# Calibration of the OSU setup (LJU diary 5)

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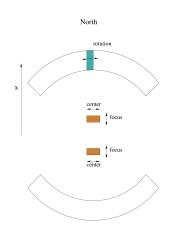


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### PET: layout



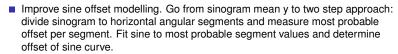
- Calibration refers to (micro) positioning of the detectors in the detector model
- A total of 5 parameters to be estimated: x and y of both Si sensors, rotation of the PSPMT module. Distance of PSPMT fixed.
- 4 runs at disposal: [20180920/16 si: 32k] [20180926/1 sibgo: 29k] [20180924/1 silyso: 10.5k] [20180928/1 1 lysobgo: 81k]
- Constraints: fixed rotation axis, equivalent to source following a sine curve with 0 offset focus of the source; exploit parallax to determine axial position of the sensor.

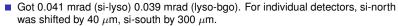
Parameters corellated

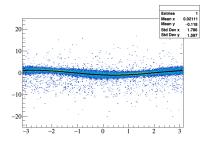


### PET: initial trials

- Couple of false starts:
- Overconstrained model tried first: allow only for y positions + rotation.
  Used sibgo run to fix si-north, si run to fix si-south si-lyso to determine rotation and compare to
  bgo-lyso rotation
- Rotations were 0.034 mrad (si-lyso) to 0.039 mrad (lyso-bgo).

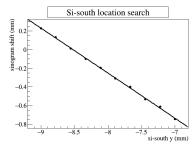






### PET: initial trials

- Very little noise in location search plots
- replaced binary search with data fitting. Binary search works well with sinogram mean y, but fitting noise may overwhelm the method at short steps.
- based on the slope and variation, expected accuracy is in  $\mu$ m.



- Discrepancy in PSPMT angle (remember: one arm goes through si-bgo, si-si and si-lyso, the other through lyso-bgo) is alleviated if I allow axial (along x) shift of si detectors.
- incorporate x-searching into calibration algorithm





## PET: calibration strategy 2.0

- Start with well defined sensors: bgo
- Use runs that collect bgo data to calibrate others: sibgo for si, lysobgo for PSPMT.
- For sibgo a y/x pairing plot can be made assume si-north is at a particular axial location x, the fixed axis requirement yields a corresponding y. Range between -130 and -120 should suffice
- The lysobgo run should yield a definitive lyso rotation.
- Once PSPMT rotation is known, similar plot as for si-north can be made using si-lyso data, again using only the fixed axis requirement.
- Then, si-north/si-south correlation can be made. At a particular distance of one detector module (say si-north) the fixed axis requirement will yield a particular si-south distance/offset combination.
- The si-north/si-south pairings will all yield a particular source focus on the si-si sinogram. The one with lowest spread/best resultion will be selected as the micro-positioning optimum.





### PET: calibration 2.0 initial results

- Automated procedure
- First results showing relation of x/y coordinates for fixed axis with si-north, based on the si-bgo run.

/home/studen/temp/calibration2/siNort





