

# Next Generation Beam Position Acquisition and Feedback Systems

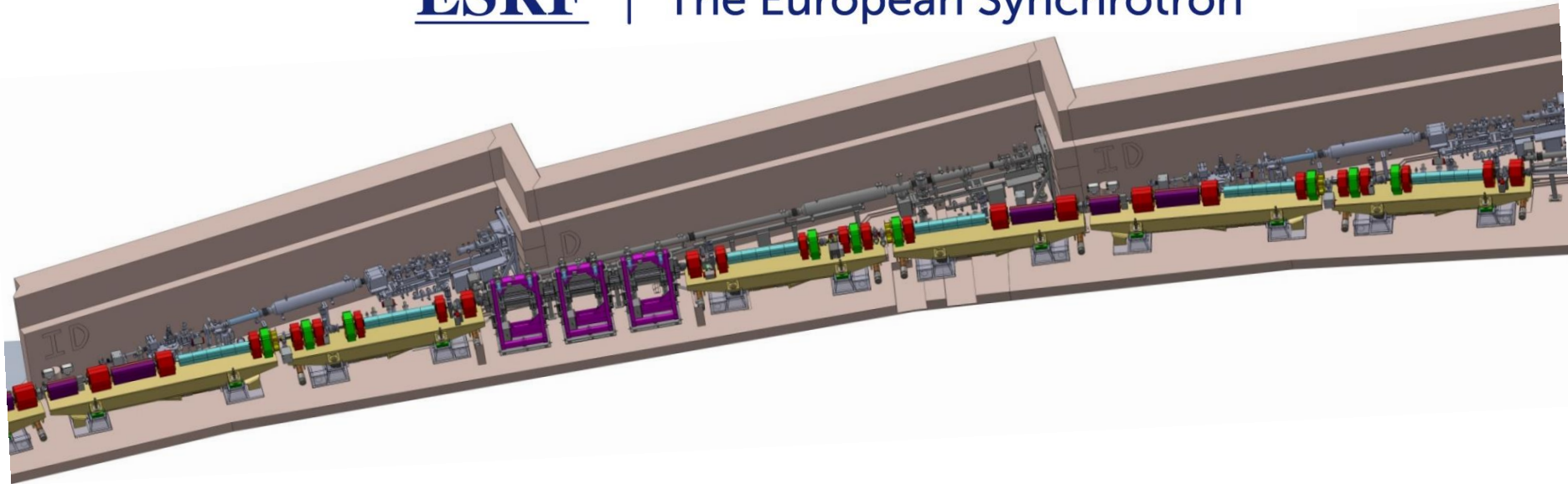
ALBA Synchrotron, 12-14 November 2018

## *Suppression of the injection perturbations using feed-forward techniques*

*Eric PLOUVIEZ, Benoit ROCHE, ESRF Accelerator & Source Division*



| The European Synchrotron



## TOP UP OPERATION

(one refill every 20 minutes instead of twice a day)

⇒ we need to address a new kind of beam position perturbation;

The injection system (kickers and septum) causes beam position oscillation which is perturbing our users experiments.

- Specificity:  
Reproducible shape , triggered by the injection .

I DO NOT PRETEND THAT ANYTHING IS REALLY  
TECHNICALLY ORIGINAL IN OUR SYSTEMS

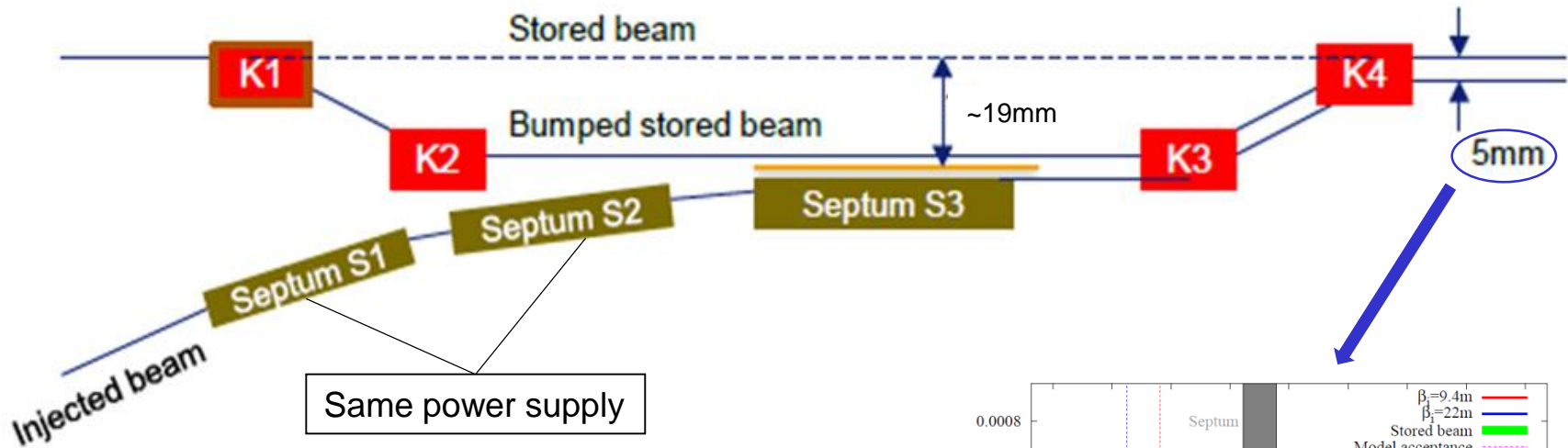
BUT I THINK IT IS INTERESTING TO PRESENT  
THIS APPROACH IN THE FRAME OF THIS WORKSHOP  
IN ORDER TO COMPARE IT TO WHAT COULD BE ACHIEVED  
WITH PURE FEEDBACK SYSTEMS

## Classical four kickers bump scheme

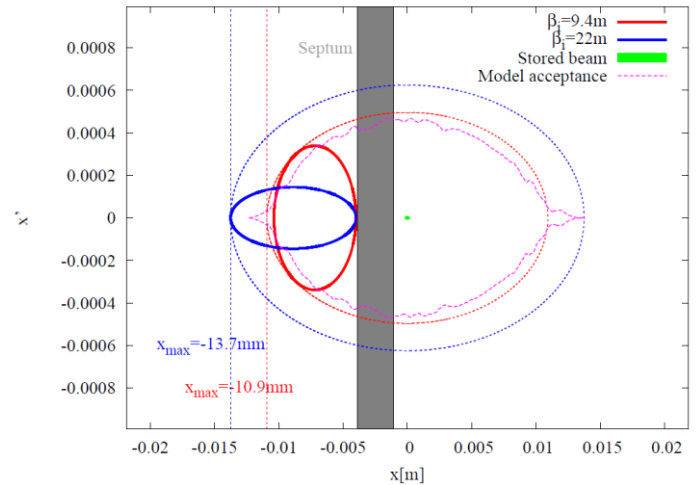
Injection induced perturbation:

- Septum field leakage
- Non closure of the bump during the rise and fall of the bump due to the presence of sextupoles inside the bump

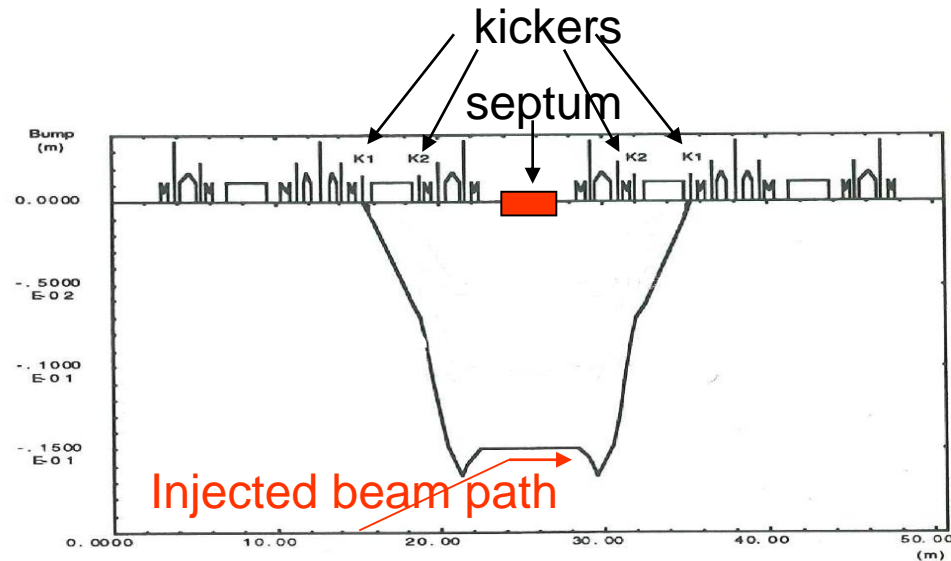
# ESRF storage ring injection scheme



- Pulsed elements at the end of the transfer line:
  - 2 active septa S1 and S2
  - 1 in-vacuum septum



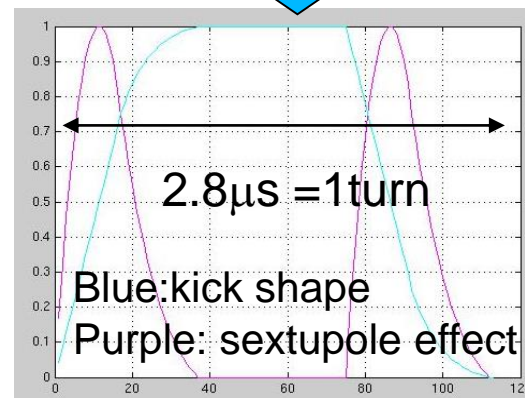
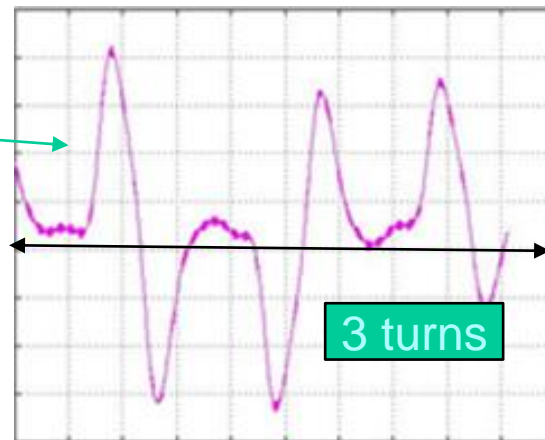
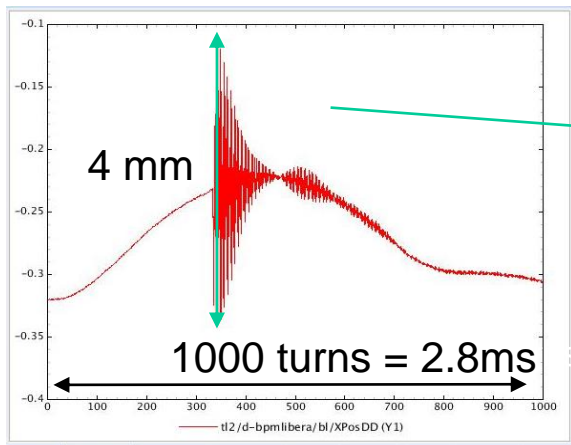
# PARASITIC BEAM POSITION OSCILLATION DURING THE INJECTION IN THE SR



The injection kick path includes sextupoles => the kicker bump is not closed during the kick rise time and fall time

There is a small leakage of the septum field

# PERTURBATION OBSERVED ON THE HORIZONTAL BEAM POSITION



## Orbit Correction Feedback :

- Limited bandwidth  
(compared to the available correctors bandwidth)
- Limited kicker strength.

## Instability Feedback:

- Limited kicker strength
- Limited bandwidth  
(compared to the available correctors bandwidth)



Orbit Correction Feedback bandwidth: 150Hz  
Corrector strength:  
Parasitic kick strength:  
The correction signal results in overshoot without real reduction of the perturbation peak amplitude.  
Sometime the orbit correction stops due to an excessive demand on the corrector strength

The corrector bandwidth is 500Hz which is enough to generate a correction signal, so how can we use it more efficiently?

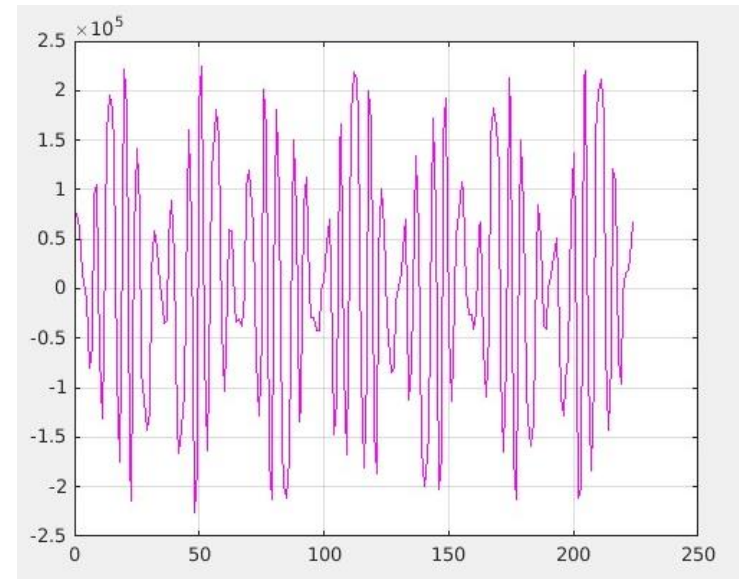
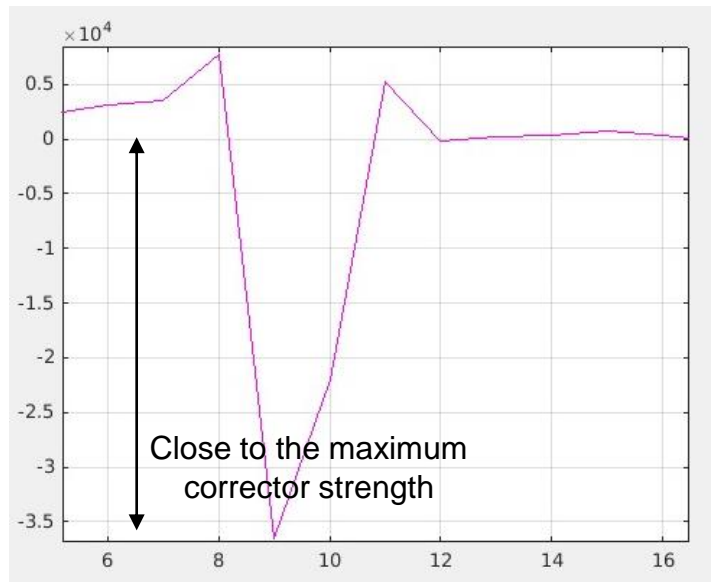
## Normal Fast Orbit Correction effect:

Correction calculated with the normal orbit correction matrix :

- Will use mostly two correctors

The feedback bandwidth is 150Hz:

- The correction will be produced with a delay of about 2ms => no effect!



Correction signal stored in a look up table :

- Efficient use of the corrector bandwidth:
  - No loop stability problem
  - Allows some bandwidth extension by pre emphasis of the signal
- Better use of the available correction strength:
  - Correction spread over 6 correctors instead of 2 when the correction is calculated by the feedback loop using the standard SVD derived correction matrix

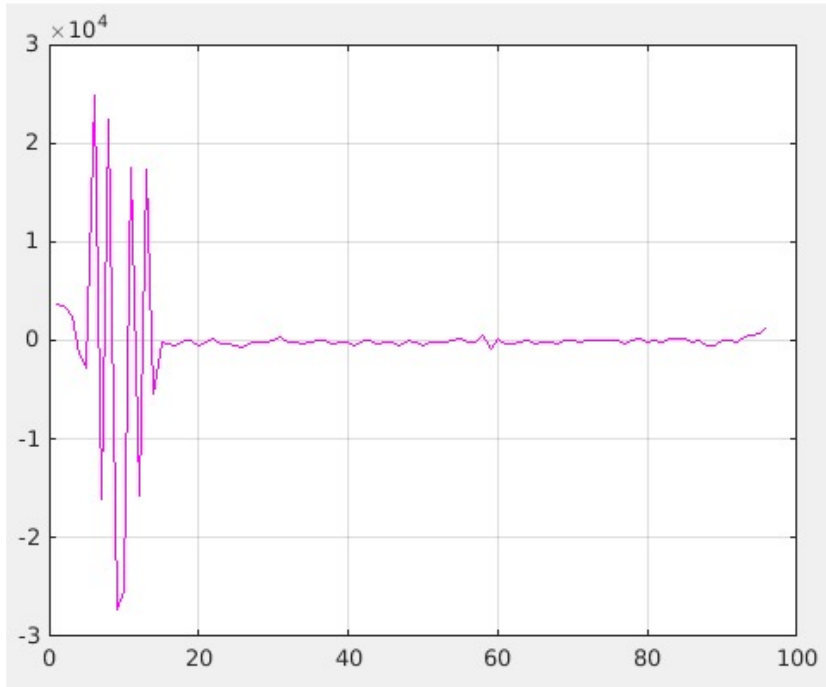
We can use more correctors :

- 6 correctors are available between the two ID straight sections surrounding the injection straight section

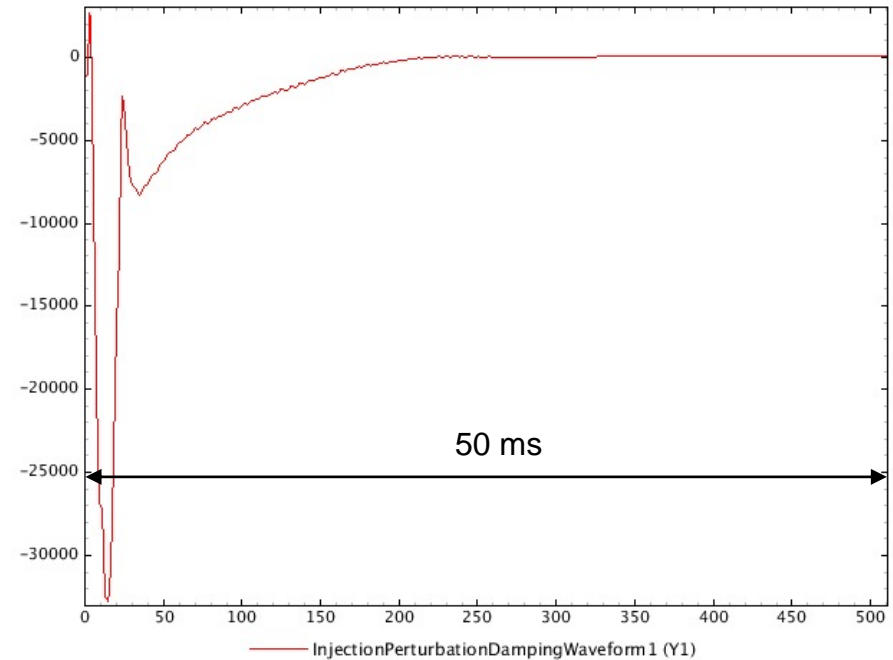
The correction generation is triggered by the injection timing

- no delay
- Correction signal generation is fully using the 500Hz correctors bandwidth

# Orbit correction: feedforward correction

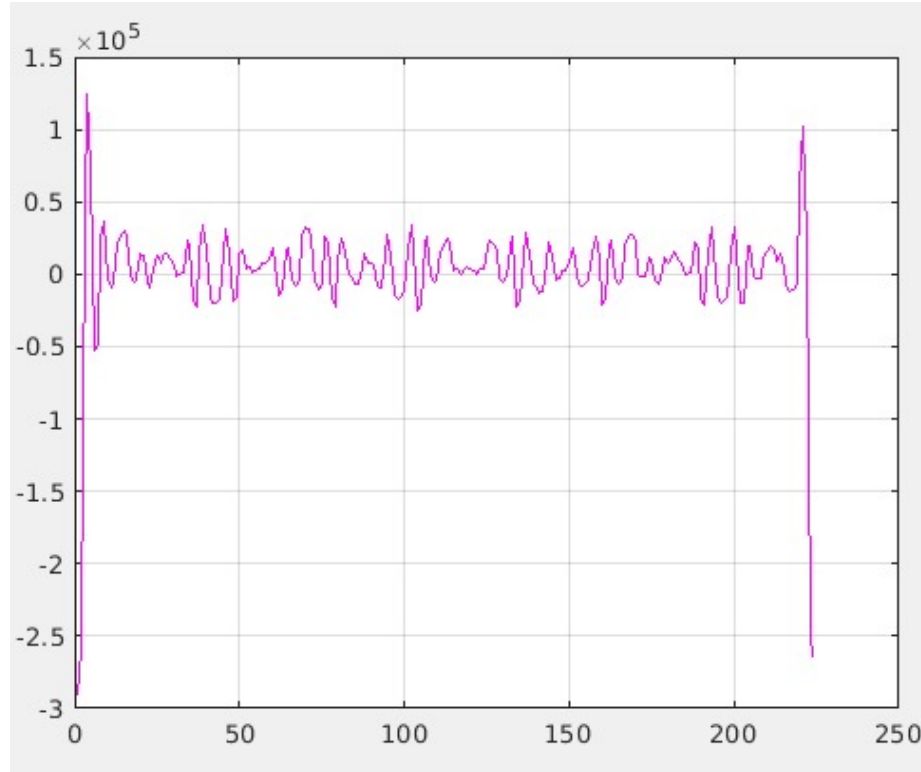


CORRECTION KICKS  
CANCELLING THE SEPTUM LEAK



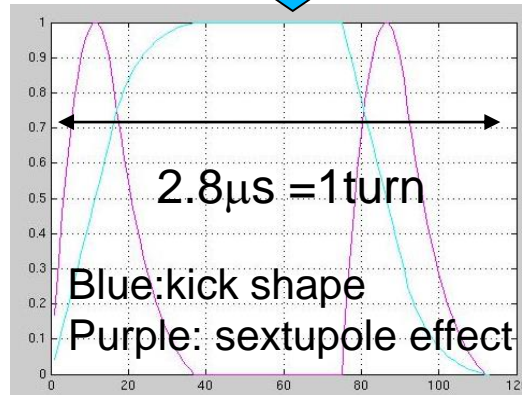
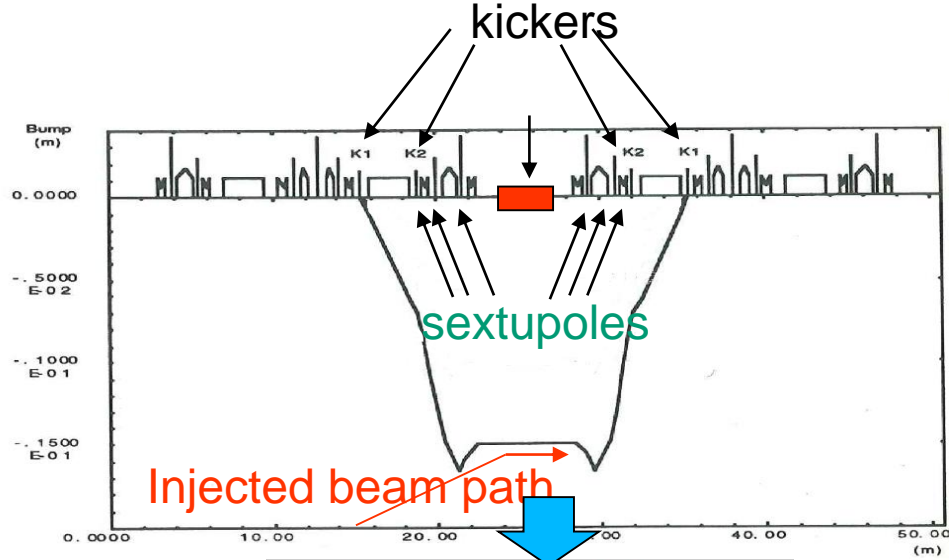
TIME DOMAIN WAVEFORM USED TO  
MODULATE THE CORRECTION KICKS

## Orbit correction: feedforward correction



MAXIMUM ORBIT PERTURBATION DURING THE SEPTUM PULSE

# PERTURBATION DUE TO THE INJECTION KICKERS



KICKERS STRENGTH: .5 mrad

SPURIOUS KICKS DUE TO THE SEXTUPOLES: .05 mrad

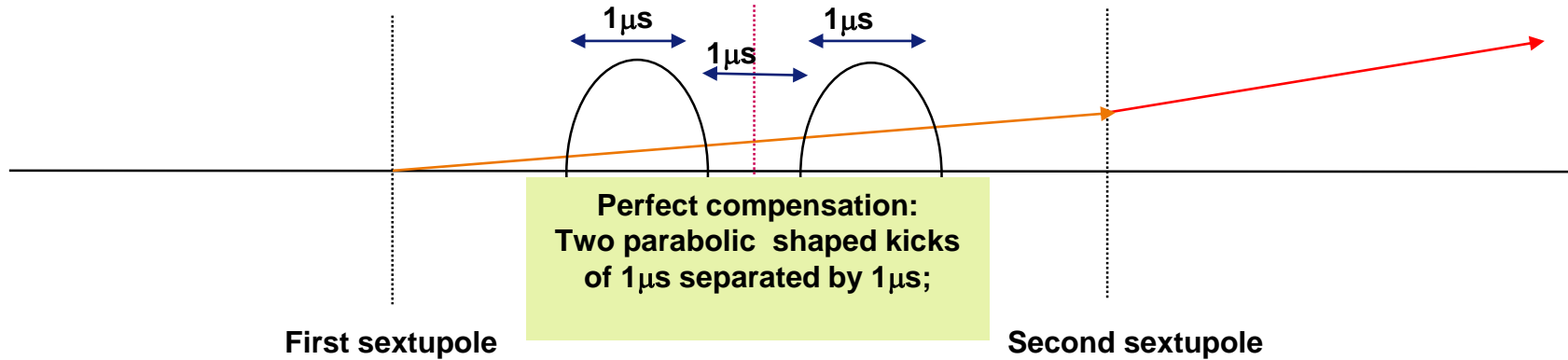
PURELY ACTIVE CANCELLATION WOULD  
REQUIRE VERY STRONG CORRECTORS

PASSIVE CANCELLATION BY:

1. SHAPING THE KICKERS FIELDS (DIPOLE +QUADRUPOLE)
2. ADDING AN OCTUPOLE IN THE BUMP



# PASSIVE COMPENSATION



## Parasitic kick: $d \cdot K(t)^2$

How can we generate:  $K(t) - d \cdot K(t)^2$  instead of  $K(t)$  ?

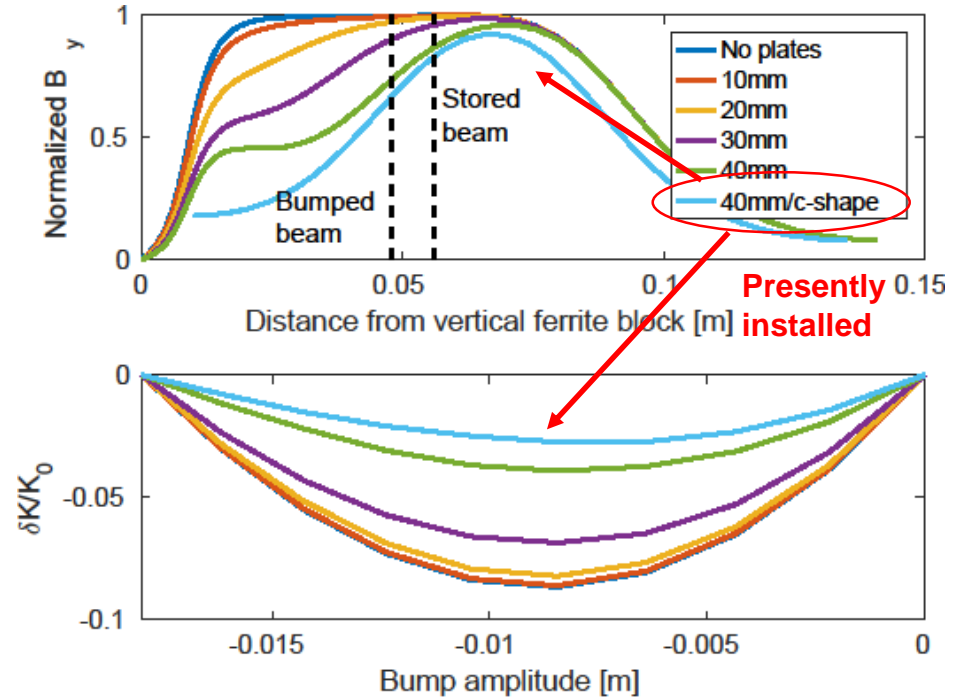
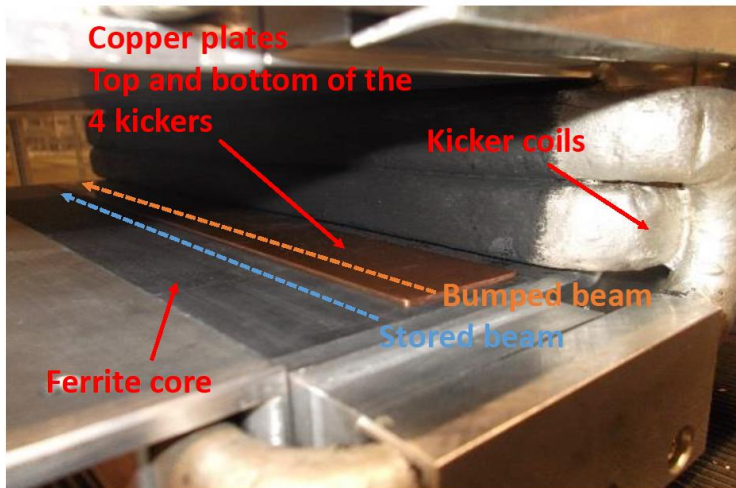
$$K(t) - d \cdot K(t)^2 = K(t) \cdot (1 - d \cdot K(t))$$

we can get the  $(1 - d \cdot K(t))$  factor from the B field variation with  $dx$  inside the kicker magnet:

$$B = B_0 - (b \cdot dx)$$

# Kicker passive compensation

- Idea: add copper shims inside the kickers ferrite gap to generate a non-linear field
- Shape this field with the shims dimension in order to cancel the sextupole field: **reduction of both beta-beat and orbit distortions**
- Creates vertical field gradient: **alignment is now critical**



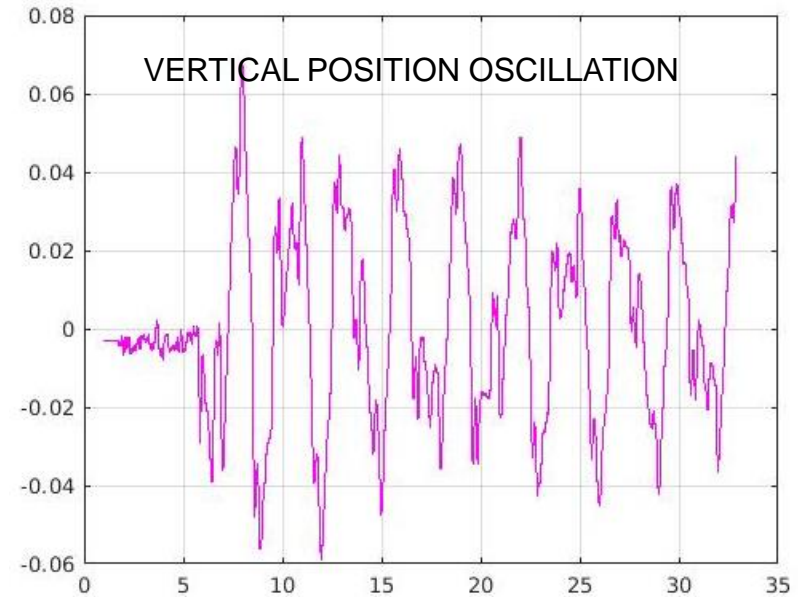
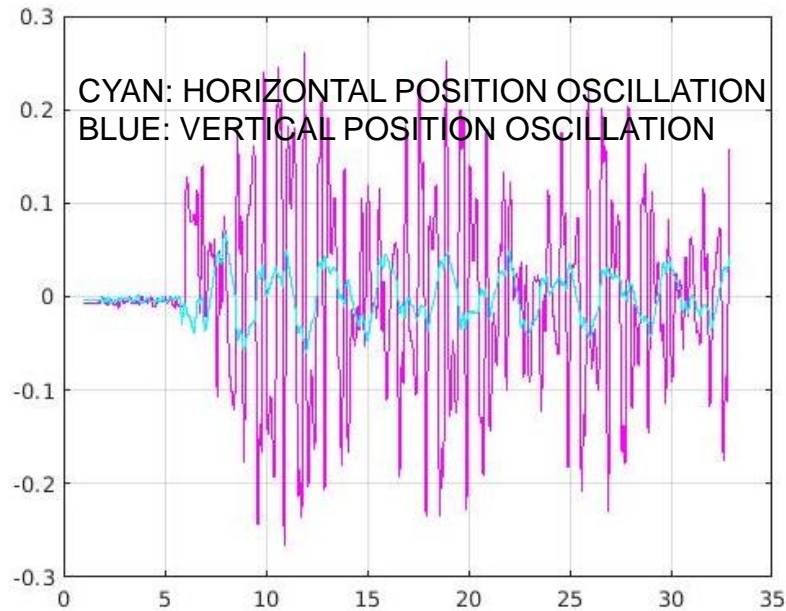
- Ideal conditions and 18mm bump amplitude, simulations indicate a factor 3 improvement

Courtesy Simon White



ACTUALLY THE FULL PASSIVE COMPENSATION OF THE SEXTUPOLES EFFECT REQUIRED ALSO THE IMPLEMENTATION OF AN OCTUPOLE IN ORDER TO FULLY CANCEL THE TRANSIENT QUADRUPOLE FIELD EFFECT WHICH RESULTED IN A BEAM BLOW UP DURING THE BUMP CREATION

# SITUATION AFTER THE SHIMS AND OCTUPOLE IMPLEMENTATION



1. HUGE REDUCTION OF THE HORIZONTAL PERTURBATION
2. STILL A VERTICAL PERTURBATION DUE TO A MORE DIFFICULT ALIGNEMENT OF THE KICKERS (NOW DIPOLE/QUADRUPOLE)

REQUESTED BANDWIDTH: around 1 MHz

REQUESTED KICKER STRENGTH:  $6\mu\text{rad}$  (H) and  $2\mu\text{rad}$  (V)

STRIPLINE KICKERS:  $.5\mu\text{rad}$

MAGNETIC KICKERS:  $4\mu\text{rad}$

BUT ONLY ONE STRIPLINE OR MAGNETIC KICKER AVAILABLE

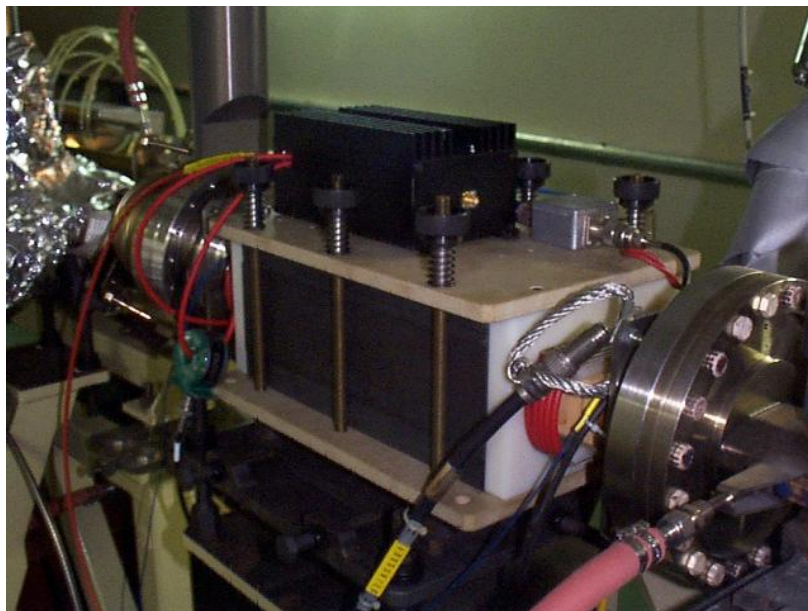
=> no closed bump correction possible

TRANSVERSE DAMPING TIME : 6ms =>

a perturbation suppression obtained over

a several  $2.8\mu\text{s}$  revolutions will still be very beneficial.

And it reduces also the necessary kicker strength



## SR magnetic shaker

- 400W amplifier => 4 A peak current
- 6 coils
- Set up bandwidth: 1 MHz
- 6 GeV beam, B field effect => 4  $\mu$ rad peak /turn

The chromaticity on the ESRF storage ring is high,  
especially in the vertical plane =>  
Due to the decoherency the correction cannot be done over  
a too large number of turns

Other constraint: no DC component in the correction waveform  
(the amplifier bandwidth does not goes down to DC )

1. HORIZONTAL CORRECTION OVER 9 TURNS (H tune= .44)
2. VERTICAL CORRECTION OVER 5 TURNS (V tune = .39)
3. CORRECTION SIGNAL GENERATED USING A LOOK UP TABLE.

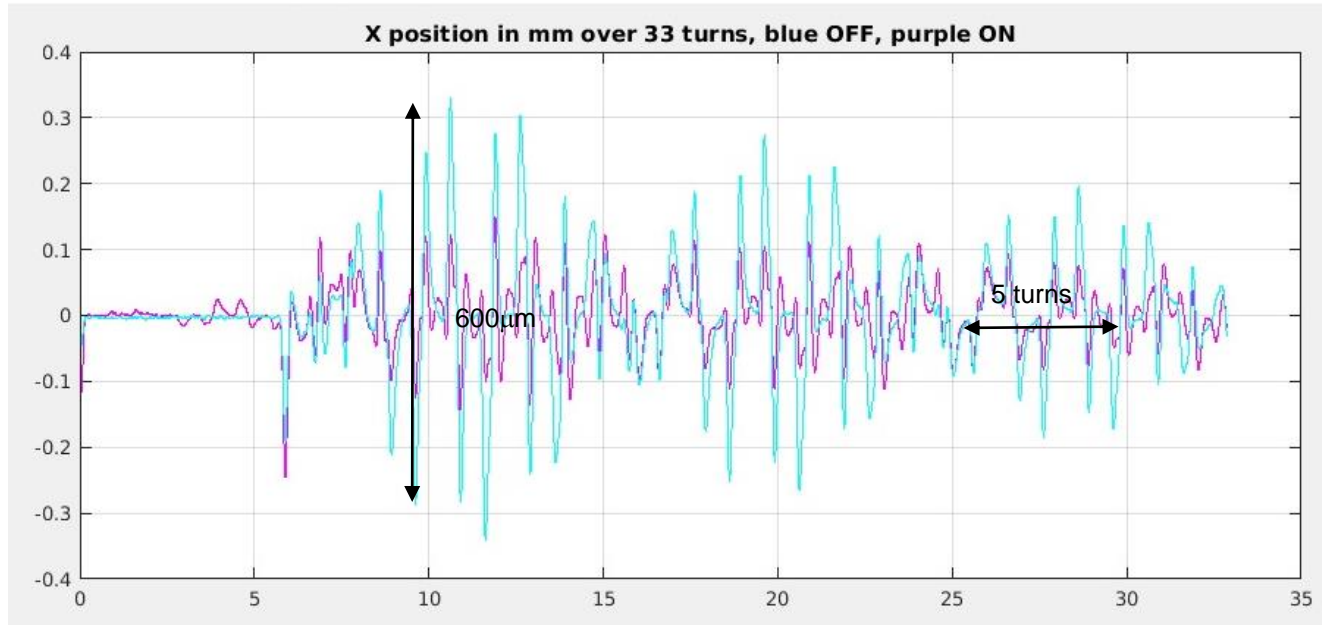


### PERTURBATION SHAPE MEASUREMENT:

- BPM pick up:  
4 buttons with RF matching transformers
- Signal processor:  
ADC data from an Itech Spark => 304 samples per turn, 1014 samples

For each of the 304 samples we get the amplitude and phase of the perturbation over 9 turns (horizontal) or 5 turns (vertical) , assuming it is an oscillation at the betatron frequency , and we use these data and the phase shift between the BPM pick up and the corrector to calculate a correction signal .....

# DAMPING OF THE HORIZONTAL PERTURBATION OVER 9 TURNS



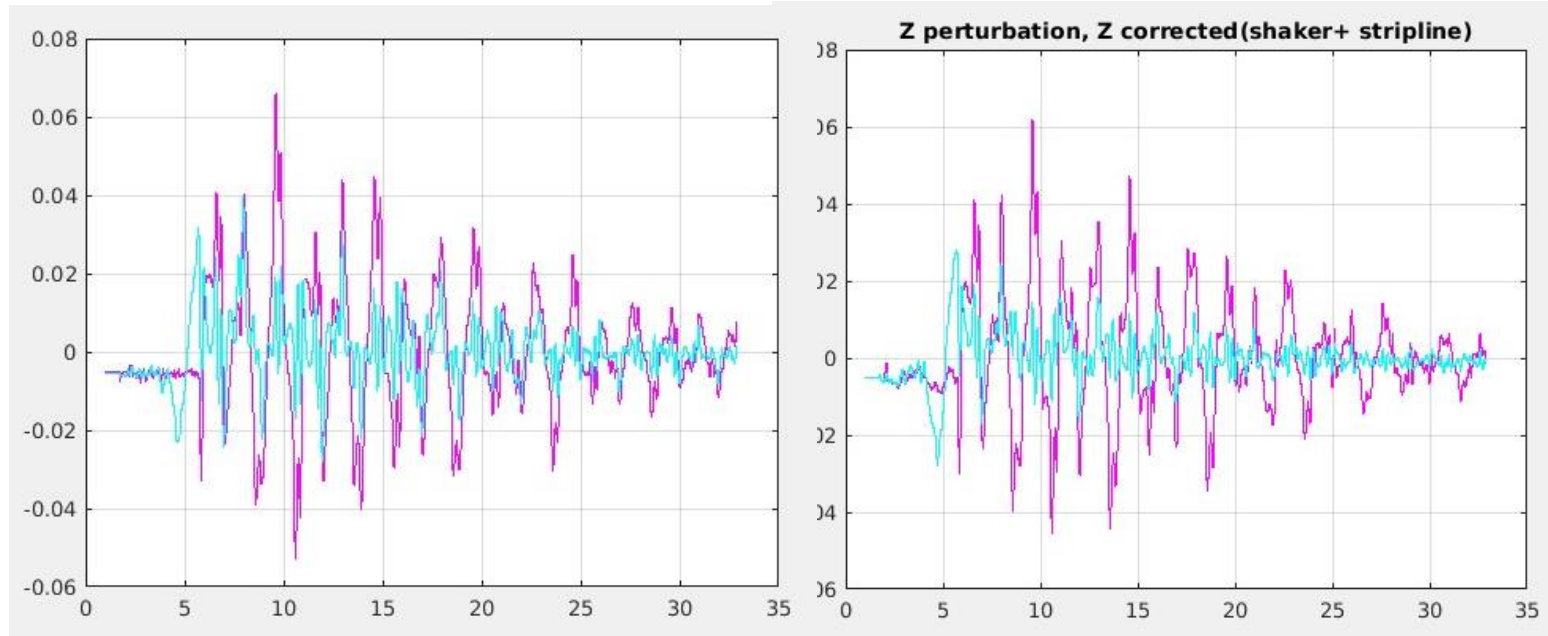
rms oscillation:  
Without active damping: 100 $\mu$ m  
with damping: 50 $\mu$ m  
normal beam size: 350 $\mu$ m

# DAMPING OF THE VERTICAL PERTURBATION OVER 5 TURNS

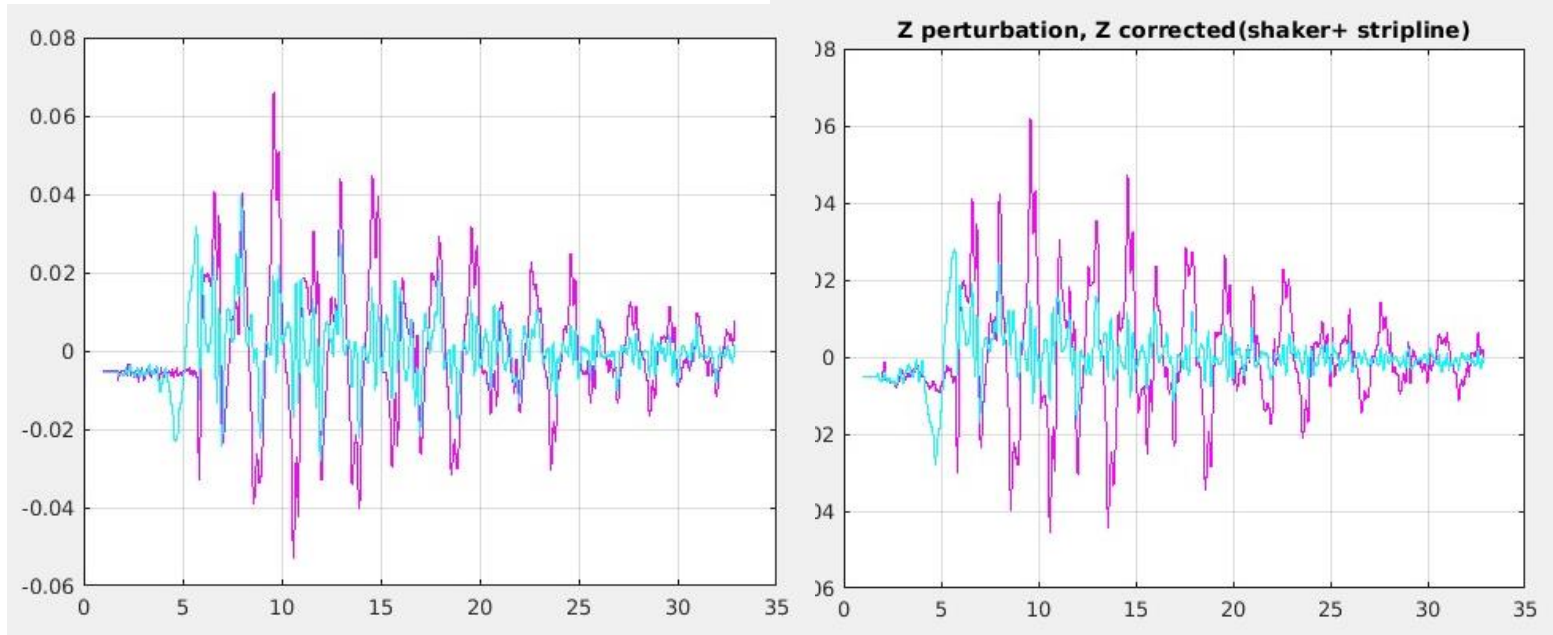


rms oscillation:  
without active damping: 25 $\mu$ m  
with damping: 10 $\mu$ m  
normal beam size: 15 $\mu$ m

# IMPROVED DAMPING OF THE VERTICAL PERTURBATION BY ADDING A STRIPLINE



**Left : damping with the shaker Right: damping using the shaker and the stripline**



**Left : damping with the shaker Right: damping using the shaker and the stripline**

## RANDOM PERTURBATION PATTERN

1. PERTURBATION MEASUREMENT OVER ONE TURN
2. CORRECTION CALCULATION AND GENERATION  
OVER A FEW EXTRA TURNS

THANKS FOR YOUR ATTENTION

