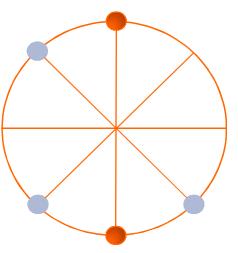
Cogging
Semi-Fine Adjust without collisions?
Fine Adjust
When?

# **COGGING MEETING**

### **COGGING WITH BPTX - 1**

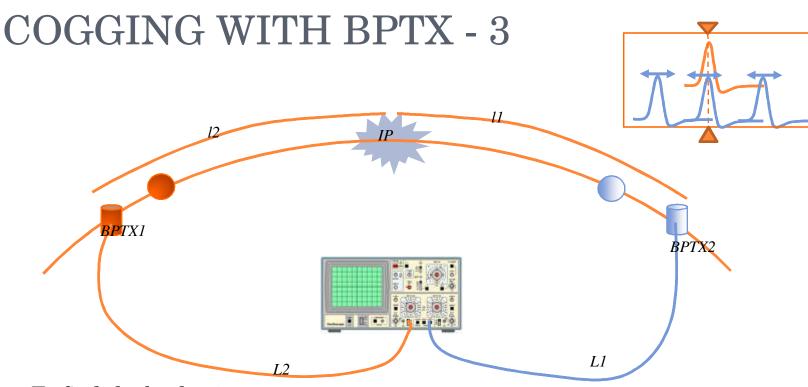


- Cogging = find the phase of Frev to get 1x1 pilot bunches in buckets1
- By definition, buckets1 collide in P1 and P5
- Could we do it with other buckets?
- Buckets resolution = 1/RFfreq = 2.5ns (74.95cm between 2 consecutive bunches)
- To be done @ 450GeV
- No collisions required
- Can we keep the Frev1 constant and only move Frev2 (we set arbitrarily the bucket 1 of beam1 and we look for bucket 1 of beam2)?
- Remember: 30cm=1ns

2

#### **COGGING WITH BPTX - 2** BPTX1 BPTX1 BPTX2 BPTX2 ATLAS & CMS (scope based) LHCb & ALICE(VME board based) 0 ....

- Trigger on BPTX1
- BPTX of ATLAS and CMS should see (ideally) a zero time difference (T\_beam1-T\_beam2) between the two BPTXs
- ALICE and LHCb should see a time difference of 66693ns and 22231+3\*25 ns respectively (using 88.924450us Frev period) => is it possible to compensate these delays in order to keep the nominal resolution of BPTXs?



- To find the bucket1...
- Delay between bunch1 and bunch2 must be minimal after compensation of
  - The theoretical expected delay between bunches
  - the real distance of each BPTX from IP (\*c)
  - the distance between each BPTX and the measurement device (\*signal speed in copper= 20cm/ns=2c/3)
- To which precision do we know l1-l2 and L1-L2?
- Minimal absolute resolution required for BPTX is +-1.25ns (including uncertainties in 11, 12, L1 and L2)

4

# **COGGING WITH BPTX - 4**

- How do we exchange data there? Phone? DIP?
- Minimum configuration: ATLAS and CMS have both to be there (in case of trouble with one of the 2 systems). Would be great to have LHCb and ALICE too (they use a different system).
- Each bucket adjustment will require a full cycle with a resync and an injection.
- How many iterations will be expected?
- How long will it take?

# SEMI-FINE ADJUSTMENTS WITHOUT COLLISIONS?

- Could we proceed to semi-fine adjustments without collisions? (only using BPTX)
  - Yes once the fine adjustment will have been done and the BPTX calibrated...
  - But what about doing it BEFORE?
- Of course, depends on l1-l2 and L1-L2 precision
- Goal: achieve a crossing point adjustement to within about 5 cm of the nominal.
- Detectors acceptance is designed for seeing interaction vertices from about -10 cm to +10cm

## FINE ADJUSTMENT -1

- During collisions
- Can be done continuously without resync
- Which scheme?
  - 2x2 @ 5<sup>e</sup>10
  - B1: 1 + 892
  - B2: 1 + 1786
  - All IPs
  - Collisions Rate >100Hz
- Precision on the RF side : 1/128deg of the 400 RF = 20ps (0.6cm)
- One fine adjust to be done for each energy level?
  - One at 450GeV
  - One at 1.1TeV (phase will slightly vary between injection and high energy if we keep the adjustments values of the injection)
  - One at 3.5TeV
  - ....?

## FINE ADJUSTMENT -2

- Which sub-detectors are going to give the feedback?
  - If it is the trackers, will they take data? Will we be on STABLE BEAM?
  - What is the delay to get accurate feedback on the real rate?
  - 1 Bunch length = 33.6cm (1.12ns) => *is this value still true?*
  - 1 σ rms = 0.202ns=6.7cm => *and this one*?
  - Convolution of 2 bunch profiles (including RF phase jitter) => 95% of distribution within 18cm (0.6ns) => and this one?
  - What resolution could we hope to get with the feedback from experiments?
  - What is an acceptable adjustment value?
  - How do we exchange feedback? DIP?
  - How long will it take to get acceptable adjustment (5cm = 160ps)?
- With this adjustments, the BPTX will be calibrated => what will be the optimal resolution of BPTXs after calibration?

	V	WHEN WILL IT HAPPEN?													
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	Oct Nov Isolde Dec													BLM checks, energy tracking, LBDS BI BLM checks, energy tracking, LBDS BI	BARON
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Mo Tu We Th Fr Sa Su		28	5 HWC			6 2		et e	BEAM COMMISSIONING AT 450 GeV	450 GeV 450 GeV Collisions	RAMP TO 1.1 TeV	7 Collisions	21 Xmas Day	Mike, LPC, 26 <sup>th</sup> of October	9

Technical Stop Beam commissioning SPS et al physics