

Digital Electronics & DAQ for FAIR
**Algorithms for position calculation
and achievable resolution**

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for the Dept. of Beam Instrumentation**

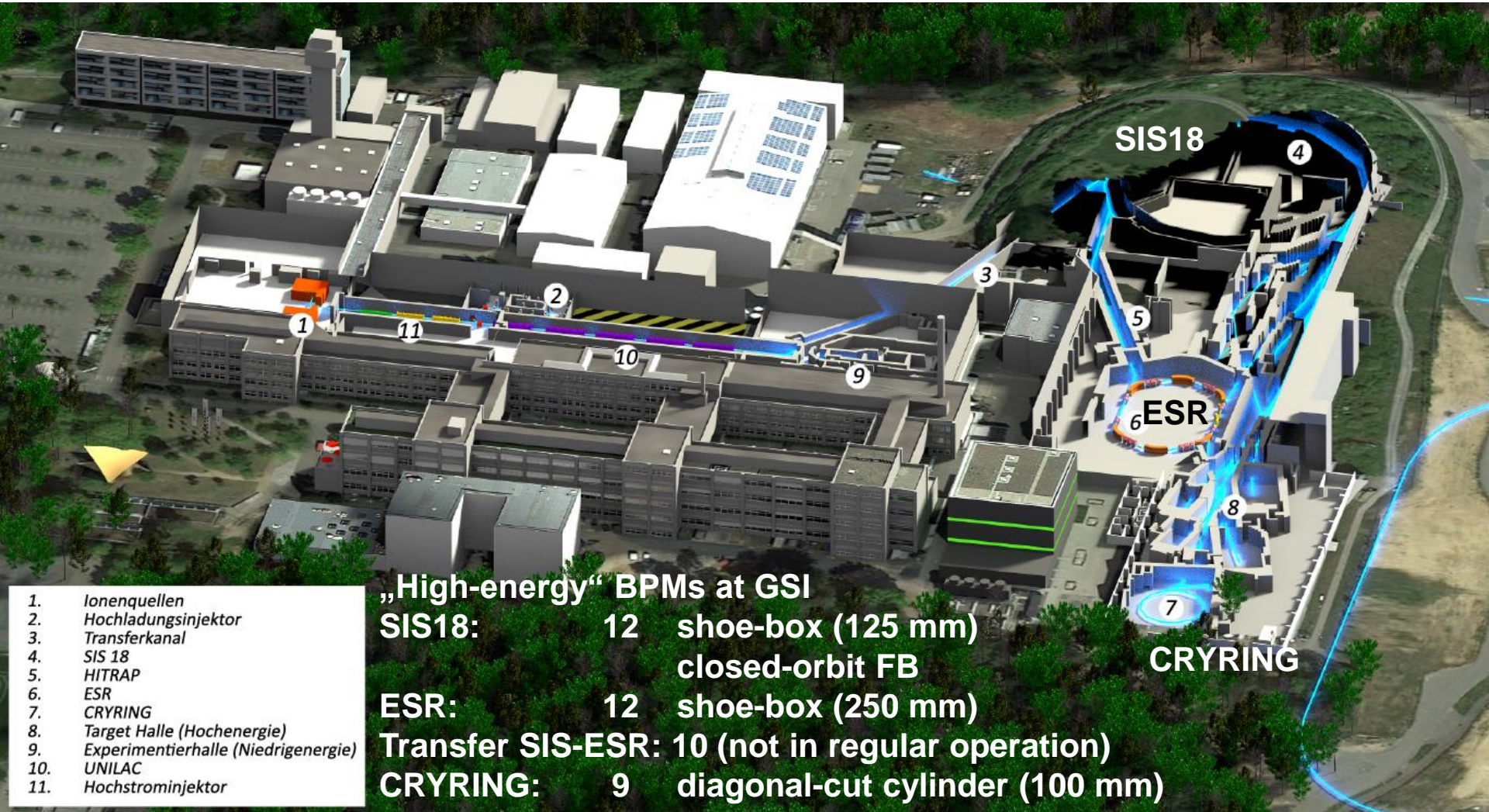
**Acknowledgements to
K. Lang, O. Chorniy, P. Miedzik, P. Kowina, P. Forck (GSI)
D. Tavares (LNLS)**

Outline of talk

- Motivation
 - BPM systems at GSI & FAIR
- Beam position in time-domain analysis
 - Asymmetry measurement (Δ/Σ)
 - Comparison of „classical“ estimators and least-squares fit of (Δ/Σ) tuples
 - Model prediction of position uncertainty
- Experimental verification: applications and tests
 - Bunch and orbit position uncertainty
 - Robustness of position and tune spectra
 - Multi-turn injection & coasting beam
 - Detour on electron machines: comparison to IQ demodulation
- Conclusion & Outlook

Motivation

BPM systems at GSI



1. Ionenquellen
2. Hochladungsinjektor
3. Transferkanal
4. SIS 18
5. HITRAP
6. ESR
7. CRYRING
8. Target Halle (Hochenergie)
9. Experimentierhalle (Niedrigenergie)
10. UNILAC
11. Hochstrominjektor

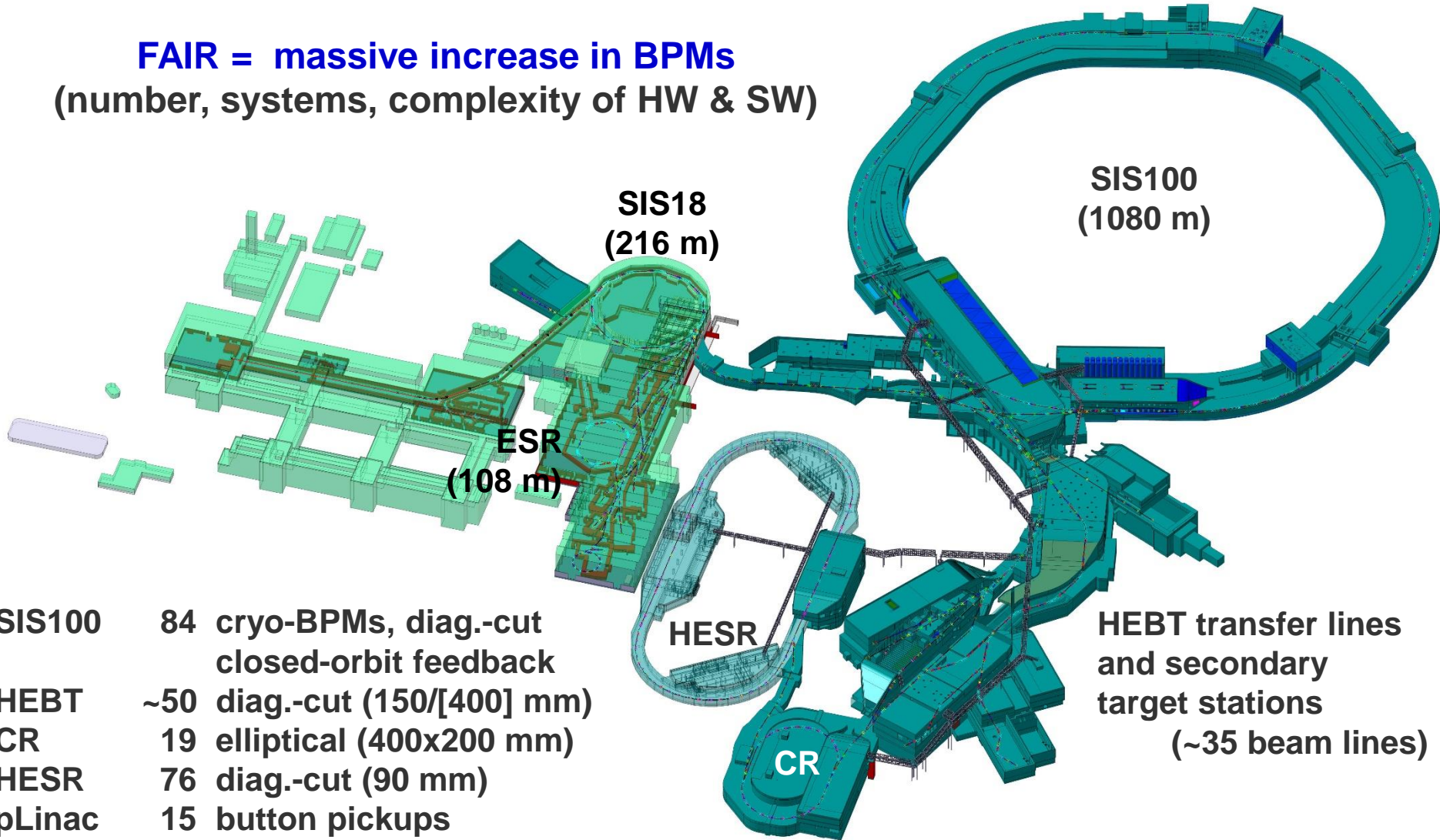
„High-energy“ BPMs at GSI

SIS18:	12	shoe-box (125 mm)
		closed-orbit FB
ESR:	12	shoe-box (250 mm)
Transfer SIS-ESR:	10	(not in regular operation)
CRYRING:	9	diagonal-cut cylinder (100 mm)

Motivation

BPM systems at FAIR

FAIR = massive increase in BPMs
 (number, systems, complexity of HW & SW)



SIS100	84 cryo-BPMs, diag.-cut closed-orbit feedback
HEBT	~50 diag.-cut (150/[400] mm)
CR	19 elliptical (400x200 mm)
HESR	76 diag.-cut (90 mm)
pLinac	15 button pickups

HEBT transfer lines and secondary target stations
 (~35 beam lines)

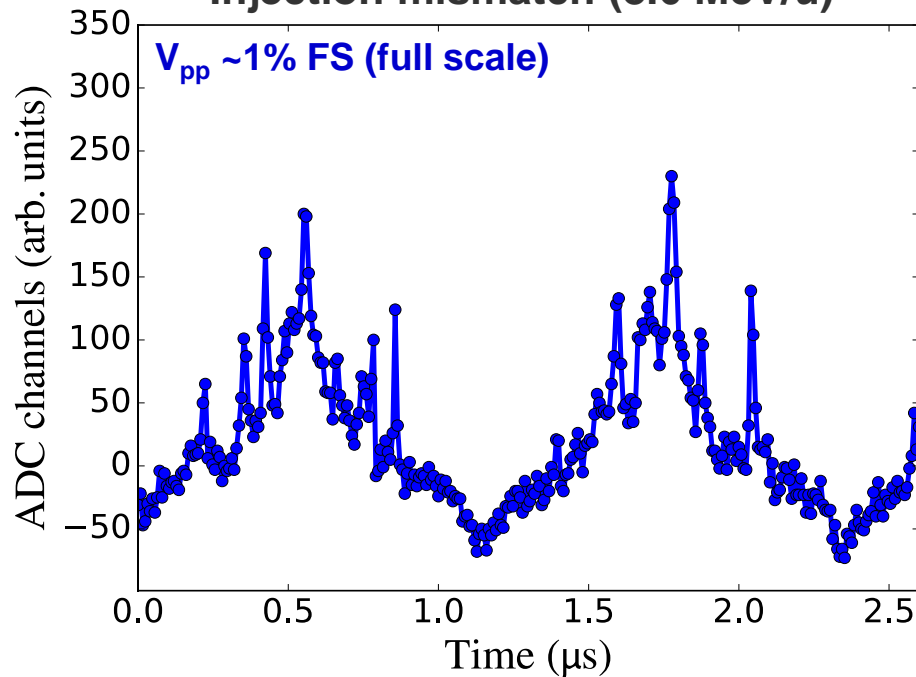
	SIS100 (100 Tm) pBar Production	CRYRING (1.44 Tm) March 2018 test
Beam	protons	Magnesium Mg ¹⁺
No. of particles	2.5x10 ¹³	~1x10 ^[6-8]
Energy	30 GeV	32 keV/u (max. energy)
Harmonic number	10 → 1	18
Pulse length	~500 – 50 ns	few μs
Electrode signal	~2000 Volt	μV – tens of mV
Front-end electronics	<ul style="list-style-type: none"> • 18:2 matching transformer • (-50 – 60) dB amplifier • BW = (0.04 – 7/55) MHz 	<ul style="list-style-type: none"> • High-impedance +40/60 dB amplifier • BW = (0.01 – 4/40) MHz
Data acquisition	250 MSa/s ADC (± 1 Volt, 16 bit, ENOB= 12)	125 MSa/s ADC (± 1 Volt, 16 bit)
RF gymnastics	bunch merging & compression (SIS100), bunch rotation & stochastic cooling (CR), longitudinal slip stacking (HESR)	

Position measurement

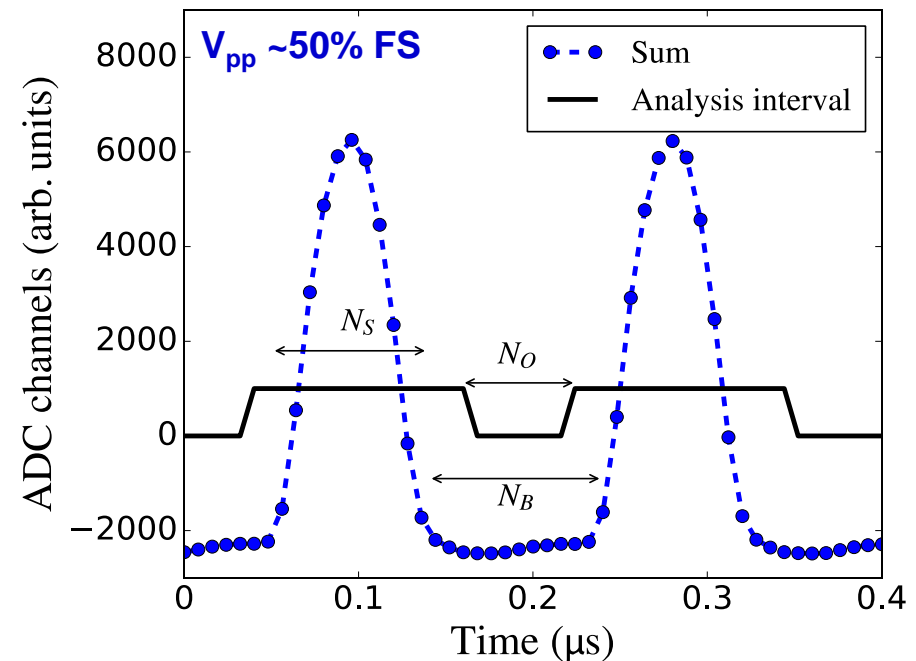
Real signals from SIS18

- DAQ hardware : 125 MSa/s, 14 bit ADC, ENOB~10 (Libera Hadron Platform A)
- TOPOS system: integral with baseline restoration and dual-threshold detection

Injection mismatch (8.6 MeV/u)



After acceleration to 300 MeV/u



- Bunch quality differs strongly throughout cycle: Baseline restoration or bunch detection difficult or unreliable. Ideally, new analysis is independent of bunch shape.
- General question: How can we predict the uncertainty of a bunch or orbit position?

Position measurement

Approach of evaluation

BPM: symmetric detector sensing an asymmetry between signals $S_{\{L,R,T,B\}}$
many geometries with „linear“ and non-linear response to beam offsets



variety of algorithms and approaches

difference-over-sum (Δ/Σ) logarithmic ratio amplitude to phase conversion ...



most methods can be expressed as functions of (Δ/Σ)

R. Shafer, Beam position monitoring, AIP Conf. Proc. 249 (1992)

focus on asymmetry (Δ/Σ)

$$x = (1/s_X) \cdot \frac{f(S_R) - f(S_L)}{f(S_R) + f(S_L)} \quad \text{with sensitivity } s_X \text{ (\%/mm)}$$

$f(S_R), f(S_L)$ is the scalar result of a function $f(\)$
operating on a set of data samples of right/left signal S_R / S_L

Position measurement

Approach of evaluation

Any function $f(c \cdot S) = c \cdot f(S)$ is eligible, even better: $f(c \cdot S + \text{offset}) = c \cdot f(S)$

But which candidate is „optimal“, at least for us?



peak value (S_{\max})	integral after baseline restoration (INT)
integral of absolute value $ S $	root-sum-square (RSS)	standard deviation (STD)

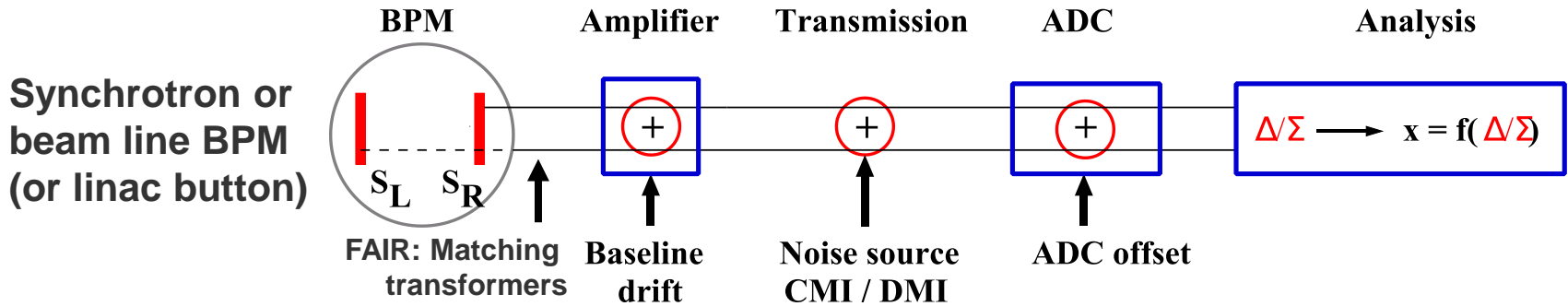
We overlooked STD initially !

define empirical requirements for “optimum” result



judge by robustness (behaviour, characteristics) & uncertainty

evaluate direct digitisation by a linear system in time-domain

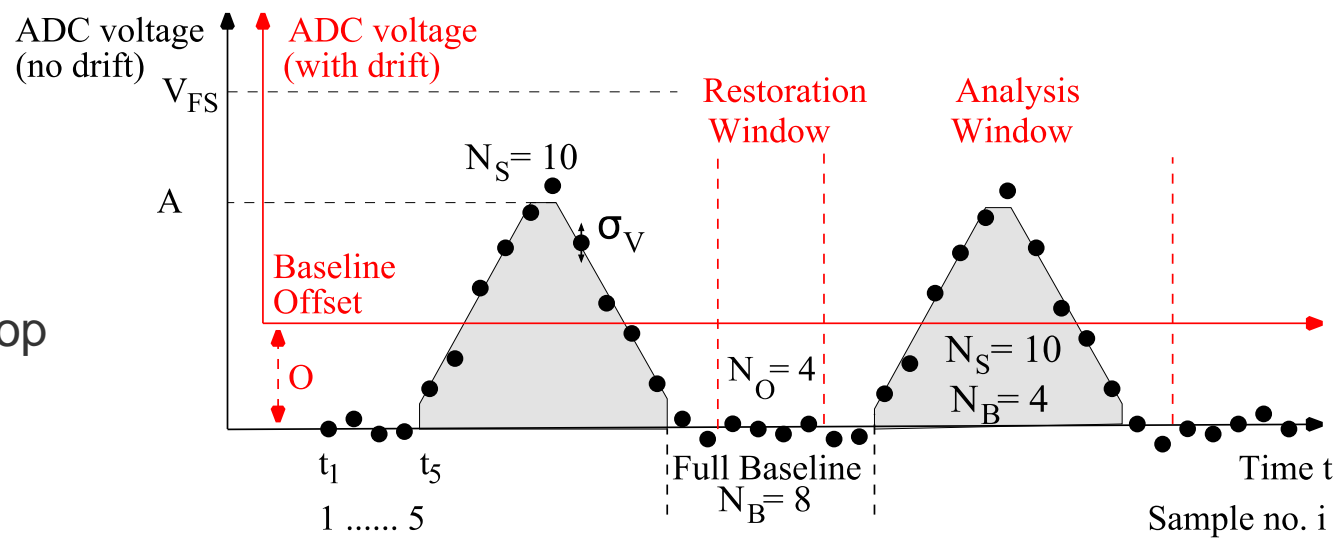


Time-domain model

“Classic” (Δ/Σ) approach

Statistical model: triangle (or square) of independent samples with uncertainty σ_V

- Analytical calculation
- for arbitrary position
 - with & w/o baseline droop
 - for INT, RSS, STD



Position uncertainty of centred beam for

- integral with baseline restoration
- root-sum-square ($RSS = \sqrt{\sum_i (S_i)^2}$)
- standard deviation (STD)

$$\sigma_{INT} = \frac{1}{s} \frac{\sqrt{N + (N^2/N_O)} \sigma_V}{\sqrt{2} I} \quad (N = N_S + N_B)$$

$$\sigma_{RSS} = \frac{1}{s} \frac{\sigma_V}{\sqrt{2} RSS}$$

Uncertainty depends on offset / baseline droop!

$$\sigma_{STD} = \frac{1}{s} \frac{\sigma_V}{\sqrt{2N} STD}$$

Time-domain model

Least-squares fit

Analytic evaluation of model signals in least-squares fit of (Δ, Σ) tuples

- position given by slope m , i.e. signal correlation
- uncertainty is a natural „by-product“

- $\Delta = m \cdot \Sigma$ (direct proportion)

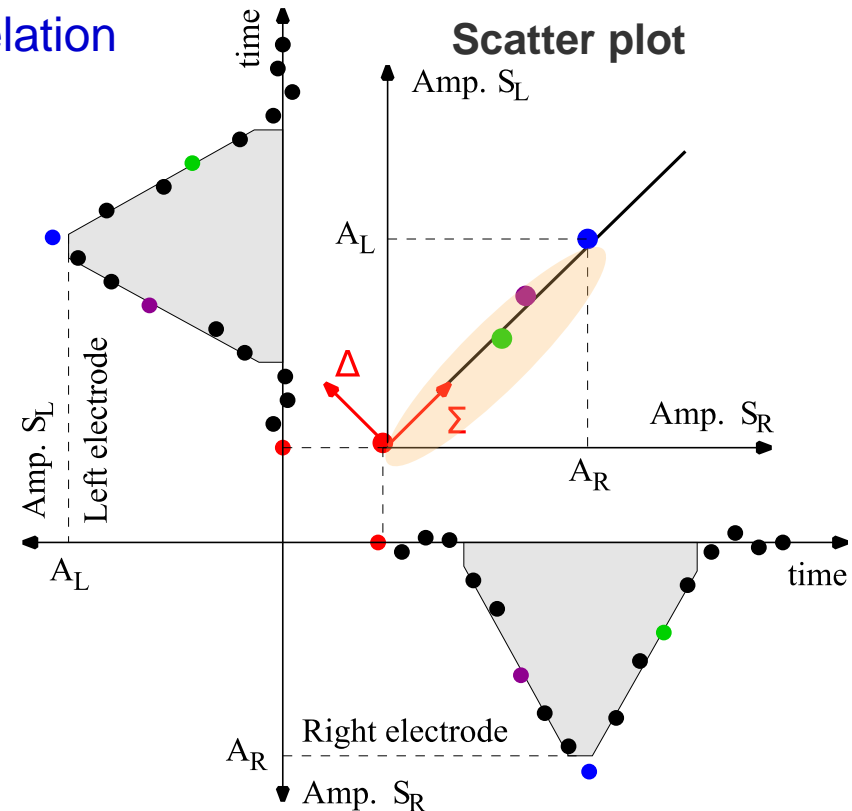
! note: $m = (x \cdot s)$!

$$\langle m \rangle = \frac{\overline{\Delta \cdot \Sigma}}{\overline{\Sigma^2}} \quad \sigma^2_{\langle m \rangle} = \frac{\sigma^2_{\Delta}}{N \overline{\Sigma^2}}$$

- $\Delta = m \cdot \Sigma + c$ (straight-line)

$$\langle m \rangle = \frac{\text{cov}(\Delta, \Sigma)}{\sigma^2_{\Sigma}} \quad \sigma^2_{\langle m \rangle} = \frac{\sigma^2_{\Delta}}{N \sigma^2_{\Sigma}}$$

$$\langle c \rangle = \bar{\Delta} - \langle m \rangle \bar{\Sigma}$$



Result:

- Integral with baseline restoration: $\langle c \rangle = 0 \Rightarrow \langle m \rangle = \bar{\Delta} / \bar{\Sigma}$
- For centred beams, uncertainties are identical to those of classical approach,

e.g. for direct proportion:
$$\sigma^2_{\langle m \rangle} = \frac{\sigma^2_{\Delta}}{N \overline{\Sigma^2}} = \frac{\sigma^2_{\Delta}}{\Sigma(\Sigma_i)^2} = \frac{2 \sigma^2_V}{\Sigma(2 S_i)^2} = \frac{\sigma^2_V}{2 R S S^2} = (s \cdot \sigma)^2_{RSS}$$

Time-domain model

Analysis properties

Classical approach	Integral	RSS	STD
Least-squares	constrained fit	direct proportion	straight line
Coordinate system	absolute	absolute	relative / floating
Position weight	Σ	Σ^2	$(\Sigma - \bar{\Sigma})^2$
Need for			
- baseline restoration	yes	no	no
- ADC zero adjustment	no	yes	no
Tolerance to			
- AC coupling (baseline droop)	no	yes	yes
- random offsets	no	no	yes
- low-frequency distortion (for small amplitudes)	no	no	$v < 10 \frac{MHz}{N}$ (rough rule of thumb)

Time-domain model

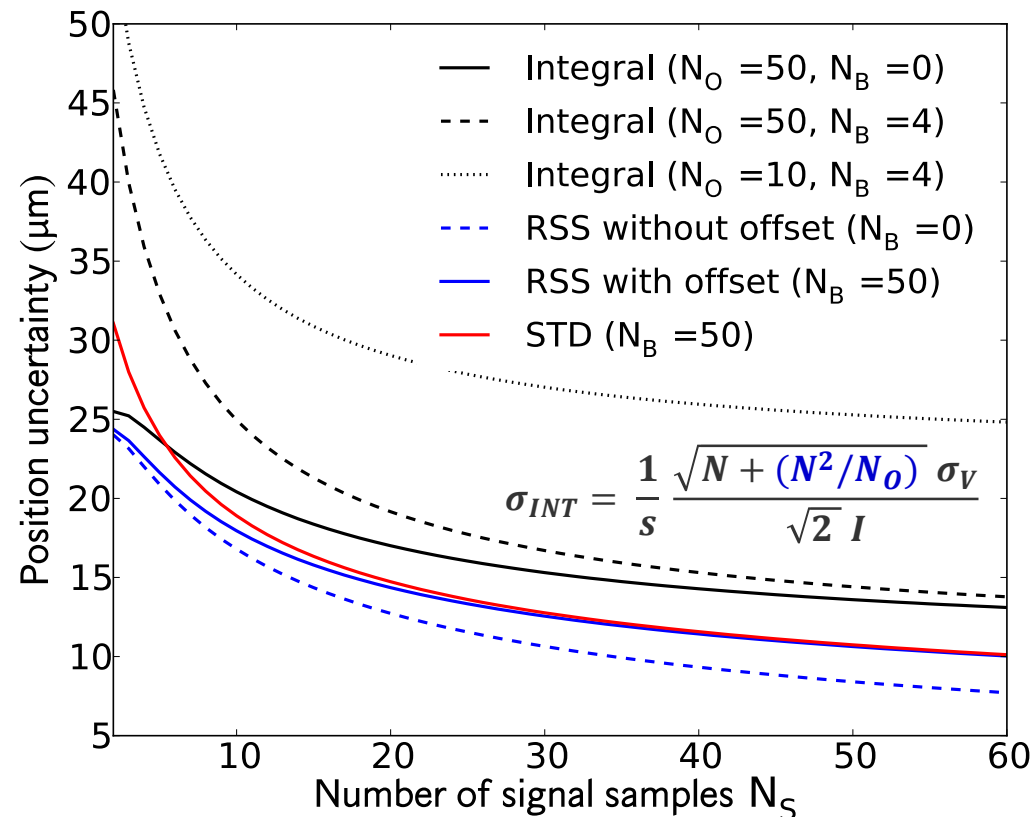
Achievable resolution

- Uncertainty comparison for centred, triangular pulse
- Example: straight-line fit

$$\sigma_{\langle m \rangle} = \sqrt{\frac{3}{2}} \left(\frac{\sigma_V}{A V_{FS}} \right) \sqrt{\frac{(N_S + N_B)}{(N_S + 2) \left(\frac{1}{4} N_S + N_B \right)}}$$

- Analysis parameters
 - no. of signal samples N_S
 - no. of baseline samples N_B
- SIS18 hardware parameters
 - noise $\sigma_V = 1$ mV
 - full scale $V_{FS} = 2$ Volt
 - signal amplitude $A = 0.5$ FS
 - sensitivity $s_V = 2$ (%/mm)

equiv. to diag.-cut cylinder ($s = 1/r$)
of $r = 50$ mm radius



FAIR: 250 MSa/s is sufficient for smallest 50 ns pulse length, yielding ~ 13 samples (requirement $\sigma_{x/y} < 0.1$ mm)

Experiments (flat top)

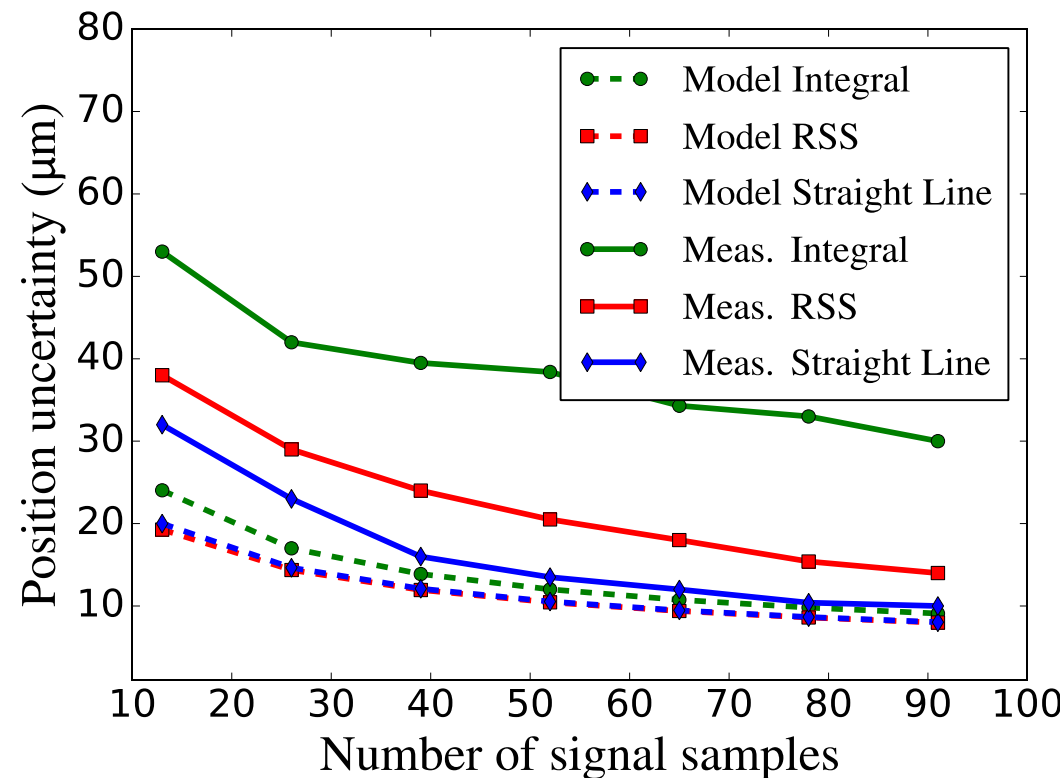
Uncertainty comparison

Experiment conditions

- Data taken after acceleration to 300 MeV/u
- Vertical BPM: pulse shape ($N_S \sim 13$) as in slide 8 ($A = 0.5$), sensitivity $s_V = 2$ (%/mm)
- **Analysis:** Include increasing number of bunches to statistically simulate larger number of signal samples, **for a case where expected uncertainties are similar**

Result

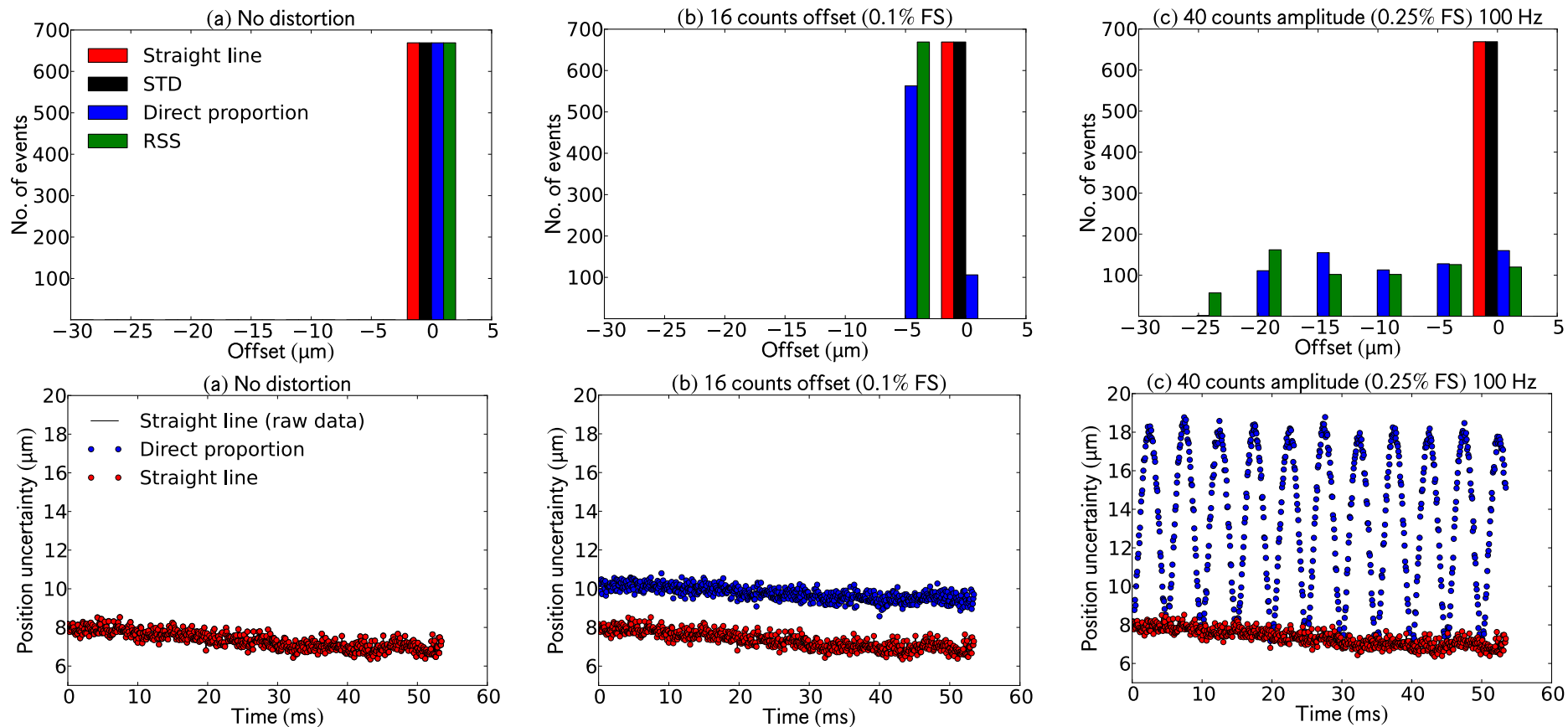
- Simple model seems to provide reasonable estimates
- Only straight-line fit approaches theoretical limit for $N_S > 40$
- $\sigma_y(\text{short bunch}) < 0.05$ mm
or $\sigma_m = (\sigma_y \cdot s) < 1 \times 10^{-3}$



Experiments (flat top)

Orbit uncertainty & robustness

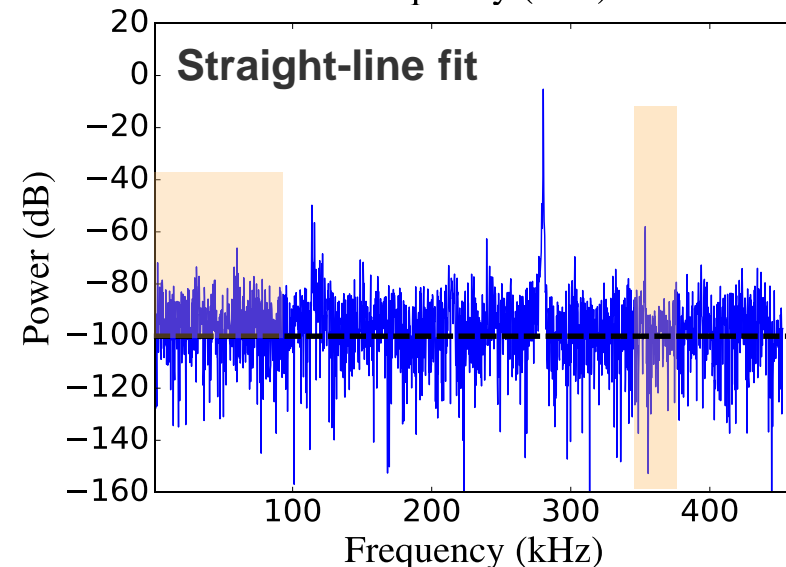
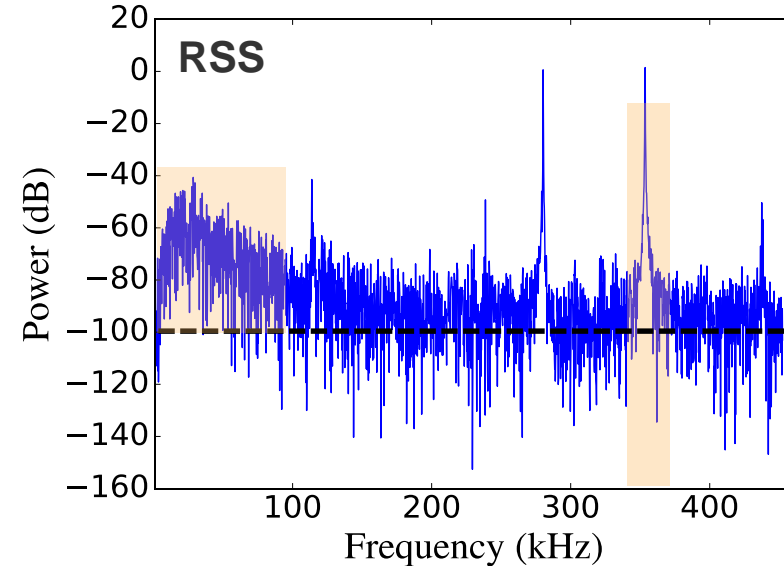
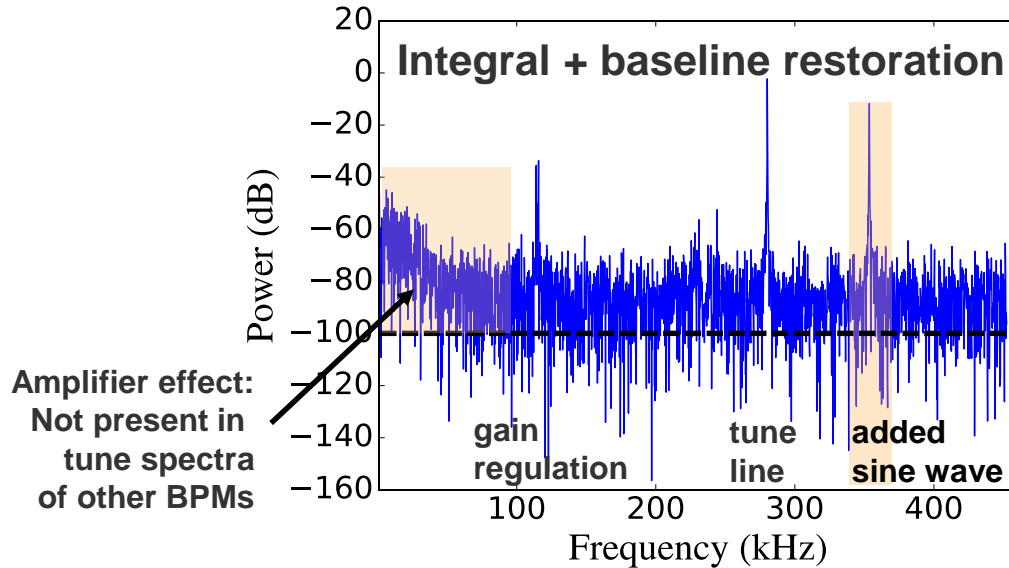
- 300 MeV/u data (hor. BPM, $s_H = 0.8\%/mm$, 10000 samples/fit ~ 75 turns, $A = 0.3$)
- Add distortion to one electrode signal in analysis and calculate offset to raw data



Result: Orbit uncertainty $< 10 \mu\text{m}$; RSS and direct proportion sensitive to distortions

Experiments (flat top)

Horizontal tune & robustness



- Tune measurement: 2000 turns, 20 samples/fit
 $v = 280$ kHz ($v_{ref} = 905$ kHz)
- 112, 224 kHz by amplifier gain regulation loop
- Add 353 kHz sine wave of 0.15% FS amplitude wave to one BPM electrode in analysis

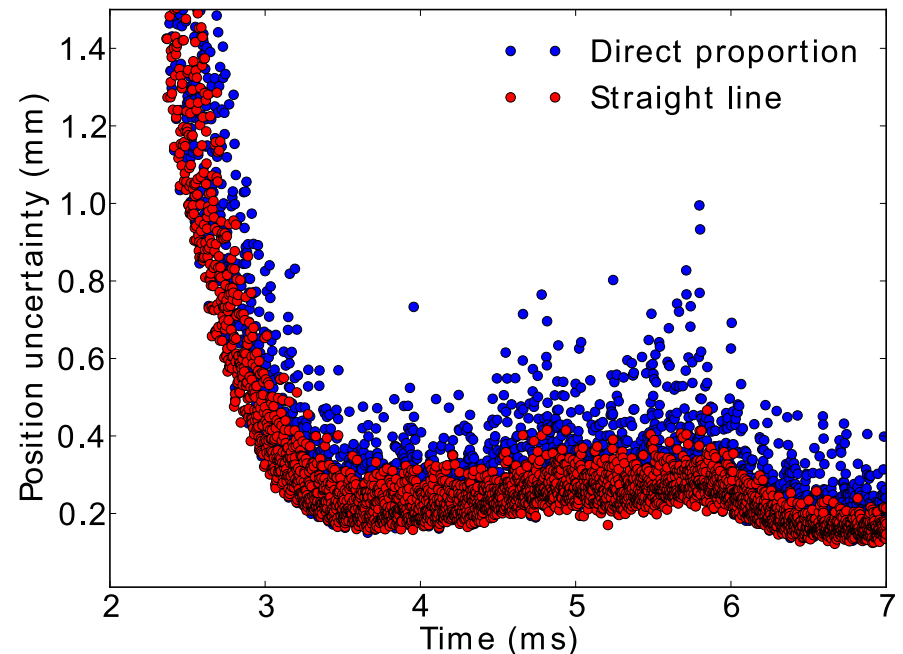
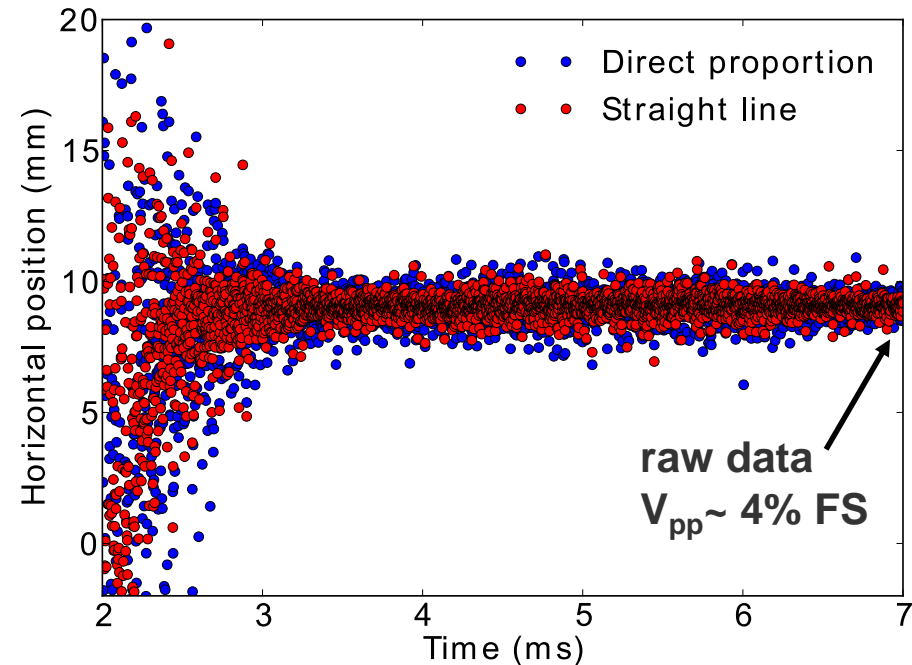
Result: Straight-line fit able to suppress added interference and real amplifier noise (< 100 kHz)

rule of thumb: $v < 10 \frac{MHz}{N} = 500$ kHz

Experiments (start of cycle)

Orbit by asynchronous mode

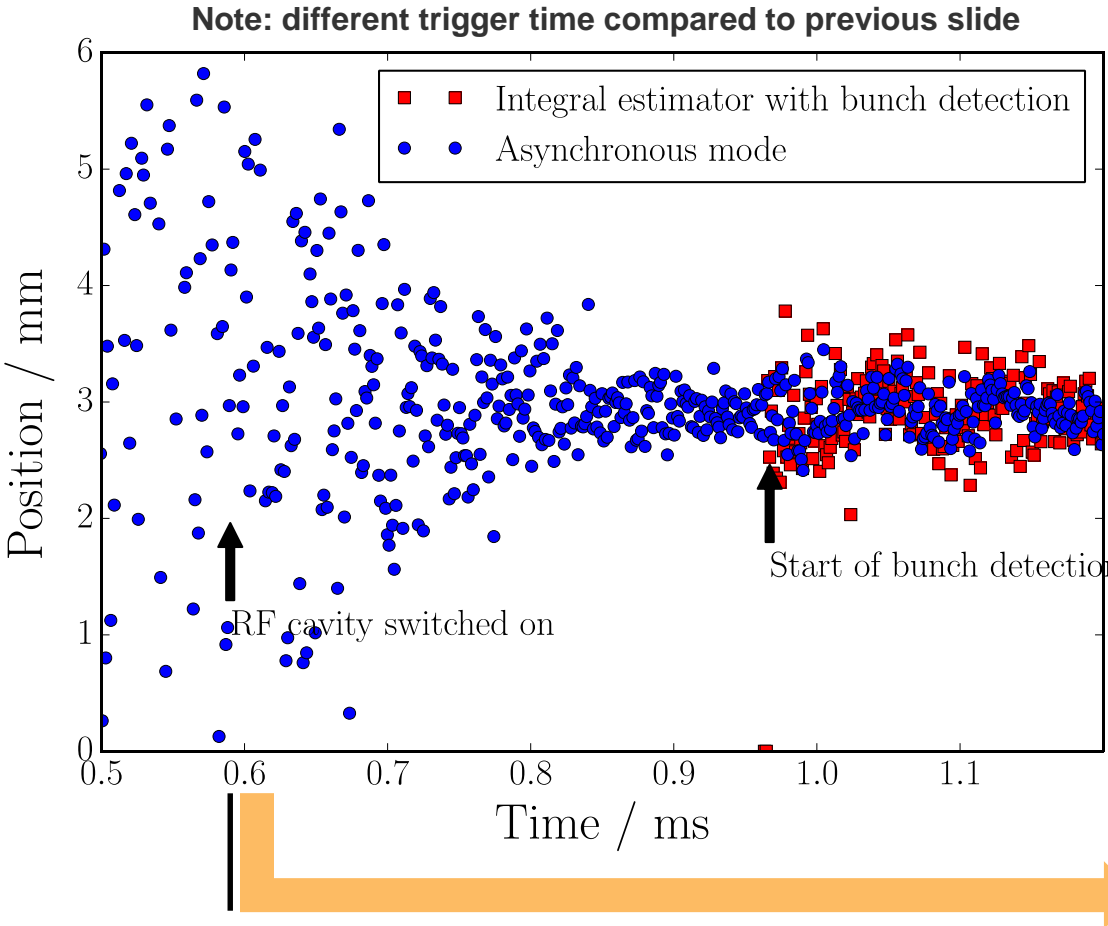
- **Asynchronous mode:** Data stream of fit results for fixed number of samples
200 samples/fit = 625 kHz stream (3125 positions in 5 ms)
„observer“ mode: no external signals, no bunch detection,...
- Check positions after multi-turn injection in SIS18 for direct prop. and straight-line



Result: RSS yields slightly larger jitter, its uncertainty shows outliers / asymmetric tail

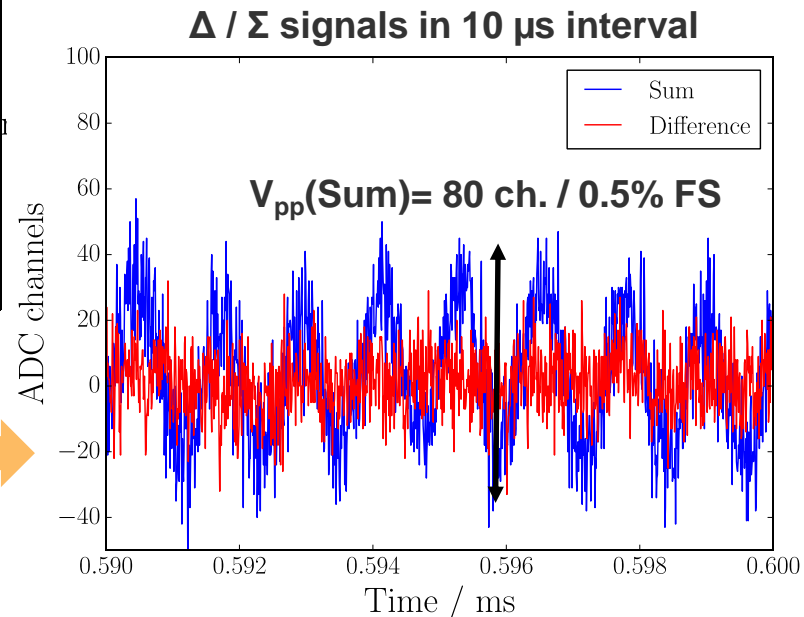
Experiments (start of cycle)

Asynchronous mode vs SIS18 TOPOS

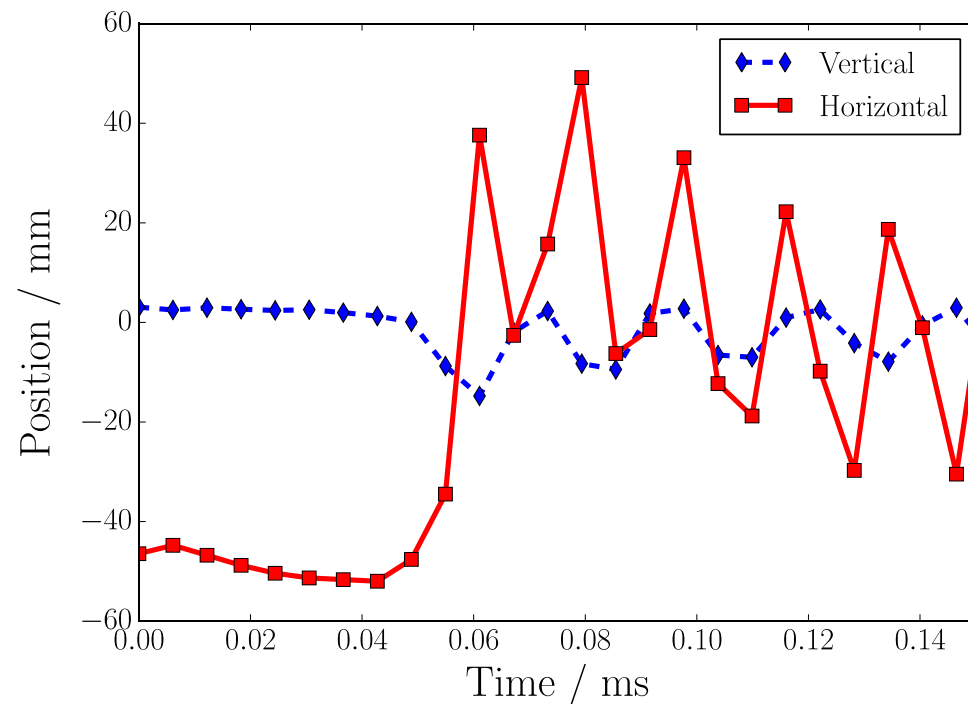
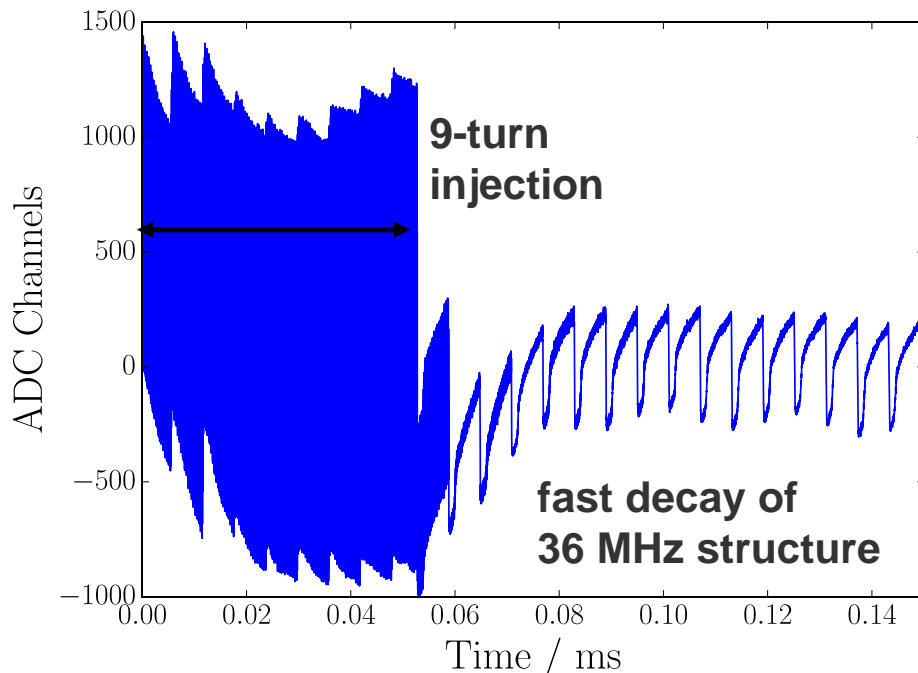


Result:

- Asynchronous mode „locks“ quickly onto bunch signal and exceeds TOPOS performance
- Dual-threshold detection needs minimum bunch quality to start tracking of positions



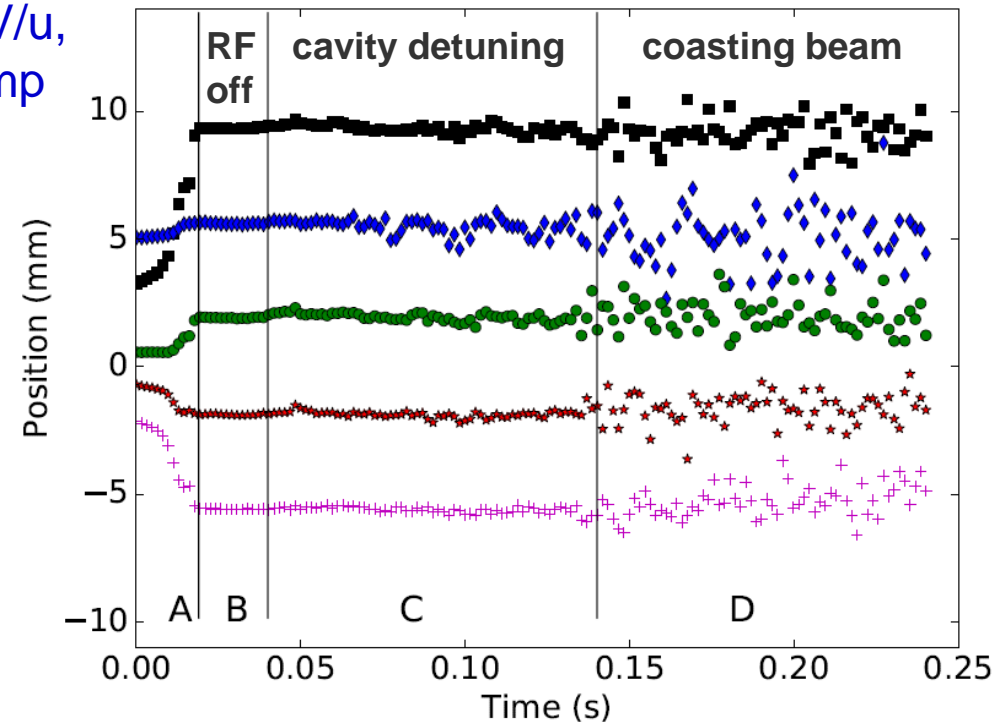
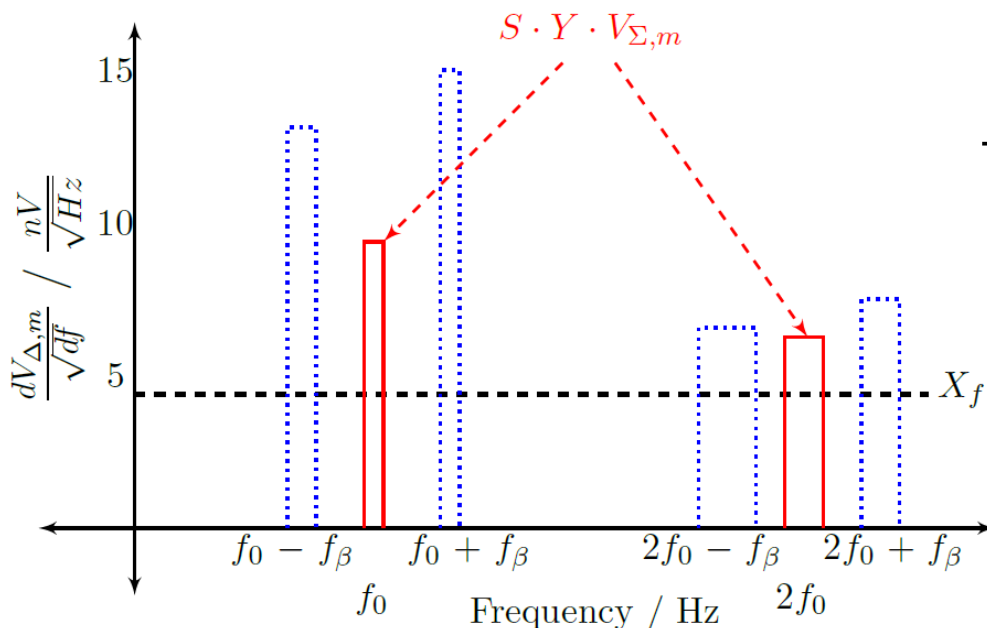
- Multi-turn injection from UNILAC injector
- Turn-by-turn position evaluation using standard deviation (STD)
- Last injected turn dominates position due to fast decay of structure
- Reproduction of design offset due to injection bumper



Experiments

“Exotic“ applications

- Coasting high-intensity beam (400 MeV/u, Xe⁴³⁺, 11 mA DC current) with orbit bump
- Position calculation by straight-line fit after FFT filter on revolution frequency and higher harmonics (up to 20)
- Confirmation by IPM profile monitor



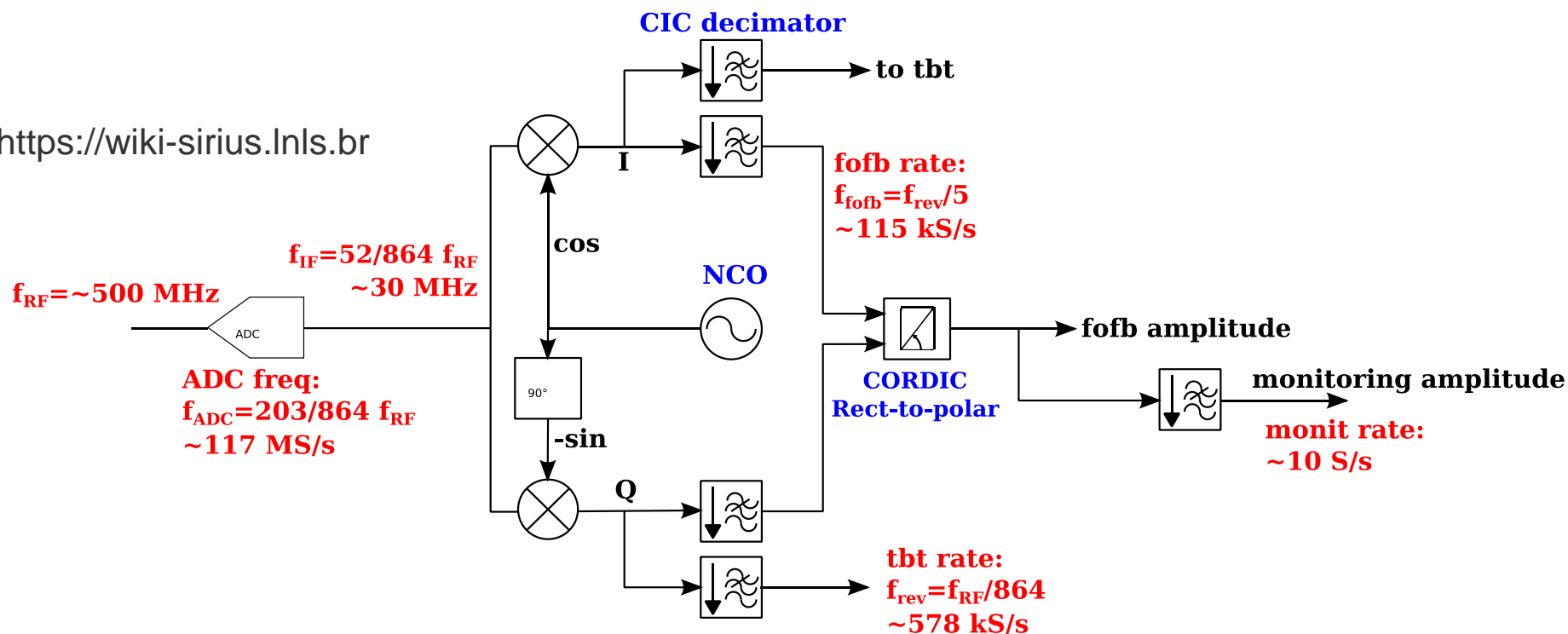
Region A: Amplifier overload
 (\Rightarrow positions not correct)
 for all position, but 5 mm data
 where we used a smaller gain!

Simulation

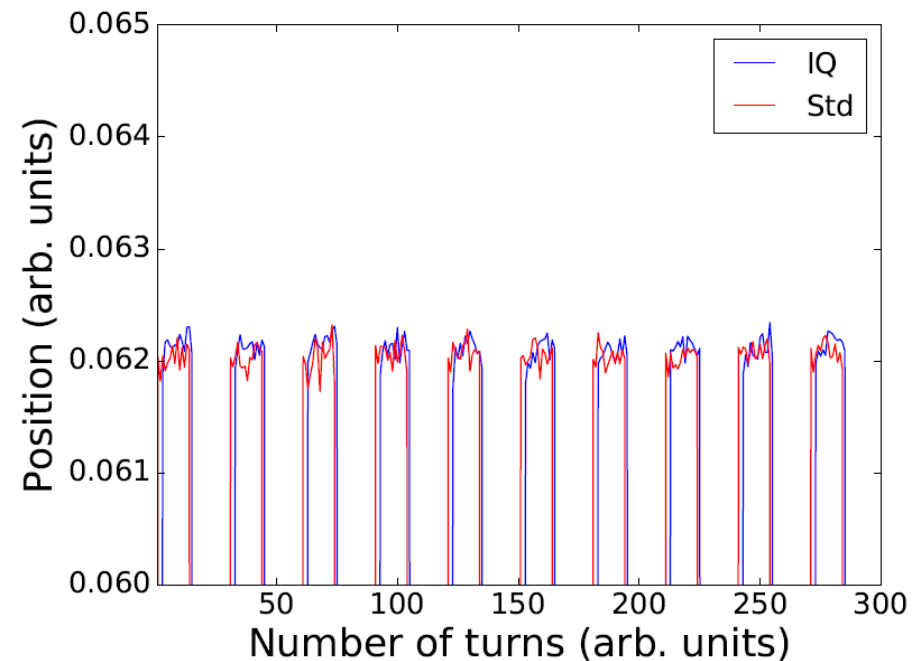
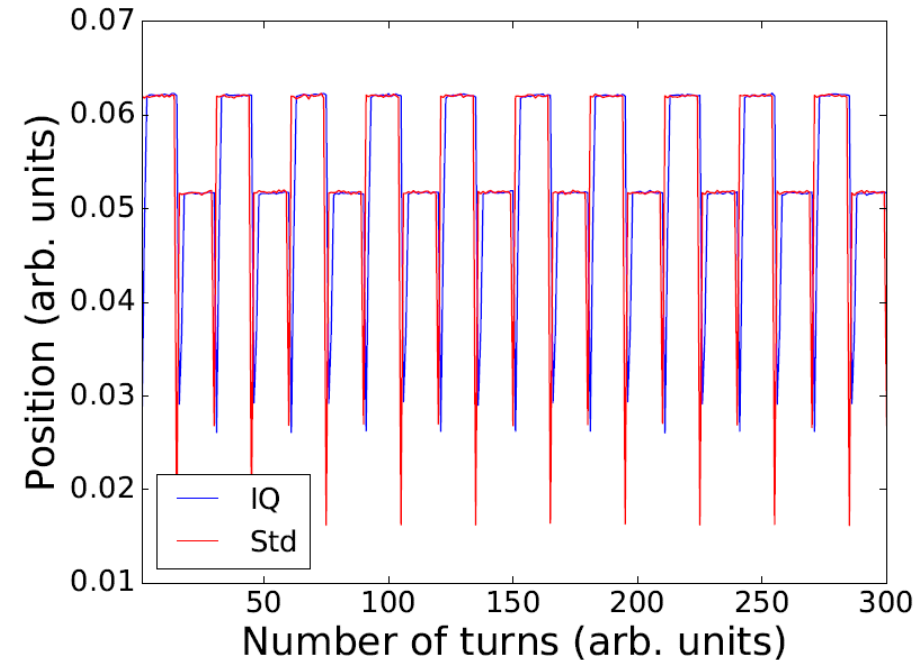
Comparison to IQ demodulation

- BPM system for Sirius light source (by courtesy of D. Tavares, LNLs)
- Simulated ADC raw data analysed as turn-by-turn blocks using STD
- Results of both approaches in good agreement

<https://wiki-sirius.lnl.s.br>



- BPM system for Sirius light source (by courtesy of D. Tavares, LNLS)
- Simulated ADC raw data analysed as turn-by-turn blocks using STD
- Results of both approaches in good agreement



Conclusion & Outlook

- Review of position analysis for a linear system in time-domain
 - “Practical” statistical model: position uncertainty & robustness
 - Straight-line fit (or STD) provides good robustness and resolution, matching model prediction (more information: A. Reiter, S. Singh, NIM A 890 (1018) 18-27 and “arXiv 1609.01332”)
- New approach has led to significant improvements (and some new applications)
 - smaller measurement uncertainty
 - orbit position stream via asynchronous mode in extended interval in cycle
 - analysis of tune, multi-turn injection and coasting beam pilot test
 - was compared to simulated data for Sirius BPM system
 - can be applied to linac buttons
- Development status / realisation
 - CRYRING: Straight-line fit (and averaging) stage implemented on FPGA
bunch-by-bunch position via RF clock signal
 - SIS18: Direct proportion
 - FAIR: Tests at SIS18 (incl. COFB) and ESR, position calculation options:
bunch detection & integral / narrow-band analysis / **user-defined calc.**

Finally, ...

I show some room for improvement

and thank the organisers for the invitation ...



..... and everyone of you for your kind attention !

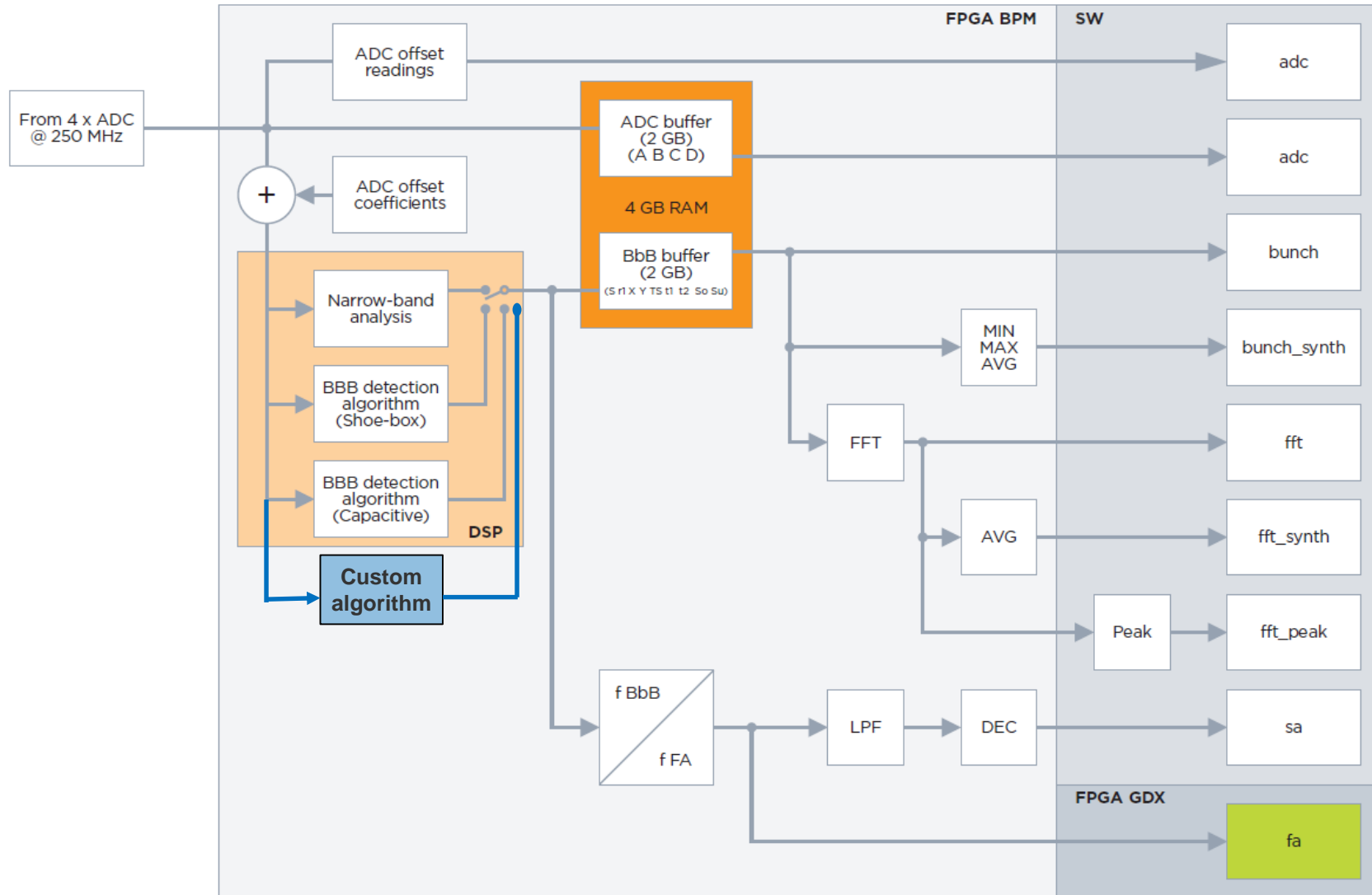
Spare slides

Rendering of FAIR Research Campus



FAIR BPM system

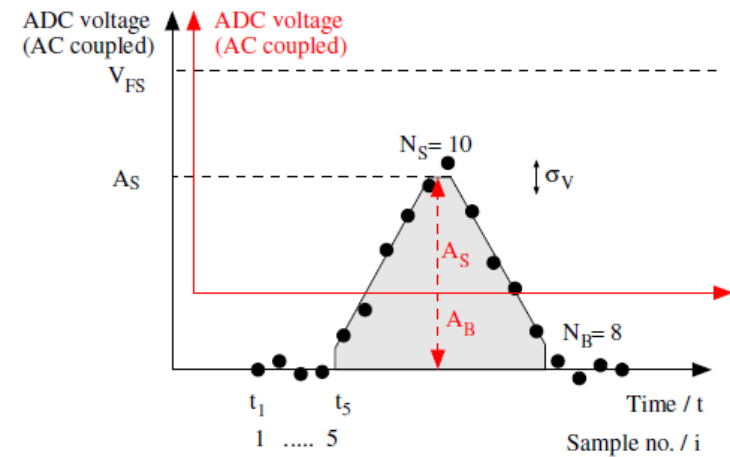
Data paths



Time-domain model

Analytic formulae

Triangular pulse with baseline offset due to cyclic pulses
Turn-by-turn analysis ($h=1$):
Analyse all signals in one period N_S and N_B
Amplitudes refer to black coordinate system without offset



Integral:

$$\frac{\sigma_{\langle x \rangle}}{r} = \frac{4 \cdot \sigma_V}{V_{FS}} \frac{\sqrt{A_L^2 + A_R^2}}{(A_L + A_R)^2} \cdot \frac{1}{N_S} \sqrt{(N_S + N_B) + \frac{(N_S + N_B)^2}{N_O}}$$

RSS: Balanced system - N_B samples between pulses

$$\frac{\sigma_{\langle x \rangle}}{r} \approx \frac{2\sqrt{3} \cdot \sigma_V}{V_{FS}} \cdot \frac{\sqrt{A_L^2 + A_R^2}}{(A_L + A_R)^2} \cdot \sqrt{\frac{N_S(N_S + N_B)}{(N_S + 2)(\frac{1}{4}N_S^2 + N_S N_B + N_B + \frac{1}{4}N_S)}}$$

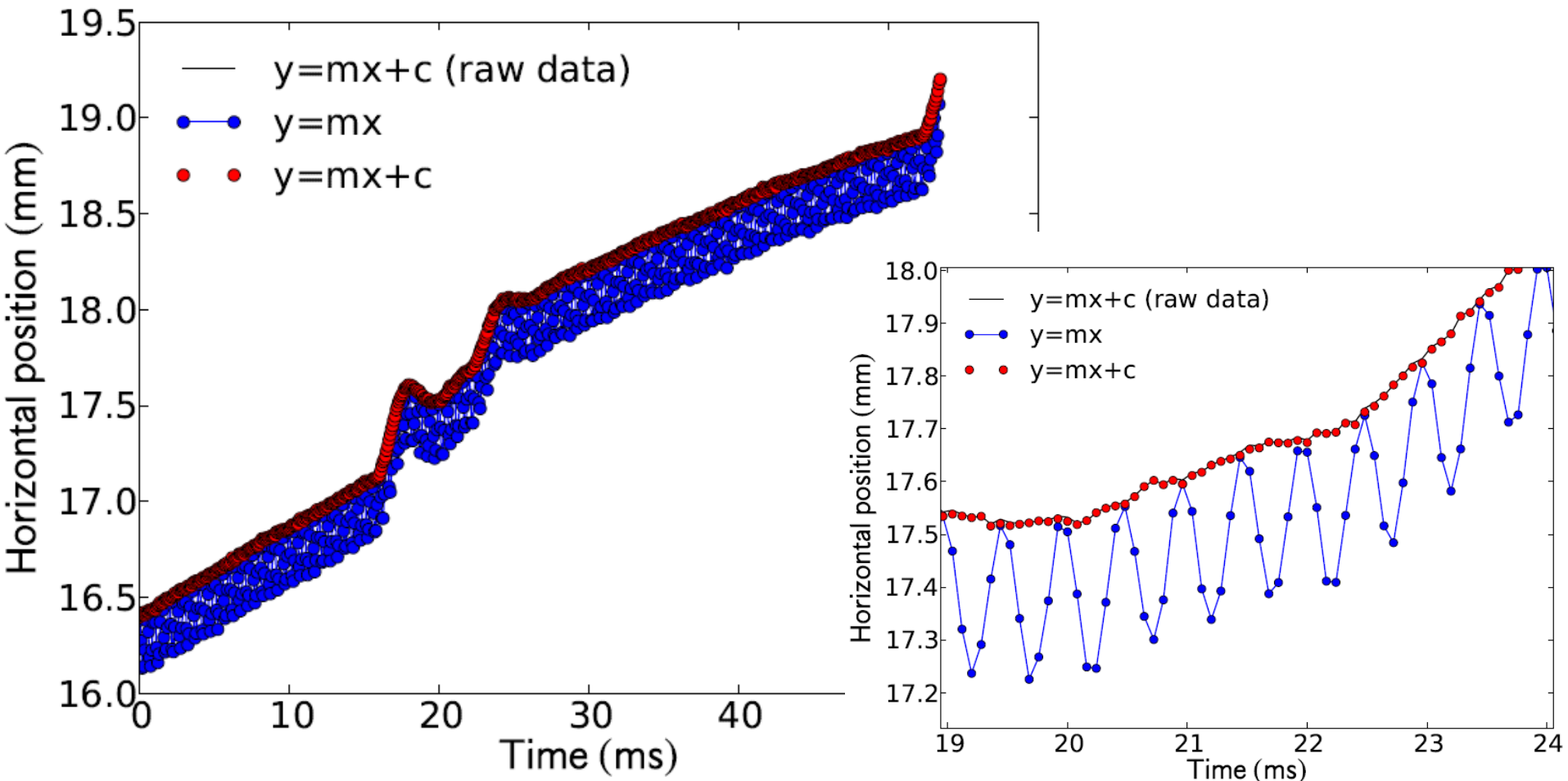
Fit: Identical for RSS for leading terms of N_S and N_B

$$\frac{\sigma_{\langle x \rangle}}{r} \approx \frac{2\sqrt{3} \cdot \sigma_V}{V_{FS}} \cdot \frac{\sqrt{A_L^2 + A_R^2}}{(A_L + A_R)^2} \cdot \sqrt{\frac{N_S(N_S + N_B)}{(N_S + 2)(\frac{1}{4}N_S^2 + N_S N_B)}}$$

Experiments (flat top)

SIS18 cycle

- Signal amplitude 30% FS, 10000 samples / fit ($v_{cut} \sim 1$ kHz)
- Added distortion: 1 kHz sine wave of 160 ch. amplitude (1% FS)

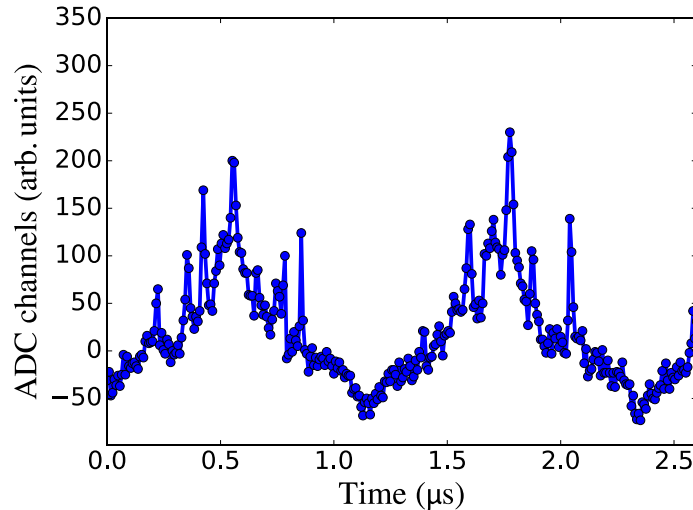


Signal Examples

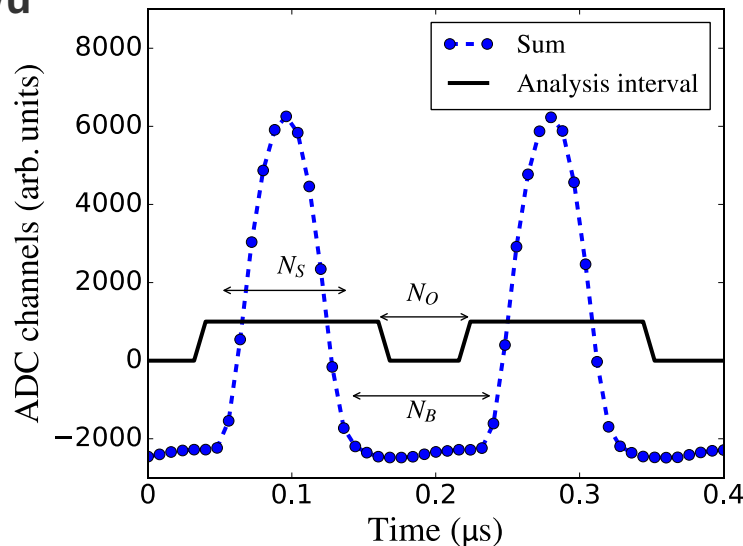
SIS18: 125 MSa/s, 14 bit ADC, Platform A

CRYRING: 125 MSa/s μ TCA DAQ

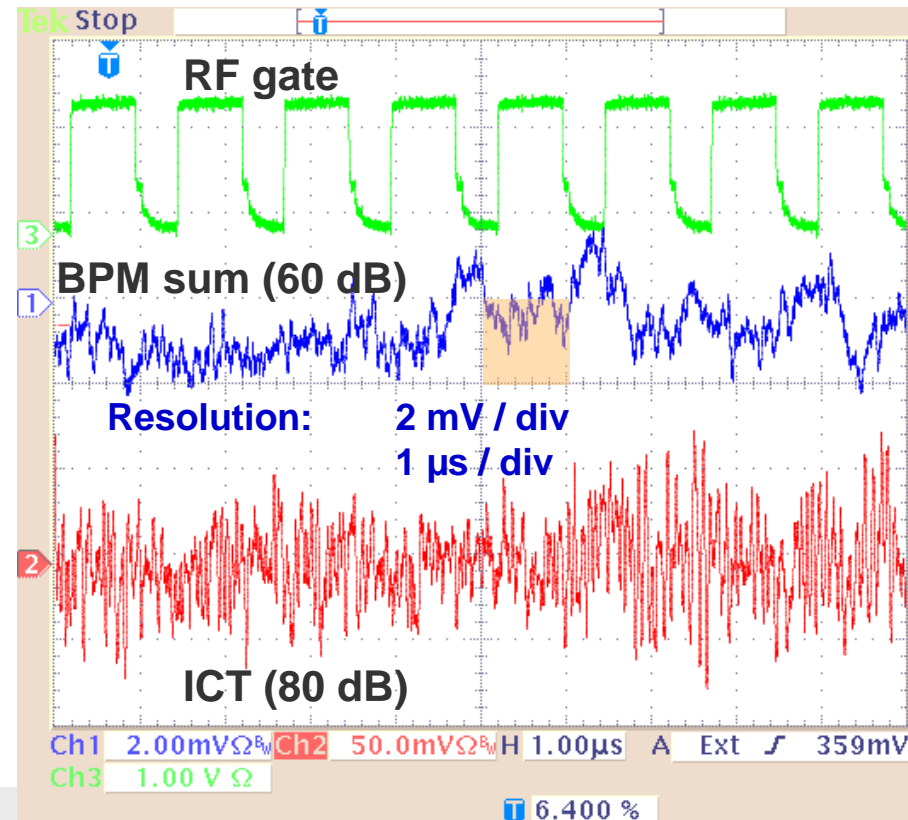
Injection mismatch



300 MeV/u



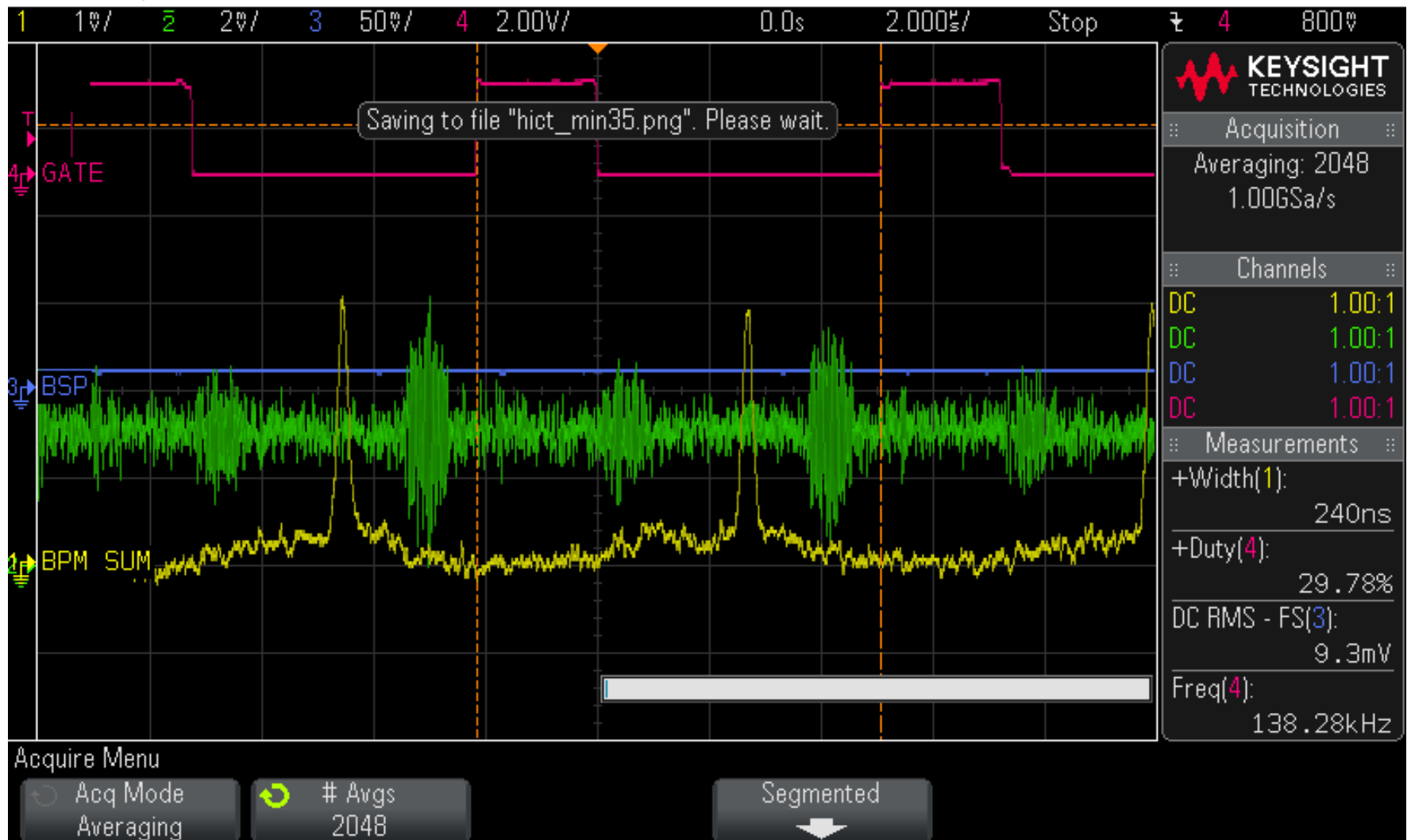
Mg+ „bunches“ after acceleration
gain +60 dB, 4 MHz filter



MSO-X 2024A, MY58101875: Sat Nov 10 03:45:44 2018



MSO-X 2024A, MY58101875: Sat Nov 10 03:48:21 2018



MSO-X 2024A, MY58101875: Sat Nov 10 04:07:36 2018



Our latest child

CRYRING – a low energy synchrotron

- 1.44 Tm storage ring
- 54 m circumference
- mainly for atomic physics
- Storage of cooled heavy ions from experimental storage ring ESR
- Electron cooler and laser facility
- Research opportunities to study interaction of heavy ions, electrons and photons

... and other reasearch

Atomic

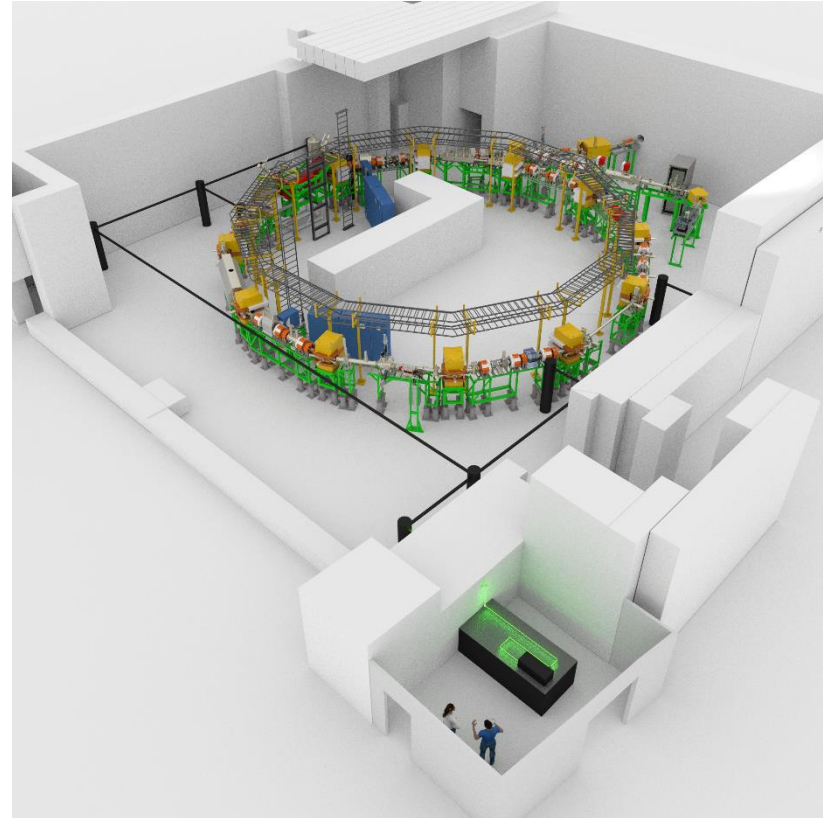
Nuclear and particle

Material Science

Accelerator Physics

...

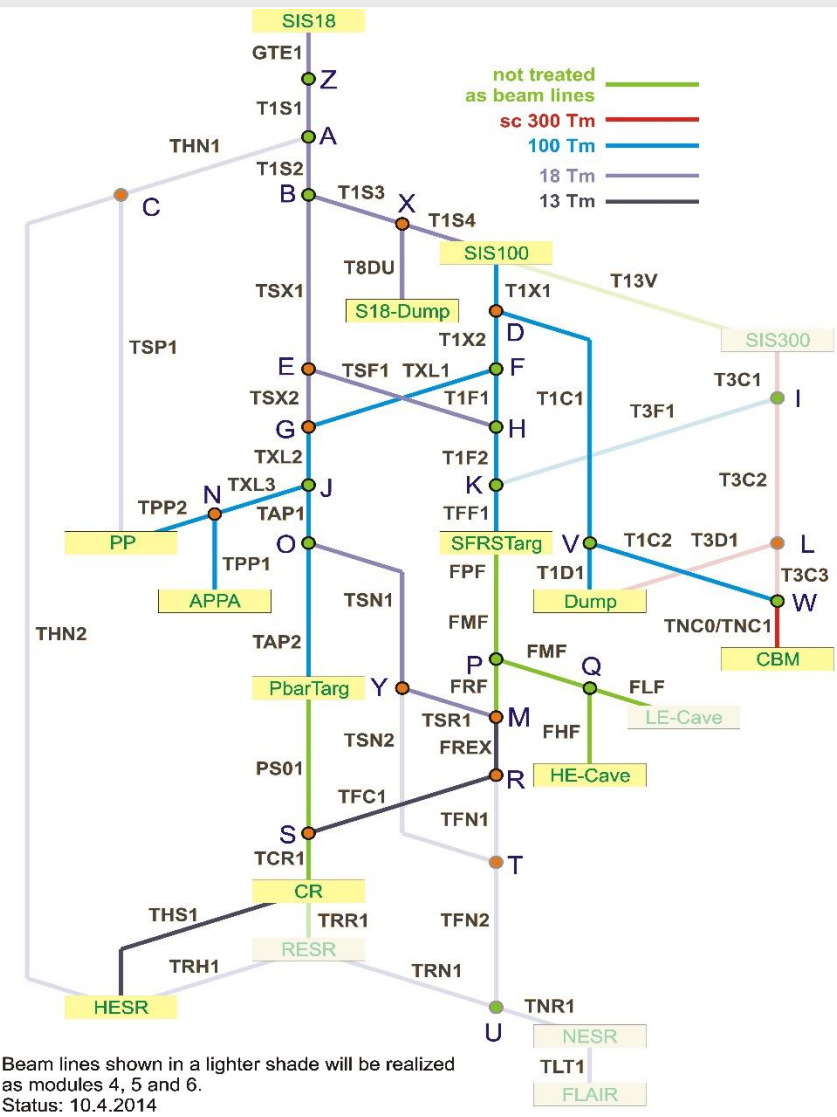
...



Parallel Operation New Beam Line Network

- „Design ions“: proton and $U^{(28 / 73 / 92)}$
- Other ions: C, N, Ne, Ar, Ni, Kr, Xe, Au, etc.
- SIS18 & SIS100 beams for users
- Slow / fast extraction: 10-30 s / 30-100 ns

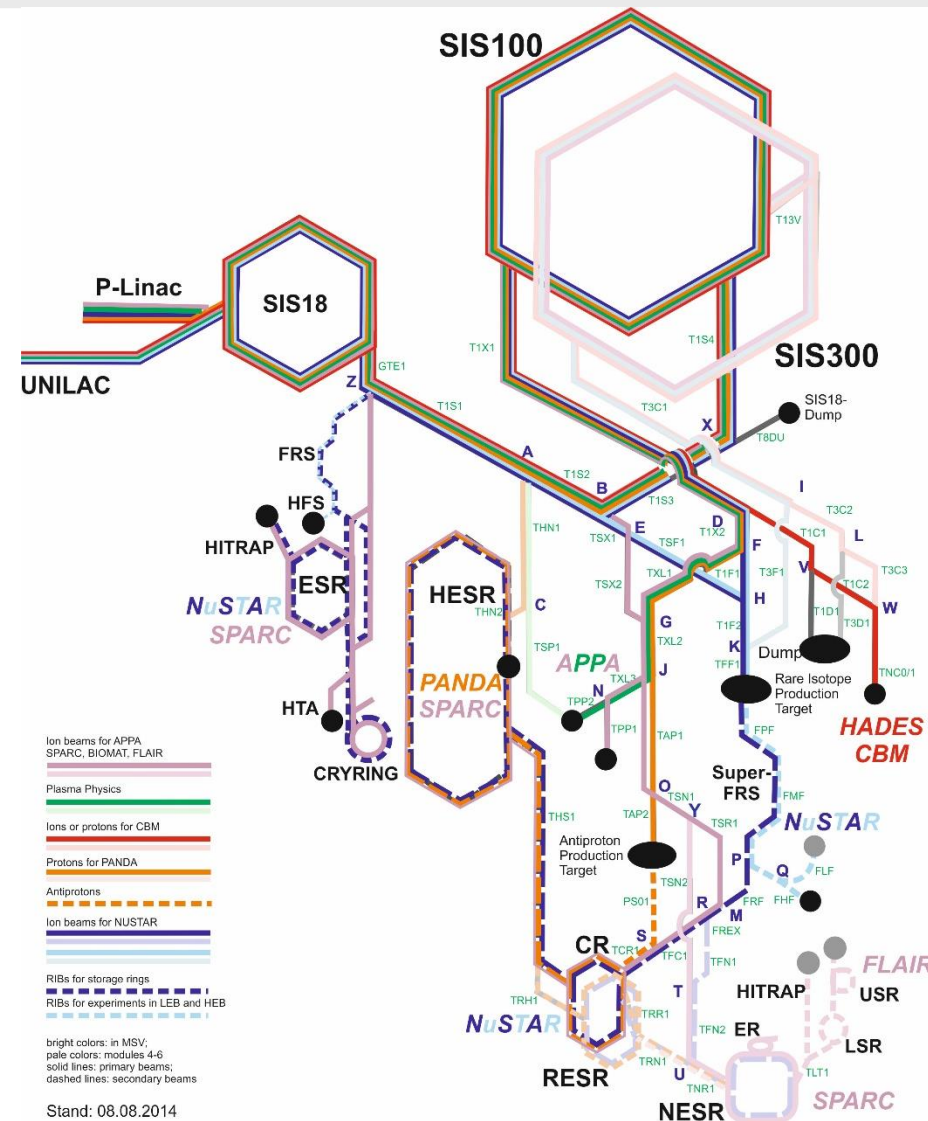
- NuSTAR
 - U^{28+} ; 1 GeV/u, 3×10^{11} to fixed target
 - U^{28+} ; 1 GeV/u, 70 ns, 5×10^{11} to CR
- CBM
 - U^{92+} ; 10 GeV/u; 1.5×10^{10} ; 10 s spill
- pBar Production
 - p ; 30 GeV; 2.5×10^{13} ; 50 ns
- APPA
 - BioMat, SPARC: highly charged ions up to 10 GeV/u; slow extraction
 - Plasma Physics: see NuSTAR; 1 shot every 2 minutes (PHELIX laser)
- FLAIR (ESR/CRYRING/HITRAP)
 - Highly charge ions
 - Deceleration 4 MeV/u – 500 keV/u – 6 keV/u
 - Trapping of ions for experiments



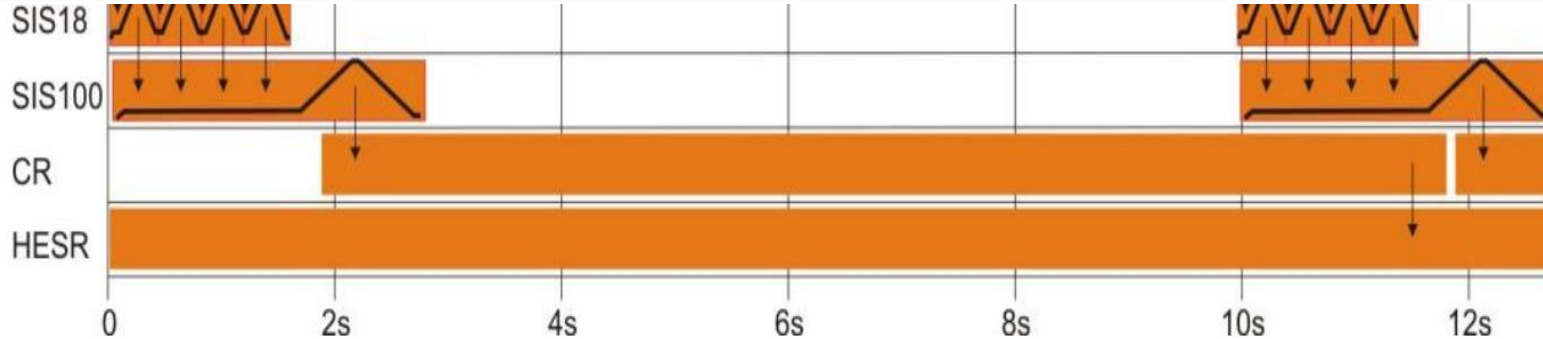
Green spots at junctions indicate that the connection going straight is open when the junction dipole is switched off.

Parallel Operation The Underground Map

- Parallel operation to supply several users simultaneously
- Complex pattern of beam chains to be implemented
- White Rabbit Timing system (CERN) and BuTiS Bunch Timing system BuTiS (GSI) and an effective beam scheduling logic will be most crucial
- More than 60 timing domains



pBar Beam Production Beam Pattern



- Design luminosity $L = 2 \times 10^{32} \text{ cm}^{-2} \text{ s}^{-1}$ (100 mb total inelastic pBar-p cross section: $2 \times 10^7 \text{ s}^{-1}$ consumption)
- p-Linac produces 4 pulses of 70 MeV proton beam in $\sim 1.2 \text{ s}$ (2.5 Hz)
- SIS18 accelerates each pulse to 4 GeV and needs $\sim 1.6 \text{ s}$, including pre- and postprocessing
- SIS100
 - Injection of 4 batches from SIS18 needs $\sim 1.2 \text{ s}$, yields $\sim 2 \times 10^{13}$ protons
 - Merging into one single bunch, acceleration to 28.8 GeV/u
 - Compression to bunch length of $\sim 30 \text{ ns}$
 - Cycle length $\sim 2.7 \text{ s}$ in MSV with reduced no. of RF cavities, 2.55 s in final setup
- Cooling in CR
 - Bunch rotation to reduce momentum spread ($\Delta p/p \pm 3\%$)
 - Adiabatic de-bunching
 - Stochastic cooling down to $p/p 0.1\%$, Emittance(h,v) $\sim 5 \text{ pi mm mrad}$
 - Repetition time 10 s
- Accumulation in HESR
 - Accumulation of 1×10^{10} antiprotons in 1000 s
 - Decelerate/accelerate
 - Beam on target for $\sim 1000 \text{ s}$

pBar Beam Production

Example Beam Chain

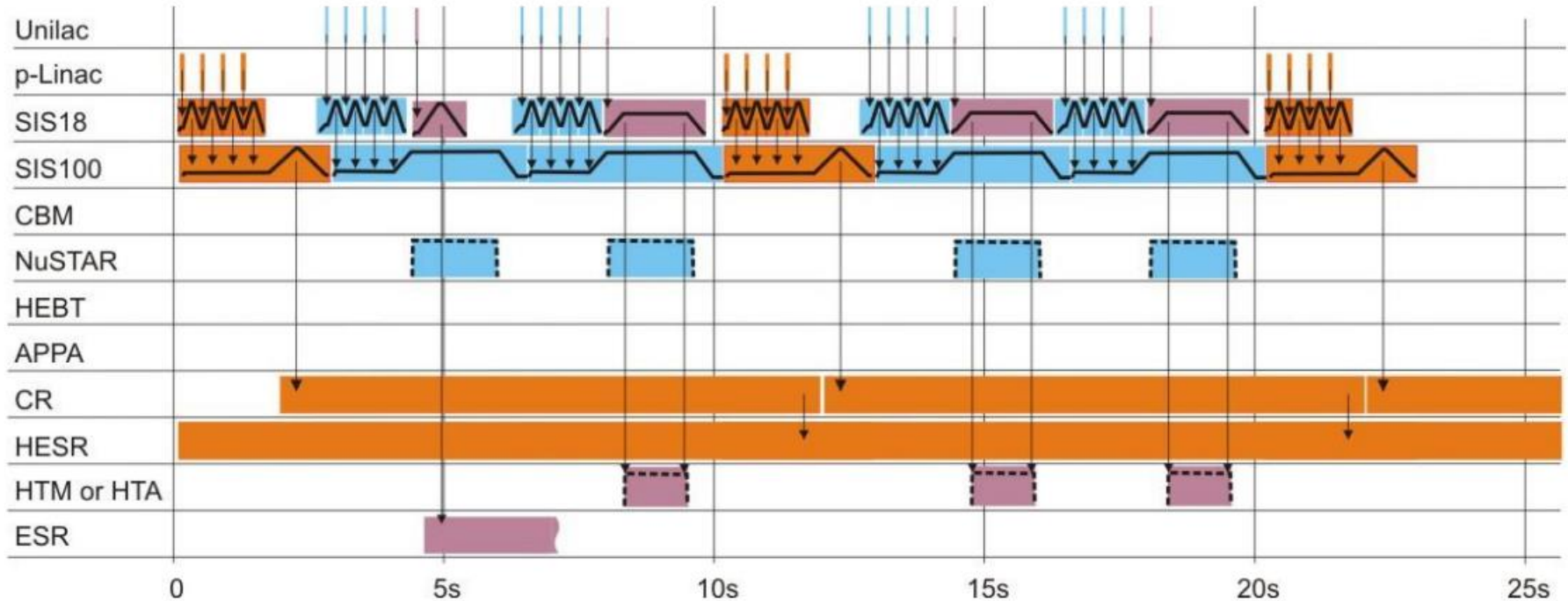


Figure 3-3: Reference Pattern with Antiproton Production as Main Process and NuSTAR as second priority user.