

# Next Generation Beam Position Acquisition and Feedback Systems

ALBA Synchrotron, 12-14 November 2018

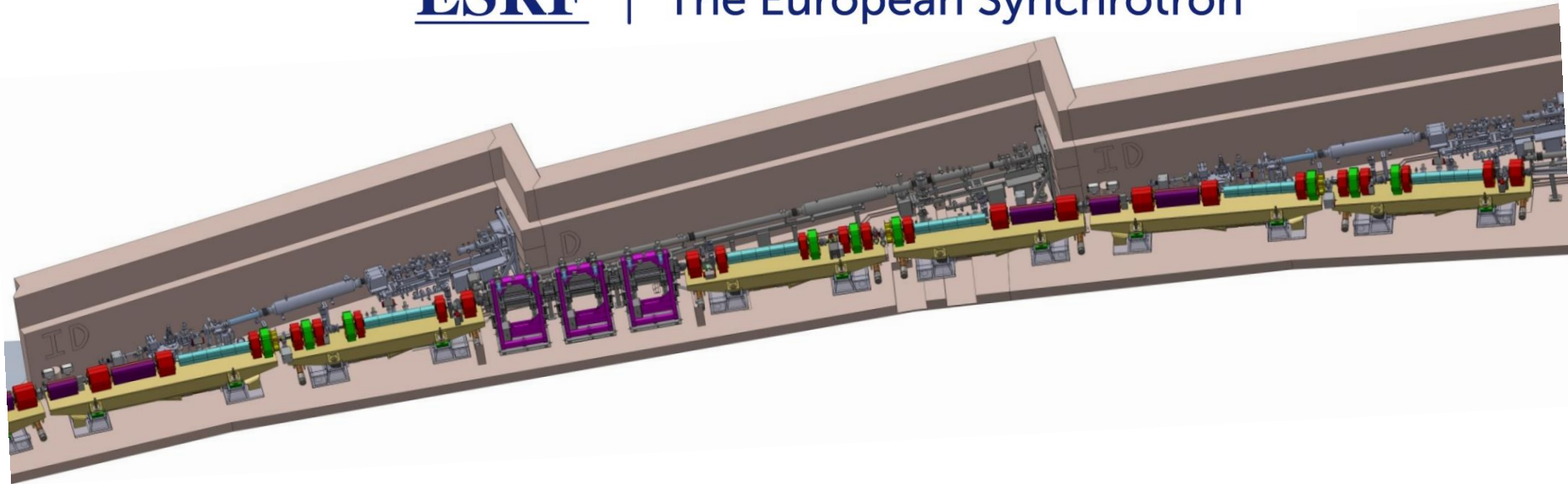
## *A fast orbit correction scheme for the ESRF EBS*

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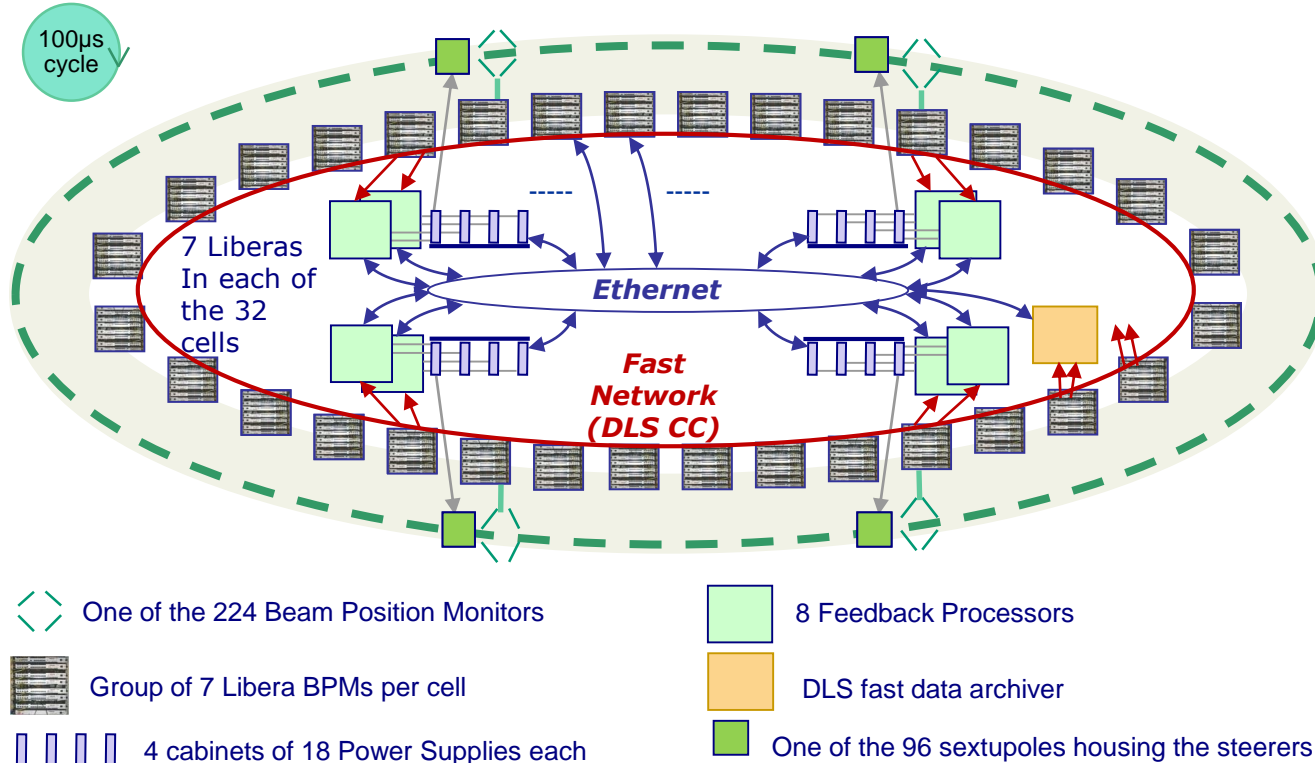


The European Synchrotron



# Present ESRF fast Orbit Feedback

## Architecture

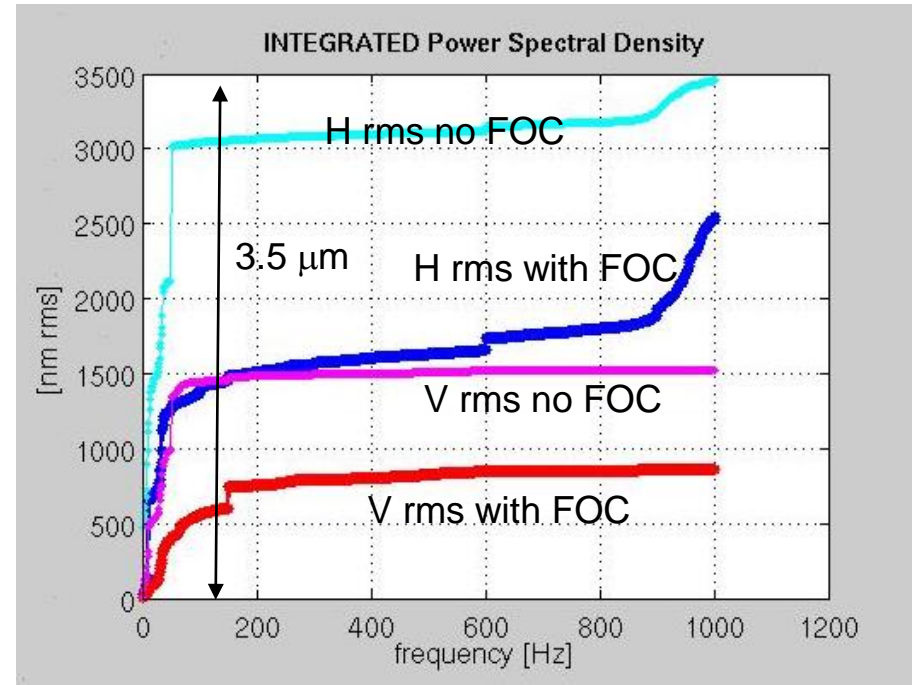


# MOTIVATION OF OUR APPROACH

On our present ring  
Vertical emittance: 6pm  
Horizontal emittance: 4nm

Orbit stability from .01Hz to 1 Hz:  
Vertical:  $.5\mu\text{m}$   
Horizontal:  $.8\mu\text{m}$

Orbit stability from 1Hz to 500Hz:  
Vertical:  $1\mu\text{m}$   
Horizontal:  $1.8\mu\text{m}$



Integrated spectrum of the orbit perturbation with and without fast orbit correction

## MOTIVATION OF OUR APPROACH

For EBS:

- the vertical emittance will be the same and we aim at reaching the same stability
- The horizontal emittance is much lower but the stability achieved on our present ring would be sufficient

**Can we simply reuse our present system without any extra development?**

Which means implementing a fast orbit correction using only:

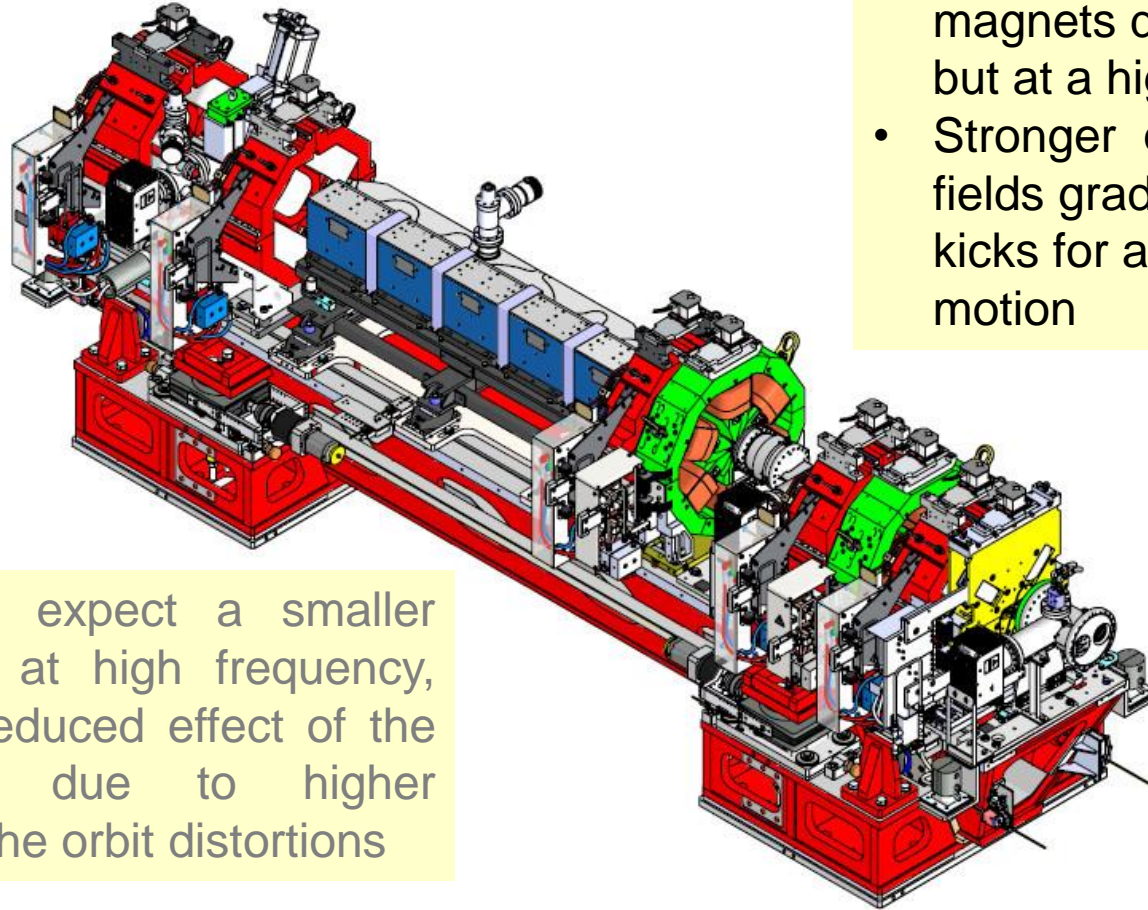
- 6 fast BPM per cell
- 3 fast correctors per cell

When the new orbit correction is supposed to require:

- 10BPM per cell
- 9 correctors per cell

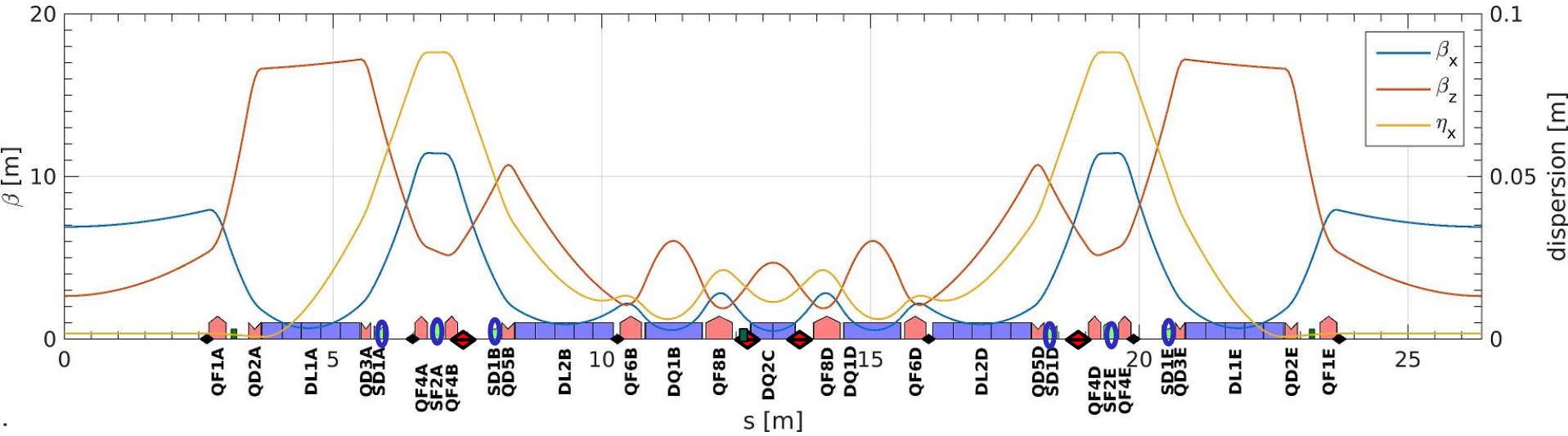
# NEW FAST ORBIT CORRECTION PERFORMANCE

- Stiffer girders: smaller magnets displacement, but at a higher frequency
- Stronger quadrupoles fields gradient => Larger kicks for a given magnet motion



Eventually, we expect a smaller orbit distortion at high frequency, but maybe a reduced effect of the FOC system due to higher frequencies of the orbit distortions

# EBS NEW LATTICE



## **10 BPM per cell:**

6 Libera Brilliance (with fast outputs)  $\blacklozenge$

4 Libera Sparks (no fast outputs)  $\blacklozenge$

## **9 correctors per cell:**

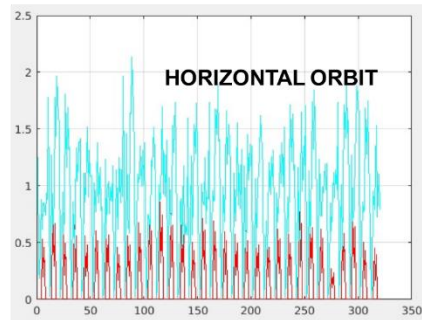
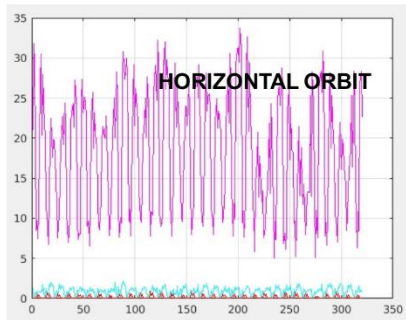
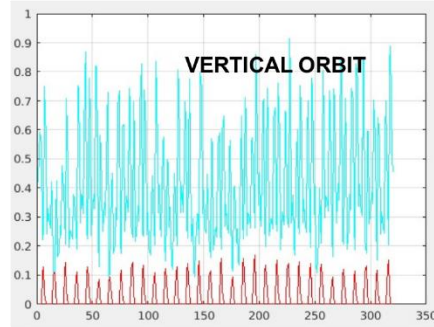
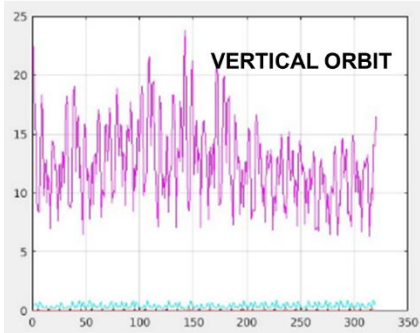
3 fast correctors (500Hz BW)  $\blacksquare$

6 slow correctors  $\circ$



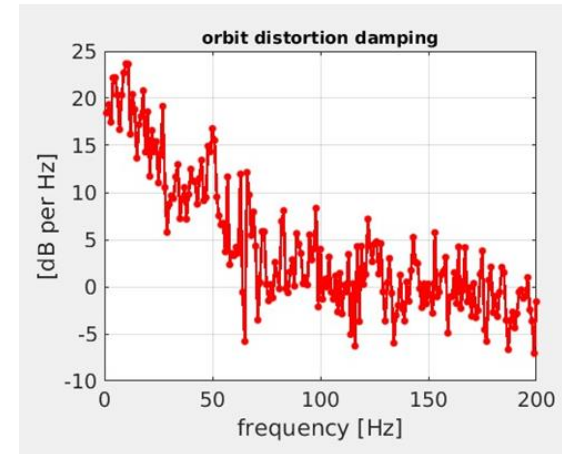
# FAST ORBIT CORRECTION PERFORMANCE

10 sets of random quadrupole magnet displacements

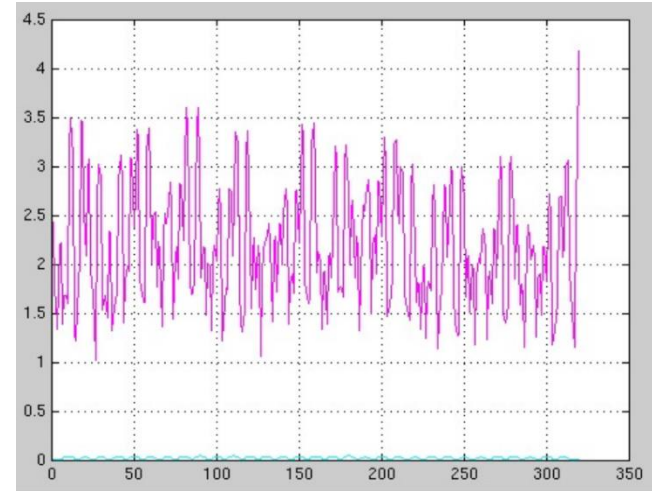
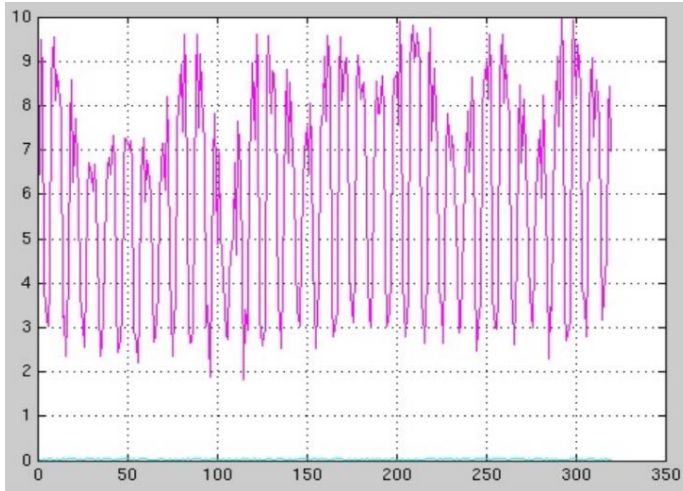


**Magenta:**  
Orbit distortion at the location of the 320 BPMs  
**Blue:**  
Orbit measured using 192 BPMs and corrected using 96 fast correctors  
**Red:**  
Orbit measured using 320 BPMs and corrected using 288 correctors

When the frequency increases, most of the residual distortion will come from the limited bandwidth of the correction



# FAST ORBIT CORRECTION PERFORMANCE



For the BPMs located at the end of the straight section, the correction is nearly perfect



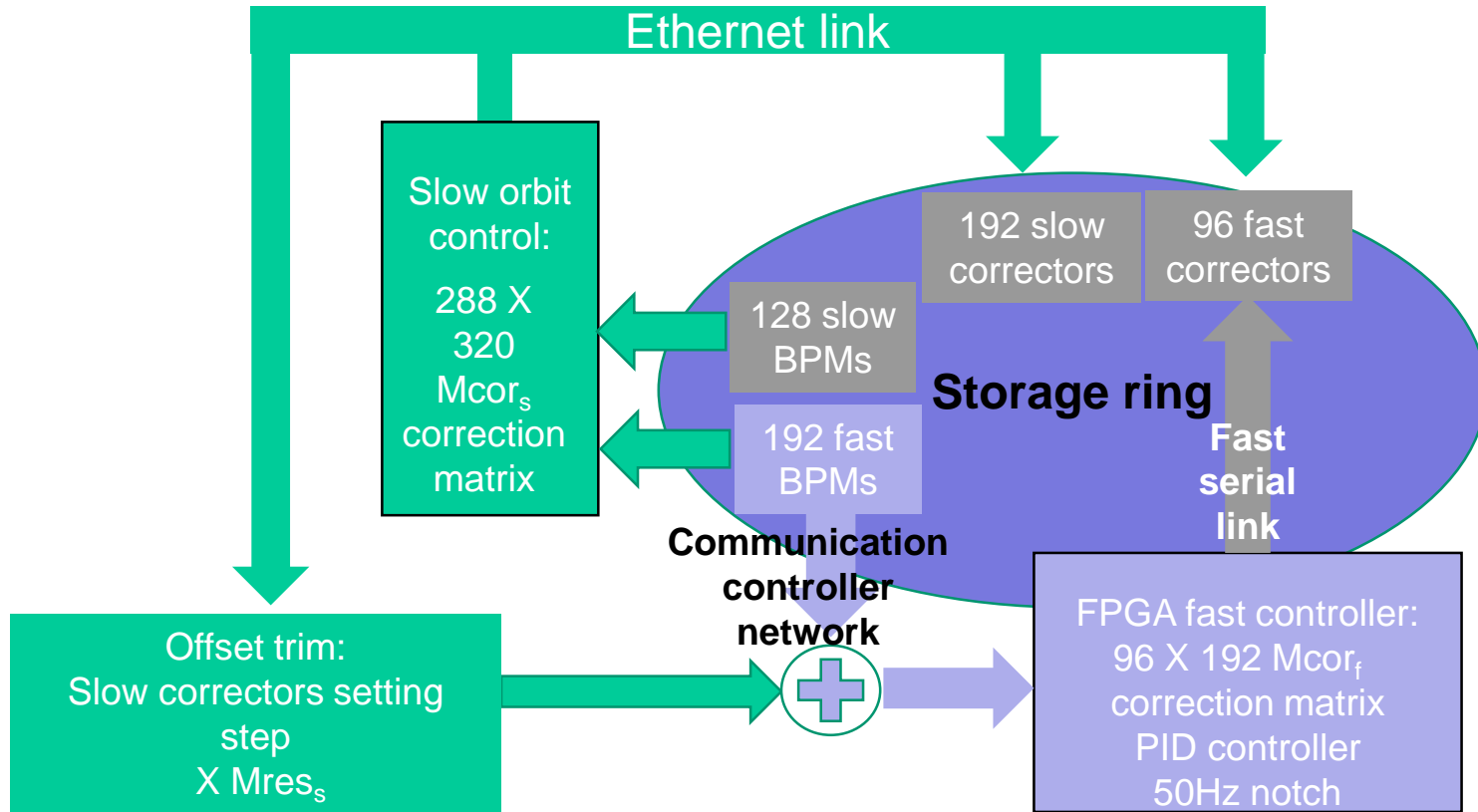
# Conclusion

**The 320 BPMs and 288 correctors are required to put the beam optimal orbit in term of coupling, lifetime**

...

**However small and fast orbit distortion with no DC component can be corrected with a smaller set of BPM and correctors without spoiling the quality of the correction**

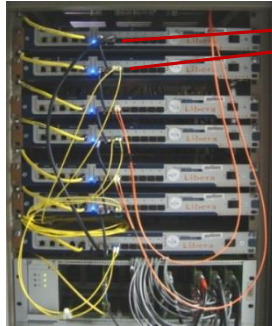
# Scheme Implementation



Hybrid slow/fast orbit control flow chart

# FAST ORBIT CORRECTION COMPONENTS

**From Liberass to the correctors power supplies → 10kHz data flow**



**196 Libera BPMs**

**196 X & Z positions**

**8 FPGA PMCs correctors each driving up to 7 crates (42 channels)**



**Up to 42 corrections**

**Corrections**

**48 Power Supplies Crates,**



**each driving 2 correctors**



**96 fast correctors**

**Diagnostics**

**Fast data archiver developed by DLS: 10 days buffer of all the data of the FOC**

# CORRECTORS

192 correctors embedded in the sextupoles;  
Slow response (1Hz BW)

92 fast correctors (500Hz BW capability):  
Versatile magnets to be used as fast dipoles  
and skew quadrupole



# CORRECTORS POWER SUPPLY CONTROL

**Fast correctors magnets power supplies** → *Each channel receives its setpoint from two sources*

**Static correction:**

+/- 1.8 A maxi 16bits resolution

Set point from Ethernet :

**Golden orbit**

**Dynamic correction:**

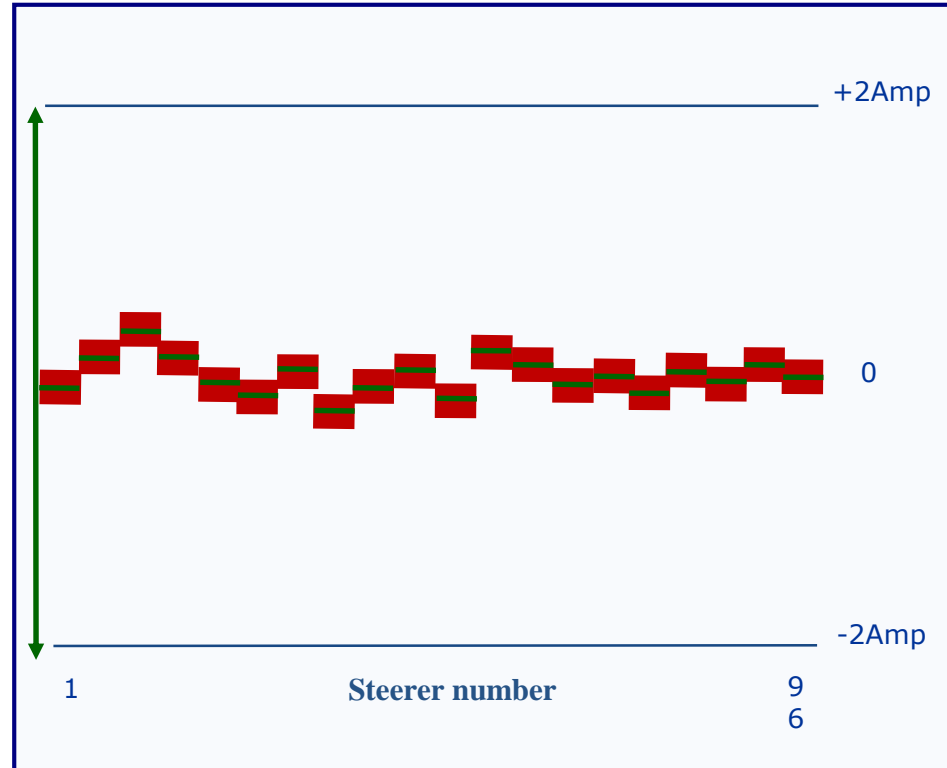
+/- 200mA 16 bits resolution

Set point at 10kHz

from serial line : **FOFB**

**Closed loop resolution:**

**19 bits or 2ppm**



# Fast power supply design

## Fast power supply internal controller:

$di/dt$  limited =>

50Hz bandwidth for the full +/- 100mA swing

500Hz small signal bandwidth

## Dual slow/fast inputs advantage:

- By frequently downloading of the average of the fast inputs settings to the slow inputs, the fast stop of the fast correction becomes straightforward...

- 19 bits resolution when the loop is closed, without the constraint of a true 19 bits resolution design

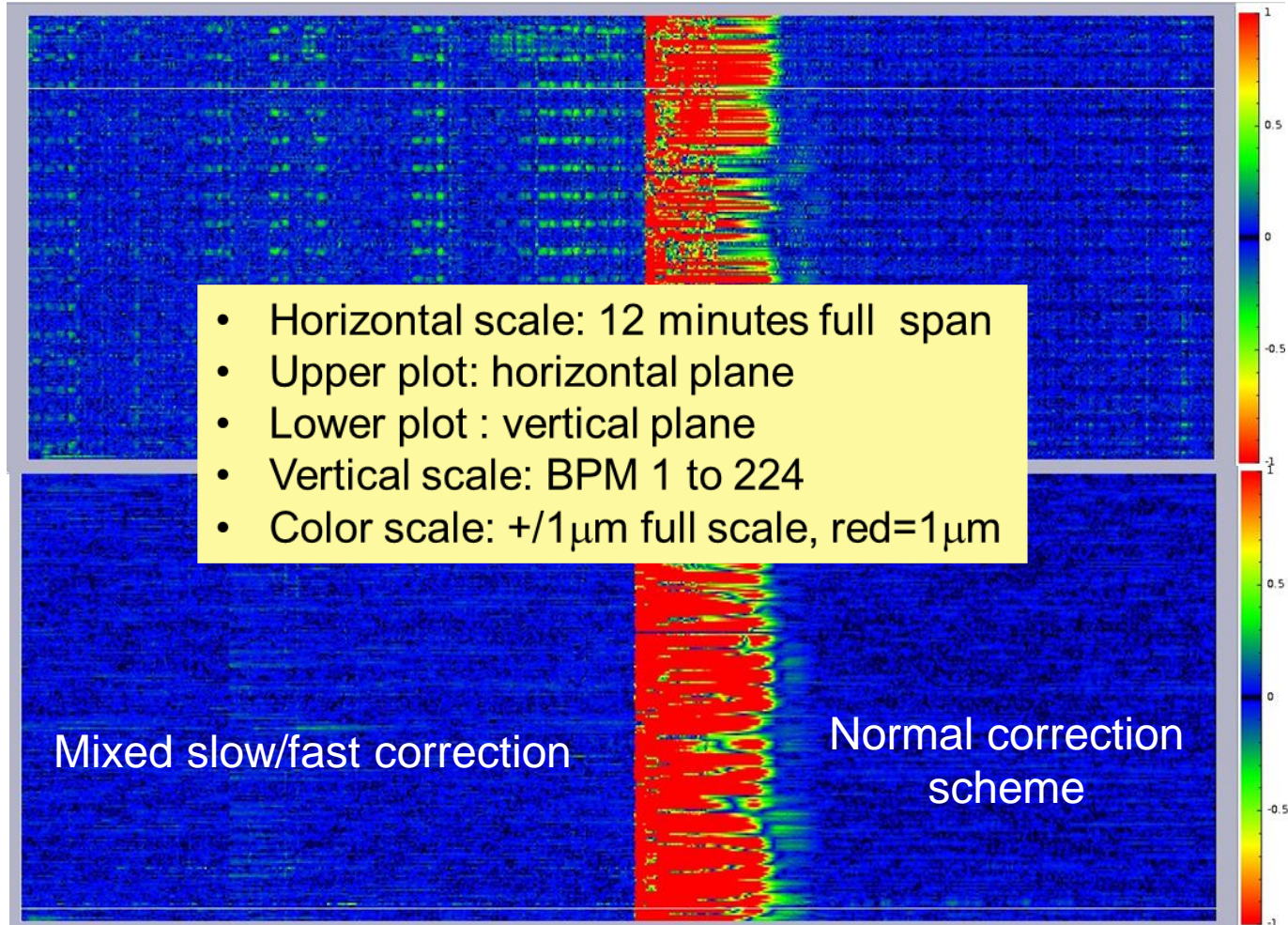


## ON THE PRESENT ESRF STORAGE RING

We used only 5 BPMs and 2 correctors per cell for the Fast Orbit Correction

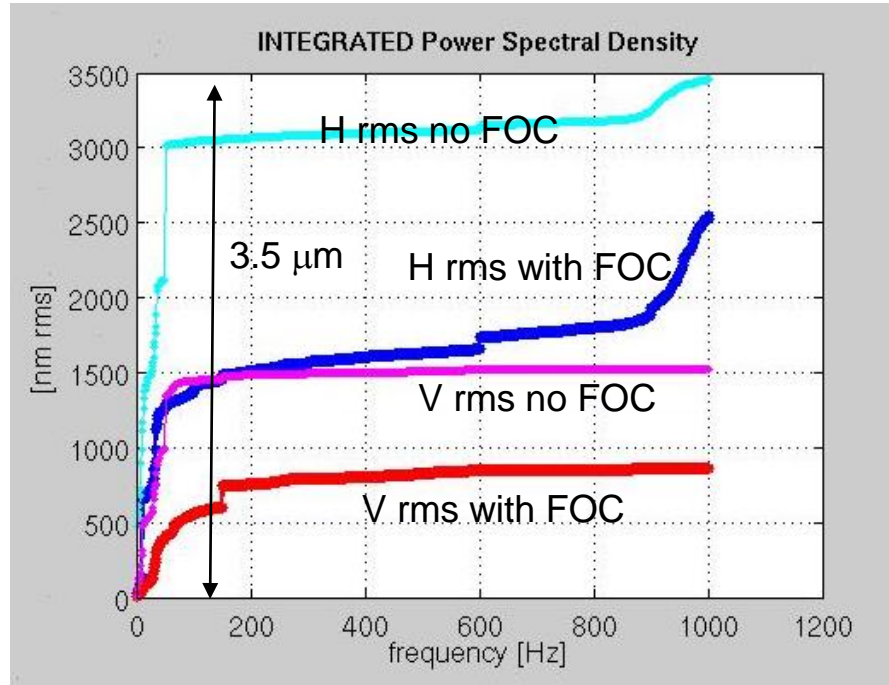
We used the full set of 7 BPMs and 3 correctors per cell for slow orbit corrections ( one correction every 5 seconds)

# FAST ORBIT CORRECTION PERFORMANCE

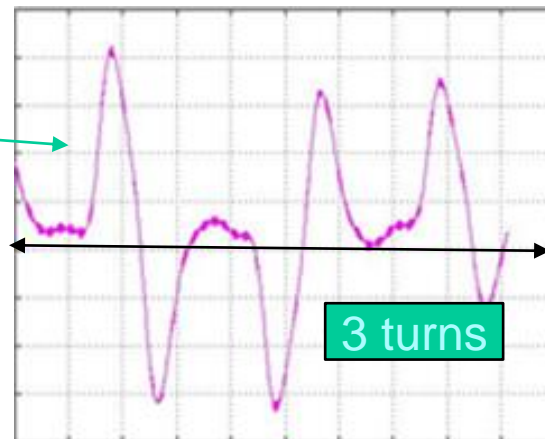
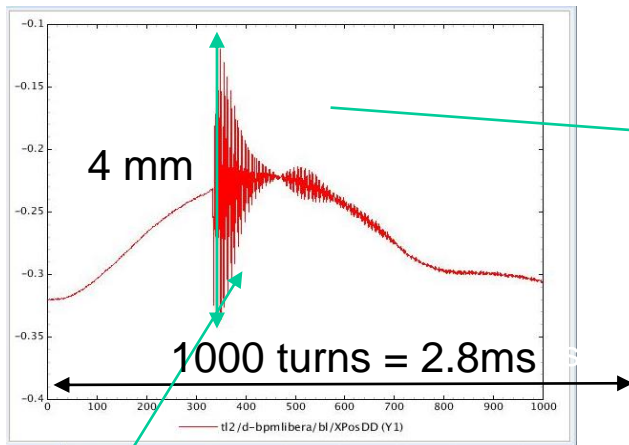


# FAST ORBIT CORRECTION PERFORMANCE AT HIGH FREQUENCY

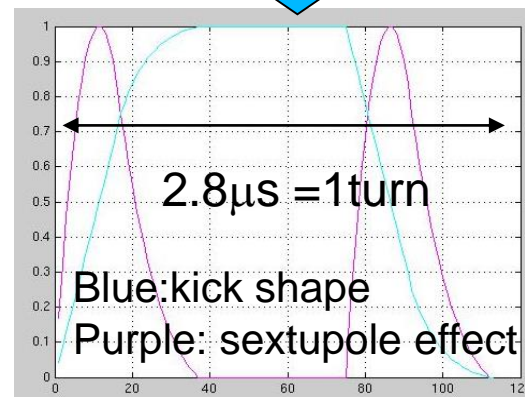
Integrated spectrum of the orbit perturbation with and without fast orbit correction



# PERTURBATION OBSERVED ON THE HORIZONTAL BEAM POSITION



Scale for the fast oscillation signal on the right plot due to a BPM bandwidth limitation



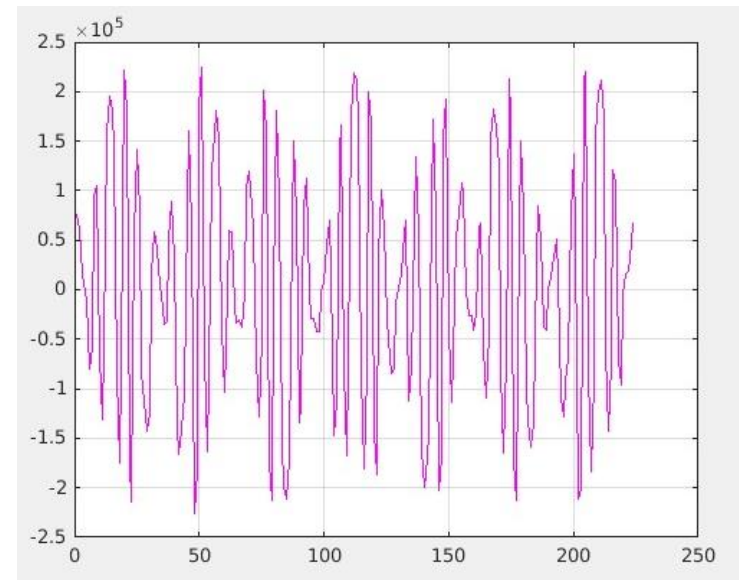
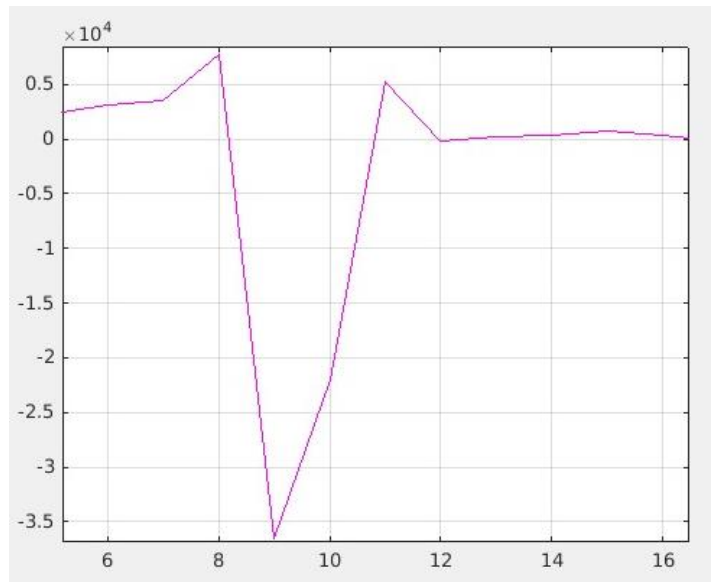
## Normal Fast Orbit Correction effect:

Correction calculated with the normal orbit correction matrix :

- Will use mostly two correctors

The feedback bandwidth is 150Hz:

- The correction will be produced with a delay of about 2ms => no effect!



Orbit Correction Feedback bandwidth: 150Hz

Corrector strength:

Parasitic kick strength:

The correction signal results in overshoot without real reduction of the perturbation peak amplitude.

Sometime the orbit correction stops due to an excessive demand on the corrector strength

The corrector bandwidth is 500Hz which is enough to generate a correction signal, so how can we use it more efficiently?



Correction signal stored in a look up table :

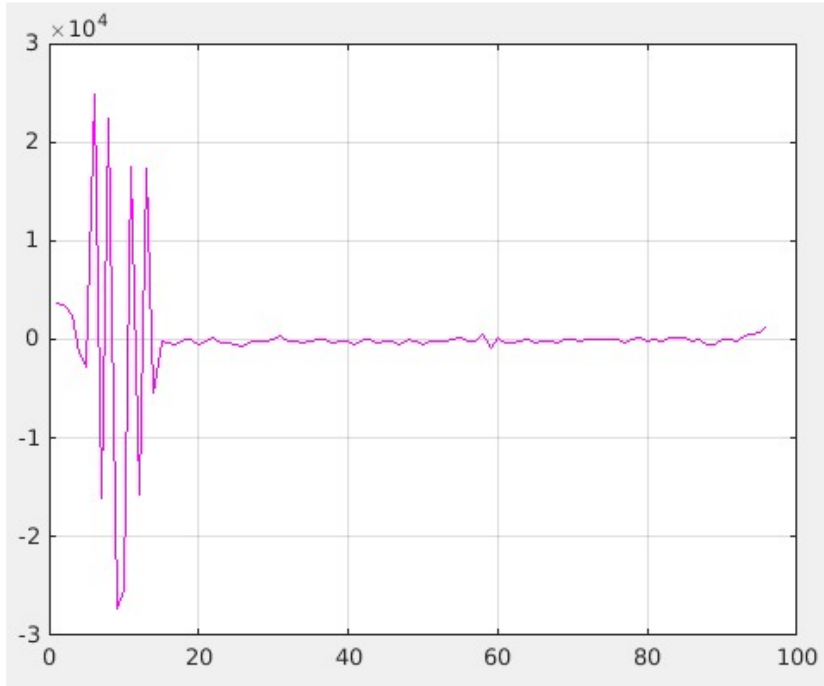
- Efficient use of the corrector bandwidth:
  - No loop stability problem
  - Allows some bandwidth extension by pre emphasis of the signal
- Better use of the available correction strength:
  - Correction spread over 6 correctors instead of 2 when the correction is calculated by the feedback loop using the standard SVD derived correction matrix

We can use more correctors :

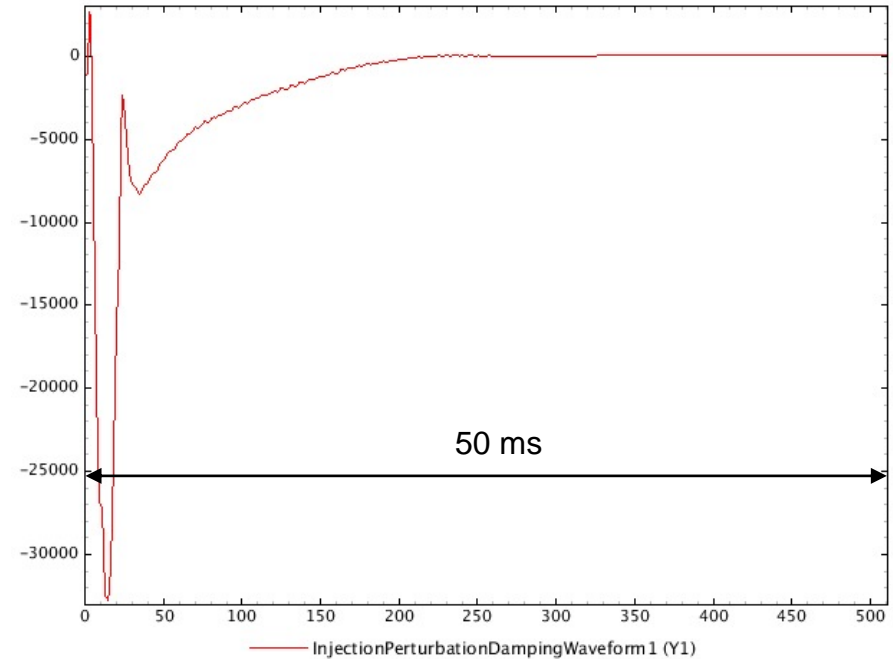
- 6 correctors are available between the two ID straight sections surrounding the injection straight section

The correction generation is triggered by the injection timing

- no delay
- Correction signal generation is fully using the 500Hz correctors bandwidth

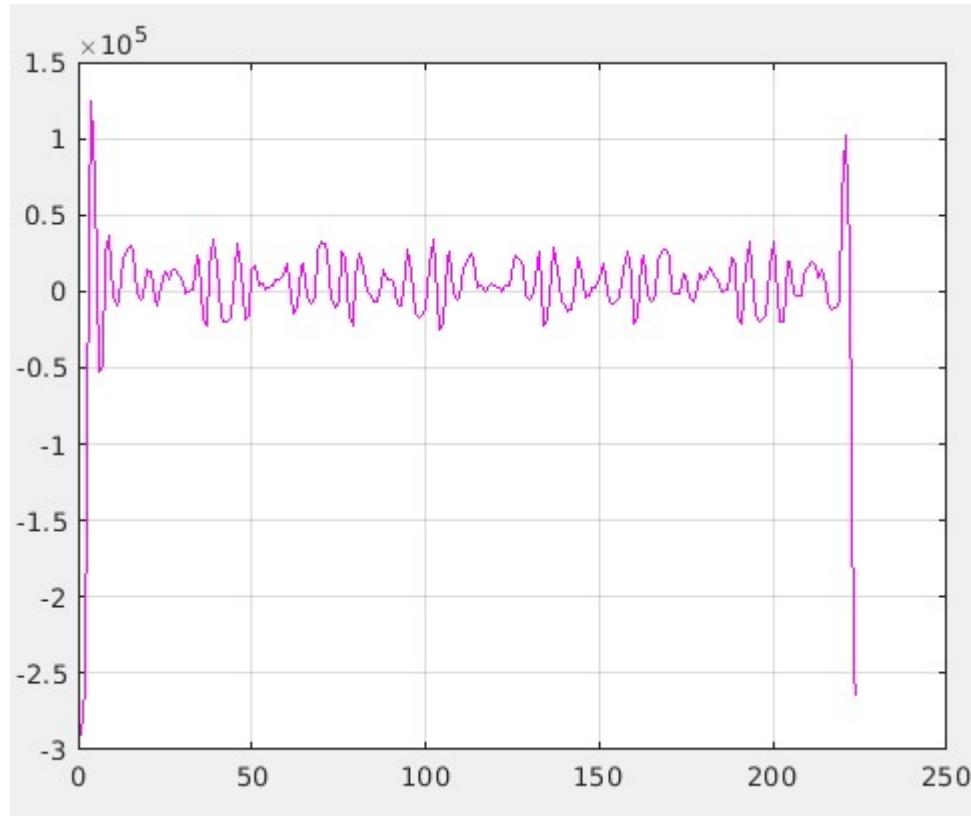


CORRECTION KICKS  
CANCELLING THE SEPTUM LEAK



TIME DOMAIN WAVEFORM USED TO  
MODULATE THE CORRECTION KICKS

## Orbit correction: feedforward correction



MAXIMUM ORBIT PERTURBATION DURING THE SEPTUM PULSE

THANKS FOR YOUR ATTENTION

