

Optimal scheduling of radial velocity follow-up of transiting exoplanets

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Extreme Precision in Radial Velocity
Grindelwald, 18th – 21st March 2019

Bayesian Decision Theory

The best experiment is the one which maximizes its expected utility

$$\begin{aligned} EU(\mathbf{e}) &= \int U(\mathbf{D}_e, \mathbf{e}) P(\mathbf{D}_e | \mathbf{D}_c, \mathbf{e}) d\mathbf{D}_e \\ &= \int U(\mathbf{D}_e, \mathbf{e}) \int P(\mathbf{D}_e | \boldsymbol{\theta}, \mathbf{M}, \mathbf{e}) P(\boldsymbol{\theta} | \mathbf{M}, \mathbf{D}_c) d\boldsymbol{\theta} d\mathbf{D}_e \end{aligned}$$

where

\mathbf{e} **experiment parameters (e.g. spatial or time coordinates)**

\mathbf{D}_e **a priori possible data values acquired through experiment \mathbf{e}**

\mathbf{D}_c **current data values acquired through previous experiments**

$\boldsymbol{\theta}$ **parameters of the data-generating model (\mathbf{M} , assumed true a priori)**

Bayesian Decision Theory

Most useful from a Bayesian point of view are the data D_e , obtained under experiment e , which maximize the distance between posterior and prior distributions

$$U(D_e, e) = \int P(\theta | M, D_c, D_e, e) \ln \left[\frac{P(\theta | M, D_c, D_e, e)}{P(\theta | M, D_c)} \right] dD_e$$

Kullback-Leibler divergence

And if $P(D_e | \theta, M, e)$ is independent of e then

$$EU(e) = \text{constant} - \int P(D_e | M, D_c, e) \ln [P(D_e | M, D_c, e)] dD_e$$

$$= \text{constant} + E[I(D_e, e)]$$

Shannon entropy



maximum entropy sampling

Ford (2008)

Loredo et al. (2004, 2012)

where $I(D_e, e)$ is the information associated with a given set of measurements D_e in nats.

Problem

When to schedule radial velocity measurements in order to maximize the information with respect to the masses of exoplanets detected in transit?

Generic Model

For each radial velocity measurement d_i

$$d_i = \sum_{j=1}^{n_p} K_j \{ e_j \cos \omega_j + \cos[\omega_j + \phi(t_i | P_j, \tau_j, e_j)] \} + v_s(t_i) + \epsilon_i$$

where n_p is the number of planets, v_s is the radial velocity of the star, and ϵ_i represents stochastic instrumental, atmospheric and astrophysical (e.g. stellar activity) model components.

We will assume each ϵ_i is **iid Gaussian distributed**

$$P(\{\epsilon_i\}) \sim \prod_{i=1}^N N(0, \sigma_i)$$

Scheduling Model

For each radial velocity measurement d_i

$$d_i = \sum_{l=1}^{n_t} K_l \cos \left[\omega_l + \frac{2\pi(t_i - \tau_l)}{P_l} \right] + v_s + \varepsilon_i \quad \longrightarrow \quad \text{linear model}$$

where now n_t is the number of transiting planets, all assumed to have circular orbits, and v_s is the assumed constant radial velocity of the star. The values of ω_l and τ_l are completely degenerate, and such that at the time of transit $d_i = 0$.

For a linear model, and in the presence of iid Gaussian uncertainty, if all M parameter (K_l, v_s) prior distributions are uniform then

$$EU(\mathbf{e}) = -\frac{1}{2} [M + M \ln(2\pi) - \ln(|\mathbf{G}^T \mathbf{E}^{-1} \mathbf{G}|)] + \text{constant}$$

\mathbf{G} - matrix containing the values the basis functions take at t_i

\mathbf{E} - data variance-covariance matrix (diagonal, with terms σ_i^2)

Transiting planets with circular orbits

If no extra planets were assumed to exist in the system, then analysis and scheduling models would coincide, and the marginal posterior distributions for any K_l and \mathbf{v}_S would be Gaussians. In the particular case of $n_t = 1$,

$$K = \mu_K \pm \sigma_K$$

$$\sigma_K^2 = \left[\sum_{i=1}^N \frac{1}{\sigma_i^2} \sum_{i=1}^N \frac{\left(\cos \left[\omega + \frac{2\pi(t_i - \tau)}{P} \right] \right)^2}{\sigma_i^2} - \left(\sum_{i=1}^N \frac{\cos \left[\omega + \frac{2\pi(t_i - \tau)}{P} \right]}{\sigma_i^2} \right)^2 \right]^{-1} \sum_{i=1}^N \frac{1}{\sigma_i^2}$$

If the $\{\sigma_i\}$ were all equal, when would σ_K^2 be minimized?

When RV measurements are performed in quadrature!

$$\sigma_K = \frac{\sigma}{\sqrt{N}} \quad \text{c.f.} \quad \sigma_K = \frac{\sigma\sqrt{2}}{\sqrt{N}} \quad \text{for uniform sampling in phase (e.g. Cloutier et al. 2018)}$$

Transiting planets with non-circular orbits

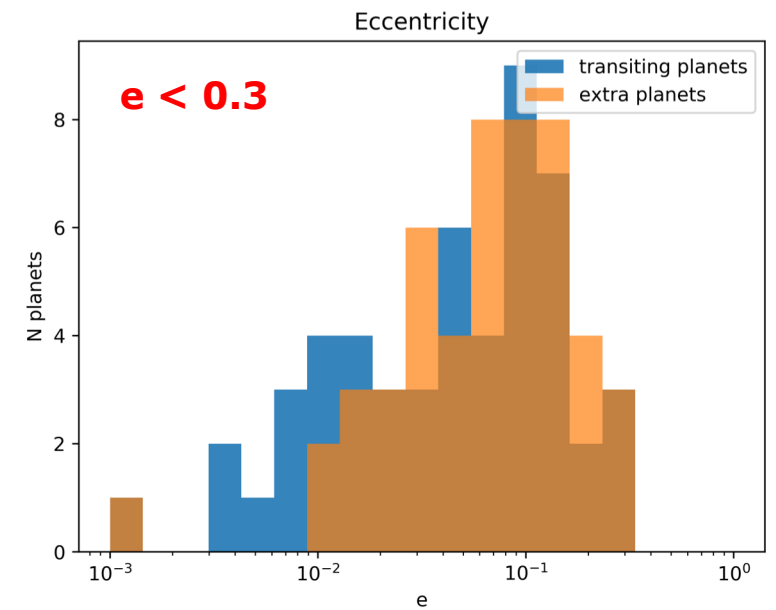
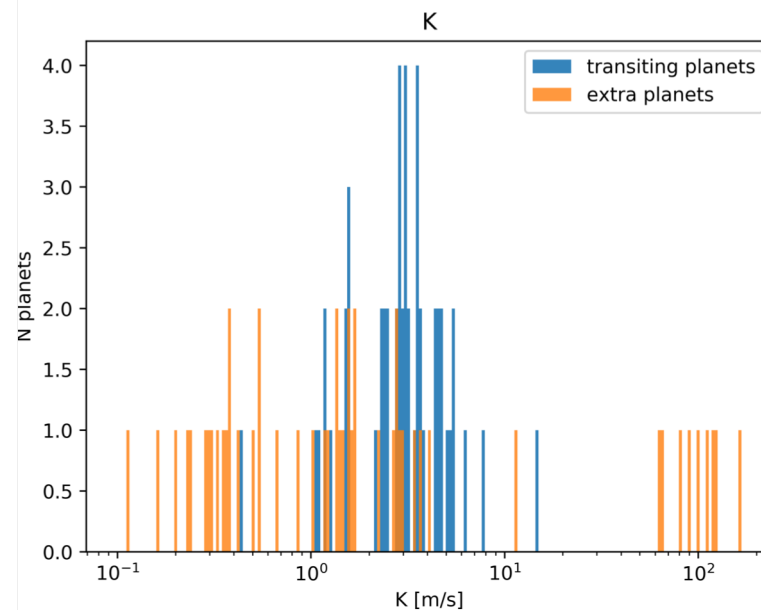
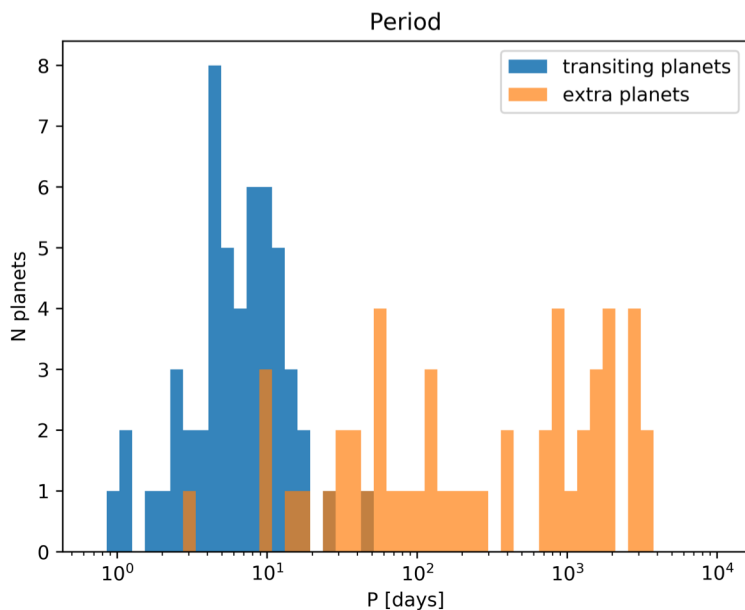
A Revised Exoplanet Yield from the Transiting Exoplanet Survey Satellite (TESS)
Barclay, Pepper and Quintana, 2018, ApJSS, 239

Among which, 50 stars were selected for ESPRESSO follow-up with:

$-80 < \delta < +30$, $V < 11$, $T_{\text{eff}} < 6000$ K, $\log_g > 4.0$

and at least one orbiting planet with 3 TESS detected transits, $S/N < 10$ and a radius below $4 R_{\oplus}$

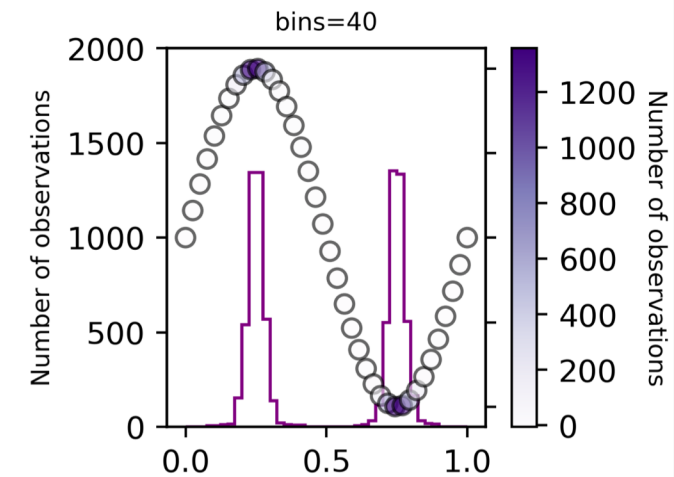
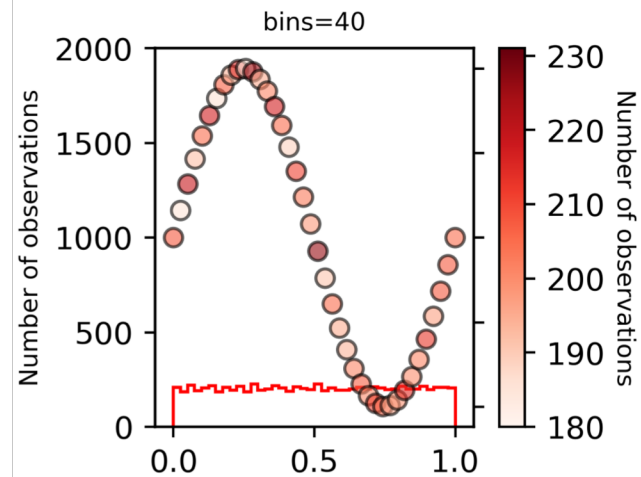
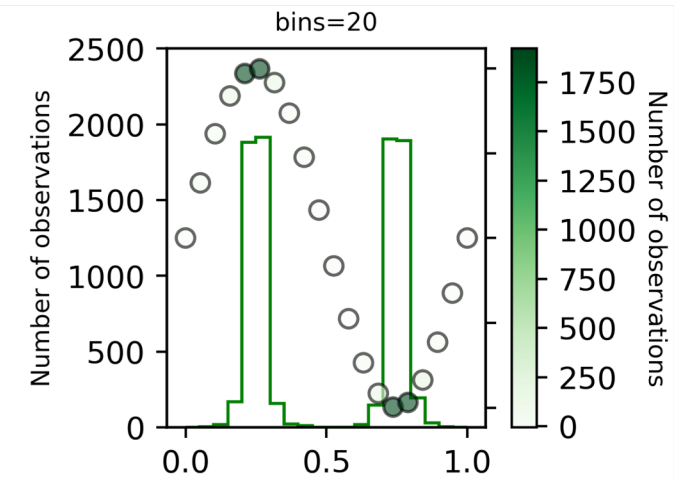
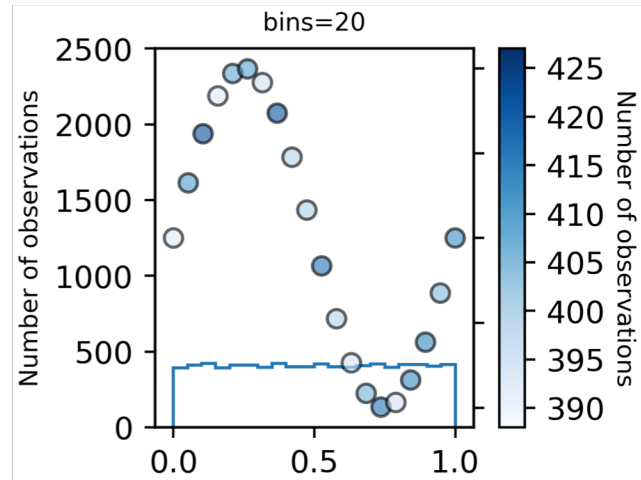
Extra planets, non-detectable by TESS and with $K > 0.1$ m/s, were randomly added to each system according to Poisson distributions with means as in Fressin et al. (2013), extrapolated up to 2 years, and with means as in Herman, Hu and Wu (2019), for periods between 2 and 10 years. All planets in any system were assumed co-planar, with eccentricities drawn from the Beta distribution assumed in Barclay et al. (2018).



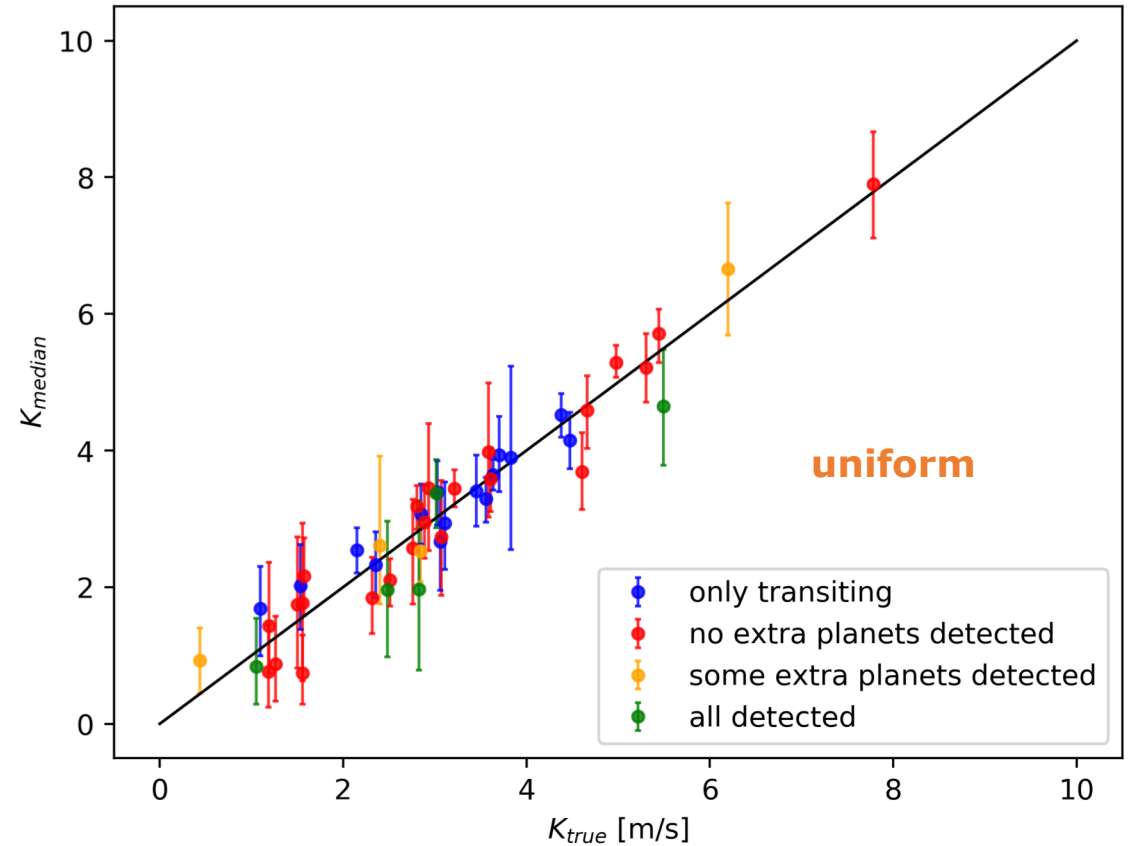
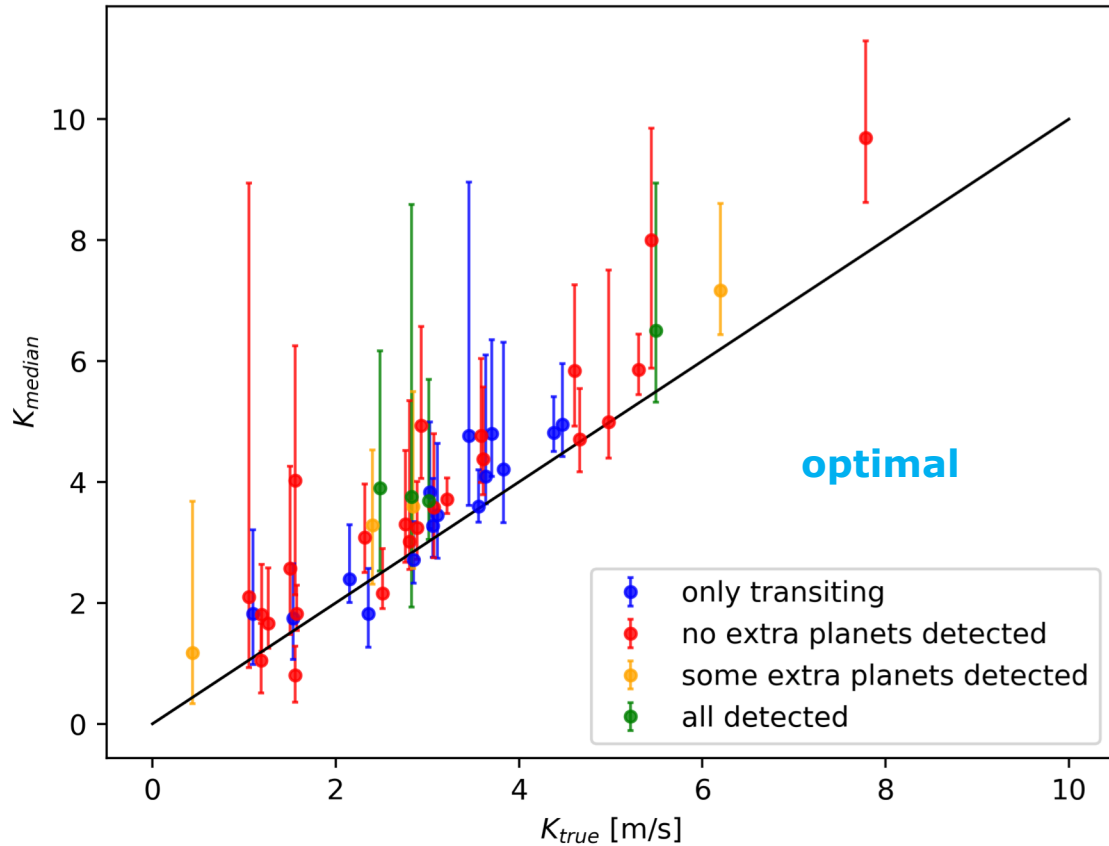
Transiting planets with non-circular orbits

ESPRESSO GTO-type schedules for transit follow-up were simulated 7 times, assuming that **30% of the ESPRESSO guaranteed time for exoplanet science** was available during **3 years**, which amounts to **1102 observational slots of (15+9) minutes**, i.e. about **61.4 effective nights**.

Optimal (for $e=0$) and **uniform-in-phase** schedulers were then applied. The later evenly distributes the available observational slots among all 50 stars, while ensuring each star is observable with airmass below 2 and the phase space is sampled as uniformly as possible (uses a maximin space-filling design based on L^2 relaxation, e.g. Pronzato 2016). **For each possible time, t_i , the value of σ_i was estimated using the ESPRESSO ETC, and then a time-independent contribution from stellar activity, specific to each star, was added in quadrature (Cegla et al. 2014).**

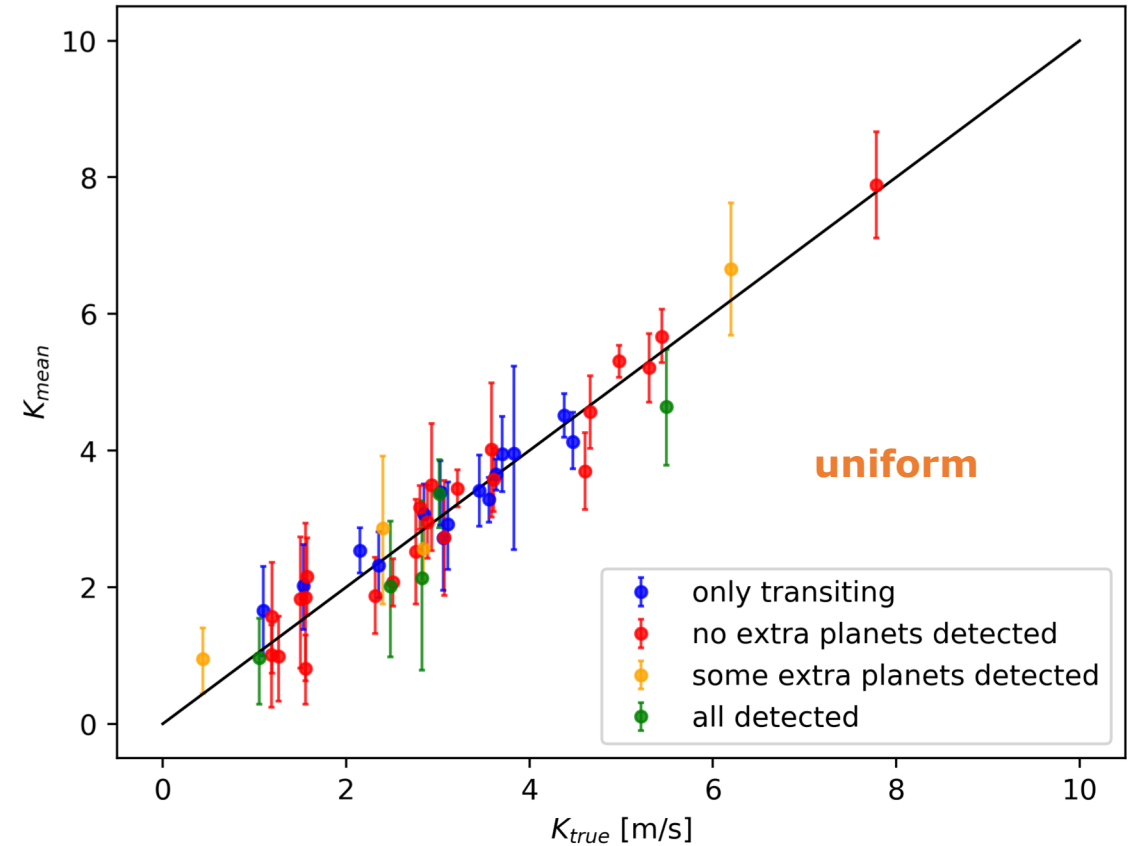
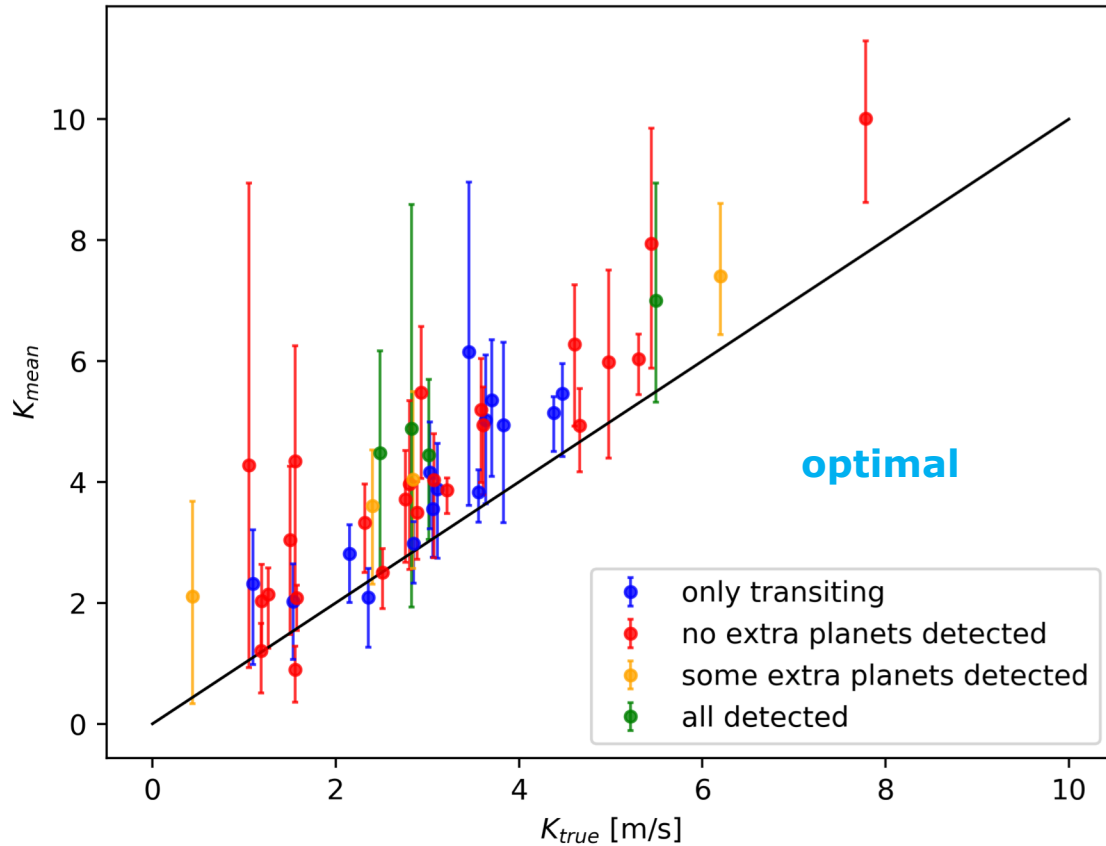


Transiting planets with non-circular orbits



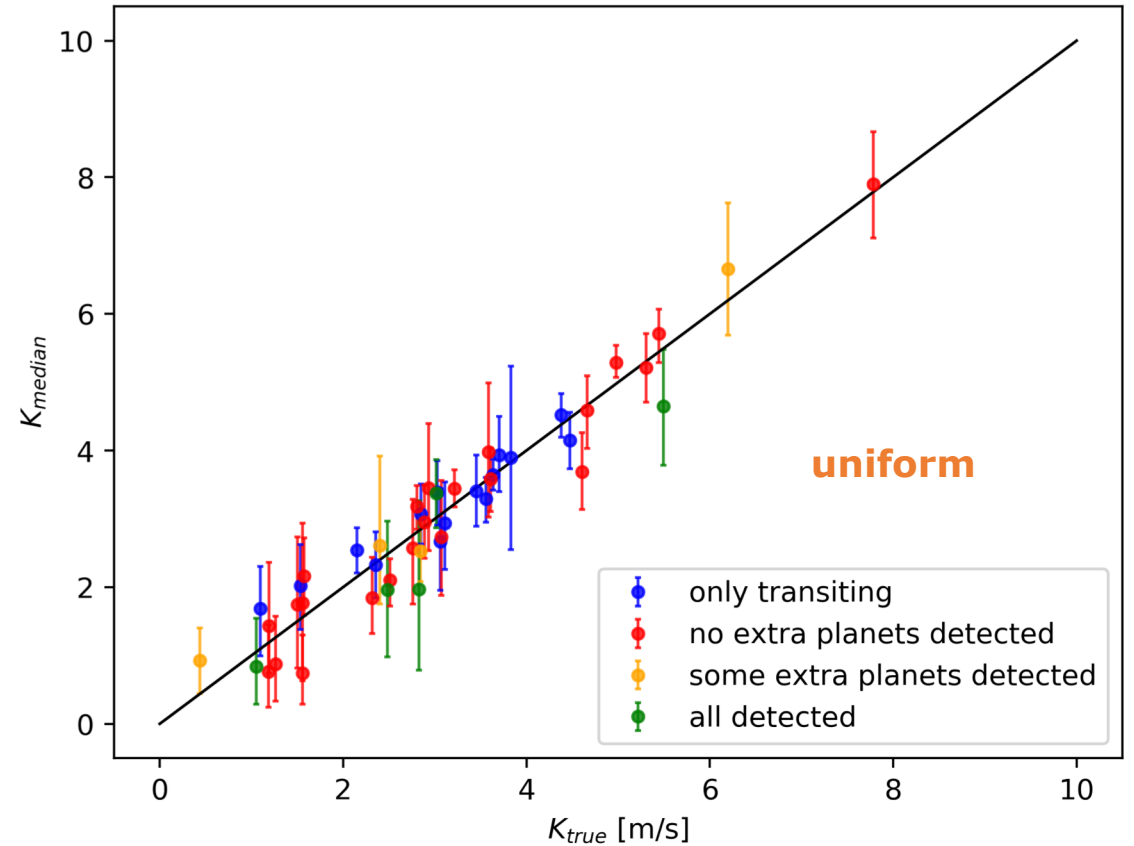
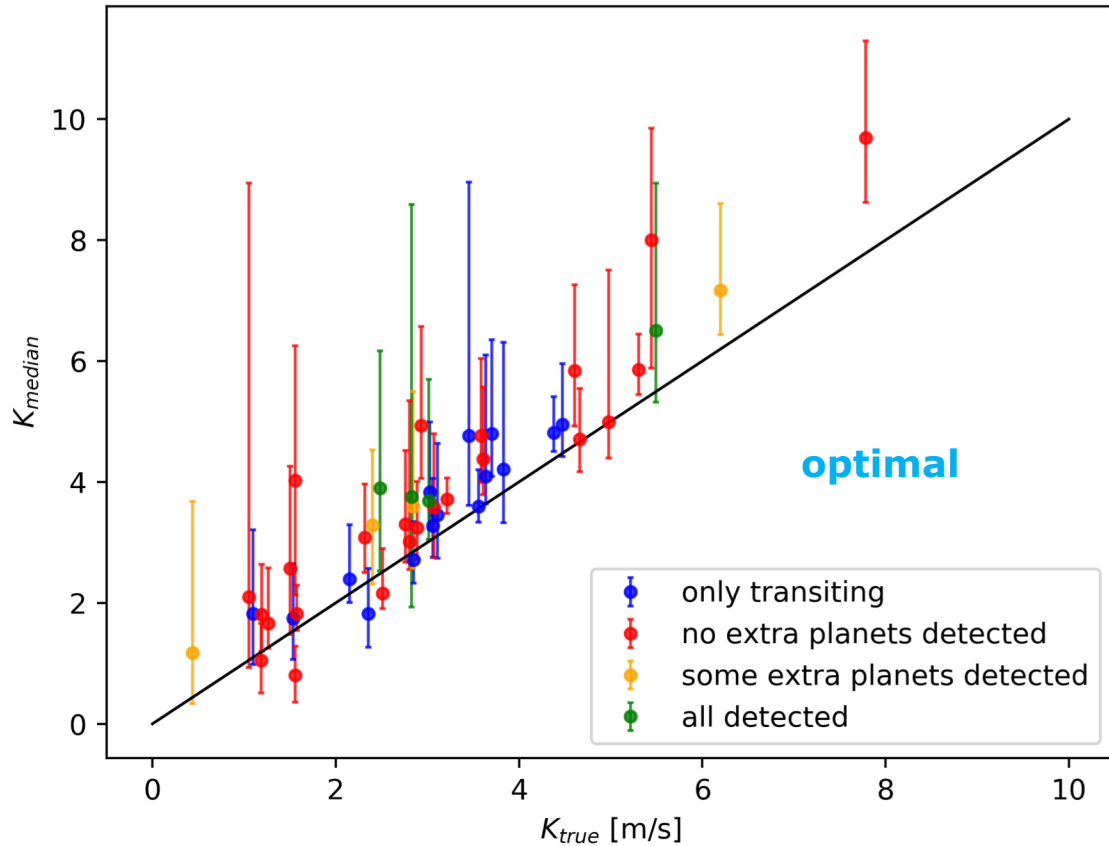
Medians plus symmetric credible intervals centred on median containing 0.68 of the probability, for one realization of each type of schedule

Transiting planets with non-circular orbits



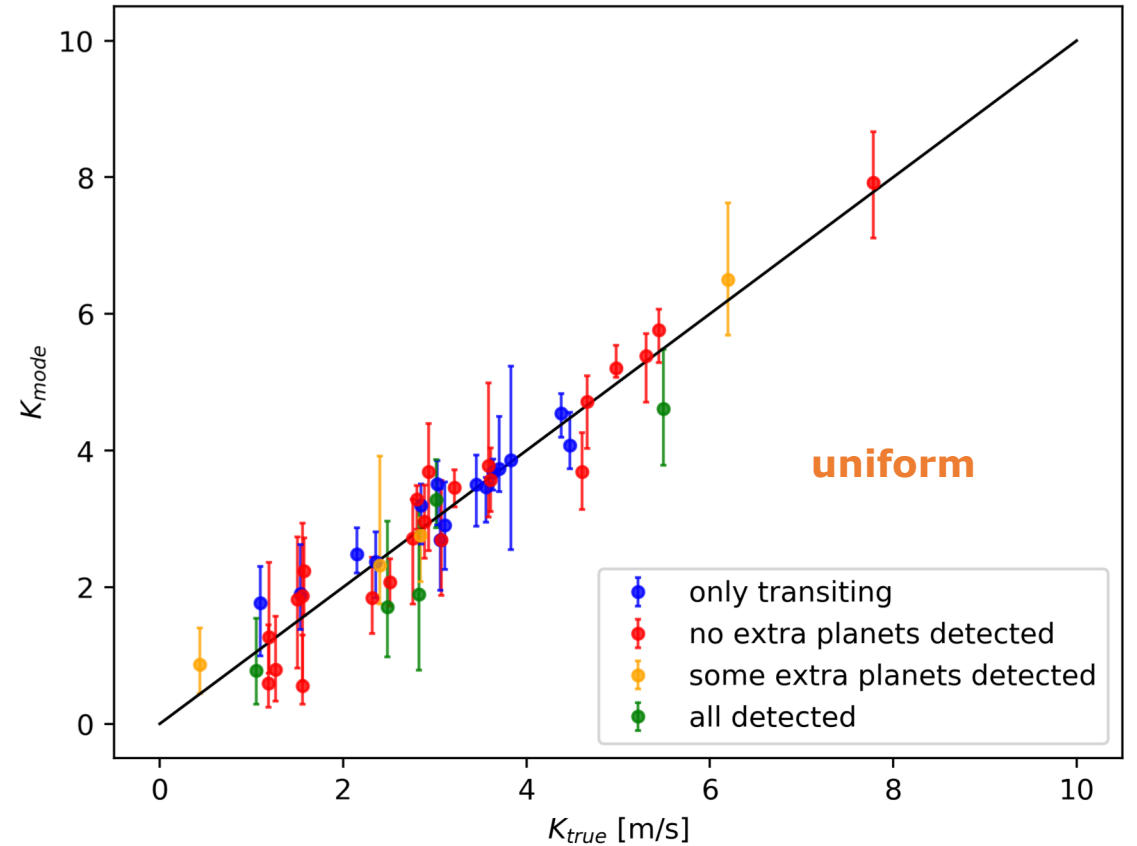
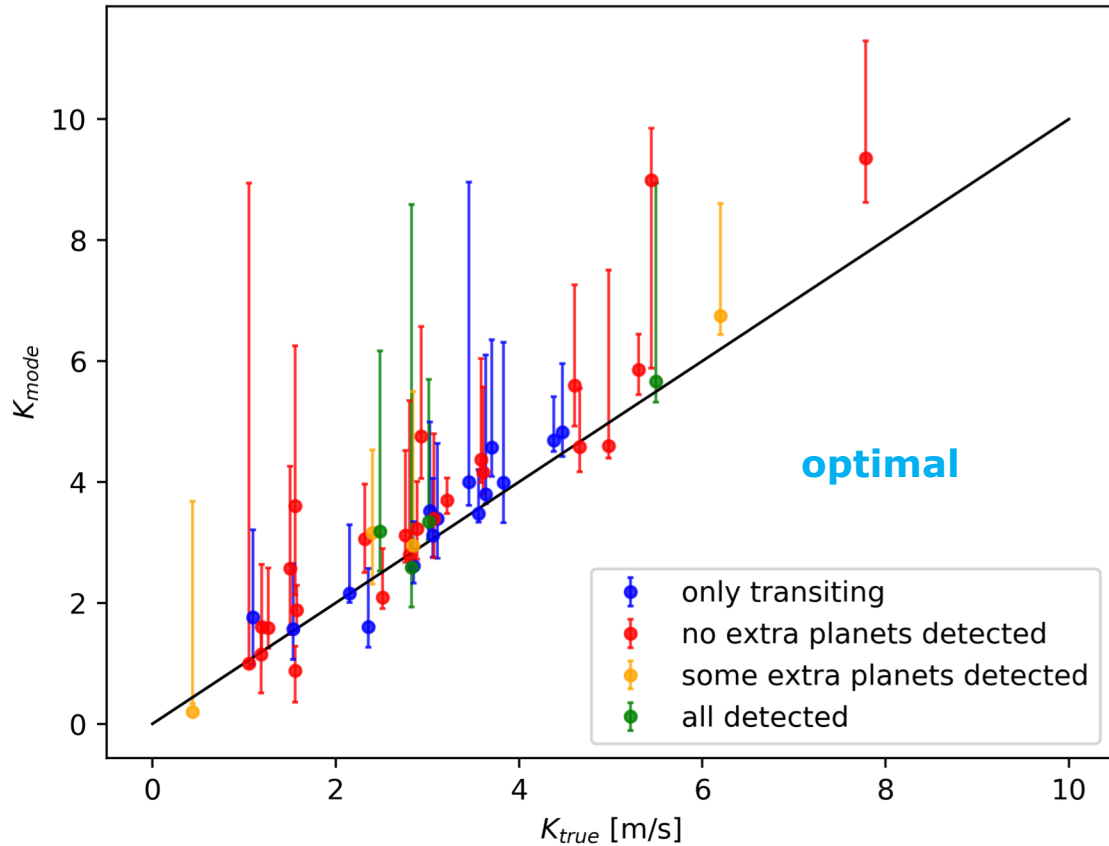
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Transiting planets with non-circular orbits



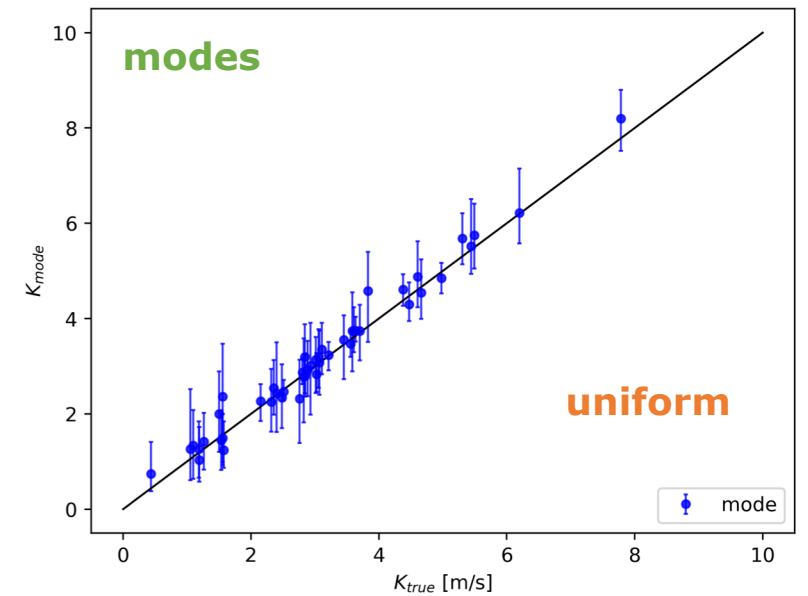
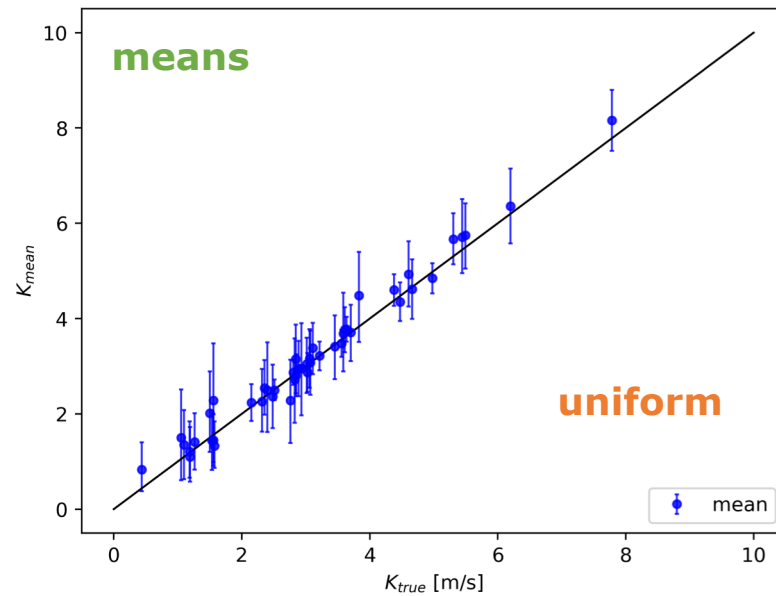
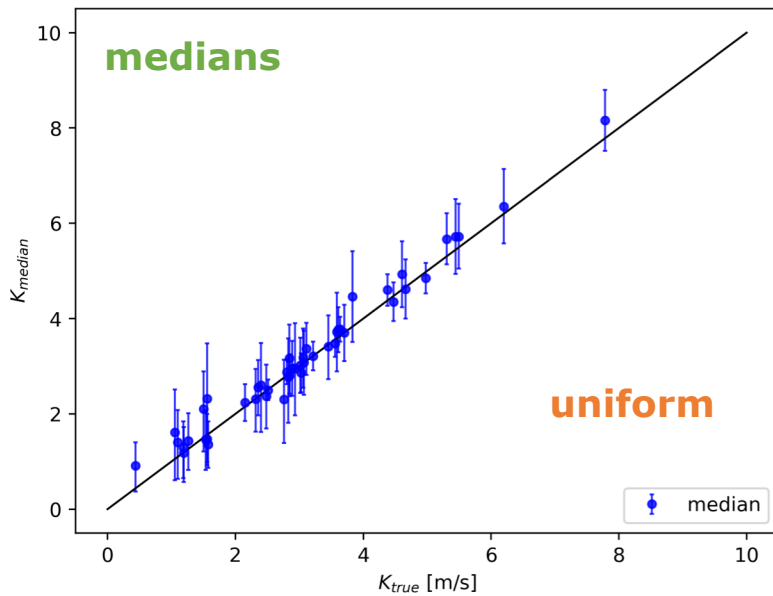
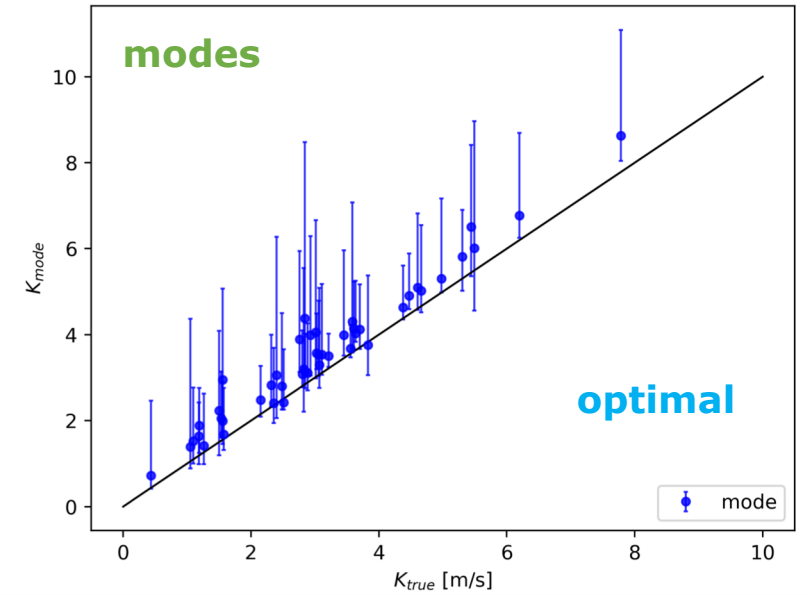
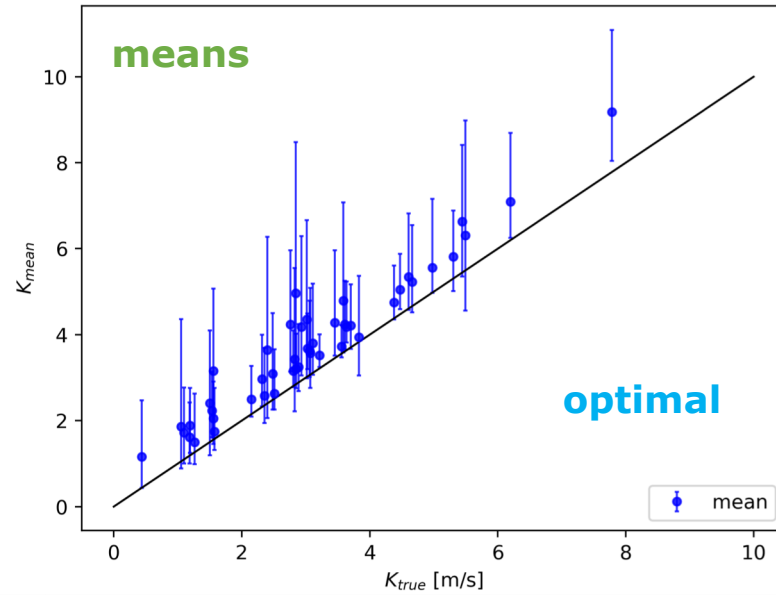
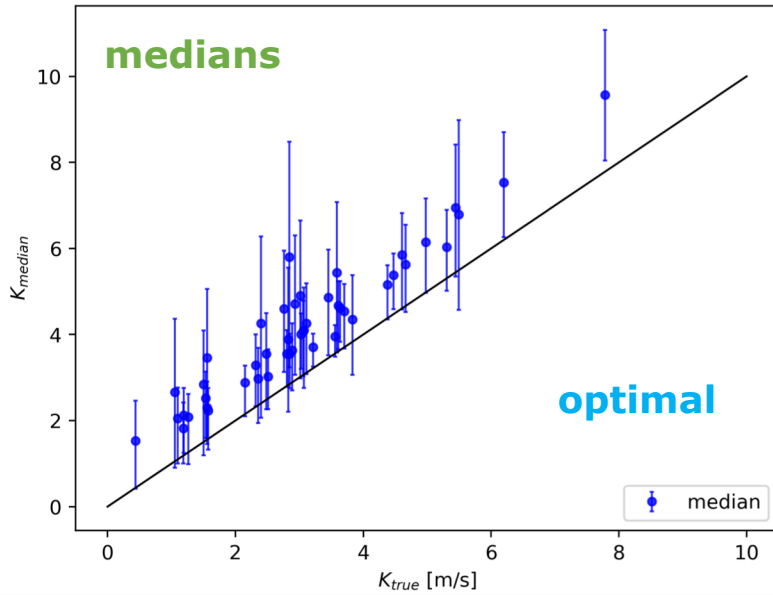
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Transiting planets with non-circular orbits

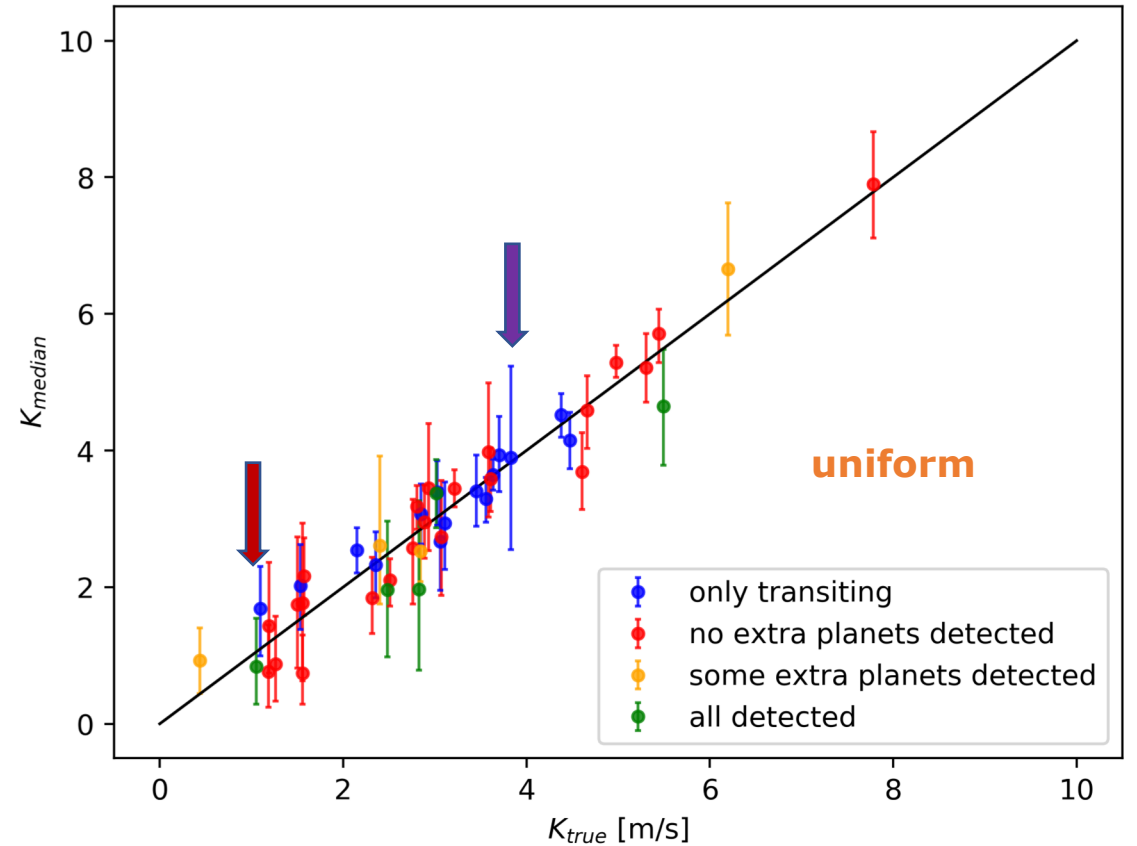
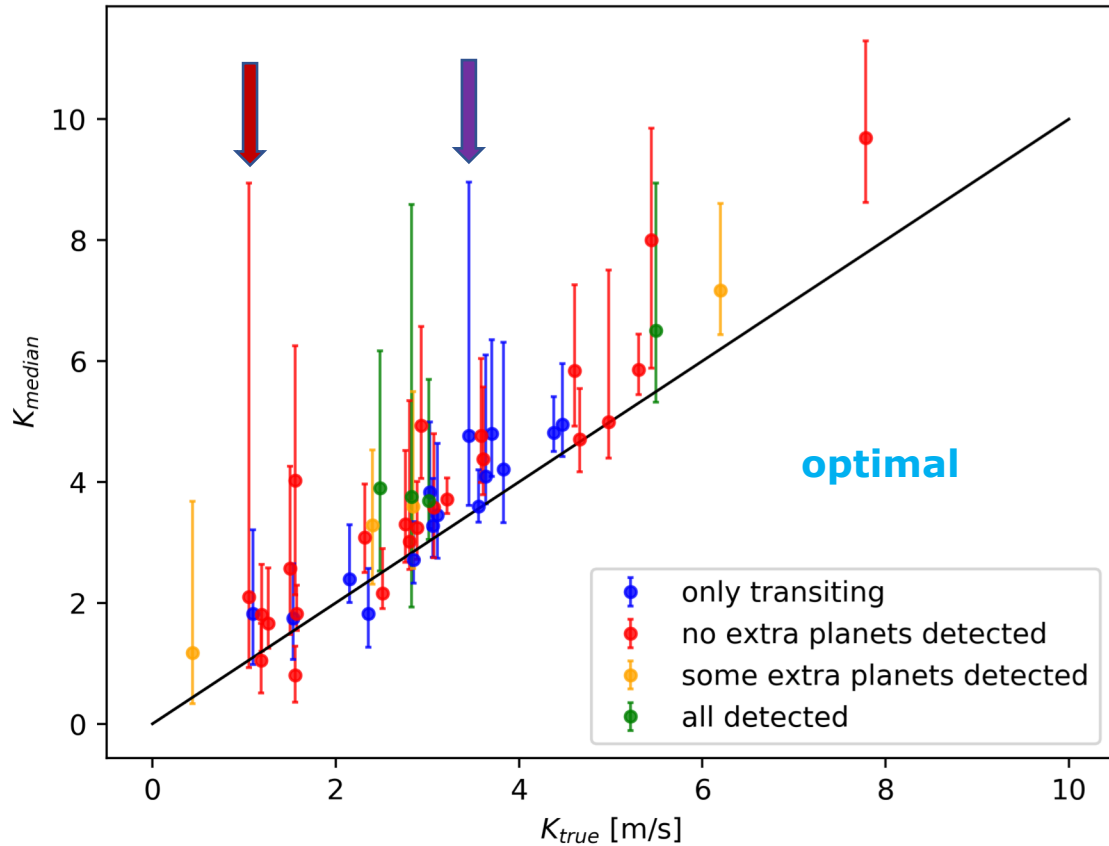


Modes plus symmetric credible intervals centred on median containing 0.68 of the probability, for one realization of each type of schedule

Average over 7 realizations of each type of schedule, of medians, means and modes, as well as of the limits of the symmetric credible intervals centred on median containing 0.68 of the probability

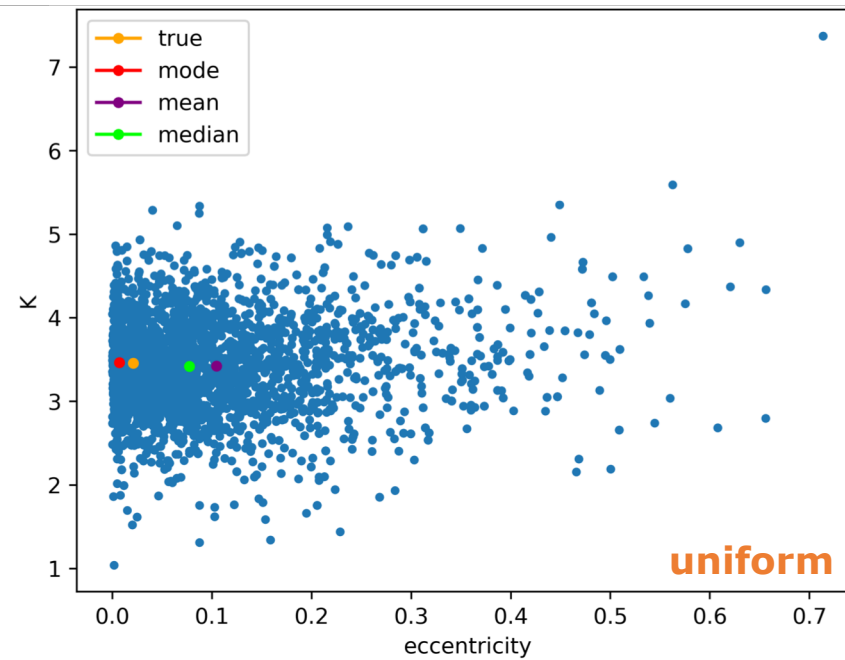
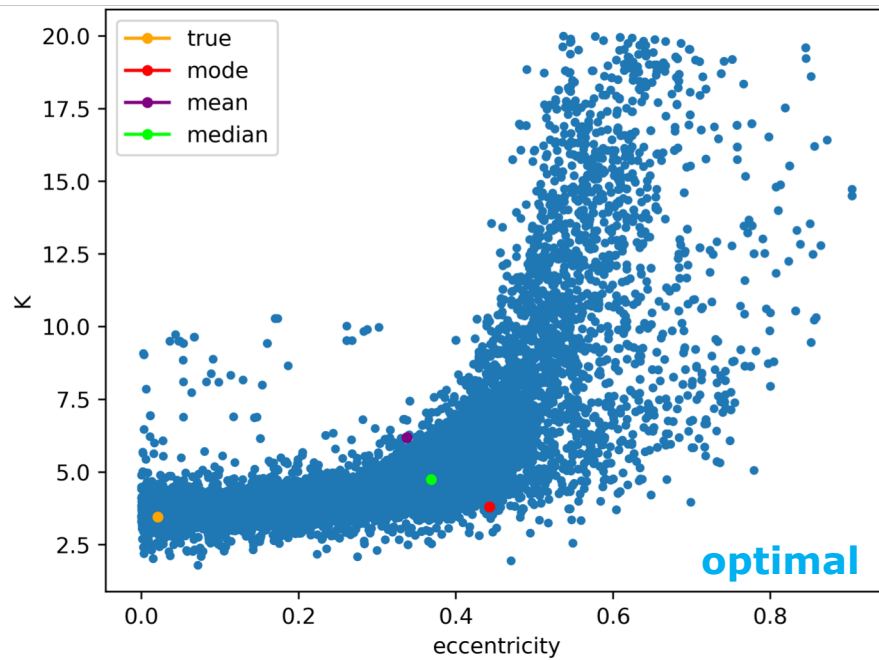
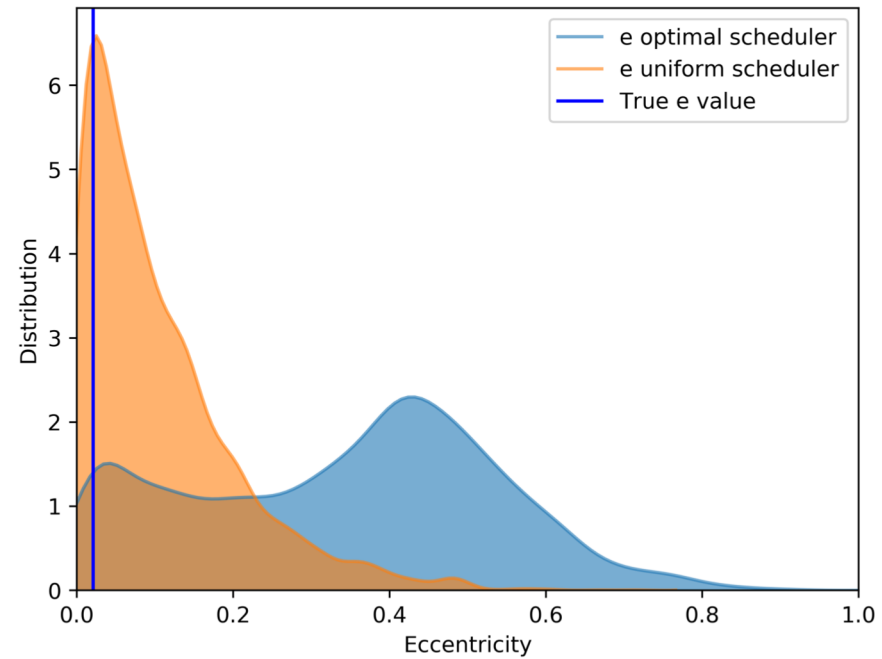
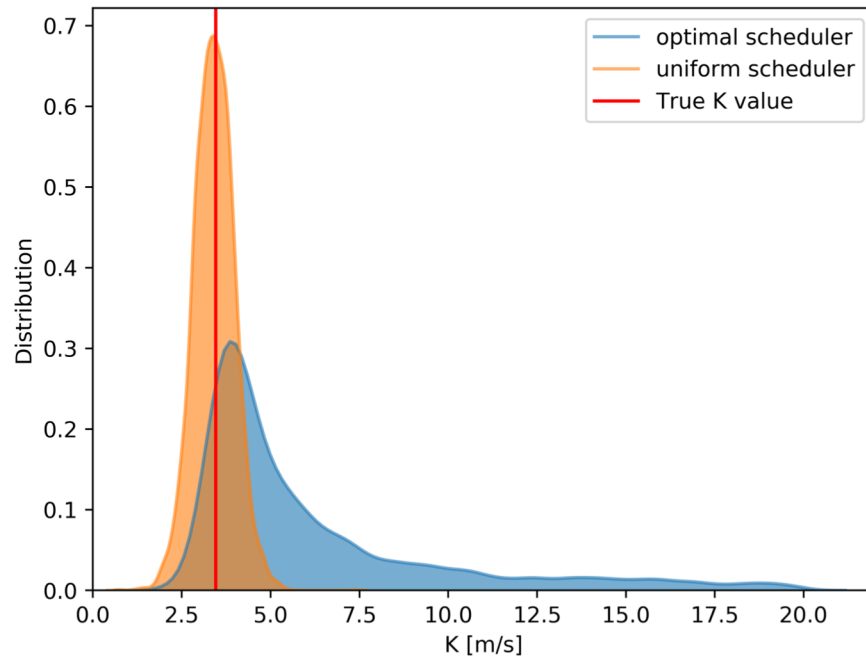


Transiting planets with non-circular orbits

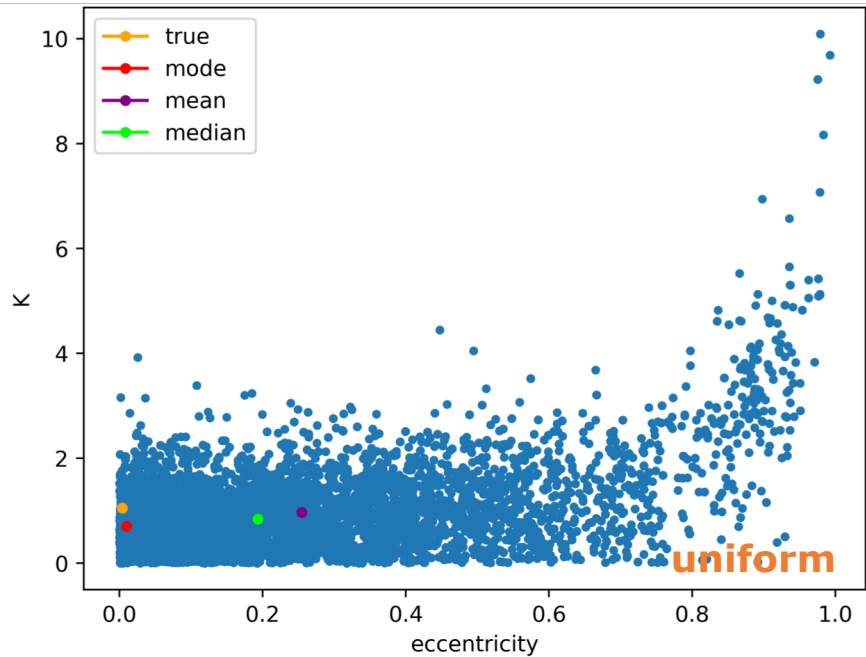
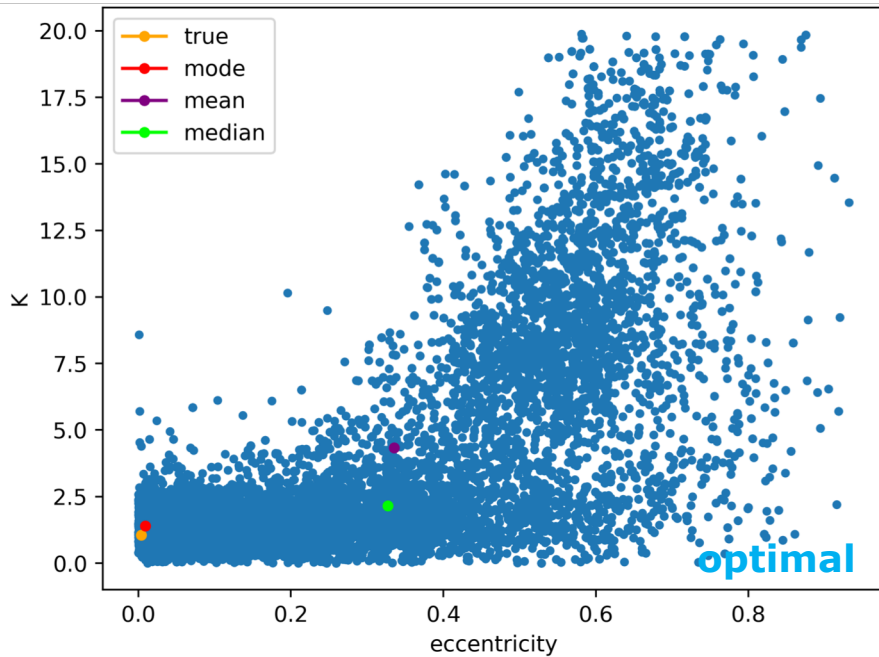
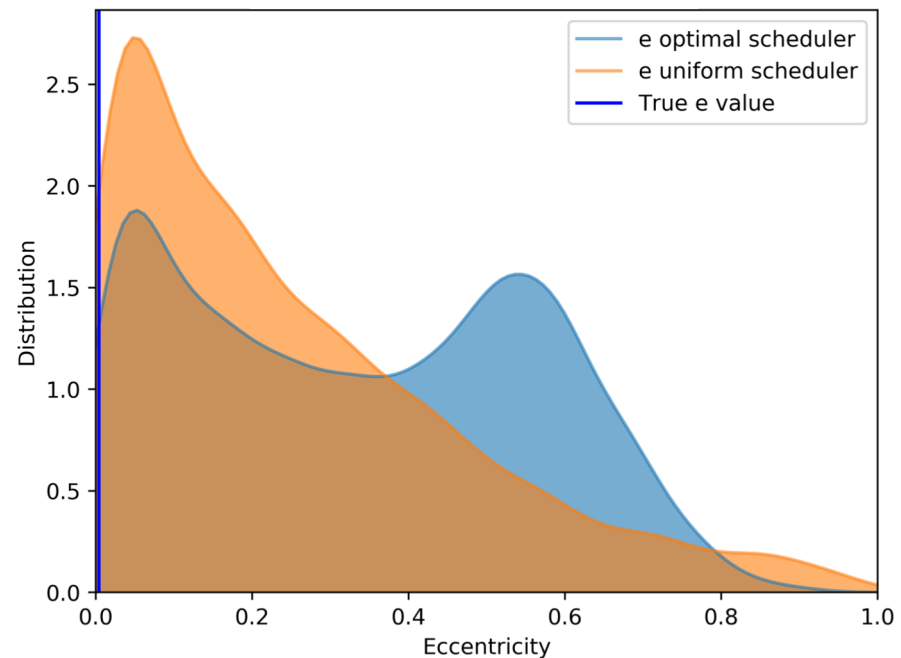
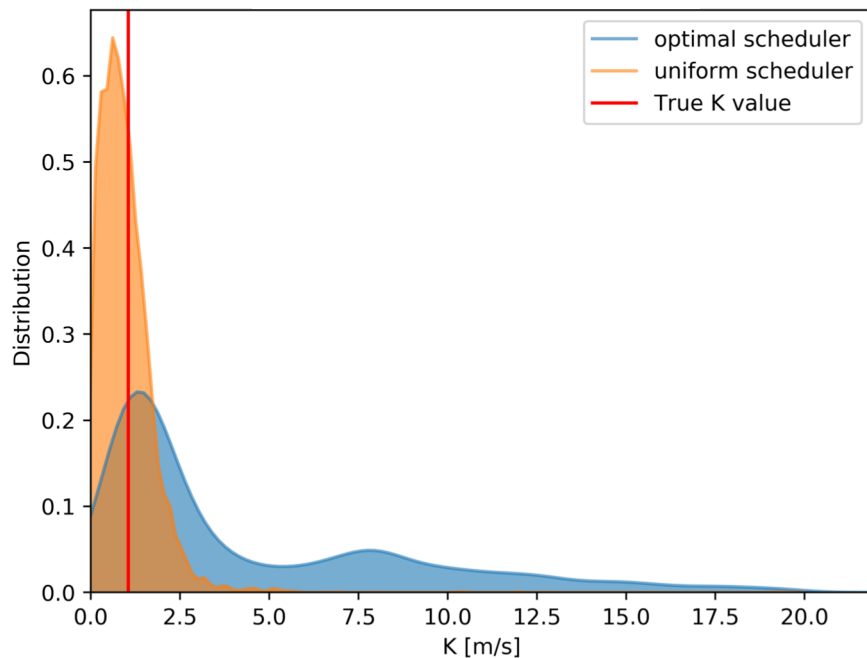


Medians plus symmetric credible intervals centred on median containing 0.68 of the probability, for one realization of each type of schedule

One transiting planet, no extra planet, $\sigma_{\text{act}} = 2.0$ m/s



**One transiting planet, one extra planet ($K=11.6$ m/s, $e=0.057$, $P=806.1$ days),
detected under uniform sampling, not-detected under optimal sampling, $\sigma_{\text{act}} = 2.1$ m/s**



Posterior probability distributions for K, centered on its true value, for 15 systems with only one (transiting) planet, assuming $e = 0$ and no other planets exist

