# Classification Baseline

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### **Classification Bug**

The classification architecture we used in NIPS had 4 hidden layers. It turns out that all 4 layers were constrained to have the same weight. This has been fixed and resulted in slightly better accuracy using NIPS architecture.

Before, we showed that scanning over n\_hidden\_layers had little effect. Due to the discovery of this bug, this result is obviously called into question.

```
lass Classifier_Net(nn.Module):
def __init__(self, hiddenLayerNeurons, nHiddenLayers, dropoutProb, windowSize):
    super().__init__()
    self.windowSize = windowSize
    self.nHiddenLayers = nHiddenLayers
    self.input = nn.Linear(windowSize * windowSize * 25, hiddenLayerNeurons)
    self.hidden = nn.Linear(hiddenLayerNeurons, hiddenLayerNeurons)
    self.hidden.cuda()
    self.dropout = nn.Dropout(p = dropoutProb)
    self.dropput.cuda()
    self.output = nn.Linear(hiddenLayerNeurons, 2)
def forward(self, x, _):
    lowerBound = 26 - int(math.ceil(self.windowSize/2))
    upperBound = lowerBound + self.windowSize
    x = x1:, lowerBound:upperBound, lowerBound:upperBound]
    x = x.contiguous().view(-1, self.windowSize * self.windowSize * 25)
    x = self.input(x)
    for _ in range(self.nHiddenLayers-1):
        x = F.relu(self.hidden(x))
        x = self.dropout(x)
    x = F.softmax(self.output(x), dim=1)
    return x
```

NIPS architecture (when windowSize == 25)

```
class Classifier_Net(nn.Module):
 def __init__(self, hiddenLayerNeurons, nHiddenLayers, dropoutProb, windowSize):
     super().__init_()
     self.windowSize = windowSize
     self.nHiddenLayers = nHiddenLayers
     self.input = nn.Linear(windowSize * windowSize * 25, hiddenLayerNeurons)
     self.hidden = [None] * self.nHiddenLayers
     self.dropout = [None] * self.nHiddenLayers
     for i in rance(self.nHiddenLayers):
         self.hidden[i] = nn.Linear(hiddenLayerNeurons, hiddenLayerNeurons)
         self.hidden[i].cuda()
         self.dropout[i] = nn.Dropout(p = dropoutProb)
         self.dropout[i].cuda()
     self.output = nn.Linear(hiddenLayerNeurons, 2)
 def forward(self, x, _):
     lowerBound = 26 - int(math.ceil(self.windowSize/2))
     upperBound = lowerBound + self.windowSize
     x = x[:, lowerBound:upperBound, lowerBound:upperBound]
     x = x.contiguous().view(-1, self.windowSize * self.windowSize * 25)
     x = self.input(x)
     for i in range(self.nHiddenLayers-1);
         x = F.relu(self.hidden[i](x))
         x = self.dropout[i](x)
     x = F.softmax(self.output(x), dim=1)
     return x
```

#### fixed architecture

### **Baseline Classification**

Using a window size of 25x25 on new fixed-angle samples with energy between 50-70 GeV, we get an analogue of the data used in the NIPS paper.

When using the original buggy architecture, we got very slightly worse results (sorry, overwrote the plot). With the fixed architecture, our accuracy is better by about 4 percent.

#### **NIPS** paper

#### new samples

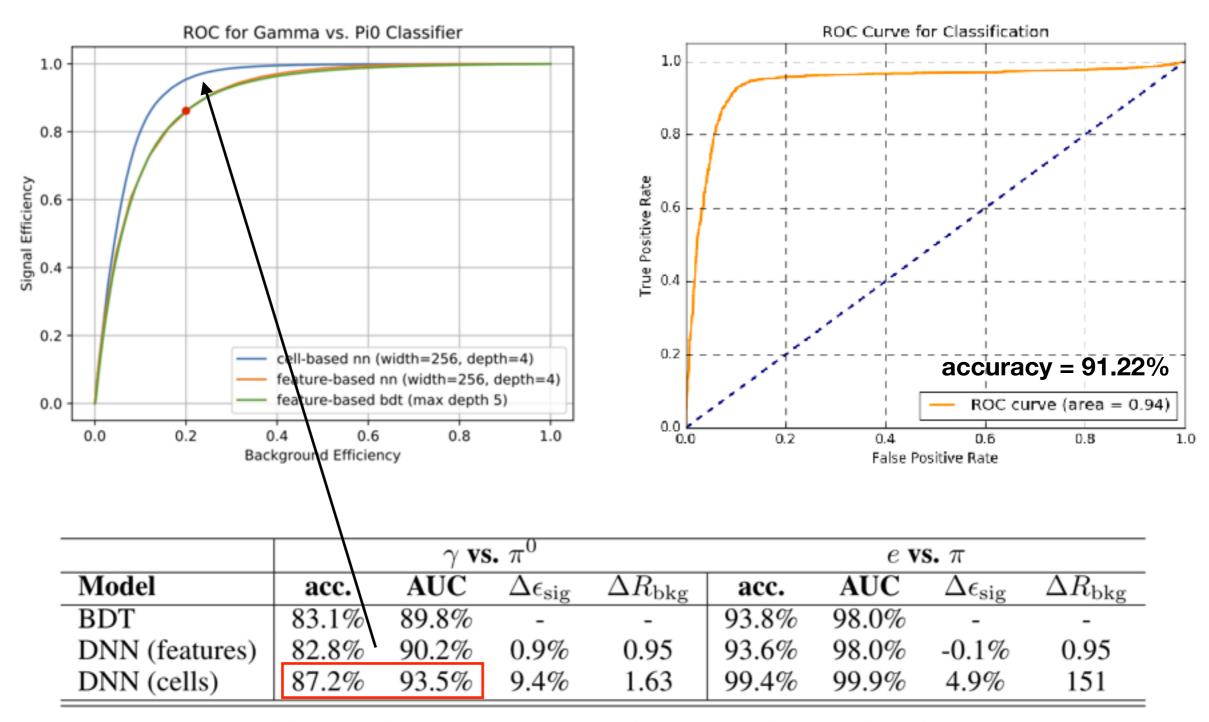
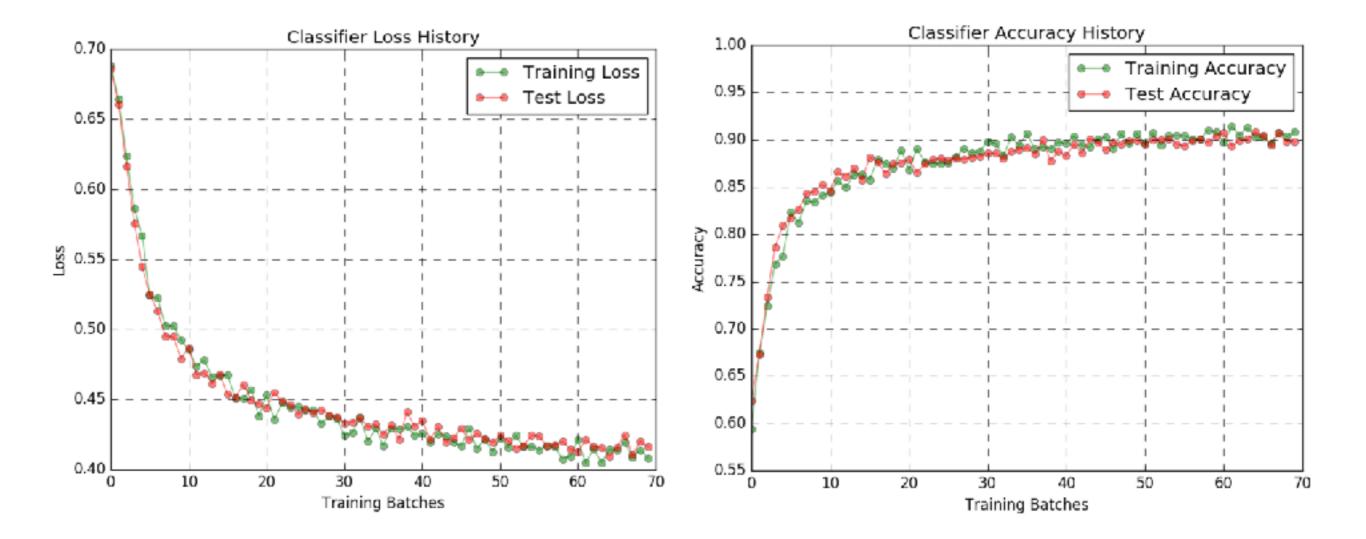


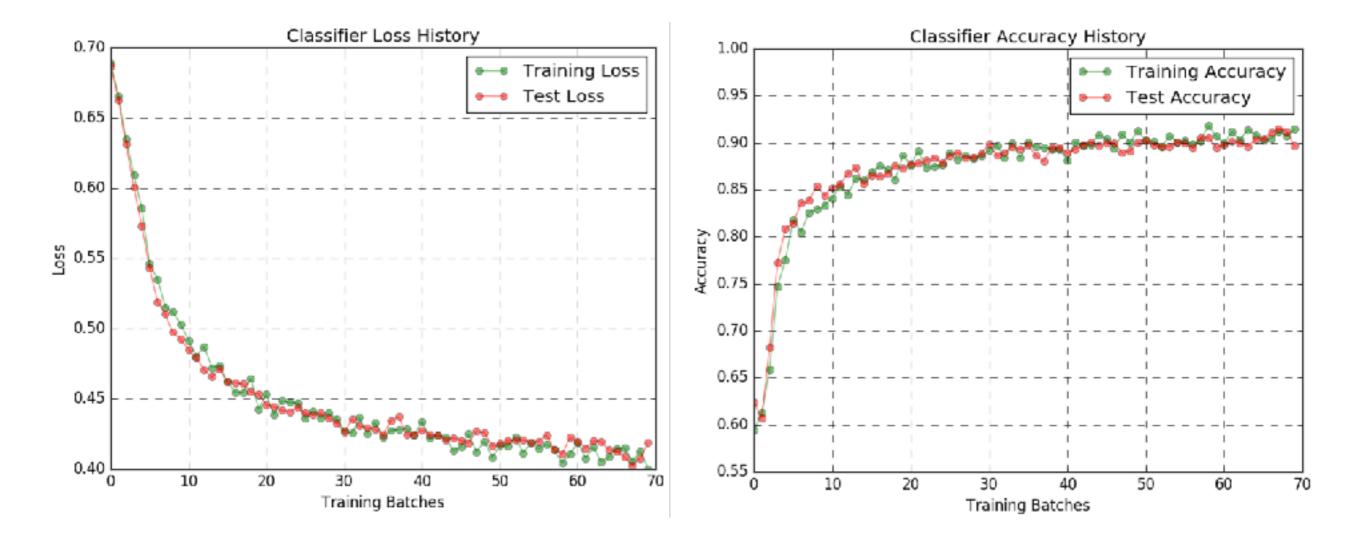
Table 1: Performance parameters for BDT and DNN classifiers.



### **Baseline w/ Expanded Window**

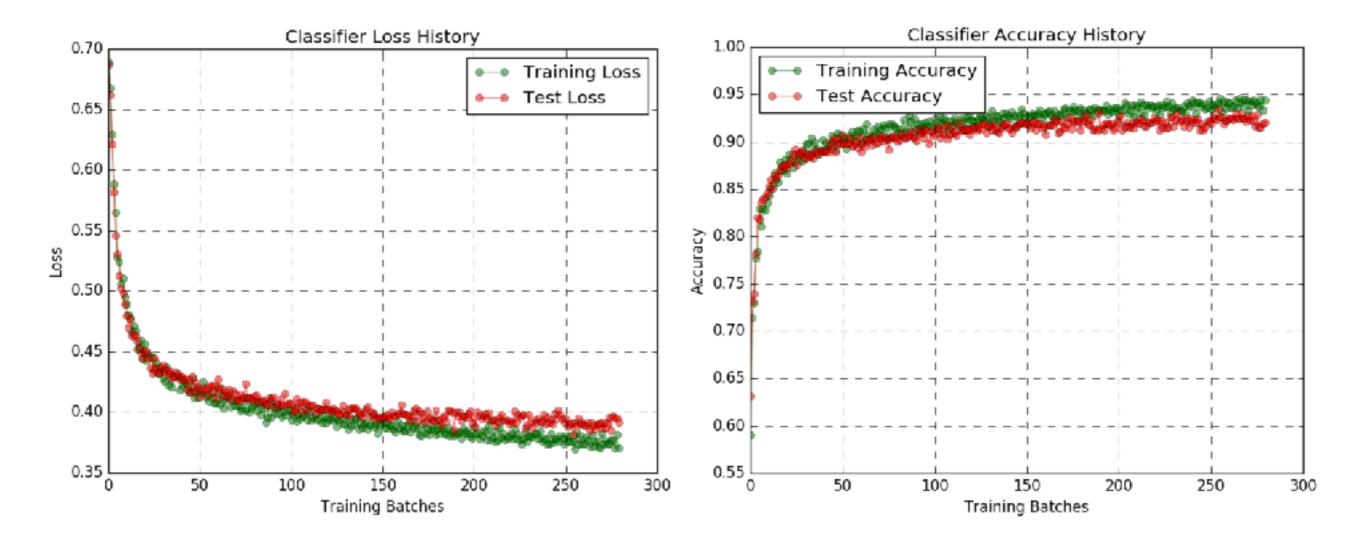
Using a window size of 51x51 on new fixed-angle samples with energy between 50-70 GeV, the same as before except with the larger window.

The results are maybe slightly better than the 25x25 window. Doesn't look like the larger window is either hurting or helping much. It's probably best to keep the larger window since it does contain some info.



### Expanded Window, Longer Train

Now training for 20 epochs instead of 5.



## **Energy-Range Classification**

Still using the NIPS architecture with a window size of 25x25, we now use all of the new fixed-angle samples (instead of just those with energy between 50-70 GeV). Note there are more samples, so it takes longer to get through 5 epochs of training.

We also show the results of various hyperparameter scans.

