





**RF Systems**

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### **SUMMARY**

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- Definitions
- RF system anatomy

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- Standing wave resonant cavities: basic theory and merit figures
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### **What are RF Systems for in Particle Accelerators?**

The motion of the charged particles in particle accelerators is governed by the Lorentz force:









### **What are RF Systems for in Particle Accelerators? (cont'd)**

The elementary energy gain of a *charge subject to the Lorentz force is:* 

$$
dW = v dp = \vec{v} \cdot d\vec{p} = \vec{v} \cdot \left[ q \left( \vec{E} + \vec{v} \times \vec{B} \right) \right] dt = q \vec{E} \cdot d\vec{r}
$$

The energy gained by a charged particle with  
motion law 
$$
\vec{r}(t)
$$
 interacting with a variable electric  
field along a portion of its trajectory is given by:  

$$
\Delta W_{21} = q \int_{\vec{r}_1}^{\vec{r}_2} \vec{E}(\vec{r}(t), t) \cdot d\vec{r} = q \int_{z_1}^{z_2} E_z(z(t), t) dz
$$



### **DEFINITION:**

*straight line trajectory*

The **RADIOFREQUENCY (RF) SYSTEMS** are the hardware complexes devoted to the generation of the accelerating E-fields.

They have been mainly developed in the **RADIO WAVE REGION** of the e.m. spectrum, because of both physics (synchronization with the revolution frequencies of synchrotrons and cyclotrons) and technical (availability of power sources) motivations.







### **RF Systems: Basic Definitions and Anatomy**









### **RF Systems: Basic Definitions and Anatomy**

The RF systems in particle accelerators are the hardware complexes dedicated to the generation of the e.m. fields to accelerate charged particle beams.

#### **Accelerating Structures**

- Resonant Cavities
	- Single or multi-cell
	- Room-temperature or Superconducting
- Travelling wave sections
- RF Deflectors (either SW or TW)









### **More on RF Systems**

- Actual RF system frequencies in particle accelerators span from  $\approx$ 10 MHz to 30 GHz and beyond;
- Depending on the characteristics of the beam RF systems can operate either continuously (CW) or in pulsed regime;
- Facility total RF powers up to  $\approx 100$  MW rms and  $\approx 10$  GW pulsed (up to  $\approx 2$  MW rms and  $\approx 100$  MW pulsed per station);
- Lot of science and technology involved (electromagnetism, HV, vacuum, cryogenics and superconductivity, electronics, computing, material and surface physics, cooling, ...);
- Accelerations for energy increase (toward final energy, as in linacs, synchrotrons, cyclotrons, …) or for energy restoring (around nominal energy, as in storage rings …);
- RF accelerating fields also provide particle capture and longitudinal focusing (see Longitudinal Dynamics lectures);
- In some cases, through different mechanisms, accelerating fields also influence the beam transverse equilibrium distributions (adiabatic damping in linacs, radiation damping in lepton synchrotrons and storage rings …).







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### **RF Accelerating structures**

The Wideröe Drift Tube Linac is an historical and didactical example of acceleration based on variable fields. The beam is accelerated while crossing the gap between equipotential drift tubes. The length of the tubes has to match the beam velocity in order to cross each gap in phase with the accelerating field:

$$
\frac{L_n}{v_n} = \frac{T_{RF}}{2} \longrightarrow \begin{cases} L_n = \frac{1}{2} v_n T_{RF} = \frac{1}{2} \beta_n \lambda_{RF} \\ <\Delta U >_{ave} = q V_{kick} / L_n = 2 q V_{kick} / \beta_n \lambda_{RF} \end{cases}
$$



There are two main consequences from the previous conditions:

- 1. The tube equipotentiality requires  $\lambda_{RF} >> L_n \rightarrow \beta_n \ll 1$ , which only applies for non-relativistic beams. To efficiently accelerate relativistic beams distributed fields have to be used.
- 2. Average gradients are inversely proportional to the RF wavelengths. The use of high RF frequencies increases the acceleration efficiency.

**The natural evolution of the drift tubes was represented by high frequency, field distributed structures like resonant RF cavities and disk-loaded waveguides.**









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## **Travelling Wave (TW) RF Accelerating Structures**

**Already in the "Longitudinal Dynamics" lectures by Joel Le Duff**







### **RF Acc. Structures: TW iris-loaded waveguides**

According to Maxwell equations an e.m. wave travelling along a **transverse uniform guide** has always a phase  $v_{ph}$  velocity larger than the light speed *c* and **can not** be synchronous with a particle beam.  $\int$ ω









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### **RF Acc. Structures: TW iris-loaded waveguides**

To "slow-down" the phase velocity of the guided wave periodic structures, also called "iris loaded", are used. According to the Floquet theorem, the field in the structure is that of a special wave travelling within a spatial periodic profile, with the same spatial period D of the structure. The periodic field profile can be Fourier expanded in a series of spatial harmonics with different phase velocity according to:

$$
\begin{array}{c}\n\begin{pmatrix}\n\overrightarrow{2a} & 0 \\
\overrightarrow{2a} & 0 \\
\hline\n0 & 0\n\end{pmatrix}\n\end{array}
$$

$$
\vec{E}(x, y, z, t) = \sum_{i=-\infty}^{+\infty} \vec{E}_{n,i}(x, y) e^{-j\frac{2\pi i}{D}z}
$$
\n
$$
\vec{E}(x, y, z, t) = \sum \vec{E}_{n,i}(x, y) e^{-j\left[\omega t - \left(k_n + \frac{2\pi i}{D}\right)z\right]}
$$

*n i*

,

$$
\vec{E}(x, y, z, t) = \sum_{n} \vec{E}_{n}(x, y, z) e^{j[\omega t - k_{n}(\omega)z]}
$$

$$
\vec{E}_{n}(x, y, z + D) = \vec{E}_{n}(x, y, z)
$$

An iris loaded structure typical dispersion curve is plotted aside. In this case:

- a) The plot is periodic in *k*, with a period of  $2\pi/D$ ;
- b) Every plot period is the dispersion curve of a particular spatial harmonic;
- c) By design, at a *certain excitation frequency ω\** the fundamental spatial harmonic can be made *synchronous with the beam*;
- d) The high order spatial harmonics  $(i=1,2,3,...)$  are not synchronous and do not accelerate the beam over long distances.









### **RF Acc. Structures: TW iris-loaded waveguides**

The most famous TW structure is the iris loaded accelerating waveguide developed at the "Stanford Linear Accelerator Center" (SLAC). It is an S-band structure ( $f = 2856$  MHz) composed by 86 accelerating cells, with input/output couplers, capable of delivering accelerating fields up to 30MV/m.





**Other details in the "Introduction to Linacs" lectures by Maurizio Vretenar!**









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## **Standing Wave (SW) RF Accelerating Structures: Resonant Cavities**

**Already in the "Longitudinal Dynamics" lectures by Joel Le Duff Much more in the "RF cavities" lecture by Erk Jensen!**







### **RF Accelerating structures: Resonant Cavities**

High frequency accelerating fields synchronized with the beam motion are obtained by exciting metallic structures properly designed. In this case the structure physical dimensions are comparable with the e.m. field wavelength, and the exact spatial and temporal field profiles have to be computed (analytically or numerically) by solving the Maxwell equations with the proper boundary conditions.



**Resonant cavities are (almost) closed volumes were the e.m fields can only exists in the form of particular spatial conformations (resonant modes) rigidly oscillating at some characteristics frequencies (Standing Waves).**

*Reentrant or nose-cone cavities*





*Disk-loaded or coaxial cavities*







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### **Modes of a Resonant Cavity: General Problem**

The resonant cavity modes are solutions of the homogeneous Maxwell equations inside closed volumes surrounded by perfectly conducting walls. The mathematical problem has the following formal expression:

*Homogeneous Maxwell Equations + perfect metallic boundaries*

$$
\begin{cases}\n\text{Wave equation} \\
\text{Field solenoidality} \rightarrow \begin{cases}\n\nabla^2 \vec{E}(\vec{r}, t) = \varepsilon \mu \frac{\partial^2}{\partial t^2} \vec{E}(\vec{r}, t) \\
\vec{\nabla} \cdot \vec{E}(\vec{r}, t) = 0\n\end{cases} \longrightarrow \begin{cases}\n\nabla^2 \vec{E}(\vec{r}) = -k^2 \vec{E}(\vec{r}) \\
\vec{\nabla} \cdot \vec{E}(\vec{r}) = 0 \\
\vec{n} \times \vec{E}(\vec{r}, t) = 0\n\end{cases}\n\end{cases}
$$

According to the theory of linear operators, the solution is represented by a discrete set of eigen-functions  $\vec{E}_n(\vec{r})$  $\vec{F}$  (  $\vec{r}$ and their associated eigenvalues  $k_n = \omega_n/c$ . The magnetic field eigenfunctions  $\vec{B}_n(\vec{r})$  can be obtained from the Maxwell 3<sup>rd</sup> equation:  $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial x}$  *i*  $\vec{B}$   $\vec{B}$  *t*  $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \frac{1}{phasors} \rightarrow \vec{\nabla} \times \vec{E}_n(\vec{r}) = -j\omega_n \vec{B}_n(\vec{r})$ ∂  $\vec{\nabla}\times\vec{E}=-\frac{\partial}{\partial\vec{\nabla}}$ The  $\vec{E}_n(\vec{r})$  functions are the cavity modes, each one resonating at a certain specific frequency  $\omega_n$ . The eigenfunctions are also a linear independent base, so that the actual fields  $\vec{E}(\vec{r},t)$ ,  $\vec{B}(\vec{r},t)$  can always be represented as a linear superposition of the cavity modes:  $\vec{E}(\vec{r},t) = \sum_{n} a_n \vec{E}_n(\vec{r}) e^{j\omega_n t}$ ;  $\vec{B}(\vec{r},t) = \sum_{n} a_n \vec{B}_n(\vec{r}) e^{j\omega_n t}$  $\vec{E}(\vec{r},t) = \sum_{n} a_{n} \vec{E}_{n}(\vec{r}) e^{j\omega_{n}t}$ ;  $\vec{B}(\vec{r},t) = \sum_{n} a_{n} \vec{B}_{n}(\vec{r}) e^{j\omega_{n}t}$  $\vec{F}(\vec{r}, t) = \sum_{a} \vec{F}(\vec{r}) e^{j\omega_{n}t} \cdot \vec{B}(\vec{r}, t) = \sum_{a} \vec{B}(\vec{r}, t)$ 







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### **Energy Gain**

Cavities are normally designed to exploit the field of a **particular resonant mode** to accelerate the beam (accelerating mode). The lowest frequency mode (**fundamental mode**) is generally used for this task.



Let's consider a charge *q* travelling at constant speed *v* along a cavity gap on the reference frame *z*-axis. Assume that only the accelerating mode  $\vec{E}_a(r, \varphi, z)$  is excited. The longitudinal E-field on the axis is:

$$
E_z(z,t) = \Re\Bigl[\vec{E}_a(r=0,z)\cdot\hat{z}e^{j\omega_a t}\Bigr] = \Re\Bigl[E_z(z)e^{j\omega_a t}\Bigr]
$$

Being the charge eq. of motion  $z = v(t - t_0)$ , the energy gain for a single gap transit is:

$$
\Delta U = q \int_{-L/2}^{L/2} \Re e \Big[ E_z(z) e^{j \omega_a (z/v-t_0)} \Big] dz = q \Re e \Bigg[ e^{-j \varphi_0} \int_{-L/2}^{L/2} E_z(z) e^{j \omega_a z/v} dz \Bigg] \text{ with } \varphi_0 = \omega_a t_0
$$

The **maximum energy gain**  $\Delta U_{\text{max}}$  is obtained at the **optimal** value of the **injection phase**  $\varphi_0$ :

$$
\Delta U_{\text{max}} = qV_{\text{max}} = q \left| \int_{-L/2}^{L/2} E_z(z) e^{j\omega_a z/v} dz \right| \xrightarrow{E_z(z) = \text{even function}} \sum_{-L/2}^{L/2} E_z(z) \cos(\omega_a z/v) dz
$$







### **Cavity Loss –** *Q* **factor**

Real cavities are *lossy*. *Surface currents dissipate energy*, so that a certain amount of RF power must be provided from the outside to keep the accelerating field at the desired level. If the external excitation is turned off, fields inside the cavity *decay exponentially* with a time constant  $\tau_n$  characteristic of any given mode.

In frequency domain, the dissipation makes the modes resonating *not only at the eigenvalue frequency*  $\omega_n$  but in a *frequency band* of width  $\Delta \omega_n$  around  $\omega_n$ . Both the bandwidth  $\Delta \omega_n$  and the decay time  $\tau_n$  are related to the *quality factor Q* of the mode defined as:

$$
Q = \omega_n \frac{U}{P} \longrightarrow \begin{cases} \tau_n = 2Q/\omega_n \\ \Delta \omega_n \vert_{3dB} = \omega_n/Q \end{cases}
$$

where *U* and *P* are the e.m. energy stored in the mode and the corresponding power dissipation on the walls. General expressions for *U* and *P* are:



$$
U = \iint_{Vol} \left( \frac{1}{4} \varepsilon \left| \vec{E} \right|^2 + \frac{1}{4} \mu \left| \vec{H} \right|^2 \right) d\tau; \quad P = \frac{1}{2} R_s \int_{Surf.} H_{tan}^2 d\Sigma \quad with \quad R_s = \frac{1}{\sigma \delta} = \sqrt{\frac{\omega \mu_0}{2\sigma}}
$$







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### **Cavity Loss – Superconductivity**

Superconductivity is a very wellknown physical phenomenon that is widely used in RF for particle accelerators.

*Surface resistance* is *reduced* by *orders of magnitude* (5 typically) in superconducting (SC) cavities, which are then very suitable when large gradients have to be sustained continuously or in a high duty-cycle regime.

**Surface resistance**

$$
R_{\rm S}=R_{\rm BCS}+R_{\rm res}
$$

$$
R_{\rm BCS} = A \frac{1}{T} \omega^2 \exp \left(-\frac{\Delta(T)}{kT}\right) \qquad T \leqslant \frac{T_{\rm c}}{2}
$$

 $k$  the Boltzmann constant

A is a material parameter,

 $\Delta(T)$  is the energy gap of the superconducting material





**1.3 GHz, 2-cell cavity for Cornell ERL injector.**







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### **Shunt impedance**

One of the most important parameter to characterize the cavity accelerating modes is the shunt impedance  *defined as:* 



The shunt impedance is the parameter that qualifies the efficiency of an accelerating mode. The higher the value, the larger the attainable accelerating voltage for a given power expenditure.

Another very useful parameter is the ratio between shunt impedance and quality factor :

$$
\left(\frac{R}{Q}\right) = \frac{V^2}{2P} \frac{P}{\omega U} = \frac{1}{2\omega} \frac{\left| \int_{\text{trajectory}} E_z(z) e^{j\omega z/v} dz \right|^2}{\int_{\text{Vol.}} \left(\frac{1}{4} \varepsilon |\vec{E}|^2 + \frac{1}{4} \mu |\vec{H}|^2 \right) d\tau}
$$

The *(R/Q)* is a pure geometric qualification factor. In fact, for a given mode it is straightforward that the *(R/Q)* does not depend on the cavity wall conductivity, and its value is preserved if homothetic expansions of a given geometry are considered.

#### **The** *(R/Q)* **is a qualification parameter of the cavity geometrical design.**







### **Merit Figures**









### **Input-Output coupling**

Real cavities are never completely closed volumes. At the least, apertures for beam transit (beam tubes) are required, as well as RF input couplers to feed the cavity, and RF output couplers to probe the field inside. The RF couplers can be of different types:

Magnetic (loop) input coupler

• Electric couplers (Antennas): the inner of a coaxial line connected from the outside couples to the cavity mode E-field;



- Magnetic couplers (Loops): the cavity mode B-field couples to a loop connecting inner and outer conductors of a coaxial line.
- Waveguide couplers: the cavity mode fields are coupled to an external waveguide of proper shape and cut-off through a hole or a slot in the cavity walls



### **Coupling and loading parameters of a cavity**

The coupling strength of a port can be measured as the amount of power  $P_{out}$  extracted form the cavity through the port itself for a given level of the mode fields inside. This leads to the definitions of the *external-Q* ( $Q_{\text{ext}}$ ) (in analogy with the definition of the resonance quality factor  $Q$ ) and coupling coefficient  $\beta$  of a coupler according to :

$$
Q_{ext} = \omega \frac{U}{P_{out}};
$$
  $\beta = \frac{Q_0}{Q_{ext}} = \frac{P_{out}}{P_{walls}}$ 

where  $Q_0$  is the usual quality factor of the resonant mode, related only to the dissipation  $P_{walls}$  on the cavity walls.

The extra-power flow through the cavity couplers, in addition to the power loss in the walls, may significantly change the characteristics of the resonance. This effect is known as "cavity loading". The loaded cavity Q-factor  $Q_L$  is lowered by the power coupled out through the ports and result to be:

$$
Q_L = \omega \frac{U}{P_{Tot}} = \omega \frac{U}{P_{walls} + \sum P_{out_n}} \rightarrow \frac{1}{Q_L} = \frac{P_{walls}}{\omega U} + \sum \frac{P_{out_n}}{\omega U} \rightarrow \begin{cases} \frac{1}{Q_L} = \frac{1}{Q_0} + \sum \frac{1}{Q_{ext_n}} \\ \frac{1}{Q_L} = \frac{1 + \sum \beta_n}{Q_0} \end{cases}
$$









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The cavity resonant frequencies need to be continuously controlled during operation. Actual frequencies are affected by thermal drifts and, in case of superconducting cavities, by pressure variations in the cryogenic bath.

Storage ring cavities have to be largely detuned during beam injection to compensate the beam loading. Synchrotron cavity frequencies have to follow beam velocity increase associated to the energy ramping.

The frequency control is normally obtained through small deformations of the cavity boundaries. The Slater theorem can be used to compute the resonant frequency change, according to:

$$
\frac{\Delta \omega}{\omega_0} = \frac{\int_{\Delta V} (\mu H^2 - \varepsilon E^2) d\tau}{\int_V (\mu H^2 + \varepsilon E^2) d\tau} = \frac{\Delta U_H - \Delta U_E}{U}
$$

Cavity tuning is normally actuated through:

- Cooling fluid temperature control (linac TW or SW sections);
- Structure pushing/stretching by application of axial forces (SC and multi-cell cavities);
- Variable penetration of tuning plungers in the cavities volume (room-temperature, single cell cavities under heavy beamloading).









### **RF Systems**

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## **RF Power Sources**







### **RF Power Sources: Solid State Amplifiers**

Various technologies available:

- Silicon bipolar transistors
- silicon LDMOS
- GaAsFET,
- Static Induction Transistors (SITs)



The power required is obtained by operating numerous transistors in parallel.











### **RF Power Sources: Tetrodes (***Grid Tubes***)**

Tetrodes are long-time, well established grid tubes RF sources.

• Evolution of Triodes;

RF Source

- Widely used in industry, TV and communications;
- Electrons in the tube are produced by thermo-ionic effect at the cathode;
- Intensity of the captured current at the Anode electrode is modulated by the Control grid potential;
- Screen grid increases RF isolati between electrodes.

Frequency /

**few %**

Tetrodes **<sup>50</sup>**<sup>÷</sup> **1000 MHz /**





#### **RF** performance









### **RF Power Sources: Inductive Output Tubes**

Inductive Output Tubes (IOTs) are grid tubes (also known as "klystrodes") commercially available since '80s. They combine some design aspects of tetrodes and klystrons:

- Anode grounded and separated from collector;
- Tube beam current intensity modulated by the RF on the grid. RF input circuit is a resonant line;
- Short accelerating gap to reduce transit-time, beam emerging from a hole in the anode;
- RF output extracted from a tuned cavity between anode and collector decelerating the bunched beam;
- High efficiency, widely used in TV and communications.

**150 kW CW RF Amp for ELETTRA SLS (Trieste) 2**×**80 kW IOTs**

<b>RF</b> Source	Frequency / Bandwidth	Max Power	Class of operation / Efficiency	Features	Drawbacks	$\frac{O}{W}$
Inductive <b>Output Tubes</b> (IOTs)	$100 \div 2000$ MHz / few $%$	500 kW/ tube	B, C $\eta \leq 80\%$	Efficient $\blacksquare$ Reliable $\blacksquare$ Cheap	$\blacksquare$ HV • Power limited $(Q)$ high freq.)	









### **RF Power Sources: Klystrons (***Velocity Modulation Tubes***)**

The klystron has been invented in late '30s by Hansen and Varian Bros.

- Based on the velocity modulation concept;
- After being accelerated to a non-relativistic energy in an electrostatic field, a thermoionic beam is velocity-modulated crossing the gap of an RF cavity (buncher) excited by the RF input signal.
- Velocity modulation turns into density modulation after the beam has travelled a drift space. RF power output is extracted from a tuned output cavity (catcher) excited by the bunched beam.
- Other passive cavities are generally placed between buncher and catcher to enhance the bunching process.
- Beam particle transverse motion is focused all over the fly by solenoidal magnetic fields.
- Operation as oscillator is possible by feeding back an RF signal from catcher to buncher.









### **RF Power Sources: Examples of klystrons**

The klystron is the most widely diffused RF source in particle accelerators. A large variety of tubes exists for different applications, spanning wide ranges of frequency and output power, as well as different duty cycles. Principal tube categories are:

- High power CW tubes (up to 2 MW), for synchrotron, storage rings and CW linacs;
- Very high peak power (up to 100 MW) tubes for low duty-cycle machines (1÷4 μs, 100 Hz rep rate), such as S-band, C-band (and proposed Xband) normal-conducting linacs;
- High peak power (up to 10 MW) tubes for high duty cycle machines (1 ms, 10 Hz rep rate), such as SC linacs for FEL radiation production or for future linear colliders. Multi-beam klystrons have been developed for this task.

**≈1 %**

 $≈2$  MW rms

RF Source Frequency /

Klystrons **0.3**<sup>÷</sup> **30 GHz /**









#### *A.Gallo: RF Systems* **RF Power Sources (***Others***):**

### **Magnetrons and Travelling Wave Tubes (TWTs)**

In a Magnetron the cathode and anode have a coaxial structure, and a longitudinal static magnetic field (perpendicular to the radial DC electric field) is applied . The cylindrical anode structure contains a number of equally spaced cavity resonators and electrons are constrained by the combined effect of a radial electrostatic field and an axial magnetic field. The output power is coupled out from one of the cavities connected to a load through a waveguide.

Magnetrons are oscillators providing output power up to 1 MW.

#### electron-emitting focus RF input RF output electrode cathode helix anode electron beam magnetic field multistage depressed heater electron gun collector

#### microwave radiation path of an cathode electron magne anode output antenna cavities cooling fins **RF** fields © 2004 Encyclopædia Britannica, Inc.

#### **Magnetron Sketch**

Helix Travelling Wave Tubes are widely used μ-wave amplifiers.

Amplification is due to a continuous bunching of a thermo-ionic electron beam interacting with an RF filed travelling along an helix line which allows the energy transfer from the beam to the line. Typical gains are 40 to 60 dB while DCto-RF conversion efficiency up to  $\approx$  75 %.

#### **Helix Travelling Wave Tube Sketch**









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## **RF Power Distribution**



### **Transmission Lines and Waveguides**

In most cases RF Power is transferred from sources to the accelerating structure through a network of **coaxial transmission lines** or **rigid rectangular waveguides**.



- No cut-off (usable from dc)
- No dispersion
- $E_r(r) \div H_{\phi}(r) \div 1/r$
- $Z_0 = V/I = 1/(2\pi) \cdot (\mu/\epsilon)^{1/2} \cdot ln(b/a)$
- Large attenuation
- Difficult to cool



- Only  $\lambda < \lambda_c$ ,  $\lambda_c = 2x$  (cut-off wavelength)
- Low attenuation
- Easy to cool
- Suitable at high frequency, high power







### **Special Components in the WG Networks**

**Circulators** are **non-reciprocal 3-ports** (typically) devices based on the peculiar properties of the ferrite materials. They are interposed between the RF power sources and the cavities to convey the reflected power on dummy loads.



#### **CIRCULATORS HYBRID JUNCTIONS / POWER SPILTTERS**



#### **DIRECTIONAL COUPLERS**

Directional Couplers are quadrature hybrids with unequal coupling coefficients. They are mainly used to sample the fields in the waveguides for control and diagnostic purposes.



used to feed various accelerating structures from a single RF power source. Phase relation among ports depends upon the chosen splitting technique.









CIRCULATOR Υ

Z٥





### **RF Power Sources: Pulse Compression (SLED)**

The Stanford Linac Energy Doubling (SLED) is a system developed to compress RF pulses in order to increase the peak power (and the available accelerating gradients) for a given total pulse energy. This is obtained by capturing the pulsed power reflected by a high-Q cavity properly excited by the RF generator (typically a klystron). In fact the wave reflected by an overcoupled cavity ( $β ≈ 5$ ) peaks at the end of the RF pulse to about twice the incident wave level (with opposite polarity).<br>By playing with this, and properly tailoring the incident

wave, accelerating gradients integrated over a small portion of the original pulse duration are almost doubled.













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# **Beam Loading and Low Level RF (LLRF)**







### **THE CAVITY RLC MODEL**

The beam-cavity interaction can be conveniently described by introducing the resonator RLC model. According to this model, the cavity fundamental mode interacts with the beam current just like a parallel RLC lumped resonator. The relations between the RLC model parameters and the mode field integrals  $\omega_{cav}$  (mode angular resonant frequency),  $V_c$  (maximum voltage gain for a particle travelling along the cavity gap for a given field level),  $U$  (energy stored in the mode),  $P_d$ (average power dissipated on the cavity walls) and *Q* (mode quality factor), are given by:









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### **Generator - Cavity -Beam model: Beam loading**

The cumulative contribution of many bunch passages depends essentially on the RF harmonic of the beam spectrum. The static beam loading problem consists in computing:

- the overall **contribution** of the **beam** to the **accelerating voltage**;
- the **RF generator power** needed to refurnish both cavity and beam;
- the **optimal values** of **cavity detuning** and **cavity-to-generator coupling** to minimize the power request to the generator.











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### **Generator - Cavity -Beam model: Beam loading**

The reflection coefficient *ρ* on the RF power transmission line according to the system model is given by:

Being the detuning parameter  $\delta$  defined as:  $\delta = \frac{\omega_{RF}}{\omega_{cav}} - \frac{\omega_{cav}}{\omega_{RF - cav}} \approx 2 \frac{\Delta \omega_{RF - cav}}{\omega_{RF - cav}}$ 

minimizing the power reflection requires an optimal cavity detuning given by:

 $\omega_{\scriptscriptstyle cav}$   $\omega_{\scriptscriptstyle{RF}}$ 

$$
\delta = -\frac{I_b R/Q}{V_c} \sin(\phi_s) \implies \Delta \omega_{RF-cav} = -\omega_{RF} \frac{I_b R/Q}{2V_c} \sin(\phi_s)
$$

*RF*

ω



acceleration offcrest of a large beam current may require large cavity detuning !



Zero for optimal coupling factor

Zero for optimal cavity detuning

Complete minimization of the power reflection requires also an optimal value of the input coupling coefficient  $\beta$ :

$$
\beta_{opt} = 1 + \frac{I_b R_s}{V_c} \cos(\phi_s) = 1 + \frac{P_{beam}}{P_{cav}}
$$

$$
P_{FWD} = \frac{1}{2} \frac{V_c^2}{R_s} + \frac{1}{2} I_b V_c \cos(\phi_s) = P_{cav} + P_{beam}
$$







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### **Low-level RF Control (LLRF)**

The Low-level RF is the hardware section pre-forming the RF signal before being amplified to fed the accelerating structures.

The LLRF system consists in a number of integrated controllers of various topologies (servo loops, beam feedback loops, feed-forward schemes) that accomplish several tasks such as:

- automatic cavity tuning, compensating thermal drifts and beam loading variations;
- automatic RF level control, to follow beam loading variation in Storage Rings (SRs) or to stabilize the beam energy in linacs;
- automatic RF phase control, to stabilize the bunch timing (SRs, linacs) and energy (linacs);
- suppression of beam instabilities arising from the interaction with the cavity accelerating mode in SRs, obtained through a combination of feedback loops (beam phase loop, direct RF feedback loop, comb loop, …) and/or beam feed-forward compensations;





*Automatic tuning loop*

• …

*Automatic RF level control*



- Revolution frequency tracking, RF phase jump and all related controls during transition energy crossing in synchrotrons (RF gymnastics);
- adaptive feedback and/or feed-forward systems to compensate transient effects in pulsed regime or due to beam gaps;







### **An example: PEP-II (SLAC B-factory) LLRF**

Tuner loops - standard tuning for minimum reflected power

#### Klystron operating point support

- Ripple loop adjusts a complex modulator to maintain constant gain and phase shift through the klystron/modulator system.
- Klystron saturation loops maintain constant saturation headroom

#### Direct feedback loop (analog)

- Causes the station to follow the RF reference adding regulation of the cavity voltage
- Extends the beam-loading Robinson stability limit
- Lowers the effective fundamental impedance seen by the beam

#### Comb filter (digital)

• Adds narrow gain peaks at synchrotron sidebands to further reduce the residual impedance

#### Gap feedback loop (digital)

• Removes revolution harmonics from the feedback error signal to avoid saturating the klystron on gap synchronous phase transients

Longitudinal feedback uses RF as low-frequency "woofer" kicker











### **An example: PEP-II (SLAC B-factory) LLRF**

Tuner loops - standard tuning for minimum reflected power

Klystron operating point support



- In the last decades the LLRF controls have progressively evolved from fully analog electronics systems (as they were in CERN PS pioneeristic age) to more and more digital electronics based systems, exploiting the great potentiality of DSP (first) and FPGA (now) controllers.
	- Extends the beam-loading Robinson stability limit
	- Lowers the effective fundamental impedance seen by the beam.

Loop technology legend Magenta - EPICS loop

- In modern machines LLRF is becoming more and more complex task (a science in itself!) requiring a combination of different expertise such as RF, electronics and computational engineering.
	- Removes revolution harmonics from the feedback error signal to avoid saturating the klystron on gap synchronous phase transients

Longitudinal feedback uses RF as low-frequency "woofer" kicker