Global numerical simulations of giant glitches in full general relativity

Aurélien Sourie



in collaboration with

N. Chamel (ULB), J. Novak (LUTH) & M. Oertel (LUTH)

Sourie, Oertel & Novak, PRD, 2016; Sourie, Chamel, Novak & Oertel, MNRAS, 2017



- 2 Equilibrium configurations of superfluid NSs
 Model assumptions
 Fluid couplings
- Applications to the dynamics of giant glitches
 - Transfer of angular momentum
 - Impact of GR on the dynamics of pulsar glitches

4 Conclusion

Introduction	
0	

Superfluid NSs at equilibrium

Applications to pulsar glitches 00000 Conclusion 00

Superfluidity in neutron stars

Theoretical predictions:

$$T \lesssim T_c^{\,\text{max}} \sim 10^8 - 10^{10}$$
 K

 \rightsquigarrow superfluid neutrons in the core & in the inner crust of NSs.





Observational evidence:

- Long relaxation time scales in pulsar glitches,
- Fast cooling in Cassiopeia A,
- QPOs from SGRs, ...

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
⊙●	0000000	00000	00
This work			

Consequence of superfluidity:

several **dynamically distinct** fluids inside NSs, coupled through both *dissipative* and *non-dissipative* effects.

Questions:

What is the impact of **general relativity** on the *non-dissipative couplings* between the fluids ?

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
⊙●	0000000	00000	00
This work			

Consequence of superfluidity:

several **dynamically distinct** fluids inside NSs, coupled through both *dissipative* and *non-dissipative* effects.

Questions:

What is the impact of **general relativity** on the *non-dissipative couplings* between the fluids ?

Are **general-relativistic effects** important on the *global dynamics* of *giant pulsars glitches* ?

Introduction

- Equilibrium configurations of superfluid NSs
 Model assumptions
 Fluid couplings
- Opplications to the dynamics of giant glitches
 - Transfer of angular momentum
 - Impact of GR on the dynamics of pulsar glitches

4 Conclusion

Superfluid NSs at equilibrium •••••• Applications to pulsar glitches 00000 Conclusion 00

Assumptions & ingredients Pricet al., PRD, 2005 & Sourie et al., PRD, 2016

Equilibrium configurations:

- T = 0 and no magnetic field,
- dissipative effects are neglected,
- uniform composition: p, e⁻, n
 the crust is not included,
- asymptotically flat, stationary, axisymmetric & circular metric,
- rigid-body rotation: Ω_n, Ω_p
 → global model.



< 🗆 I

6/21

Superfluid NSs at equilibrium 000000

Applications to pulsar glitches

Conclusion

Assumptions & ingredients Prix et al., PRD, 2005 & Sourie et al., PRD, 2016

Equilibrium configurations:

- T = 0 and no magnetic field,
- dissipative effects are neglected.
- **uniform** composition: p, e^-, n ↔ the crust is not included.
- asymptotically flat, stationary, axisymmetric & circular metric.
- **rigid-body** rotation: Ω_n , Ω_p → global model.



Superfluid NSs at equilibrium •••••• Applications to pulsar glitches 00000 Conclusion 00

Assumptions & ingredients Pricet al., PRD, 2005 & Sourie et al., PRD, 2016

Equilibrium configurations:

- T = 0 and no magnetic field,
- dissipative effects are neglected,
- uniform composition: p, e⁻, n
 the crust is not included,
- asymptotically flat, stationary, axisymmetric & circular metric,
- rigid-body rotation: Ω_n, Ω_p
 → global model.



The neutron star is thus described by two perfect fluids:

--- a neutron superfluid and a fluid of charged particles

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	⊙●○○○○○	00000	00
Equations c	of state		

- Polytropic EoSs,
- Density-dependent RMF models (DDH & DDH δ).



Introduction 00 Superfluid NSs at equilibrium

Applications to pulsar glitches

Conclusion 00

Fluid angular momenta

→ Komar angular momentum (axisymmetry):

$$J_{\mathsf{K}} = J_{\mathsf{n}} + J_{\mathsf{p}}$$

see Langlois, Sedrakian & Carter, MNRAS, 1998.

Intr	o di	io	

Superfluid NSs at equilibrium

Applications to pulsar glitches

Conclusion 00

Fluid angular momenta

→ Komar angular momentum (axisymmetry):

$$J_{\mathsf{K}} = J_{\mathsf{n}} + J_{\mathsf{p}}$$

see Langlois, Sedrakian & Carter, MNRAS, 1998.

Moments of inertia:

$$dJ_X = I_{XX} \ d\Omega_X + I_{XY} \ d\Omega_Y \qquad X, Y \in \{n, p\}$$
$$\hat{I}_X = I_{XX} + I_{XY} \qquad \hat{I} = \hat{I}_n + \hat{I}_p$$

< □ →

Intr	o di	io	

Superfluid NSs at equilibrium

Applications to pulsar glitches

Conclusion 00

Fluid angular momenta

→ Komar angular momentum (axisymmetry):

$$J_{\mathsf{K}} = J_{\mathsf{n}} + J_{\mathsf{p}}$$

see Langlois, Sedrakian & Carter, MNRAS, 1998.

Moments of inertia:

$$dJ_X = I_{XX} \ d\Omega_X + I_{XY} \ d\Omega_Y \qquad X, Y \in \{n, p\}$$
$$\hat{I}_X = I_{XX} + I_{XY} \qquad \hat{I} = \hat{I}_n + \hat{I}_p$$

 $\rightarrow I_{XY}$ contains any possible non-dissipative couplings between the fluids.

< 🗆)

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	०००●०००	00000	00
Angular m	nomentum of fluid X		

In the slow-rotation approximation and to first order in the lag $\delta\Omega = \Omega_n - \Omega_p$, we get:

$$\begin{split} J_X &\simeq \int_{\Sigma_t} n_X \mu^X \frac{B}{N} \left(\Omega_X - \omega \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \\ &+ \int_{\Sigma_t} n_X \mu^X \varepsilon_X \frac{B}{N} \left(\Omega_Y - \Omega_X \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \end{split}$$

Introduction 00	Superfluid NSs at eq ०००●०००	uilibrium	Applications to pulsar glitches	Conclusion 00
A manula m		finial V		

In the slow-rotation approximation and to first order in the lag $\delta\Omega=\Omega_n-\Omega_p$, we get:

$$\begin{split} J_X &\simeq \int_{\Sigma_t} n_X \mu^X \frac{B}{N} \left(\Omega_X - \omega \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \\ &+ \int_{\Sigma_t} n_X \mu^X \varepsilon_X \frac{B}{N} \left(\Omega_Y - \Omega_X \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \end{split}$$

entrainment effect

due to the strong interactions between nucleons *in the core*:

$$p_X^{\alpha} = \mathcal{K}^{XX} n_X u_X^{\alpha} + \mathcal{K}^{XY} n_Y u_Y^{\alpha}$$

relativistic frame-dragging effect

associated with the rotation of the two fluids, Ω_n and Ω_p :

$$g_{t\varphi} \neq 0$$

Carter, Annals of Physics, 1975

PHAROS WG1+WG2 meeting

University of Coimbra - September, 27th 2018

Andreev & Bashkin, SJETP, 1976

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	००००●००	00000	00
Fluid cou	olings		

$$J_X = \int n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta \, \mathrm{d}^3 V \times \Omega_X$$
$$+ \int \varepsilon_X n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta \, \mathrm{d}^3 V \times (\Omega_Y - \Omega_X)$$
$$- \int \omega n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta \, \mathrm{d}^3 V$$

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	००००●००	00000	00
Fluid cour	olings		

$$J_{X} = \int n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times \Omega_{X} \qquad \rightsquigarrow \quad I_{X} \Omega_{X}$$
$$+ \int \varepsilon_{X} n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times (\Omega_{Y} - \Omega_{X})$$
$$- \int \omega n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V$$

• $I_X =$ "moment of inertia" of fluid $X \rightarrow \int_{\Sigma_t} \rho_X r^2 \sin^2 \theta \, d^3 V$

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	००००●००	00000	00
Fluid cou	plings		

$$J_{X} = \int n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times \Omega_{X} \qquad \rightsquigarrow \quad I_{X} \Omega_{X}$$
$$+ \int \varepsilon_{X} n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times (\Omega_{Y} - \Omega_{X}) \qquad \rightsquigarrow \quad I_{X} \tilde{\varepsilon}_{X} (\Omega_{Y} - \Omega_{X})$$
$$- \int \omega n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V$$

• $I_X =$ "moment of inertia" of fluid $X \rightarrow \int_{\Sigma_t} \rho_X r^2 \sin^2 \theta \, d^3 V$

• $\tilde{\varepsilon}_X$ = entrainment parameter averaged over the star.

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	○○○○●○○	00000	00
Fluid cou	nlings		

$$J_{X} = \int n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times \Omega_{X} \qquad \rightsquigarrow \quad I_{X} \Omega_{X}$$
$$+ \int \varepsilon_{X} n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \times (\Omega_{Y} - \Omega_{X}) \qquad \rightsquigarrow \quad I_{X} \tilde{\varepsilon}_{X} (\Omega_{Y} - \Omega_{X})$$
$$- \int \omega n_{X} \mu^{X} \frac{B}{N} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V \qquad \qquad \rightsquigarrow \quad - I_{X} \left(\varepsilon_{XX}^{LT} \Omega_{X} + \varepsilon_{YX}^{LT} \Omega_{Y} \right)$$

• $I_X =$ "moment of inertia" of fluid $X \rightarrow \int_{\Sigma_r} \rho_X r^2 \sin^2 \theta \, d^3 V$

- $\tilde{\varepsilon}_X$ = entrainment parameter averaged over the star.
- $\varepsilon_{YX}^{LT} \& \varepsilon_{XX}^{LT}$ = contribution of fluids Y and X on Lense-Thirring effects on X.

Introduction Superfluid NSs at equilibrium Applications to pulsar glitches Conclusion oo

Entrainment VS frame-dragging

In the general-relativistic framework, one thus gets:

$$J_{X} = I_{X} \left(1 - \varepsilon_{XX}^{LT} - \tilde{\varepsilon}_{X} \right) \Omega_{X} + I_{X} \left(\tilde{\varepsilon}_{X} - \varepsilon_{YX}^{LT} \right) \Omega_{Y}$$

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	○○○○○●○	00000	00
Entrainment	t VS frame-dragging		

In the general-relativistic framework, one thus gets:

$$J_{X} = I_{X} \left(1 - \varepsilon_{XX}^{LT} - \tilde{\varepsilon}_{X} \right) \Omega_{X} + I_{X} \left(\tilde{\varepsilon}_{X} - \varepsilon_{YX}^{LT} \right) \Omega_{Y}$$

• In the Newtonian limit (see, e.g., Sidery+, MNRAS, 2010):

$$J_X = I_X \left(1 - \tilde{\varepsilon}_X \right) \Omega_X + I_X \tilde{\varepsilon}_X \Omega_Y$$

 $-\rightarrow$ the fluids are only coupled by entrainment.

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	०००००●੦	00000	00
Entrainme	nt VS frame-dragging		

In the general-relativistic framework, one thus gets:

$$J_{X} = I_{X} \left(1 - \varepsilon_{XX}^{LT} - \tilde{\varepsilon}_{X} \right) \Omega_{X} + I_{X} \left(\tilde{\varepsilon}_{X} - \varepsilon_{YX}^{LT} \right) \Omega_{Y}$$

• In the **Newtonian limit** (see, e.g., Sidery+, *MNRAS*, 2010):

$$J_X = I_X \left(1 - \tilde{\varepsilon}_X \right) \Omega_X + I_X \tilde{\varepsilon}_X \Omega_Y$$

 $-\rightarrow$ the fluids are only coupled by entrainment.

• In **GR**: additional coupling through frame-dragging effects. --→ already pointed out by Carter, Annals of Physics, 1975

Introduction

Superfluid NSs at equilibrium 000000● Applications to pulsar glitches 00000 Conclusion 00

Entrainment VS frame-dragging

Total coupling coefficients:

$$\hat{\varepsilon}_{X} = I_{XY} / \left(I_{XX} + I_{XY} \right)$$

In the slow-rotation approximation:

$$\hat{\varepsilon}_{\mathsf{p}} = \frac{\tilde{\varepsilon}_{\mathsf{p}} - \varepsilon_{\mathsf{n}\,\mathsf{p}}^{LT}}{1 - \varepsilon_{\mathsf{p}\,\mathsf{p}}^{LT} - \varepsilon_{\mathsf{n}\,\mathsf{p}}^{LT}}$$

Remarks:

• in Newt. gravity: $\hat{\varepsilon}_{X} = \tilde{\varepsilon}_{X}$

•
$$\hat{\varepsilon}_{n} = \hat{I}_{p} / \hat{I}_{n} \times \hat{\varepsilon}_{p} \simeq 0.05 \times \hat{\varepsilon}_{p}$$



Introduction 00 Superfluid NSs at equilibrium 000000● Applications to pulsar glitches 00000 Conclusion

Entrainment VS frame-dragging

Total coupling coefficients:

$$\hat{\varepsilon}_{X} = I_{XY} / \left(I_{XX} + I_{XY} \right)$$

In the slow-rotation approximation:

$$\hat{\varepsilon}_{\mathbf{p}} = \frac{\tilde{\varepsilon}_{\mathbf{p}} - \varepsilon_{\mathbf{n}\,\mathbf{p}}^{LT}}{1 - \varepsilon_{\mathbf{p}\,\mathbf{p}}^{LT} - \varepsilon_{\mathbf{n}\,\mathbf{p}}^{LT}}$$

Remarks:

• in Newt. gravity: $\hat{\varepsilon}_X = \tilde{\varepsilon}_X$

•
$$\hat{\varepsilon}_{n} = \hat{I}_{p} / \hat{I}_{n} \times \hat{\varepsilon}_{p} \simeq 0.05 \times \hat{\varepsilon}_{p}$$



- Model assumptions • Fluid couplings
- 3 Applications to the dynamics of giant glitches
 - Transfer of angular momentum
 - Impact of GR on the dynamics of pulsar glitches

Introduction Superfluid NSs at equilibrium

Applications to pulsar glitches ●0000 Conclusion 00

Vortex-mediated glitch theory

Anderson & Itoh, Nature, 1975



Key assumption: the vortices can **pin** to the crust and/or to flux tubes.

Introduction Superfluid NSs at equilibrium

Applications to pulsar glitches ●0000 Conclusion 00

Vortex-mediated glitch theory

Anderson & Itoh, Nature, 1975



Once a critical lag $\Omega_n - \Omega_p$ is reached:

some vortices get unpinned and are allowed to move radially

--> angular momentum transfer between the fluids

00 000000	00000	actors to pulsar gritches	00
Angular momentum t	ransfer et al., <i>MNRAS</i> , 2010		

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	⊙●○○○	00
Angular mo	mentum transfer 5. 1998 & Sidery et al.: <i>MNRAS</i> , 2010		

$$\Gamma_{\text{int}} = -\int \frac{\mathcal{R}}{1+\mathcal{R}^2} \Gamma_{n} n_{n} \varpi_{n} \chi_{\perp}^2 \, \mathrm{d}\Sigma \times (\Omega_{n} - \Omega_{p}) = -2\bar{\mathcal{B}}\hat{l}_{n} \Omega_{n} \zeta \times \delta\Omega$$

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	⊙●○○○	00
Angular mo	mentum transfer 5. 1998 & Sidery et al.: <i>MNRAS</i> , 2010		

$$\Gamma_{\text{int}} = -\int \frac{\mathcal{R}}{1+\mathcal{R}^2} \Gamma_{n} n_{n} \varpi_{n} \chi_{\perp}^2 \, \mathrm{d}\Sigma \times (\Omega_{n} - \Omega_{p}) = -2\bar{\mathcal{B}}\hat{l}_{n} \Omega_{n} \zeta \times \delta\Omega$$

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	⊙●○○○	00
Angular mo	mentum transfer 5. 1998 & Sidery et al.: <i>MNRAS</i> , 2010		

$$\Gamma_{\text{int}} = -\int \frac{\mathcal{R}}{1+\mathcal{R}^2} \Gamma_n n_n \varpi_n \chi_{\perp}^2 \, d\Sigma \times (\Omega_n - \Omega_p) = -2\bar{\mathcal{B}}\hat{l}_n \Omega_n \zeta \times \delta\Omega$$
superfluid vorticity

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	○●○○○	00
Angular mo	mentum transfer 5 1998 & Sidery et al., <i>MNRAS</i> , 2010		



Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	○●○○○	00
Angular mo	mentum transfer 5 1998 & Sidery et al., <i>MNRAS</i> , 2010		



Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	○●○○○	00
Angular mo	mentum transfer 5 1998 & Sidery et al., <i>MNRAS</i> , 2010		

Assuming straight vortices, the mutual friction moment considered reads



→ the geometry of the vortex array and the interactions between superfluid vortices and superconducting flux tubes are **poorly known**.

Introduction 00	Superfluid NSs at equilibrium 0000000	Applications to 00●00	pulsar glitches	Conclusion 00
Spin-up t	ime scale			
Evolu	tion equations:			
(— — — Г .	۰. ف	<u>^</u> ^	

$$\begin{cases} J_{n} = +I_{int}, \\ \dot{J}_{p} = -\Gamma_{int}. \end{cases} \longrightarrow \frac{\delta\Omega}{\delta\Omega} = -\frac{II_{n}}{I_{nn}I_{pp} - I_{np}^{2}} \times 2\bar{\mathcal{B}}\zeta\Omega_{n} \end{cases}$$

► Theoretical rise time:

$$\rightsquigarrow \delta\Omega(t) = \delta\Omega_0 \times e^{-\frac{t}{\tau_r}}$$

$$\tau_{\rm r} = \frac{\hat{l}_{\rm p}}{\hat{l}} \times \frac{1 - \hat{\varepsilon}_{\rm p} - \hat{\varepsilon}_{\rm n}}{2\zeta \bar{\mathcal{B}} \Omega_{\rm n}}$$

Introduction 00	Superfluid NSs at equilibrium 0000000	Applications 00●00	s to pulsar glitches	Conc 00	lusion
Spin-up t	ime scale				
Evolu	tion equations:				
j j	$n_n = + \Gamma_{int},$	$\delta \dot{\Omega}$	ĴĴ n		

 $\int J_p = -\Gamma_{int}$.

$$\rightsquigarrow \delta\Omega(t) = \delta\Omega_0 \times e^{-\frac{t}{\tau_r}}$$

$$\tau_{\rm r} = \frac{\hat{l}_{\rm p}}{\hat{l}} \times \frac{1 - \hat{\varepsilon}_{\rm p} - \hat{\varepsilon}_{\rm n}}{2\zeta \bar{\mathcal{B}} \Omega_{\rm n}}$$

 $\overline{\delta\Omega} = -\frac{1}{I_{\rm nn}I_{\rm pp} - I_{\rm np}^2} \times 2B\zeta\Omega_{\rm n}$

Numerical modelling:

hyp: hydrodynamical time ~ 0.1 ms \ll rise time (dissipation)

--→ Computation of $\Omega_n(t)$ & $\Omega_p(t)$ profiles from $\Omega_{n,0} > \Omega_{p,0}$ using a quasi-stationary sequence of equilibrium configurations.

l ntroduct ○○	ion Superfluid NSs a 0000000	tequilibrium App 000	lications to pulsar glitches ●○	Conclusion 00
Time	e evolution			
	$\Delta\Omega/\Omega = M$	10 ⁻⁶ , $\Omega_{\sf n}^f = \Omega_{\sf p}^f = {ar B}$ ${}^{\prime}_{\sf G} = 1.4~{\sf M}_{\odot}~\&~ar {\cal B}$ =	$2\pi imes 11.19$ Hz, $= 10^{-4}$	
1.2×10 ⁻¹ 1×10 ⁻¹ 0 ⁻¹	$\Omega_n^0 \Omega_n$	$\Omega_{n}^{l} = \Omega_{p}^{l}$ $($ $\Omega_{n}^{l} = \Omega_{p}^{l}$ $($ $($ C C $($ C	$\begin{array}{c c} DDH & -r \\ DDH & -r \\ DDH & -r \\ DDH & -r \\ fit: \tau_r = \\ DDH & -r \\ fit: \tau_r = \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	umerics + 4.23 s

---> the spin-up time scale can be very precisely estimated from *stationary configurations* only.

t (s)

PHAROS WG1+WG2 meeting University of Coimbra - September, 27th 2018

10⁻¹⁰

t (s)



--- GR can have a large impact on the dynamics of pulsar glitches!

1 Introduction

- 2 Equilibrium configurations of superfluid NSs
 Model assumptions
 2 Elvid assumptions
 - Fluid couplings
- 3 Applications to the dynamics of giant glitches
 - Transfer of angular momentum
 - Impact of GR on the dynamics of pulsar glitches

4 Conclusion

Introduction	Superfluid NSs at equilibrium	Applications to pulsar glitches	Conclusion
00	0000000	00000	●○
Conclusion	& perspectives		

- Additional coupling through relativistic frame-dragging effects,
- Relativistic corrections on the spin-up time: \sim 50% (core),
 - \hookrightarrow should be included in a quantitative model of glitches.

Future work:

- Build a local model in which only a small part of the superfluid is decoupled from the rest of the star (differential rotation),
- Take the crust into account!



Antonelli & Pizzochero, 2017

Superfluid NSs at equilibrium

Applications to pulsar glitches



Thank you!



Influence of general relativity on $\tau_{\rm r}$



Rotating neutron stars, at **equilibrium**, described by $(\mathcal{E}, \boldsymbol{g})$:

- ullet asymptotically flat: $oldsymbol{g} o oldsymbol{\eta}$ at spatial infinity $(r o +\infty),$
- stationary & axisymmetric: $\frac{\partial g_{\alpha\beta}}{\partial t} = \frac{\partial g_{\alpha\beta}}{\partial \varphi} = 0$,
- circular: perfect fluids \Rightarrow purely circular motion around the rotation axis with Ω_n , Ω_p (+ rigid rotation).

Spacetime metric in quasi-isotropic coordinates:

 $g_{\alpha\beta} \,\mathrm{d} x^{\alpha} \,\mathrm{d} x^{\beta} = -N^2 \,\mathrm{d} t^2 + A^2 (\mathrm{d} r^2 + r^2 \,\mathrm{d} \theta^2) + B^2 r^2 \sin^2 \theta (\mathrm{d} \varphi - \omega \,\mathrm{d} t)^2$

At spatial infinity

$$N, A, B \rightarrow 1$$
 & $\omega \rightarrow 0$

Metric potentials



Image: Ima

Relativistic two-fluid hydrodynamics

Carter, "Covariant theory of conductivity in ideal fluid or solid media", 1989 & Carter & Langlois, Nuc. Phys. B, 1998

System = two **perfect** fluids:

- superfluid neutrons $\rightarrow \vec{n}_n = n_n \vec{u}_n$,
- protons & electrons $\rightarrow \vec{n}_{p} = n_{p}\vec{u}_{p}$.

Energy-momentum tensor

$$T_{\alpha\beta} = n_{n\alpha} p_{\beta}^{n} + n_{p\alpha} p_{\beta}^{p} + \Psi g_{\alpha\beta}$$

 \hookrightarrow conjugate momenta

Entrainment matrix:

$$\begin{cases} p_{\alpha}^{\mathsf{n}} = \mathcal{K}^{\mathsf{n}\mathsf{n}} n_{\alpha}^{\mathsf{n}} + \mathcal{K}^{\mathsf{n}\mathsf{p}} n_{\alpha}^{\mathsf{p}} \\ p_{\alpha}^{\mathsf{p}} = \mathcal{K}^{\mathsf{p}\mathsf{n}} n_{\alpha}^{\mathsf{n}} + \mathcal{K}^{\mathsf{p}\mathsf{p}} n_{\alpha}^{\mathsf{p}} \end{cases}$$

--> entrainment effect

Equation of state $\mathcal{E}(n_{n}, n_{p}, \Delta^{2})$

< 🗆)

3+1 formalism



Foliation of the spacetime (\mathcal{E}, g) by $(\Sigma_t)_{t \in \mathbb{R}^2}$ with unit normal \vec{n}

Eulerian observer \mathcal{O}_n : 4-velocity = \vec{n}

• lapse function N : $\vec{n} = -N\vec{\nabla}t$, • shift vector $\vec{\beta}$: $\vec{\partial}_t = N\vec{n} + \vec{\beta}$.



3+1 metric:

$$g_{\alpha\beta} \,\mathrm{d} x^{\alpha} \,\mathrm{d} x^{\beta} = -N^2 \,\mathrm{d} t^2 + \gamma_{ij} \left(\mathrm{d} x^i + \beta^i \,\mathrm{d} t\right) \left(\mathrm{d} x^j + \beta^j \,\mathrm{d} t\right)$$

< 🗆 I

Numerical procedure



$$|H_{k+1}^{i}(r,\theta) - H_{k}^{i}(r,\theta)| < \epsilon$$

At each iteration

For given values of $(\mu^{n}, \mu^{p}, \Delta^{2})$, we compute:

- 1. Ψ , $n_{\rm n}, n_{\rm p}$ and lpha from the EoS
- 2. The source terms E, p_{φ} , S^{i}_{i} ,
- 3. Einstein Equations are solved,
- 4. Kinetic terms U_i et Γ_i ,
- 5. Computation of H_{k+1}^i .

< 🗆)

Density profiles

$$M_{
m G}=1.4$$
 ${
m M}_{\odot}$, $\Omega_{
m n}/2\pi=\Omega_{
m p}/2\pi=716$ Hz



< □ ▶

28 / 21

Superfluid vorticity

$$w_{\mu\nu} =
abla_{\mu}p_{\nu}^{n} -
abla_{\nu}p_{\mu}^{n} \longrightarrow \varpi_{n} = \sqrt{rac{w_{\mu\nu}w^{\mu\nu}}{2}}$$



 $\Omega^{n}/2\pi = \Omega^{p}/2\pi = 716 \text{ Hz}$

< 🗆 I

Angular momenta

Axisymmetry $\leftrightarrow ~ec{\chi}$

Komar definition:

$$J_{\mathsf{K}} = -\int_{\Sigma_t} \underbrace{\boldsymbol{\mathcal{T}}(\vec{\boldsymbol{n}}, \vec{\boldsymbol{\chi}})}_{-p_{\varphi}} \,\,\mathrm{d}^3 V$$



Eulerian observer \vec{n} (3+1)

Angular momentum of each fluid Langlois, Sedrakian & Carter, MNRAS, 1998

$$p_{\varphi} = \underbrace{\prod_{n} n_{n} p_{\varphi}^{n}}_{j_{\varphi}^{n}} + \underbrace{\prod_{p} n_{p} p_{\varphi}^{p}}_{j_{\varphi}^{p}}$$
$$\mathbf{x} = \int_{\Sigma_{t}} j_{\varphi}^{\mathbf{X}} A^{2} B r^{2} \sin \theta \, \mathrm{d}r \, \mathrm{d}\theta \, \mathrm{d}\varphi$$

< 🗆 I

Fluid couplings



< 🗆)

Influence of Ω on the couplings



Where does the vortex unpinning take place?

Glitches have been generally thought to originate from the crust, because:

- the core superfluid was expected to be strongly coupled to the crust Alpar et al., ApJ, 1984
- the analysis of glitch data suggested that the superfluid represents a few percent of the total angular momentum of the star Link et al., PRL, 1999

However, this scenario has been recently challenged:

- considering entrainment effects, the crust does not carry enough angular momentum Andersson et al., PRL, 2012 & Chamel, PRL, 2013
- ► a huge glitch has been observed in PSR 2334+61 Alpar, AIP Conf.Proc., 2011
- the core superfluid could be decoupled from the rest of the star, if vortices are pinned to flux tubes Gügercinoglu & Alpar, ApJ, 2014

The core superfluid plays a more important role than previously thought.

Gravitational wave amplitude



PHAROS WG1+WG2 meeting

University of Coimbra - September, 27th 2018

Dynamical effective mass:

$${}^{3}\vec{p}_{X}=m_{X}^{*}{}^{3}\vec{u}_{X}$$

 \rightarrow in the rest frame of the second fluid.



The Vela pulsar

$$\Delta\Omega/\Omega=10^{-6}$$
, $\Omega_{
m n}^{f}=\Omega_{
m p}^{f}=2\pi imes11.19$ Hz



 $\blacktriangleright \ \bar{\mathcal{B}} \nearrow \Longrightarrow \tau_{\mathsf{r}} \searrow$

The Vela pulsar

$$\Delta\Omega/\Omega=10^{-6}$$
, $\Omega_{
m n}^{f}=\Omega_{
m p}^{f}=2\pi imes11.19$ Hz



$$\blacktriangleright \ \bar{\mathcal{B}} \nearrow \Longrightarrow \tau_{\mathsf{r}} \searrow$$

$$au_{
m r} < 30 \ {
m s} \Rightarrow {ar {\cal B}} > 10^{-5}$$

< 🗆)

The Vela pulsar

$$\Delta\Omega/\Omega=10^{-6}$$
, $\Omega_{
m n}^{f}=\Omega_{
m p}^{f}=2\pi imes11.19$ Hz



$$\blacktriangleright \ \bar{\mathcal{B}} \nearrow \Longrightarrow \tau_{\mathsf{r}} \searrow$$

$$au_{
m r} < 30 \,\, {
m s} \Rightarrow ar{\mathcal{B}} > 10^{-5}$$

•
$$ar{\mathcal{B}} < 0.5 \rightsquigarrow au_{
m r} > 0.6~{
m ms}$$

 $\stackrel{\longleftrightarrow}{\hookrightarrow} \text{the glitch event is a} \\ \textbf{quasi-stationary} \text{ process} \\$

In Newtonian gravity

In the Newtonian limit ($\mu^{X}\simeq m_{X}$, B=N=1, $\omega=0$), we get:

$$J_{X} = \int_{\Sigma_{t}} \rho_{X} \left(1 - \varepsilon_{X}\right) \Omega_{X} r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V + \int_{\Sigma_{t}} \rho_{X} \varepsilon_{X} \left(\Omega_{Y} - \Omega_{X}\right) r^{2} \sin^{2} \theta \, \mathrm{d}^{3} V$$

Defining the moment of inertia I_X and the mean entrainment parameter $\tilde{\varepsilon}_X$ as

$$I_X \equiv \int_{\Sigma_t} \rho_X r^2 \sin^2 \theta \, \mathrm{d}^3 V \qquad \qquad I_X \tilde{\varepsilon}_X \equiv \int_{\Sigma_t} \rho_X r^2 \sin^2 \theta \, \varepsilon_X \, \mathrm{d}^3 V$$

$$J_{X} = I_{X} \left(1 - \tilde{\varepsilon}_{X} \right) \Omega_{X} + I_{X} \tilde{\varepsilon}_{X} \Omega_{Y}$$

$$\rightsquigarrow I_{XY} = \frac{\partial J_X}{\partial \Omega_Y} = I_X \tilde{\varepsilon}_X$$

see, e.g., Sidery, Passamonti & Andersson, *MNRAS*, 2010.

Let's go back to

$$\begin{split} J_X &\simeq \int_{\Sigma_t} n_X \mu^X \frac{B}{N} \left(\Omega_X - \omega \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \\ &+ \int_{\Sigma_t} n_X \mu^X \varepsilon_X \frac{B}{N} \left(\Omega_Y - \Omega_X \right) r^2 \sin^2 \theta \, \mathrm{d}^3 V \end{split}$$

Let's go back to

$$J_{X} \simeq \int_{\Sigma_{t}} i_{X} \left(\Omega_{X} - \omega\right) \, \mathrm{d}^{3}V + \int_{\Sigma_{t}} i_{X} \varepsilon_{X} \left(\Omega_{Y} - \Omega_{X}\right) \, \mathrm{d}^{3}V$$

where $i_X \equiv n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta$ (\rightarrow in Newt. grav., $i_X = \rho_X r^2 \sin^2 \theta$).

Let's go back to

$$J_{\boldsymbol{X}} \simeq \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{X}} - \boldsymbol{\omega} \right) \, \mathrm{d}^{3} \boldsymbol{V} + \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \boldsymbol{\varepsilon}_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{Y}} - \boldsymbol{\Omega}_{\boldsymbol{X}} \right) \, \mathrm{d}^{3} \boldsymbol{V}$$

where $i_X \equiv n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta$ (\rightarrow in **Newt. grav.**, $i_X = \rho_x r^2 \sin^2 \theta$).

The "moment of inertia" I_X and the mean entrainment parameter $\tilde{\varepsilon}_X$ are now given by

$$I_X \equiv \int_{\Sigma_t} i_X \, \mathrm{d}^3 V \qquad \qquad I_X \tilde{\varepsilon}_X \equiv \int_{\Sigma_t} i_X \varepsilon_X \, \mathrm{d}^3 V$$

Let's go back to

$$J_{\boldsymbol{X}} \simeq \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{X}} - \boldsymbol{\omega} \right) \, \mathrm{d}^{3} \boldsymbol{V} + \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \boldsymbol{\varepsilon}_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{Y}} - \boldsymbol{\Omega}_{\boldsymbol{X}} \right) \, \mathrm{d}^{3} \boldsymbol{V}$$

where $i_X \equiv n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta$ (\rightarrow in **Newt. grav.**, $i_X = \rho_x r^2 \sin^2 \theta$).

The "moment of inertia" I_X and the mean entrainment parameter $\tilde{\varepsilon}_X$ are now given by

$$I_X \equiv \int_{\Sigma_t} i_X \, \mathrm{d}^3 V \qquad \qquad I_X \tilde{\varepsilon}_X \equiv \int_{\Sigma_t} i_X \varepsilon_X \, \mathrm{d}^3 V$$

The additional term associated with **frame-dragging effect** can be expressed as

$$\int_{\Sigma_{\mathbf{f}}} i_{\mathbf{X}} \omega \, \mathrm{d}^{3} \mathbf{V} \equiv I_{\mathbf{X}} \left(\varepsilon_{\mathbf{X} \to \mathbf{X}}^{LT} \Omega_{\mathbf{X}} + \varepsilon_{\mathbf{Y} \to \mathbf{X}}^{LT} \Omega_{\mathbf{Y}} \right)$$

Let's go back to

$$J_{\boldsymbol{X}} \simeq \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{X}} - \boldsymbol{\omega} \right) \, \mathrm{d}^{3} \boldsymbol{V} + \int_{\boldsymbol{\Sigma}_{\boldsymbol{t}}} i_{\boldsymbol{X}} \boldsymbol{\varepsilon}_{\boldsymbol{X}} \left(\boldsymbol{\Omega}_{\boldsymbol{Y}} - \boldsymbol{\Omega}_{\boldsymbol{X}} \right) \, \mathrm{d}^{3} \boldsymbol{V}$$

where $i_X \equiv n_X \mu^X \frac{B}{N} r^2 \sin^2 \theta$ (\rightarrow in **Newt. grav.**, $i_X = \rho_x r^2 \sin^2 \theta$).

The "moment of inertia" I_X and the mean entrainment parameter $\tilde{\varepsilon}_X$ are now given by

$$I_X \equiv \int_{\Sigma_t} i_X \, \mathrm{d}^3 V \qquad \qquad I_X \tilde{\varepsilon}_X \equiv \int_{\Sigma_t} i_X \varepsilon_X \, \mathrm{d}^3 V$$

The additional term associated with **frame-dragging effect** can be expressed as

$$\int_{\Sigma_{t}} i_{X} \omega \, \mathrm{d}^{3} V \equiv I_{X} \left(\varepsilon_{X \to X}^{LT} \Omega_{X} + \varepsilon_{Y \to X}^{LT} \Omega_{Y} \right)$$

$$J_{X} = I_{X} \left(1 - \varepsilon_{X \to X}^{LT} - \tilde{\varepsilon}_{X} \right) \Omega_{X} + I_{X} \left(\tilde{\varepsilon}_{X} - \varepsilon_{Y \to X}^{LT} \right) \Omega_{Y}$$

Frame-dragging contribution

$$\rightsquigarrow I_{XY} = \frac{\partial J_X}{\partial \Omega_Y} = I_X \left(\tilde{\varepsilon}_X - \varepsilon_{Y \to X}^{LT} \right)$$

--- additional coupling arising from frame-dragging effects.

Already pointed out by B. Carter in 1975. By dimensional considerations:

$$\begin{split} I_{n} \varepsilon_{pn}^{LT} &= I_{p} \varepsilon_{np}^{LT} \\ &\simeq \kappa G I_{n} I_{p} / (R^{3} c^{2}) \\ &\times \left(1 - \varepsilon_{nn}^{LT}\right) \left(1 - \varepsilon_{pp}^{LT}\right) \end{split}$$

Carter, Annals of Physics, 1975

PHAROS WG1+WG2 meeting



 $\kappa_{num} \simeq 3.8$



< 🗆)



quasi-periodic giant glitches with a very narrow spread in size

< 🗆)



quasi-periodic giant glitches with a very narrow spread in size

glitches of various sizes at random intervals of time

< 🗆 I



quasi-periodic giant glitches with a very narrow spread in size

glitches of various sizes at random intervals of time

Different models of glitches Haskell & Melatos, IJMPD, 2015

- ► Rearrangement of the moment of inertia --→ crustquakes,
- Angular momentum transfer between two fluids --> superfluidity.