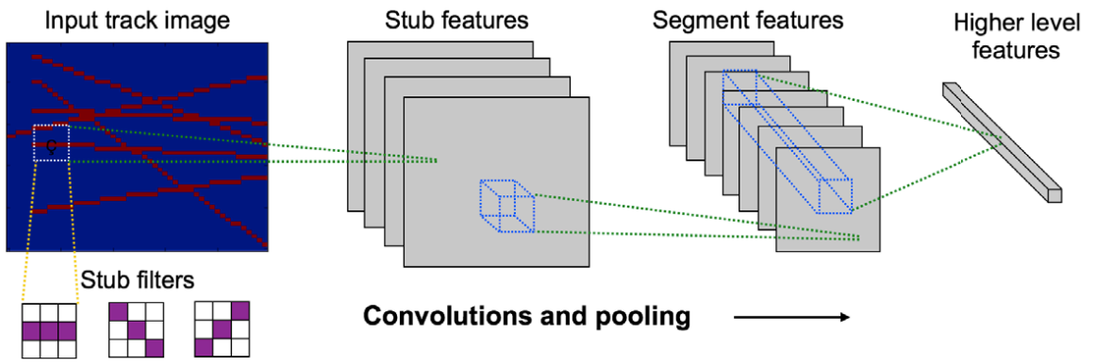


Image:
Convolutional Neural network for track finding via (sub-)feature pooling

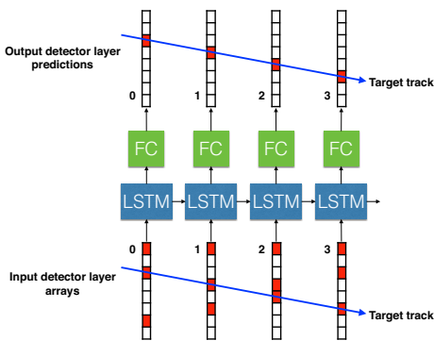
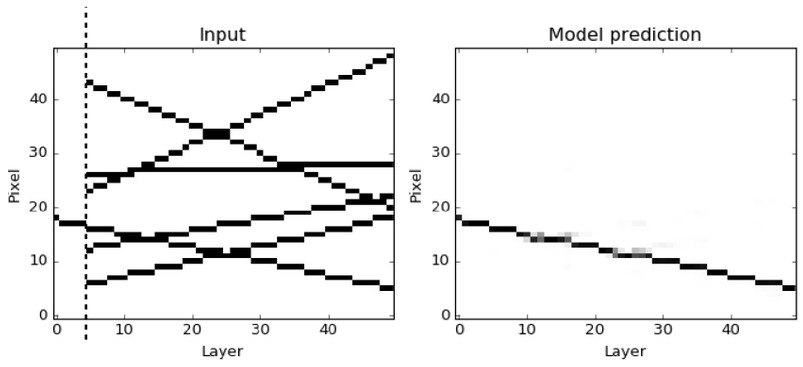


Image:
Recurrent Neural network for prediction via Long Short Term Memory (LSTM)



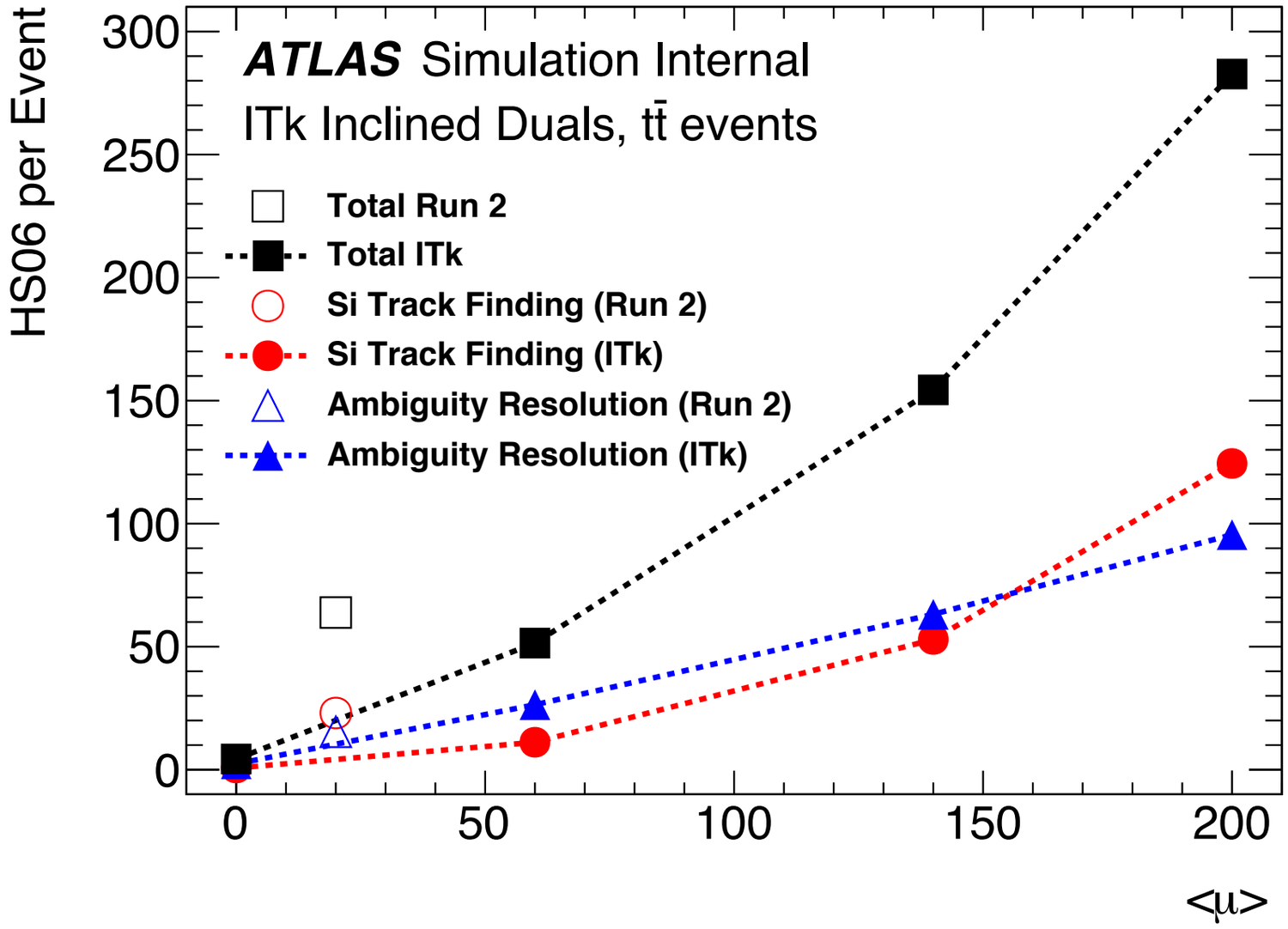
Examples & more information:

See talk by Maurizio

CERN co-organized, Tracking Machine Learning Challenge (Apr 2018)

Backup

HL-LHC CPU extrapolation

Based on ATLAS ITk estimates

- similar picture for CMS