



Latest FONT Resolution and IP Feedback Results

D. Bett, T. Bromwich, P. Burrows, C. Perry, R. Ramjiawan
FONT, John Adams Institute, University of Oxford

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Outline

Background

- Introduction to ATF2
- FONT system and cavity BPM signal processing.
- Recent modifications to the FONT system.

Results of resolution studies

- Best BPM resolution results (April 2018).
- Work towards achieving consistent resolution results (April 2018).

Results of feedback studies

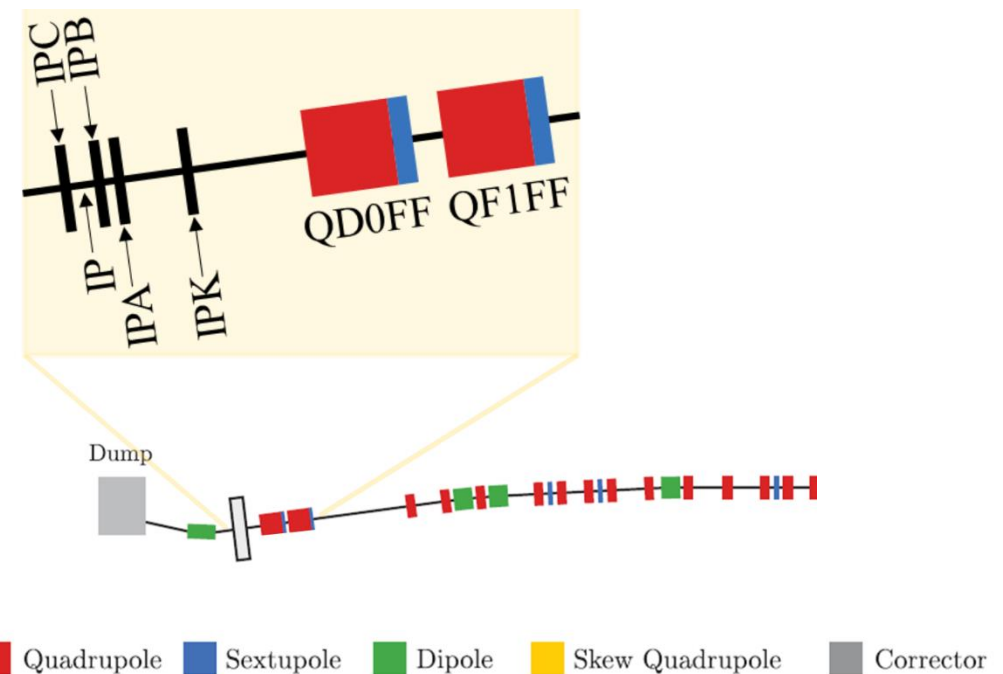
- Beam stabilisation results: (December 2017)
 - 1-BPM feedback,
 - 2-BPM feedback.

Plans for future work

FONT IP Feedback System

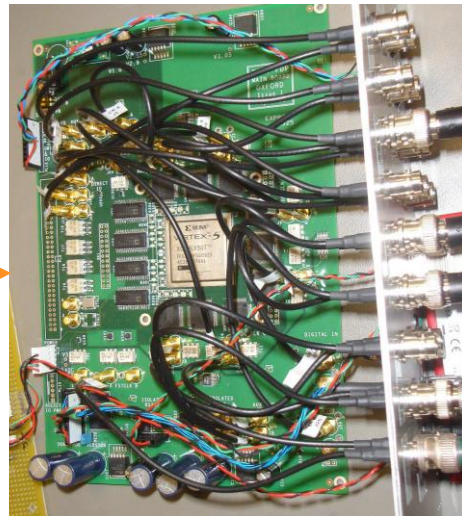
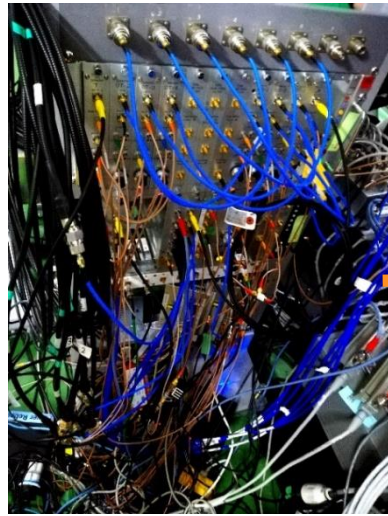
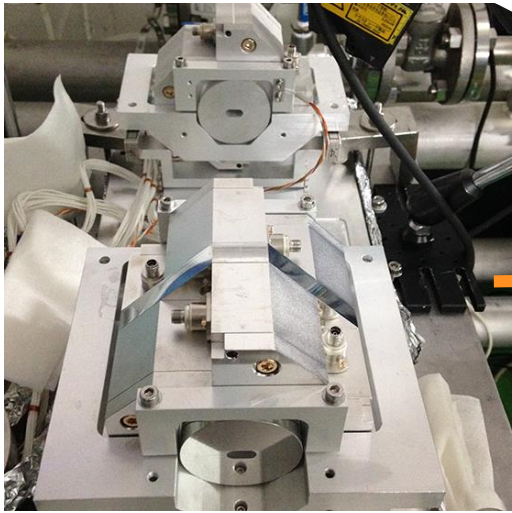
FONT IP Feedback Region of ATF2

- The FONT (Feedback On Nanosecond Timescales) IP feedback system contains:
 - C-band cavity beam position monitors (BPMs), IPA, IPB and IPC to measure the beam orbit,
 - a digital board (FONT 5A) to compute the feedback correction,
 - a stripline kicker, IPK, to implement the correction.
- The system acts on a two-bunch train with 280 ns bunch separation, stabilising bunch-2 based on position measurements of bunch-1, requiring a high bunch-to-bunch correlation.
- The latency of the system must be less than the bunch separation, requiring fast signal processing; for the system described here, a latency of 232.4 ns has been demonstrated.



FONT IP feedback system with kicker IPK, cavity BPMs: IPA, IPB and IPC, and final focus quadrupoles QD0FF and QF1FF.

FONT IP Feedback System



- C-band cavity Beam Position Monitors - IPA, IPB and IPC.
- All with decay times between 20 and 25 ns.
- Mounted on piezo-mover systems to allow for alignment of BPMs with beam in x , y and also to adjust the pitch.

- Two-stage processing electronics: down-mix and process cavity signals.
- Produces two signals at baseband: I and Q which contain beam position and angle information.

- FONT 5A digital board with Virtex-5 Field Programmable Gate Array (FPGA).
- ADCs to digitise I and Q waveforms at 357 MHz.
- DACs to provide analogue output to drive kicker.

- Stripline kicker and specialised amplifier (provided by TMD Technologies) used to provide feedback correction.
- Amplifier provides ± 30 A of current to drive the kicker, with a fast rise time of 35 ns to reach 90% of peak output.

Digitisation of the BPM Waveform

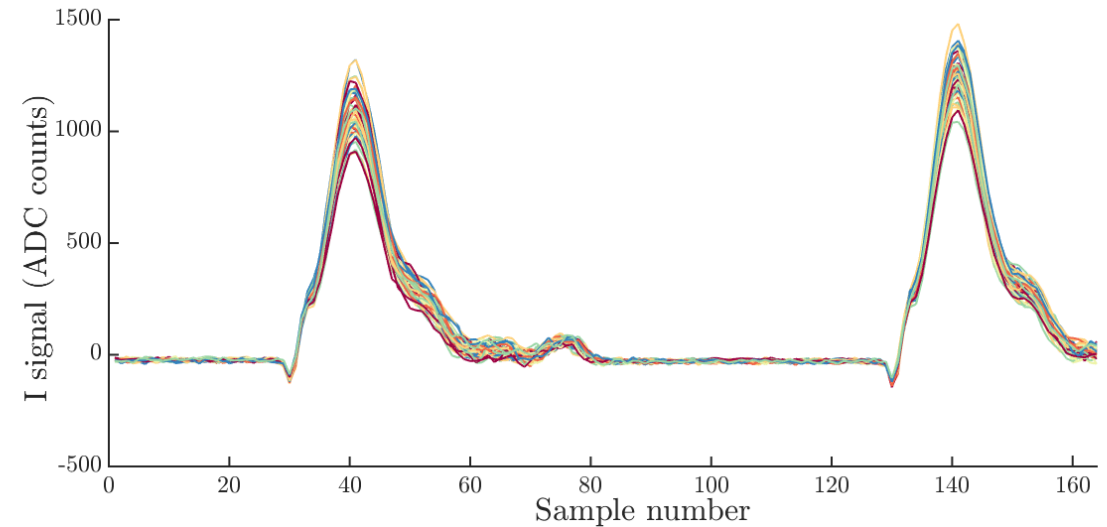
- The waveforms I and Q are digitised at 357 MHz by ADCs on the FONT 5A board; these digitised samples are used to compute a bunch position:

$$y = \frac{1}{k} \left(\frac{I}{q} \cos \theta_{IQ} + \frac{Q}{q} \sin \theta_{IQ} \right),$$

where k and θ_{IQ} are determined through position calibration.

Single sample vs. integrated sample

- Single sample:** only a single sample of each of the I and Q waveforms are used, resolution in this mode typically ~ 50 nm.
- Integrated sample:** integration over a multi-sample window is used (up to 15 samples), this can improve the signal-to-noise ratio of the position measurement and consequently, the resolution. Resolution achieved in this mode of 20 nm.
- Improvements to the FONT system allow for feedback using multiple samples of the BPM waveforms.



Example I signal waveform, in two bunch operation with 280 ns bunch spacing. Consecutive samples are separated by 2.8 ns.

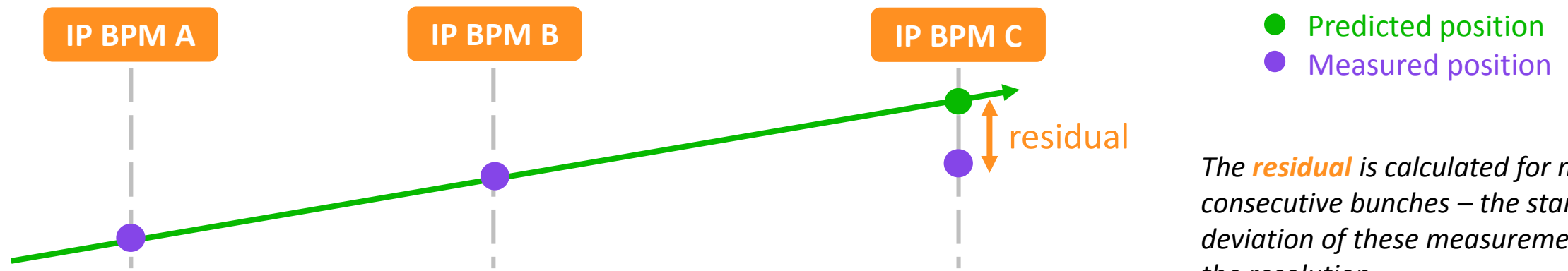
Resolution Studies

April 2018

Calculating the Resolution

- Only two BPMs are required to characterise the straight-line bunch trajectory, so we are able to use the third BPM to estimate the resolution of the measurement.
- The resolution which is relevant for feedback is the **geometric resolution** – determined using the longitudinal separation of the BPMs. We can achieve better resolution measurements in off-line analysis by using **least squares fitting** for the bunch position but this is not possible within the latency required for feedback

$$\text{residual} = y_{\text{pred}} - y_{\text{meas}}$$
$$\text{resolution} = \text{std}(\text{residuals})$$



The *residual* is calculated for many consecutive bunches – the standard deviation of these measurements is the resolution.

Resolution Results

- Resolution results from April 2018: we were able to achieve resolution of ~ 20 nm, and we were able to reproduce this performance consistently across ten repeat data sets, with all ten data sets having sub-25 nm resolution.
- There is very little improvement to the resolution from using fitting to position or charge, suggesting the calibration and charge normalisation were performed successfully.
- These data were analysed using an integration window of 15 samples. Single sample resolutions were measured between 40-45 nm.

Resolution results from a data set collected 19th April 2018 as part of 10 repeat resolution measurements.

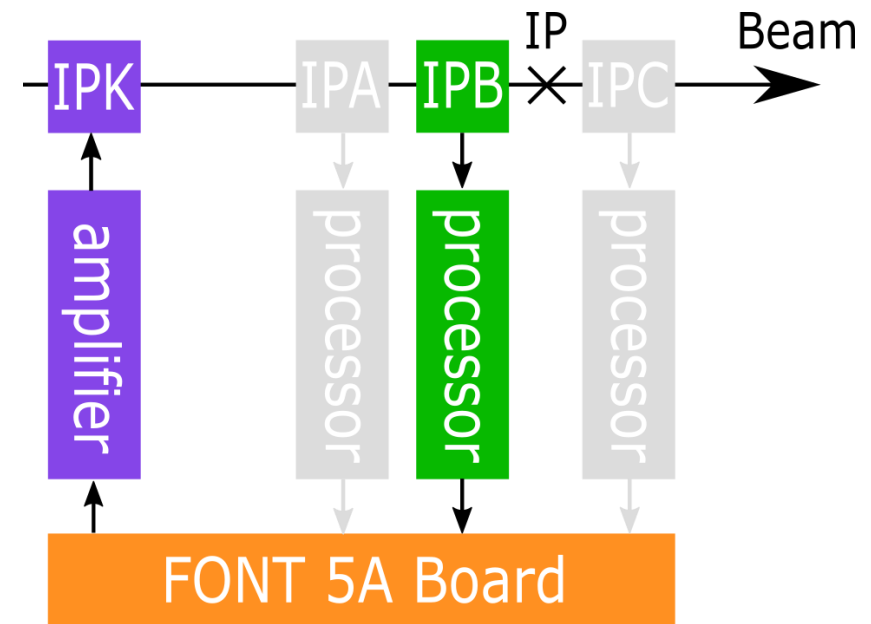
| Resolution | IPA (nm) | IPB (nm) | IPC (nm) | Comments |
|-----------------------------|----------------|----------------|----------------|---|
| Geometric | 20.6 ± 1.0 | 20.6 ± 1.0 | 20.6 ± 1.0 | Resolution achievable for feedback |
| Fitting position | 20.4 ± 1.0 | 20.5 ± 0.8 | 20.3 ± 0.8 | Fit out inaccuracies in calibration |
| Fitting position and charge | 19.9 ± 0.9 | 19.9 ± 0.8 | 19.7 ± 0.9 | Fit out inaccuracies in calibration and position-charge correlation (from imperfect charge normalisation) |

1-BPM Feedback Results

Dec 2017

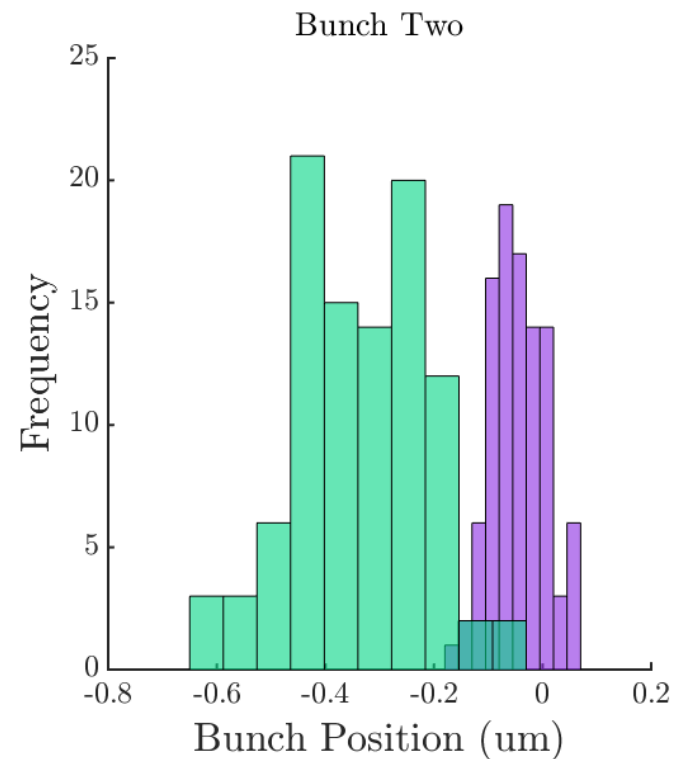
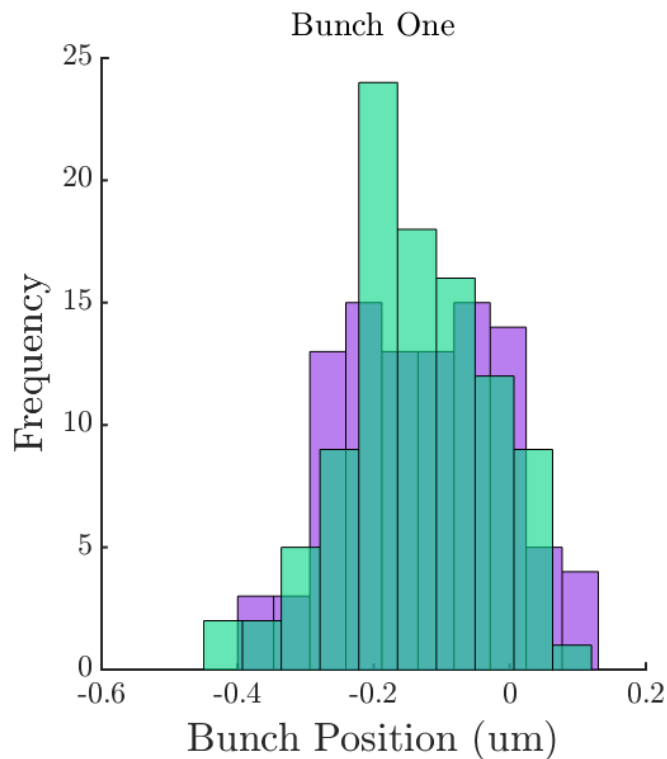
IP Feedback Results – 1-BPM Mode

- In 1-BPM feedback mode, position measurements at one BPM are used to stabilise the beam locally.
- Limit to 1-BPM feedback performance = $\sqrt{2} \times \sigma_{res}$, so it is clearly important to improve the resolution accessible in real-time during feedback.
- Previous best stabilisation performance in single-sample 1-BPM mode = 74 nm. This is consistent with a single sample resolution of approximately 50 nm.



1-BPM Feedback Results – With Integration

Best results demonstrated for 1-BPM feedback mode with stabilisation at IPC.



| Position jitter (nm) | | |
|----------------------|--------------|-------------|
| Bunch | Feedback off | Feedback on |
| 1 | 109 ± 11 | 118 ± 8 |
| 2 | 119 ± 12 | 50 ± 4 |

Feedback **off** correlation: **84%**

Feedback **on** correlation: **-26%**

- 10 samples integrated for feedback - optimised empirically.
- Feedback gain: $G = 0.95$.
- Predicted stabilisation: 65 nm, suggests the measured correlation was lower than the true correlation – typically due to the resolution introducing a random component to the position measurement.
- Stabilisation below 55 nm was reproducible.

2-BPM Feedback Results

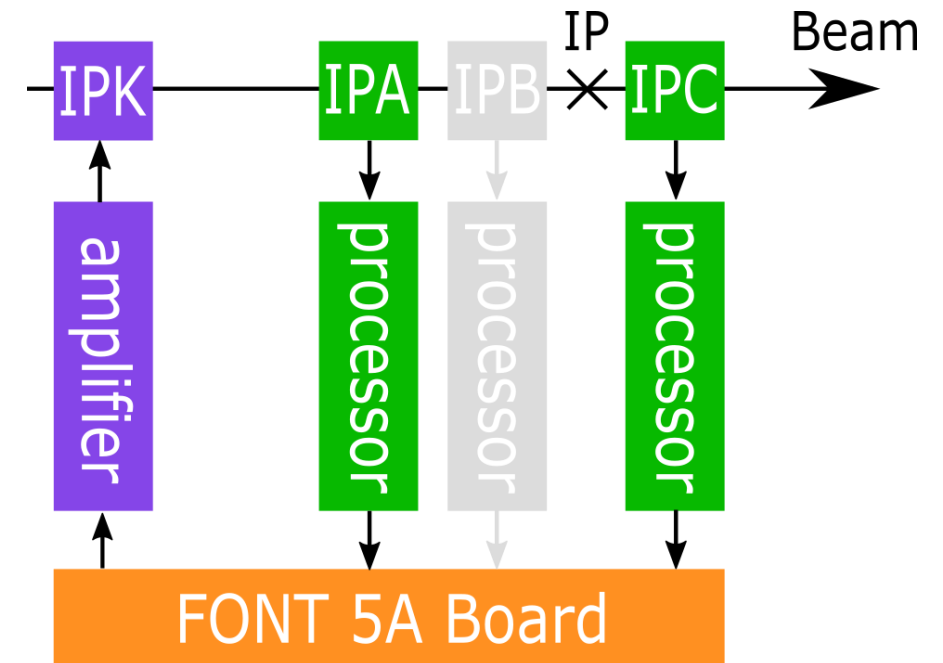
Dec 2017

IP Feedback Results – 2-BPM Mode

- Beam position measurements at IPA and IPC are interpolated and used to stabilise the beam at an intermediate location, for this study, at IPB.
- For stabilisation at IPB, the feedback BPMs IPA and IPC contribute in a ratio 32:68, so that the interpolated resolution is:

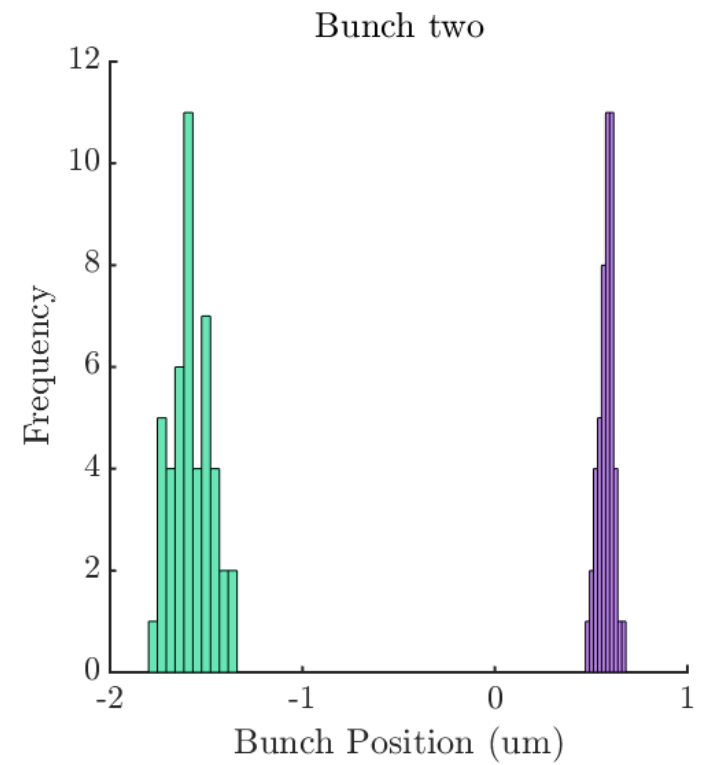
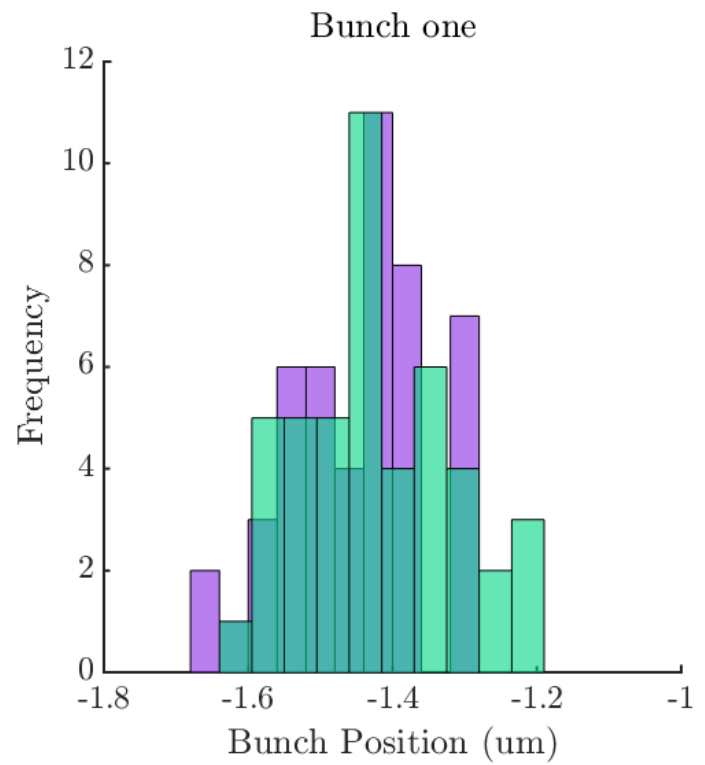
$$\begin{aligned}\sigma_{\text{interp}} &= \sqrt{0.32^2 \sigma_{\text{BPM}}^2 + 0.68^2 \sigma_{\text{BPM}}^2} \\ &= 0.75 \sigma_{\text{BPM}}\end{aligned}$$

- Previous best 2-BPM single-sample feedback performance = 68 nm (consistent with a resolution of < 55 nm).
- Limit to feedback performance in 2-BPM mode = $1.25 \times \sigma_{\text{res}}$, so it is important to improve the resolution by using integration.



2-BPM Feedback Results

Best results demonstrated for 2-BPM feedback mode, with stabilisation at IPB.



| Position jitter (nm) | | |
|----------------------|--------------|-------------|
| Bunch | Feedback off | Feedback on |
| 1 | 106 ± 16 | 106 ± 16 |
| 2 | 96 ± 10 | 41 ± 4 |

- Five-sample integration window, empirically optimised to improve both the measured correlation and resolution.
- Feedback stabilising to: **41 ± 4 nm**, shows excellent agreement with predicted stabilisation of 40 nm.
- Feedback gain: G= 0.8.

Feedback **off** correlation: **92%**
 Feedback **on** correlation: **41%**

The correlation is not fully removed, suggesting feedback gains were set too low; higher gains may offer better performance.

Summary

- While performing resolution studies in April 2018, we were able to reproducibly achieve resolution better than 25 nm; with best results of 20 nm resolution.
- Improvements to the feedback firmware allow for the use of an integrated period of the BPM waveform. Integration is shown to improve the useable BPM resolution and consequently feedback performance.
- This was tested with two different feedback modes in December 2017:
 - 1-BPM feedback showed stabilisation to **50 ± 4 nm**.
 - 2-BPM feedback showed stabilisation to **41 ± 4 nm**.

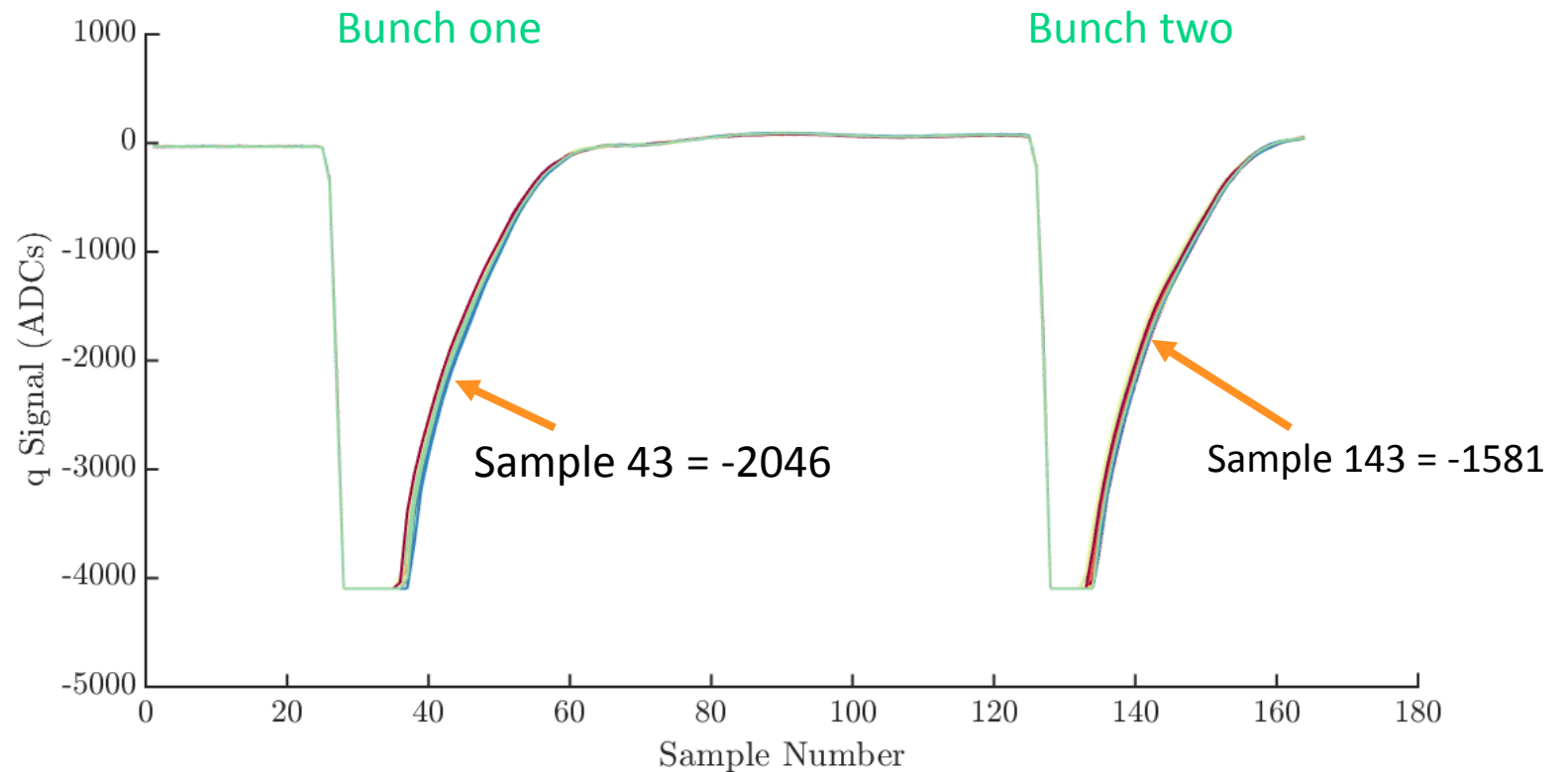
Both of these results show a significant improvement over the best feedback performance in single sample mode.

Thank you for listening

Extra slides

BPM Resolution (Bunch 1 & 2)

- Bunch charge at reference samples used for feedback (43 and 143):
 - Bunch-1: -2046 ADCs
 - Bunch-2: -1581 ADCs
- Resolution scales **inversely with charge**: bunch-2 with a lower bunch charge has a correspondingly poorer resolution.
- Geometric resolution:
 - Bunch-1: 31 nm
 - Bunch-2: **39 nm**
- Potential limitations when measuring feedback performance as the resolution of bunch-2 is similar to the expected level of stabilisation.



Charge signal, with samples used for charge normalisation during feedback highlighted.

Expected Stabilisation

- The position of the corrected bunch, Y_2 , in terms of the uncorrected bunch-1 and bunch-2 positions, y_1 and y_2 is:

$$Y_2 = y_2 - y_1 + c$$

where c is a constant offset which may be applied in order to shift arbitrarily the mean position of the stabilised bunches.

- Taking the variance of this equation gives the predicted level of beam stabilisation:

$$\sigma_{Y_2}^2 = \sigma_{y_1}^2 + \sigma_{y_2}^2 - 2\sigma_{y_1}\sigma_{y_2}\rho_{12}$$

- σ_{Y_2} = jitter of corrected bunches
- $\sigma_{y_{1,2}}$ = uncorrected jitter of bunch-1,2
- ρ_{12} = bunch-to-bunch correlation
- The best performance is achieved for $\rho_{12} = 1$ and $\sigma_{y_1} = \sigma_{y_2}$, in this situation the level of stabilisation then just depends on the resolution of the position measurement (for 2-BPM feedback this is $1.25 \times \sigma_{res.}$).

Expected Feedback Performance

- It is useful to compare the beam stabilisation achieved with that expected, taking into account the imperfect correlation and the differences in bunch-1 and bunch-2 jitters.
- Integration significantly improves the predicted performance. This is an effect of the better resolution improving the jitter measurement and the estimation of the bunch-to-bunch correlation.

| Window width | Res. (nm) | Pred. performance (nm) | Sample window |
|--------------|----------------|------------------------|---------------|
| 1 | 40.8 ± 2.9 | 62.4 ± 5.2 | 38 |
| 2 | 37.9 ± 2.7 | 58.0 ± 5.4 | 38 to 39 |
| 3 | 33.1 ± 2.3 | 48.2 ± 5.2 | 37 to 39 |
| 4 | 31.9 ± 2.3 | 40.4 ± 5.3 | 36 to 39 |
| 5 | 31.2 ± 2.2 | 40.1 ± 5.5 | 36 to 40 |
| 6 | 31.2 ± 2.2 | 40.4 ± 5.2 | 35 to 40 |
| 7 | 32.3 ± 2.3 | 42.4 ± 5.3 | 35 to 41 |
| 8 | 36.2 ± 2.6 | 53.4 ± 5.1 | 35 to 42 |
| 9 | 41.0 ± 2.9 | 67.9 ± 8.7 | 35 to 43 |
| 10 | 46.1 ± 3.3 | 82.5 ± 9.0 | 35 to 44 |