



AIDA<sup>2020</sup>



# Towards full electromagnetic physics vectorisation in the GeantV transport framework

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on behalf of the GeantV development team

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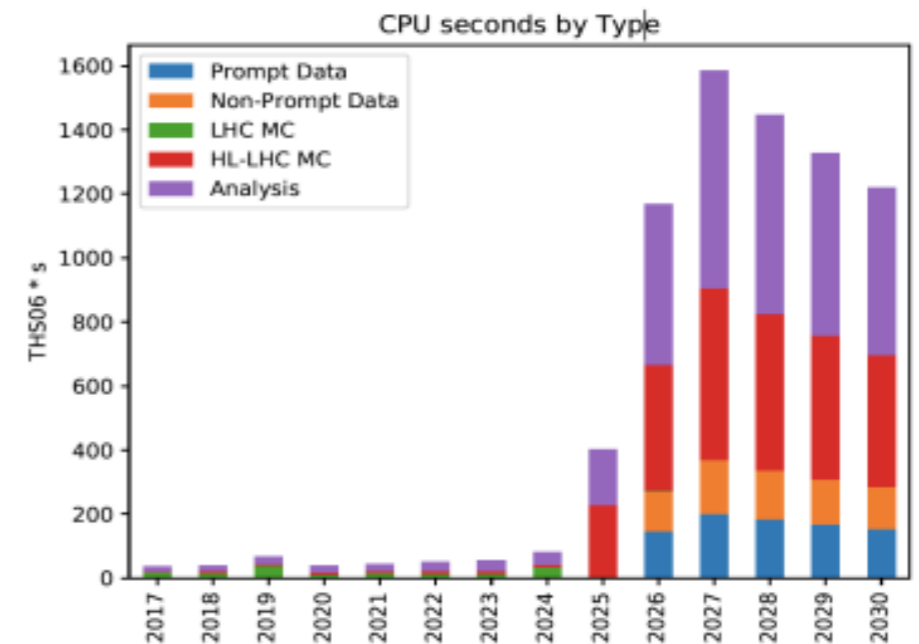
# INTRODUCTION

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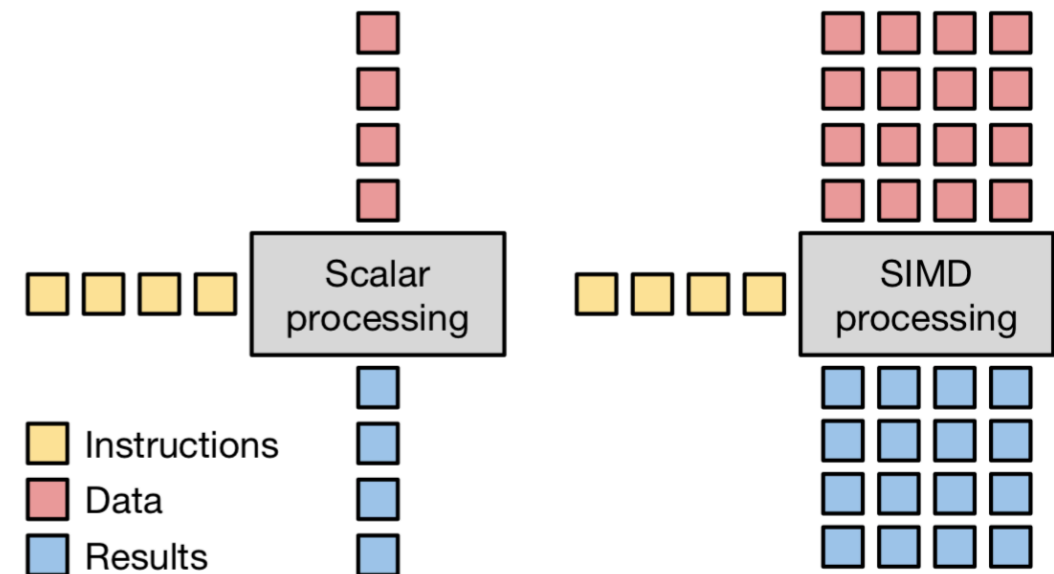
- Event simulation is one of the **most time consuming** parts of the workflow, in the HEP sw ecosystem
  - For high-luminosity LHC phase (HL-LHC), the upgraded experiments expect to collect **150 times more data** than in Run 1
- The **GeantV R&D project** was launched in 2013, aiming at exploring emerging computer technologies in order to significantly increase run-time performance of detector simulation



**CMS and Atlas estimated CPU needs for HL-LHC (source: CWP)**

# INTRODUCTION

- Event simulation is one of the **most time consuming** parts of the workflow, in the HEP sw ecosystem
  - For high-luminosity LHC phase (HL-LHC), the upgraded experiments expect to collect **150 times more data** than in Run 1
- The **GeantV R&D project** was launched in 2013, aiming at exploring emerging computer technologies in order to significantly increase run-time performance of detector simulation
- The project studies performance gains when changing the classic particle transport approach, propagating **multiple tracks from multiple events in parallel**
  - improving code and data locality in the process
  - enabling SIMD/SIMT execution models:  
Vectorization+Multithreading
- **Vectorization of physics library** is important as key part of the algorithmic chain



# WHEN CAN WE PROFIT FROM VECTORIZATION

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## ➤ Functions with many **math computations**

- Such as +, \*, /, sqrt, sin, cos, exp, log (ordered according to approximate computation complexity)

## ➤ Functions with **minimal branching**

- Branching **\*\*may\*\*** require to evaluate both branches for vectorized code

### Scalar code

```
if (cond > rndArray[0]) {  
  eps = Math::Exp(-a11 * rndArray[1]);  
  eps2 = eps * eps;  
} else {  
  eps2 = eps02 + (1. - eps02) * rndArray[1];  
  eps = std::sqrt(eps2);  
}
```

### Vector code

```
MaskD_v cond1 = cond > rnd1;  
if (!MaskEmpty(cond1)) {  
  vecCore::MaskedAssign(eps, cond1, Math::Exp(-a11 * rnd2));  
  vecCore::MaskedAssign(eps2, cond1, eps * eps);  
}  
if (!MaskEmpty(!cond1)) {  
  vecCore::MaskedAssign(eps2, !cond1, eps02 + (1.0 - eps02) * rnd2);  
  vecCore::MaskedAssign(eps, !cond1, Math::Sqrt(eps2));  
}
```

## ➤ Functions not bounded by **memory access**

- Load 4 doubles into SIMD register is one instruction but it is not faster than loading values one by one

# GEANTV EM PHYSICS LIBRARY

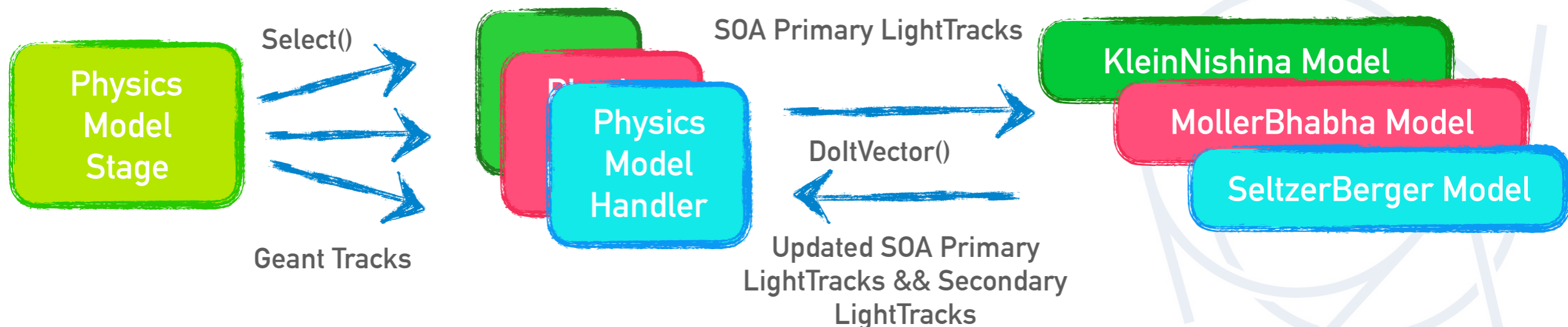
## Current State

particle	processes	model(s)	
		GeantV	Geant4
$e^-$	ionisation	Møller [100eV-100TeV]	Møller [100eV-100TeV]
	bremsstrahlung	Seltzer-Berger [1keV-1GeV]	Seltzer-Berger [1keV-1GeV]
		Tsai (Bethe-Heitler) w. LPM. [1GeV-100TeV]	Tsai (Bethe-Heitler) w. LPM. [1GeV-100TeV]
	Coulomb sc.	GS MSC model [100eV-100TeV]	Urban MSC model [100eV-100MeV]
Mixed model [100MeV-100TeV]			
$e^+$	ionisation	Bhabha [100eV-100TeV]	Bhabha [100eV-100TeV]
	bremsstrahlung	Seltzer-Berger [1keV-1GeV]	Seltzer-Berger [1keV-1GeV]
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	Coulomb sc.	GS MSC model [100eV-100TeV]	Urban MSC model [100eV-100MeV]
			Mixed model [100MeV-100TeV]
annihilation	Heitler ( $2\gamma$ ) [0-100TeV]	Heitler ( $2\gamma$ ) [0-100TeV]	
$\gamma$	photoelectric	Sauter-Gavrila + EPICS2014 [1eV-100TeV]	Sauter-Gavrila + EPICS2014 [1eV-100TeV]
	incoherent sc.	Klein-Nishina <sup>+</sup> [100eV-100TeV]	Klein-Nishina <sup>+</sup> [100eV-100TeV]
	$e^-e^+$ pair production	Bethe-Heitler <sup>+</sup> [100eV-80GeV]	Bethe-Heitler <sup>+</sup> [100eV-80GeV]
		Bethe-Heitler <sup>+</sup> w. LPM [80GeV-100TeV]	Bethe-Heitler <sup>+</sup> w. LPM [80GeV-100TeV]
	coherent sc.	-	Livermore
+	energy loss fluct.	-	Urban

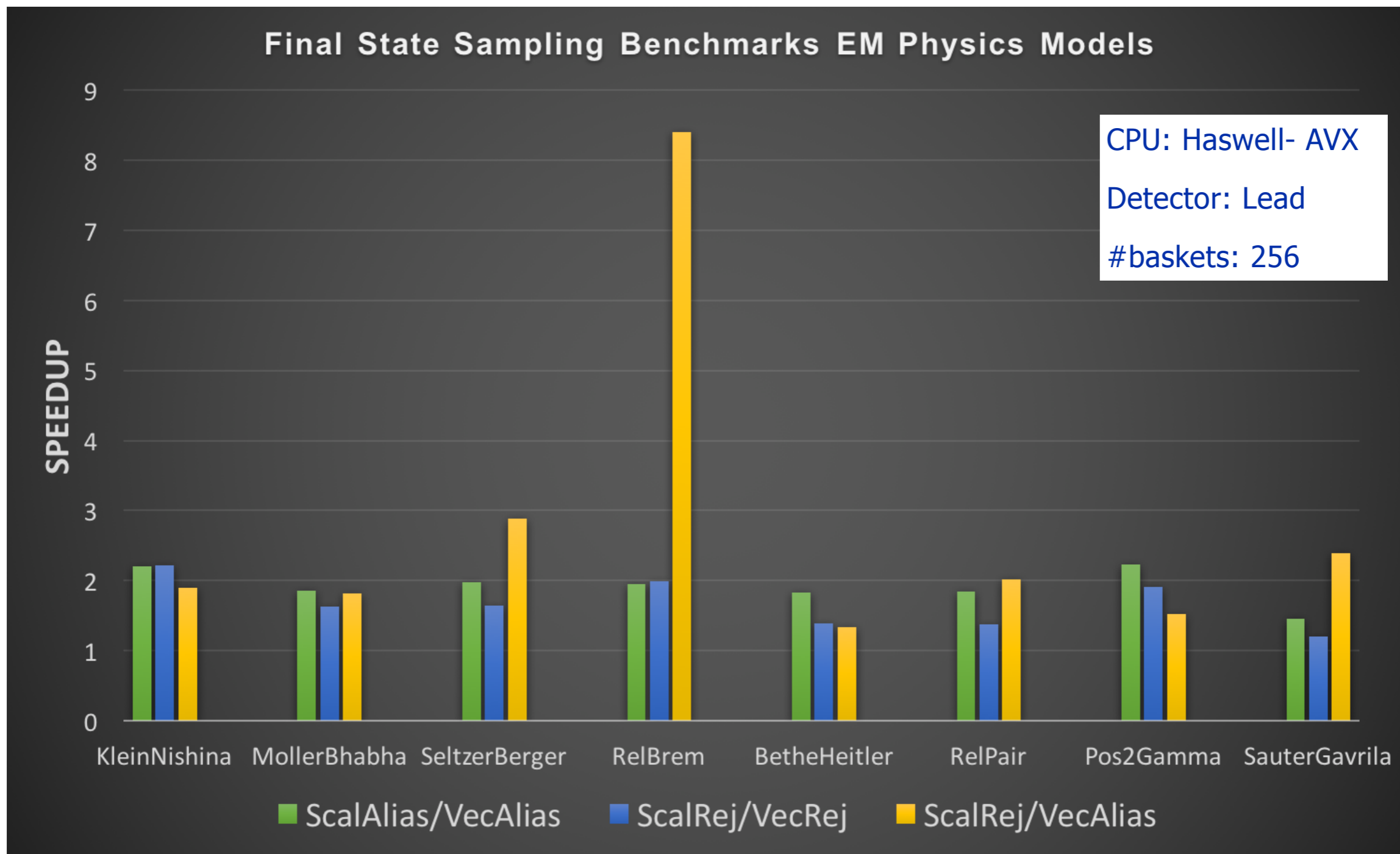
- Every model is **tested and verified against the corresponding Geant4** model (cross section per atom, cross section per volume, and kinematic of primary and secondary particles)
- **EM showers** in GeantV can be **fully simulated** in real applications (i.e. FullCMS, TestEM3, TestEM5, FullLHCb) and the results are verified against the corresponding Geant4 simulation

# ELECTROMAGNETIC PHYSICS – FINAL STATE GENERATION

- Once the particle undergoes a physics process, the **final state generation stage** occurs:
  - Differential cross sections are used to update the **kinematic properties** of the primary particle and to **produce secondary particles** (if necessary)
  - Sampling with rejection / Sampling with Alias tables + approximations
- The final state generation involves **two main** parts in GeantV:
  - **Framework** part: filtering of tracks (according to particles type, physics process), gathering relevant track information into SOA form (LightTracks), call the physics model
  - **Model** part: Specific code for the selected physics model: update primaries, create secondaries..



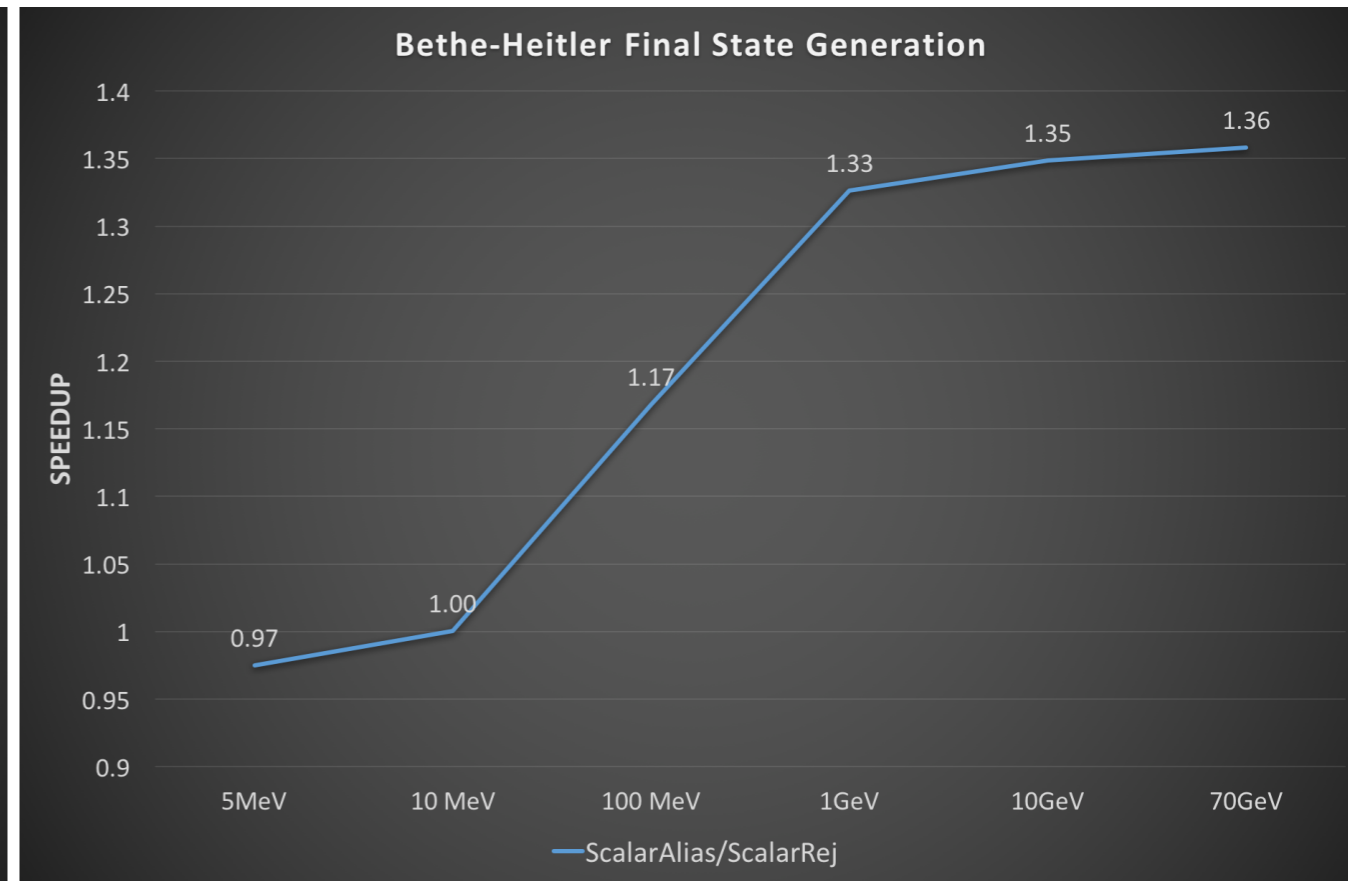
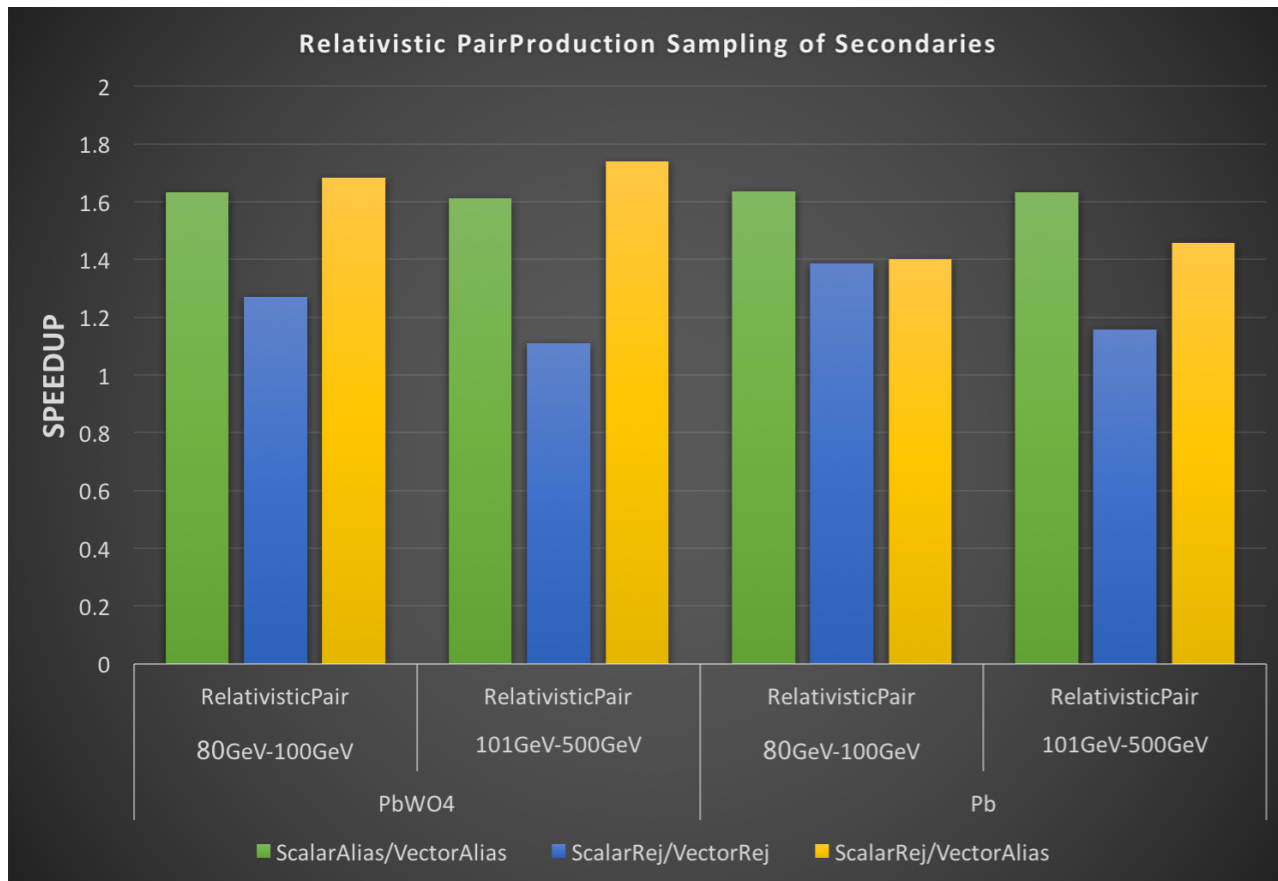
# MODEL LEVEL TEST BENCHMARKS



See next talk, from [A. Gheata](#) for benchmarks on the full simulation chain



# TUNING THE SIMULATION THROUGH MODELS



CPU: Haswell - AVX  
 Detector: Pb/PbWO4  
 Model for Energy Range [80GeV-100TeV]  
 #baskets: 256

CPU: Haswell - AVX  
 Detector: Pb  
 Model for Energy Range [2 e<sup>-</sup>mc<sup>2</sup>-80GeV]  
 Scalar execution

# SUMMARY

- Physics model integrated in the GeantV framework and validated against corresponding Geant4 simulation
- Most of the **EM physics library** models are now **vectorized**
  - Work in progress on Multiple scattering
  - Optimization of the current vectorized implementations
- SpeedUp
  - At the level of final-state EM Model: between 1.5-3 on Haswell, 2-4 on Skylake with AVX2
  - See A. Gheata [talk](#) for the impact on realistic EM showers in calorimeters and fullCMS applications

## WORK IN PROGRESS

- Work on **other parts** of the physics framework
  - ComputeIntLenght(), generation and insertion of secondary particles, etc..
- VecMath library and Vectorized pRNG (handling reproducibility issues)
- Study the possibility to substitute double precision computations with single one, in some parts of the physics library (i.e. transport in magnetic field)
- Add **AVX512** support (UME::SIMD)
  - currently there is no way to test consistently AVX512

GeantV project is hosted at: <https://gitlab.cern.ch/GeantV/geant>  
GeantV website: <http://geant.cern.ch>

**THANKS FOR THE ATTENTION!**



**QUESTIONS?**



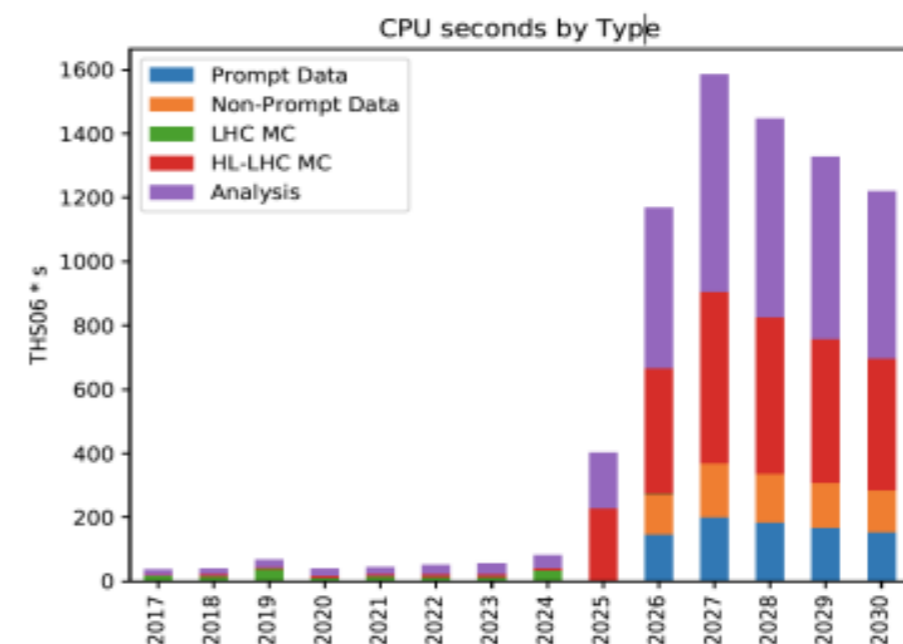
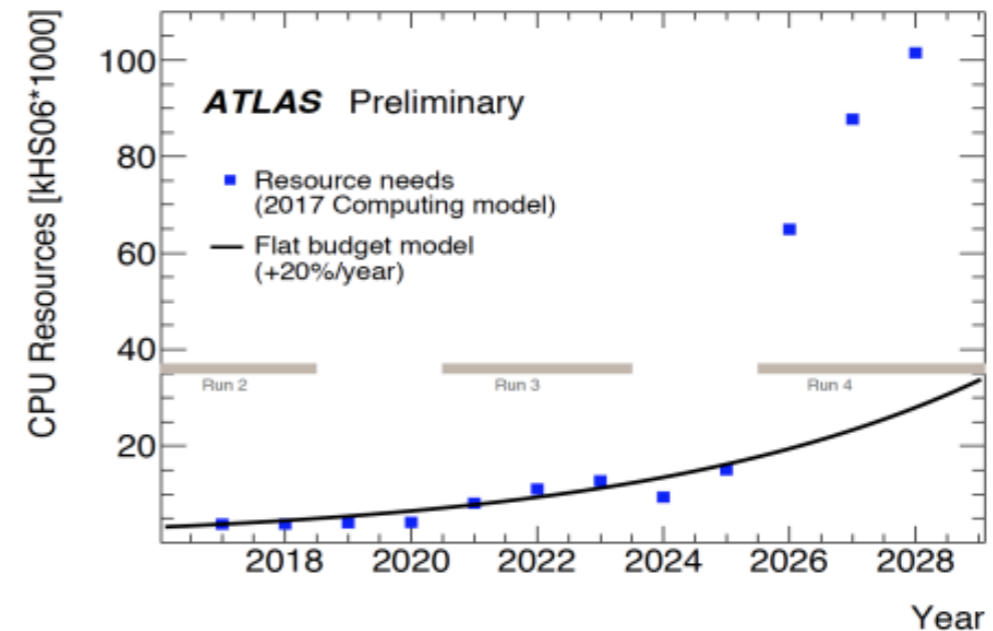
# BACKUP



# NEED FOR FASTER SIMULATION CODE FOR HEP COMMUNITY

Estimated ~10x CPU needs for the HL-LHC era

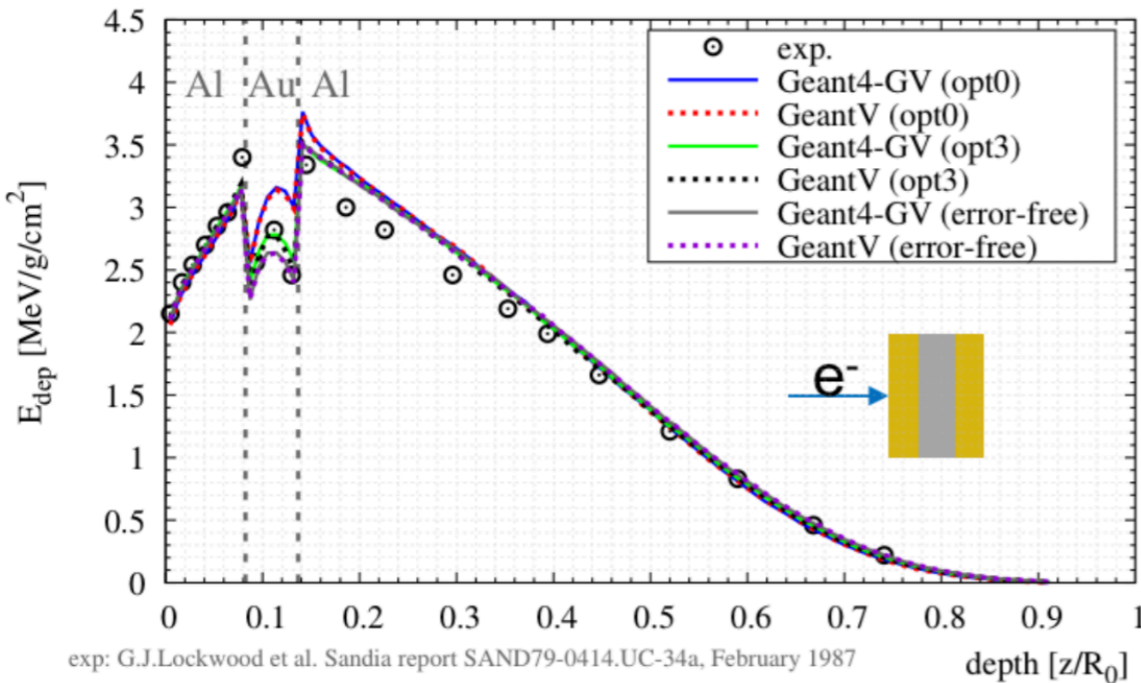
- During the first two runs, the LHC experiments produced, reconstructed, stored, transferred, and analysed **tens of billions** of simulated events
- As part of the high-luminosity LHC physics program (HL-LHC), the upgraded experiments expect to collect **150 times more data** than in Run 1
- More than **50%** of WLCG power used for simulations
- **GeantV**: path towards a faster toolkit **2-5 x Geant4**



**CMS and Atlas estimated CPU needs for HL-LHC (source: CWP)**

# EM PHYSICS MODELS VALIDATION

Energy deposit of  $E_p = 1.0$  [MeV]  $e^-$  in Al[168.4 $\mu$ m]-Au[21.7 $\mu$ m]-Al[1.5904mm] as a function of the depth (MSC  $R_f = 0.1$ ; cut = 100 [nm])



## Multi-layered target

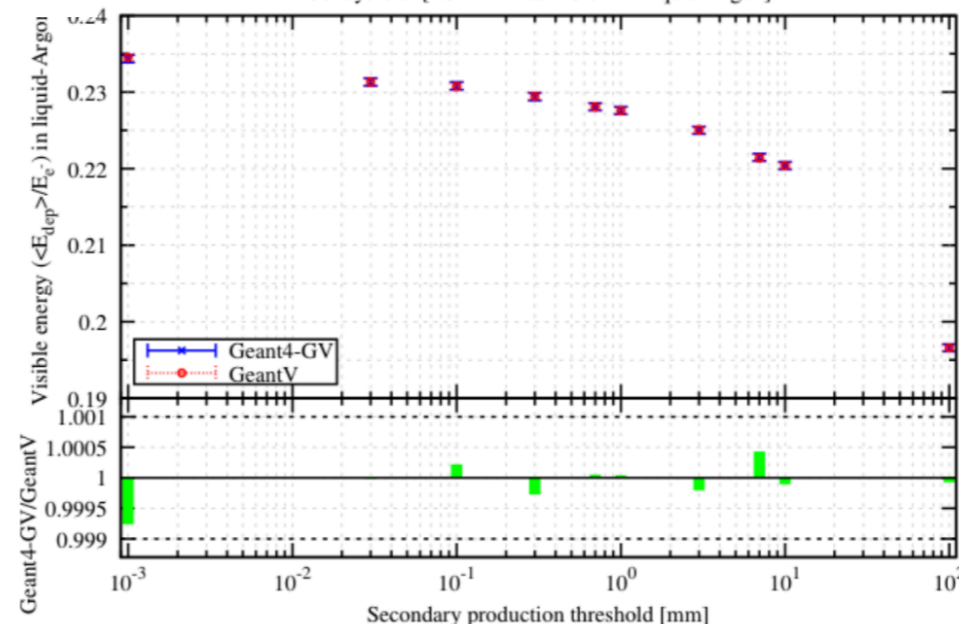
Work in progress on vectorization of all the EM physics - expected to be included in the beta release!

Scalar EM models revisited in a vectorization friendly way (e.g. vectorizable sampling) and validated against Geant4 version.

$10^5$   $e^-$  in ATLAS bar. simpl. cal. : 50 layers of [2.3 mm Pb + 5.7 mm lAr]; p.cut = 0.7 [mm]

material	$e^-/e^+$ : ionisation, bremsstrahlung, msc; $\gamma$ : Compton, conversion							
	GeantV		Geant4		GeantV		Geant4	
	$E_d$ [GeV]	rms [MeV]	tr.l. [m]	rms [cm]	$E_d$ [GeV]	rms [MeV]	tr.l. [m]	rms [cm]
Pb	0.69450	15.198	51.015	1.189	0.69448	15.234	51.016	1.192
lAr	0.22792	14.675	106.11	7.592	0.22796	14.656	106.13	7.582

$10^4 e^- E_e = 10$  [GeV] in Sampling Calorimeter: 50 layers of [2.3 mm Lead + 5.7 mm liquid-Argon]



Mean number of :

gamma	405.87	406.15
electron	9411.49	9419.44
positron	53.77	53.71
charged steps	11470	11476
neutral steps	49177	49222

credit: M. Novak

ATLAS simplified sampling calorimeter

# MAXIMUM SPEEDUP ACHIEVABLE

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- Depends on the **vector width** but..
- Generally is **less than the vector register width**
- some operations are **slower** for vector registers

Reciprocal Throughput\* for Division DP  
(SandyBridge)

Scalar	10-20 cycles
Vector	20-44 cycles

- Maximum speedup for division will be  $\sim 2$  for this CPU
- **Overhead** payed to gather data into SIMD vectors
- Another important factor is the **number of execution units** for particular instructions = number of instructions that can be executed simultaneously.

\*The average number of core clock cycles per instruction for a series of independent instructions of the same kind in the same thread.

\*\*

# RESULTS: MODEL LEVEL TEST BENCHMARKS

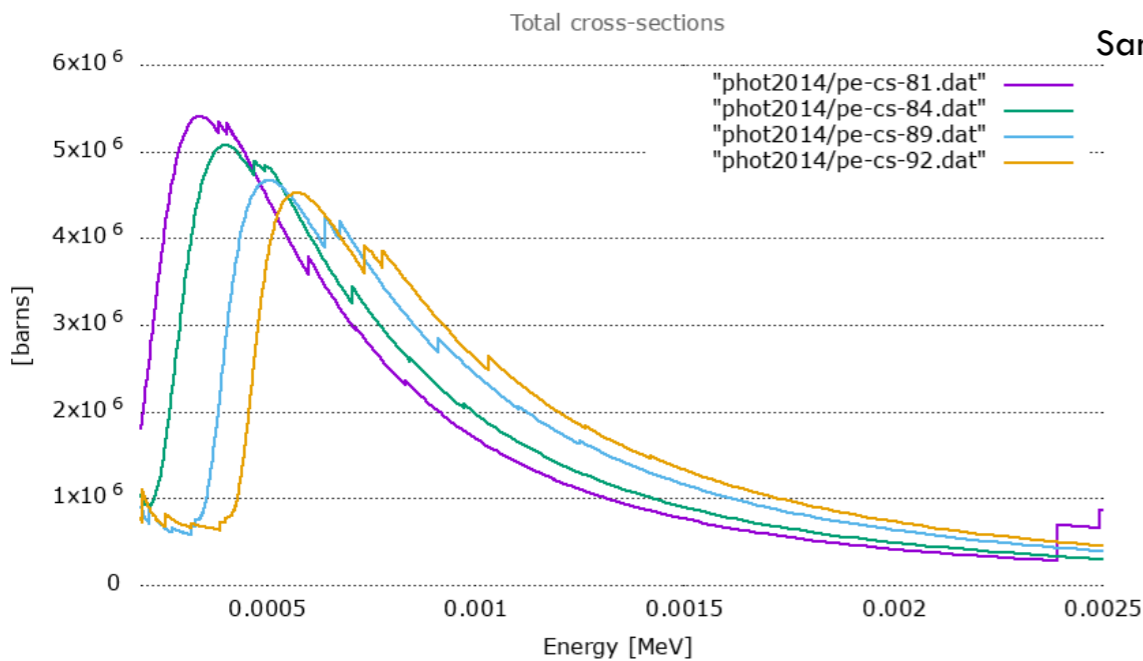
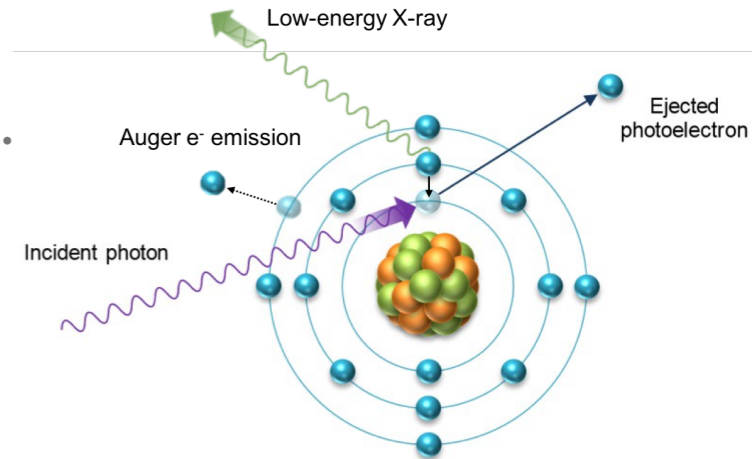
Model	Haswell (avx)	
	Scalar Time [ms]	SpeedUp
Klein-Nishina alias	56.4	2.2
Klein-Nishina rej	48.37	2.21
Moller-Bhabba alias	51.32	1.85
Moller-Bhabba rej	50.21	1.62
Seltzer-Berger brems alias	73.19	1.98
Seltzer-Berger brems rej	106.63	1.64
Relativistic brems alias	76.96	2
Relativistic brems rej	330.57	2
Bethe-Heitler pair alias	86.53	1.82
Bethe-Heitler pair rej	62.98	1.39
Relativistic pair alias	91.66	1.37
Relativistic pair rej	83.42	1.83
Positron2Gamma alias	60.78	2.23
Positron2Gamma rej	41.34	1.91
Sauter-Gavrila alias	66.4	1.45
Sauter-Gavrila rej	108.89	1.2

Test with Lead, #baskets: 256

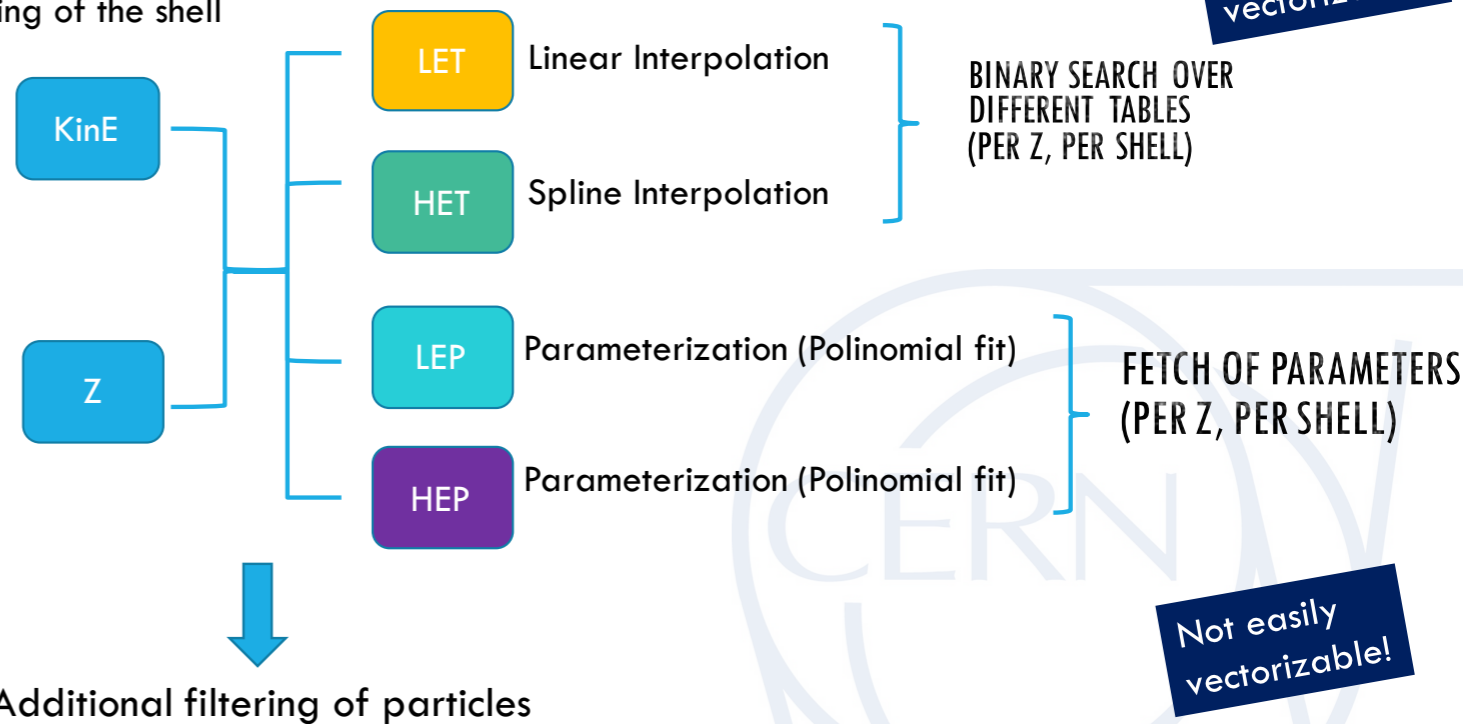


# EXAMPLE: PE EFFECT

- Photoelectric effect total cross-section is not an easy function
  - Fit in two different energy ranges, but not below k-shell binding energy
    - Tabulated cross-sections left for low energies
  - For the final state sampling one need to sample
    - the angle: described by the SauterGavrila differential cross-section
    - the subshell: This is going through a binary search algorithm (not vectorizable) + linear or spline interpolation

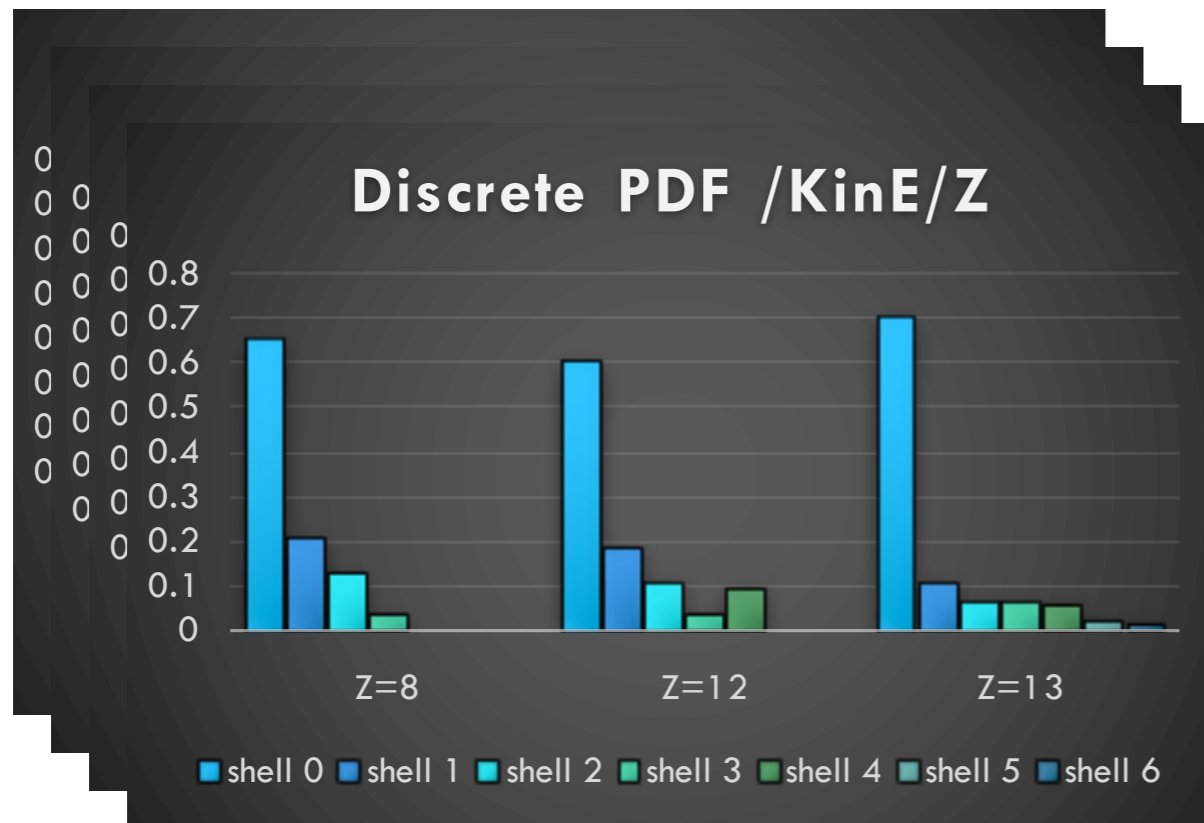


Sampling of the shell

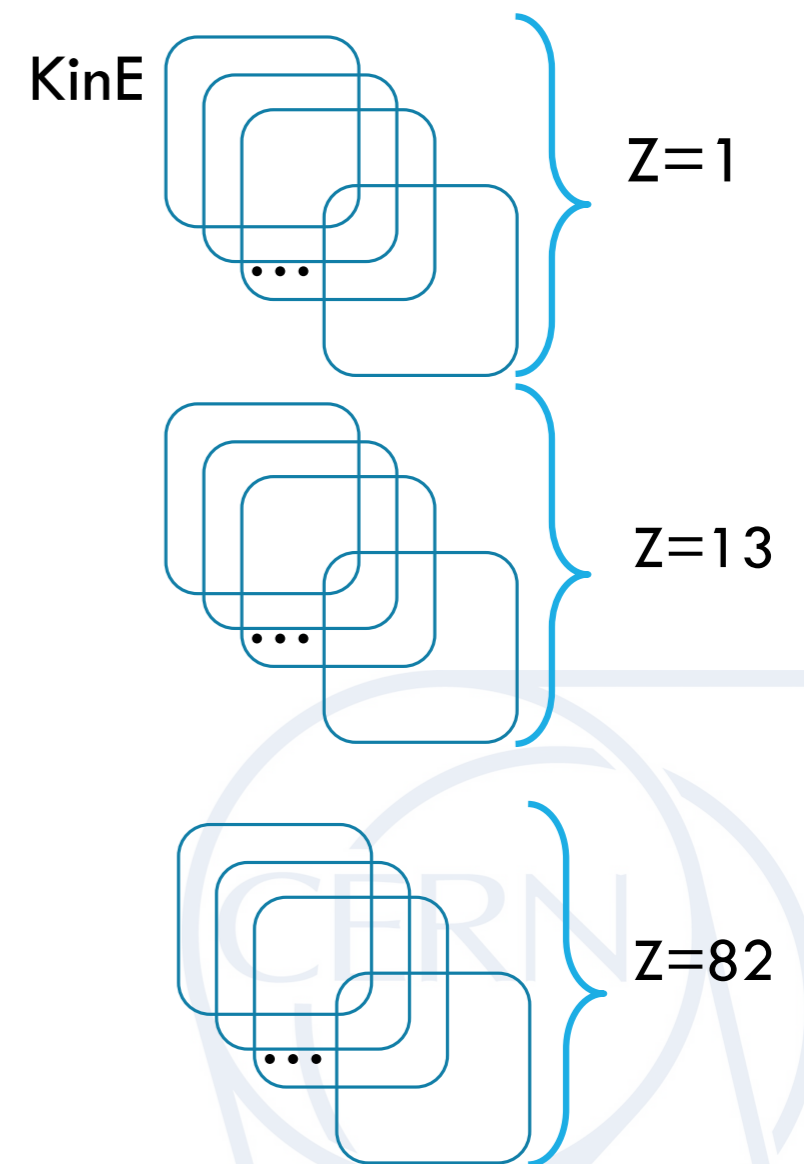


Additional filtering of particles

# VECTORIZATION WITH DISCRETE ALIAS TABLES



## ALIAS TABLE FOR DISCRETE DISTRIBUTION



- We generated a denser ss-cs dataset
  - to build equally spaced (in energy) discrete PDFs for each element (linearly interpolated)
  - From them we can build Alias Table
    - PRO: sampling of shells with only one case
    - CONS: Gathering operations

# VECTORIZATION OF REJECTION SAMPLING

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# VECTORIZATION OF REJECTION SAMPLING

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- 1 Prepare values that are needed for sampling, in form of arrays



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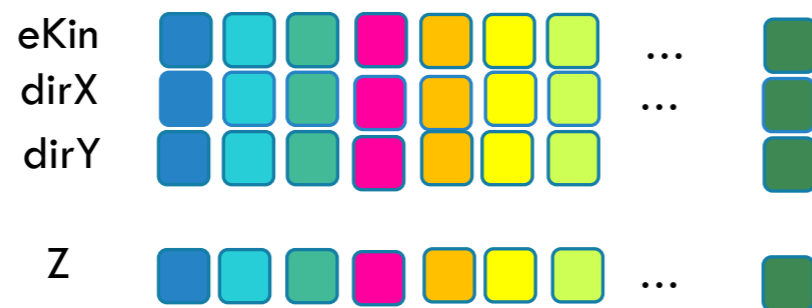
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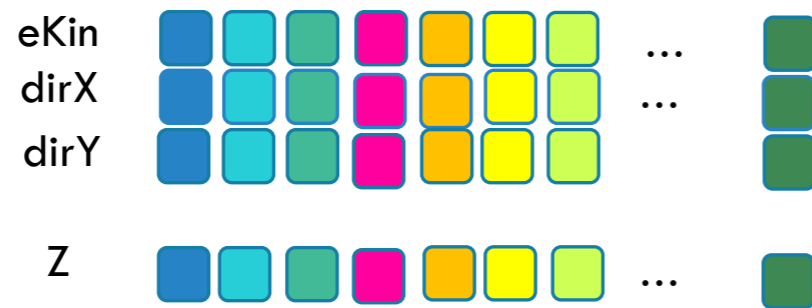
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# VECTORIZATION OF REJECTION SAMPLING

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- 2

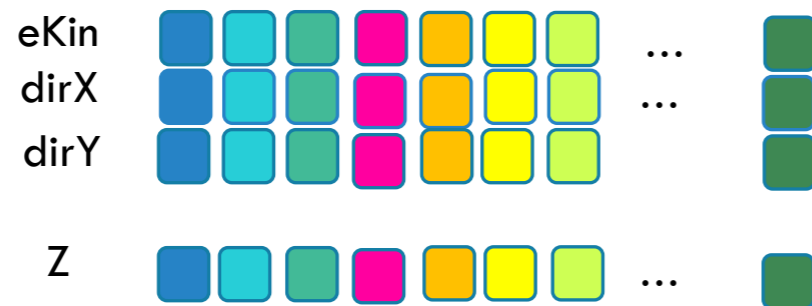
Store in SIMD vector the indexes of the current tracks that have to be sampled





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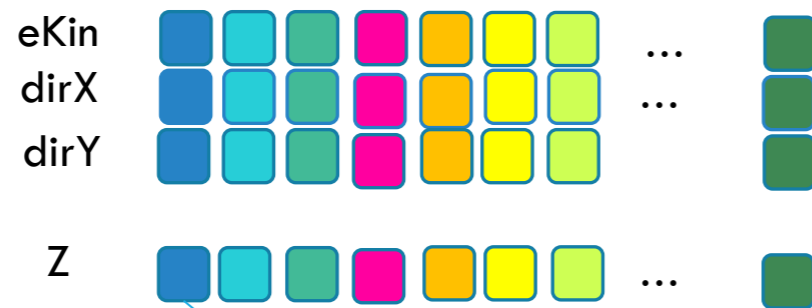


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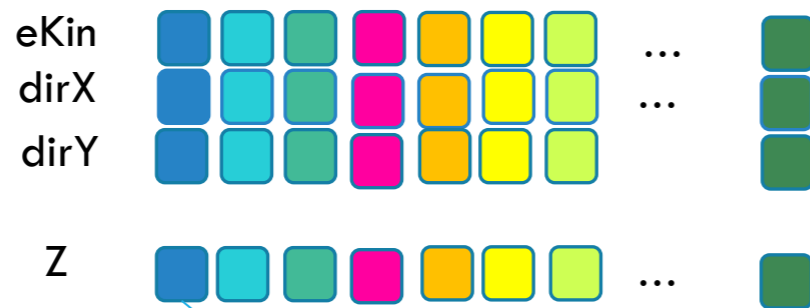


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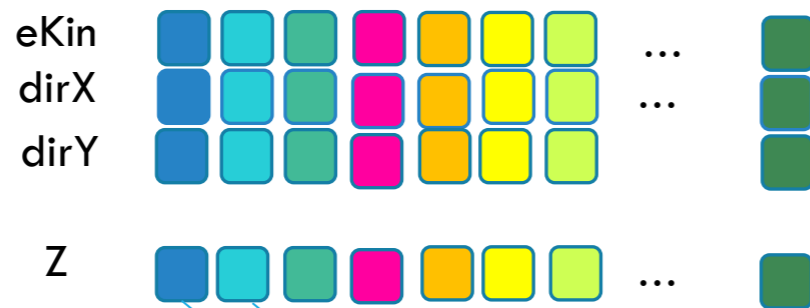


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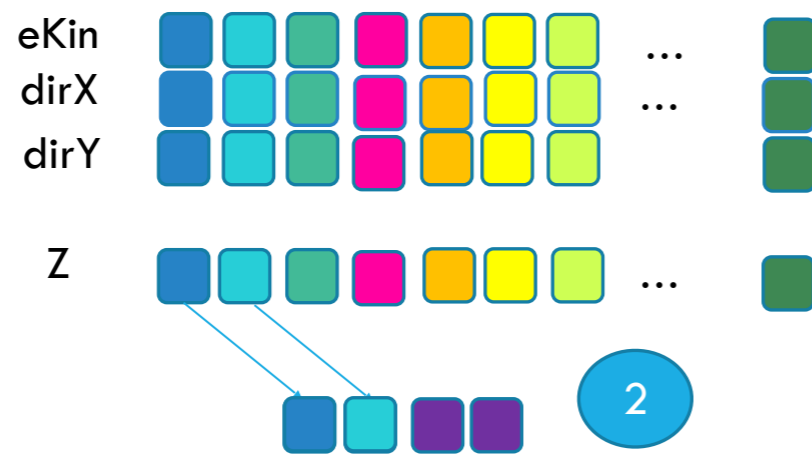


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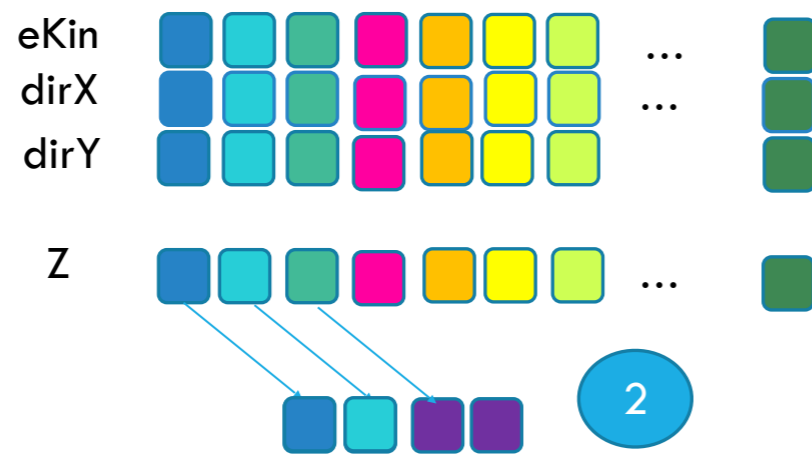


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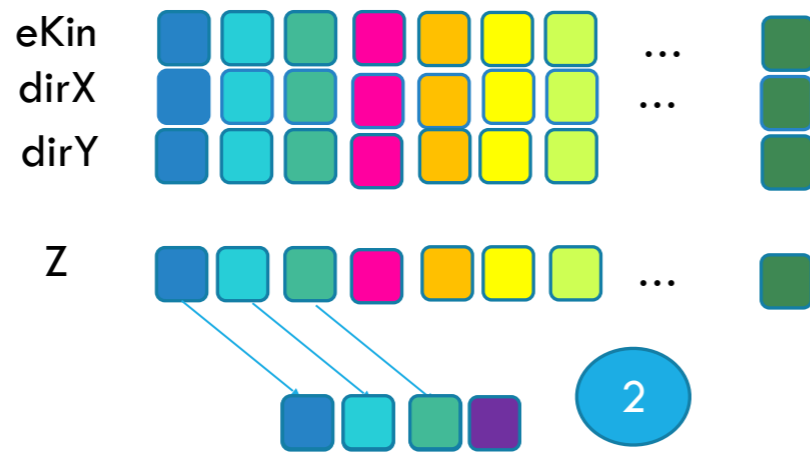


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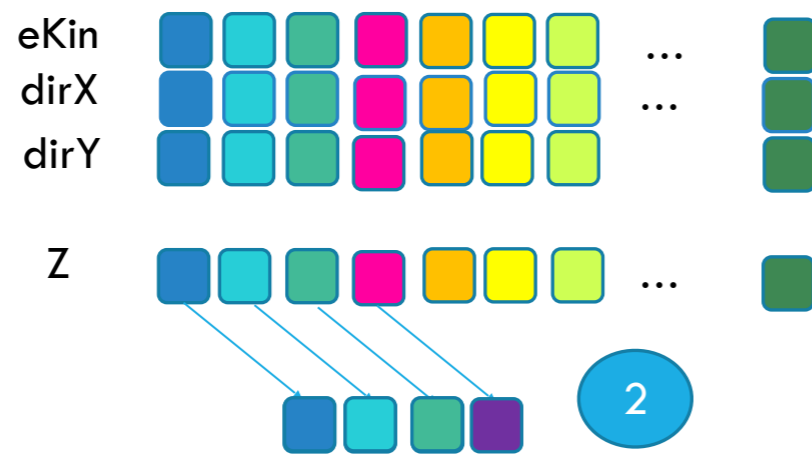


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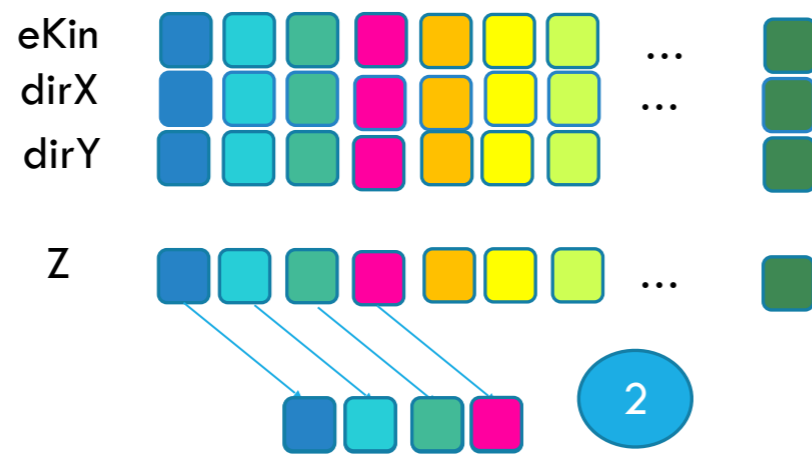
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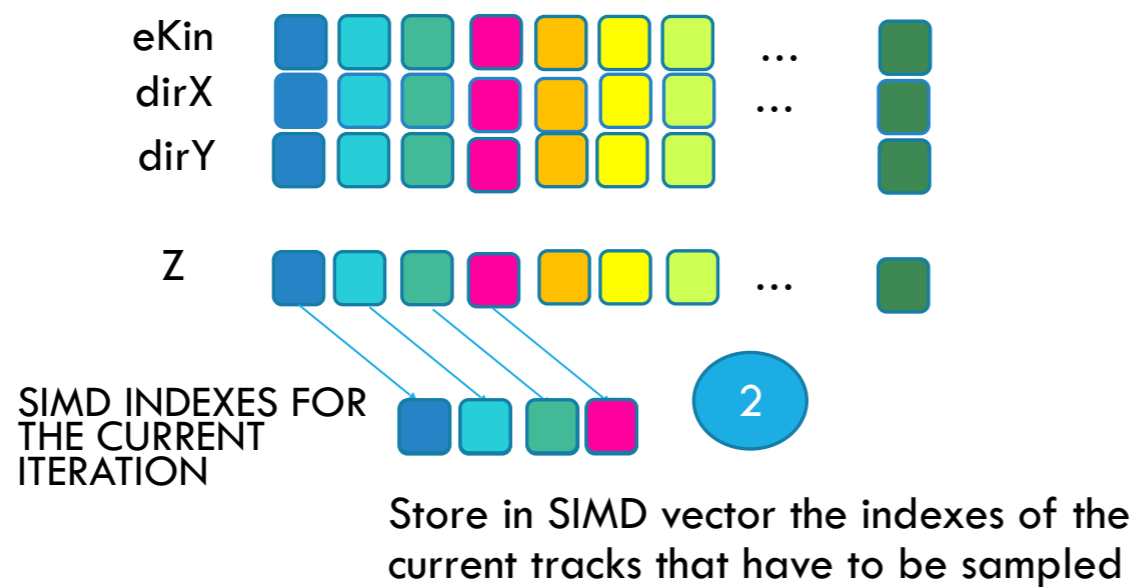


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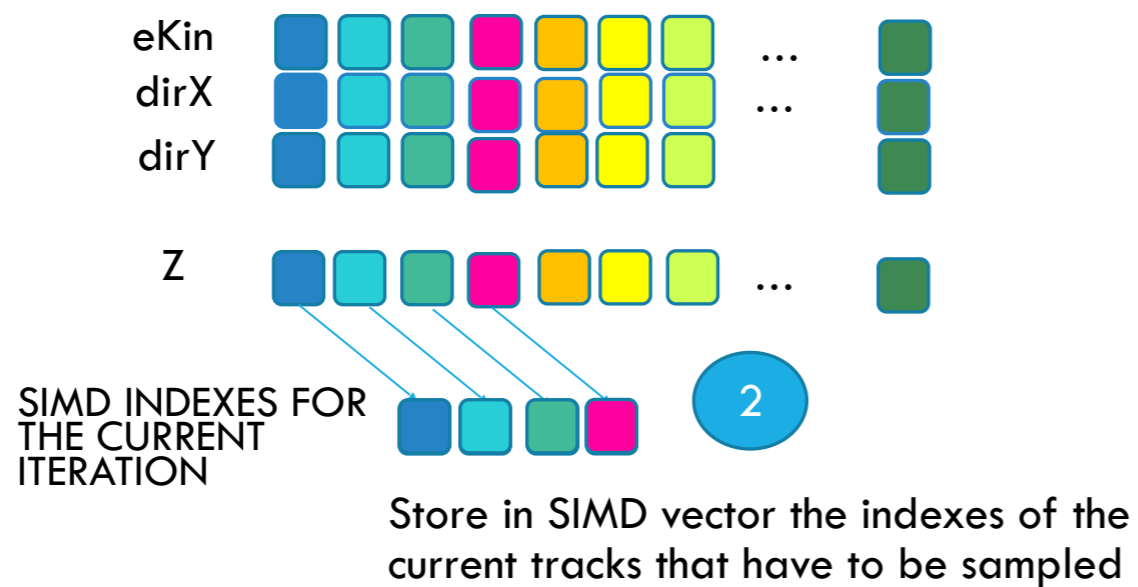
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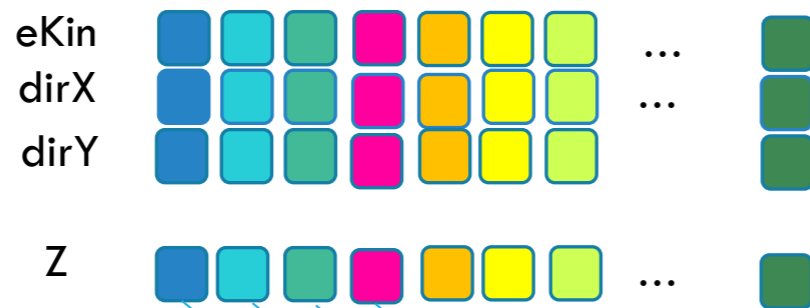


- 3 Gather values from array using this indexes

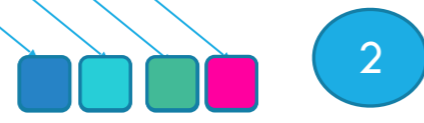


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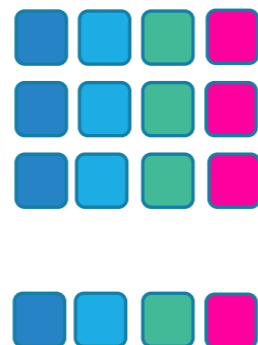


SIMD INDEXES FOR THE CURRENT ITERATION



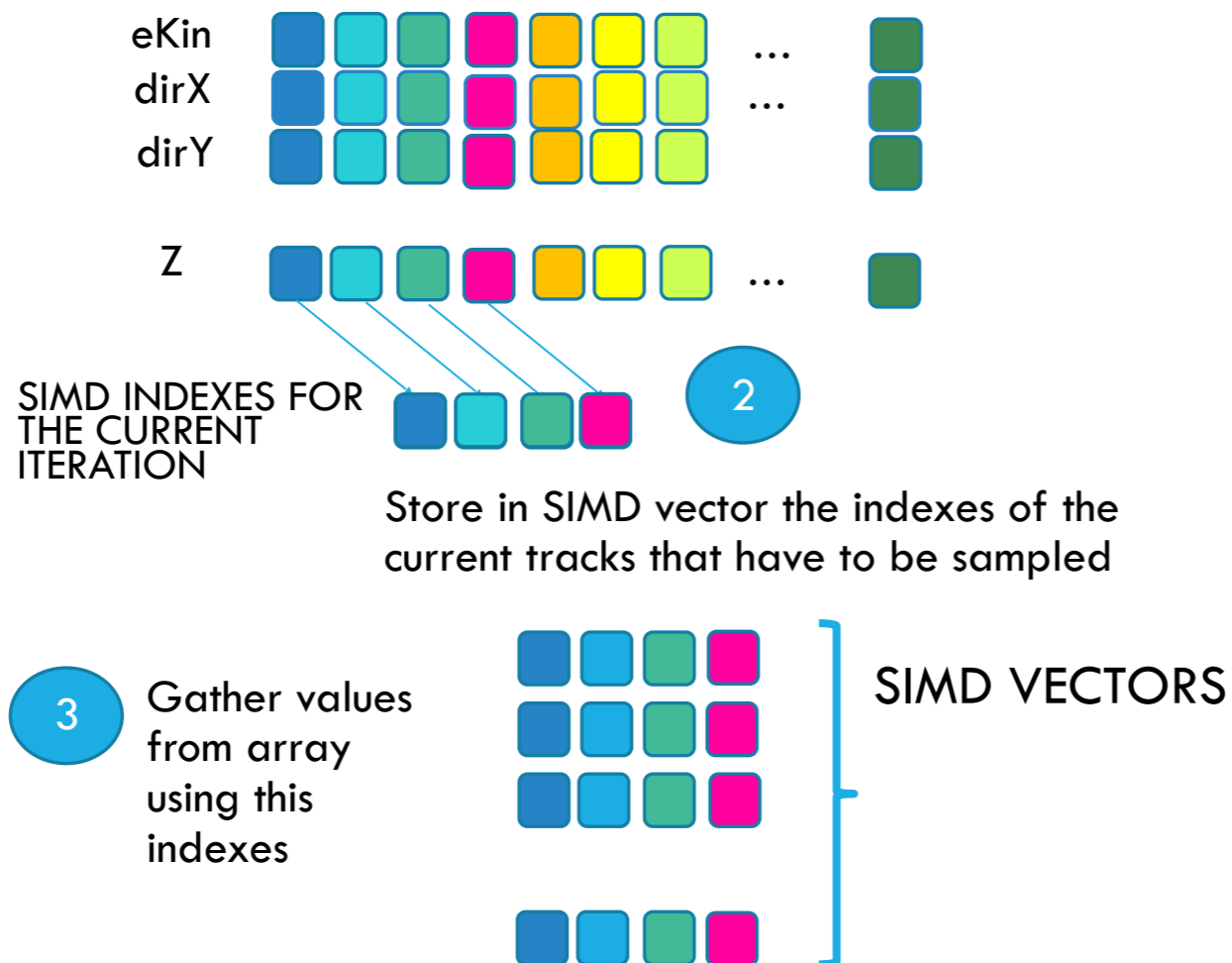
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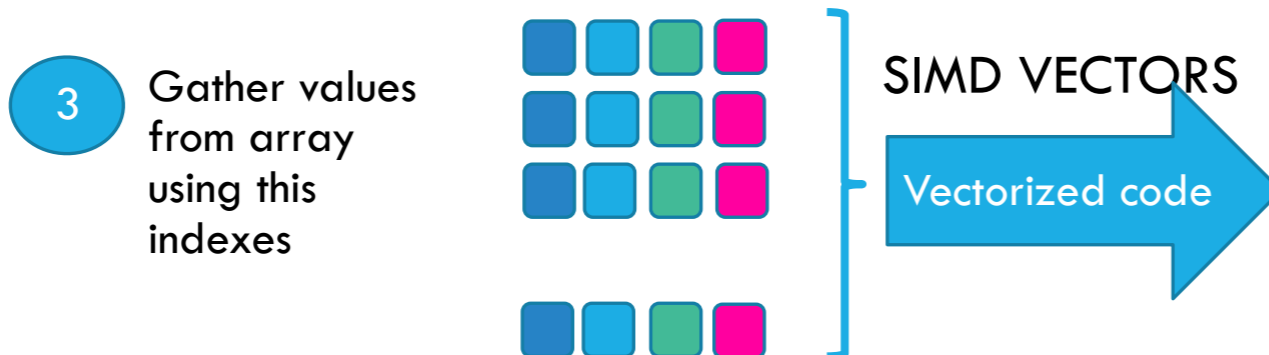
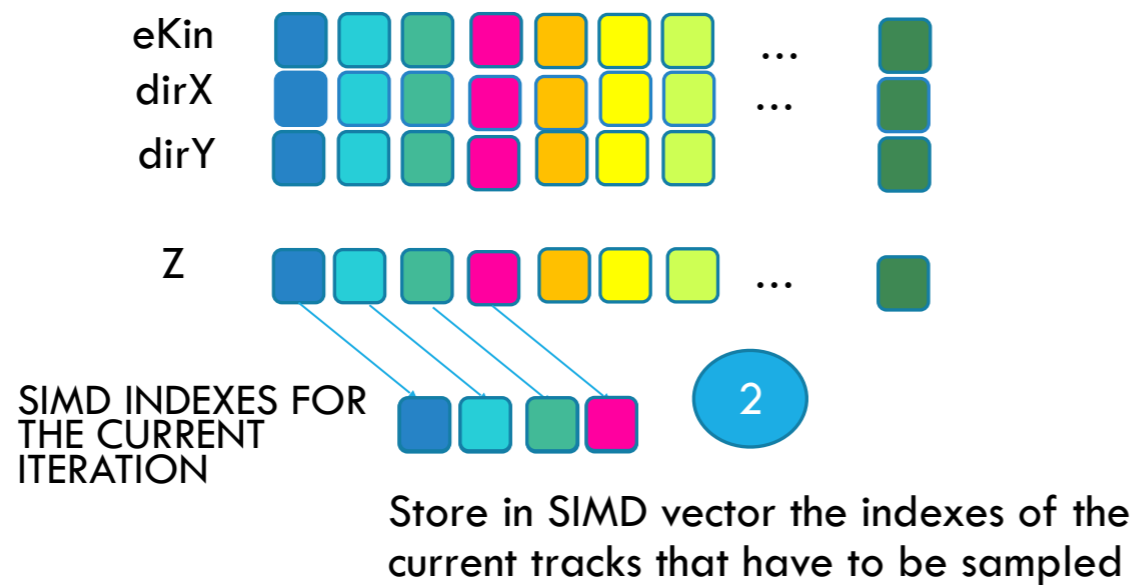
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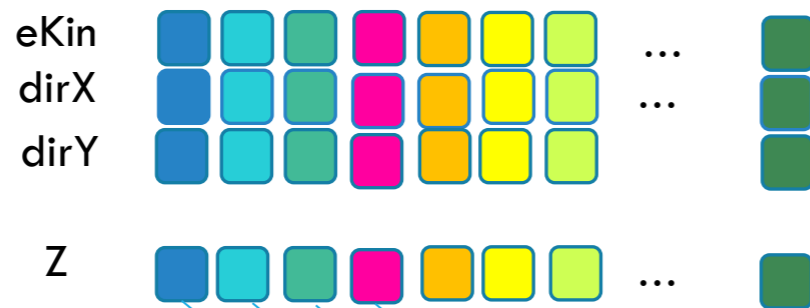
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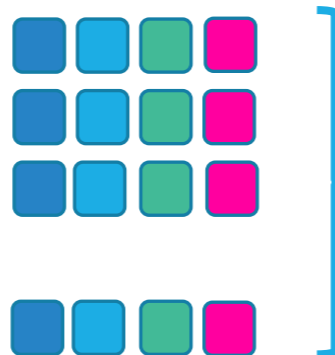
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SIMD INDEXES FOR THE CURRENT ITERATION

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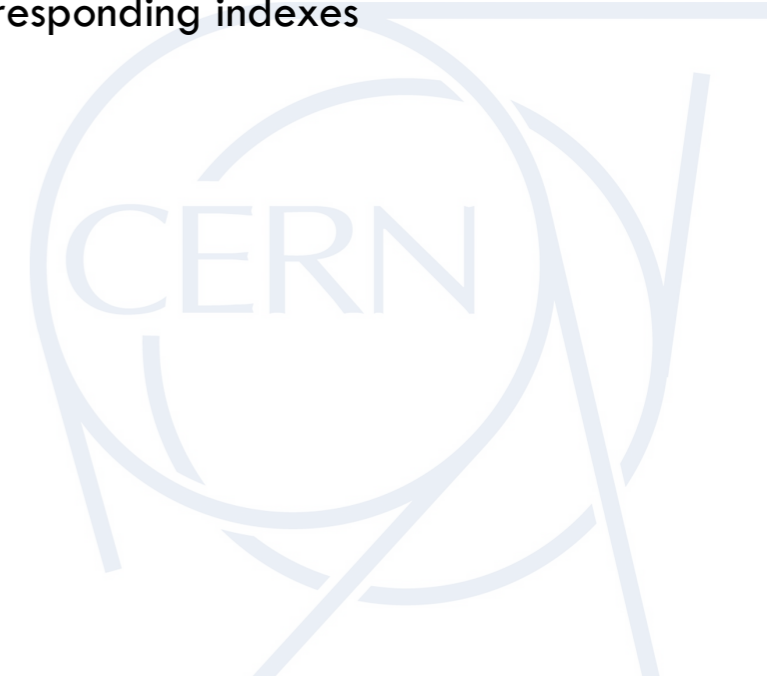
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SIMD VECTORS

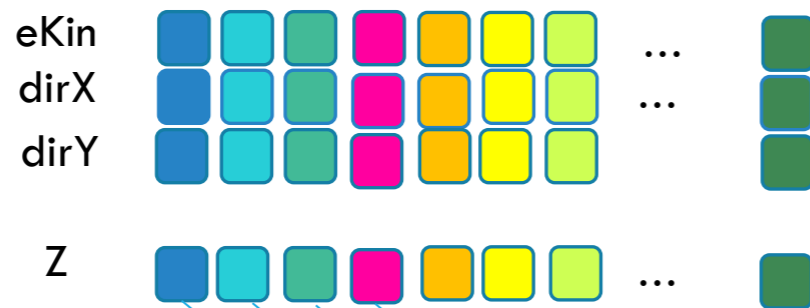
Vectorized code

- 4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes



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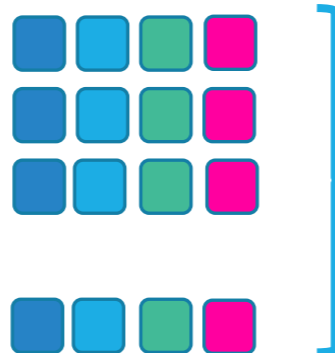
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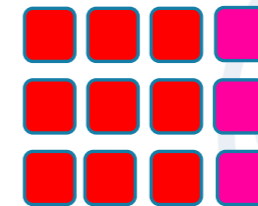
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SIMD VECTORS

Vectorized code

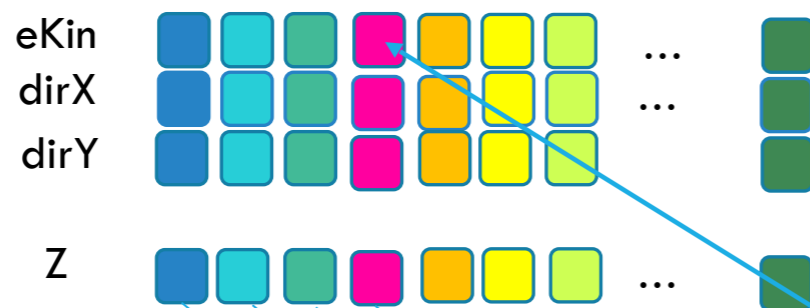
- 4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes





# VECTORIZATION OF REJECTION SAMPLING

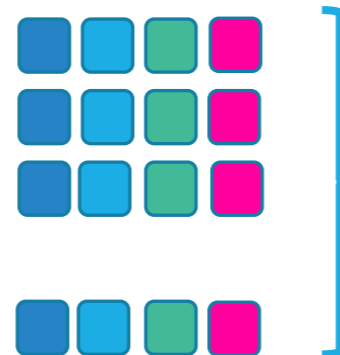
- 1 Prepare values that are needed for sampling, in form of arrays



SIMD INDEXES FOR THE CURRENT ITERATION

2 Store in SIMD vector the indexes of the current tracks that have to be sampled

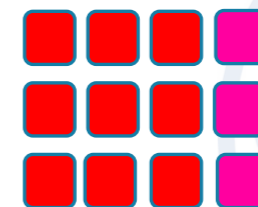
- 3 Gather values from array using this indexes



SIMD VECTORS

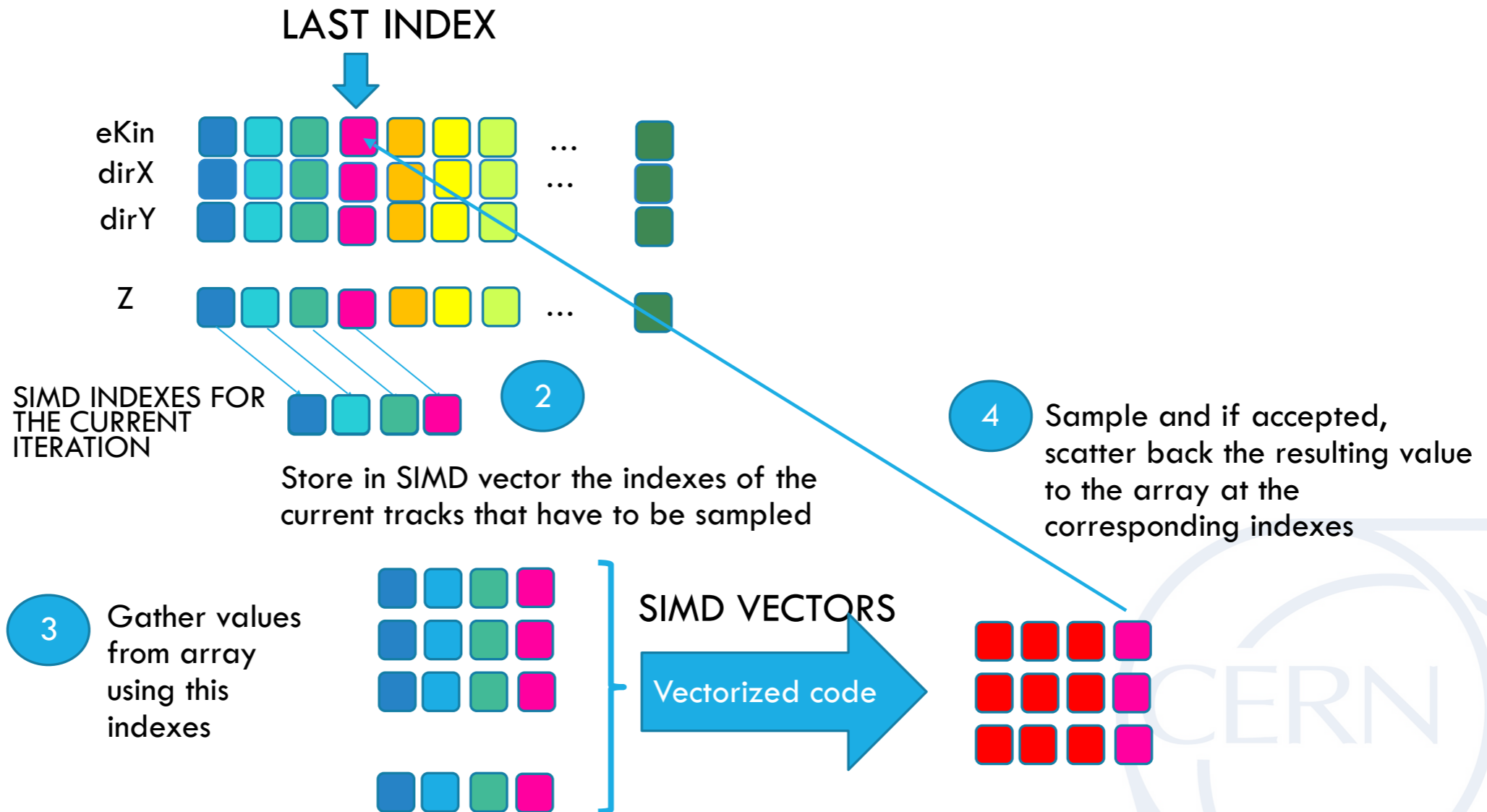
Vectorized code

- 4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes



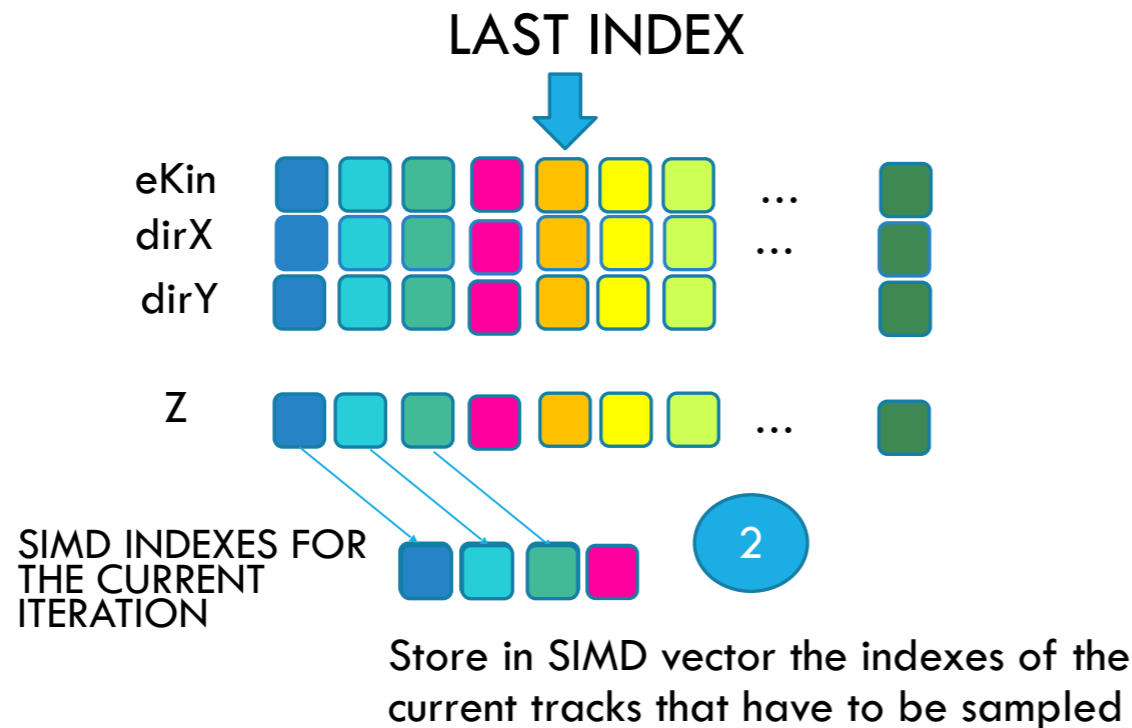
# VECTORIZATION OF REJECTION SAMPLING

1 Prepare values that are needed for sampling, in form of arrays

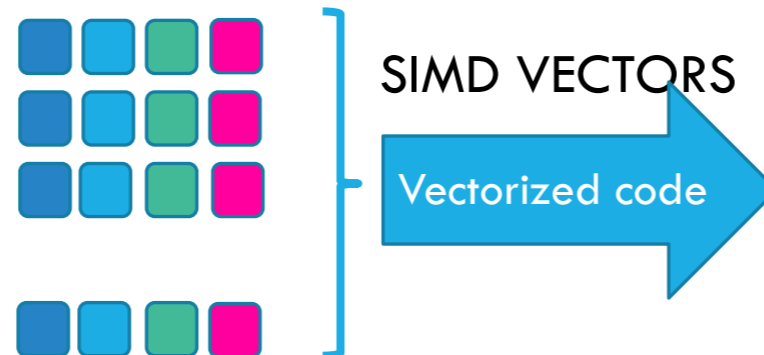


# VECTORIZATION OF REJECTION SAMPLING

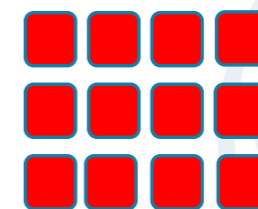
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes

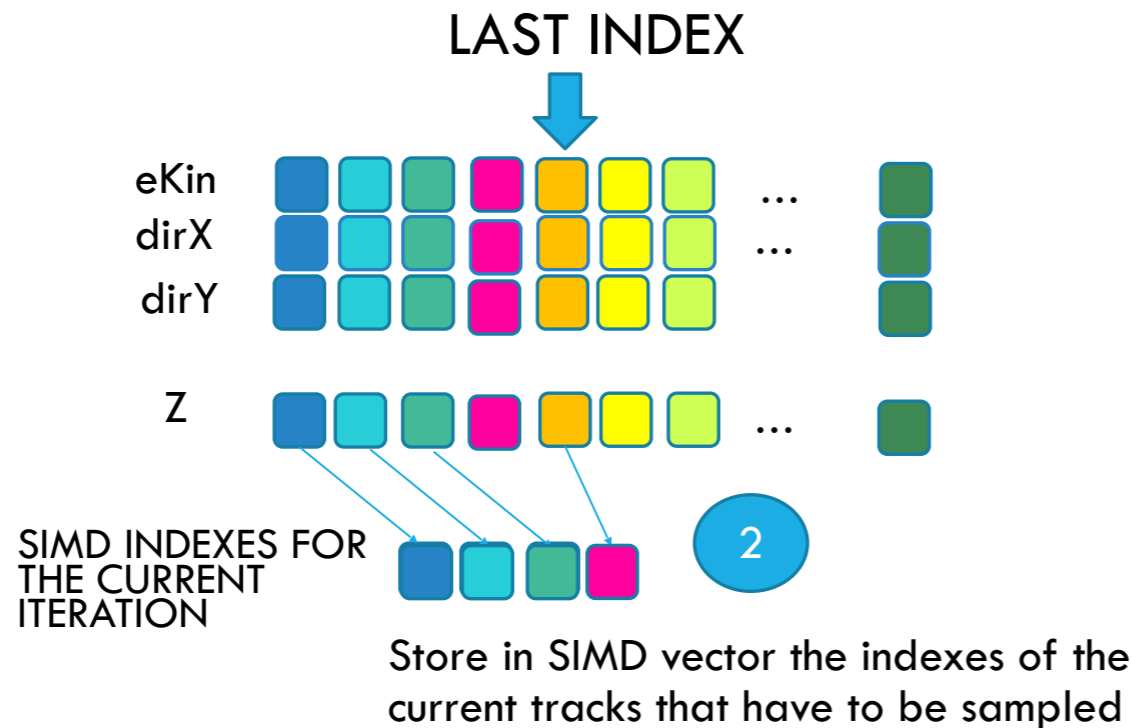


4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes

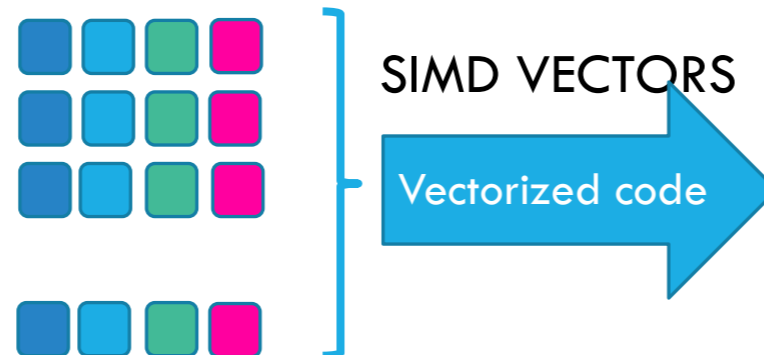


# VECTORIZATION OF REJECTION SAMPLING

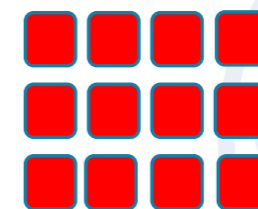
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes

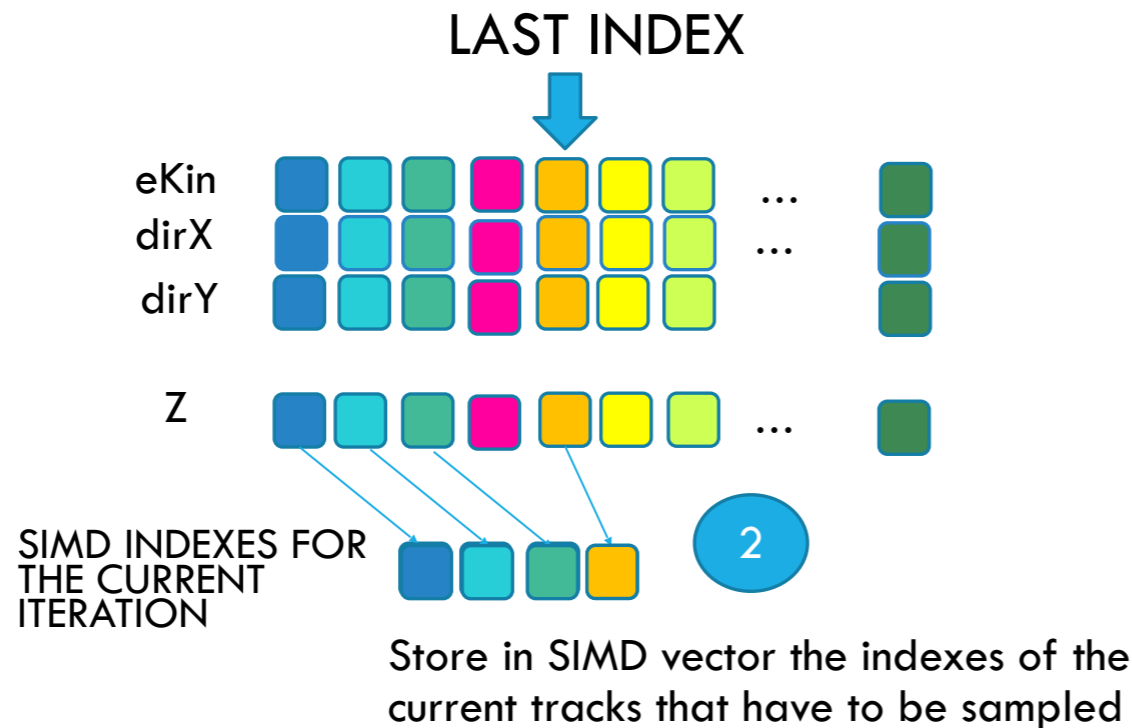


4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes

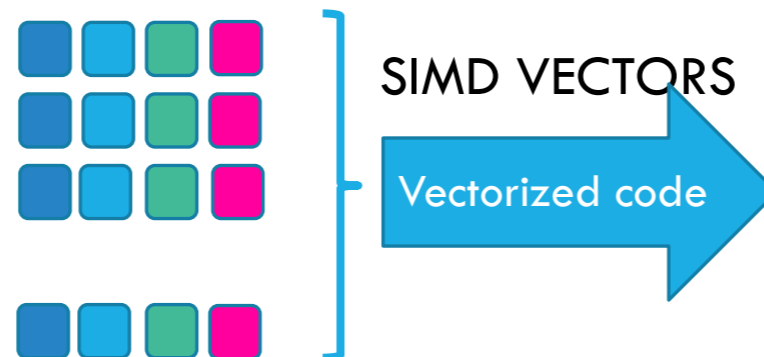


# VECTORIZATION OF REJECTION SAMPLING

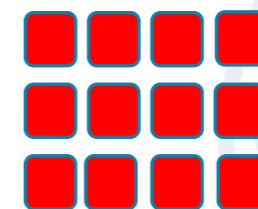
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes

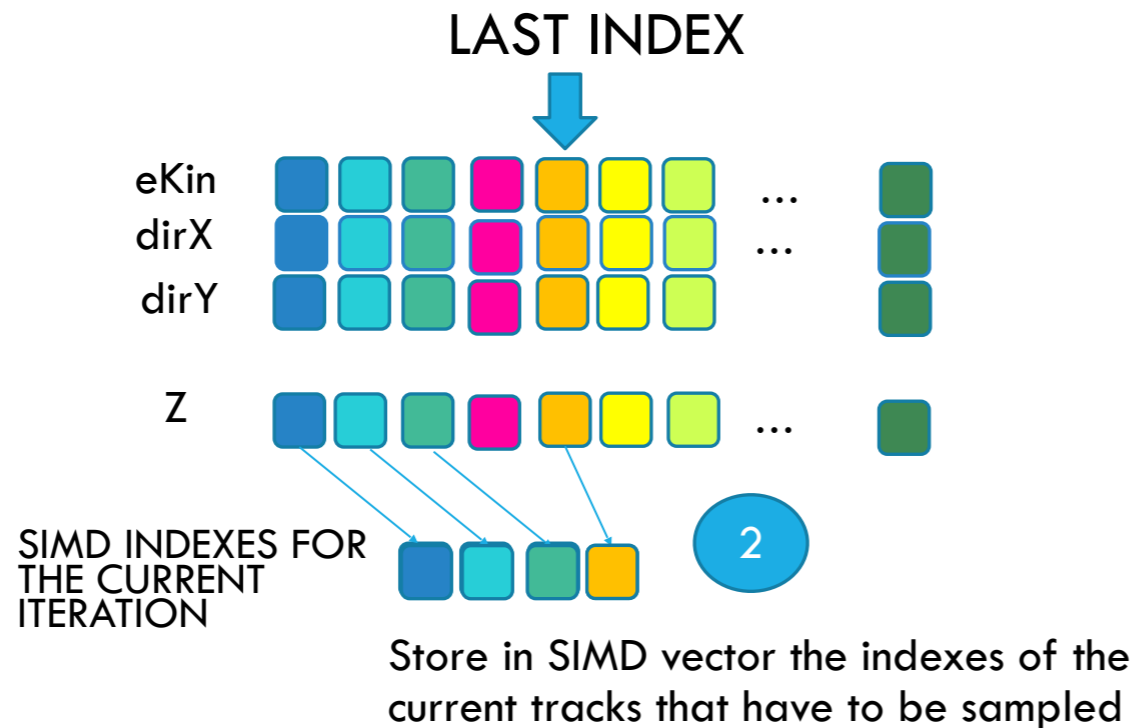


4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes

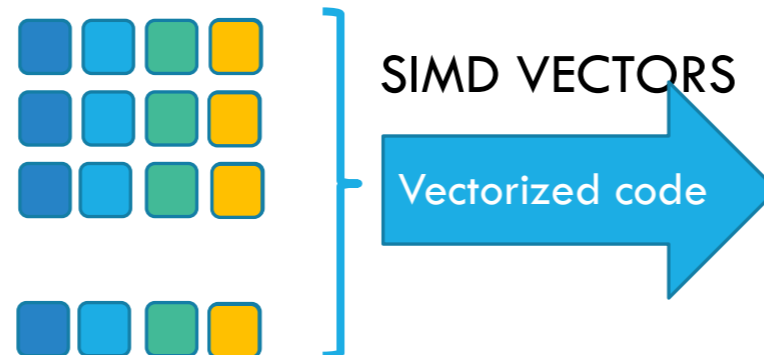


# VECTORIZATION OF REJECTION SAMPLING

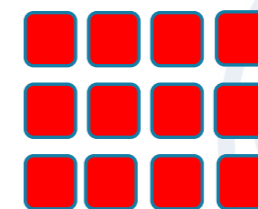
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes

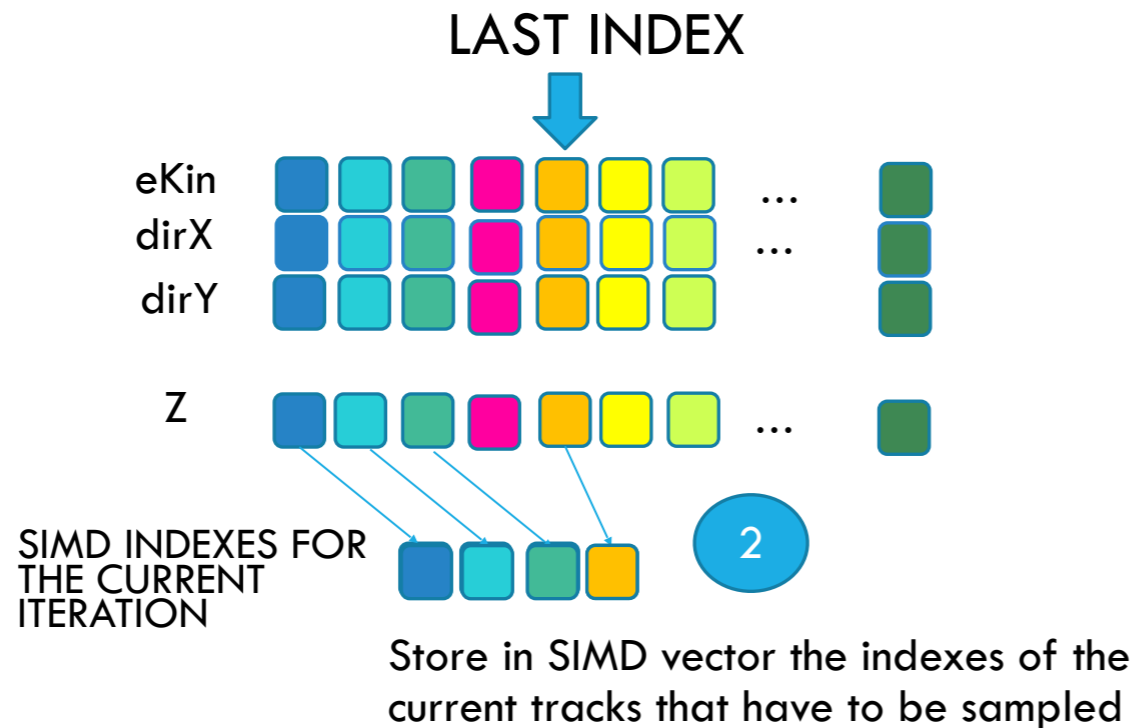


4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes

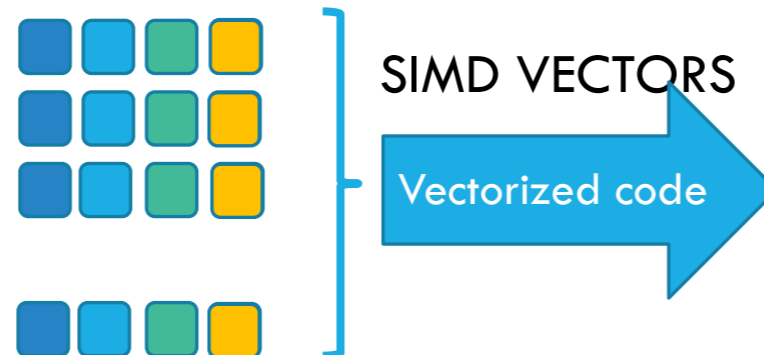


# VECTORIZATION OF REJECTION SAMPLING

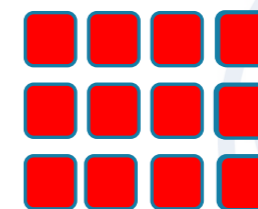
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes

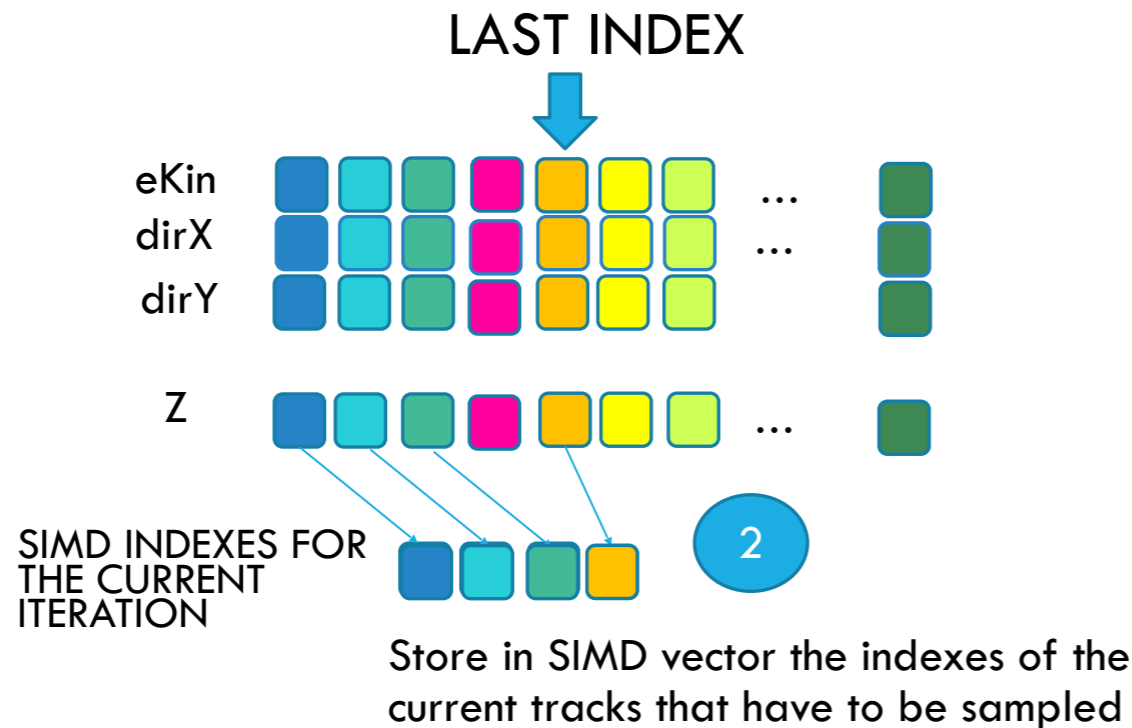


4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes

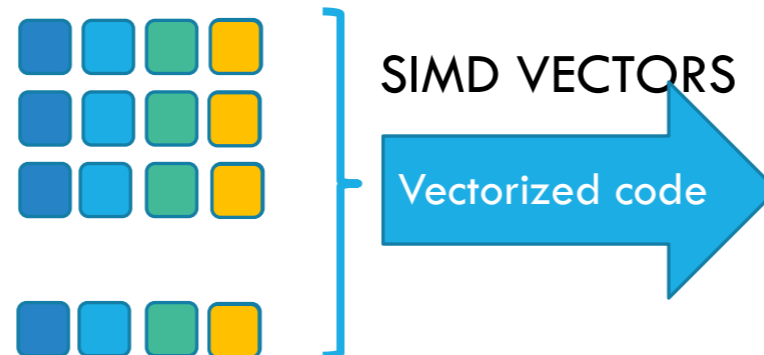


# VECTORIZATION OF REJECTION SAMPLING

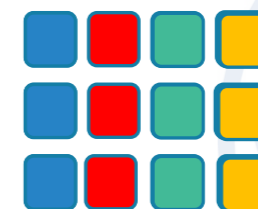
1 Prepare values that are needed for sampling, in form of arrays



3 Gather values from array using this indexes



4 Sample and if accepted, scatter back the resulting value to the array at the corresponding indexes





# VECTORIZATION OF REJECTION SAMPLING

1 Prepare values that are needed for sampling, in form of arrays

