

MATHEMATICAL MODELING OF REAL WORLD PROCESSES

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Barbara Wagner (WIAS) CERN Training Lecture 2019 14/15 March 2019

¹ Scaling

2 Interface formation

³ Matched asymptotic expansions

⁴ Multi-scale dynamics

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W.I.S.E. NASA,

STARS - AMEBEA - LIQUID UNDER THERMAL GRADIENT

- Single to multi-armed spirals
- Forces that govern the motion of the indivdual stars or amebea are very different !!
- Presently no one can compute millions/billions of 3D paths of interacting stars or amebea, yet
	- o on a large scale the millions of individuals behave as if their mass were continuously distributed
	- forming similar large scale structures
- Mathematical model that is able to describe these large scale patterns will have to be able to reduce the description to the essential most dominant forces creating these structures and their dynamics
- Power of Applied Mathematics is to be able model these (physically unrelated) structures AND analyse them with common mathematical tools
- Derivation of a averaged continuum model, analysis, numerical solution
- Important in modeling: Know the errors
- Dimensional Analysis and Scaling

- \bullet 1945 first atomic explosion in New Mexico: classified¹
- **1947** movie of explosion appeared
- 1950 G. I Taylor (University of Cambridge) published article on energy (still classified!!!) of explosion.
- What effects might be expected during nuclear fission?

To answer this question:

Calculate motion and pressure of ambient gas after explosion What is known? What can be assumed?

- After short, intense initial period: Shock appears
- Governing equations inside shock wave
- Assume: viscous effects are negligible (at this early stage), spherical symmtry

Conservation of mass *∂tρ* +

Conservation of momentum *∂tu* + *u∂ru* +

$$
\overline{}
$$

Conservation of energy
$$
\partial_t \left(\frac{p}{q^2} \right)
$$

Boundary Conditions

$$
\rho_s(u_s - D) = -\rho_0 D \n\rho_s(u_s - D)^2 + p_s = p_o + \rho_0 D^2 \n\rho_s(u_s - D) \left(\frac{\gamma}{\gamma - 1} \frac{p_s}{\rho_s} + \frac{(u_s - D)^2}{2} \right) = -\rho_0 D \left(\frac{\gamma}{\gamma - 1} \frac{p_0}{\rho_0} + \frac{D^2}{2} \right)
$$

1

ρ γ

 $\frac{1}{r^2}\partial_r\left(\rho r^2 u\right)=0$

1 $\frac{1}{\rho}\partial_r p = 0$

ρ^{$γ$}

 $= 0$

 $\bigg) + u \partial_r \left(\frac{p}{p} \right)$

Initial Conditions

$$
\rho(r,0) = \rho_0(r), \quad p(r,0) = p_0(r), \quad u(r,0) = 0 \quad r \ge r_0
$$

$$
\rho(r,0) = \rho_i(r), \quad p(r,0) = p_i(r), \quad u(r,0) = u_i(r) \quad r < r_0
$$

$$
E = 4\pi \int_0^{r_0} \rho_i \left(\frac{u_i^2}{2} + \frac{1}{\gamma - 1} \frac{p_i}{\rho_i}\right) r^2 \, dr
$$

- (i) Location of shock r_s depends on: $E, \rho_0, t, t_0, p_0, \gamma$
- (ii) Assume: energy is suddenly released in infinitely concentrated form

⇒ point source i.e. *r*⁰ *≪ r^s*

Assume: pressure of moving gas $p_s \gg p_0 \Rightarrow$ neglect terms with p_0 at shock

Units

\n
$$
[E] = \frac{gcm^2}{s^2}, \, [\rho_0] = \frac{g}{cm^3}, \, [t] = s, \, [r_0] = cm, \, [p_0] = \frac{g}{cm^2}
$$
\n(i) & (ii) \Rightarrow neglect r_0, p_0

- \Rightarrow *S* = $\left(\frac{Et^2}{\rho_0}\right)$ $\int^{1/5}$ \Leftarrow dimension of length $⇒ I := \frac{r_s}{S} = F(S, ρ_0, t, γ)$ dimensionless !
- *⇒* depends only on constant *γ*
- $⇒$ Taylor's Scaling Law $r_s = C(γ) \left(\frac{Et^2}{ρ_0}\right)$ \setminus ^{1/5}
- \Rightarrow $\frac{5}{2}$ log₁₀ $r_s = \frac{5}{2}$ log₁₀ $C + \frac{1}{2}$ log₁₀ $\left(\frac{E}{\rho_0}\right)$ $\int +\log_{10} t \Rightarrow E$

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Assumptions

(i) A quantity *u* to be determined in terms of measurable quantities $\{w_1, ..., w_n\}$:

$$
u = f(w_1, \ldots, w_n) \tag{1}
$$

(iii) The dimension of a quantity *z* is a product of powers of the fundamental dimensions

$$
[z] = L_1^{\alpha_1} L_2^{\alpha_2} \cdots L_m^{\alpha_m} \quad \alpha_i \in \mathbb{R}
$$

Conclusions

(i) (1) can be expressed in terms of dim'less quantities.

(ii) *{u, w*1*, ..., wn}* involve *m* fundamental dimensions *L*1*, ..., L^m*

(ii)
$$
b_i = \begin{bmatrix} b_{1i} \\ \vdots \\ b_{mi} \end{bmatrix}
$$
 dimension of w_i , $B = \begin{bmatrix} b_{11} & \dots & b_{1n} \\ \vdots & & \vdots \\ b_{m1} & \dots & b_{mn} \end{bmatrix}$ dimension of problem.
Number of dim'less quantities is $k + 1 = n + 1 - r(B)$, where $r(B) =$ rank of B.

Exactly k of these depend on $\{w_1, ..., w_n\}$

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(iii) Let x_i , $i = 1, ...k$ be $k = n - r(B)$ linearly independent solutions x of $Bx = 0$. Let *a* be the dimension vector of *u* and *y* a solution of $By = -a$. Then (1) reduces to $\pi = g(\pi_1, ..., \pi_k),$ (2)

 $\pi = uw_1^{y_1} \cdots w_n^{y_n}$ and $\pi_i = uw_1^{x_{1i}} \cdots w_n^{x_{ni}}$

where

are dim'less quantities and (1) becomes

 $-\frac{1}{2}y_1 \cdots w_n^{-y_n} g(\pi_1, ..., \pi_k)$ (3)

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Homework !

- Let $u = R$ radius of shock wave, with $R = f(w_1, ..., w_4)$ and $w_1 = E$, $w_2 = t$, $w_3 = \rho_0$, $w_4 = p_0$
- Using fundamental dimensions, obtain dimension matrix

$$
B = \begin{bmatrix} 2 & 0 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ -2 & 1 & 0 & -2 \end{bmatrix}
$$

Apply Buckingham-Pi: $r(B) = 3 \Rightarrow k = n - r(B) = 4 - 3 = 1.$ Solution to $Bx = 0$ is $x_1 = -\frac{2}{5}x_4, \quad x_2 = \frac{6}{5}x_4, \quad x_3 = -\frac{3}{5}x_4$ where x_4 arbitrary (e.g. $x_4 = 1$) $⇒$ Dimensionless quantity: $π₁ = p₀($ $\frac{t^6}{π²}$ $E^2 \rho_0^3$ $\sqrt{\frac{1}{5}}$ Solution of $By = -a$ is $y = \frac{1}{5}$ 5 Γ \parallel *−*1 *−*2 1 0 T \parallel , dimension of R is $a =$ Γ $\overline{1}$ 1 0 0 1 \mathbf{I} *⇒* Dimensional Analysis: *R* = $(Et^2)^{1/5}$ $\left(\frac{\partial}{\partial \rho_0}\right)$ *g*(*π*₁)

Cahn-Hilliard equation
$$
\frac{\partial \phi}{\partial t} = \nabla \cdot \left(M \, \nabla \frac{\delta f}{\delta \phi} \right)
$$

Total free energy: Ginzburg-Landau free energy

$$
f[\phi,T]=\int_V F(\phi({\bf x}),T({\bf x}))+\frac{1}{2}\epsilon|\nabla \phi|^2\,d{\bf x}
$$

Bulk free energy:

$$
F = \phi(1 - \phi) + k_B T(\phi \ln \phi + (1 - \phi) \ln(1 - \phi))
$$

Simplest free energy, combining bulk contribution from a binary mixture and interfacial energy.

Mass conservation:
$$
\frac{\partial \phi}{\partial t} = -\nabla \cdot \mathbf{J}
$$

$$
\mathbf{J} = -M\nabla \cdot \mu \quad \text{with} \quad \mu = \frac{\delta f}{\delta \phi}
$$

$$
\frac{\partial u}{\partial t} = \Delta \mu \text{ in } \Omega = \Omega_+ \cup \Omega_-
$$

$$
\mu = F'(u) - \epsilon^2 \Delta u
$$

$$
n \cdot \nabla \mu = 0, \quad n \cdot \nabla u = 0 \text{ on } \partial \Omega
$$

- \bullet Solutions reach near phase equilibrium after $O(1)$ time. Near phase equilibrium:
- solution has developed an interface between precipitates $Ω_+$, $Ω_−$ of width of $O(ε)$
- approaching a sharp interfaces Γ*^k* as *ϵ →* 0
- \bullet Dynamics of the precipitates evolves on the slow time-scale $\tau = \varepsilon t$

$$
\Rightarrow \quad \epsilon \frac{\partial u}{\partial \tau} = \Delta \, \mu
$$

Analysis *⇒* Matched Asymptotic Expansions

Definitions

(i) Let $u(\mathbf{x}; \epsilon)$ and $v(\mathbf{x}; \epsilon)$ be functions defined in $D \subset \mathbb{R}^n$ and $I: 0 \leq \epsilon \leq \epsilon_0(\mathbf{x})$. Then

$$
u(\mathbf{x}; \epsilon) = O(v(\mathbf{x}; \epsilon)), \text{ in D, as } \epsilon \to 0
$$

if for each $\mathbf{x} \in D$ there exists $k(\mathbf{x})$ and and *I* such that $|u| \leq k|v|$ for each $\epsilon \in I$.

$$
(\mathsf{ii})
$$

$$
u(\mathbf{x};\epsilon) = o(v(\mathbf{x};\epsilon)), \text{ in D, as } \epsilon \to 0
$$

if for each $\mathbf{x} \in D$ and given $\delta > 0$, there exists $I: 0 \leq \epsilon \leq \epsilon(\mathbf{x}, \delta)$ s.t. $|u| \leq \delta |v|$ for all $\epsilon \in I$ and denote this by $u \ll v$.

- (iii) An asymptotic sequence $\{\phi_n(\epsilon)\}\$, $n = 1, 2, ...$ is a sequence such that $\phi_{n+1}(\epsilon) = o(\phi_n(\epsilon))$ as $\epsilon \to 0$.
- $(i\vee)$ The series $\sum_{n=1}^{N} \phi_n(\epsilon) u_n(\mathbf{x})$ is called an asymptotic expansion of u w.r.t. $\{\phi_n(\epsilon)\}$ for $\epsilon\to 0$, if for each $M=1,...,N$

$$
u(\mathbf{x};\epsilon)-\sum_{n=1}^N\phi_n(\epsilon)u_n(\mathbf{x})=o(\phi_M),\quad\text{as}\quad \epsilon\to 0
$$

Example²: Consider erf(*x*) = $\frac{2}{\sqrt{\pi}} \int_0^x \exp(-t^2) dt$

exp(*−t* 2) is analytic in the entire complex plane C so that its Taylor series

$$
\mathrm{erf}(x) = \frac{2}{\pi} \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!} = \frac{2}{\sqrt{\pi}} \left(x - \frac{x^3}{3} + \frac{x^5}{10} - \frac{x^7}{42} + \frac{x^9}{216} - \frac{x^{11}}{1320} + \dotsb \right)
$$

converges with infinite radius of convergence.

Accuracy: For an accuracy of 10*−*⁵

upto $x = 2$ need 16 terms, upto $x = 3$ need 31 terms, upto $x = 5$ need 75 terms

For round-off error 10*−*⁷ : At *x* = 5 largest term is 6*.*6 *·* 10⁸ *⇒* WRONG answer!

ALTERNATIVE: Integrate by parts

$$
\operatorname{erf}(x) = 1 - \frac{2}{\sqrt{\pi}} \int_x^{\infty} \exp(-t^2) dt = 1 - \frac{\exp(-x^2)}{x\sqrt{\pi}} \left(1 - \frac{1}{2x^2} + \frac{1 \cdot 3}{(2x^2)^2} - \frac{1 \cdot 3 \cdot 5}{(2x^2)^3} + \dotsb \right)
$$

⇒ series diverges for all x and radius of convergence is zero! BUT:

x = 2*.*5 need 3 terms for accuracy of 10*−*⁵ , *x* = 3 need 2 terms for accuracy of 10*−*⁵

This series is an asymptotic expansion!

² Jon Chapman, Univ. of Oxford

A simple but instructive example:

$$
\epsilon y'' + 2y' + 2y = 0 \quad \text{in} \quad 0 < x < 1, \quad \epsilon \ll 1
$$
\n
$$
y(0) = 0 \quad y(1) = 1
$$

- As *ϵ →* 0 order of ODE decreases *⇒* one BC can't be satisfied *⇒* singular perturbation problem
- Region where *ϵ* = 0-problem does not have solution: Boundary layer
- Where is the boundary layer (BL)?
- Let BL be at $x = x_0$: $x = x_0 + \epsilon^{\alpha} \bar{x}$ or

Inner (BL) variable

$$
\bar{x} = \frac{x - x_0}{\epsilon^{\alpha}}, \quad \alpha > 0
$$

• Assume $x_0 = 0$, define $Y(\bar{x}; \epsilon) = y(x; \epsilon)$ Inner (BL) problem

$$
\epsilon^{1-2\alpha} \frac{d^2 Y}{d\bar{x}^2} + 2\epsilon^{-\alpha} \frac{dY}{d\bar{x}} + 2Y = 0, \quad 0 < \bar{x} < \infty, \quad Y(0) = 0
$$

Outer expansion Assume solution of outer problem has asymptotic expansion

$$
y(x; \epsilon) = y_0(x) + \epsilon y_1(x) + O(\epsilon^2)
$$

Note: iterative method Leading order problem (O(1)):

$$
y'_0 + y_0 = 0 \quad y_0(1) = 1
$$

$$
\Rightarrow y_0(x) = \exp(1-x)
$$

Inner expansion Assume

$$
Y(\bar{x}; \epsilon) = Y_0(\bar{x}) + \epsilon^{\gamma} Y_1(\bar{x}) + O(\epsilon^{\delta}), \quad \delta > \gamma, \quad \gamma > 0
$$

Leading order problem:

$$
\epsilon^{1-2\alpha} \frac{d^2}{d\bar{x}^2} \left(Y_0 + h.o.t.\right) + 2 \epsilon^{-\alpha} \frac{d}{d\bar{x}} \left(Y_0 + h.o.t.\right) + 2 \left(Y_0 + h.o.t.\right) = 0
$$

Dominant balance *⇒* leading order problem

- (i) 1st and 3rd term balance and 2nd term is of smaller order as *ϵ →* 0 \Rightarrow 1 − 2 α = 0 \Rightarrow $\alpha = \frac{1}{2}$
- *⇒* 1st and 3rd are *O*(1) and 2nd of *O*(*ϵ −*1*/*2) as *^ϵ [→]* ⁰ (ii) 1st and 2nd term balance and 3rd is smaller
	- $⇒ \alpha = 1$ $⇒$ 1st & 2nd are $O(\epsilon^{-1})$ and 3rd $O(1)$ $\sqrt{ }$

$$
\frac{d^2Y_0}{d\bar{x}^2} + 2\frac{dY_0}{d\bar{x}} = 0 \quad \text{for} \quad 0 < \bar{x} < \infty
$$
\n
$$
Y_0(0) = 0
$$

*⇒ Y*0(¯*x*) = *A*(1 *−* exp(*−*2¯*x*))

Matching

- There exist a domain where inner and outer solutions approximate same function
	- *⇒* Overlap-Domain
	- *⇒* there exist an intermediate variable *x^η* such that

Theorem

Kaplun's Extension Theorem

Let $\epsilon \ll \eta(\epsilon) \ll 1$ *such that* $x_{\eta} = x/\eta(\epsilon)$

(i) *There exist an* $\eta_1(\epsilon)$ *such that for* x_η *fixed*

 $\lim_{\epsilon \to 0} y_{outer}(x_\eta) - y_0(\eta(\epsilon) \quad x_\eta) = 0$ for any $\eta(\epsilon)$ that satisfies $\eta_1(\epsilon) \ll \eta(\epsilon) \ll 1$.

(ii) *There exist an* $\eta_2(\epsilon)$ *such that for* x_η *fixed*

 $\lim_{\epsilon \to 0} y_{inner}(x_\eta) - Y_0(\epsilon \eta(\epsilon) x_\eta) = 0$ for any $\eta(\epsilon)$ that satisfies $\epsilon \ll \eta(\epsilon) \ll \eta_2(\epsilon)$.

Remark

Kaplun's Hypothesis

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*The domain of validity of youter and yinner overlap, i.e. η*¹ *≪ η*2*. In this overlap domain the leading orders of youter and yinner agree.*

Proofs: P. Lagerstrom, "Matched asymptotic expansions: Ideas and Techniques", Spriner-Verlag, 1988.

Matching

Let $\eta(\epsilon)=\epsilon^\beta$ with $0<\beta< 1$ so that $\epsilon\ll\epsilon^\beta\ll 1$ and define the intermediate variable *x*

$$
x_{\eta}=\frac{x}{\epsilon^{\beta}}.
$$

Then

$$
y_{inner} = A \left[1 - \exp \left(-2 \frac{x_{\eta}}{\epsilon^{1-\beta}} \right) \right] + h.o.t. \rightarrow A + e.s.t. + h.o.t. \text{ as } \epsilon \rightarrow 0, x_{\eta} \text{ fixed}
$$

and

$$
y_{outer} = \exp\left(1 - x_{\eta} \epsilon^{\beta}\right) + h.o.t. \rightarrow \exp(1) + h.o.t. \quad \text{as } \epsilon \rightarrow 0, x_{\eta} \text{ fixed}
$$

 \Rightarrow *A* = exp(1).

Uniformly valid (composite) expansion

To leading order the asymptotic solution valid in the whole domain:

$$
y_c(x;\epsilon) = y_0(x) + Y_0\left(\frac{x}{\epsilon}\right) - \text{matched part} + h.o.t.
$$

Matched part: $y_0(0)$.

$$
\Rightarrow y_c(x; \epsilon) = \exp(1-x) - \exp\left(1 - \frac{2x}{\epsilon}\right) + h.o.t.
$$

Next order problem

$$
\frac{dy_1}{dx} + y_1 = -\frac{1}{2}\frac{d^2y_0}{dx^2}, \quad y_1(1) = 0, \qquad \frac{d^2Y_1}{d\bar{x}^2} + 2\frac{dy_1}{d\bar{x}} = -2Y_0, \quad Y_1(0) = 0
$$

- also needed to estimate validity of leading order result
- multiple BL, corner layers, transition layers, ...

Outer problem

$$
u(\tau, \mathbf{x}; \varepsilon) = u_o(\tau, \mathbf{x}) + \varepsilon u_1(\tau, \mathbf{x}) + \varepsilon^2 u_2(\tau, \mathbf{x}) + O(\varepsilon^3)
$$

$$
\mu(\tau, \mathbf{x}; \varepsilon) = \mu_o(\tau, \mathbf{x}) + \varepsilon \mu_1(\tau, \mathbf{x}) + \varepsilon^2 \mu_2(\tau, \mathbf{x}) + O(\varepsilon^3)
$$

Leading order

$$
0 = \Delta \mu_{\rm o} = \Delta F'(u_{\rm o})
$$

$$
\underline{O(\varepsilon)}
$$

$$
\frac{\partial u_{\rm o}}{\partial \tau} = \Delta \mu_1 = \Delta \left(F''(u_{\rm o}) u_1 \right)
$$

 $O(\varepsilon^2)$

$$
\frac{\partial u_1}{\partial \tau} = \Delta \mu_2 = \Delta \left(F''(u_0)u_2 + \frac{1}{2} F'''(u_0)u_1^2 - \Delta u_0 \right)
$$

- + boundary conditions on *∂*Ω
- Boundary conditions on Γ*^k ⇒* matching to 'inner' problem near Γ*^k*

Inner problem Define boundary layer with $z =$ 'inner' variable Parametrization of curve Γ*k*: $\boldsymbol{r}(\tau,s)=(r_1(\tau,s),r_2(\tau,s)),\,s$ is arclength

$$
\mathbf{x}(\tau,s,z) = \mathbf{r}(\tau,s) + \epsilon z \, \mathbf{\nu}(\tau,s)
$$

$$
\mathbf{x} = (x_1, x_2) = (x, y), \ \mathbf{r}(\tau, s) = (r_1(\tau, s), r_2(\tau, s))
$$

$$
\nu(\tau,s) = \left(-\frac{\partial r_2}{\partial s}(\tau,s), \frac{\partial r_1}{\partial s}(\tau,s)\right), \quad \mathbf{t}(\tau,s) = \left(\frac{\partial r_1}{\partial s}(\tau,s), \frac{\partial r_2}{\partial s}(\tau,s)\right)
$$

Sharp-interface model

$$
\Delta \mu_1^- = 0 \text{ in } \Omega^-, \quad \mathbf{n} \cdot \nabla \mu_1^- = 0 \text{ on } \partial \Omega^-, \quad \mu_1^\pm = \tilde{\mu}_1(\tau, \mathbf{r}), \quad \Delta \mu_1^+ = 0 \text{ in } \Omega^+
$$

t

 Ω

 Ω_{+} (c) $\qquad \qquad$ (e)

x ^ν ^ε^z{**^r**

 $+$

Γ*^k*

Interfacial velocity

$$
V^{\nu}=-\frac{[[\nu\cdot\nabla_{\!\!\!\ell}\mu_1^{\pm}(\tau,r)]]}{[[u_{\rm o}^{\pm}]]}
$$

Sharp-interface model governs the long-time dynamics of the phase field model Barbara Wagner (WIAS) CERN Training Lecture 2019 14/15 March 2019

Karin Jacobs and group: Condensed Matter Physics, Saarland University

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Bulk $(0 < z < h)$:

$$
\rho(\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u}) = -\nabla p + \mu \Delta \mathbf{u}, \quad \nabla \cdot \mathbf{u} = 0, \mathbf{u} = (u, w), \quad \mathbf{x} = (x, z)
$$

Capillary interface $(z = h(x, t))$:

$$
\mathbf{n} \cdot \underline{\Pi} \cdot \mathbf{t} = 0, \quad \mathbf{n} \cdot \underline{\Pi} \cdot \mathbf{n} = \sigma \kappa - \phi'(h), \quad (0, \partial_t h) \cdot \mathbf{n} = \mathbf{u} \cdot \mathbf{n}.
$$

$$
\kappa = \frac{\partial_{xx} h}{(1 + (\partial_x h)^2)^{3/2}}, \quad \mathbf{t} = \frac{(1, \partial_x h)^T}{(1 + (\partial_x h)^2)^{1/2}}, \quad \mathbf{n} = \frac{(-\partial_x h, 1)^T}{(1 + (\partial_x h)^2)^{1/2}},
$$

$$
\underline{\Pi} = -p \operatorname{id} + \mu \begin{pmatrix} 2\partial_x u & \partial_x u + \partial_x w \\ \partial_z u + \partial_x w & \partial_z w \end{pmatrix}.
$$

Liquid/solid interface $(z = 0)$: $w = 0$ Navier-Slip condition: $u = b \partial_z u$ \circ \vdash z h_{\Box}

 $\overline{\mathbf{x}}$

 $b = ∘$

• No-slip $(b = 0)$:

$$
\partial_t h = -\partial_x \left[h^3 \partial_x \left(\partial_{xx} h - \phi'(h) \right) \right]
$$

Weak-slip (*b ∼* 1):

$$
\partial_t h = -\partial_x \left[\left(h^3 + bh^2 \right) \partial_x \left(\partial_{xx} h - \phi'(h) \right) \right]
$$

 $\textsf{Intermediate-slip}\ (1\ll b\ll\epsilon_{\ell}^{-2})$:

$$
\partial_t h = -\partial_x \left[h^2 \partial_x \left(\partial_{xx} h - \phi'(h) \right) \right]
$$

Strong-slip $(b = \beta/\epsilon_{\ell}^2)$:

$$
\operatorname{Re}(\partial_t u + u \partial_x u) = \frac{4 \partial_x (h \partial_x u)}{h} + \partial_x (\partial_{xx} h - \phi'(h)) - \frac{u}{\beta h}
$$

$$
\partial_t h + \partial_x (h u) = 0
$$

Surface directed spinodal decomposition

 $\begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$
Confined bulk diffusion $\begin{bmatrix} 0.5 \\ 0.0 \end{bmatrix}$

 $\overline{}$

 ^A B A B z=0 x z=h θ φ=0 z=1 φ<0 φ>0

 ϕ order parameter, μ chemical potential, F bulk free energy

$$
\phi_t = \Delta \mu, \qquad \mu = F'(\phi) - \epsilon^2 \Delta \phi,
$$

$$
F(\phi) = -\chi \phi^2 + \phi^4/6, \qquad \chi = (1 - T)/T
$$

Boundary conditions at $z = 0$, d for antisymmetric walls:

$$
\mu_z = 0 \quad \text{(no-flux)},
$$

$$
\epsilon \phi_z = \beta_1 (1 - \phi^2 / (3 \chi_0)^{1/2})
$$

Initial condition

$$
\phi(z,0)=0.
$$

Cahn 1977, Binder 1995, Puri & Binder (2002, 2007,*. . .*), Gheoghegan & Krausch (2003) Cubic surface energy: e.g. Xu & Wang 2011

$$
\partial_{xx}\mu^{(1)} + \partial_{zz}\mu^{(1)} = 0, \qquad \text{on } 0 < z < h \quad \text{and} \quad h < z < d,
$$
\n
$$
\mu^{(1)} = \frac{\sigma h_{xx}}{(1 + h_x^2)^{1/2}}, \quad h_t = \frac{1}{2(3\chi)^{1/2}} \left(\left[\partial_x \mu^{(1)} h_x - \partial_z \mu^{(1)} \right]_+^+ \right), \quad \text{at } z = h,
$$
\n
$$
\partial_z \mu^{(1)} = 0 \qquad \text{at } z = 0, \, d.
$$

Conditions at 3-phase contact line $x = s(t)$:

$$
h = 0, h_x = \tan \theta, q = 0,
$$

with
$$
\cos \theta = \frac{2\beta_1(1+\chi)}{3\sigma} \quad \text{(Cahn 77 - Modica 87).}
$$

Conditions for A/B interface at $x \to \infty$:

$$
h \to 1, \quad q \to 0.
$$

Notice mass conservation:

$$
h_t + q_x = 0 \quad \text{with } q = \partial_x \int_0^d \mu dz.
$$

For *θ ≪* 1, rescale and use thin film approximation.

$$
\begin{aligned} \partial_{\tilde{z}\tilde{z}}\tilde{\mu} &= 0, \qquad \text{on } 0 < \tilde{z} < h(\tilde{x}, \tilde{t}) \text{ and } \tilde{h}(\tilde{x}, \tilde{t}) < \tilde{z} < d, \\ \tilde{\mu} &= \tilde{h}_{\tilde{x}\tilde{x}}, \qquad \text{at } \tilde{z} = \tilde{h}(\tilde{x}, \tilde{t}), \\ \tilde{h}_{\tilde{t}} &= -[\partial_{\tilde{z}}\tilde{\mu}]_{-}^{+}, \qquad \text{at } \tilde{z} = \tilde{h}(\tilde{x}, \tilde{t}), \\ \partial_{\tilde{z}}\tilde{\mu} &= 0 \qquad \text{at } \tilde{z} = 0, d; \end{aligned}
$$

Integrate and combine with mass conservation:

$$
\tilde{h}_{\tilde{t}} + \tilde{h}_{\tilde{x}\tilde{x}\tilde{x}\tilde{x}} = 0.
$$

Contact line and far-field conditions:

$$
x = s(t): \quad \tilde{h} = 0, \quad \tilde{h}_{\tilde{x}} = 1, \quad \tilde{h}_{\tilde{x}\tilde{x}\tilde{x}} = 0; \quad \tilde{x} \to \infty: \quad \tilde{h} \to 1, \quad \tilde{h}_{\tilde{x}\tilde{x}\tilde{x}} \to 0.
$$

Top: Evolution of film in lubrication model – Bottom: Phase field model Parameters PFM: $\chi_0 = 0.1$, $\beta_1 = 0.11$, $\varepsilon = 0.03$, $\theta = 50^\circ$.

Parameters PFM: $\chi_0 = 0.1$, $\beta_1 = 0.11$, $\varepsilon = 0.03$, , $\theta = 45^\circ$.

Hennessy et al., EPL 2014, Hennessy et al., SIAP, 2014

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