

# Quantum Gravity Simulations with MIXMAX Generator

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Athens, July 4th, 2018

## Introduction

- Discretization

- Numerical setup

- Minimal triangulation

## Measurements

- Observables

- Phase structure

## MIXMAX vs Ran3

## New bifurcation phase

## Topology

## Parallelization

- Parallel rejection

- Parallel tempering

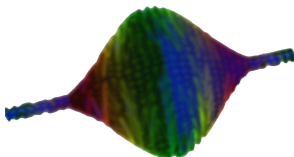
# Introduction to Causal Dynamical Triangulations

## What is Causal Dynamical Triangulations?

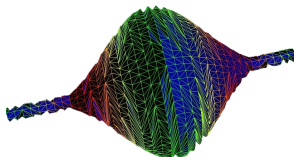
Causal Dynamical Triangulations (CDT) is a background independent approach to quantum gravity. It provides a lattice regularization of the formal gravitational path integral via a sum over causal triangulations.

$$\int \mathcal{D}[g] e^{iS^{EH}[g]} \longrightarrow \sum_{\mathcal{T}} e^{-S^R[\mathcal{T}]}$$

continuous



discrete



## MIXMAX and CDT

For the last three years we have been using the standard version of the MIXMAX pseudorandom number generator with  $N = 256$ ,  $s = -1$ ,  $m = 0$  (and discarding the first component) in our CDT code.

It shows many advantages:

- ▶ Great quality (passes Big Crush from *TestU01*)
- ▶ Very fast (although it's a small part,  $< 0.5\%$  CPU time)
- ▶ Convenient vector size ( $255 = 3 \times 85$ )
- ▶ Convenient output size (61-bits, double)

**It just works!**

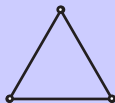
We encountered no issues which could be related to the RNG.

## Regularization via triangulation

- ▶ A *four-dimensional* simplicial manifold is obtained by gluing pairs of four-simplices along their three-faces (tetrahedra).
- ▶ The metric is **flat** inside each 4-simplex.
- ▶ Curvature is localized at triangles.
- ▶ Global proper-time foliation. Spatial states are *three-dimensional* geometries. Discretized states are build from equilateral **tetrahedra**.
- ▶ Length of time links  $a_t$  and space links  $a_s$  is constant.

### Fundamental building blocks

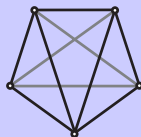
2D



3D



4D



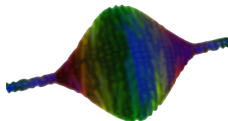
## Regge action

The **Einstein-Hilbert action** has a natural realization on piecewise linear geometries called **Regge action**

$$S^E[g] = -\frac{1}{G} \int dt \int d^D x \sqrt{g} (R - 2\Lambda)$$

The partition function

$$\int D[g] e^{iS^{EH}[g]} \rightarrow \sum_{\mathcal{T}} e^{-S^R[\mathcal{T}]}$$



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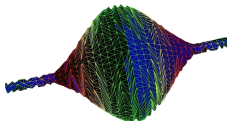
$$S^R[\mathcal{T}] = -K_0 N_0 + K_4 N_4 + \Delta(N_{14} - 6N_0)$$

$N_0$  number of vertices

$N_4$  number of simplices

$N_{14}$  number of simplices of type  $\{1, 4\}$

$K_0$   $K_4$   $\Delta$  bare coupling constants  $(G, \Lambda, a_t/a_s)$



# Causal Dynamical Triangulations

- ▶ The partition function of quantum gravity is defined as a formal integral over all geometries weighted by the Einstein-Hilbert action.

$$Z = \int \mathcal{D}[g] e^{iS^{EH}[g]}$$

- ▶ To make sense of the gravitational path integral one uses the standard method of regularization - discretization.
- ▶ The path integral is written as a nonperturbative sum over all causal triangulations  $\mathcal{T}$ .
- ▶ Wick rotation is well defined due to global proper-time foliation. ( $a_t \rightarrow ia_t$ )
- ▶ Using Monte Carlo techniques we can approximate expectation values of observables.



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# Monte Carlo simulations - initial and minimal configuration

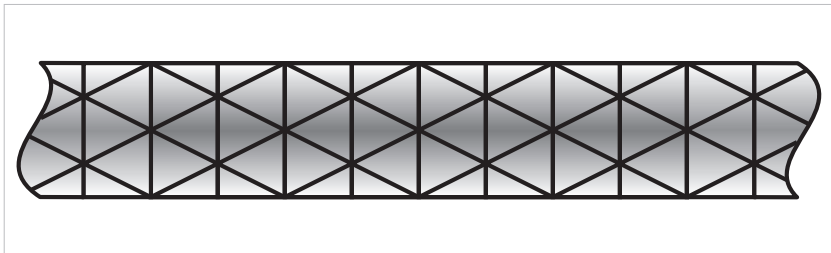
To start the simulations we need to construct an initial triangulation with the desired topology.

**Spherical topology** ( $S^3 \times S^1$ )

- ▶ **Minimal** triangulation: **five** tetrahedra.

**Toroidal topology**  $T^3 \times S^1$

- ▶ Regular **initial** triangulation: **1024** four-simplices per slice
- ▶ **Minimal** triangulation: layered and interlaced structure, 15 vertices (not  $3^3$ ) and **90** tetrahedra.



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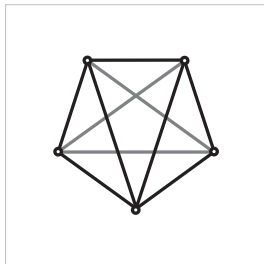
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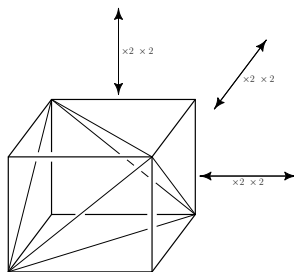
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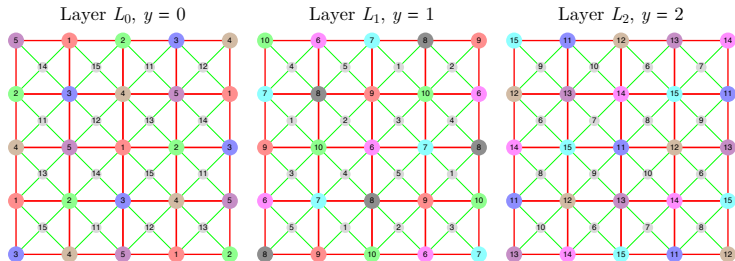
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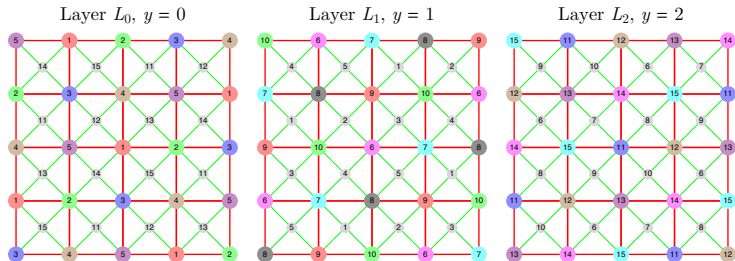
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**Stronger finite size effects!**



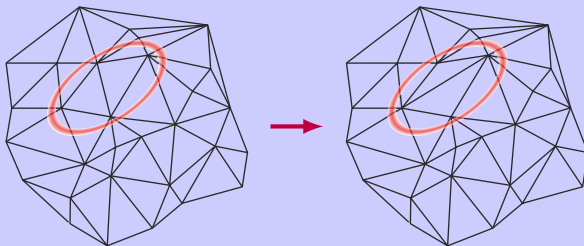


# Monte Carlo simulations - Pachner moves

Random walk over configuration space:

- ▶ **Ergodicity** all possible configurations can be generated by moves
- ▶ **Fixed topology** moves don't change the topology
- ▶ **Causality** moves preserve the foliation
- ▶ **4D CDT** set of 7 moves

## Example of a 2D Monte Carlo move



# Monte Carlo Markov Chain

- ▶ We perform a random walk in the phase-space of configurations (space of piecewise linear geometries).
- ▶ Each step is one of the 4D CDT moves.
- ▶ The weight (acceptance probability)  $W(\mathcal{A} \rightarrow \mathcal{B})$  of a move from configuration  $\mathcal{A}$  to  $\mathcal{B}$  is determined (not uniquely) by the **detailed balance** condition:

$$P(\mathcal{A})W(\mathcal{A} \rightarrow \mathcal{B}) = P(\mathcal{B})W(\mathcal{B} \rightarrow \mathcal{A})$$

- ▶ The Monte Carlo algorithm ensures that we probe the configurations with the probability  $P(\mathcal{A})$ .
- ▶ After sufficiently long time, the configurations are independent.
- ▶ All we need, is the probability functional for configurations  $P(\mathcal{A})$  up to the normalization (Regge action).

# Dynamical lattice

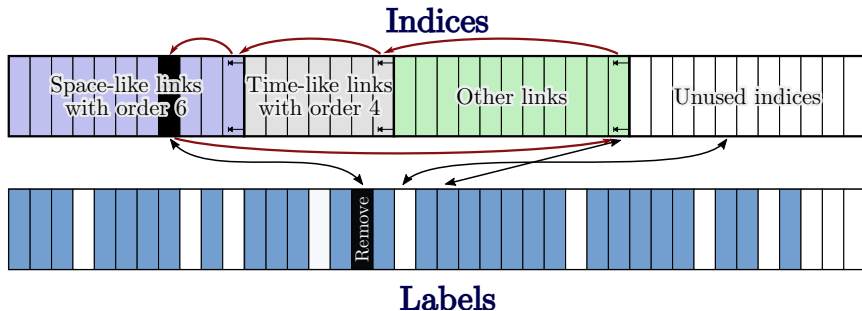
- ▶ The Monte Carlo moves alter the underlying spacetime lattice making it dynamical. The *(sub)-simplices* appear and disappear modifying the connectivity.
- ▶ To effectively deal with such system various techniques are used.

Basic stages of a single move attempt:

- ▶ Choose **which** move type (with adjusted probabilities).
- ▶ Choose **where** to make the move (index).
- ▶ Verify move validity (hash table) and calculate its weight (maximal information).
- ▶ Check **whether** to make the move (detailed balance). Reject the move, or accept the move.
- ▶ Update the triangulation if move was accepted.

## Internals of CDT code: indices and labels

- ▶ Each object (point, link, triangle or simplex) is assigned two integer numbers: a **label** and an **index**.
- ▶ The label is fixed during the object lifetime allowing for its unique identification. Labels are not ordered continuously (removal).
- ▶ Indices are ordered continuously. They are split into few types to quickly find a valid move location. Index of a (sub)-simplex may change for various reasons (hidden randomness).

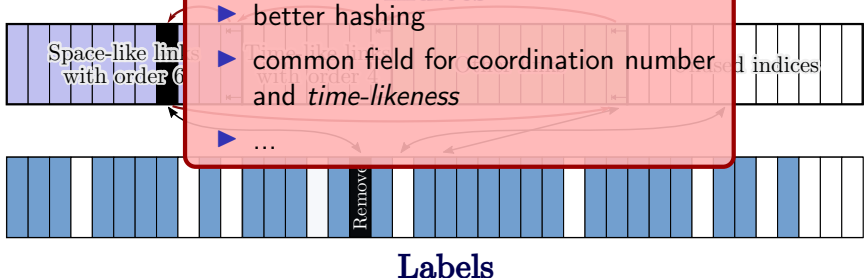


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## New version (> 30% faster)

- ▶ rewritten code
- ▶ simple, separate containers for sub-simplices
- ▶ tabularization
- ▶ avoid  $\text{int} \leftrightarrow \text{f.p.}$  conversions
- ▶ better hashing
- ▶ common field for coordination number and *time-likeness*
- ▶ ...



## Internals of CDT code: data structures

- ▶ Simulations are limited by **CPU time** consumption, while **memory** usage is not a bottle-neck.
- ▶ To enhance the acceptance rate of the moves and gain fast access to necessary data **maximal information philosophy** is adopted.
- ▶ Various information about points, links, triangles and simplices (but not tetrahedra) are stored:

```
struct triangle
{
    int p[3]; /* Vertex labels */
    int n;    /* Coordination number */
    int s;    /* Simplex which owns this triangle */
    int i;    /* Index */
    int h;    /* Hash code of triangle */
    int next; /* Next triangle in hash table list */
}
```

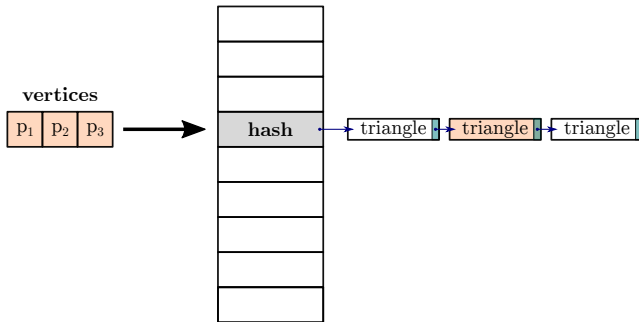
## Internals of CDT code: hash tables

- ▶ To perform a fast check if a *link* or *triangle* with given vertices exists, a **hash table** is used.
- ▶ Verification of tetrahedron existence is more complicated and demands making a loop around a triangle.

Given labels of vertices  $p[0] < p[1] < p[2]$  we calculate the *hash code*,

$$h = (p[0] \ll 8) \text{ xor } (p[1] \ll 4) \text{ xor } p[2]$$

Triangles with the same *hash code* are stored in a singly-linked list.



## Numerical setup

- ▶ **Monte Carlo** algorithm probes the space of configurations with the probability  $P[\mathcal{T}] = \frac{1}{Z} e^{-S[\mathcal{T}]}$ .
- ▶ To calculate the **expectation value of an observable**, the path integral is approximated by a sum over a finite set of Monte Carlo configurations.

$$\begin{aligned}\langle \mathcal{O}[g] \rangle &= \frac{1}{Z} \int \mathcal{D}[g] \mathcal{O}[g] e^{-S[g]} \\ &\downarrow \\ \langle \mathcal{O}[\mathcal{T}] \rangle &= \frac{1}{Z} \sum_{\mathcal{T}} \mathcal{O}[\mathcal{T}] e^{-S[\mathcal{T}]} \\ &\downarrow \\ \langle \mathcal{O}[\mathcal{T}] \rangle &\approx \frac{1}{K} \sum_{i=1}^K \mathcal{O}[\mathcal{T}^{(i)}]\end{aligned}$$

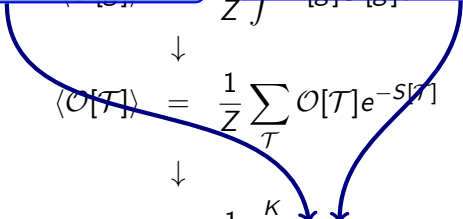


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Example of an observable is  $n_t$ , the number of tetrahedra building slice  $t$ ,  $t = 1, \dots, T$ .

Configurations are generated with proper probability  $P[\mathcal{T}] = \frac{1}{Z} e^{-S[\mathcal{T}]}$ . Normalization  $Z$  is not needed.

$$\begin{aligned} \langle \mathcal{O}[\mathcal{T}] \rangle &= \frac{1}{Z} \int \mathcal{O}[\mathcal{T}] e^{-S[\mathcal{T}]} \mathcal{D}\mathcal{T} \\ &\downarrow \\ \langle \mathcal{O}[\mathcal{T}] \rangle &= \frac{1}{Z} \sum_{\mathcal{T}} \mathcal{O}[\mathcal{T}] e^{-S[\mathcal{T}]} \\ &\downarrow \\ \langle \mathcal{O}[\mathcal{T}] \rangle &\approx \frac{1}{K} \sum_{i=1}^K \mathcal{O}[\mathcal{T}^{(i)}] \end{aligned}$$


# What can we measure?

From the computational point of view, the basic observables are the parameters which appear in the bare action:

$N_0$  number of vertices

$N_{41}$  number of simplices of type  $\{4, 1\}$

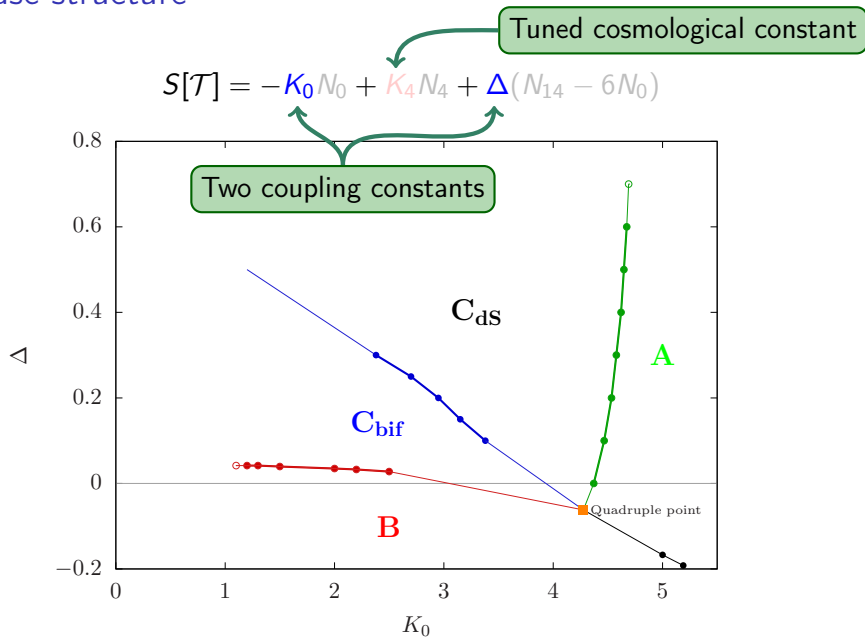
$N_{32}$  number of simplices of type  $\{3, 2\}$

The number of all remaining sub-simplices can be expressed as a linear combination of above parameters.

The simplest observable providing information about spacetime geometry is **spatial volume**  $n_t$  defined as a number of tetrahedra building a three-dimensional slice  $t = 1 \dots T$ .

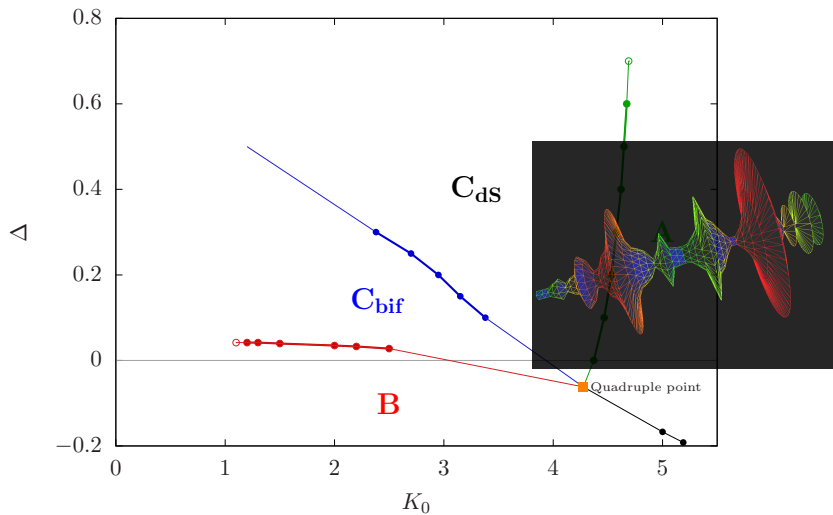
(Proper definition of e.g. curvature is non-trivial.)

# Phase structure



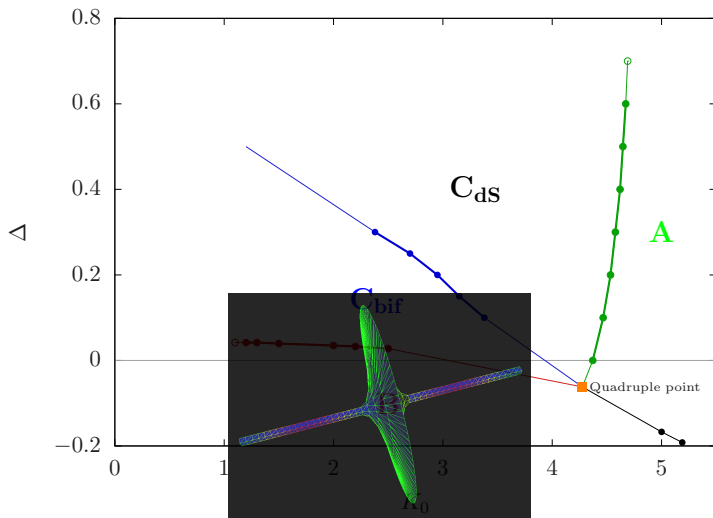
# Phase structure

$$S[\mathcal{T}] = -K_0 N_0 + K_4 N_4 + \Delta(N_{14} - 6N_0)$$



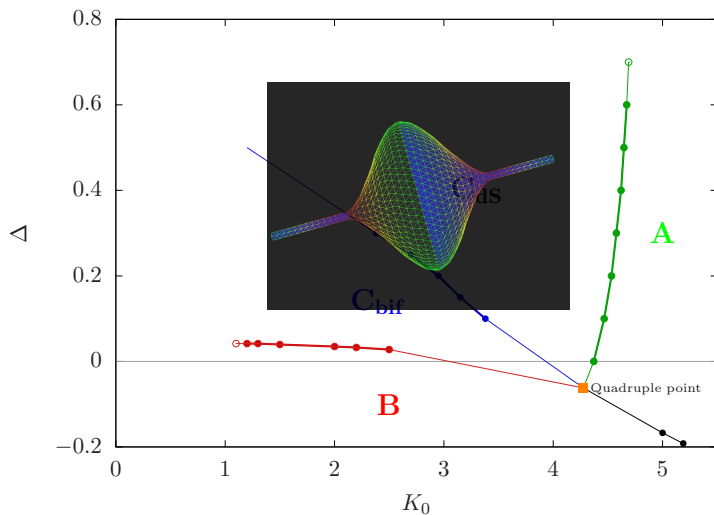
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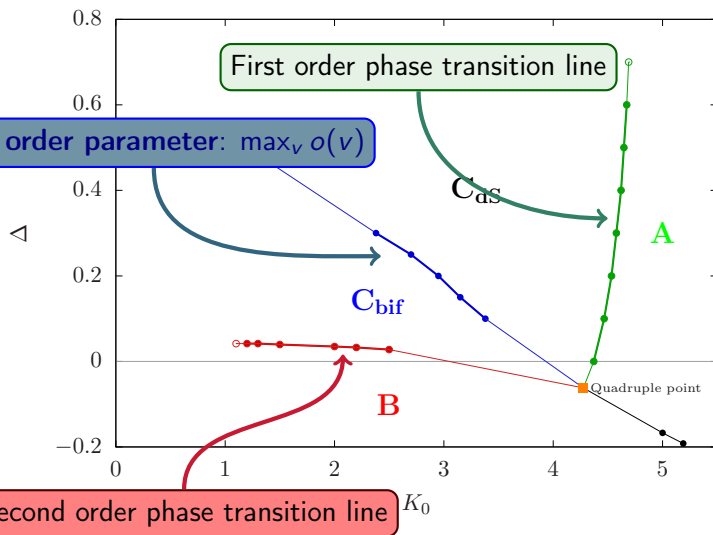
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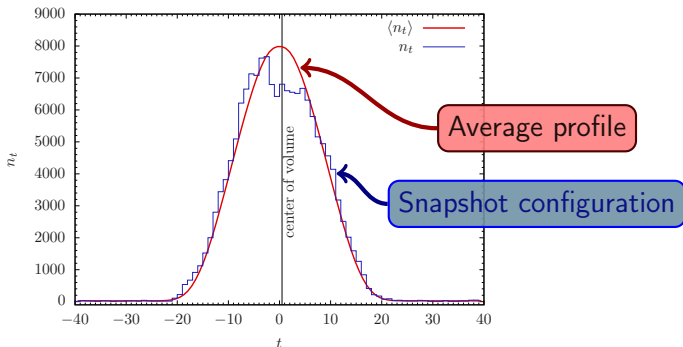


## De Sitter phase - background geometry

- ▶ In phase **C** the time translation symmetry is spontaneously broken and the three-volume profile  $n_t$  is bell-shaped.
- ▶ The average volume  $\langle n_t \rangle$  is with high accuracy given by formula

$$\langle n_t \rangle = H \cos^3 \left( \frac{t}{W} \right)$$

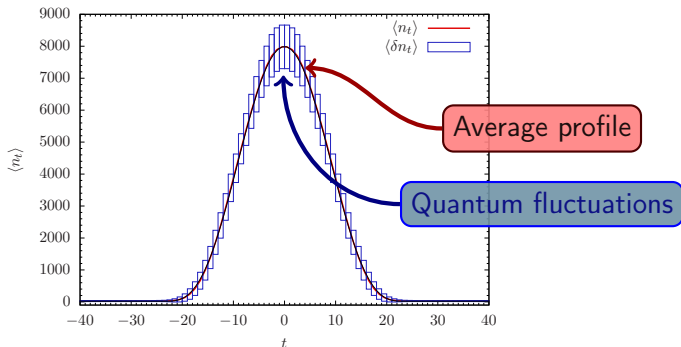
a classical **vacuum** solution.





## De Sitter phase - properties

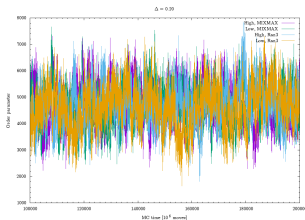
- ▶ Phase **C**, the so called de Sitter phase, is physically most interesting.
- ▶ A **four-dimensional** background geometry emerges dynamically. The background geometry corresponds to Euclidean **de Sitter** space ( $S^4$ ), a classical **vacuum solution**.
- ▶ It is also possible to study **quantum fluctuations** around it.



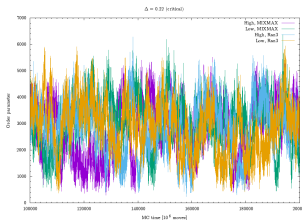
# Autocorrelation: MIXMAX vs Ran3

The MC moves introduce only small local changes and the configurations may be correlated for a long time.

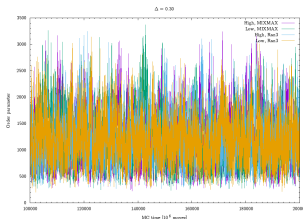
$$\Delta = 0.20$$



$$\Delta = 0.22 \text{ (critical)}$$



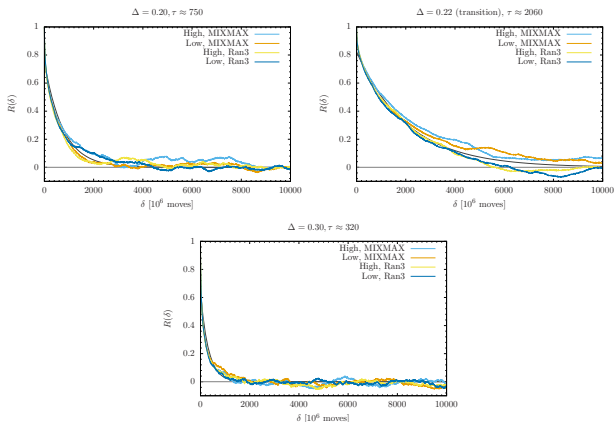
$$\Delta = 0.30$$



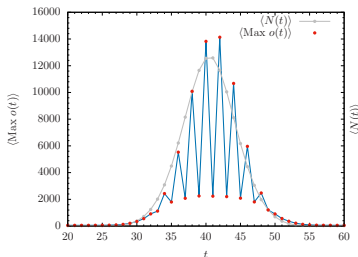
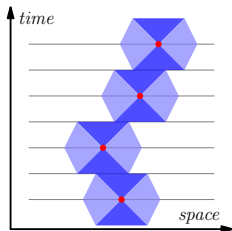
# Autocorrelation time: MIXMAX vs Ran3

Often in the vicinity of phase transition, a phenomenon of critical slowing down is observed.

It takes longer for the system to thermalize, amplitude of fluctuations increases and the autocorrelation time grows.

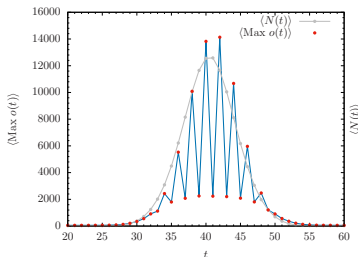
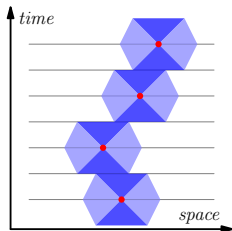


# The new bifurcation phase



- ▶ The spatial volume profile  $\langle n_t \rangle$  is similar as in phase C. But the agreement with  $\cos^3(t)$  is broken.
- ▶ The transfer matrix bifurcates into two branches. At some volume the kinetic term splits into a sum of two shifted Gaussians.
- ▶ Every second slice **singular** vertices of very high order appear.  
New **order parameter**:  $\max_v o(v)$ .
- ▶ Not captured by global properties of the triangulation ( $N_0, N_{32}$ ).

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Difficult to dissolve

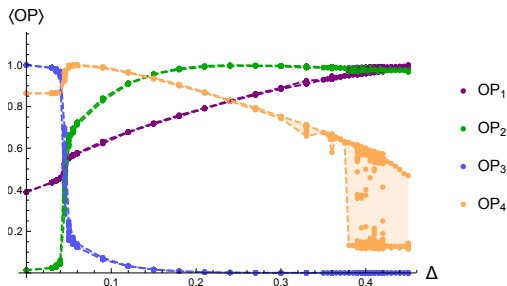


# Toroidal topology - phase transitions

For the toroidal topology, the  $C_{bif}/C_{dS}$  transitions reveals a hysteresis and very long **thermalization time**.

Reason?

- ▶ Strong finite size effects
- ▶ Phase transition order depends on topology?



How to improve the simulations?

# Motivation

- ▶ Limited *single-core* performance (gates, frequency, voltage, power)
- ▶ Cheap access to many cores

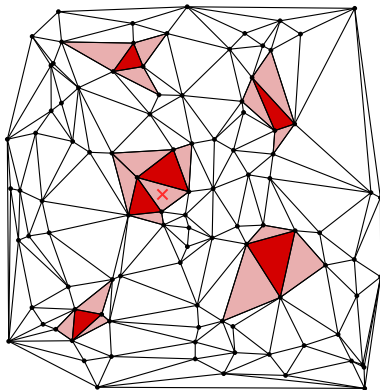
Naive parallelization is used to multiply the statistic, but ...

- ▶ ... a thermalized configuration is needed.
- ▶ Thermalization stage is a bottleneck
- ▶ Critical slowing down near phase transition
- ▶ Need to speed-up a single Monte Carlo Markov chain  $\Rightarrow$  parallelization
- ▶ Large minimal triangulation  $\Rightarrow$  strong finite size effects  $\Rightarrow$  large triangulations
- ▶ Simple parallelization does not work ...

## Simple parallelization

A simple parallel algorithm, where many threads modify the same triangulation, has a very large overhead

- ▶ Detect collisions
- ▶ Thread synchronization: withdraw a move
- ▶ Move weight depends on global parameters - threads are coupled



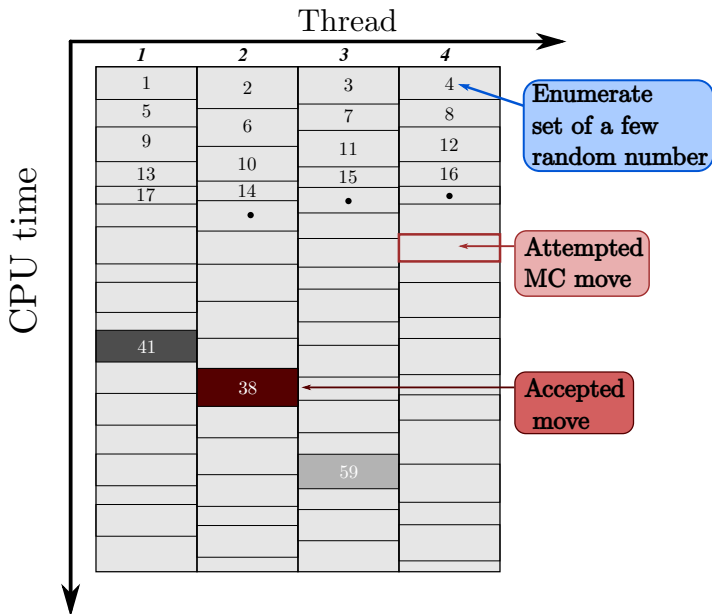


## Parallel rejection

(by Jack Laiho, Phys. Rev. D **96** (2017) 064015)

- ▶ In some regions, the acceptance rate of MC moves is very low (critical slowing down)
- ▶ In such case a **parallel rejection** algorithm can be applied
- ▶ Multiple threads execute a series of **attempted moves**
- ▶ When one of them succeeds, rest of the threads are **stopped** and the triangulation is **updated**
- ▶ No collision detection is necessary
- ▶ To guarantee compatibility with the scalar version, *youngest* move has to be chosen (wait)
- ▶ Each attempted move is identified by three *random* numbers:
  - ▶ **which** move
  - ▶ **where** to make the move
  - ▶ **whether** to make the move (detailed balance)
- ▶ A block of random numbers is precomputed and split between threads. Synchronization with the RNG (separate thread).

## Parallel rejection - diagram

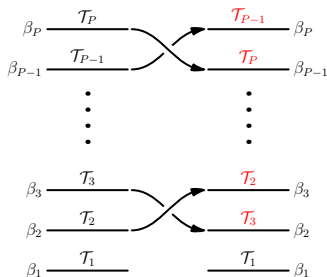


## Parallel rejection - issues

- ▶ For three threads we gained 100% speed up for very small acceptance rate  $\frac{1}{400}$
- ▶ Different move types significantly vary in acceptance rate
- ▶ Fixed number of random numbers (3) consumed per attempted move
- ▶ Replicability, compatibility with scalar version
- ▶ Thread synchronization is expensive
- ▶ Low level libraries, single barrier from pthreads
- ▶ Atomic operations (counter), busy waiting

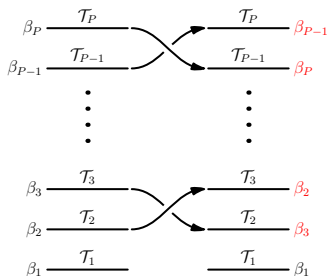
## Replica exchange

- ▶ In this method we run a number of processes (replicas) with slightly different values of coupling constants.
- ▶ Periodically, the configurations are exchanged between processes with a certain probability (detailed balance).
- ▶ A *CDT configuration* is a heavy object (triangulation + additional data). Instead, the sets of a few coupling constants (denoted as  $\beta$ ) are exchanged.



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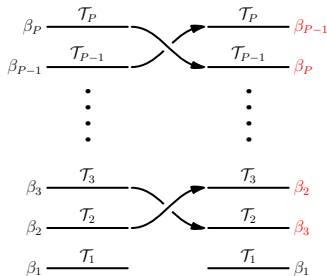


## Replica exchange

- ▶ Exchange probability fulfills the *detailed balance condition*,

$$P(A) = P_1(\mathcal{T}_1)P_2(\mathcal{T}_2), \quad P(B) = P_2(\mathcal{T}_1)P_1(\mathcal{T}_2),$$
$$W(A \rightarrow B) = \min\left\{1, \frac{P_2(\mathcal{T}_1)P_1(\mathcal{T}_2)}{P_1(\mathcal{T}_1)P_2(\mathcal{T}_2)}\right\}$$

- ▶ **Implementation:** Managing process and *Linux message queues* to notify *working* processes when and with whom exchange



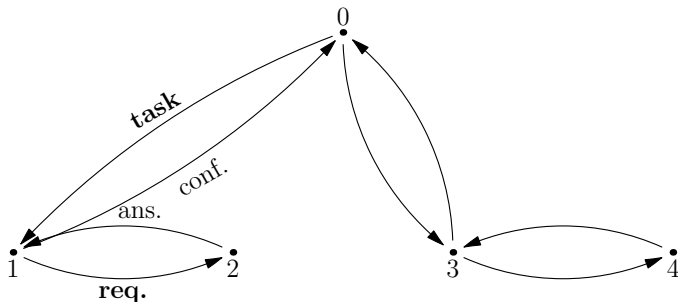
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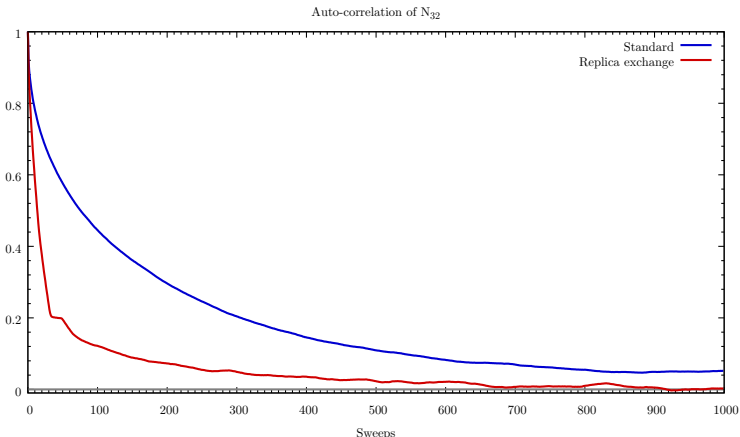
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# Autocorrelation time

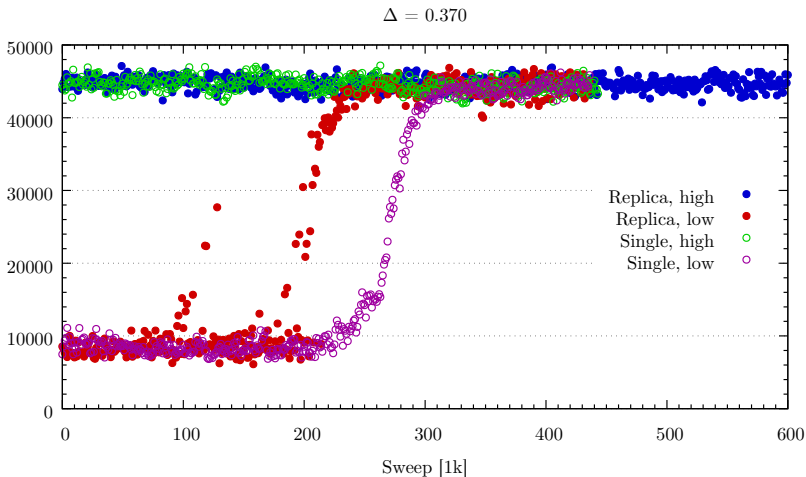
- ▶ History of one configuration (Markov chain) contributes to many simulations and reduces the autocorrelation time.
- ▶ Exchange rate has to be higher than the autocorrelation time
- ▶ For 31 replicas a significant decrease of autocorrelation time is observed. A point near A/C transition (toroidal topology):





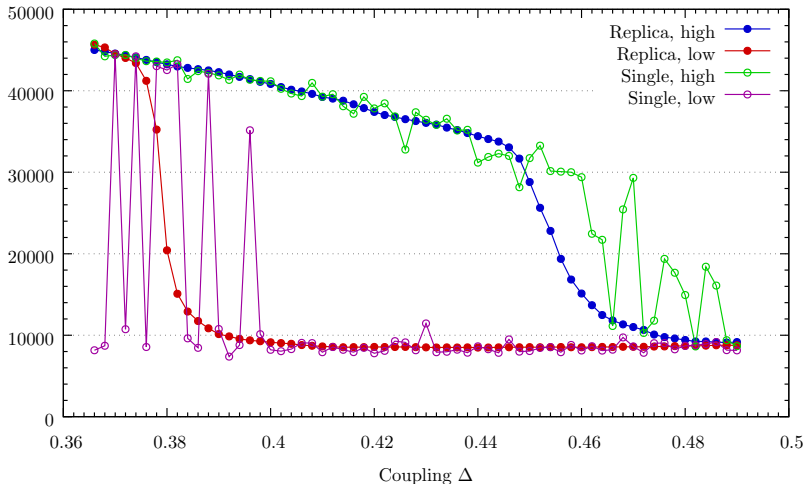
## Replica exchange - hysteresis

Monte Carlo history of the relevant order parameter  $\text{Max } o(p)$  for single value of coupling constants. Visible jump and exchanges.



## Replica exchange - hysteresis

Average value of the order parameter as a function of coupling constant. Comparison: replica exchange vs single threaded.



Thank You!