

Scaling the EOS namespace Quick overview, and current status

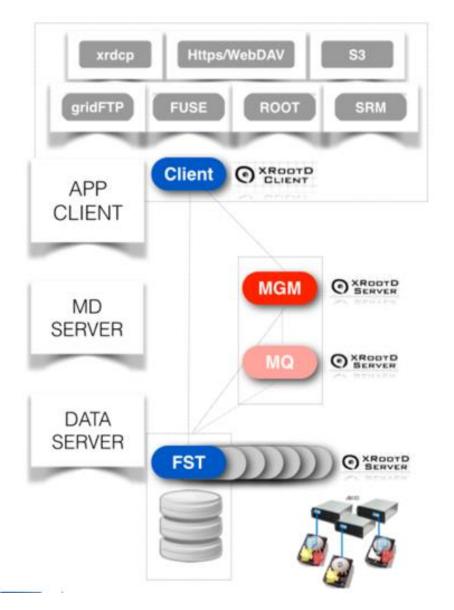
Georgios Bitzes, Elvin Sindrilaru, Andreas J. Peters, Andrea Manzi (speaker)





Architecture

- File Storage Nodes (FST): Management of physical disks, file serving
- Metadata Servers (MGM): Namespace + client redirection to FSTs
- Message Queue (MQ): Inter-cluster communication, heartbeats, configuration changes





The namespace subsystem

- EOS presents one single namespace to files it manages
 - ... even though they are typically spread across hundreds of disk servers and thousands of physical disks
- Handles file permissions, metadata, quota accounting, mapping between logical filenames and physical locations
- -rw-rw-r-- 1 user group 21 Jul 2 10:02 dir1/filename



In-memory namespace implementation

- The MGM previously held the **entire** namespace in-memory. Each file / directory entry allocates up to 1kb as a C++ structure in memory.
- Linear on-disk changelogs to track all namespace changes
 - file additions, metadata changes, physical location migrations ...
 - One for files, one for directories
- The in-memory contents are reconstructed on reboot by replaying the changelogs



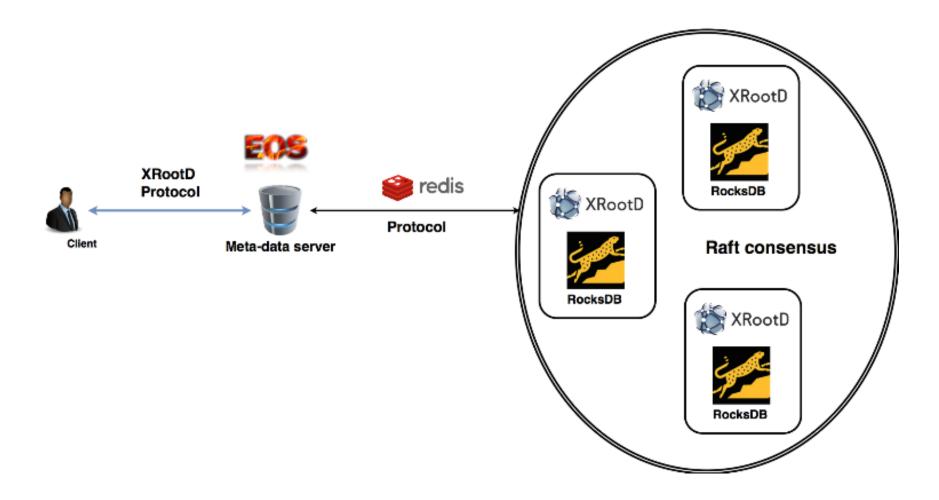
In-memory namespace implementation (2)

- Why replace the namespace implementation?
- Long boot time, proportional to the number of files on an instance. For large namespaces can exceed 1hour
 - Requires a lot of RAM





Architectural evolution





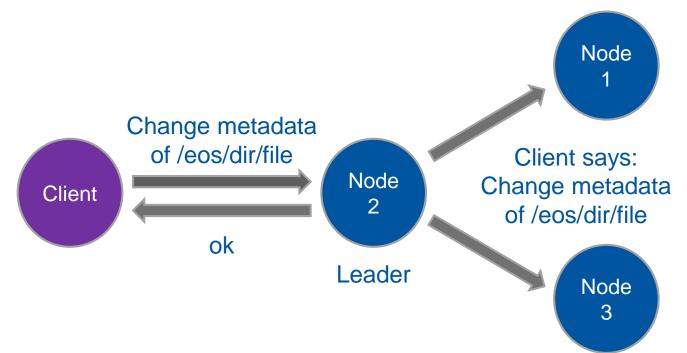
Architectural evolution (2)

- We've designed and implemented **QuarkDB**, a highly available datastore for the namespace.
 - Redis protocol, supports a small subset of Redis commands.
 - RocksDB as the underlying storage backend.
 - High availability: **Raft consensus** algorithm.
- Implement the minimum necessary, and keep the system simple
 - QuarkDB runs as a plug-in to the XRootD server framework used by EOS

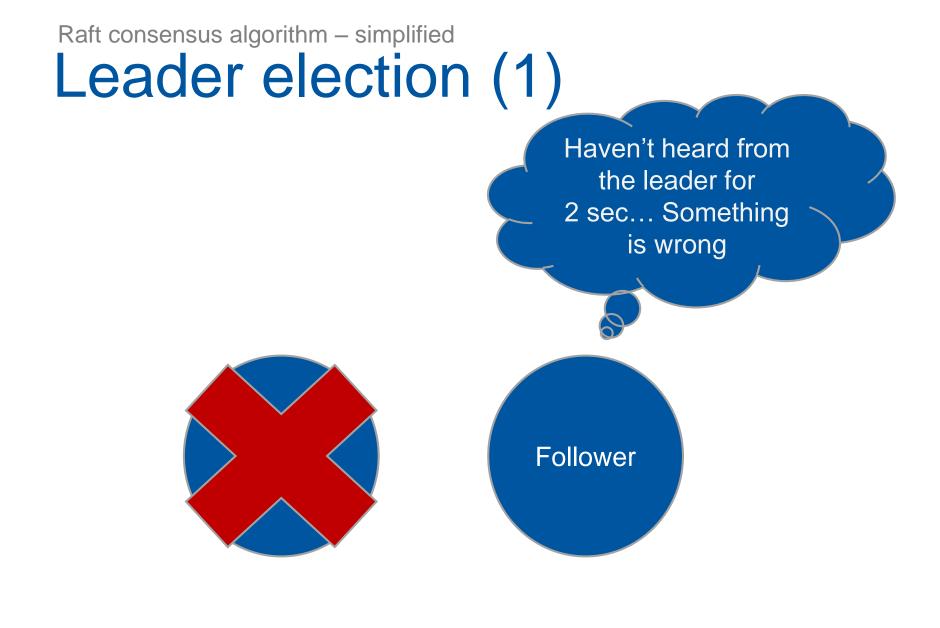


Raft consensus algorithm – simplified Replication

One of the nodes is elected to become the *master* (or *leader*)





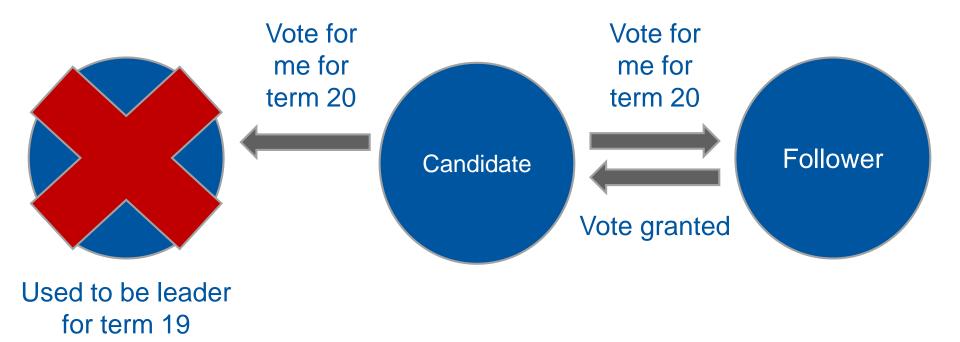




Raft consensus algorithm – simplified

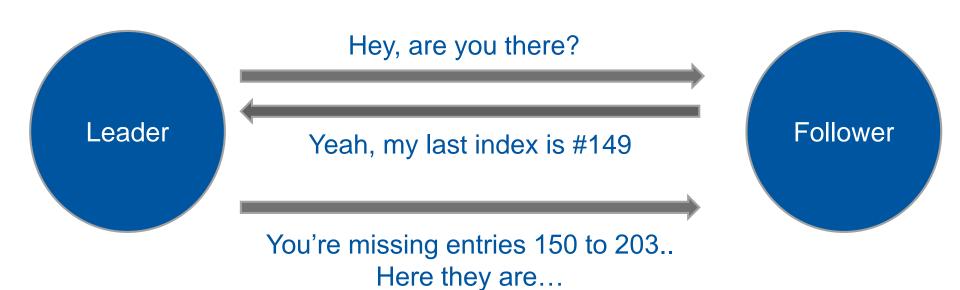
Leader election (2)

A successful election: 2 out of 3 nodes agree on the new leader











QuarkDB Testing

- Consensus bugs would be hard to trace, it has to be correct.
- QuarkDB is being tested extensively.
 - Unit, stress, chaos tests: From testing parsing utility functions, to simulating constant leader crashes and ensuring nodes stay in sync.
 - Test coverage: **91%**, measured on each commit.
 - All tests running under AddressSanitizer & ThreadSanitizer, on each commit.



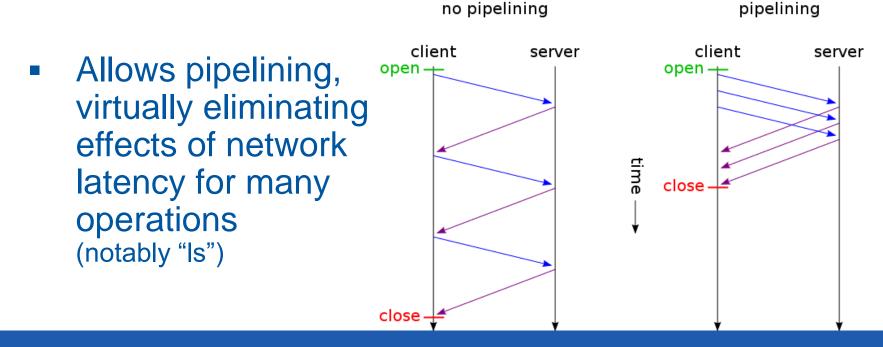
Problem: Network latency

- Previous assumption throughout the MGM code: Access latency to the NS is *minimal*, all lives in-memory.
- But with QDB, metadata lives a network roundtrip away...
 - Caching frequently accessed entries in the MGM helps a lot.
- Certain locks which were fine to hold for inmemory NS operations, were causing trouble for new NS.



Problem: Network latency (2)

- Using prefetching to first load metadata into the MGM cache, before holding any locks.
 - Allows staging in-flight requests from many clients simultaneously.





Current status

- **EOSPPS**: our pre-production instance runs NS on QuarkDB since 7 months
- 3.4 billion files (most are empty) larger namespace than all other instances combined
- Boot time: A couple of minutes J



Next steps: Implementing HA at the MGM level. Multiple standby MGMs, coordination through QuarkDB on who becomes active



Thanks

- <u>https://gitlab.cern.ch/eos/quarkdb</u>
- Current status: ~18k lines of code
 - including tests, tools
 - excluding dependencies
- More on Raft:
 - <u>https://raft.github.io/raft.pdf</u>
 - https://thesecretlivesofdata.com/raft/

Questions, comments?

