



AutoTunes

1. Motivation
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4. Results

Work with Leif Gellersen





Motivation

Motivation:

- Retuning the Herwig dipole shower
- Top Tunathon workshop in Manchester
- Is it a solved problem?
- Reduce human interaction

Goals:

- Keep possibility to interpret result
- Set weights for single observables automatically
- Set up flexible framework to test new weights
- Tune many parameters of the model -> high dim.
- Clear, simple and reproducible definition what was done in tune.



The Problem

Tuning is a very physicist dependent procedure:

- What data to tune to?
 - knowledge of data (Do we know some data is not „good“?)
 - Some data in rivet is same data (e.g. differential and integrated, updates...)
 - If many groups at LEP measure the same observable, does this enhance the weight in the next tune? (Only use one b-frag?)
- Correlations in the model?
 - knowledge of model (Should be given... but e.g. influence of 2->3 jet rate on b-fragmentation?)



Professor

Professor:

- Tool to compare and tune theory output to data
- First fit polynomials P for each bin i and parameter vector x to theory prediction T :

$$P_i(\vec{x}) = A_i + B_i^\mu x^\mu + C_i^{\mu\nu} x^\mu x^\nu + \dots \rightarrow \min(\chi^2(T_i(\vec{x}), P_i(\vec{x}))) \quad \forall \vec{x} \in [\vec{x}_{\min}, \vec{x}_{\max}]$$

- Then minimize $\chi^2(P(\vec{x}), D, \vec{w})$ with D =data points, w =weights for data points.
- So χ^2 depends on weights assigned to observables
- Polynomial approach good if observables predictions smooth and local \rightarrow Taylor expansion.. $[\vec{x}_{\min}, \vec{x}_{\max}]$ not to big!
- Polynomial approach grows fast with number of dimensions. But models have large number of parameters.



Reduce the dimension of the problem

Aim to reduce number of dimensions in a way that maximizes correlations between parameters. Professor can then work on the subspace of x to find best fit values.

How can we get information about the correlation and if a parameter matters for an observable?

If we find correlations and split the dimensions in subspaces, how can we weight the important bins in this sub-tune.

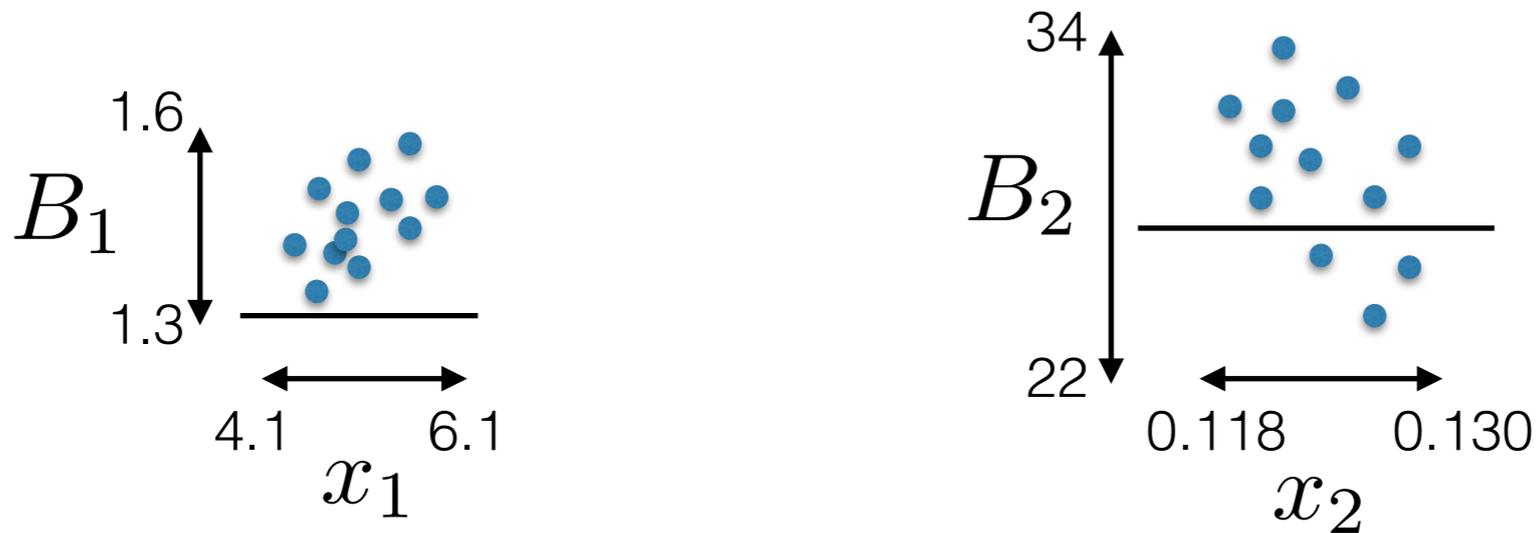
Summarize:

- How to split the d -dim space?
- How to tune sub-space?



Reduce the dimension of the problem

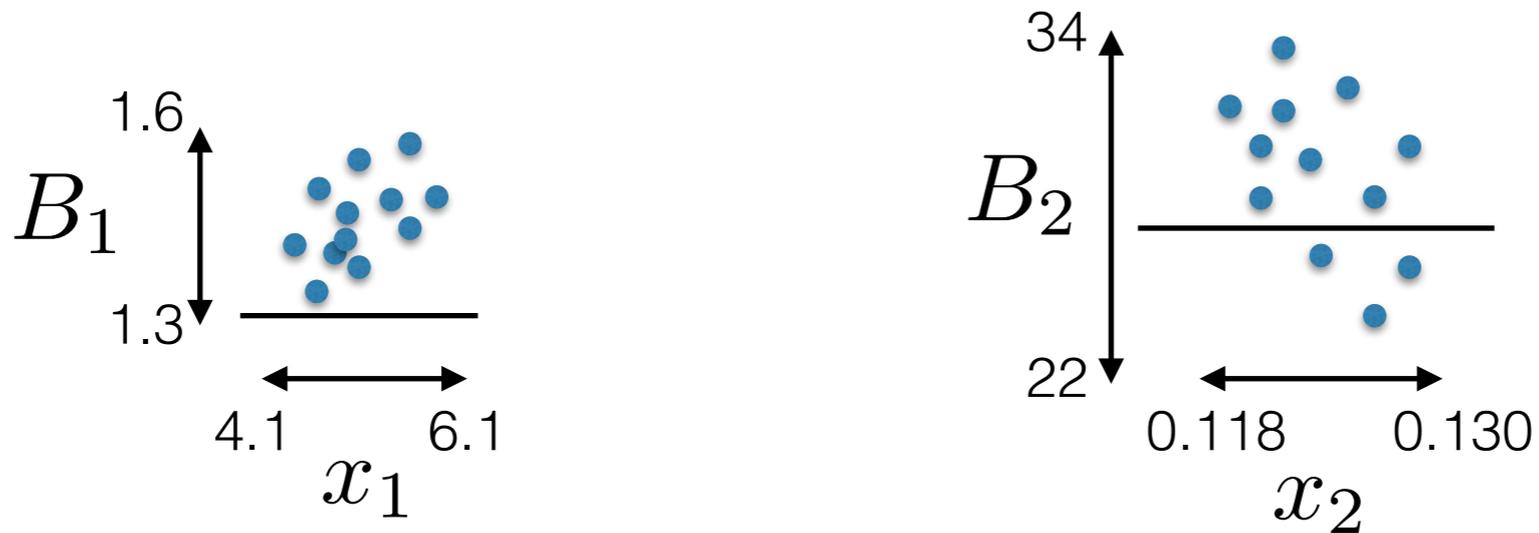
Lets start with observables/bins:





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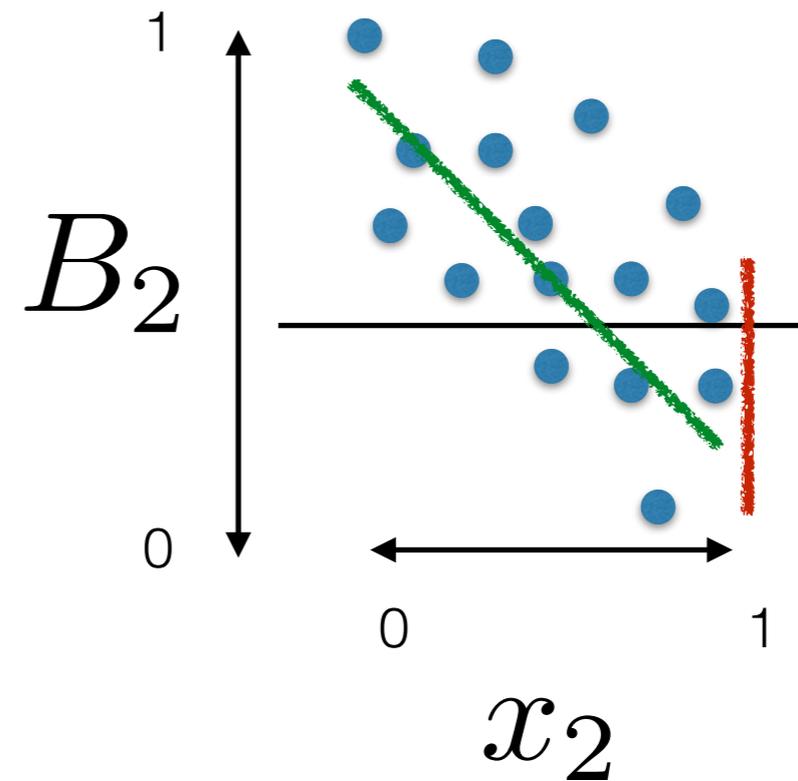


Reduce the dimension of the problem

Slope and scatter:

Slope indicates the dependence on parameter.

Scatter either by not-linear behavior and/or **other** parameters are important in this.

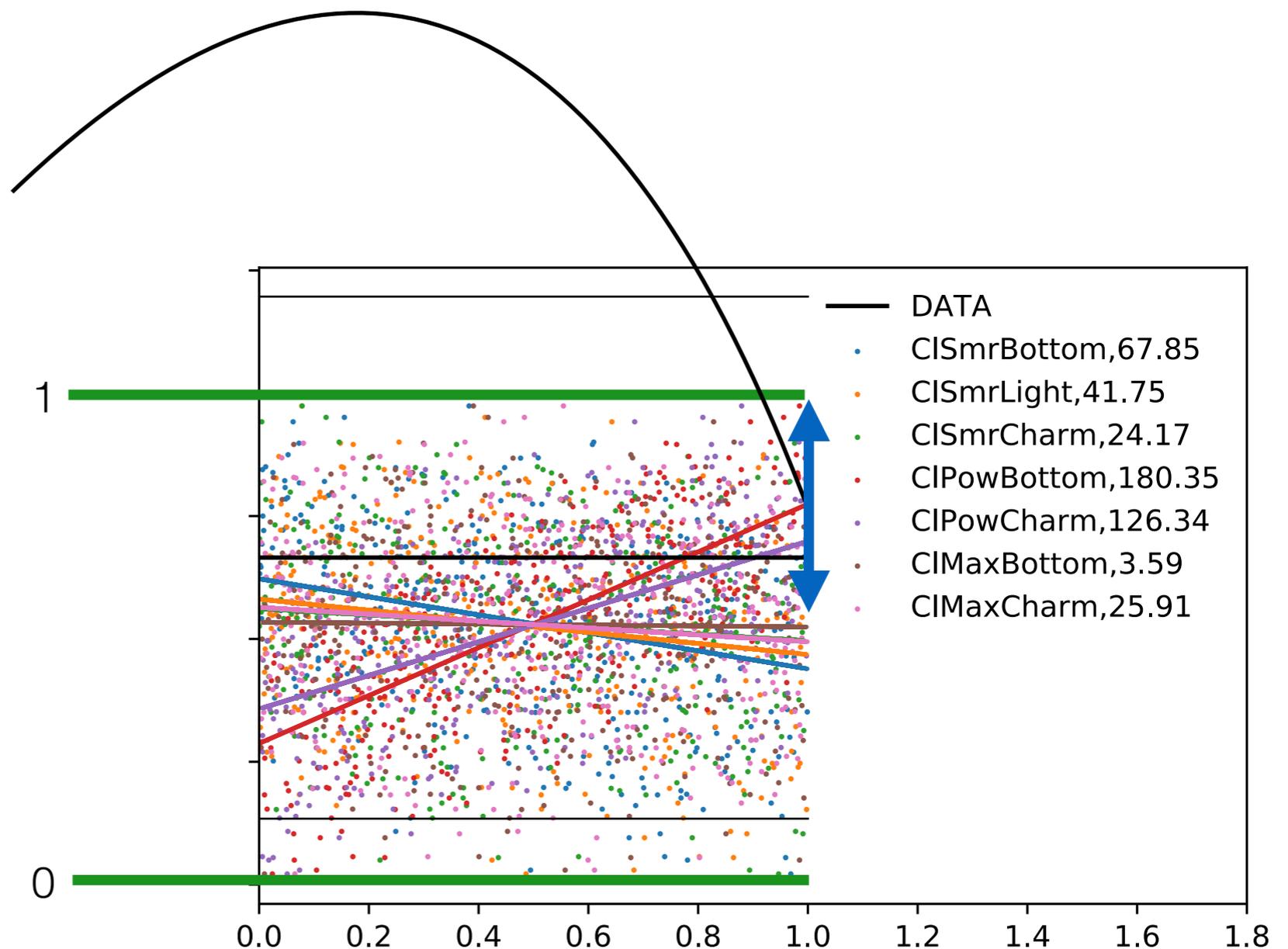




Reduce the dimension of the problem

Real life Example (arbitrary bin):

- Color of points misleading
- ~1000 random theory points
- height normalization by spread of random points.
- Here only 7 dims.
- If bin depends on more than one parameter, the slope of the a parameters are affected by the others.
- Don't care about data. This is just to get theory dependence.





Another Example:

$$B_0 = x_1 + x_2 + \lambda x_3 + \lambda x_4$$

$$B_1 = x_1 + x_2 + x_3 + \lambda x_4$$

$$B_2 = \lambda x_1 + x_2 + x_3 + \lambda x_4$$

$$B_3 = \lambda x_1 + \lambda x_2 + x_3 + x_4$$

$$S_0 = (1, 1, \lambda, \lambda)$$

$$S_1 = (1, 1, 1, \lambda)$$

$$S_2 = (\lambda, 1, 1, \lambda)$$

$$S_3 = (\lambda, \lambda, 1, 1)$$

B_0 = \p
B_1 = \p
B_2 = \l
B_3 = \l

S_0 = (1
S_1 = (1
S_2 = (\l
S_3 = (\l

Assume 4 bins that are described by 4 parameters.

Same parameter important in various bins!

$$\begin{matrix} S_0 = (1, 1, \lambda, \lambda) \\ S_1 = (1, 1, 1, \lambda) \\ S_2 = (\lambda, 1, 1, \lambda) \\ S_3 = (\lambda, \lambda, 1, 1) \end{matrix}$$

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Note:

By normalizing to spread we suppress influence of bins with bad resolution.

High discriminating power if lambda small



Another Example:

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$$N_i^\mu = S_i^\mu \circ \left(\sum_i S_i^\mu \right)^{-1}$$

Elementwise:

- We normalized the x-range!!
- Parameter that is important in many observables should be tuned last.
See tune-step selection



Split/chunk the d-dimensions

$$B_0 = x_1 + x_2 + \lambda x_3 + \lambda x_4$$

$$B_1 = x_1 + x_2 + x_3 + \lambda x_4$$

$$B_2 = \lambda x_1 + x_2 + x_3 + \lambda x_4$$

$$B_3 = \lambda x_1 + \lambda x_2 + x_3 + x_4$$

$$S_0 = (1, 1, \lambda, \lambda)$$

$$S_1 = (1, 1, 1, \lambda)$$

$$S_2 = (\lambda, 1, 1, \lambda)$$

$$S_3 = (\lambda, \lambda, 1, 1)$$

$$N_i^\mu = S_i^\mu \circ \left(\sum_i S_i^\mu \right)^{-1}$$

Combination vectors:

$$J_0 = (1, 1, 0, 0)$$

$$J_1 = (1, 0, 1, 0)$$

$$J_2 = (1, 0, 0, 1)$$

$$J_3 = (0, 1, 1, 0)$$

$$J_4 = (0, 1, 0, 1)$$

$$J_5 = (0, 0, 1, 1)$$

Maximize the projection on subspaces :

$$w_k = \sum_i (N_i J_k)^2$$

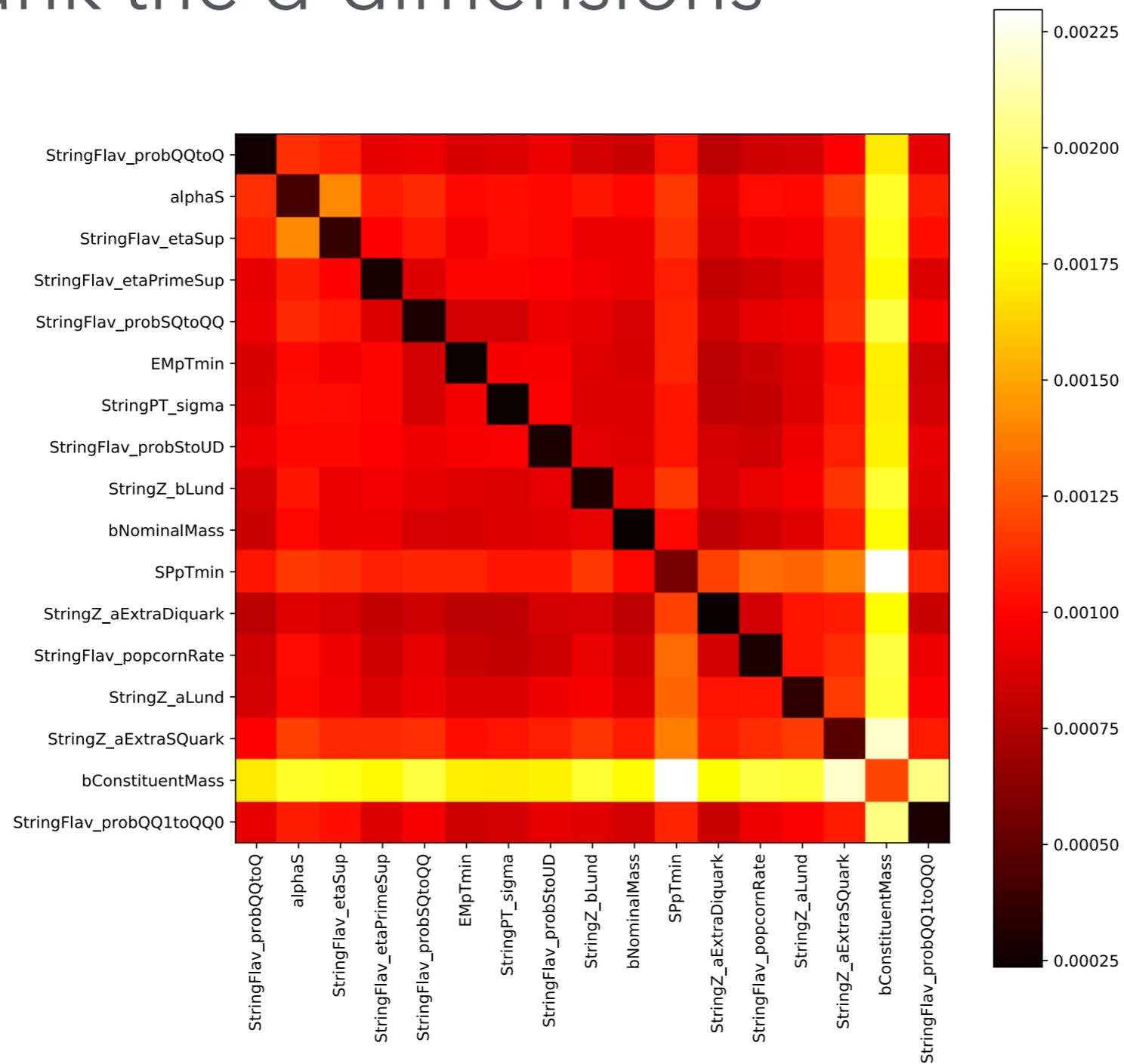
Correlates parameters that have influence in same bins.

$\max(w_k)$ defines first sub-tune.

Next sub-tunes orthogonal to J_k .



Split/chunk the d-dimensions



This is the Herwig shower with Lund stings..

Interfaced with modified version of TheP8I interface used for Ariadne.



Split/chunk the d-dimensions

The weight for observables should be large in a sub-tune if it „points“ in the direction of the currently tested/tuned subset of directions:

Currently testing various weight combinations (numerically and influence on Chi2):

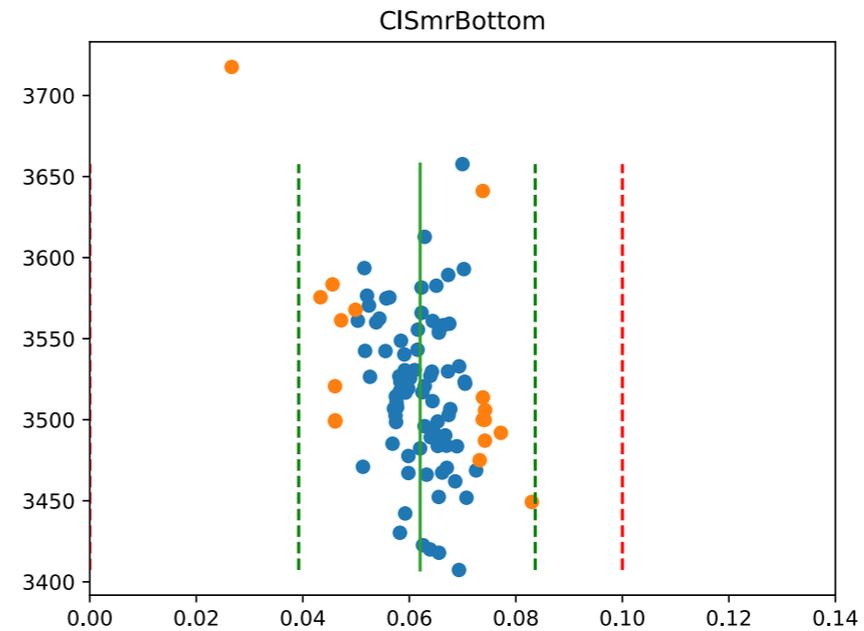
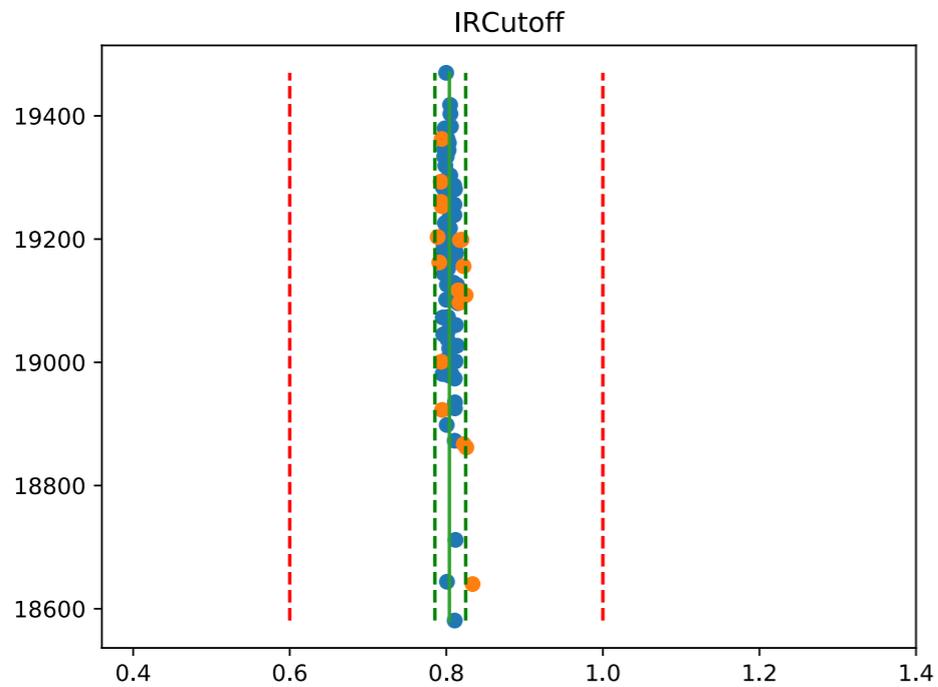
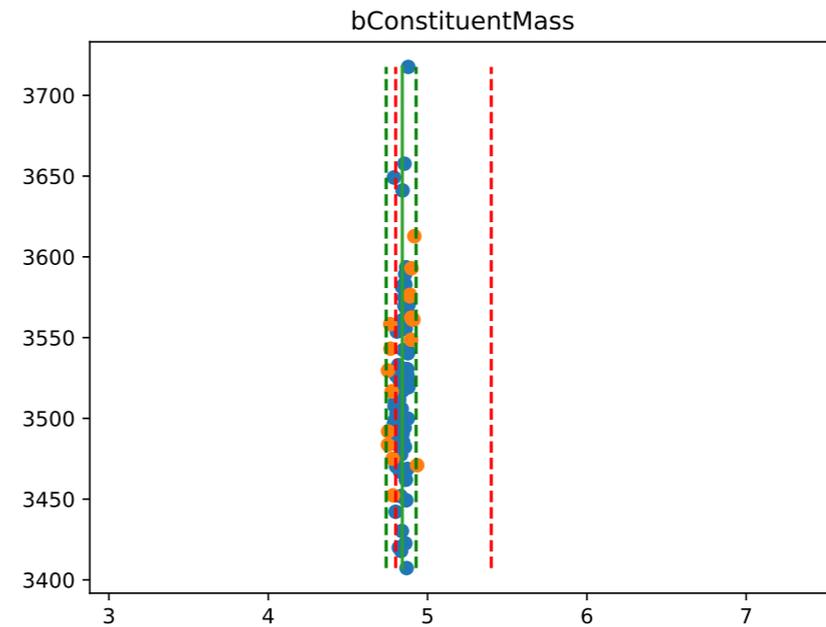
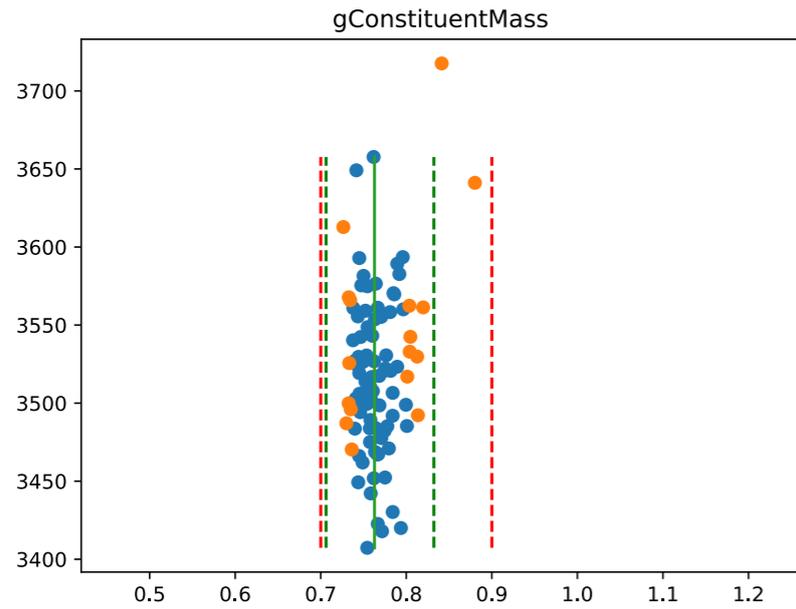
$$W_i = (N_i J_{\text{Step1}})^2$$

$$W_i = (N_i J_{\text{Step1}})$$

$$W_i = (N_i J_{\text{Step1}})^2 / |N_i|$$

Bins that „point“ in same directions can be correlated. These weights could have influence if we want to reduce impact of similar measurements.

Results



The End



Thank you!