

Assembling, lowering and moving around 14000 tons





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CMS at LHC versus CLIC-SiD



Both detectors are solenoids

Have **comparable** diameter and fields

Design in **slices** for opening and maintenance

Airpads for horizontal x and y movement

The CMS plug could serve as example for a CLIC platform



Why assembly at the surface?



Some pictures instead of arguments



Why assembly at the surface 1







Why assembly at the surface 2







LC meeting on platforms

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Why assembly at the surface 3







.....l see you understand

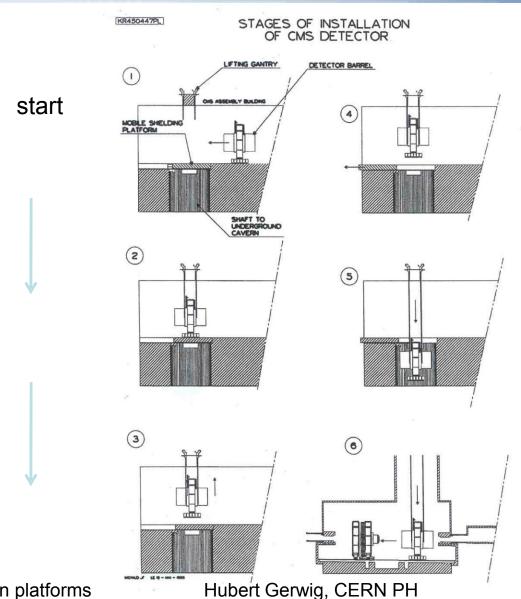






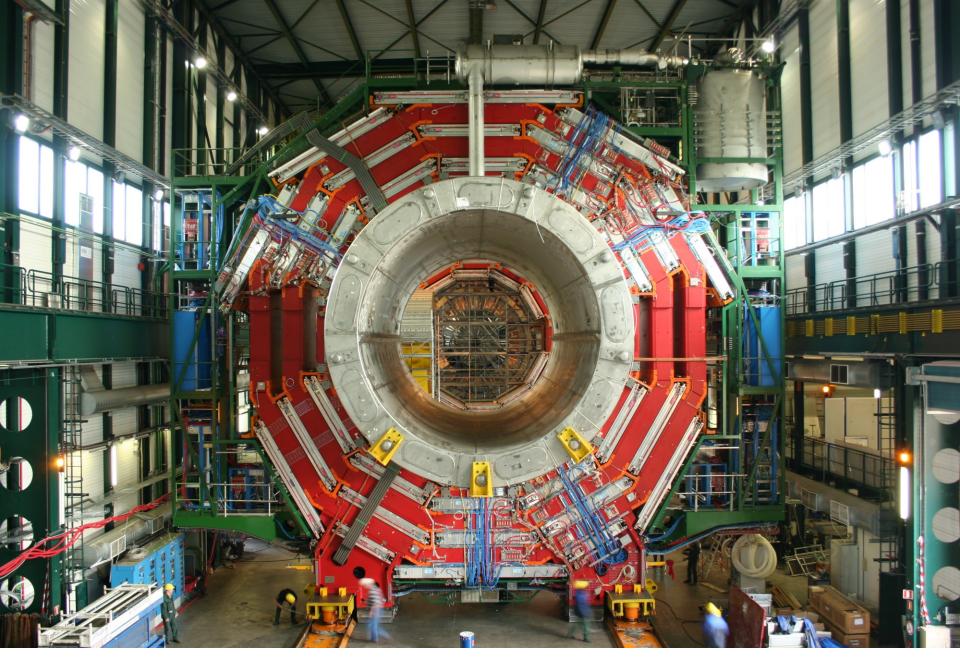
Lowering principle





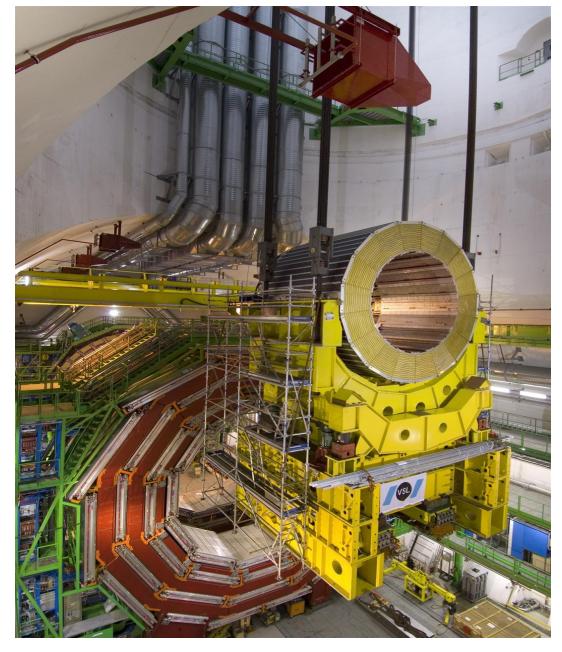
LC meeting on platforms

Fig. 26.15.: Lifting scenario for the central barrel ring YB0, using the shielding plug closing the main access shaft PX56.

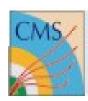


Hadronic Calorimeter arriving in the cavern

Some 700 tonnes



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Gantry Installation





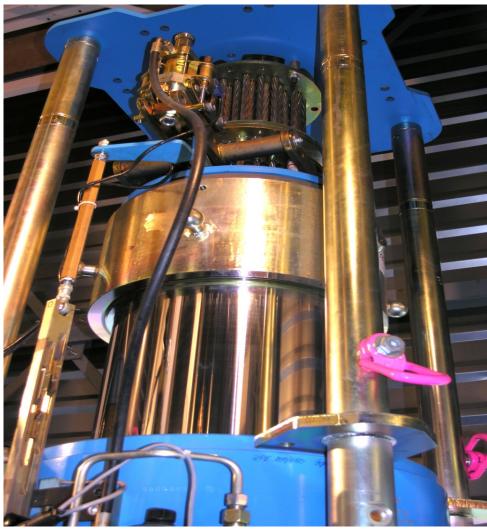




Strand coils and hydraulic jack









Central Barrel + coil = 2000 tons

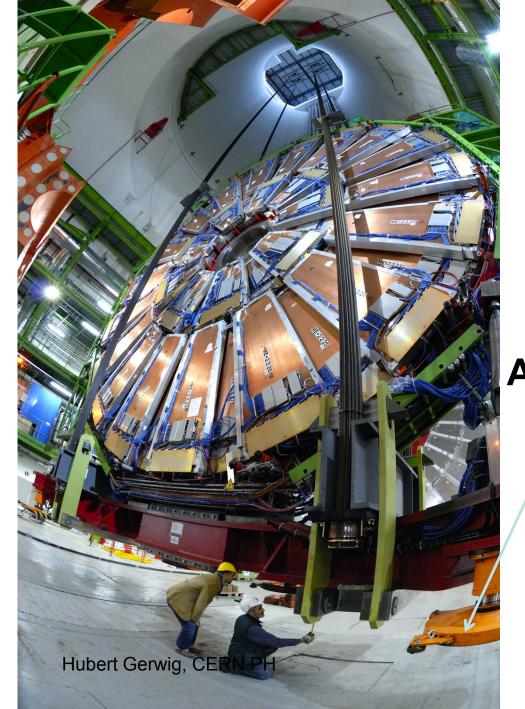




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End-cap YE+2 880 tons

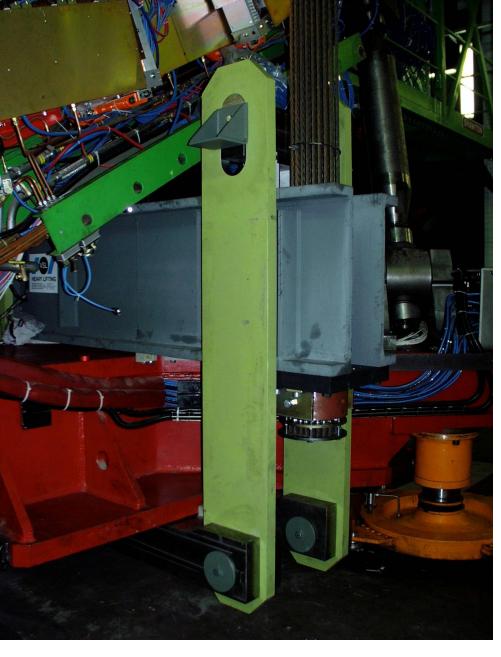


Airpad

End-cap YE+1
1430 tonnes









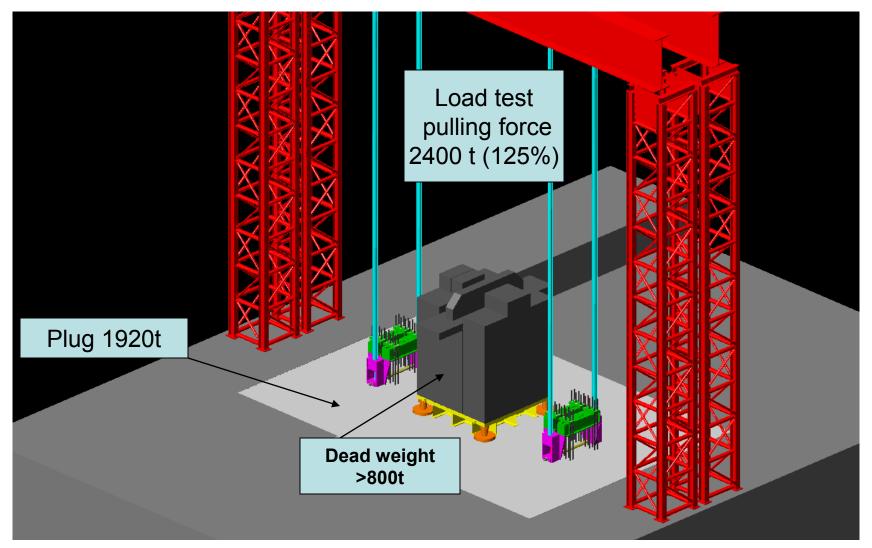
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Gantry load test using the plug

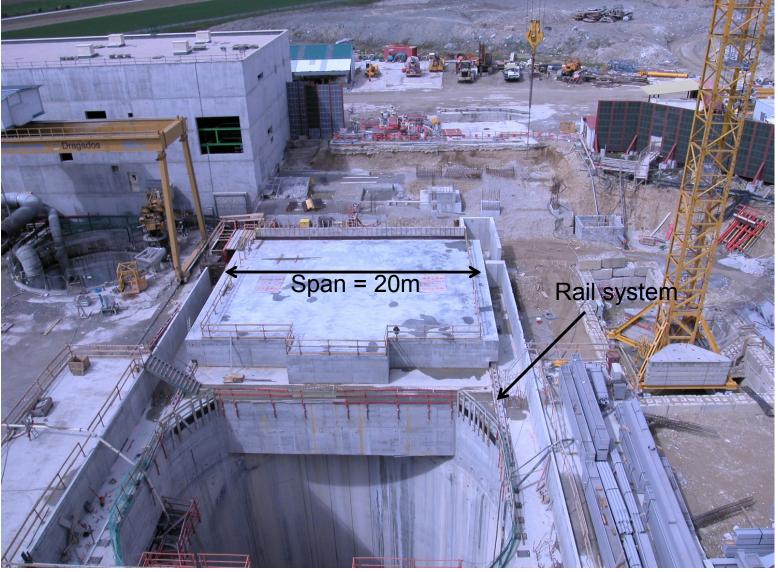






Plug manufacture on surface





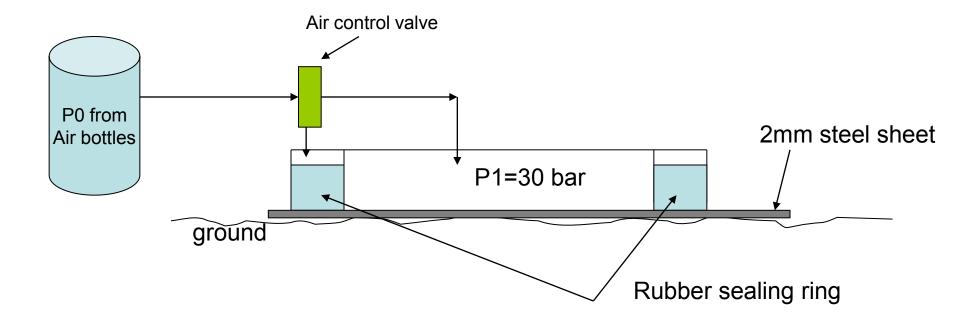


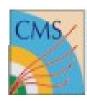
About the airpads



CMS is built in a surface hall and moves on air pads

These air pads are not really comparable to classical air cussions as they have nearly no air losses due to a sealing ring





Air pad photo





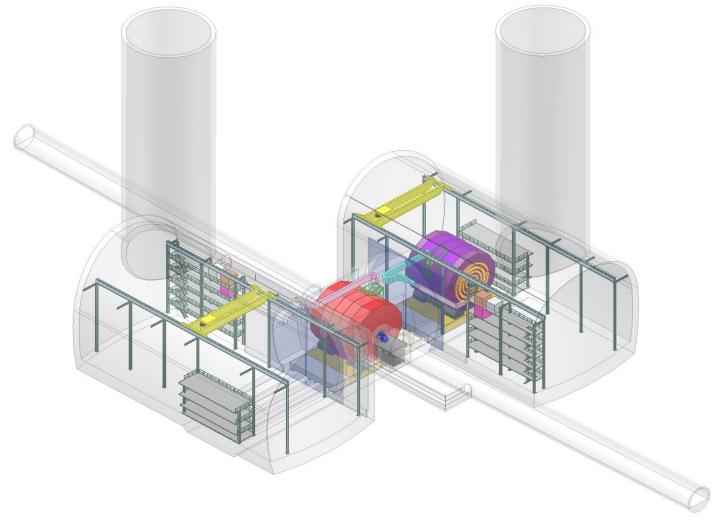
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CLIC cavern at a deep site

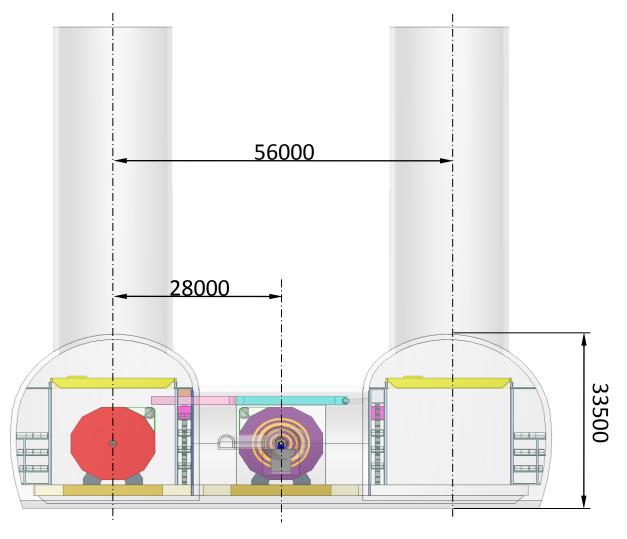






CLIC cavern cut at IP

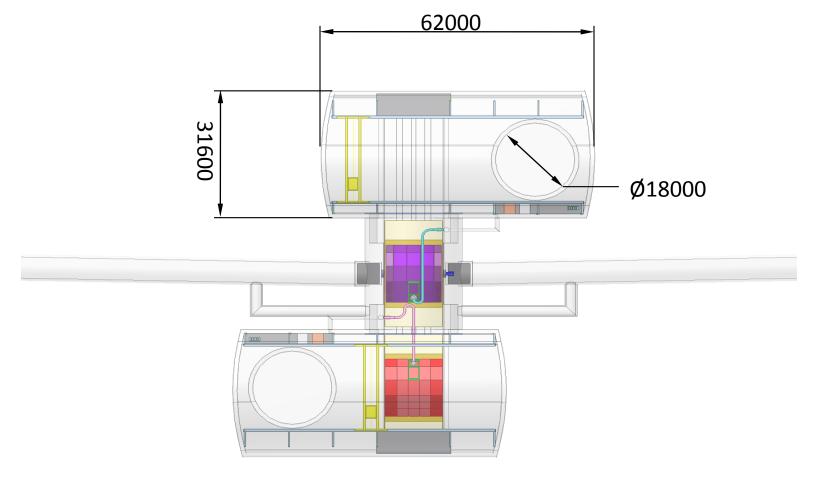






CLIC cavern top view







Last slide



- A CLIC detector may weigh 12000 tonnes
- Its platform 2000 tonnes
- Friction factor of an airpad is <1%
- Seen my experience on CMS there is no problem to move the whole experiment on a platform BUT it has to be engineered
- And even with one experiment only you have to bring it on IP (via a platform)!